Introduction

(Digital Image Processing)

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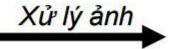
September 2018

Compare

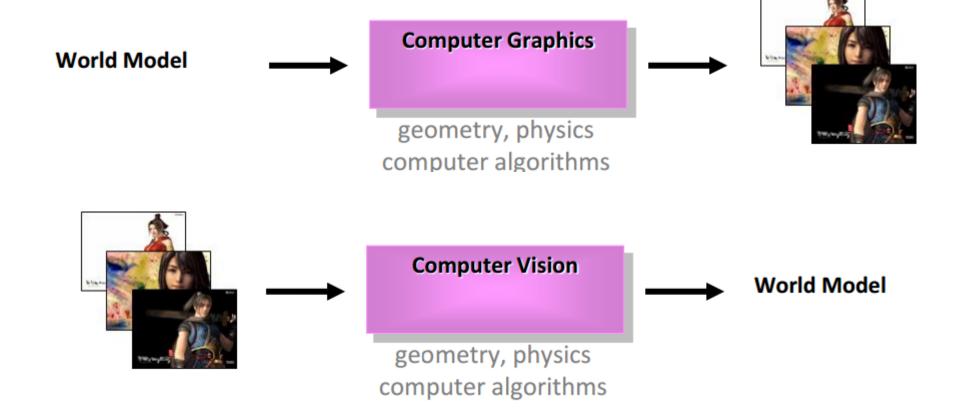
Digital image processing

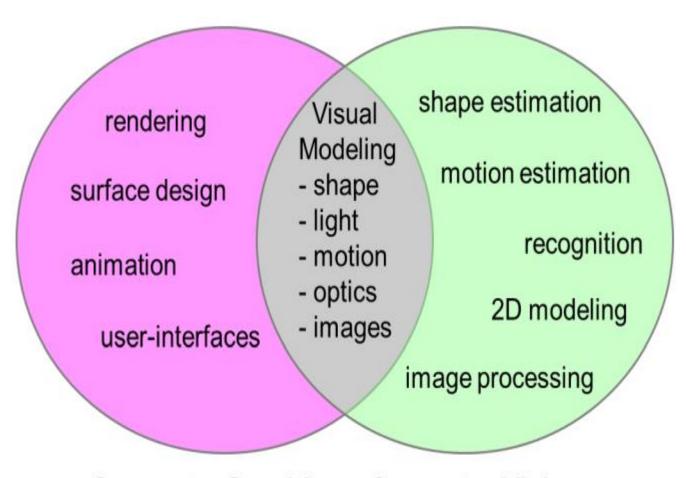
- Computer graphics
 - Computer Vision





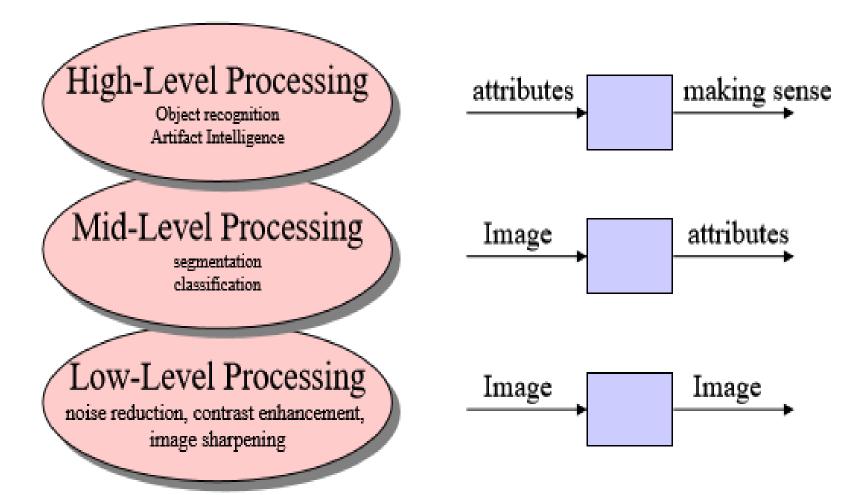






Computer Graphics Computer Vision

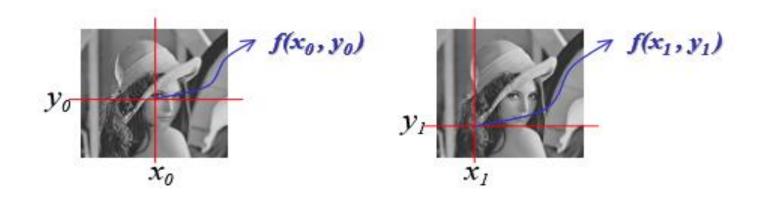
Image processing to computer vision



Digital image processing

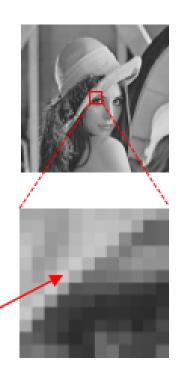
1.1 What is digital image processing?

- Image
 - A 2D function, f(x, y) Intensity = $D\hat{0}$ sáng
 - x and y are spatial coordinates
 - Amplitude of f is called the intensity or gray level



Digital image processing

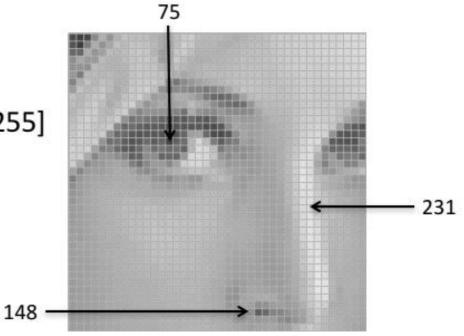
- Digital image
 - x, y, f(x, y) are all finite and discrete
 - is composed of a finite number of elements
 - These elements are referred to as
 - picture elements
 - image elements
 - pels
 - pixels most widely used



pixel

Images as functions

- An image contains discrete number of pixels
 - A simple example
 - Pixel value:
 - "grayscale"(or "intensity"): [0,255]



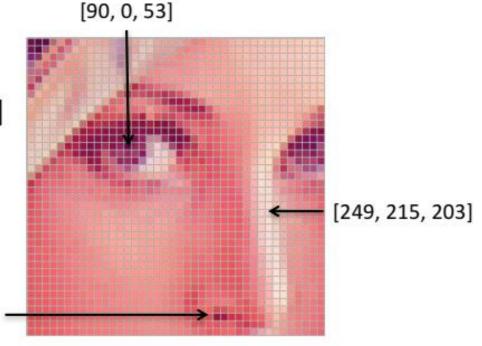
Images as functions

- An image contains discrete number of pixels
 - A simple example
 - Pixel value:
 - "grayscale"

(or "intensity"): [0,255]

- "color"
 - RGB: [R, G, B]
 - Lab: [L, a, b]
 - HSV: [H, S, V]

[213, 60, 67]



Images as discrete functions

- Images are usually digital (discrete):
 - Sample the 2D space on a regular grid
- Represented as a matrix of integer values

							pixe	ı
	j	_					•	
	62	79	23	119	120	05	4	0
i	10	10	9	62	12	78	34	0
	10	58	197	46	46	0	0	48
1	176	135	5	188	191	68	0	49
	2	1	1	29	26	37	0	77
	0	89	144	147	187	102	62	208
	255	252	0	166	123	62	0	31
	166	63	127	17	1	0	99	30

nival

Image formation

- What the computer "sees" is just a grid of numbers.
- this grid of numbers is all the computer "sees".
- Our task then becomes to turn this noisy grid of numbers into the perception: "side mirror".

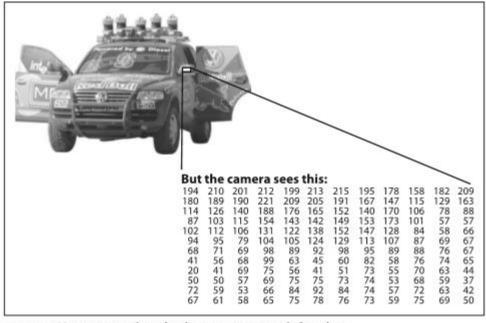
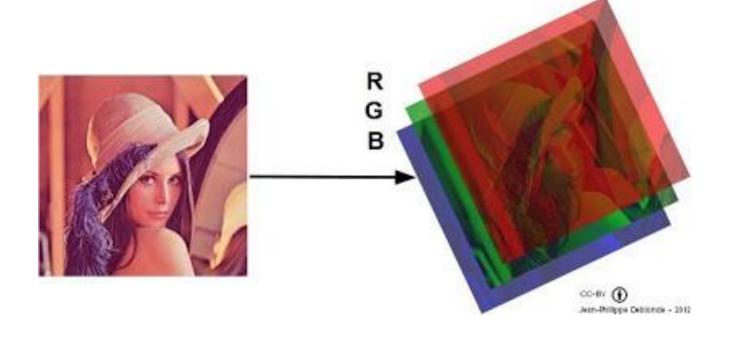
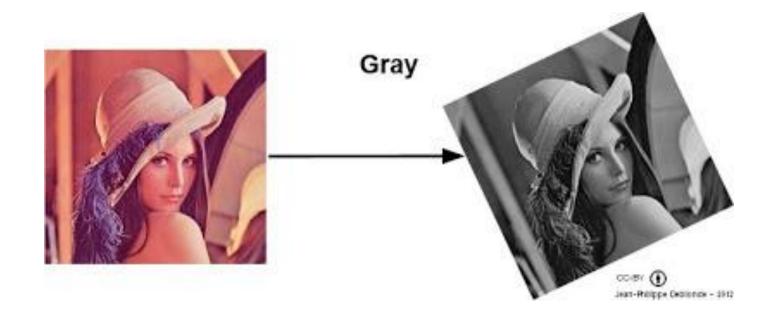


Figure 1-1. To a computer, the car's side mirror is just a grid of numbers

Grayscale & Color image





RGB to Grayscale

• The **lightness** method

$$I = (max(R, G, B) + min(R, G, B)) / 2.$$

• The average method

$$I = (R + G + B) / 3.$$

• The **luminosity** method

$$I = 0.21 R + 0.72 G + 0.07 B.$$









Tools to learn DIP

- OPENCV Library
 - OpenCV for C++
 - Emgu for C#
 - OpenCV for Java/Python

Good for programmers
Fast and efficent
OPEN SOURCE

MATLAB

Very easy to program

Less efficient

NOT FREE

Using OpenCV & Matlab

OpenCV

```
Example 2-1. A simple OpenCV program that loads an image from disk and displays it on the screen #include "highgui.h"
```

```
I = imread('cameraman.tif');
int main( int argc, char** argv ) {

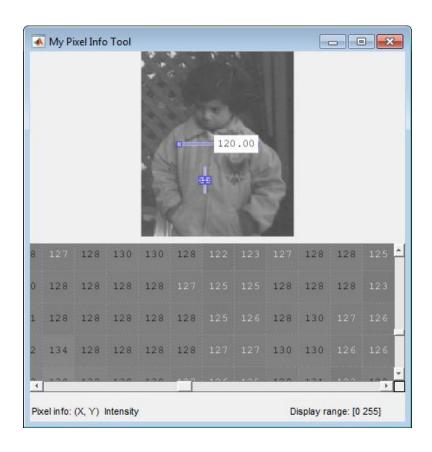
    Matlab

                                                                                              imshow(I)
    IplImage* img = cvLoadImage( argv[1] );
   cvNamedWindow( "Example1", CV WINDOW AUTOSIZE );
    cvShowImage( "Example1", 1mg );
   cvWaitKey(0);
    cvReleaseImage( &img );
                                        #include <opency2/opency.hpp> //Include file for every supported OpenCV function
    cvDestroyWindow( "Example1" );
                                        int main (int argc, char** argv ) {
                                          cv::Mat img = cv::imread(argv[1],-1);
                                          if (img.empty()) return -1;
                                          cv::namedWindow( "Example1", cv::WINDOW AUTOSIZE );
                                          cv::imshow( "Example1", img );
                                          cv::waitKey(0);
                                          cv::destroyWindow( "Example1" );
```

Build App To Display Pixel Information

• https://www.mathworks.com/help/images/build-app-to-display-pixel-information.html

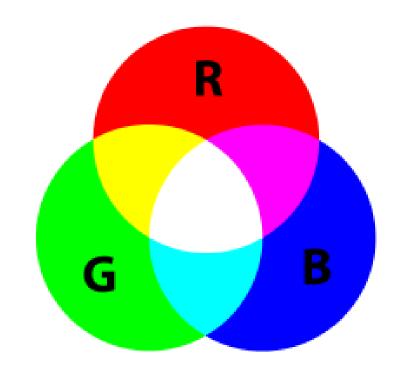
```
function my pixinfotool(im)
% Create figure, setting up properties
fig = figure('Toolbar', 'none',...
              'Menubar', 'none',...
              'Name', 'My Pixel Info Tool',...
              'NumberTitle', 'off',...
              'IntegerHandle','off');
% Create axes and reposition the axes
% to accommodate the Pixel Region tool panel
ax = axes('Units','normalized',...
           'Position',[0 .5 1 .5]);
% Display image in the axes
img = imshow(im);
% Add Distance tool, specifying axes as parent
distool = imdistline(ax);
% Add Pixel Information tool, specifying image as parent
pixinfo = impixelinfo(img);
% Add Display Range tool, specifying image as parent
drange = imdisplayrange(img);
% Add Pixel Region tool panel, specifying figure as parent
% and image as target
pixreg = impixelregionpanel(fig,img);
% Reposition the Pixel Region tool to fit in the figure
% window, leaving room for the Pixel Information and
% Display Range tools.
set(pixreg, 'units', 'normalized', 'position', [0 .08 1 .4])
```

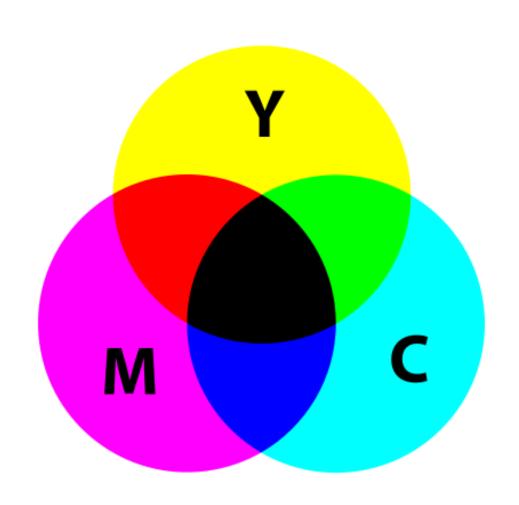


Many color spaces? Why?

https://en.wikipedia.org/wiki/Color space

- RGB uses additive color mixing, because it describes what kind of light needs to be emitted to produce a given color. RGB stores individual values for red, green and blue.
- RGBA is RGB with an additional channel, alpha, to indicate transparency.





- CMYK uses subtractive color mixing used in the printing process
- HSV (hue, saturation, value), also known as HSB (hue, saturation, brightness) is often used by artists because it is often more natural to think
- HSL (hue, saturation, lightness/luminance), also known as HLS or HSI (hue, saturation, intensity) is quite similar to HSV, with "lightness" replacing "brightness".

- ABSOLUTE color space
 - A color space in which the perceptual difference between colors is directly related to distances between colors as represented by points in the color space
 - CIEXYZ and sRGB are examples of absolute color spaces
 - The L*a*b* is sometimes referred to as absolute, though it also needs a white point specification to make it so

Color space	Color mixing	Primary parameters	Used for	Pros and cons
RGB	Additive	Red, Green, Blue		Easy but wasting bandwidth
CMYK	Subtractive	Cyan, Magenta, Yellow, Black	Printer	Works in pigment mixing
YCbCr YPbPr	additive	Y(luminance), Cb(blue chroma), Cr(red chroma)	Video encoding, digital camera	Bandwidth efficient
YUV	additive	Y(luminance), U(blue chroma), V(red chroma)	Video encoding for NTSC, PAL, SECAM	Bandwidth efficient
YIQ	additive	Y(luminance), I(rotated from U), Q(rotated from V)	Video encoding for NTSC	Bandwidth efficient

Color Space conversion

http://www.equasys.de/colorconversion.html

RGB to YLIV color conversion for analog TV

YUV to RGB color conversion for analog TV

A Theory Based on Conversion of RGB image to Gray image

Grey image

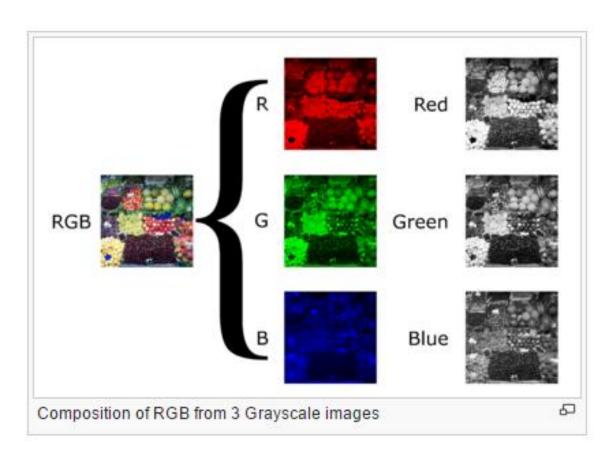
Grey color codes chart

Color	HTML / CSS Color Name	Hex Code #RRGGBB	Decimal Code (R,G,B)	
	gainsboro	#DCDCDC	rgb(220,220,220)	
	lightgray / lightgrey	#D3D3D3	rgb(211,211,211)	
	silver	#C0C0C0	rgb(192,192,192)	
	darkgray / darkgrey	#A9A9A9	rgb(169,169,169)	
	gray / grey	#808080	rgb(128,128,128)	
	dimgray / dimgrey	#696969	rgb(105,105,105)	
	lightslategray / lightslategrey	#778899	rgb(119,136,153)	
	slategray / slategrey	#708090	rgb(112,128,144)	
	darkslategray / darkslategrey	#2F4F4F	rgb(47,79,79)	
	black	#000000	rgb(0,0,0)	

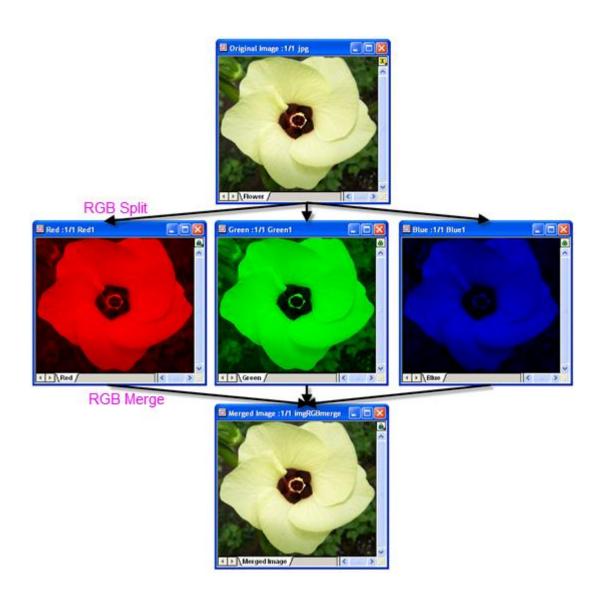
• http://www.rapidtables.com/web/color/gray-color.htm

Grayscale as single channels of multichannel color images

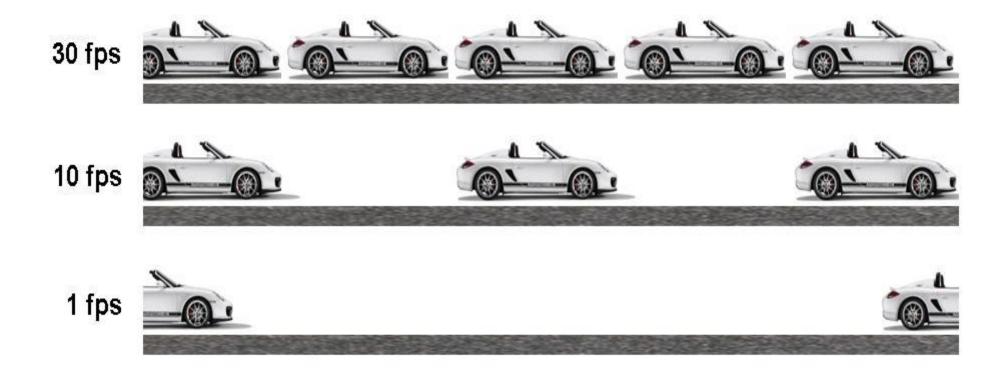
- Color images are often built of several stacked color channels,
- each of them representing value levels of the given channel.
- For example, RGB images are composed of three independent channels for red, green and blue primary color components;



```
img = imread('filename.png'); % Read image
red = img(:,:,1); % Red channel
green = img(:,:,2); % Green channel
blue = img(:,:,3); % Blue channel
```

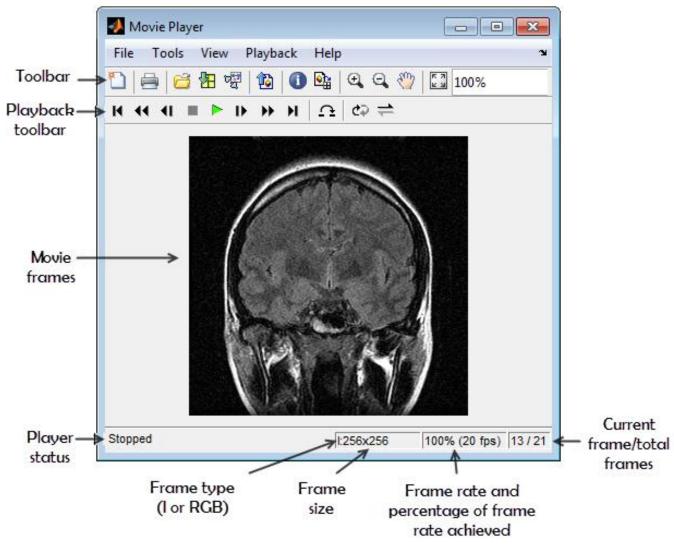


Video processing



Play video in Matlab

```
implay('rhinos.avi');
```



OpenCV

- From video file
 - VideoCapture frameSource("file name");

- Webcam
 - VideoCapture frameSource(0);

Homework topics

Topics

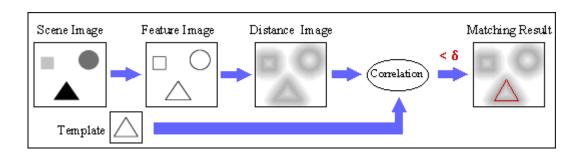
- 1. Mean-shift segmentation
- 2. K-means clustering
- 3. Graph based segmentation
- 4. Motion detection
- 5. Watershed segmentation

- 6. Corner detection
- 7. Template matching
- Distance transform
 & Chamfer matching
- 9. Hough transform& Line detection

Edge detection

- Gradient
- Edge detection
 - Sobel
- Canny algorithm

Chamfer matching



- Distance transform
- Chamfer matching
 - The Chamfer Matching Algorithm basically calculates the distance (dissimilarity) between two images. The basic idea is to:
 - Extract the edge/contours of a query image as well as target image.
 - Take one point/pixel of contour in query image and find the distance of a closest point/pixel of contour in target image.
 - Sum the distances for all edge points/pixels of query image.
 - This gives the Chamfer Distance i.e. a value of dis-similarity between two images. The lower the value better the result. take care of scaling, and sliding windows)

Segmentation

- Thresholding
- Otsu method
- K-means clustering
- Graph-based segmentation

Contact

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