

# Using Graph Databases to Explore Genetic Programming Run Dynamics

Nicholas Freitag McPhee, David Donatucci, and Thomas Helmuth and others(?)

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**Key words:** keywords to your chapter, these words should also be indexed

## 1 Introduction

It is common practice in most empirical evolutionary computation (EC) research to perform numerous (possibly hundreds) of runs, and then simply report a handful of aggregate statistics at the end that are expected to summarize and represent the (hopefully) complex interactions and dynamics of those many runs. Tables present values such as mean or median best fitnesses at the end of runs, collapsing the complexities of dozens or hundreds of runs into a single number, possibly with a standard deviation or (even better) a confidence interval to give a sense of the distribution. Often more informative are plots, which can, for example, show how these numbers change over time during the runs, possibly giving a sense of the system

It would be nice to scrape, say, the GECCO 2014 proceedings and get some numbers to back this up.

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dynamics. These plots, however, often aggregate runs in a way that obscure important moments that, if explored, might reveal valuable insight into the evolutionary dynamics being reported.

An alternative would be to collect, store, and analyze at least some of the rich panoply of evolutionary and genealogical events that make up the vital low-details details of these runs. Databases provide a natural tool for storing and accessing the data, but traditional relational databases are poorly suited for a variety of queries that are important for the genealogical analysis we need for exploring the evolutionary dynamics of our EC runs. If, for example, we have a `ParentChild` table, it's easy enough to find Alice's parents. Finding Alice's grandparents, siblings, or cousins, however, is less straightforward, with queries becomes increasingly difficult as we move farther out across the relationship tree.

In this chapter we illustrate the use of graph databases as an alternative storage and analysis tool for evolutionary computation runs. In Donatucci et al (2014) we have demonstrated that graph databases can be an effective tool for analyzing complex genetic programming (GP) dynamics, which led directly to a proposed change to standard sub-tree crossover in tree-based GP, McPhee et al (2015). Here we will use the open source Neo4J graph database tool<sup>1</sup> to explore data from a collection of PushGP runs on several problems drawn from a benchmark collection of introductory programming problems taken from Helmuth and Spector (2015).

Note that this is *not* going to be a presentation of “traditional” “hypothesis-driven” research. It will be based on an *assumption*, namely that something interesting happens in these runs, and that we can learn useful things by exploring them in more detail, but the presentation will be fairly discursive, reflecting our back-and-forth experience of wrestling with the data. Our initial queries start from fairly obvious questions (e.g., “Why did we succeed here?”), but from there we have a dialog with data, letting the answers to early questions shape and guide our subsequent exploration. We are presenting not the tidy, sterile summary of our adventures, but the messier (but we think more informative in this context) journal of what Pickering would call our “mangle of practice” (Smith et al (2008); Pickering (1993)).

*More stuff would have to be added here, including a roadmap.*

## 2 Motivation

Consider the job of a paleontologist, who regularly reconstructs not just individuals but also species and entire phylogenetic trees on the basis of handful of teeth and bones, or even just impressions left in prehistoric mud. They rarely have DNA, so any evolutionary relationship is inherently speculative, subject to constant debate and revision. Even with detailed DNA sequences, the construction of phylogenetic trees for existing species is a challenge.

A reference for all of this phylogenetic reconstruction stuff would be useful.

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<sup>1</sup> <http://neo4j.com/>

In evolutionary computation, however, we have access to *everything*, at least in principle. Every selection, every mating, every mutation, and every crossover happens in our code and on our watch. Yet we typically throw almost all that data away, reporting just aggregate statistics and summary plots, completely failing to take advantage of our privileged position, a position most paleontologists would presumably eye with considerable envy. Not only does this seem an inherent waste, these aggregations typically obscure critical moments in the dynamics of runs which might speak volumes if explored.

While this sort of aggregate reporting is often valuable, allowing for important comparative analysis of, for example, the impact of different genetic operators, it typically fails to provide any sense of the *why*. Yes, Treatment A led to better aggregate performance than Treatment B – but what happened in the runs that led to that result? Any success at the end of a run is ultimately the intricate combination of hundreds or thousands of selections, recombinations and mutations, and if Treatment A is in some sense “better” than Treatment B, it must ultimately be because it affected all those genealogical and genetic events in some significant way, biasing them towards events that made success more likely.

Unfortunately, published research very rarely includes information that might shed light on these *why* events. We rarely see evolved programs, for example, or any kind of post-run analysis of those programs, and there is almost never any data or discussion of the genealogical history that might help us understand how a successful program actually came to be. Sometimes these events and details aren’t included for reasons of space and time; evolved programs, for example, are often extremely large and complex, and a meaningful presentation and discussion of such a program could easily take up more space than authors have available given the typical space limitations in published work. Our suspicion, however, is that another reason this sort of *why* analysis often isn’t reported is because it isn’t done, in no small part because it’s hard. As EC researchers we’re in the “privileged” position of being able to collect anything and everything that happens in a run, but that’s a potentially huge amount of data, and leaves us with two substantial problems: How to *store* the data, and how to *analyze* the data after it’s stored.

Assuming one has access to the necessary gigabytes or terabytes of storage, databases are the obvious tool for the collection of the data. Most common database structures and tools, however, don’t lend themselves to the kinds of analysis that we want and need in evolutionary computation work. Most relational and document-based databases, for example require things like complex and expensive recursive joins to trace significant hereditary lines, making this approach increasingly infeasible. In exploring the dynamics of an EC run, we’re going to want to be able to make connections across dozens or even hundreds of generations, which simply isn’t plausible with a relational database. (See Robinson et al (2013) for more on these feasibility/efficiency issues.)

*Say a little about how graph databases rock on this and that’s why we’re using them here. Also mention that Neo4J isn’t the only option out there; it just happens to be the one that we’re using.*

Perhaps include a sample plot and show how it hides things? One of Tom’s diversity or cluster plots? A synthetic plot? Maybe that’s just not necessary?

### 3 A little background on problems and tools

#### 3.1 *Neo4J and Cypher*

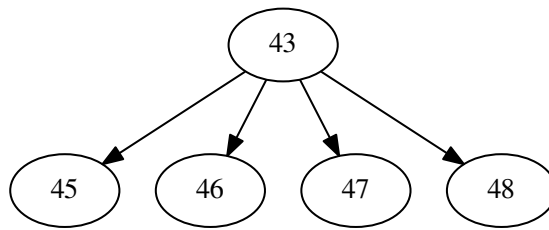
Graph databases are a relatively new approach, where data is stored as a collection of nodes and relationships in a graph, with a specialized query language that makes it easy to ask questions about complex relationships. This section further describes Neo4j, its query language Cypher, and the various advantages they hold over relational databases in recording and accessing information that relies heavily on recursion.

Neo4j is a form of data management system based upon a graph. Information is stored by means of vertices and edges, commonly referred to as nodes and relationships, respectively. In our work, nodes represent individuals, and relationships represent the transformations between individuals. As a GP system generates individuals, new nodes and relationships can be added to the database for later analysis.

Cypher allows this data to be readily extracted from the Neo4j database. There are three fundamental elements to queries in Cypher. The `START` clause specifies a starting location in the database, indicating the node or nodes where the query will begin. The `RETURN` clause specifies which nodes, relationships, or properties should be returned to the user. The `MATCH` clause is the main section of a query, specifying what patterns in the graph the query will discover. To write the `MATCH` clause, nodes and relationships are drawn with ASCII characters. A node is indicated by parenthesis `( )`, directed relationships are indicated with `-->` or `<--` depending on the direction of the relationship, and undirected relationships are indicated with `--`. Brackets `[ ]` between the dashes can be used to specify relationship names prefixed by a colon. In the example query below, the `START` clause indicates that the query should start with node 43, called `parent`, the `MATCH` clause finds all nodes that are children of the starting node, and the `RETURN` clause yields the starting node and all nodes that are children of that node.

```
START parent=node(43)
MATCH (parent)-[:PARENTOF]->(child)
RETURN parent, child;
```

Performance is the key advantage in our research of graph databases over relational databases. As the data set grows, recursive queries such as those needed to explore graph relationships become highly inefficient when using relational databases, as numerous joins are needed. In graph databases, however, the portion of the data set that must be searched is limited because the query will only search along an available path connected by relationships, allowing queries to remain efficient



**Fig. 1** Graphical representation of the results of a sample Cypher query

### ***3.2 PushGP and lexicase selection***

Say a little about

- Plush genomes
- Push programs
- Alternation
- The two kinds of mutation

Say enough about lexicase so people have some sense of why it might be interesting and different from, e.g., tournament selection.

Mention timing out and errors penalties.

### ***3.3 Replace-space-with-newline***

Say enough about this problem so that people can understand the error vectors.

## **4 Lexicase, meet Replace-space-with-newline**

We did one hundred runs of the replace-space-with-newline problem using lexicase selection, and found that 55 of these succeeded in the sense that an individual was discovered that had zero error on all 200 of the training cases. Tournament selection with tournament size 7 only had 13 successes out of 100 runs, and IFS only had 17 successes out of 100 runs, so it seems that lexicase selection provides a significant advantage here.

**Query 1** Cypher query to find all the ancestors of “winners” in the last 9 generations of a run. The pattern `(w {total_error: 0})` matches nodes with total error 0, i.e., “winners”. The pattern `(c)-[*0..7]->(w)` matches any path from some node `c` to a winning node `w` that has between 0 and 7 edges.

---

```
MATCH (p)-->(c)-[*0..7]->(w {total_error: 0})
RETURN DISTINCT id(p), id(c);
```

---

### 4.1 Hey, we won! But how did we get there?

It’s interesting the lexicase did so well, but that leaves us with the crucial question of *why*? So we chose one successful run to explore in more detail. It’s important to note here that we’re making no claims that this is a “representative” run (whatever that would even mean); it’s an *interesting* run, though, and our hope is that by understanding its dynamics better we can learn useful things about both the problem and the tools we’re applying.

An obvious place to start is at the end when the GP system solved the problem. So we used Neo4J to find all the ancestors of any “winning” individual, i.e., individual with a total error of on all 200 test cases. Using Cypher (Neo4J’s query language), we can easily ask for this subset of the population going back to generation 79 using the query in Query 1.<sup>2</sup>

Figure 2 shows the ancestry of all of the winners from generation 87 (when we first found a winner in this run) back to generation 79. Each node in the graph represents an individual, and each directed edge indicates a parent-child relationship, with the edge going from the parent to the child. The numbers inside the nodes are Neo4J internal IDs; we’ll use these as “names” for the individuals as we tell the stories we uncover.<sup>3</sup> As a happy accident coming from having a population size of 1,000, the first two digits of the Neo4J idea also happens to indicate what generation that individual was from.

Ignoring for the moment the adornments (shape, shading, etc.), there are several things that we can observe right away:

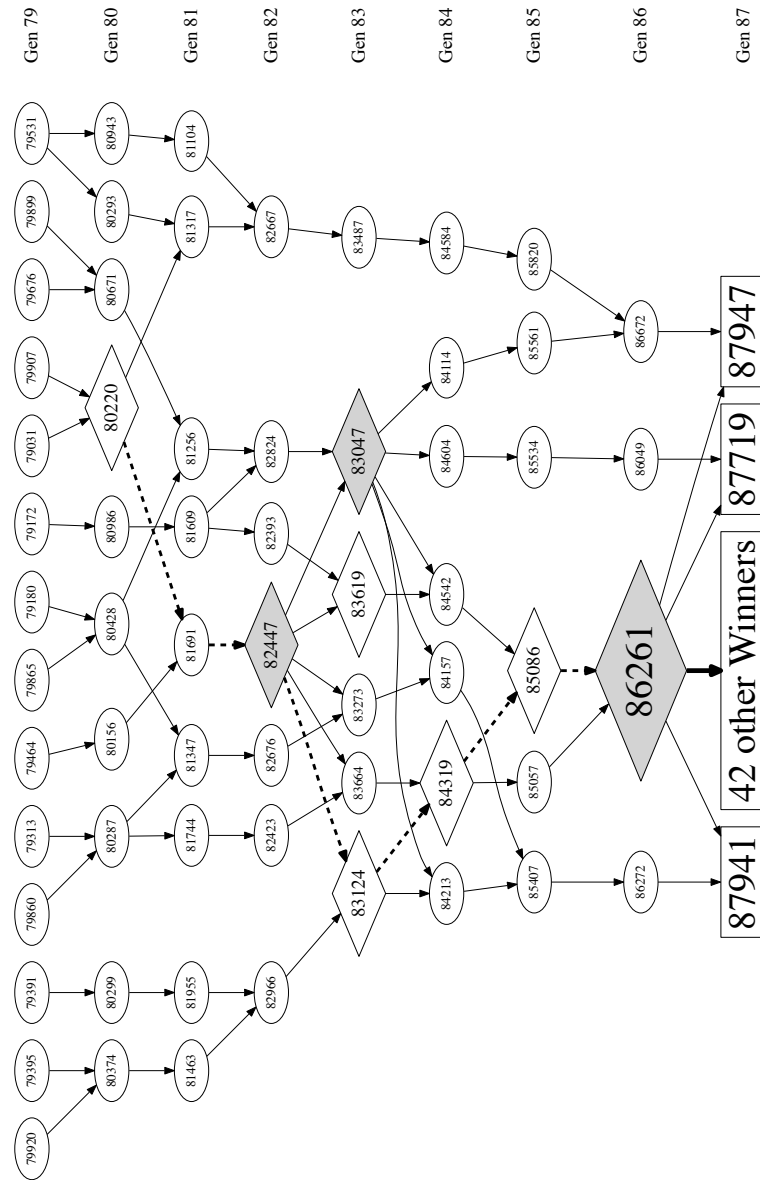
- There are 45 distinct winners in the final generation, or 4.5% of the population of 1,000 individual. This tells us that constructing a winner from the individuals in generation 86 wasn’t entirely trivial, but it also wasn’t a huge challenge and happened multiple times.
- Those 45 winners only had four distinct ancestors in the preceding generation.
- All 45 winners had a single individual (86261, marked with a large shaded diamond near the center bottom) as at least one of their parents, and 42 of them

<sup>2</sup> We could certainly have gone back farther in time, but the graph would have become impossible to read as the number of nodes would have ballooned from a few dozen to hundreds or thousands. We went back to generation 79 because that was the most recent generation that had more than 10 distinct ancestors of a winning individual.

<sup>3</sup> We actually assign each individual a UUID so we can combine multiple runs, but the Neo4J IDs are shorter and easier to use in our story telling.

Should all the query details go in an appendix that eventually becomes a tech report or some such? I’m not sure if they aren’t just a distraction here.

We need the crazy `p->c->w` thing in Query 2 to extract single edges, but I don’t know if we want to talk about that.



**Fig. 2** Ancestry of the 45 “winners” from run 6 of lexicae, replace-space-with-newline. Nodes with diamonds instead of ellipses had an unusually large number of offspring. Shaded nodes had an unusual number of offspring that were ancestors of winners. The dashed lines highlight individuals that had an unusually large number of distinct ancestry paths down to a winner. See the text for more details

**Query 2** Cypher query to find, for each ancestor  $p$  of a winner, how many distinct offspring  $n$  that ancestor  $p$ , regardless of whether  $n$  is itself an ancestor of a winner. The query then sorts by that count, and returns the 20 highest results.

---

```
MATCH (p)-->(c)-[*0..7]->(w {total_error: 0})
MATCH (p)-->(n)
RETURN DISTINCT id(p), count(DISTINCT n)
ORDER BY count(distinct n) DESC
LIMIT 20;
```

---

had 86261 as their *only* parent, i.e., they were mutations of 86261, or were the result of self-crosses of 86261. To simplify the graph, we’ve combined those 42 individuals into a single node labelled “42 Winners”.

- The number of ancestors of winners doesn’t grow quickly as we move back in time. We have to go back to generation 80 to find 10 individuals (or 1% of the population) that are ancestors of winners, and in generation 79 there are still only 14 ancestors of winners. In fact we have to go back all the way to generation 63 to find a time where over 100 individuals (or over 10% of the population) were ancestors of a winning individual.

## 4.2 Surprising fecundity (especially given that total error)

Looking at Figure 2 we can see that a few individuals have more offspring represented than others. As we’ve already mentioned, individual 86261 has 45 successful offspring, and both individuals 82447 and 83047 have five offspring in the graph, i.e., five offspring that were ancestors of a winning individual in generation 87. Each of these is marked in Figure 2 with a shaded diamond.

Figure 2, however, only tells us how many offspring an individual had that were themselves either a winner or an ancestor of a winner, as no other nodes are displayed. One might, however, wonder how many total offspring an individual has regardless of whether they were a winner or not. Query 2 identifies the most fecund ancestors of winners in these last nine generations. That reveals several results that were quite surprising to at least some of the authors, the most remarkable being that individual 86261 was a parent of 934 of the 1,000 individuals in generation 87! Given that lexicase selection was designed in significant part of spread selection events out across the population, this makes it clear that there are times when lexicase does the opposite, and instead puts nearly all its eggs in a single basket. This level of selection focus would simply be impossible using almost any other common type of selection such as tournament selection; in most uses of tournament selection, for example, no individual can be in more than a relative handful of tournaments, and thus can’t be a parent terribly often no matter how fit they are.

While no other node in Figure 2 has nearly as many children as 86261 did, there are several that had very high reproduction rates, putting them well above what



**Table 1** The total error and rank (by total error) in the population in that individual’s generation for the sequence of “diamond” individuals from in Figure 2.

Individual	Total error	Rank in population
80220	321	147
81691	441	268
82447	107	1
83124	157	85
84319	240	188
85086	100,000	971
86261	4,034	765

would be possible with something like tournament selection. Individual 82447, for example, had 443 offspring, including the 5 illustrated in Figure 2. In fact there were eight individuals in Figure 2 that have more than 100 offspring; each of these is indicated with a diamond shape instead of the standard ellipse. This highlights a particularly interesting ancestry chain from 80220 through 81691, 82447, 83124, 84319, 85086 to 86261, marked with dashed edges in Figure 2. With the exception of 81691, which “only” had 17 offspring, each of these seven individuals had more than 100 offspring, and thus had a fairly dominate role in shaping the generation that followed them.

If we look at the total error in of the individuals in Figure 2, we again find some significant surprises that tell us quite a lot about lexicase selection. In particular, if we look at the total error for each individual along the dashed path from 80220 through 82447 to 86261, the fitness of the first five individuals in the chain aren’t too surprising. One (individual 82447) has the best total error in that generation and all but 81691 (the individual with only 17 offspring) are in the top fifth of the population when ranked by total fitness. The fitnesses of the last two (the grandparent and parent of *every* one of the 45 solutions), however, came as quite a shock. In particular individual 85086 has a total error of 100,000, placing it *very near the bottom of the population by total error* (rank 971). Individual 86261, which was the parent of 924 of the 1,000 individuals in the next generation, has a total error of 4,034, placing it below 3/4 of the population in its generation by that aggregate measure.

So how could individuals with such terrible total fitness end up being selected so often as parents? Exploring the specific test case errors reveals that individual 85086 is perfect on half of the test cases (all those that involve printing), but gets a penalty error of 1,000 on the other half, presumably because it never actually returns a value. Every one of its ancestors in Table 1, however, has at least a few non-zero errors on the printing test cases, meaning that any lexicase ordering that places a few key printing test cases before any of the “return” test cases would likely select individual 85086.

What about individual 86261, with it’s 934 offspring? It is perfect (has error zero) on 194 of the 200 test cases, with it’s total error of 4,034 coming from the remaining 6 test cases. On four of these it, like individual 85086, fails to return a value and gets the penalty of 1,000; it has an error of 17 on the other two. Thus it gets

97% of the test cases correct, but happens to be *heavily* penalized for its behavior on 4 of the 6 it gets wrong. In a system that aggregates the errors, its rank of 765 out of 1,000 would mean that it would probably have no offspring. With lexibase selection, however, its success on the 194 test cases means that it is selected (from this population) almost every time. In fact only 152 of the 1,000 individuals in the final generation had a parent who *wasn't* 86261, and only 116 other individuals in generation 86 had an offspring in the next generation. While four of those had 10 or more offspring in the last generation, none of those four actually gave rise to a winner. The three parents of winners other than 86261 (individuals 86272, 86049, and 86672 in Figure 2) had very few offspring (1, 2, and 2 respectively), suggesting that they may not have contributed much (or anything) to their successful progeny, and the success of their offspring was due more to the good fortune of mating with 86261 than anything else.

### 4.3 *How exactly did we get here?*

Now that we know quite a lot about who gave rise to those 45 winners, what genetic operations brought them about? The largest group was 18 of the 45 which came about through uniform-close-mutation alone, *all* of which were mutations of individual 86261. This indicates that success can be achieved via a fairly simple modification to 86261's genome that only modifies where some code blocks end.

The other large group was 17 winners that arose via alternation followed by uniform-mutation. 14 of these were the result of a self-cross of 86261 and itself, with the other three being crosses between 86261 and the other three parents of winners (86272, 86049, and 86672). There were also two smaller groups of winners, 6 which were the result of alternation alone (all self-crosses of 86261), and 4 from uniform-mutation alone applied to 86261.

An obvious question then is What changed in moving from 86261 to the final solutions. The genomes and programs involved are fairly complex (over 200 instructions), and as mentioned in the introduction, a full analysis of the genomes and behaviors of the the individuals involved is beyond the scope of this paper. It is possible, however, and our graph database analysis has clearly identified individuals whose genomes and programs deserve additional study.

Based on our graph database work, we can also propose a hypothesis that this additional study could explore. 86261's total error of 4,034 comes in large part from failing to return a value on four test cases. A distinct possibility is that 86261 simply times out on those four test cases. The efficacy of uniform-close-mutation suggests that there might be some sequence of instructions that are being executed repeatedly via a loop or recursion, and there are uniform-close-mutations that shorten that block in ways that allow it to complete all the test cases within the time limit without changing the value returned.

## 5 So what did we learn in all this?

*Connect the following back to Section 4.2.*

Lexicase selection (?) was designed in significant part with the intent of increasing and maintaining diversity. The key assumption was that it would distribute the selection events across a variety of groups of individuals, as the population separates into sections focusing on different subsets of the test cases. As ? shows, this is to a significant degree a “true” (or at least reasonable) story, with lexicase generally leading to more diversity than either tournament selection or implicit fitness sharing.

A flip side of that assumption was that individuals probably didn’t have disproportionately large numbers of offspring, as the selections are being spread out across these different groups of individuals. In exploring one lexicase run on the Replace Space With Newlines problem, however, we discovered that while in general this story held true, there were moments in the course of the run where the reality was *wildly* different.

## 6 Section Heading

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Use the standard `equation` environment to typeset your equations, e.g.

$$a \times b = c , \tag{1}$$

however, for multiline equations we recommend to use the `eqnarray` environment.

$$\begin{array}{l} a \times b = c \\ \mathbf{a} \cdot \mathbf{b} = \mathbf{c} \end{array} \tag{2}$$

## 7.1 Subsection Heading

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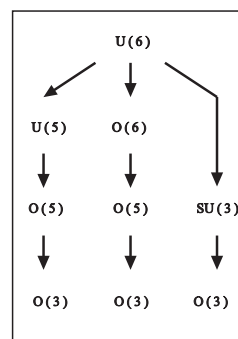
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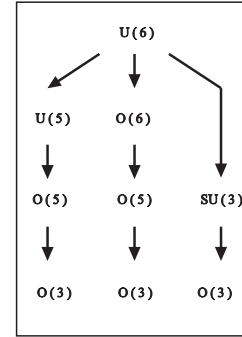
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**Fig. 3** If the width of the figure is less than 7.8 cm use the `sidecaption` command to flush the caption on the left side of the page. If the figure is positioned at the top of the page, align the sidecaption with the top of the figure – to achieve this you simply need to use the optional argument `[t]` with the `sidecaption` command



<sup>4</sup> Footnotes are easily added with this simple command.

**Fig. 4** If the width of the figure is less than 7.8 cm use the `sidecaption` command to flush the caption on the left side of the page. If the figure is positioned at the top of the page, align the sidecaption with the top of the figure – to achieve this you simply need to use the optional argument `[t]` with the `sidecaption` command



1. Livelihood and survival mobility are oftentimes coutcomes of uneven socioeco-  
nomic development.
  - a. Livelihood and survival mobility are oftentimes coutcomes of uneven socioe-  
conomic development.
  - b. Livelihood and survival mobility are oftentimes coutcomes of uneven socioe-  
conomic development.
2. Livelihood and survival mobility are oftentimes coutcomes of uneven socioeco-  
nomic development.

#### *Subparagraph Heading*

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- Livelihood and survival mobility are oftentimes coutcomes of uneven socioeco-  
nomic development, cf. Table 2.
  - Livelihood and survival mobility are oftentimes coutcomes of uneven socioe-  
conomic development.
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conomic development.
- Livelihood and survival mobility are oftentimes coutcomes of uneven socioeco-  
nomic development.

**Table 2** Please write your table caption here

Classes	Subclass	Length	Action Mechanism
Translation	mRNA <sup>a</sup>	22 (19–25)	Translation repression, mRNA cleavage
Translation	mRNA cleavage	21	mRNA cleavage
Translation	mRNA	21–22	mRNA cleavage
Translation	mRNA	24–26	Histone and DNA Modification

<sup>a</sup> Table foot note (with superscript)

## 8 Section Heading

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- Type 1 That addresses central themes pertaining to migration, health, and disease. In Sect. 6, Wilson discusses the role of human migration in infectious disease distributions and patterns.
- Type 2 That addresses central themes pertaining to migration, health, and disease. In Sect. 7.1, Wilson discusses the role of human migration in infectious disease distributions and patterns.

### 8.1 Subsection Heading

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Please note that the first line of text that follows a heading is not indented, whereas the first lines of all subsequent paragraphs are.

**Theorem 0.1.** *Theorem text goes here.*

**Definition 0.1.** Definition text goes here.

*Proof.* Proof text goes here.  $\square$

### Paragraph Heading

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**Theorem 0.2.** *Theorem text goes here.*

**Definition 0.2.** Definition text goes here.

*Proof.* Proof text goes here.  $\square$

**Acknowledgements** If you want to include acknowledgments of assistance and the like at the end of an individual chapter please use the `acknowledgement` environment – it will automatically render Springer's preferred layout.

## References

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