

# Animation & Simulation

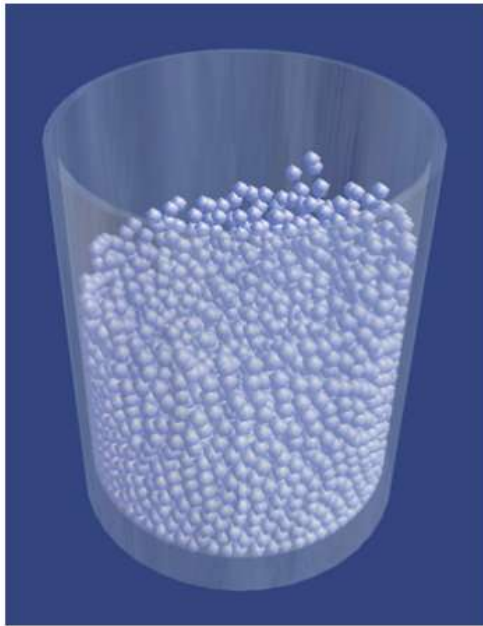
He Wang (王鹤)

# Fluids: Liquids and Gases

- Computational Fluid Dynamics (CFD, no more cheating)
  - Particle-based approach (Lagrangian)
    - Use particles to approximate mass of a fluid
    - Metaballs, simplistic
    - Smoothed particle hydrodynamics (SPH)
      - Trace particles (positions, velocities)
      - Each particle has mass, density and influence an nearby area

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# Fluids: Liquids and Gases

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  - Particle-based approach (Lagrangian) Matthias Müller, David Charypar and Markus Gross
  - Particle-based Fluid Simulation for Interactive Applications (SCA 2003)

$$\text{scalar } A_S(\mathbf{r}) = \sum_j m_j \frac{A_j}{\rho_j} W(\mathbf{r} - \mathbf{r}_j, h),$$

where  $j$  iterates over all particles,  $m_j$  is the mass of particle  $j$ ,  $\mathbf{r}_j$  its position,  $\rho_j$  the density and  $A_j$  the field quantity at  $\mathbf{r}_j$ .

$W(\mathbf{r}, h)$  is called the smoothing kernel  $\int W(\mathbf{r}) d\mathbf{r} = 1$

If we are interested in density, then

$$\rho_S(\mathbf{r}) = \sum_j m_j \frac{\rho_j}{\rho_j} W(\mathbf{r} - \mathbf{r}_j, h) = \sum_j m_j W(\mathbf{r} - \mathbf{r}_j, h)$$

If we want derivatives, then

$$\nabla A_S(\mathbf{r}) = \sum_j m_j \frac{A_j}{\rho_j} \nabla W(\mathbf{r} - \mathbf{r}_j, h)$$

$$\nabla^2 A_S(\mathbf{r}) = \sum_j m_j \frac{A_j}{\rho_j} \nabla^2 W(\mathbf{r} - \mathbf{r}_j, h)$$

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$$\text{scalar } A_S(\mathbf{r}) = \sum_j m_j \frac{A_j}{\rho_j} W(\mathbf{r} - \mathbf{r}_j, h),$$

Not needed anymore, due to the derivative of the velocity field is essentially the derivative of the particle velocity,  $D\mathbf{v}/Dt$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

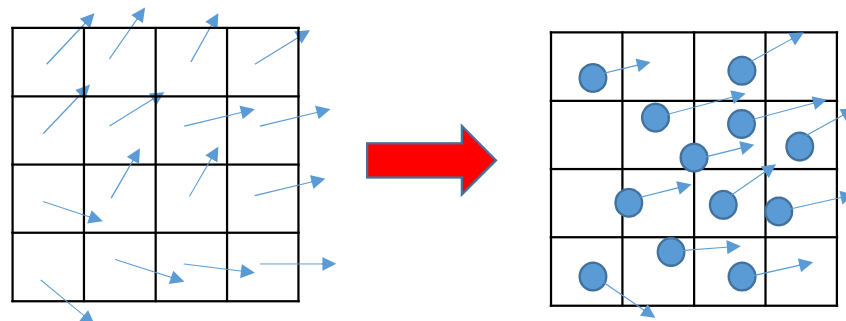
Mass conservation

Not needed anymore!

$$\rho \left( \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p + \rho \mathbf{g} + \mu \nabla^2 \mathbf{v}$$

Three forces, pressure, external force and viscosity

Momentum conservation



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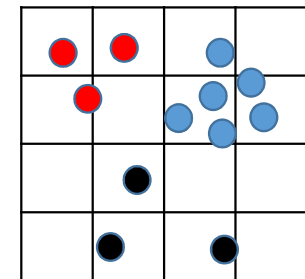
- Pressure

$$\mathbf{f}_i^{\text{pressure}} = -\nabla p(\mathbf{r}_i) = -\sum_j m_j \frac{p_j}{\rho_j} \nabla W(\mathbf{r}_i - \mathbf{r}_j, h)$$

So 
$$\mathbf{f}_i^{\text{pressure}} = -\sum_j m_j \frac{p_i + p_j}{2\rho_j} \nabla W(\mathbf{r}_i - \mathbf{r}_j, h)$$

Not symmetric

- Normal Density
- Low Density
- High Density



Where pressure can be computed as  $p = k(\rho - \rho_0)$   $k$  is a gas constant depending on the temperature

Rest density, manually defined

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Three forces, pressure, external force and viscosity

- Viscosity

$$\mathbf{f}_i^{\text{viscosity}} = \mu \nabla^2 \mathbf{v}(\mathbf{r}_i) = \mu \sum_j m_j \frac{\mathbf{v}_j}{\rho_j} \nabla^2 W(\mathbf{r}_i - \mathbf{r}_j, h)$$

Since viscosity only depends on the velocity differences

$$\mathbf{f}_i^{\text{viscosity}} = \mu \sum_j m_j \frac{\mathbf{v}_j - \mathbf{v}_i}{\rho_j} \nabla^2 W(\mathbf{r}_i - \mathbf{r}_j, h)$$

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Three forces, pressure, external force and viscosity

- Surface tension, (not in the equation, why?)
  - The equation is for internal where attributes are equal in all directions



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Three forces, pressure, external force and viscosity

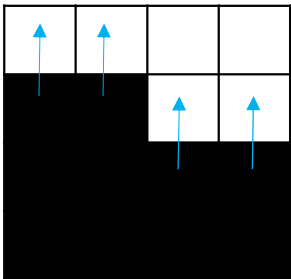
- Surface tension
  - A field with 1 wherever there is fluid and 0 otherwise, colour field  $c$

$c_S(\mathbf{r}) = \sum_j m_j \frac{1}{\rho_j} W(\mathbf{r} - \mathbf{r}_j, h)$  then its gradient  $\mathbf{n} = \nabla c_s$  yields the surface normal pointing into the grid  
its divergence gives curvature

$$\kappa = \frac{-\nabla^2 c_s}{|\mathbf{n}|}$$

$$\mathbf{f}^{\text{surface}} = \sigma \kappa \mathbf{n} = -\sigma \nabla^2 c_s \frac{\mathbf{n}}{|\mathbf{n}|}$$

The minus is necessary to get positive curvature for convex fluid volumes



Black cells: 1, White cells: 0

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Three forces, pressure, external force and viscosity

- External forces
  - Constant, e.g. gravity
  - Changing, user interaction

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Three forces, pressure, external force and viscosity

- Kernel functions  $W(r, h) \rightarrow h$  is radius, manually set.
  - Stability, accuracy and speed highly dependent on the choice of  $W$
  - Smooth functions are good
  - Vanishing derivatives at the boundary tends to more stable

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Three forces, pressure, external force and viscosity

- Kernel functions  $W(r, h)$ , general purpose

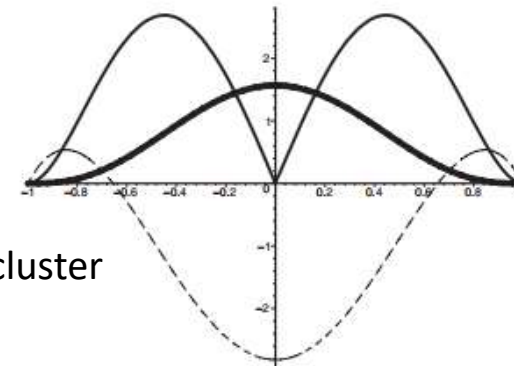
$$W_{\text{poly6}}(\mathbf{r}, h) = \frac{315}{64\pi h^9} \begin{cases} (h^2 - r^2)^3 & 0 \leq r \leq h \\ 0 & \text{otherwise} \end{cases}$$

Not for computing pressure force as particles can cluster

Why? (hint: gradient near zero)

$$\mathbf{f}_i^{\text{pressure}} = - \sum_j m_j \frac{p_i + p_j}{2\rho_j} \nabla W(\mathbf{r}_i - \mathbf{r}_j, h)$$

Thick line: function, thin line: gradient, dashed: Laplacian



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Three forces, pressure, external force and viscosity

- Kernel functions  $W(r, h)$ , for pressure

For pressure force

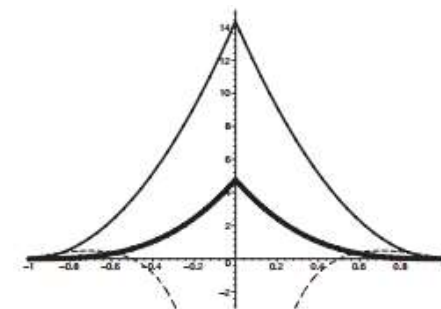
$$W_{\text{spiky}}(\mathbf{r}, h) = \frac{15}{\pi h^6} \begin{cases} (h-r)^3 & 0 \leq r \leq h \\ 0 & \text{otherwise,} \end{cases}$$

First, Laplacian vanishes at boundaries

However, do not work for viscosity, why? (hint: Laplacian near zero)

$$\mathbf{f}_i^{\text{viscosity}} = \mu \sum_j m_j \frac{\mathbf{v}_j - \mathbf{v}_i}{\rho_j} \nabla^2 W(\mathbf{r}_i - \mathbf{r}_j, h)$$

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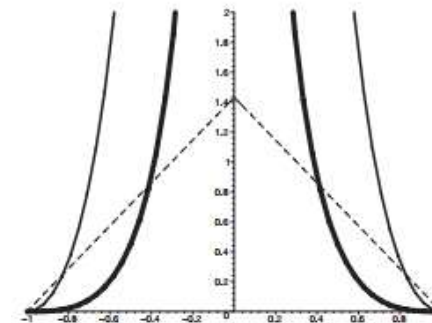
- Kernel functions  $W(r, h)$ , for viscosity
  - Viscosity, needs Laplacian to be positive to reduce relative speeds

$$W_{\text{viscosity}}(\mathbf{r}, h) = \frac{15}{2\pi h^3} \begin{cases} -\frac{r^3}{2h^3} + \frac{r^2}{h^2} + \frac{h}{2r} - 1 & 0 \leq r \leq h \\ 0 & \text{otherwise.} \end{cases}$$

$$\nabla^2 W(\mathbf{r}, h) = \frac{45}{\pi h^6} (h - r)$$

$$W(|\mathbf{r}| = h, h) = 0$$

$$\nabla W(|\mathbf{r}| = h, h) = \mathbf{0}$$



Thick line: function, thin line: gradient, dashed: Laplacian

# Fluids: Liquids and Gases

- Computational Fluid Dynamics (CFD, no more cheating)
  - Particle-based approach (Lagrangian)
    - Integration (leapfrog)

$$\begin{aligned}\mathbf{v}_i^{n+1/2} &= \mathbf{v}_i^n + \mathbf{a}_i^n \frac{\Delta t}{2}, \\ \mathbf{r}_i^{n+1} &= \mathbf{r}_i^n + \mathbf{v}_i^{n+1/2} \Delta t, \\ \mathbf{v}_i^{n+1} &= \mathbf{v}_i^{n+1/2} + \mathbf{a}_i^{i+1} \frac{\Delta t}{2}.\end{aligned}$$

- Implementation tricks
  - Use a grid with cell of size  $h$ , to limit search within one cell and its neighbours.
  - Use the colour field and its gradient to identify surface particles, with threshold  $l$   
 $|\mathbf{n}(\mathbf{r}_i)| > l$ ,  $-\mathbf{n}(\mathbf{r}_i)$  Is the direction of the surface normal at particle  $i$
  - Visualising the surface (you don't have to do this in the coursework)
    - Point splatting (Zwicker et al., In Proceedings of the 28th annual conference on Computer graphics and interactive techniques)
    - Marching cubes

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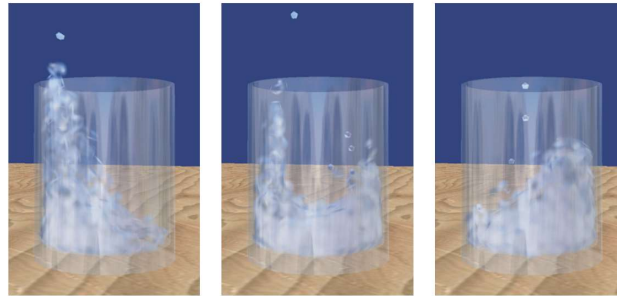


Figure 4: *The user interacts with the fluid causing it to splash.*



Figure 5: *Pouring water into a glass at 5 frames per second.*



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  - Particle-based approach (Lagrangian)
    - Fast
    - Less accurate, more difficult to extract surface geometries (e.g Marching Cubes)