



Without loss of generality assume Aaron moves to position $(f, 0)$ in polar coordinates and Erin moves to position $(g, 0)$ in polar coordinates, where $f = f(R)$ and g is constant, and the true position of the fly is (R, θ)

$$P(R \leq r) = \frac{\pi r^2}{\pi \cdot 1^2} = r^2 \text{ for } 0 \leq r \leq 1, \text{ so } f_R(r) = 2r \text{ for } 0 \leq r \leq 1.$$

$$\theta \sim \text{Uniform}(0, \pi) \text{ so } P(0 \leq \alpha) = \frac{\alpha}{\pi} \text{ for } 0 \leq \alpha \leq \pi.$$

Let D_E and D_A be the distance from the fly to each robot.

$$\text{Then, } D_E = |g - R| \text{ and } D_A = \sqrt{R^2 + f^2 - 2Rf \cos \theta} \text{ (using the cosine rule)}$$

$$\begin{aligned} \Rightarrow P(\text{Aaron wins}) &= P(D_A < D_E) = P(D_A^2 < D_E^2) \\ &= P(R^2 + f^2 - 2Rf \cos \theta < g^2 + R^2 - 2gR) \\ &= P(\cos \theta > \frac{f^2 + g(2R - g)}{2Rf}) \\ &= \int_0^1 P(\cos \theta > \frac{f^2 + g(2R - g)}{2Rf} | R=r) \cdot 2r \, dr \end{aligned}$$

Since both bots play optimally, assume Aaron knows the value of g , and he also knows the value of r .

$$\text{If } g > 2r, \text{ choosing } f=0 \text{ gives } P(\cos \theta > \frac{f^2 + g(2r - g)}{2rf}) = P(\cos \theta > -\infty) = 1$$

$$\text{If } g < 2r, \text{ choosing } f = \sqrt{g(2r - g)} \text{ gives the minimum value of } \frac{f^2 + g(2r - g)}{2rf}, \text{ and } P(\cos \theta > \frac{f^2 + g(2r - g)}{2rf}) = \cos^{-1}\left(\sqrt{\frac{g}{r}(2 - \frac{g}{r})}\right) \cdot \frac{1}{\pi}.$$

$$\Rightarrow P(\text{Aaron wins}) = \int_0^{2g} 1 \cdot 2r \, dr + \int_{2g}^1 \frac{2r}{\pi} \cos^{-1}\left(\sqrt{\frac{g}{r}(2 - \frac{g}{r})}\right) \, dr$$

Substituting $r = g u$ in the second integral,

$$P(\text{Aaron wins}) = \frac{1}{4}g^2 + \frac{2g^2}{\pi} \int_{\frac{1}{2}}^{\frac{2}{g}} u \cos^{-1}\left(\sqrt{\frac{1}{u}(2 - \frac{1}{u})}\right) \, du$$

Dividing by g^2 and differentiating with respect to g ,

$$\begin{aligned} \frac{d}{dg} \left(\frac{P}{g^2} \right) &= \frac{d}{dg} \left(\frac{1}{4} \right) + \frac{d}{dg} \left(\frac{2}{\pi} \int_{\frac{1}{2}}^{\frac{2}{g}} u \cos^{-1}\left(\sqrt{\frac{1}{u}(2 - \frac{1}{u})}\right) \, du \right) \\ \frac{g^2 \frac{dP}{dg} - 2Pg}{g^4} &= \frac{2}{\pi} \cdot -\frac{1}{g^2} \cdot \frac{1}{g} \cos^{-1}\left(\sqrt{g(2 - g)}\right) \end{aligned}$$

$$\text{Erin chooses } g \text{ that minimizes } P \Rightarrow \frac{dP}{dg} = 0 \text{ gives } P = \frac{1}{\pi} \cos^{-1}\left(\sqrt{g(2 - g)}\right) \text{ at the optimal value of } g$$

Thus, at the critical value $g = g'$,

$$\begin{aligned} \frac{1}{\pi} \cos^{-1}\left(\sqrt{g'(2 - g')}\right) &= \frac{1}{4}g'^2 + \frac{2g'^2}{\pi} \int_{\frac{1}{2}}^{\frac{2}{g'}} u \cos^{-1}\left(\sqrt{\frac{1}{u}(2 - \frac{1}{u})}\right) \, du \\ \Rightarrow \frac{\pi}{8} - \frac{1}{2g'^2} \cos^{-1}\left(\sqrt{g'(2 - g')}\right) + \int_{\frac{1}{2}}^{\frac{2}{g'}} u \cos^{-1}\left(\sqrt{\frac{1}{u}(2 - \frac{1}{u})}\right) \, du &= 0 \end{aligned}$$

Using that $0 \leq g' \leq 2$ we can solve this via any root-finding software, giving the solution $g' = 0.5013069942$, with corresponding probability

$$P(\text{Aaron wins}) = 0.1661864865 \quad (10dp)$$