

Impact of Crossover Bias in Genetic Programming

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ABSTRACT

In tree-based genetic programming (GP) with sub-tree crossover, the parent contributing the root portion of the tree (the *root parent*) often contributes more to the semantics of the resulting child than the *non-root parent*. Previous research demonstrated that when the root parent had greater fitness than the non-root parent, the fitness of the child tended to be better than if the reverse were true. Here we explore the significance of that asymmetry by introducing the notion of *crossover bias*, where we bias the system in favor of having the more fit parent be the root parent.

Here we apply crossover bias to several problems. In most cases we found that crossover bias either improved performance or had no impact, but in certain circumstances adding crossover bias actually hurt performance. We also found that the effectiveness of crossover bias is dependent on the problem, and significantly dependent on other parameter choices.

While this work focuses specifically on sub-tree crossover in tree-based GP, many biological and artificial evolutionary systems have substantial asymmetries, many of which remain unstudied. This work suggests that there is probably value in exploration of the impacts of those asymmetries.

Categories and Subject Descriptors

I.2.2 [Artificial Intelligence]: Automatic Programming-Program transformation

General Terms

Algorithms

Keywords

genetic programming, crossover bias, root parent, crossover asymmetry, sub-tree crossover

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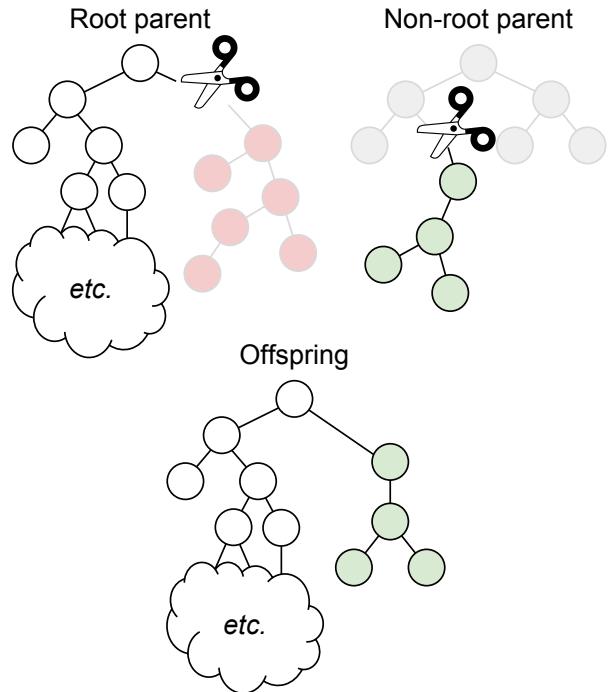


Figure 1: Sub-tree crossover, illustrating the asymmetric role of the *root* and *non-root* parents.

1. INTRODUCTION

As Figure 1 illustrates, the widely used sub-tree crossover operator in tree-based genetic programming (GP) [10] is an inherently asymmetric operation, with one parent contributing the root node and, in most cases, a substantially larger number of nodes than the other parent. This asymmetry has been noted before, e.g., [6] where they refer to the parent that contributes the root node as the *root parent* and the other parent as the *non-root parent*. It has also been previously observed [2, 5, 7] that the root parent often contributes more to the semantics of the resulting individual. This is in part because the root parent typically contributes more overall nodes, and because the nodes closest to the root of the tree frequently have a stronger impact on the result of evaluating the tree in question. While the specific impact of this asymmetry depends on the details of the function set and the particular trees chosen as parents, asymmetry has a

Algorithm 1 Crossover bias

Require: Two individuals, RP (root parent) and NRP (non-root parent), are chosen as parents.

if $\text{RANDOM}(0, 1) \leq \text{XO_bias}$ **then** \triangleright Do we force bias?

if $\text{FITNESS}(\text{RP})$ worse than $\text{FITNESS}(\text{NRP})$ **then**

RP, NRP := NRP, RP \triangleright Swap so RP is more fit

end if

end if

substantial effect on the semantics of the offspring in many common tree-based GP settings.

An important impact of this asymmetry was recently noted in [5], where they observed that the fitness of the offspring tended to improve when the root parent had better fitness than the non-root parent. To explore this further, we implemented what we refer to as *crossover bias*, which allowed us to probabilistically force the GP system to assign the individual with the greater fitness to be the root parent. In this paper, we apply crossover bias (Section 2) to a variety of test problems (Section 3). The results (Section 4) make it clear that crossover bias can have a substantial impact on the performance of GP runs, but that the results are heavily parameter dependent and, to a lesser degree problem dependent. In general, however, we find (Section 5) that incorporating some crossover bias is, at least in these problems, usually either advantageous or neutral.

2. CROSSOVER BIAS

For this work, we implemented crossover bias with a parameter specifying the probability of forcing the more fit parent to be the root parent when performing crossover, as detailed in Algorithm 1. Every time a crossover event was to be performed, we would use this probability to decide whether to force the more fit parent to be the root parent. Note that if the random value in Algorithm 1 didn't cause crossover bias to be applied, then the parents were left in their original random order, meaning that there is a 50% chance that the root parent is the more fit parent even without any crossover bias.

In this paper we focus on five levels of crossover bias:

- 0.00 bias - no crossover bias is applied;
- 0.25 bias - system forced to use the more fit parent as the root parent in 25% of cases;
- 0.50 bias - system forced to use the more fit parent as the root parent in 50% of cases;
- 0.75 bias - system forced to use the more fit parent as the root parent in 75% of cases; and
- 1.00 bias - system forced to always use the more fit parent as the root parent, sometimes referred to as "with crossover bias".

The 0.00 case, where no crossover bias is applied, is just standard sub-tree crossover, where there will be a 50% chance of the root parent being the more fit parent.

We also experimented with *reverse bias*, where the weaker parent was always forced to be the root parent. In general, the results for reverse bias revealed that there wasn't any statistically significant difference from no bias, so in the interest of simplification we've omitted reverse bias from the remainder of the paper.

Parameter	Values
Crossover bias	0, 0.25, 0.5, 0.75, and 1
Tournament size	2, 3, 5, and 7
Elitism %	0 and 1% (& sometimes 0.1%)
Population size	1,024 and 10,240
# of generations	100
# of runs per treatment	100

Table 1: Shared parameters

3. EXPERIMENTAL SETUP

To better understand the impact of crossover bias on GP performance, we experimented with five problems: K Landscapes with $K = 6$ [14], ORDERTREE [3], U.S. Change, Sine regression [10], and Pagie-1 regression [9]. Three of these (K Landscapes, ORDERTREE, and Pagie-1 regression) are taken from recent benchmark suggestions [15]. U.S. Change is a program synthesis problem that has proven interesting for evolutionary program synthesis [17], and sine regression is the example problem used in earlier work on the impact of root and non-root parents [5].

The one problem not precisely described elsewhere in the literature is the U.S. Change problem, where the task is to take as input an amount, and to return as output the minimum number of coins required to make that amount using (a subset of) standard U.S. coins with amounts 25, 10, 5, and 1. So, for example, given 118 as input, the result should be 9 since

$$4 \times 25 + 1 \times 10 + 1 \times 5 + 3 \times 1 = 118,$$

and this set of $4 + 1 + 1 + 3 = 9$ coins is the minimal set making a total of 118. Our function set for this problem was $+, -, \times, \%, {}^1\text{mod}, \text{min}$, and max . The terminal set consisted of the input x , integer ephemeral random constants taken uniformly from the range $[-50, 50]$, and the set of constants $\{0, 1, 4, 5, 9, 10, 24, 25\}$. The test cases were all inputs in the range $[0, 150)$.

All our experiments used the previously published settings, function sets, etc., with the exception of the parameters listed in Table 1,² which are shared throughout these experiments. Our evolutionary system is generational, with all new individuals being generated via subtree crossover (i.e., no mutation or reproduction) unless there is a non-zero elitism percentage. Our primary goal was to better understand the impact of crossover bias, so we performed runs with a variety of crossover bias probabilities. In addition, we wanted to see how crossover bias might interact with some other commonly manipulated parameters as listed in Table 1. Unless otherwise noted, all plots, etc., in what follows will include results from all possible combinations of values in Table 1. Each box plot in Figure 2, for example, includes the results of 100 runs for each of the combinations of all four tournament sizes, both elitism proportions, and both population sizes.

¹Protected integer division (quotient), returning 1 if the denominator is 0.

²The function set for Pagie-1 specified in [9] is simply $+, -, \times$, and $\%$ (protected division). The function set given in [4] and implemented in ECJ is "koza2", which also includes various trigonometric and logarithmic functions. The performance of GP varies substantially between the two function sets; here we follow the original Pagie-1 paper and use the simpler function set.

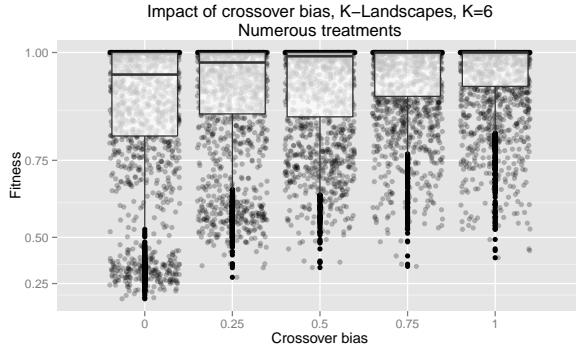


Figure 2: Impact of crossover bias on fitness for K Landscapes problem, for a variety of treatments.

Can we drop 0.1% from the table and just handle it as an exception like Tarpeian?

As Section 4 shows, there were some quite substantial interactions between crossover bias and some of the other parameter settings. In particular, we found that there are parameter values where crossover bias appears to have a substantial and significant impact, and other parameter settings where crossover bias has almost no effect on the results. Based on these observed patterns, we found it useful to identify two specific subsets of the parameter settings listed in Table 1: “*bias-effective settings*” and “*non-bias-effective settings*”. The bias-effective settings are binary tournaments, no elitism, and population size of 10,240; the non-bias-effective settings, conversely, are tournament size 7, non-zero elitism percentage, and population size 1,024. These terms will be used in the remainder of the paper, which will also include some discussion of why crossover bias might interact with these parameters in this way.

All experiments were run using a copy of ECJ 21³ that we modified to support crossover bias.

4. RESULTS

All tests of differences in fitness or hits in this section are performed using pairwise Wilcoxon tests with Holm corrections. Tests of differences in the number of successes are performed using pairwise tests of proportions (chi-squared) with Holm corrections. All statistics calculations were performed with R [12] and plots were generated using the ggplot2 package [16].

4.1 K Landscapes

Figure 2 shows the impact of crossover bias on this problem across all the combinations of parameter values in Table 1. Increasing the amount of crossover bias consistently improves the fitness of the results. All the differences are statistically significant ($p < 0.012$) except for the difference between bias probability 0.75 and 1.00.

Compare this to the results shown in Figure 3, which plots the same data separated out by tournament size. It is clear that for binary tournaments, increasing the crossover bias probability continues to improve the fitness – all the differences are strongly statistically significant ($p < 6 \times 10^{-8}$).

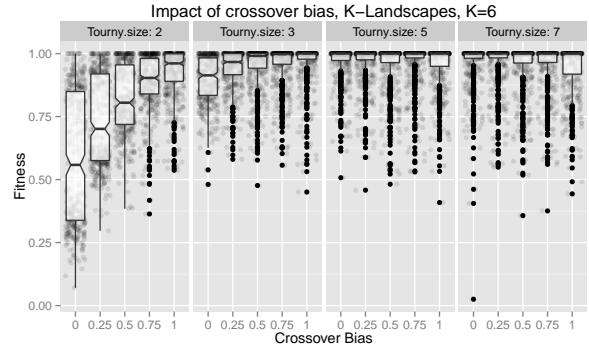


Figure 3: Impact of crossover bias on fitness for K Landscapes problem, for various tournament sizes.

This continues to be true for tournament size 3; all the differences are statistically significant except for those between bias 0.50 and 0.75, which was very close ($p = 0.05620$). None of the differences for tournament size 5 are significant. For tournament size 7, however, it does look like the reverse is true, where increasing crossover actually hurts fitness. Almost none of the differences for tournament size 7 are statistically significant, however, with the only exception being the difference between 0.25 and 1.00 ($p = 0.21$).

Nic needs to check the $p=0.21$ above since that clearly isn't significant. Either Nic was confused, or the number should be 0.021.

Take hyphen out of K Landscapes graph titles, and remove K=6.

Figure 4 filters out only the data gathered using the bias-effective treatment, discussed in Section 3. It is clear that the impact of crossover bias is much stronger in this case than in the more general case shown in Figure 2. Here all the differences are strongly statistically significant ($p < 10^{-11}$). In addition to improvements in fitness, increasing the crossover bias also increases the number of “perfect” solutions discovered. Out of 100 runs with a crossover bias setting of 1.00, 15 of these runs resulted in the discovery of a “perfect” solution. By comparison, only 1 or 2 runs out of 100 resulted in “perfect” solutions for each of the other crossover bias probabilities. This difference is statistically significant with $p \leq 0.03$.

4.2 ORDERTREE

It should be noted that, for the ORDERTREE problem we used the full set of parameters outlined in Section 3, with one exception: the population size for the ORDERTREE runs was limited to 1,024. This was a consequence of the large trees generated for this problem, resulting in out of memory errors for the larger population size of 10,240.

Initial runs of this problem with (1.00) and without (0.00) crossover bias across all four tournament sizes demonstrated that in each case, adding crossover bias improved fitness. Additionally, these improvements were statistically significant ($p < 0.002$).

Figure 5 generalizes this to cover the full range of crossover bias percentages, and shows a more complex picture. For binary tournaments, we observed a drop in fitness from bias 0.75 to bias 1.00, where the fitness for 1.00 is actually slightly below that for 0.50 as well. All these differences are statis-

³<http://cs.gmu.edu/~eclab/projects/ecj/>

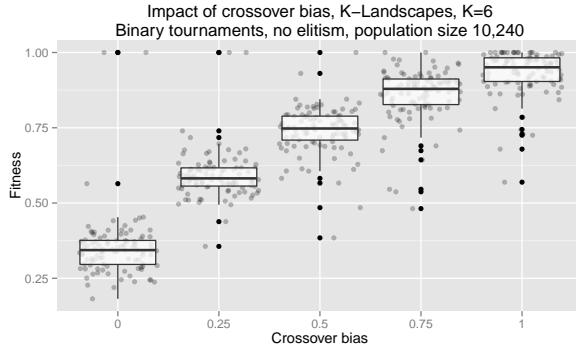


Figure 4: Impact of crossover bias on fitness for K Landscapes problem, restricted to bias-effective parameter settings.

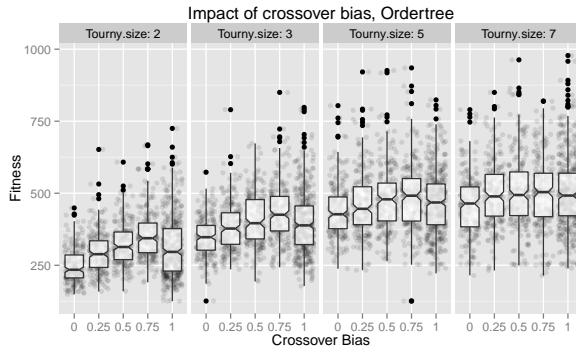


Figure 5: Impact of crossover bias on fitness for ORDERTREE problem for multiple tournament sizes.

tically significant ($p < 0.03$), with the exception of the difference between bias 0.25 and bias 1.00, so bias 0.75 is the clear winner in this scenario. This drop in fitness for bias 1.00 is consistent across the other three tournament sizes as well. However, it is also apparent from the figure that in general the impact of crossover bias lessens with the larger tournament sizes, both in the increase in fitness up to bias 0.75, and the drop from there to bias 1.00.

Change caps on ORDERTREE in figure titles.

4.3 U.S. Change Problem

In contrast to the structural problems discussed in the previous section, which used fitness as the measure of success of a run, for the U.S. Change problem we measured success in “hits” (the number of test cases that are correctly solved). There are 150 test cases in our implementation, so an optimal program will have a score of 150 hits.

Figure 6 shows the impact of crossover bias on the number of hits for the U.S. Change problem across the full collection of parameter settings. This suggests that in general there is little consistent impact of crossover bias; while most of the differences in this plot are not statistically significant, two are: the differences between crossover bias 0.00 and crossover bias 0.50 and 0.75 are both statistically significant ($p \leq 0.015$), even if numerically small.

However, if we limit our attention to the bias-effective

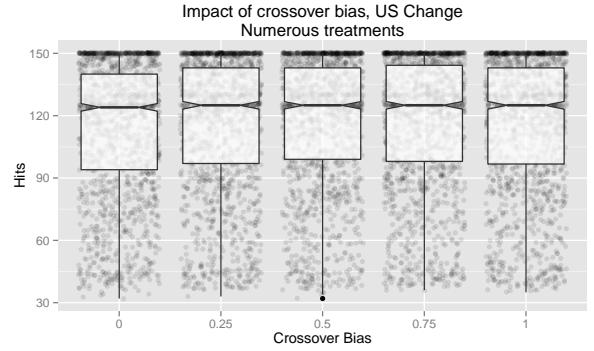


Figure 6: Impact of crossover bias on the number of hits for the U.S. Change problem across a variety of treatments.

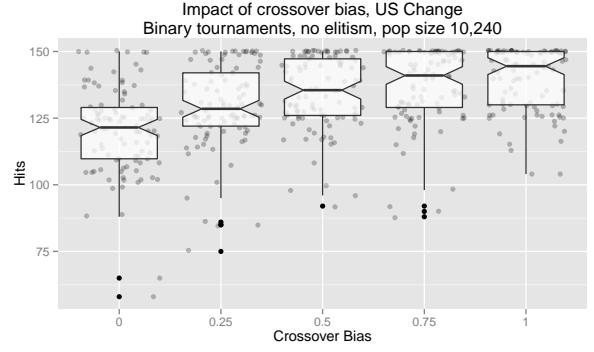


Figure 7: Impact of crossover bias on the number of hits for the U.S. Change problem, limited to bias-effective parameters.

parameter settings (Section 3), then we find that crossover bias has a substantial and statistically significant impact, as is seen in Figure 7. Here the bulk of these pairwise differences are statistically significant ($p < 0.0002$). The major exception is the difference between crossover bias 0.75 and 1.00 ($p = 0.43078$). Two other adjacent pairs have p -values slightly above 0.05: crossover bias 0.25 vs 0.50 ($p = 0.05036$), and 0.50 vs 0.75 ($p = 0.08019$).

If complete success was considered vital (which might be the case if we were evolving software for use in a production system), then it would make sense to see if crossover bias has a significant impact on the success rate. Figure 8 shows the number of successes for the various crossover bias values when using the bias-effective parameter settings. None of the adjacent differences (for example, crossover bias 0.50 vs 0.75) are statistically significant, while most of the non-adjacent differences (for example, crossover bias 0.25 vs 0.75) are statistically significant, with the exceptions being crossover bias 0.00 vs 0.50, and bias 0.50 vs 1.00 ($p = 0.09361$ in both cases).

4.4 Page-1 Problem

In addition to the parameters outlined in Section 3, the Page-1 problem was also run both with and without Tarpeian bloat control.

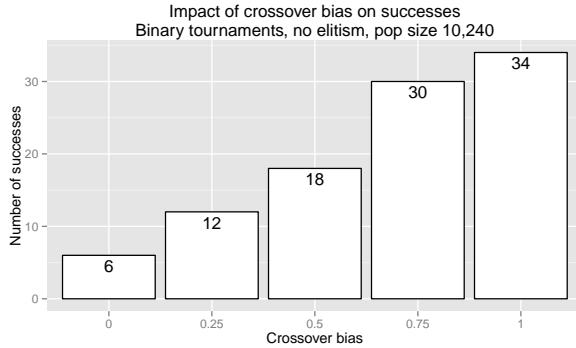


Figure 8: Impact of crossover bias on the number of successes runs for the U.S. Change problem when using to bias-effective parameters.

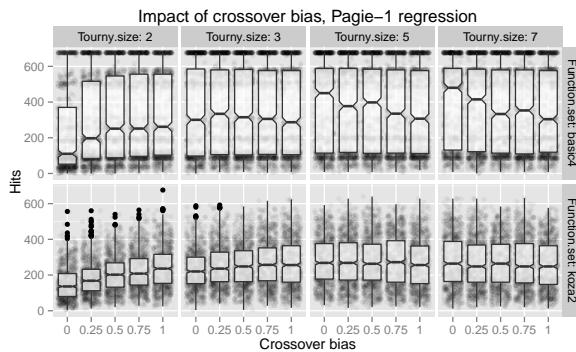


Figure 9: Impact of crossover bias on the number of hits for the Pagie-1 symbolic regression problem, broken out across the four different tournament sizes. The maximum number of possible hits is 676.

Figure 9 shows the impact of crossover bias on the number of hits for the Pagie-1 regression problem, separated out by both tournament size and function set used. The results, as can be seen in Figure 9, vary significantly. However, if limited to population size 10,240 and no elitism then the complexities of Figure 9 simplify to Figure 10.

Focusing on the binary tournament data in Figure 10, the differences between crossover bias 0.00 (standard subtree crossover) and all the other positive crossover bias values are statistically significant ($p < 10^{-12}$), and all of the differences between crossover bias 0.25 and higher biases are significant ($p < 0.007$); however, none of the differences among 0.50, 0.75, and 1.00 are statistically significant. None of the differences for tournament sizes 3, 5, or 7 are statistically significant, although the difference between crossover biases 0.00 and 1.00 are very close ($p = 0.053$) for tournament size 7. This indicates that for binary tournaments, including crossover bias substantially and significantly improves the hit rate, although all bias rates above 0.25 are very similar. For tournament size 7, however, it appears that adding crossover bias tends to reduce the hit rate, although in a less substantial and significant manner.

Figure 11 shows the number of successes (runs that exactly solve the problem). Almost none of these differences

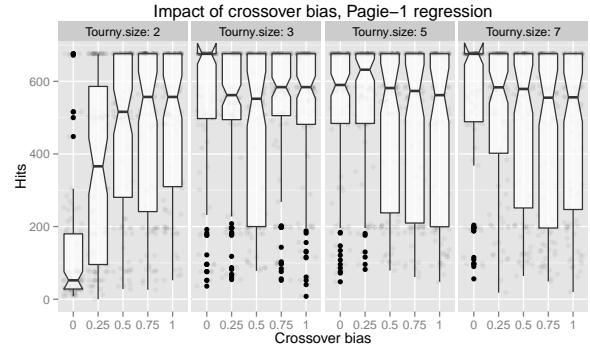


Figure 10: Impact of crossover bias on the number of hits for the Pagie-1 symbolic regression problem, broken out by tournament size. These runs use no elitism, population size 10,240, and Tarpeian bloat control.

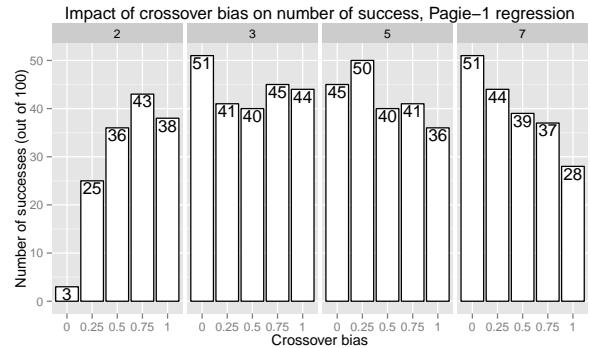


Figure 11: Impact of crossover bias on the number of successes (runs that exactly solve the problem) for the Pagie-1 symbolic regression problem broken out by tournament size (2, 3, 5, and 7). These runs use the “basic4” function set (just $+$, $-$, \times , \div), no elitism, population size 10,240, and Tarpeian bloat control.

are statistically significant, with the major exception being the small number of successes (3) for binary tournaments without bias, which is significantly different from all the other bias values for binary tournaments ($p < 0.0002$). The one other exception is for tournament size 7, the difference between the number of successes with crossover biases 0.00 and 1.00 is significant ($p = 0.015$).

4.5 Sine Problem

For the sine regression problem, we limited our runs to bias-effective and non-bias-effective settings as discussed in detail in Section 3.

Figure 12 shows the hits results for the sine regression problem using bias-effective settings. All these differences are statistically significant ($p < 10^{-5}$) except for the difference between the bias of 0.75 and 1.00. Figure 14 also shows the impact of crossover bias over time when using the bias-effective settings; the fitnesses are consistently different throughout the time of the runs, although the differences are

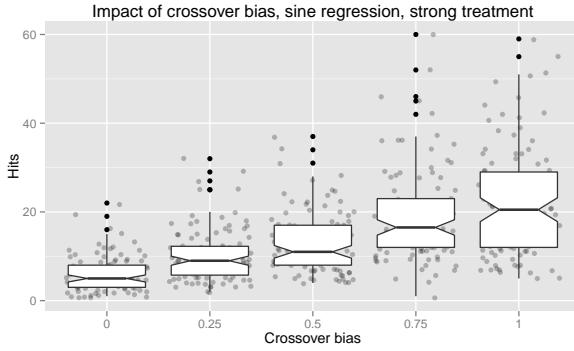


Figure 12: Impact of crossover bias on the sine symbolic regression problem with bias-effective settings.

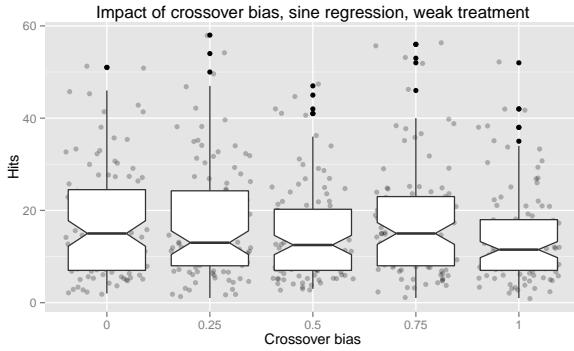


Figure 13: Impact of crossover bias on the sine symbolic regression problem with non-bias-effective settings.

shrinking towards the end as many runs find fairly highly fit individuals.

Re-do sine figures to use bias-effective and non-bias-effective in titles.

Figure 13 shows the results for the sine regression problem using the non-bias-effective parameter settings; none of these differences are statistically significant. Figure 15 also shows the impact of crossover bias over time when using the non-bias-effective settings. **Say they're all kinda the same.**

5. DISCUSSION

In general our results indicate that adding crossover bias improves performance, either generally (Figure 2) or when combined with certain other parameter choices (e.g., Figure 9). In some cases the improvements induced by crossover bias are quite substantial (e.g., Figures 4, 8, and 12), while in other situations the improvements were quite small in magnitude even when statistically significant (Figure 2). Not surprisingly, however, crossover bias is not universally helpful, and there are settings where some crossover bias improves performance more than when always applying crossover bias (Figure 5), and other settings where all tested crossover bias amounts were detrimental (tournament sizes 3, 5, and 7 in Figure 10).

One general trend seems to be that crossover bias is more effective when using the *bias-effective* parameter settings,

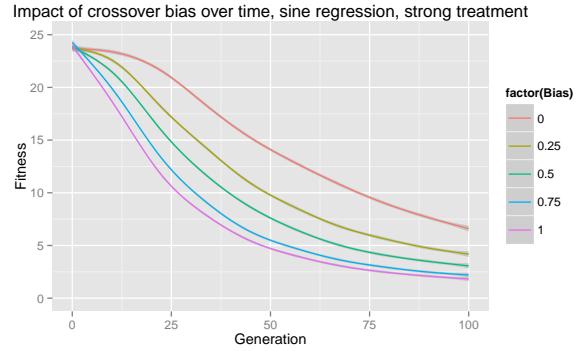


Figure 14: Impact of crossover bias on the sine symbolic regression problem with *bias-effective parameter settings*: binary tournaments, no elitism, and population size 10,240. Move this to where we define *bias-effective parameters*.

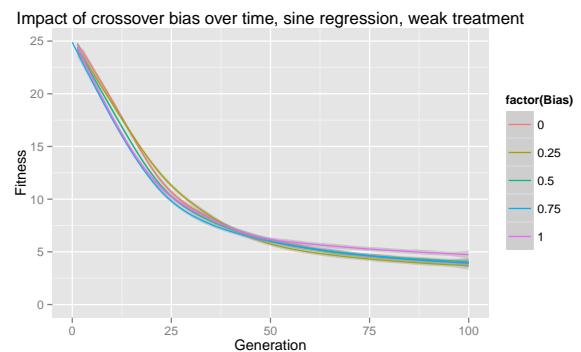


Figure 15: Impact of crossover bias on the sine symbolic regression problem with *non-bias-effective parameter settings*: tournament size 7, 0.1% elitism, and population size 1,024. Move this to where we define *non-bias-effective parameters*, combined with the previous figure as a pair of panels.

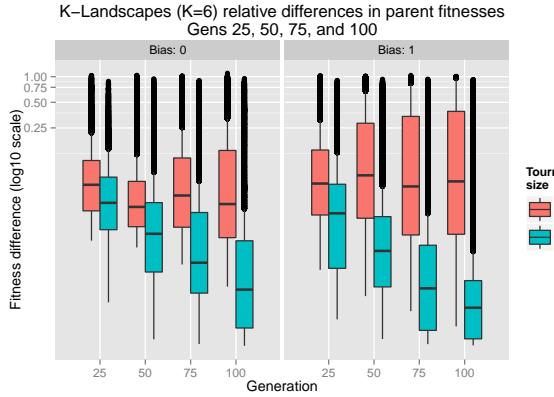


Figure 16: Plot of the normalized differences in parent fitnesses from some K Landscapes runs. Explain this.

namely smaller tournaments (size 2 instead of 7), larger populations (10,240 instead of 1,024), and no elitism. One possible explanation for this pattern is that when using the *non-bias-effective* settings (larger tournaments, smaller populations, and elitism), the difference in fitness between the two parents is likely to be closer than when using bias-effective settings, thus reducing the difference in the fitness of the parents is likely to minimize the impact of crossover bias.

To test this hypothesis, we looked at the impact of tournament size on the relative difference in parent fitness for the K Landscapes problem and the sine regression problem. For each crossover event, we compute the relative difference in parent fitness as

$$|f_A - f_B|/(f_A + f_B)$$

where f_A and f_B are the errors of the two chosen parents A and B . This has a minimum value of 0 when the two errors are the same, and a maximum value approaching 1 for the case where one of the values is nearly 0.

Figure 16 shows the distribution of the relative differences in parent fitness for the K Landscapes problem both with and without crossover bias. For tournament size 7, the difference in fitness drops significantly as the run progresses, suggesting that the both of the parents are highly fit. When using binary tournaments, the relative differences in parent fitness remains fairly stable (and high), which would suggest that crossover bias would continue to be effective throughout the run when using binary tournaments. We see similar results in the sine regression problem, as illustrated in Figure 17.

Our results also indicate that crossover bias may increase certain types of selection pressure, which could potentially increase the likelihood of premature convergence. It certainly heightens the focus on the fitter of the two parents, and increases the likelihood that that parent's semantics will be carried across into the next generation. Further research is needed to understand if this does in fact lead to premature convergence in some cases, but it's possible, for example, that this explains the fact that using some crossover bias (0.75) is better than always using crossover bias in the ORDERTREE problem (see, e.g., Figure 5).

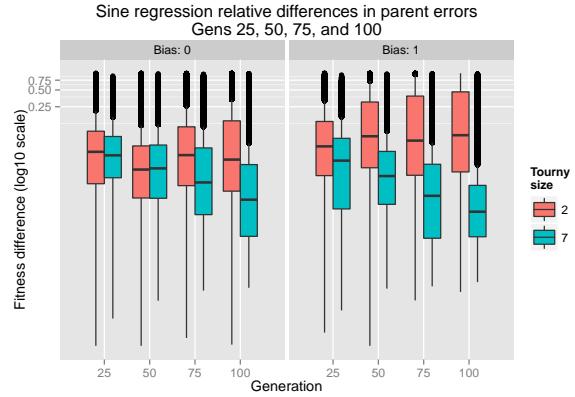


Figure 17: Plot of the normalized differences in parent errors from some sine runs. Explain this.

6. CONCLUSIONS

Based on previous observations of interesting asymmetries in the behavior of sub-tree crossover (e.g., [5]), we introduced the idea of *crossover bias*, where we probabilistically force the more fit parent to be the *root parent* when performing crossover. We then applied this new bias to experiments on several different problems. In general we found that adding crossover bias either helps or is neutral, although there were cases where its effect was detrimental.

Given these results, it seems worthwhile to at least try crossover bias, especially in settings where there are reasons to suspect that there are substantial differences between parental fitnesses. This is likely to be the case wherever selection pressure is weak (e.g., our use of binary tournaments), but could also happen when there are unavoidable steep changes in fitness, or in settings where the fitness function may vary over either time or as a function of some other variable such as location.

One outstanding question is how crossover bias affects generalization, especially since it's possible that crossover bias increases selection pressure and could consequently encourage overfitting. None of the problems used here specify a validation set, but it's clearly feasible to create validation data for the U.S. Change problem and both of the regression problems. It would be useful to expand the existing work to include validation to see what impact, if any, crossover bias has on how well evolved solutions generalize to unseen data.

While this paper focuses on asymmetry in the context of tree-based GP and sub-tree crossover, it's important to note that asymmetries like this are common in many evolutionary systems, both biological and artificial. Much eukaryote reproduction is sexual, and brings with it numerous sex-linked traits and related asymmetries; this may play an important role in speciation [11], arguably one of the most crucial of biological asymmetries. Many evolutionary computation systems other than tree-based GP also have significant asymmetries. Linear GP systems [1] and stack-based GP systems [13], for example, have asymmetries where the last instructions executed can have a disproportionate impact on the results. Similarly, changes near the front of grammatical evolution [8] strings will have a disproportionate impact by determining the important early choices in the grammar productions. In general these EC system asymme-

tries weren't intentional, but were instead simple artifacts of other system design decisions, and the potential impact of these asymmetries has been largely unstudied. The results presented here suggest that it may be important to more thoroughly explore the impact of such asymmetries, both to better understand the performance and behavior of existing systems, but also as an aid to the design and discovery of new tools like recombination operators that leverage these asymmetries.

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