

# Topic 3: Recursive design of experiments for sysid

Aria Alinejad, Johannes Djupesland, Torstein Nordgård-Hansen,  
Cameron Penne

# Summary

## 1. Introduction

- Aria

## 2. General Experiment Design

- Aria

## 3. General System Identification Experiments

- Cameron

## 4. Example

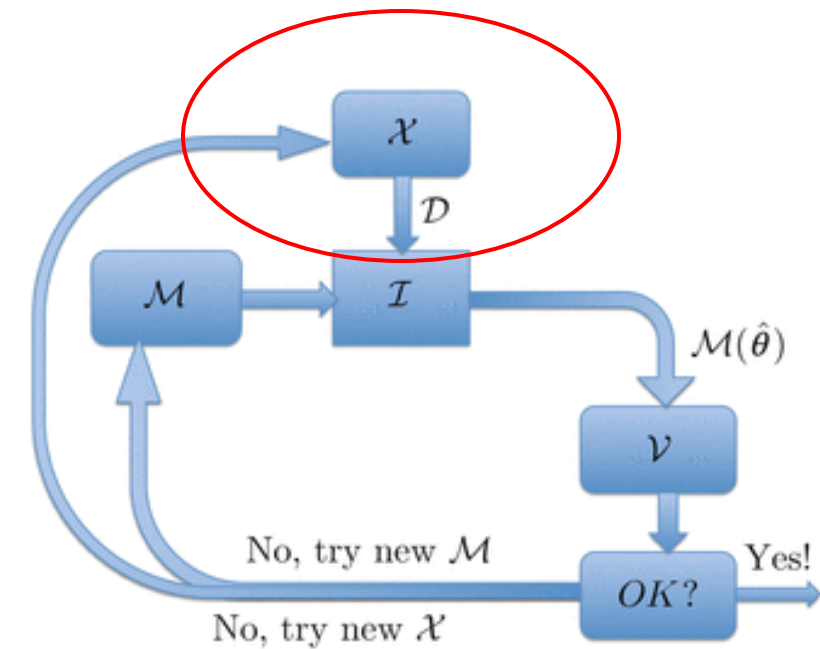
- Johannes

# Introduction

- Black box problem
- Problem:
  - We know the input and outputs of the system
  - We do not know the structure or parameters of the model
- Goal:
  - Learn a model that reproduces the behavior of the system
    - Model structure
    - Model parameters

# System identification

- $\mathcal{X}$ : The experimental conditions under which the data is generated
- $\mathcal{D}$ : The data
- $\mathcal{M}$ : The model structure and its parameters  $\theta$
- $\mathcal{I}$ : The identification method by which a parameter value  $\hat{\theta}$  in the model structure  $\mathcal{M}(\theta)$  is determined based on the data  $\mathcal{D}$
- $\mathcal{V}$ : The validation process that scrutinizes the identified model

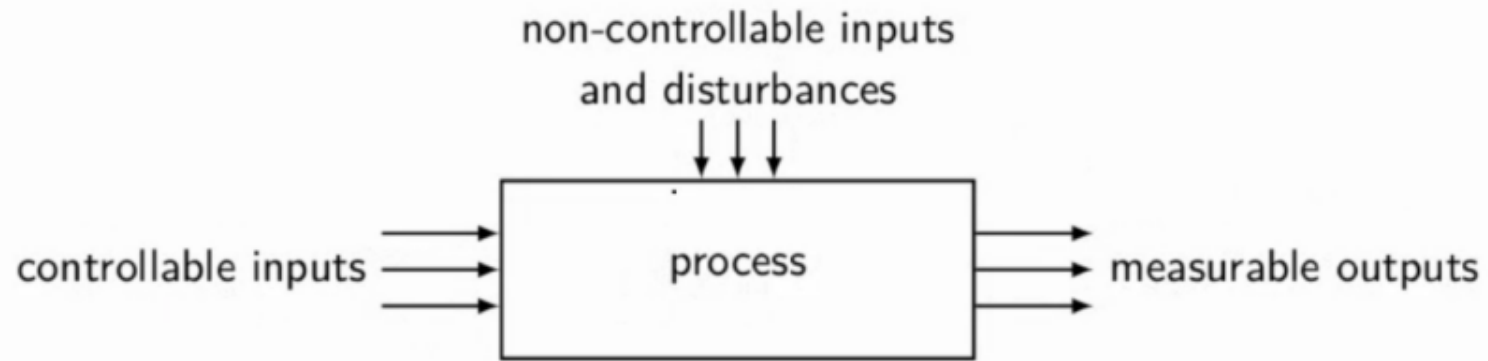


# One Variable at a time (OVAT)

- Traditional approach
- Assumes cause and effect relation between each variable and output
  - **Generally not true**
- DoE better
  - Idea is to: **Maximize information** from **minimal experimental effort**

# Design of Experiments (DoE)

- There are also non-controllable inputs and disturbances, that can not be used in DoE



# Examples (not recursive)

- Fractional factorial
- Full factorial
- Optimization designs
- Mixture designs
- Optimal designs

# General Experiment Design

- Offline
  - Use data already generated
- Online
  - Use data as it is generated in real-time



# Offline Experiment Design

1. Data collection
2. Pre-processing
3. Model structure selection
4. Model parameter estimation
5. Model validation
  - If not satisfactory, return to step 3

# Online Experiment Design

1. Model initialization
2. Data collection (continuous)
3. Model parameters update (recursive algorithm)
4. Model validation (error)
  - Run steps 2-4 until convergence

# General System Identification Experiments

- Finite-history algorithms
  - Subset of data record
- Infinite-history algorithms
  - Entire data record

# Finite-History Algorithms

- Finite-history algorithms only consider a limited number of past data points to update the model
  - Buffer or window that is moved forward as new data points are received
- Computationally efficient
- May miss long-term dependencies in the data, which can affect accuracy
- More stored data

# Infinite-History Algorithms

- Infinite-history algorithms utilize all past data points to refine the model continuously
  - New model parameters are function of old parameters and the most recent data points
- Higher accuracy, especially for long-term trends and dependencies
- Increased computational complexity
- Less stored data
  - Use most recent data in an update step

# Infinite-History Algorithms

$$\theta'(t) = \theta'(t-1) + K(t) (y(t) - y'(t))$$

- $\theta'(t)$  - current parameter estimate
- $\theta'(t-1)$  - previous parameter estimate
- $y(t)$  - output
- $y'(t)$  - predicted output
- $K(t)$  - update gain
  - Relates prediction error with the parameter update

# Infinite-History Algorithms

$$K(t) = Q(t) \psi(t)$$

- $\psi(t)$  - regression vector, gradient of parameters
- $Q(t)$  - gain

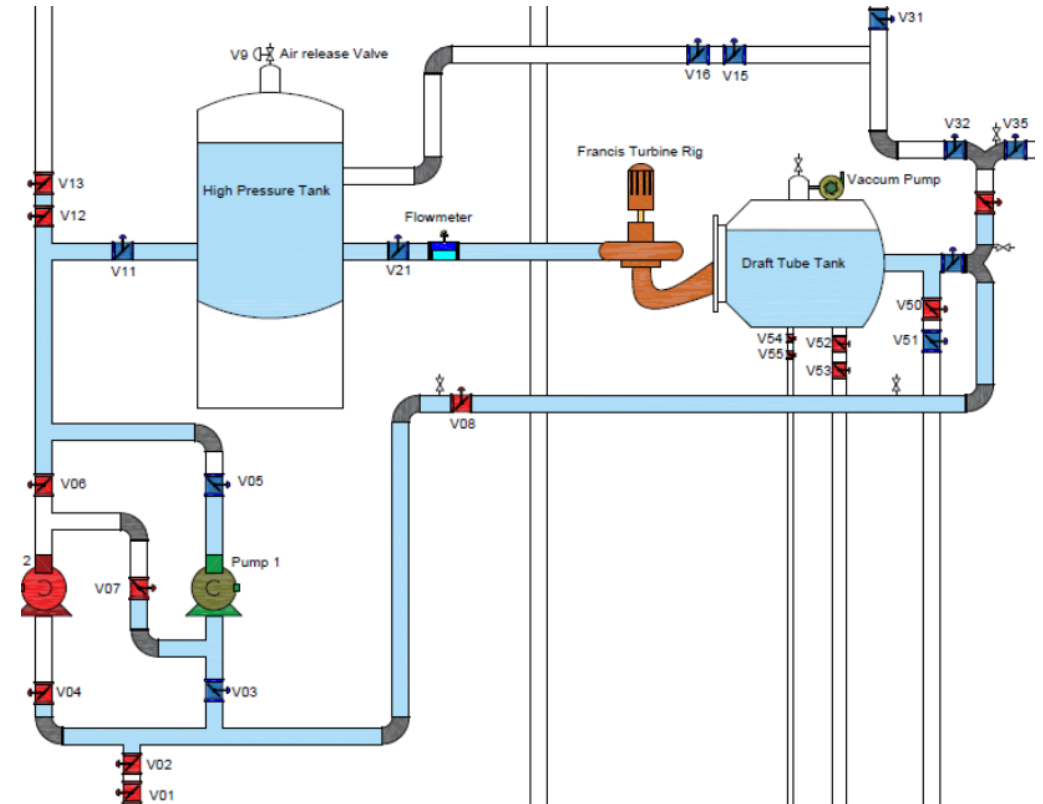
# Recursive Algorithms - Gain $Q(t)$

- Normalized or unnormalized gradient
  - Constant gain  $Q(t)$
- Forgetting factor adaptation
- Kalman filter



# Example

- Closed-loop Francis turbine test rig
- Objective:
  - Create a dynamic model for experienced head
- Rationale:
  - Create a control system for controlling head
- Actuator:
  - Pump
- Manipulated variables:
  - Generator speed
  - Guide vane angle



# Example

- Establish initial experimental design
  - Full factorial design

| Operational range |      |      |      | Excitation signals |                  |         |      |  |
|-------------------|------|------|------|--------------------|------------------|---------|------|--|
|                   | Min. | Mid. | Max. |                    | White noise      | Impulse | Ramp |  |
| Pump speed        |      |      |      |                    | Pump speed       |         |      |  |
| Generator speed   |      |      |      |                    | Generator speed  |         |      |  |
| Guide vane angle  |      |      |      |                    | Guide vane angle |         |      |  |

- Create a model and evaluate accuracy
  - Linear ARX models
  - State-space models
  - Transfer function models

# Example

- Extract key insights:
  - Factor importance
  - Interactions
  - Emerging patterns
- Refine experimental design based of insights:
  - Narrow down factor ranges
  - Test higher resolution in critical areas
- Update model, reevaluate accuracy, and extract insights
- Repeat until model accuracy converge

# Sources

- <https://se.mathworks.com/help/ident/ug/algorithms-for-online-estimation.html>
- <https://www.youtube.com/watch?v=uLbjeQrQJ3Q>
- <https://se.mathworks.com/help/ident/ug/algorithms-for-online-estimation.html>
- [https://se.mathworks.com/help/ident/online-parameter-estimation.html?s\\_tid=CRUX\\_lftnav](https://se.mathworks.com/help/ident/online-parameter-estimation.html?s_tid=CRUX_lftnav)
- <https://se.mathworks.com/help/ident/ug/what-is-online-estimation.html>
- <https://www.mathworks.com/help/ident/gs/about-system-identification.html>
- [https://link.springer.com/referenceworkentry/10.1007/978-1-4471-5058-9\\_100#Sec18279](https://link.springer.com/referenceworkentry/10.1007/978-1-4471-5058-9_100#Sec18279)
- [https://www.control.isy.liu.se/student/graduate/idkurs/Id4\\_4.pdf](https://www.control.isy.liu.se/student/graduate/idkurs/Id4_4.pdf)
- [Design of experiments – Wikipedia](#)
- [Optimal experimental design – Wikipedia](#)
- [System identification - Wikipedia](#)