

## 2. Quadratic forms in normal variates

In deriving the normal equations, we minimised the *total sum of squares*

$$SS := (y - A\beta)^T(y - A\beta)$$

w.r.t.  $\beta$ . The minimum value is called the *sum of squares for error*,

$$SSE := (y - A\hat{\beta})^T(y - A\hat{\beta}).$$

From the normal equations ( $NE$ ) and the definition of the projection matrix  $P$ ,

$$A\hat{\beta} = Py.$$

So

$$SSE = (y - Py)^T(y - Py) = y^T y - y^T Py - y^T Py + y^T P^T Py = y^T (I - P)y,$$

using  $P^T = P$  and  $P^2 = P$ , and a little matrix algebra (see e.g. [BF], 3.4) gives also

$$SSE = (y - A\beta)^T(I - P)(y - A\beta).$$

The *sum of squares for regression* is

$$SSR := (\hat{b} - \beta)^T C(\hat{b} - \beta).$$

Again, a little matrix algebra (see e.g. [BF], 3.4) gives

$$SSR = (y - A\beta)^T P(y - A\beta).$$

So

$$SS = SSR + SSE :$$

$$(y - A\beta)^T(y - A\beta) = (y - A\beta)^T P(y - A\beta) + (y - A\beta)^T (I - P)(y - A\beta); \text{ (SSD)}$$

either of both of these are called the *sum-of-squares decomposition*. Now from the model equations ( $ME$ ),  $y - A\beta = \epsilon$  is a random  $n$ -vector whose components are iid  $N(0, \sigma^2)$ . So ( $SSD$ ) decomposes a quadratic form in normal variates  $\epsilon = (\epsilon_1, \dots, \epsilon_n)^T$  with matrix  $I$  into the sum of two quadratic forms with matrices  $P$  and  $I - P$ . Now by *Craig's theorem* ([KS1], (15.55))

such quadratic forms with matrices  $A, B$  are independent iff  $AB = 0$ . But since

$$P(I - P) = P - P^2 = P - P = 0,$$

this shows that  $SSR$  and  $SSE$  are independent. Thus ( $SSD$ ) decomposes the total sum of squares into a sum of *independent* sums of squares – the main tool used in regression.

We recall some results from Linear Algebra (see e.g. [BF] Ch. 3 and the references cited there). We need the *trace*  $\text{trace}(A)$  of a square matrix  $A = (a_{ij})$ , defined as the sum of its diagonal elements:

$$\text{trace}(A) = \sum a_{ii}.$$

(i) A real symmetric matrix  $A$  can be diagonalised by an orthogonal transformation  $O$  to a diagonal matrix  $D$ :

$$O^T A O = D.$$

(ii) For  $A$  idempotent (a projection), its eigenvalues are 0 or 1.

(iii) For  $A$  idempotent, its trace is its rank.

So if we have a quadratic form  $x^T P x$  with  $P$  a projection of rank  $r$  and  $x$  an  $n$ -vector  $(x_1, \dots, x_n)^T$  with  $x_i$  iid  $N(0, \sigma^2)$ , we can diagonalise by an orthogonal transformation  $y = O x$  to a sum of squares of  $r$  normals (wlog the first  $r$ ):

$$x^T P x = y_1^2 + \dots + y_r^2, \quad y_i \text{ iid } N(0, \sigma^2).$$

So by definition of the chi-square distribution,

$$x^T P x \sim \sigma^2 \chi^2(r).$$

### *Sums of Projections*

Suppose that  $P_1, \dots, P_k$  are symmetric projection matrices with sum the identity:

$$I = P_1 + \dots + P_k.$$

Take the trace of both sides: the  $n \times n$  identity matrix  $I$  has trace  $n$ . Each  $P_i$  has trace its rank  $n_i$ , so as trace is additive

$$n = n_1 + \dots + n_k.$$

Then squaring,

$$I = I^2 = \sum_i P_i^2 + \sum_{i < j} P_i P_j = \sum_i P_i + \sum_{i < j} P_i P_j.$$

Taking the trace,

$$n = \sum n_i + \sum_{i < j} \text{trace}(P_i P_j) = n + \sum_{i < j} \text{trace}(P_i P_j) : \\ \sum_{i < j} \text{trace}(P_i P_j) = 0.$$

Now

$$\begin{aligned} \text{trace}(P_i P_j) &= \text{trace}(P_i^2 P_j^2) \quad (P_i, P_j \text{ projections}) \\ &= \text{trace}((P_j P_i) \cdot (P_i P_j)) \quad (\text{trace}(AB) = \text{trace}(BA)) \\ &= \text{trace}((P_i P_j)^T \cdot (P_i P_j)) \quad ((AB)^T = B^T A^T; P_i, P_j \text{ symmetric}) \\ &\geq 0, \end{aligned}$$

since for a matrix  $M$

$$\begin{aligned} \text{trace}(M^T M) &= \sum_i (M^T M)_{ii} \\ &= \sum_i \sum_j (M^T)_{ij} (M)_{ji} \\ &= \sum_i \sum_j m_{ij}^2 \\ &\geq 0. \end{aligned}$$

So we have a sum of non-negative terms being zero. So each term must be zero. That is, the square of each element of  $P_i P_j$  must be zero. So each element of  $P_i P_j$  is zero, so matrix  $P_i P_j$  is zero:

$$P_i P_j = 0 \quad (i \neq j).$$

This is the condition that the *linear forms*  $P_1 x, \dots, P_k x$  be independent (below). Since the  $P_i x$  are independent, so are the  $(P_i x)^T (P_i x) = x^T P_i^T P_i x$ , i.e.  $x^T P_i x$  as  $P_i$  is symmetric and idempotent. That is, the *quadratic forms*  $x^T P_1 x, \dots, x^T P_k x$  are also independent.

We now have

$$x^T x = x^T P_1 x + \dots + x^T P_k x.$$

The left is  $\sigma^2 \chi^2(n)$ ; the  $i$ th term on the right is  $\sigma^2 \chi^2(n_i)$ .

We summarise our conclusions.

**Theorem (Chi-Square Decomposition Theorem).** If

$$I = P_1 + \dots + P_k,$$

with each  $P_i$  a symmetric projection matrix with rank  $n_i$ , then

(i) the ranks sum:

$$n = n_1 + \dots + n_k;$$

(ii) each quadratic form  $Q_i := x^T P_i x$  is chi-squared:

$$Q_i \sim \sigma^2 \chi^2(n_i);$$

(iii) the  $Q_i$  are mutually independent.

This fundamental result gives all the distribution theory commonly needed for the Linear Model (for which see e.g. [BF]). In particular, since  $F$ -distributions are defined in terms of distributions of independent chi-squares, it explains why we constantly encounter  $F$ -statistics, and why all the tests of hypotheses that we encounter will be  $F$ -tests. This is so throughout the Linear Model – Multiple Regression, as here, Analysis of Variance, Analysis of Covariance and more advanced topics.

*Note.* The result above generalises beyond our context of projections. With the projections  $P_i$  replaced by symmetric matrices  $A_i$  of rank  $n_i$  with sum  $I$ , the corresponding result (Cochran's Theorem, 1934, also known as the Fisher-Cochran theorem) is that (i), (ii) and (iii) are *equivalent*. The proof is harder (one needs to work with *quadratic* forms, where we were able to work with *linear* forms). For monograph treatments, see e.g. Rao [R], sections 1c.1 and 3b.4 and Kendall & Stuart [KS1], sections 15.16 - 15.21.

### 3. The multivariate normal (Gaussian) distribution

In  $n$  dimensions, for a random  $n$ -vector  $\mathbf{X} = (X_1, \dots, X_n)^T$ , one needs

- (i) a *mean vector*  $\mu = (\mu_1, \dots, \mu_n)^T$  with  $\mu_i = EX_i$ ,  $\mu = E[X]$ ;
- (ii) a *covariance matrix*  $\Sigma = (\sigma_{ij})$ , with  $\sigma_{ij} = \text{cov}(X_i, X_j)$ :  $\Sigma = \text{cov}(X)$ .

First, note how mean vectors and covariance matrices transform under linear changes of variable:

**Proposition.** If  $Y = AX + b$ , with  $Y, b$   $m$ -vectors,  $A$  an  $m \times n$  matrix and  $X$  an  $n$ -vector, (i) the mean vectors are related by  $E[Y] = AE[X] + b = A\mu + b$ ;

(ii) the covariance matrices are related by  $\Sigma_Y = A\Sigma_X A^T$ .