06 Nov 2024

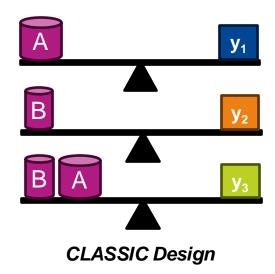
# **Variations of Optimal Designs**

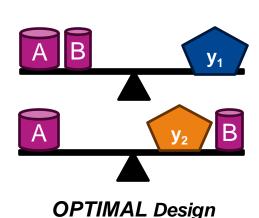
Week 11 – Advanced Topic 2

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### **Optimal Experimental Design**

- Optimization way in creating data with fewer trials / resources
- Statistical approach to select experimental points → minimizing the number of experiments or trials





# **Optimal Designs in DoE**

### What are Optimal Designs?:

Experimental setups tailored to specific objectives, providing the most informative data within given constraints (e.g. budget or time).

### Why use Optimal Designs?:

Reduce costs, improve precision, and make experiments more efficient.



# **Optimal Designs in DoE**

- The optimality of a design depends on the statistical model and is assessed with respect to a statistical criterion, which is related to the variance-matrix of the estimator.
- The inverse matrix of the variance-matrix is called the information matrix.
- Optimality-criteria are invariants of the information matrix.

### **Optimal Designs criteria**

- A-optimality ("average" or trace)
  - It seeks to minimize the trace of the inverse of the information matrix. This
    criterion results in minimizing the average variance of the estimates of the
    regression coefficients.
  - When to use: average precision across all parameters is prioritized.

#### G-optimality

- It seeks to minimize the maximum entry in the diagonal of the projection matrix X(X'X)<sup>-1</sup>X'. This results in minimizing the maximum variance of the predicted values.
- When to use: for experiments where uniform predictive capability is important.



# **Optimal Designs criteria**

#### D-optimality

- Aims at maximizing the determinant of the information matrix X'X of the design, leading to minimal parameter estimate variance.
- When to use: For models requiring high precision in parameter estimation.

#### I-optimality

- Aims at minimizing the average prediction variance over the design space.
- When to use: for applications that rely on accurate response predictions at any point within the design space.

#### Other optimality criteria

C-optimality, E-optimality, S-optimality, T-optimality, etc.



### The Fisher Information Matrix

- The Fisher Information Matrix (FIM): it captures how much information an experiment provides about the parameters of a model.
- The FIM is derived from the partial derivatives of the model's predicted responses with respect to the model parameters.
- Larger values in the FIM indicate the experimental setup provides more information about the parameters.
- In an experiment, the **covariance matrix** of the parameter estimates is proportional to the inverse of the FIM.



# **Applications and Examples**

- Simultaneous Localization and Mapping (SLAM)
  - On the comparison of uncertainty criteria for active SLAM : https://ieeexplore.ieee.org/document/6224890
  - Uncertainty-aware receding horizon exploration and mapping using aerial robots: <a href="https://ieeexplore.ieee.org/document/7989531">https://ieeexplore.ieee.org/document/7989531</a>
    - Therefore, for two robot path policies σ<sub>1</sub><sup>M</sup> and σ<sub>2</sub><sup>M</sup>, D-opt is used to evaluate which of the two (l<sub>p</sub>+l<sub>f</sub>)×(l<sub>p</sub>+l<sub>f</sub>) covariance matrices Σ<sub>p,f</sub>(σ<sub>1</sub><sup>M</sup>) and Σ<sub>p,f</sub>(σ<sub>2</sub><sup>M</sup>) corresponds to more confident belief at the *end-vertex* of each path.

$$D_{opt}(\sigma^M) = \exp(\log([\det(\mathbf{\Sigma}_{p,f}(\sigma^M)]^{1/(l_p + l_f)}))$$





### **Applications and Examples**

#### Visual 3-D reconstruction

- Active Visual Object Reconstruction using D-, E-, and T-Optimal Next
   Best Views: <a href="https://ieeexplore.ieee.org/abstract/document/4270361">https://ieeexplore.ieee.org/abstract/document/4270361</a>
- "The reconstruction is based on a probabilistic state estimation with sensor actions. The next best view is determined by a metric of the state estimation's uncertainty. We compare three metrics: Doptimality, which is based on the entropy and corresponds to the (D)eterminant of the covariance matrix of a Gaussian distribution, Eoptimality, and T-optimality, which are based on (E)igenvalues or on the (T)race of this matrix, respectively."

# **Advantages & Challenges**



Less-resources for time-saving



Leads to better model predictions



Designed to specific needs



Requires the understanding of goal



Sometimes needs costly computation



Not always suitable / applicable



### **Conclusions**

- Classical designs are easier to set up and compute, making them suitable for simpler, lower-dimensional experiments or when there's a predefined model structure.
- Optimal designs offer significant flexibility and statistical efficiency but require more computational effort and specialized software.
- Different types (D-, A-, G-, I-, and space-filling) respond to specific experimental needs, such as parameter accuracy or prediction reliability.

#### Key:

 Understand the aims and resource restriction first, optimal experiment design may depend on them.



### Thank you

#### References

- https://en.wikipedia.org/wiki/Optimal experimental design
- https://www.nature.com/articles/s41592-018-0083-2
- López-Fidalgo, J., 2023. Optimal Experimental Design. Lecture Notes in Statistics, 226.

