
ORB-Python Documentation

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Welcome to the documentation of the **ORB-Python** project.

ORB-PYTHON-API

1.1 Devices Module

1.1.1 Sensor Class

The *Sensor* class represents a sensor device with specific parameters.

```
class devices.sensor(port: int, type: int, mode: int, mem_offset: int)
```

```
    Bases: object
```

```
    get()
```

```
    getDigital()
```

```
    getValueExt(channel: int)
```

```
    S1 = 0
```

```
    S2 = 1
```

```
    S3 = 2
```

```
    S4 = 3
```

```
    Analog = 0
```

```
    T2C = 1
```

```
    TOF = 2
```

```
    Touch = 3
```

```
    UART = 4
```

1.1.2 Motor Class

The *Motor* class represents a motor device with specific parameters.

```
class devices.motor(port: int, direction: int, ticks: int, acc: int, kp: int, ki: int)
```

```
    Bases: object
```

```
    config(direction: int, ticks: int, acc: int, kp: int, ki: int)
```

```

set(mode: int, speed: int, position: int)

get()

M1 = 0

M2 = 1

M3 = 2

M4 = 3

FORWARD = 1

REVERSE = -1

POWER_MODE = 0

BRAKE_MODE = 1

SPEED_MODE = 2

MOVETO_MODE = 3

```

1.1.3 Servo Class

The *Servo* class represents a servo device with specific parameters.

```

class devices.servo(port: int)
    Bases: object
    set(speed: int, angle: int)

    S1 = 0

    S2 = 1

```

1.2 Memory Module

```

memory.setMemory(addr: int, data: list)

memory.getMemory(addr: int, length: int) → list

memory.clearMemory()

```

1.3 Time Module

```

time.getTime() → int

time.wait(ms: int)

```

1.4 Monitor Module

`monitor.getKey()` → int

`monitor.setText(text: str)`

class `monitor.keys`

Bases: object

NO_KYE = 0

A1 = 1

A2 = 2

A3 = 3

A4 = 4

A5 = 5

A6 = 6

A7 = 7

A8 = 8

B1 = 9

B2 = 10

B3 = 11

B4 = 12

B5 = 13

B6 = 14

B7 = 15

B8 = 16

B9 = 17

B10 = 18

B11 = 19

B12 = 20

C1 = 21