# Machine Learning 机器学习

Lecture 4: 决策树

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## 监督学习 Supervised Learning

Given the training dataset of (data,label) pairs,

$$D = \{(x^{(i)}, y^{(i)})\}_{i=1,2,\dots,N}$$

let the machine learn a function from data to label

$$y^{(i)} \approx f_{\theta}(x^{(i)})$$

- Function set  $\{f_{\theta}(x^{(i)})\}$  is called hypothesis space
- Learning is referred to as updating the parameter θ to make the prediction closed to the corresponding label

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$$y^{(i)} \approx f_{\theta}(x^{(i)}) \Rightarrow$$
 a decision tree

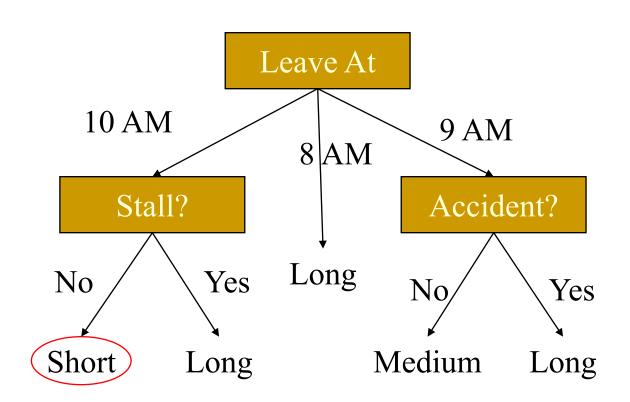
8 AM

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## 什么是决策树 What is a Decision Tree?

Let's look at a sample decision tree...

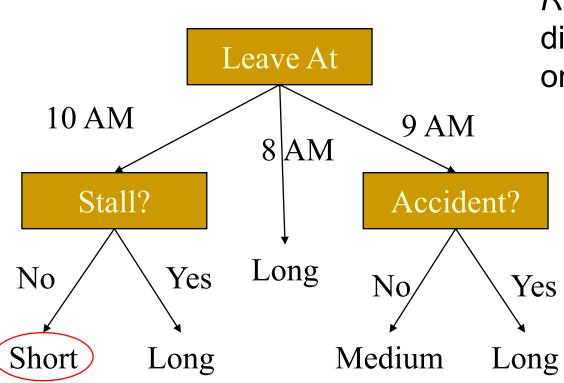
## 决策树举例 Predicting Commute Time



If we leave at 10 AM and there are no cars stalled on the road, what will our commute time be?

- Decision tree representation:
  - Each internal node tests an attribute
  - Each branch corresponds to attribute value
  - Each leaf node assigns a classification

## 决策树与规则集合 Representation as a Rule Set



If we leave at 10 AM and there are no cars stalled on the road, what will our commute time be?

Re-representation as if-then rules: disjunction of conjunctions of constraints on the attribute value instances

```
if hour == 8am
   commute time = long
else if hour == 9am
   if accident == yes
        commute time = long
   else
        commute time = medium
else if hour == 10am
   if stall == yes
        commute time = long
   else
        commute time = short
```

Problem: decide whether to wait for a table at a restaurant.
 What attributes would you use?

Goal predicate: Will wait?

- Attributes
  - 1. Alternate: is there an alternative restaurant nearby?
  - 2. Bar: is there a comfortable bar area to wait in?
  - 3. Fri/Sat: is today Friday or Saturday?
  - 4. Hungry: are we hungry?
  - 5. Patrons: number of people in the restaurant (None, Some, Full)
  - 6. Price: price range (\$, \$\$, \$\$\$)
  - 7. Raining: is it raining outside?
  - 8. Reservation: have we made a reservation?
  - 9. Type: kind of restaurant (French, Italian, Thai, Burger)
  - 10. WaitEstimate: estimated waiting time (0-10, 10-30, 30-60, >60)

- Examples (also called instances, observations, or samples) are described by features (also called attributes, or variables) and labels (also called targets or outcomes).
- E.g., situations where I will/won't wait for a table:

12 examples

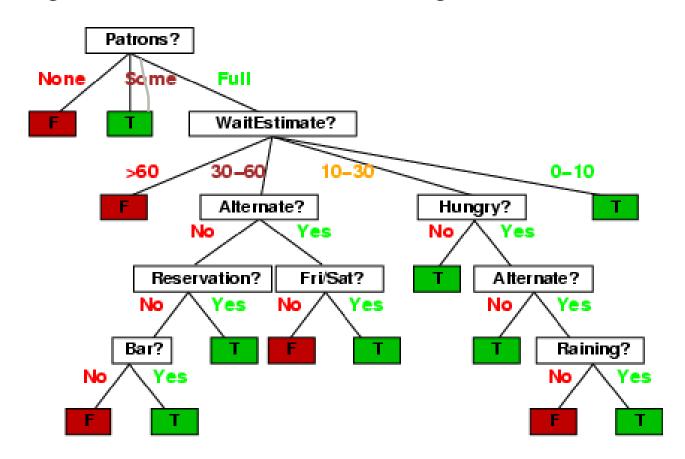
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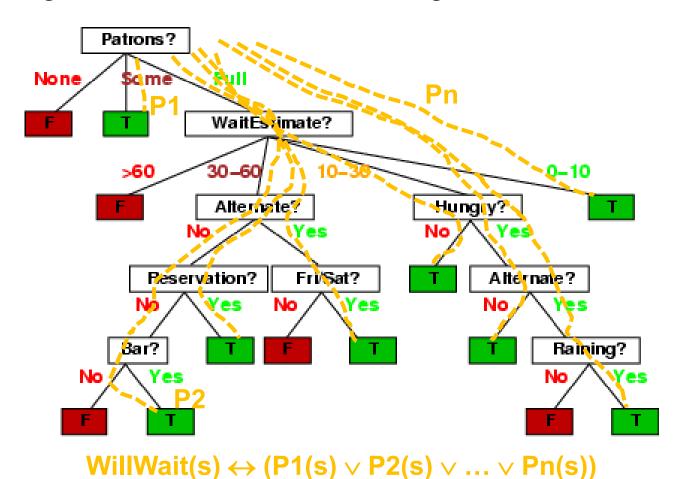
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Classification of examples is positive (T) or negative (F)

- One possible representation for hypotheses
- E.g., here is a tree for deciding whether to wait:



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#### 决策树的表达能力

Any particular decision tree hypothesis for WillWait goal predicate can be seen as

a disjunction of a conjunction of tests, i.e., an assertion of the form:

$$\forall s \; WillWait(s) \leftrightarrow (P1(s) \lor P2(s) \lor ... \lor Pn(s))$$

Where each condition Pi(s) is a conjunction of tests corresponding to the path from the root of the tree to a leaf with a positive outcome.

#### 决策树的表达能力

For 10 Boolean attributes, there are 2<sup>10</sup> possible combinations of input values (features).

For each input combination, there are 2 possible outputs (0/1).

Input features		Output	
000000000	How many entries does	0/1	
000000001	this table have?	0/1	
000000010	210	0/1	<b>Decision trees</b>
000000100		0/1	can express any Boolean function
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• • •			<b>Boolean function</b>
1111111111	J	0/1	

**Total number of distinct Boolean functions (and corresponding decision trees)**: Since there are  $2^{10}$  possible input combinations, and each combination can yield one of two possible outputs (0 or 1), the total number of distinct Boolean functions is:

$$= 2^{2^{10}}$$

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Could we construct a decision tree that has one path to a leaf for each instance, where the path tests sets each attribute value to the value of the instance?

What is the problem with this from a learning point of view?

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Could we construct a decision tree that has one path to a leaf for each instance, where the path tests sets each attribute value to the value of the instance?

What is the problem with this from a learning point of view?

**Problem:** This approach would just memorize training instances. How to deal with new instances?

It doesn't generalize!

- The basic idea behind any decision tree algorithm is as follows:
  - Choose the best attribute(s) to split the remaining instances and make that attribute a decision node
  - Repeat this process for recursively for each child
  - Stop when:
    - All the instances have the same target value
    - There are no more attributes
    - There are no more instances
    - Minimum sample size for a node (early stopping)
    - Maximum tree depth...

## ID3 启发式算法 ID3 Heuristic algorithm

How to determine the best attribute?

ID3 splits attributes based on their entropy.
 Entropy is the measure of randomness.

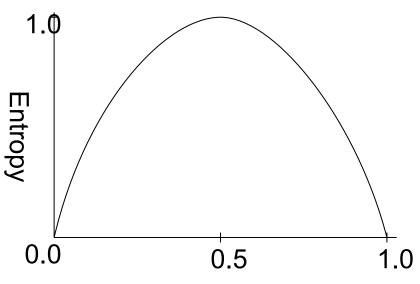


p(head)=0.5 p(tail)=0.5 H=1



p(head)=0.51 p(tail)=0.49 H=0.9997

## 熵函数 **Entropy Function**



Proportion of positive examples

For a collection D having positive and negative examples, entropy is given as:

$$Entropy(D) = -\frac{p}{p+n}\log_2\frac{p}{p+n} - \frac{n}{p+n}\log_2\frac{n}{p+n}$$

p - # positive examples

n - # negative examples

Example taken from Tom Mitchell's Machine Learning

- Examples (also called instances, observations, or samples) are described by features (also called attributes, or variables) and labels (also called targets or outcomes).
- E.g., sit What's the entropy of this collection of examples?

12 examples

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$$= -0.5 \log_2(0.5) - 0.5 \log_2(0.5) = 1$$

	6	) + } -	•	
p	=	n	=	6;
I	ס	_		n
$\overline{P}$ -	+ n	_	$\overline{P}$	+ n

= 0.5

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## 熵的通用计算公式 General Formula for Entropy

Calculation of entropy

$$Entropy(D) = -\sum_{k=1}^{|y|} p_k \log_2 p_k$$

- D = the set of examples
- $p_k$  = the portion of examples in D that belong to class k.
- |y| = the number of distinct classes (i.e. the size of the range of the target value) .

It is applicable to both binary and multiclass classification problems.

## ID3基于信息增益来选择属性 Choosing an attribute: Information Gain

- Intuition: the best attribute is the attribute that reduces the entropy (the uncertainty) the most.
- the information gain of a given attribute a relative to a collection of examples D is defined as:

$$Gain(D, a) = Entropy(D) - \sum_{v=1}^{V} \frac{|D^v|}{|D|} Entropy(D^v)$$

 $D^{v}$  is the subset of D where the attribute a takes on value V, And V is the number of distinct values that the attribute a can take.

## ID3算法构建决策树 Decision Tree Building: ID3 Algorithm

Start from the root node containing all data

- For each node, calculate the information gain of all available features
- Choose the feature with the highest information gain
- Split the data of at the node based on the selected feature (the feature is not reused in subsequent splits)
- Repeat the above steps recursively for each resulting node, until one
  of the following stopping conditions is met:
  - All instances at the node have the same target value.
  - No remaining features to split.
  - Maximum tree depth or minimum sample size for a node is reached.

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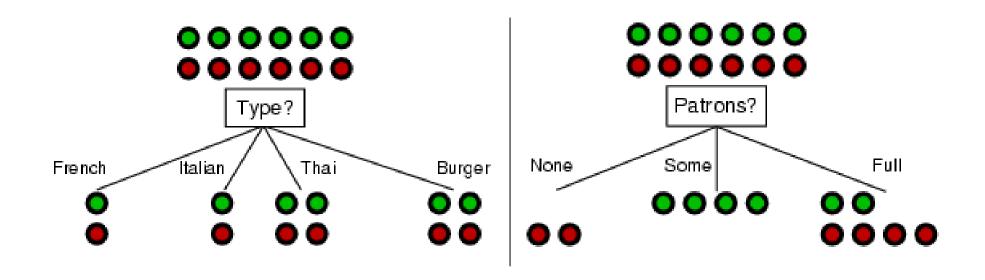
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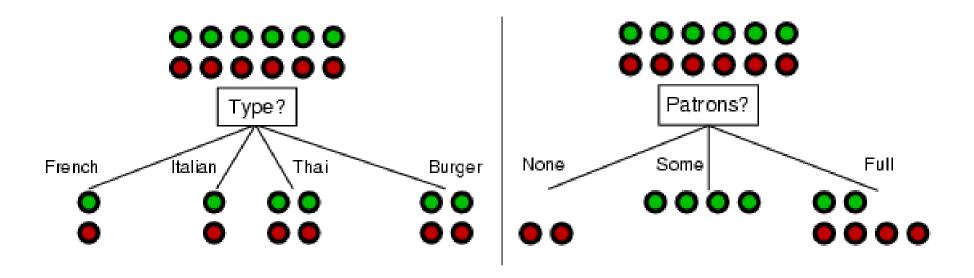
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Classification of examples is positive (T) or negative (F)

#### Which one should we pick?

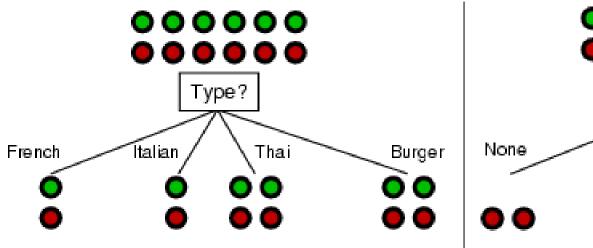


Goal: Choose the feature with the highest information gain



A perfect attribute would ideally divide the examples into sub-sets that are all positive or all negative... i.e. maximum information gain.

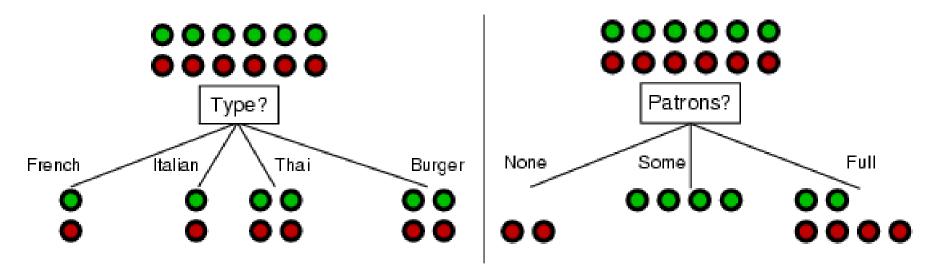
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$$Gain(D, Type) = 1 - \left[\frac{2}{12}Entropy\left(\frac{1}{2}, \frac{1}{2}\right) + \frac{2}{12}Entropy\left(\frac{1}{2}, \frac{1}{2}\right) + \frac{4}{12}Entropy\left(\frac{1}{2}, \frac{1}{2}\right) + \frac{4}{12}Entropy\left(\frac{1}{2}, \frac{1}{2}\right) + \frac{4}{12}Entropy\left(\frac{1}{2}, \frac{1}{2}\right)\right] = 0$$

$$Gain(D, Patrons) = 1 - \left[\frac{2}{12}Entropy(0,1) + \frac{4}{12}Entropy(1,0) + \frac{6}{12}Entropy\left(\frac{2}{6}, \frac{4}{6}\right)\right] = 0.541$$

Patrons has the highest 'information gain' of all attributes and so is chosen as the root.



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## 奥卡姆剃刀原则 Principle of Occam's razor

Among competing hypotheses, the one with the fewest assumptions should be selected.

Recall the function set  $\{f_{\theta}(x^{(i)})\}$  is called hypothesis space

$$\min_{\theta} \frac{1}{N} \sum_{i=1}^{N} L(y^{(i)}, f_{\theta}(x^{(i)})) + \lambda \Omega(\theta)$$
 Inductive Bias prefer/search bias Original loss Penalty on assumptions

Structural Risk Minimization, SRM

### ID3的**归纳偏置** Inductive Bias in ID3

ID3 algorithm prefers shorter trees by selecting attributes with higher information gain near the root. This helps in reducing the overall complexity of the tree.

- Occam's razor: prefer the shortest hypothesis that fits the data
- The bias in ID3 is a preference for some hypotheses(prefer/search bias), rather than a restriction of hypothesis space H. The algorithm prioritizes certain types of models (e.g., shorter trees), but other hypotheses are still possible.

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- E.g., situations where I will/won't wait for a table:

12 examples

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If add an attribute—'number'

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$$= 1 - 0 = 1$$
3
4
5
6
7
8
9

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$$Gain(D, a) = Entropy(D) - \sum_{v=1}^{V} \frac{|D^v|}{|D|} Entropy(D^v)$$

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## 信息增益率和C4.5算法 Information Gain Ratio and C4.5

$$Gain_{ratio}(D, a) = \frac{Gain(D, a)}{IV(a)}$$
 $a_* = \underset{a \in A}{\operatorname{argmax}} Gain_{ratio}(D, a)$ 

IV(a) = intrinstic value, the greater the possible number of attributes is, the greater the value is.

$$IV(a) = -\sum_{v=1}^{V} \frac{|D^{v}|}{|D|} \log_{2}^{\frac{|D^{v}|}{|D|}}$$

C4.5 is an extension of ID3
J. Ross Quinlan, The Morgan Kaufmann Series in Machine Learning, Pat Langley.
Gain Ratio for Attribute Selection

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$$= Entropy(D) - \sum_{v=1}^{V} \frac{|D^{v}|}{|D|} Entropy(D)$$

$$= 1 - \left[\frac{6}{12} Entropy(1,0) + \frac{6}{12} Entropy(0,1)\right]$$

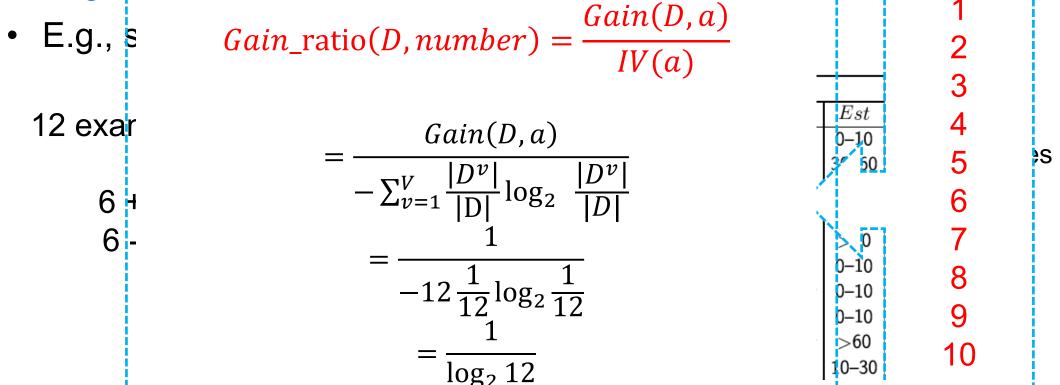
$$= 1 - 0 = 1$$
3
4
5
6
7
8
9

Number has the highest 'information gain' of all classi attributes and so is chosen as the root.

If add an attribute—'number'

• Examples (also called instances, observations, or samples) are described by features (also called attributes, or variables) and lab

targets or outcomes).



Number has the highest 'information gain' of all

Classif attributes and so is chosen as the root.

If add an attribute—'number'

#### 基尼指数和CART算法 Gini index and CART

$$Gini_{index}(D, a = v) = \frac{|D^l|}{|D|}Gini(D^l) + \frac{|D^r|}{|D|}Gini(D^r)$$

$$a_*, v_* = \underset{a \in A}{argmin} Gini_{index}(D, a = v)$$

 $D^l$  and  $D^r$  are the left and right subsets of D after splitting by a = v.

Gini(D) reflects the probability that two samples randomly selected from D belong to different classes.

Gini(D) = 
$$\sum_{k=1}^{|y|} \sum_{\mathbf{k'} \neq k} p_k p_{\mathbf{k'}} = 1 - \sum_{k=1}^{|y|} p_k^2$$

CART

Breiman et al., 1984 Classification and Regression tree W

Where  $p_k$  is the proportion of samples in class k in the dataset D

# 基尼指数和CART算法 Gini index and CART/

Binary Tree

$$Gini_{index}(D, a = v) = \frac{|D^l|}{|D|}Gini(D^l) + \frac{|D^r|}{|D|}Gini(D^r)$$

$$a_*, v_* = \underset{a \in A}{argmin}Gini_{index}(D, a = v)$$

 $D^l$  and  $D^r$  are the left and right subsets of D after splitting by a = v.

Gini(D) reflects the probability that two samples randomly selected from D belong to different classes.

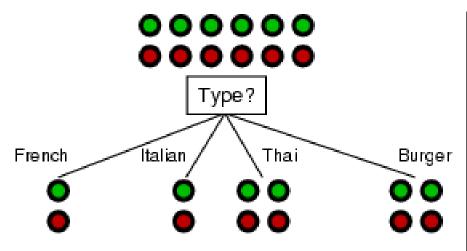
Gini(D) = 
$$\sum_{k=1}^{|y|} \sum_{\mathbf{k'} \neq k} p_k p_{\mathbf{k'}} = 1 - \sum_{k=1}^{|y|} p_k^2$$

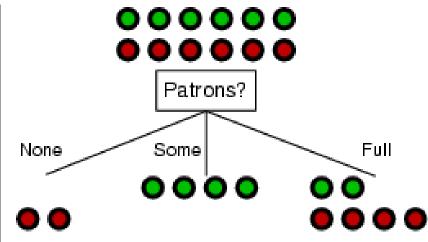
CART

Breiman et al., 1984 Classification and Regression tree Where  $p_k$  is the proportion of samples in class k in the dataset D

#### Learning decision trees: An example

$$Gini\_index(D, a = v) = \frac{|D^l|}{|D|}Gini(D^l) + \frac{|D^r|}{|D|}Gini(D^r)$$





$$Gini_index(D,Type = French) =$$

$$Gini\_index(D, Type = Italian) =$$

$$Gini\_index(D,Type = Thai) =$$

$$Gini\_index(D,Type = Burger) =$$

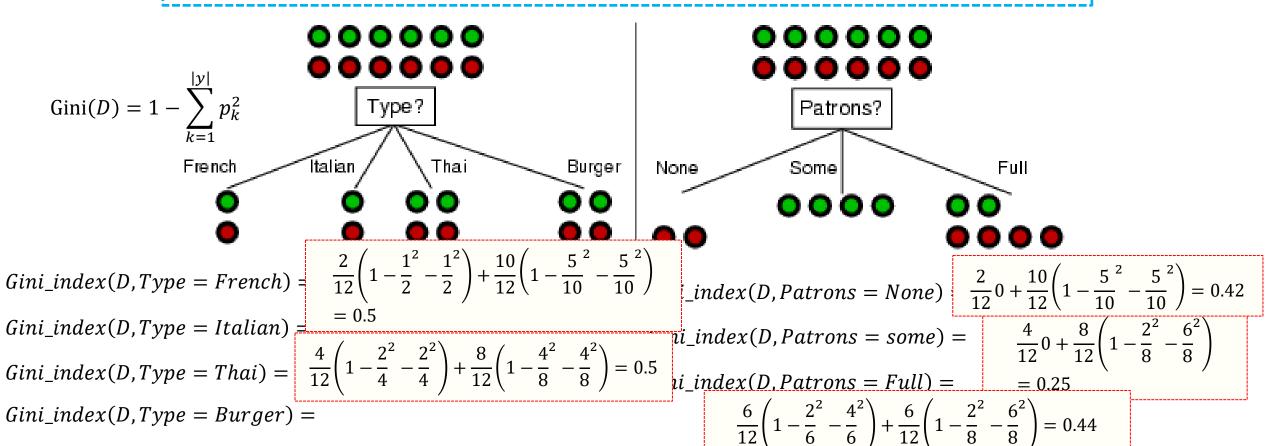
$$Gini\_index(D, Patrons = None) =$$

$$Gini\_index(D, Patrons = some) =$$

$$Gini\_index(D, Patrons = Full) =$$

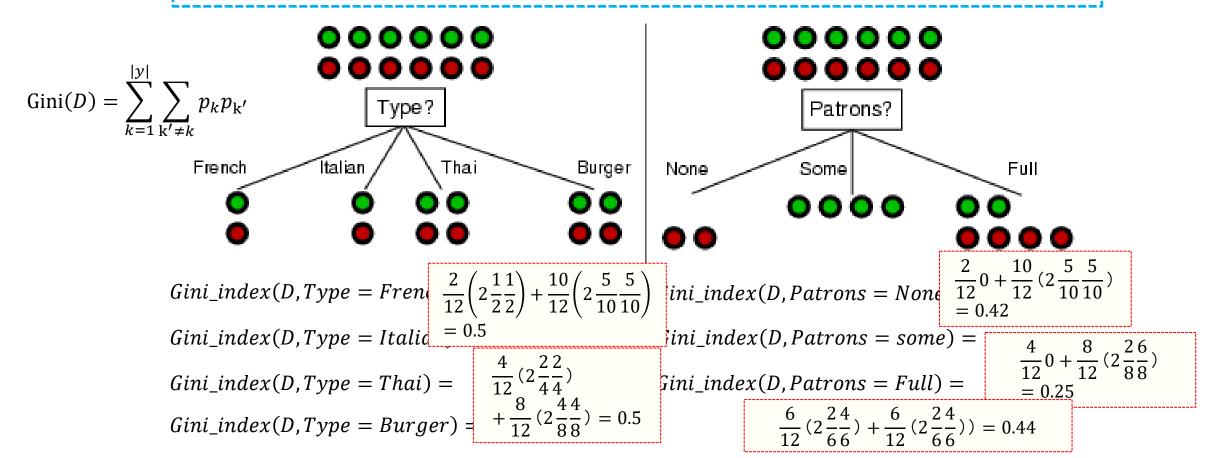
#### Learning decision trees: An example

$$Gini\_index(D, a = v) = \frac{|D^l|}{|D|}Gini(D^l) + \frac{|D^r|}{|D|}Gini(D^r)$$



#### Learning decision trees: An example

$$Gini\_index(D, a = v) = \frac{|D^l|}{|D|}Gini(D^l) + \frac{|D^r|}{|D|}Gini(D^r)$$



# 均方误差和CART算法 Mean Squared Error (MSE) and CART

$$a_*, v_* = \underset{a \in A}{\operatorname{argmin}} \left[ \min_{c^l} \sum_{x^i \in D^l} (y^i - c^l)^2 + \min_{c^r} \sum_{x^i \in D^r} (y^i - c^r)^2 \right]$$

 $a_*$ ,  $v_*$  are the optimal attribute and split point that minimize the total Mean Squared Error (MSE).

 $D^l$  and  $D^r$  are the left and right subsets of D after splitting on attribute a with a thereshold v.

 $c^{l}$  and  $c^{r}$  are predicted values for the left and right subsets, respectively.  $y^{i}$  represents the actual target value for the i-th sample.

The CART can be applied to regression task!

# 均方误差和CART算法 Mean Squared Error (MSE) and CART

$$a_*, v_* = \underset{a \in A}{argmin} \left[ \min_{c^l} \sum_{x^i \in D^l} (y^i - c^l)^2 + \min_{c^r} \sum_{x^i \in D^r} (y^i - c^r)^2 \right]$$

 $c^{l}$  and  $c^{r}$  are predicted values for the left and right subsets, respectively.  $y^{i}$  represents the actual target value for the i-th sample.

To minimize the Mean Squared Error (MSE), the predicted value is typically the mean of the target values in the subset.

$$\frac{\partial \sum_{x^i \in D^l} (y^i - c^l)^2}{\partial x} = -2 \sum_{x^i \in D^l} (y^i - c^l) = 0$$

$$\frac{\partial \sum_{x^i \in D^l} (y^i - c^r)^2}{\partial x} = -2 \sum_{x^i \in D^r} (y^i - c^r) = 0$$

$$c_l = \frac{1}{N^l} \sum_{x^i \in D^l} y^i$$

$$c_l = \frac{1}{N^r} \sum_{x^i \in D^r} y^i$$

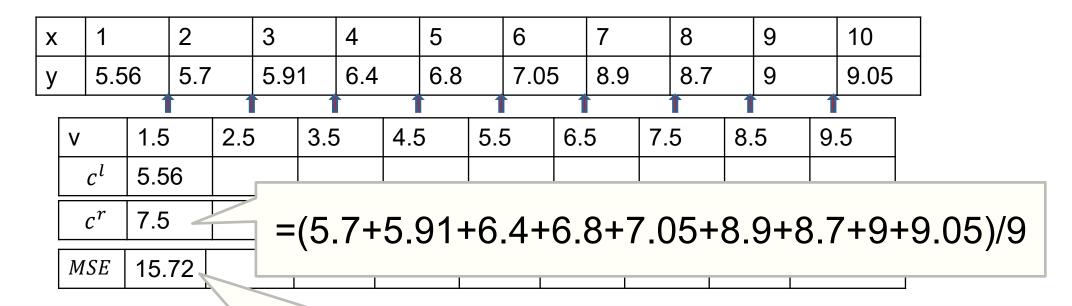
$$a_*, v_* = \underset{a \in A}{argmin} \left[ \min_{c^l} \sum_{x^i \in D^l} (y^i - c^l)^2 + \min_{c^r} \sum_{x^i \in D^r} (y^i - c^r)^2 \right]$$

$$c_l = \frac{1}{N^l} \sum_{\chi^i \in D^l} y^i, \qquad c_l = \frac{1}{N^r} \sum_{\chi^i \in D^r} y^i$$

X		1		2		3		4		5		6		7		8		9		10
У		5.56	6	5.7	,	5.9	1	6.4		6.8		7.05	)	8.9		8.7		9		9.05
		_	$\overline{1}$	Ţ	1		1		1		1		1				1		1	·
	٧		1.5		2.5		3.5	5	4.5	5	5.5	5	6.	5	7.	5	8.	5	9.	5
	m	se	15.	72	12.	07	8.3	86	5.7	78	3.9	91	1.9	93	8.6	01	11	1.73	1	5.74

$$s = 1.5, R_1 = \{1\}, R_2 = \{2,3,4,5,6,7,8,9,10\},$$
  
 $c_1 = 5.56, c_2 = 7.5$ 

X		1		2		3		4		5		6		7		8		9		10
У		5.5	6	5.7		5.9	1	6.4		6.8		7.0	5	8.9		8.7		9		9.05
			1		1		1		1		1		1		-		1		1	
	٧		1.5		2.5	)	3.5	5	4.5	5	5.5	5	6.	5	7.	5	8.	.5	9	.5
		$c^l$																		
	(	$c^r$																		
	M	SE																		

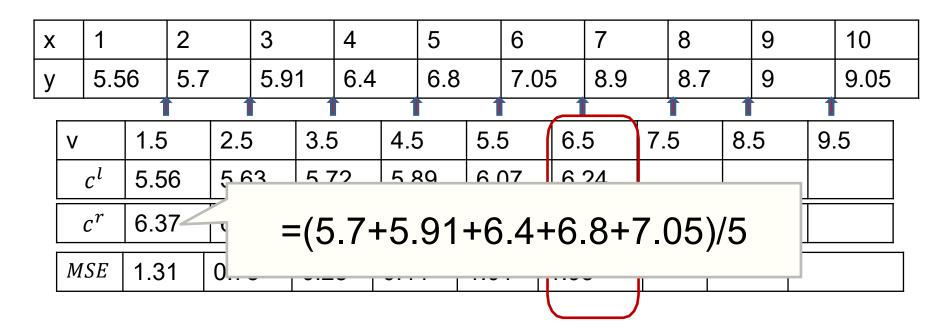


$$\sum_{x^{i} \in D^{l}} (y^{i} - c^{l})^{2} + \sum_{x^{i} \in D^{l}} (y^{i} - c^{l})^{2}$$

X		1		2		3		4		5		6		7		8		9		10	
У		5.5	6	5.7	•	5.9	1	6.4		6.8		7.0	5	8.9		8.7		9		9.05	
			1		1		1		1		1		1				1		1		
	٧		1.5		2.5	)	3.5	<del>,</del>	4.5	5	5.5	5	6.	5	7.	5	8.	.5	9	.5	
		$c^l$	5.5	6	5.6	3	5.7	<b>7</b> 2	5.8	39	6.0	)7	6.	24	6.	62	6.	.88	7	.11	
		$c^r$	7.5		7.7	3	7.9	9	8.2	25	8.5	54	8.9	91	8.9	92	9.	.03	9	.05	
	M	SE	15.	72	12.0	07	8.3	6	5.7	8	3.9	1	1.9	3	8.	01	11.	73	15.	74	

Х	1		2		3		4		5		6		7		8		9		10
У	5.5	6	5.7		5.9	1	6.4		6.8		7.05	5	8.9		8.7	•	9		9.05
		1		1		1		1		1		1				1		1	
\	<b>/</b>	1.5		2.5		3.5	5	4.5	5	5.5	5	6.	5	7.	5	8.	5	9.	.5
	$c^l$	5.5	6	5.6	3	5.7	72	5.8	39	6.0	07	6.	24	6.0	62	6.	88	7.	.11
	$c^r$	7.5		7.7	3	7.9	99	8.2	25	8.8	54	8.9	91	8.9	92	9.	03	9.	.05
	MSE	15.	72	12.0	07	8.3	6	5.7	8	3.9	1	1.9	3	8.	01 ′	11.7	73	15.	74
			•				•		•						•		•		

X	1		2		3		4		5		6		7		8		9		10
У	5.5	56	5.7		5.9	1	6.4		6.8		7.0	5	8.9		8.7		9		9.05
		1		1		1		1		1					r	1		1	
	V	1.5	)	2.5	•	3.5	5	4.5	5	5.	5	6.	5	7.	5	8.	.5	9	.5
	$c^l$	5.5	6	5.6	3	5.7	72	5.8	39	6.0	07	6.	24						
	$c^r$	6.3	7	6.5	54	6.7	<b>'</b> 5	6.9	93	7.0	05	8.	91						
	MSE	1.3	1	0.7	5	0.2	8	0.4	4	1.0	1	1.9	3						
_		•			•		•		•		•				•		•		

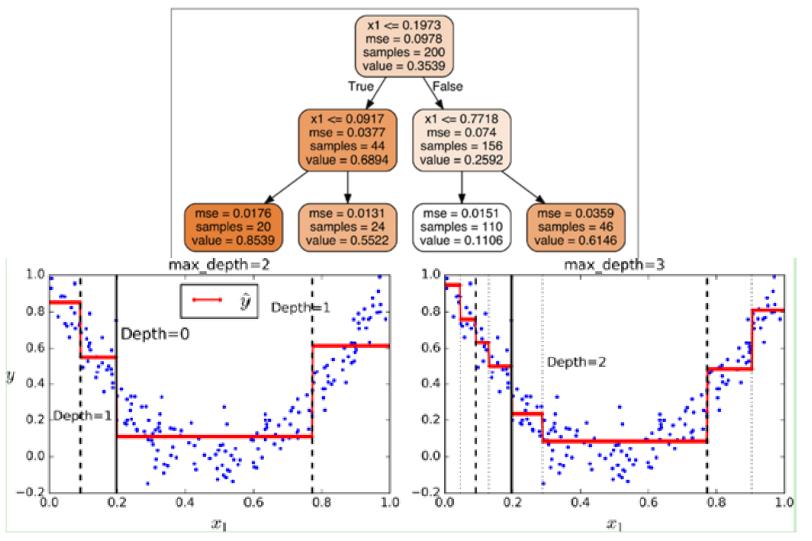


X	1		2		3		4		5		6		7		8		9		10
у	5.5	6	5.7		5.9	1	6.4		6.8		7.05	5	8.9		8.7		9		9.05
	•	1		1		1		1		1		_1		-	Î	1		1	
	V	1.5	1	2.5		3.5	5	4.5	5	5.5	5	6.	5	7.	5	8.	5	9.	5
	$c^l$	5.5	6	5.6	3	5.7	'2	5.8	39	6.0	07	6.	24						
	$c^r$	6.3	7	6.5	4	6.7	'5	6.9	93	7.0	)5	8.9	91						
	MSE	1.3	1	0.7	5	0.2	8	0.4	4	1.0	1	1.9	3						
_			•						•						·		•		

Х	1		2		3		4		5		6		7		8		9		10
У	5	5.56	5.	7	5.9	91	6.4		6.8		7.0	5	8.9		8.7		9		9.05
_				1		1		1		1		1				1		1	
V	,	1.5		2.5		3.5		4.5		5.5	,	6.5	5	7.5	5	8.	5	9	.5
	$c^l$	5.56	3	5.63	3	5.7	2	5.8	9	6.0	7	6.2	24						
	$c^r$	6.3	37	6.5	54	6.7	75	6.9	93	7.0	05	8.9	91						
	MSE	1.3	1	0.7	5	0.2	8	0.4	4	1.0	1	1.9	3						
_									•		·				•		•		

$$T = \begin{cases} 5.72 & x \le 3.5 \\ 6.75 & 3.5 < x \le 6.5 \\ 8.91 & x > 6.5 \end{cases}$$

# CART算法 Classification and Regression Tree



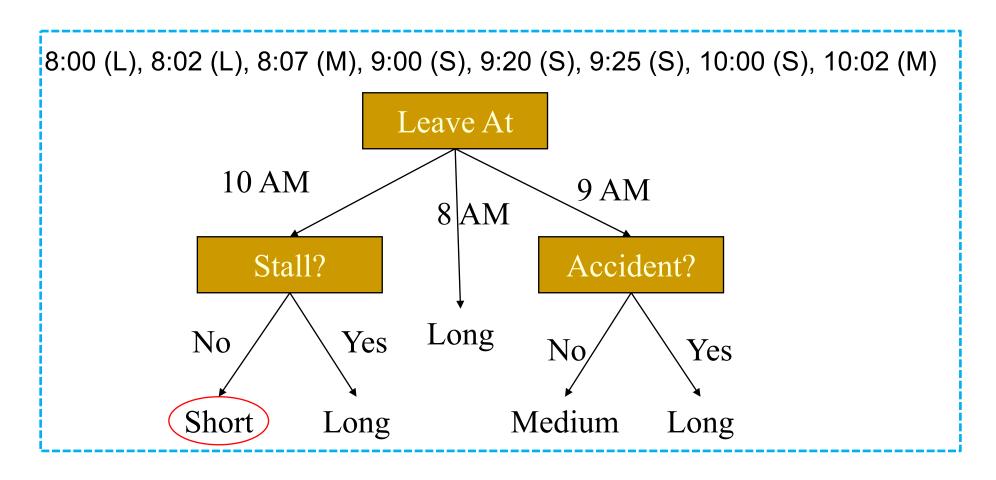
The CART can be applied to regression task!

# 决策树经典算法小结 Summary of DT algorithms

	support task	criterion structure	tree structure	continous attribute value	missing attribute value	pruning	attribute multiple use
ID3	classification	Gain information	multiple Tree	No support	No support	No support	No support
C4.5	classification	Gain information rate	multiple Tree	support	support	support	No support
CART	Classification; regression	Gini index; mean square error	binary tree	support	support	support	support

#### 连续值问题 Continuous attribute Problem

 Consider the attribute commute time, If we broke down leave time to the minute, we might get this:



#### 连续值问题 Continuous attribute Problem

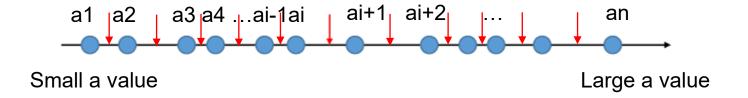
 Consider the attribute commute time, If we broke down leave time to the minute, we might get this:

8:00 (L), 8:02 (L), 8:07 (M), 9:00 (S), 9:20 (S), 9:25 (S), 10:00 (S), 10:02 (M) cut points

discretization

Since entropy is very low for each branch, we have n branches with n leaves. This would not be helpful for predictive modeling.

### 连续值离散化 Continuous attribute discretization



#### Calculate candidate cut points

$$T_a = \left\{ \frac{a^i + a^{i+1}}{2} \mid 1 \le i \le n-1 \right\}$$

the best partition point(s) are selected according to

$$T_a^* = \underset{T_a}{argmin \ Gini\_index}$$
 (CART)  
 $T_a^* = \underset{T_a}{argmax \ Gain\_ratio}$  (C4.5)

#### 缺失值处理

# Strategies for missing attribute values

D — the subset of D in which samples that have no missing values in the attribute a

 $ilde{ ilde{D}}^v$  — the subset of  $ilde{ ilde{D}}$  in which samples that have v values in the attribute a

 $\tilde{D}_k$  — the subset of  $\tilde{D}_k$  in which samples belonging to a class k $w_x$ — the weight to each sample x

Q1:如何在属性缺失的情 况下进行划分属性选择

$$\rho = \frac{\sum_{x \in \tilde{D}} w_x}{\sum_{x \in D} w_x}$$

$$\tilde{p}_k = \frac{\sum_{x \in \tilde{D}_k} w_x}{\sum_{x \in \tilde{D}} w_x} \quad (1 \le k \le |\mathcal{Y}|)$$

$$\tilde{r}_{v} = \frac{\sum_{x \in \tilde{D}^{v}} w_{x}}{\sum_{x \in \tilde{D}} w_{x}} \quad (1 \leq v \leq V)$$

$$\sum_{k=1}^{|\mathcal{Y}|} \tilde{p}_{k} = 1, \sum_{v=1}^{V} \tilde{r}_{v} = 1.$$

$$\mathbf{Q2}: 如何在属性缺失的情$$

$$\mathbf{C2}: 如何在属性缺失的情$$

$$\mathbf{C2}: \mathbf{V} = \mathbf{C}$$

$$\mathbf{C3}: \mathbf{V} = \mathbf{C}$$

$$\mathbf{C3}: \mathbf{C4}$$

#### C4.5:

Probability weights

#### Calculate Gain according to

$$Gain(D, a) = \rho \times Gain(\tilde{D}, a)$$
$$= \rho \times \left( Ent(\tilde{D}) - \sum_{v=1}^{V} \tilde{r}_v Ent(\tilde{D}^v) \right)$$

况下进行划分属性选择?

Assign x(with missing attribute a ) to each of the possible value With a probability  $r_v \cdot w_x$ 

#### 缺失值处理

# Strategies for missing attribute values

D — the subset of D in which samples that have no missing values in the attribute a

 $ar{ ilde{D}}^v$  —— the subset of  $ilde{D}$  in which samples that have  $\,v\,$  values in the attribute a

 $\tilde{D}_k$  — the subset of D in which samples belonging to a class k

 $w_x$ — the weight to each sample x

考虑样本权重后的

A1:根据缺失率的大小 对信息增益率进行拮

$$\rho = \frac{\sum_{x \in \tilde{D}} w_x}{\sum_{x \in D} w_x}$$

 $ho = \frac{\sum_{x \in \tilde{D}} w_x}{\sum_{x \in D} w_x}$  具有完整属性值的 样本比例

#### Calculate Gain according to

$$\tilde{p} = \frac{1}{\sum_{x \in D} w_x}$$
 样本比例 
$$\operatorname{Gain}(D, a) = \rho \times \operatorname{Gain}(\tilde{D}, a)$$
 
$$\tilde{p}_k = \frac{\sum_{x \in \tilde{D}_k} w_x}{\sum_{x \in \tilde{D}} w_x}$$
 
$$(1 \le k \le |\mathcal{Y}|)$$
 具有完整属性值的类 
$$= \rho \times \left( \operatorname{Ent}(\tilde{D}) - \sum_{v=1}^V \tilde{r}_v \operatorname{Ent}(\tilde{D}^v) \right)$$

$$\tilde{p}_k = \frac{\sum_{x \in \tilde{D}_k} w_x}{\sum_{x \in \tilde{D}} w_x}$$

$$\tilde{r}_v = \frac{\sum_{x \in \tilde{D}^v} w_x}{\sum_{x \in \tilde{D}} w_x} \quad (1 \le v \le V)$$
 具有特定属性值 v 的

 $\sum_{k=1}^{|\mathcal{Y}|} \tilde{p}_k = 1, \; \sum_{v=1}^{V} \tilde{r}_v = 1.$ 

加权样本比例

$$\operatorname{Ent}( ilde{D}) = -\sum_{k=1}^{|\mathcal{Y}|} ilde{p}_k \log_2 ilde{p}_k$$

C4.5:

Probability weights

Assign x(with missing attribute a ) to each of the possible value With a probability  $\tilde{r}_v \cdot w_x$ 

A2:将缺失属性的样本 属性值的分布进行分配

#### 缺失值处理

# Strategies for missing attribute values

	ID	Α	В	С	
	1	T	NaN	F	Υ
	2	T	F	NaN	N
	3	F	F	F	Υ
	4	F	T	T	N
_					

ID	Α	С	
1	T	F	
3	F	F	
4	F	T	

ID	В	С
3	F	F
4	T	T

If A=T: C=F

else: C=T

error:30%

If B=F: C=F

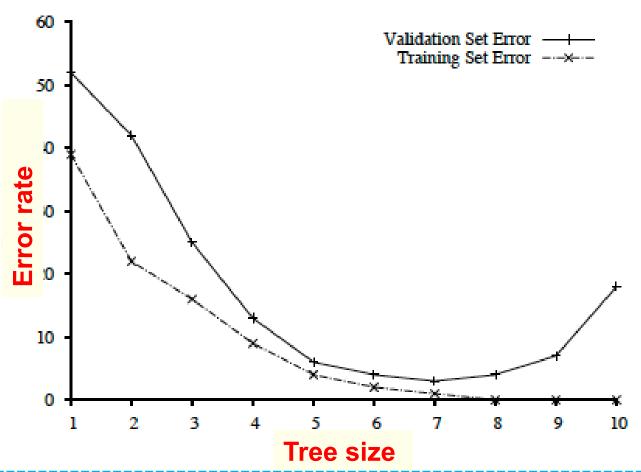
else : C=T

error:0%

Surrogate Variables order: B<A

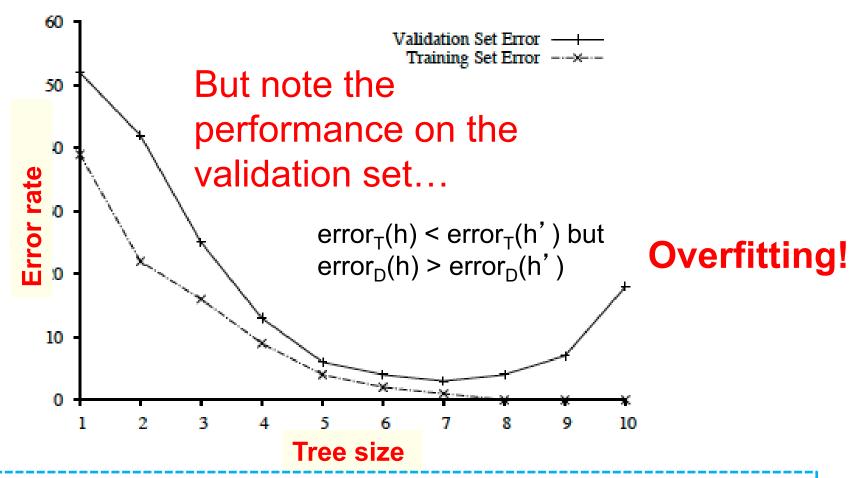
CART: surrogate splits

## 树的大小 Tree size



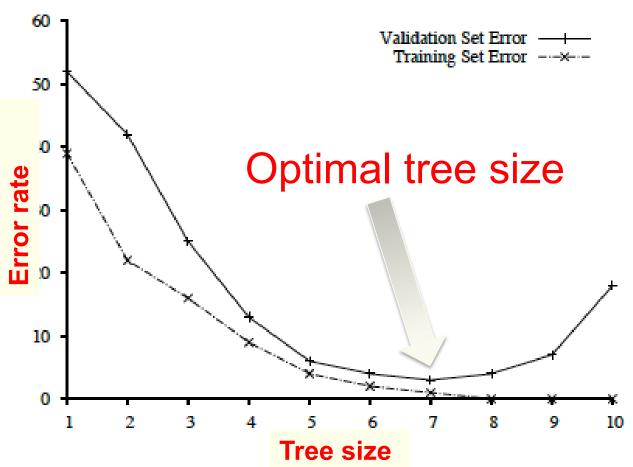
We set tree size as a parameter in our DT learning algorithm Note: with larger and larger trees, we just do better and better on the training set!

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# 树的大小 Tree size



We set tree size as a parameter in our DT learning algorithm Note: with larger and larger trees, we just do better and better on the training set!

# 确定树的最优大小 Find optimal tree size

- Procedure for finding the optimal tree size is called 'model selection'.
  - To determine validation error for each tree size, use kfold cross-validation.
  - Uses "all data test set" --- k times splits that set into a training set and a validation set.
  - After right decision tree size is found from the error rate curve on validation data, train on all training data to get final decision tree (of the right size).
  - Finally, evaluate tree on the test data (not used before) to get true generalization error (to unseen examples).

# 树剪枝 Pruning Trees

technique for reducing the number of attributes used in a tree –
 pruning

Remove subtrees for better generalization (requires a separate pruning set)

- Two types of pruning:
  - Pre-pruning (forward pruning)
  - Post-pruning (backward pruning)

# 预剪枝 Prepruning

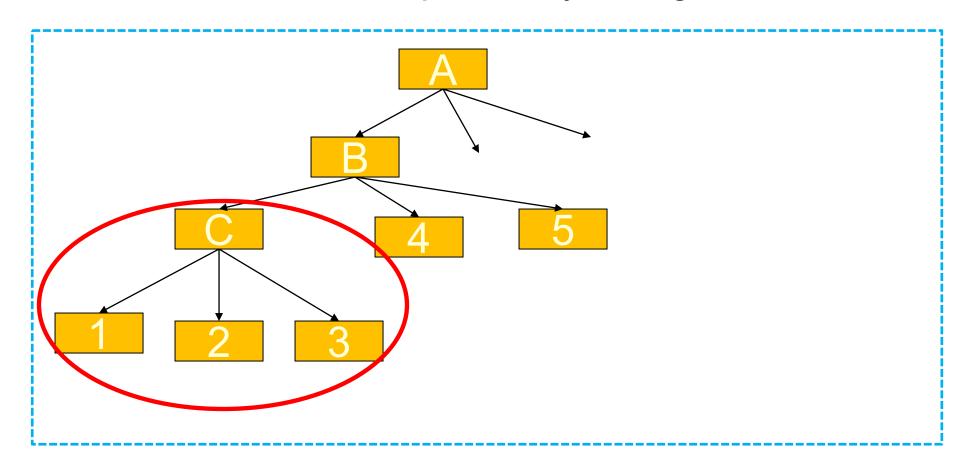
- In prepruning, we decide during the building process when to stop adding attributes
  - e.g., all attributes have been used; the number of instances in a node has less than a certain threshold; the accuracy can not been improved
  - reduce the risk of overfitting
- However, this may be problematic Why?
  - underfitting
  - Sometimes the current division of some branches can not improve the generalization performance, but the subsequent division on the basis of it may lead to a significant performance improvement

# 后剪枝 Postpruning

- Postpruning is a technique that waits until a full decision tree is built and then prunes it to remove unnecessary branches, thereby reducing overfitting.
  - Reduced-Error Pruning(REP): Evaluates the pruning effect using a validation set and removes branches that do not improve validation set performance.
  - Pesimistic-Error Pruning(PEP): Commonly used in C4.5 algorithm, this method prunes based on a pessimistic estimation of error.
  - Cost-Complexity Pruning(CCP): Commonly used in the CART algorithm, this method prunes
    the tree by minimizing a cost function that balances model complexity and error rate.
- Postpruning techniques:
  - Direct Leaf Pruning, Node Merging, Sibling Merging, Level-Based Pruning
  - Subtree Replacement, Subtree Raising
- Advantages and Disadvantages:
  - Low risk of underfitting
  - Better generalization
  - Longer training time

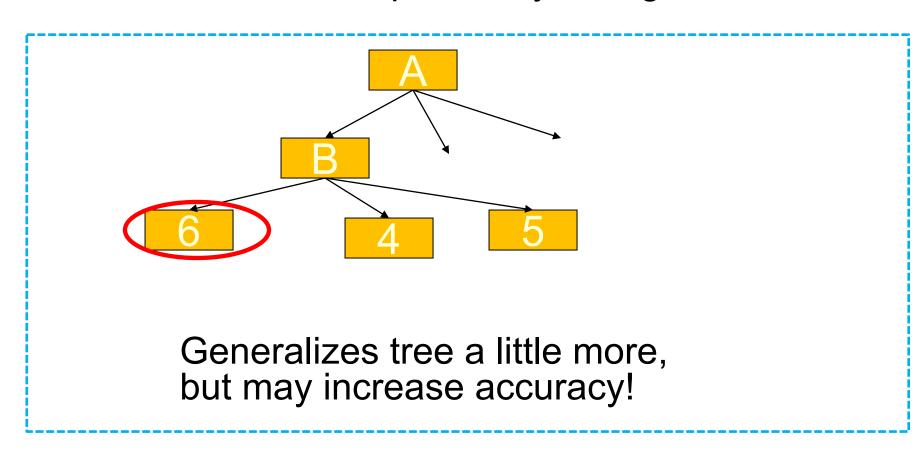
# 子树代替 Subtree Replacement

• Entire subtree is replaced by a single leaf node



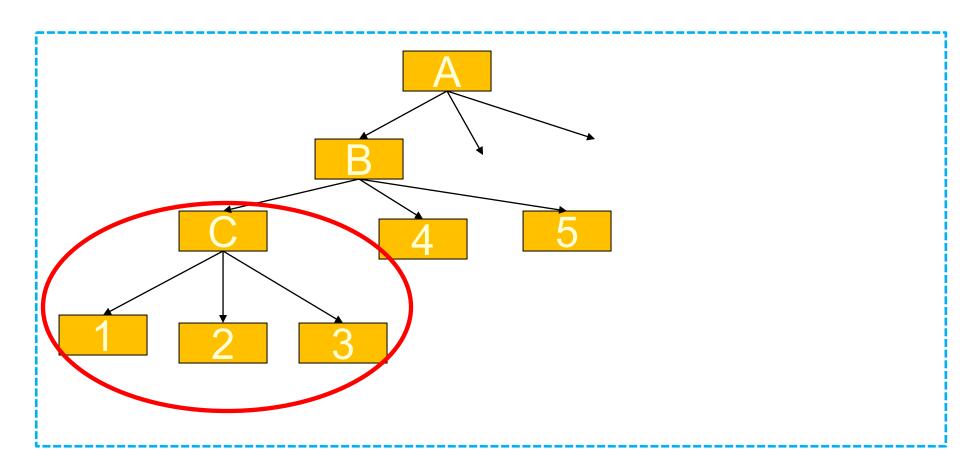
## 子树代替 Subtree Replacement

Entire subtree is replaced by a single leaf node



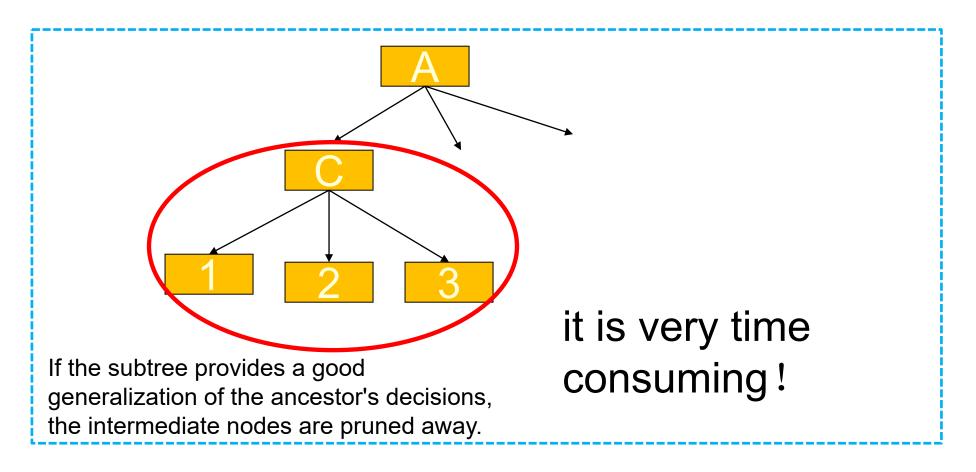
# 子树提升 Subtree Raising

Entire subtree is raised onto another node



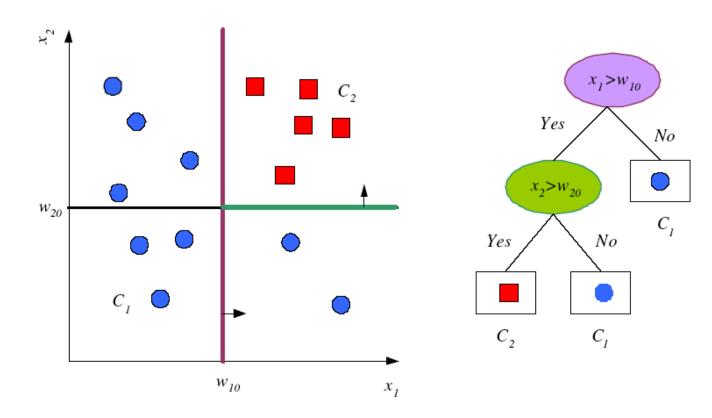
## 子树提升 Subtree Raising

Entire subtree is raised onto another node



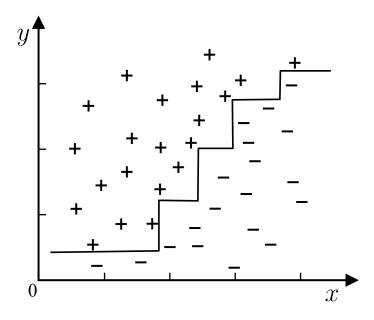
## 决策树分类界面 Decision Boundary

- Decision trees divide the feature space into axisparallel(hyper-)rectangles
- Each rectangular region is labeled with one label



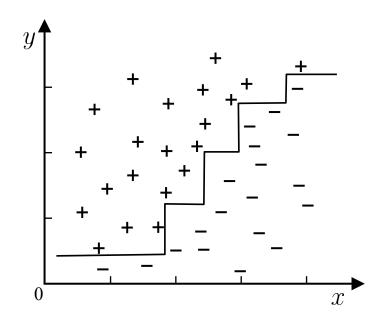
## 决策树分类界面 Decision Boundary

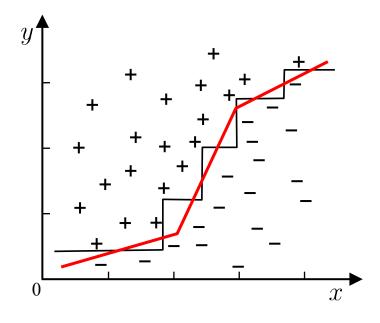
 Many segments must be used to get better approximations when the learning tasks are complex



## 决策树分类界面 Decision Boundary

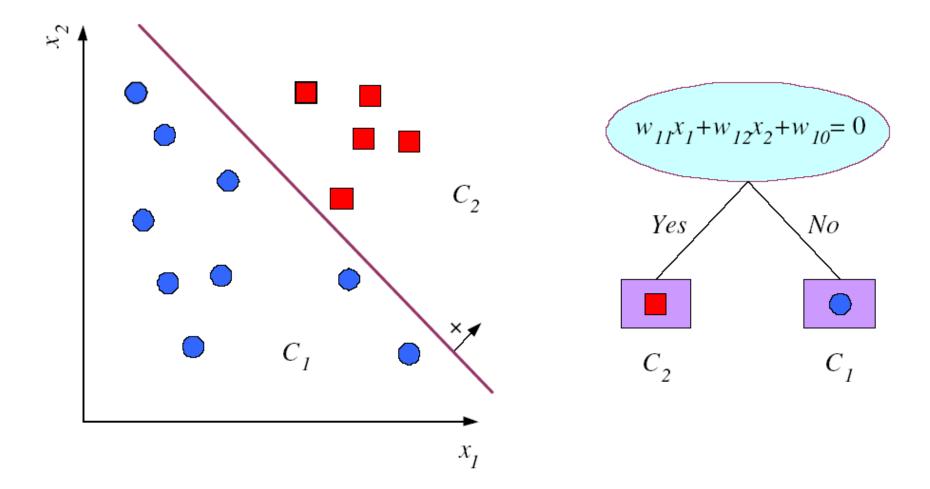
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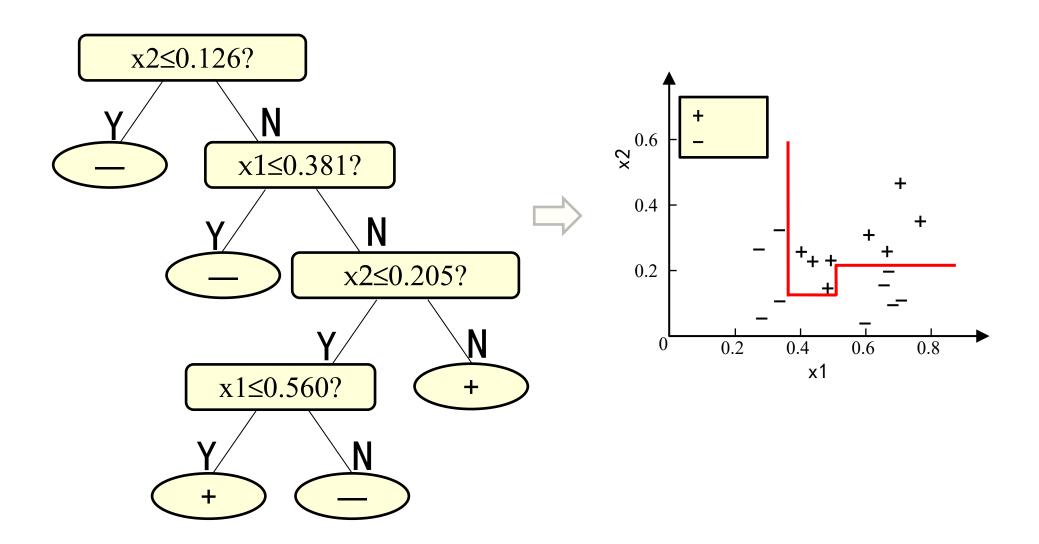


#### 多变量决策树 Multivariate Trees

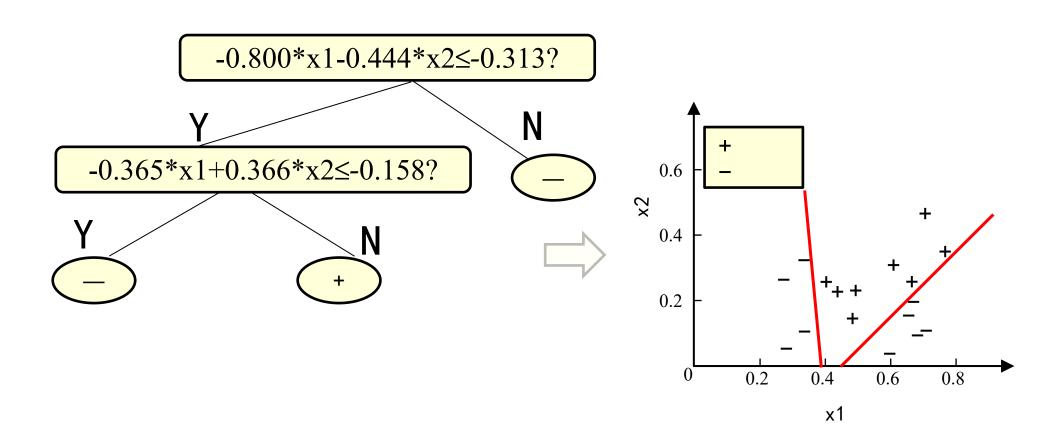
Internal nodes can test linear combination of attributes



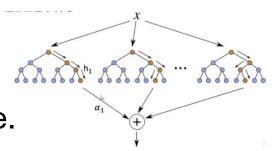
### 单变量决策树 Univariate Trees



#### 多变量决策树 Multivariate Trees



#### 集成模型 Ensemble model



Multiple decision trees are combined to improve the overall performance.

Random Forest

Each tree is built using a random subset of the data and a random subset of the feature. Each tree is constructed independently and trained in parallel, with no dependence between them.

Boosted Tree

Each new tree tries to correct the errors of the previous ones (trained on the residuals) Trees are built sequentially, with each tree dependent on the previous ones.

- XGBoost: An efficient and fast gradient boosting algorithm known for its high performance.
- LightGBM: A lightweight gradient boosting framework optimized for speed and memory efficiency, especially suitable for large datasets.
- CatBoost: A gradient boosting library designed to handle categorical features
  efficiently, with automatic handling of categorical data and robust performance
  even with default parameters.

# 决策树经典算法小结 Summary of DT algorithms

	support task	criterion structure	tree structure	continuous attribute value	missing attribute value	pruning	attribute multiple use
ID3	classification	Gain information	multiple Tree	No support	No support	No support	No support
C4.5	classification	Gain information rate	multiple Tree	support	support	support	No support
CART	Classification; regression	Gini index; mean square error	binary tree	support	support	support	support