Meetings

Tuesday, April 2nd

* Discussed the exact scope of the project:
  + Rather than actually rebuild the remote control, since this is mainly a programming project, control the car via the STM discovery.
  + Leave the car chip alone.
* Wire the rc car into a breadboard to connect to the discovery’s RX/TX pins
* Due to difficulty of reverse engineering the RC car, may scrap it for controlling an LED strip via the discovering and displaying what patterns it shows on an LCD screen.

Friday, March 29th

* First milestone document due
  + Discussion with Ashton states that the last milestone may not be possible due to timing.
* Next meeting with everyone decided for April 2nd @ 8:00a

Wednesday, March 27th

* More in-depth discussion about what milestones to expect for the project:
  + 1st – dismantle the RC car, figure out components, and interface with Discovery Board
  + 2nd – accelerator
  + 3rd – turning
  + 4th – obstacle sensing