# Machine Learning for Data Science (CS4786) Lecture 7

Non-Linear Dimensionality Reduction

Feb 23, 2016

Course Webpage:

http://www.cs.cornell.edu/Courses/cs4786/2016sp/

## ANNOUNCEMENT

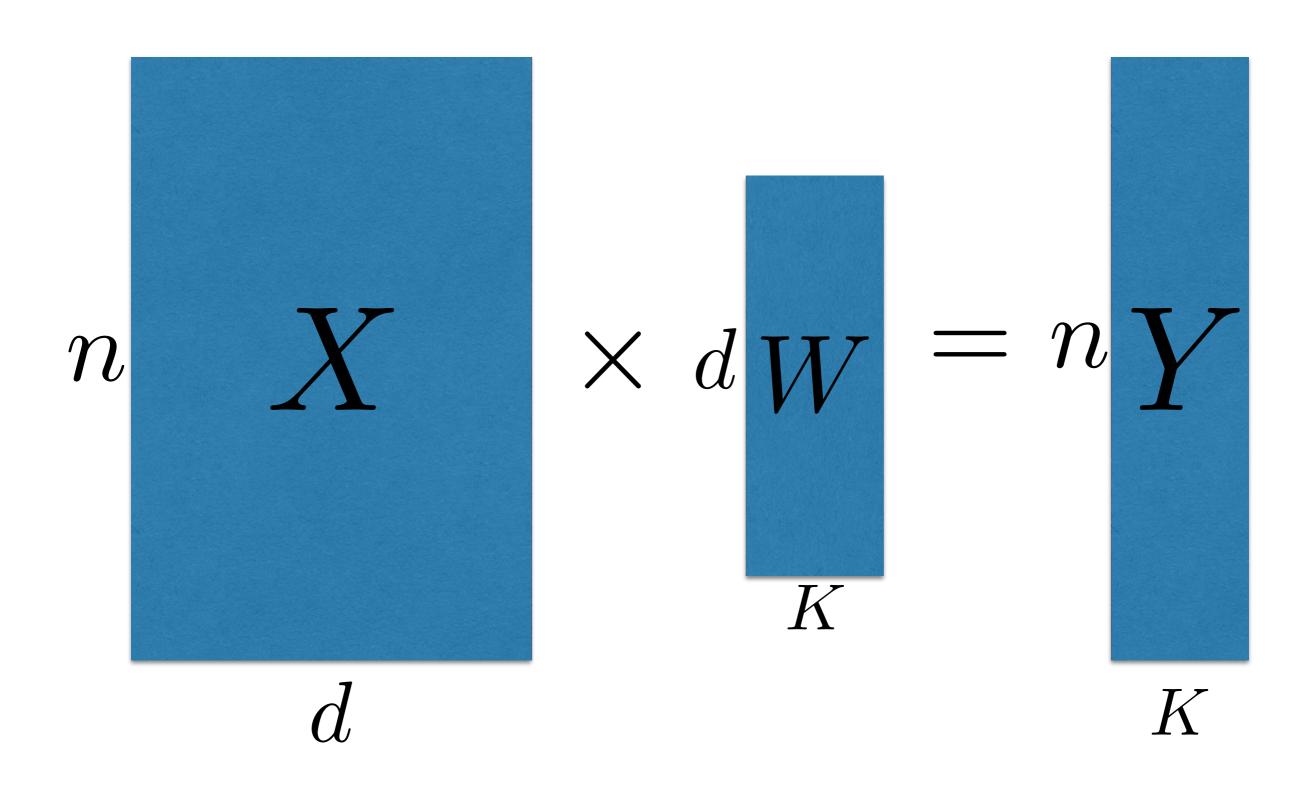
- Students added to CMS according to assignment 0.
  - If you submitted Assignment 0 and were enrolled but not added to CMS email either me or TA's
  - Collect commented assignments back from the hand-back room.

#### ANNOUNCEMENT

- Assignment 1 is out. Due on 7th March, 2016 at 11:59PM.
- Form groups early in CMS and get started early!
- Three questions, one on PCA, one on CCA and one on random projection Vs PCA.
- Hw1.pdf has the questions and instructions
- a1.zip has all the data files.

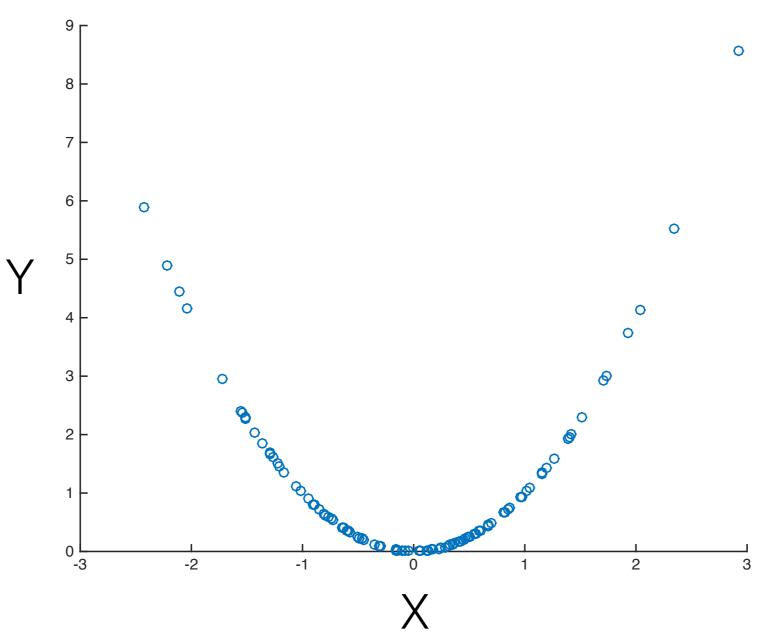
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## LINEAR PROJECTIONS



Works when data lies in a low dimensional linear sub-space

### EXAMPLE



Data is indeed one dimensional!

## LINEAR PROJECTIONS (RIGHT CO-ORDINATES)

## Demo

#### A FIRST CUT

• Given  $\mathbf{x}_t \in \mathbb{R}^d$ , vector

$$\Phi(\mathbf{x}_t) = (\mathbf{x}_t[1], \dots, \mathbf{x}_t[d], \mathbf{x}_t[1] \cdot \mathbf{x}_t[1], \mathbf{x}_t[1] \cdot \mathbf{x}_t[2], \dots, \mathbf{x}_t[d] \cdot \mathbf{x}_t[d], \dots)^{\top}$$

- Enumerating products up to order K (ie. products of at most K coordinates) we can get degree K polynomial non-linearity.
- However dimension blows up as  $d^{K}$
- Is there a way to do this without enumerating  $\Phi$ ?

#### KERNEL TRICK

- Essence of Kernel trick:
  - If we can write down an algorithm only in terms of  $\Phi(\mathbf{x}_t)^{\mathsf{T}}\Phi(\mathbf{x}_s)$  for data points  $\mathbf{x}_t$  and  $\mathbf{x}_s$
  - Then we don't need to explicitly enumerate  $\Phi(\mathbf{x}_t)$ 's but instead, compute  $k(\mathbf{x}_t, \mathbf{x}_s) = \Phi(\mathbf{x}_t)^T \Phi(\mathbf{x}_s)$  (even if  $\Phi$  maps to infinite dimensional space)
- Example: RBF kernel  $k(\mathbf{x}_t, \mathbf{x}_s) = \exp(-\sigma ||\mathbf{x}_t \mathbf{x}_s||_2^2)$
- Kernel function measures similarity between points.

•  $k^{\text{th}}$  column of W is eigenvector of covariance matrix That is,  $\lambda_k W_k = \Sigma W_k$ . Rewriting, for centered X

$$\lambda_k W_k = \frac{1}{n} \left( \sum_{t=1}^n \mathbf{x}_t \mathbf{x}_t^{\mathsf{T}} \right) W_k = \frac{1}{n} \sum_{t=1}^n \left( \mathbf{x}_t^{\mathsf{T}} W_k \right) \mathbf{x}_t$$

 $W_k$ 's can be written as linear combination of  $\mathbf{x}_t$ 's, as

$$W_k = \sum_{t=1}^n \alpha_k[t] \mathbf{x}_t$$

where 
$$\alpha_k[t] = \frac{1}{\lambda_k n} \left( \mathbf{x}_t^{\mathsf{T}} W_k \right)$$

- First note that  $\mathbf{y}_i[k] = \mathbf{x}_i^{\mathsf{T}} W_k = \sum_{t=1}^n \alpha_k[t] \mathbf{x}_i^{\mathsf{T}} \mathbf{x}_t$
- For any  $i, k \in [n]$ ,  $\lambda_k \mathbf{x}_i^{\mathsf{T}} W_k = \mathbf{x}_i^{\mathsf{T}} \Sigma W_k$  and so,

$$\lambda_{k} \sum_{t=1}^{n} \alpha_{k}[t] \mathbf{x}_{i}^{\mathsf{T}} \mathbf{x}_{t} = \lambda_{k} \mathbf{x}_{i}^{\mathsf{T}} W_{k} = \mathbf{x}_{i}^{\mathsf{T}} \Sigma W_{k}$$

$$= \frac{1}{n} \mathbf{x}_{i}^{\mathsf{T}} \left( \sum_{t=1}^{n} \mathbf{x}_{t} \mathbf{x}_{t}^{\mathsf{T}} \right) W_{k}$$

$$= \frac{1}{n} \mathbf{x}_{i}^{\mathsf{T}} \left( \sum_{t=1}^{n} \mathbf{x}_{t} \mathbf{x}_{t}^{\mathsf{T}} \right) \left( \sum_{s=1}^{n} \alpha_{k}[s] \mathbf{x}_{s} \right)$$

$$= \frac{1}{n} \sum_{s=1}^{n} \alpha_{k}[s] \sum_{t=1}^{n} (\mathbf{x}_{i}^{\mathsf{T}} \mathbf{x}_{t}) (\mathbf{x}_{t}^{\mathsf{T}} \mathbf{x}_{s})$$

• Let  $\tilde{K}$  be an  $n \times n$  matrix such that

$$\tilde{K}_{s,t} = \mathbf{x}_s^{\mathsf{T}} \mathbf{x}_t$$

Rewriting from previous slide,

$$\lambda_k \sum_{t=1}^n \alpha_k[t] \tilde{K}_{t,i} = \frac{1}{n} \sum_{s=1}^n \alpha_k[s] \sum_{t=1}^n \tilde{K}_{i,t} \cdot \tilde{K}_{t,s}$$

In other words,  $\lambda_k \tilde{K} \alpha_k = \frac{1}{n} \left( \tilde{K} \times \tilde{K} \right) \alpha_k$  and so,  $\lambda_k \alpha_k = \frac{1}{n} \tilde{K} \alpha_k$ . That is,  $\alpha_k$  is in the direction of the eigen vector of  $\tilde{K}$ .

• Further, since  $W_k$  is unit norm,

$$1 = \|W_k\|_2^2 = \left(\sum_{t=1}^n \alpha_k[t] \mathbf{x}_t\right)^\top \left(\sum_{s=1}^n \alpha_k[s] \mathbf{x}_s\right) = \alpha_k^\top \tilde{K} \alpha_k = n\lambda_k \alpha_k^\top \alpha_k$$

Hence  $\|\alpha_k\|^2 = \frac{1}{n\lambda_k}$  which is the inverse of eigen value of  $\tilde{K}$ 

Finally notice that

$$\mathbf{y}_{i}[k] = \mathbf{x}_{i}^{\mathsf{T}} W_{k} = \sum_{t=1}^{n} \boldsymbol{\alpha}_{k}[t] \tilde{K}_{t,i}$$

#### PCA REWRITTEN

- If we only need to compute projections of data points, its enough to have access to matrix  $\tilde{K}$  (a  $n \times n$  matrix)
- Projection computed by computing top eigen vectors of  $\vec{K}$
- Rescaling them by inverse of the square-root of corresponding eigen values
- Projection obtained by taking product of the top eigen vectors with matrix  $\tilde{K}$

#### KERNEL PCA

- If we want to port PCA to kernel PCA, we need to be able to write  $\tilde{K}$  in terms of kernel functions.
- We assumed centered data, so

$$\tilde{K}_{s,t} = \left(\Phi(\mathbf{x}_t) - \frac{1}{n} \sum_{u=1}^n \Phi(\mathbf{x}_u)\right)^{\top} \left(\Phi(\mathbf{x}_s) - \frac{1}{n} \sum_{u=1}^n \Phi(\mathbf{x}_u)\right)$$

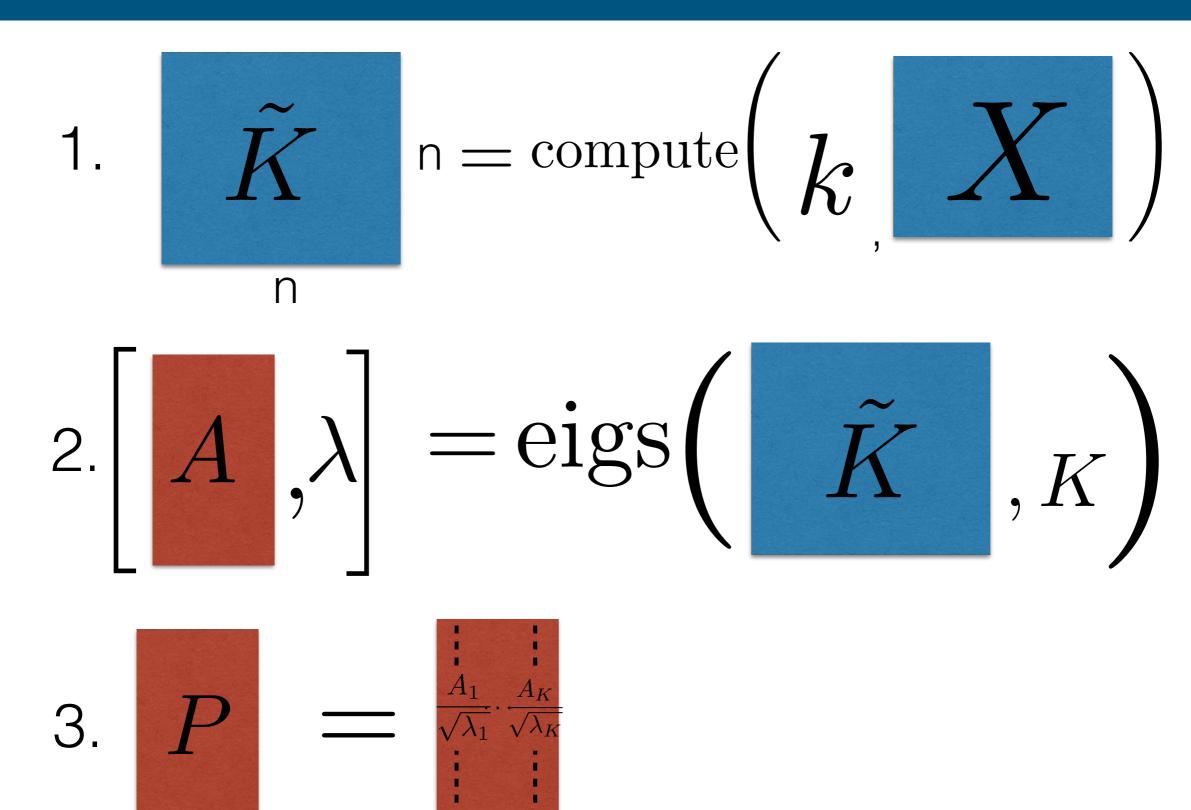
$$= \Phi(\mathbf{x}_t)^{\top} \Phi(\mathbf{x}_s) - \frac{1}{n} \sum_{u=1}^n \Phi(\mathbf{x}_u)^{\top} \Phi(\mathbf{x}_s) - \frac{1}{n} \sum_{u=1}^n \Phi(\mathbf{x}_u)^{\top} \Phi(\mathbf{x}_t)$$

$$+ \frac{1}{n^2} \sum_{u=1}^n \Phi(\mathbf{x}_u)^{\top} \left(\sum_{v=1}^n \Phi(\mathbf{x}_v)\right)$$

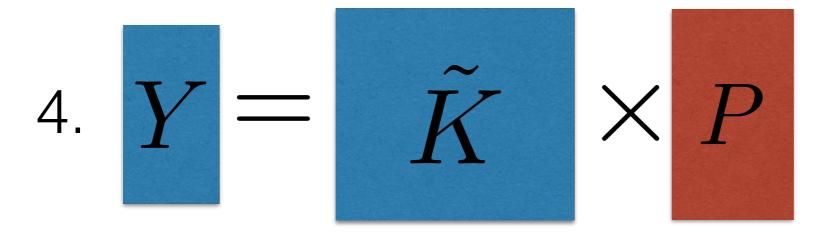
$$= k(\mathbf{x}_t, \mathbf{x}_s) - \frac{1}{n} \sum_{u=1}^n k(\mathbf{x}_u, \mathbf{x}_s) - \frac{1}{n} \sum_{u=1}^n k(\mathbf{x}_u, \mathbf{x}_t) + \frac{1}{n^2} \sum_{u=1}^n \sum_{v=1}^n k(\mathbf{x}_u, \mathbf{x}_v)$$

Knowing kernel function, we can perform Kernel PCA even when
 maps to infinite dimensional space!

#### KERNEL PCA



### KERNEL PCA



## Demo