MAS-1 Study Review

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- Probability Review
- Stochastic Processes
- Life Contingencies
- → Simulation
- Statistics
- Extended Linear Model
- Time Series

Lesson 1 : Probability Review

> Bernouilli Shortcut: If a random variable can only assume two values a and b with probability q and 1 - q, then is variance is $a(1-a)(b-a)^2$

Lesson 2 : Parametric Distri**butions**

- > Transformations:
 - Transformed: $\tau > 0$
 - Inverse: $\tau = -1$
 - Inverse-Transformed : τ < 0, τ ≠ 1

Lesson 4: Markov Chains

> Chapman-Kolmogorov:

$$P_{ij}^{(n+m)} = \sum_{k=0}^{\infty} P_{ik}^{(n)} P_{kj}^{(m)}$$

$$p_{j} = \begin{cases} \frac{j}{N}, & r = 1\\ \frac{r^{j} - 1}{r^{N} - 1}, & r \neq 1 \end{cases}$$
où $r = \frac{q}{n}$, p: winning prob.

> **Algorithmic efficency:** with N_i = number of steps from j^{th} solution to best solution.

$$\begin{split} \mathrm{E}[N_j] &= \sum_{i=1}^{j-1} \frac{1}{i} \\ \mathrm{Var}(N_j) &= \sum_{i=1}^{j-1} \left(\frac{1}{i}\right) \left(1 - \frac{1}{i}\right) \\ \mathrm{As} \ j \to \infty, \, \mathrm{E}[N_j] \to \ln j, \, \mathrm{Var}(N_j) \to \ln j \end{split}$$

Lesson 5 : Markov Chain Classification

- > An **absorbing** state is one that cannot be exi-
- > State j is **accessible** $(i \rightarrow j)$ from state i if p_{ij}^n > 0, $\forall n \geq 0$.
- > Two states **communicate** if $i \leftrightarrow j$.
- communicate with each other.
- > A Markov chain is **irreductible** if it has only one class.
- ightarrow A state (class) is **recurrent** if the probability of ightarrow **Probability of extinction :** reentering the state is 1. $\sum_{n=1}^{\infty} p_{ii}^{(n)} = \infty$
- > A state (class) si **transcient** if it is not recur-
 - $\sum_{n=1}^{\infty}p_{ii}^{(n)}<\infty$
- > A finite Markov Chain must have at least one recurrent class. If it is irreductible, then it is recurrent.

Lesson 6: Markov Chains Li- Lesson 9: Time Reversible miting Probability

- > A chain is **positive recurrent** is the expected number of transitions untils the state occur is finite, null recurrent otherwise. Null recurrent mean that the long-term proportion of time in each state is 0.
- > A chain is **periodic** when states occur every n periode for n > 1.
- > A chain is **aperiodique** when the periode is 1. In other world, $P_{ii}^{(1)} > 0$, $\forall i$
- > A chain is **ergodic** when the chain is aperiodique and positive irreductible recurrent.
- > Stationary probability:

$$\pi_j = \sum_{i=1}^n P_{ij} \pi_i \quad \sum_{i=1}^n \pi_i = 1$$

> **Limiting probabilities:** is the chain is ergodic, then

$$\mathbf{P}^{(\infty)} = \begin{pmatrix} \pi_1 & \pi_2 & \pi_3 \\ \pi_1 & \pi_2 & \pi_3 \\ \pi_1 & \pi_2 & \pi_3 \end{pmatrix}$$

Lesson 7: Time in Transient States

- > Tips: Inverting a matrix
- > $\mathbf{S} = (\mathbf{I} \mathbf{P}_{\text{transcient}})^{-1}$, where s_{ij} is the time in state j given that the current state is i.
- $\Rightarrow f_{ij} = \frac{s_{ij} \delta_{i,j}}{s_{jj}} = \sum_{n=1}^{\infty} f_{ij}^{(n)}$, where f_{ij} is the probability that state i ever transitions to state j.

Lesson 8: Branching Processes

- > A branching process is a special type of Markov chain representing the growth or extinction of a population.
- \gt $E[X_n] = E[Z]^n$, where E[Z] is the expected number of people born in a generation.
- > A **class** of states is a maximal set of state that $\operatorname{Var}(X_n) = \operatorname{Var}(Z) \cdot \operatorname{E}[Z]^{n-1} \sum_{k=1}^n \operatorname{E}[Z]^{k-1}$
 - > If X_0 ≠ 1 mean and variance of X_n need to be multiplicated by X_0 .

$$\pi_0 = \sum_{j=1}^{\infty} p_j \pi_0^j$$

- $\mu \le 1 \Rightarrow \pi_0 \ge 1$, if $X_0 = 1$.
- $-\mu > 1 \Rightarrow \pi_0 < 1$, if $X_0 = 1$.

For cubic equation, it guaranteed to factor $(\pi_0 - 1)$. Tips : Synthetic Division

ightarrow If ${f Q}$ is the reverse-time Markov chain for ergodic P, then

$$\pi_i Q_{ij} = \pi_j P_{ji}$$
 with $P_{ii} = Q_{ii}$ and if $p_{ij} = 0 \Leftrightarrow Q_{ji} = 0$

> If Q = P, then P is said to be **time-reversible**.

Lesson 10: Exponential Distribution

> Lack of memory:

$$\Pr\left(X>k+x|X>k\right)=\Pr\left(X>x\right)$$

> **Minimum**: if $X_i \sim \text{Exp}(\lambda_i)$, then

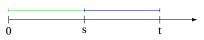
$$\min(X_1, X_2, ..., X_n) \sim \exp\left(\sum_{i=1}^n \lambda_i\right)$$

> The sum of 2 Exponentials randoms variables is the sum of the maximum and the minimum, since one must be the min and the other the

$$X_1 + X_2 = \min(X_1, X_2) + \max(X_1, X_2)$$

Lesson 11: Poisson Process

- > $X(t) \sim \text{Poisson}[m(t)]$, where m(t) is **mean va**lue function representing the mean of the number events before time t.
- > Poisson process can't deacrease over time. $N(t) \ge N(s)$
- N(0) = 0
- > Increament are **independent**:



$$\Pr[N(t) - N(s) = n | N(s) = k] = \Pr[N(t) - N(s) = n]$$

> Non-homogeneous Poisson process:

$$m(t) = \int_0^t \lambda(u) \, \mathrm{d}u$$

where $\lambda(t)$ is the **intensify function**

Homogeneous Poisson process: The Poisson process is said to be homogeneous when the intensify function is a constant.

$$m(t) = \int_0^t \lambda \, \mathrm{d}u = \lambda t$$

We then say that the process have stationary increments.

$$\Pr[N(s)] = \Pr[N(t) - N(s)]$$

Lesson 12: Poisson Process Time To Next Events

- T_n is the time between the n^e event and the (n-1)e event.
- $> S_n = \sum_{i=1}^n T_i$, is the time for the n^e event.
- > $F_{T_1}(t) = 1 e^{-\int_0^t \lambda(u) \, du}$
- > For homogeneous process:

$$T_n \sim \operatorname{Exp}(\lambda)$$

 $S_n \sim \text{Gamma}(n, \lambda)$

Lesson 13 : Poisson Process **Counting Special Type**

> If event of type 1 occur with probability $\alpha_1(t)$, then the event follow a Poisson process with

$$m(t) = \int_0^t \lambda(u) \alpha_1(u) \, \mathrm{d}u$$

Lesson 14: Poisson Process **Other Characteristics**

- > Only for homogeneous Poisson processes.
- \rightarrow The probability of k event from process 1 is given by:

$$k \sim \text{Binomial}(k+l-1,\frac{\lambda_1}{\lambda_1+\lambda_2})$$
 Then the probability that k event from process

1 occur before l from process 2 is :

$$\sum_{i=k}^{k+l-1} {k+l-1 \choose i} \left(\frac{\lambda_1}{\lambda_1 + \lambda_2}\right)^i \left(\frac{\lambda_2}{\lambda_1 + \lambda_2}\right)^{k+l-1-i}$$

 \rightarrow Given that exactly N(t) = k Poisson events occured before time t, the join distribution of event time is the joint distribution of k independent uniform random variable on (0, t).

$$F_{S_1,...,S_n|n(t)}(s_1,...s_n|k) = \frac{k!}{t^k}$$

- > For *k* independent uniform random variable on (0, t), the expected value of the jth order statistics is: $E[T^{(j)}] = \frac{jt}{(k+1)}$.
- > Tips: Statistic Order

Lesson 15: Poisson Process Sums and Mixtures

- > A Sums of independent Poisson random variables is a Poisson random with intensify function $\lambda(t) = \sum \lambda_i(t)$. Warning: Substraction dont give a Poisson random variable.
- > A Mixture of Poisson processes is not a Poisson processes.
 - Discrete mixture :

$$F_{X(t)}(t) = \sum_i w_i F_{X_i(t)}(t) \label{eq:fitting}$$
 where $w_i > 0$, $\sum w_i = 1$

- Continuous mixture :

$$F_{X(t)}(t) = \int F_{\{X_u(t)\}}(t) f(u) du$$

- If $N(t)|\lambda$ is a Poisson random variable and $\lambda \sim \text{Gamma}(\alpha, \theta)$, then $N(t) \sim$ NegBin($r = \alpha, \beta = \theta t$).

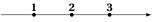
Lesson 16: Compound Poisson Processes

> A **compound** random variable *S* is define by $S = \sum_{i=1}^{N} X_i$ where N is the **primary** distribution and X the **secondary** distribution.

- \rightarrow If N(t) is a Poisson process, then S(t) is a com- \rightarrow Inclusion/exclusion bounds using minimal pound Poisson process with:
 - $E[S(t)] = \lambda t E[X]$
 - $Var(S(t)) = \lambda t E[X^2]$
 - \rightarrow If X_i is discrete, we can separate the process into a sum of subprocess view in LESSON 13.
 - > Sums of compound homogeneous Poisson process is also a Poisson process with:
 - $N(t) \sim \text{Pois}(\sum \lambda_i)$
 - $\ F_X(x) = \sum_i w_i F_{X_i(t)}(t), \quad w_i = \frac{\lambda_i}{\sum \lambda_i}$

Lesson 17: Reliability Structure Functions

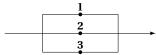
- $\Rightarrow \phi(\mathbf{x})$ is the **structure** function for a systeme. It equal 1 if the systeme function, 0 otherwise.
- A series system is define as a minimal path set. The system is working if all components are working.



The serie structure function is define as

$$\phi(\mathbf{x}) = \prod_{i=1}^{n} x_i$$

> A parallel system is define as a minimal cut set. The systeme is working at least 1 components is working.



The parallel structure function is define as

$$\phi(\mathbf{x}) = 1 - \prod_{i=1}^{n} (1 - x_i)$$

- > Tips: Minimal path set is all way for the system to work, and the minimal cut set is all the way for the system to not work.
- \rightarrow Tips: If set is $\{1,2,3\}$ and $\{1,2\}$, the *minimal* mean we only take {1,2}.
- > Tips: Minimal cut is a serie of parallel structure and minimal path is a parallel of serie structure.

Lesson 18: Reliability Probabilities

- $r(\mathbf{p})$ is the same polynomial as $\phi(\mathbf{x})$.
- > Inclusion/exclusion bounds using minimal path:

$$r(\mathbf{p}) \le \sum A_i$$

 $r(\mathbf{p}) \ge \sum A_i - \sum A_i \cup A_j$

$$r(\mathbf{p}) \leq \sum A_i - \sum A_i \cup A_j + \sum A_i \cup A_j \cup A_k$$
 Force of mortality: where $A_i = \sum p_i$ is the probability of the i^e minimal path set work. $\mu_{x+t} = \frac{f_{T_x}(t)}{t p_x}$

cut:

$$\begin{split} 1-r(\mathbf{p}) &\leq \sum A_i \\ 1-r(\mathbf{p}) &\geq \sum A_i - \sum A_i \cup A_j \\ 1-r(\mathbf{p}) &\leq \sum A_i - \sum A_i \cup A_j + \sum A_i \cup A_j \cup A_k \\ \text{where } A_i &= \sum (1-p_i) \text{ is the probability of the } \mathbf{i}^{\mathrm{c}} \\ \text{minimal cut set work.} \end{split}$$

> Bounds using intersections :

$$\prod \phi(\mathbf{X})^{\mathbf{min. cut}} \leq r(\mathbf{p}) \leq \prod \phi(\mathbf{X})^{\mathbf{min. path}}$$

$$1 - P_n = \sum_{k=1}^{n-1} {n-1 \choose k-1} q^{k(n-k)} P_k$$

$$1 - P_n \le (n+1)q^{n-1}$$

$$P_{k-1} = 1$$

Lesson 19: Reliability Time to Failure

> Expected amound of time to failure:

$$E[\mathbf{system \, life}] = \int_0^\infty r(\bar{\mathbf{F}}(\mathbf{t})) \, \mathrm{d}t$$

where,

- For serie system:

$$r(\bar{\mathbf{F}}(\mathbf{t})) = \prod_{i=1}^{n} \bar{F}_i(t)$$

$$r(\bar{\mathbf{F}}(\mathbf{t})) = \prod_{i=1}^{n} \bar{F}_{i}(t)$$
- For parallel system :
$$r(\bar{\mathbf{F}}(\mathbf{t})) = 1 - \prod_{i=1}^{n} F_{i}(t)$$

- Shortcut: k out of n system with exponentials(θ): $\mathrm{E}[T] = \theta \sum_{i=k}^{n} \frac{1}{i}$
- > Hazard rate function (failure rate function) : $h(t) = \frac{f(t)}{\bar{F}(t)}$

$$h(t) = \frac{f(t)}{\bar{F}(t)}$$

and we say that the distribution

- is an increasing failure rate if h(t) is nondeacreasing function of t.
- is an deacreasing failure rate if h(t) is non-increasing function of t.
- > Cumulatice hazard function :

$$H(t) = \int_0^t h(u) \, \mathrm{d}u = -\ln \bar{F}(t)$$

with $\frac{H(t)}{t}$ the average of the hazard rate.

Lesson 20: Survival Models

- $\Rightarrow t p_x = \frac{\ell_{x+t}}{\ell_x}, \quad t q_x = \frac{\ell_{x} \ell_{x+t}}{\ell_x}$
- $\Rightarrow _{t|u}q_{x}=rac{\ell _{x+t}-\ell _{x+t+u}}{\ell _{x}}$
- $\rightarrow t+up_x = up_x \cdot tp_{x+u}$
- $\rightarrow t|uq_x = t + uq_x tq_x = tp_x \cdot uq_{x+t}$
- \rightarrow Let be N_x the number of life surviving to age x, then

$$(N_{x+t}|N_x=n)\sim \mathrm{Bin}(n,t\,p_x)$$

$$\mu_{x+t} = \frac{f_{T_x}(t)}{t p_x} = -\frac{\mathrm{d}}{\mathrm{d}t} \ln t p_x$$

> Linear interpolation(D.U.D):

$$\ell_{x+t} = (1-t)\ell_x + t\ell_{x+1}$$

$$tq_x = t \cdot q_x$$

$$\mu_{x+t} = \frac{q_x}{1 - t \cdot q_x}$$

> **Expected life time :** Let $k_x = \lfloor T_x \rfloor$, the *full years* until death. Then e_x is the **curtate life** expectancy and e_x the complete life expec**tancy**. ω is the age where $\ell_{\omega} = 0$ and $\omega = \infty$ by convention is nothing is said.

$$e_{x} = E[K_{x}] = \sum_{k=1}^{\omega - x-1} {}_{k} p_{x}$$

$$\mathring{e}_{x} = E[T_{x}] = \int_{0}^{\omega - x} {}_{t} p_{x} dt \stackrel{\text{D.U.D}}{=} e_{x} + 0.5$$

Lesson 21: Contingent Pay-

ments

The contract here are define with K_x to pay at the end of death year. All same contract can be define with T_x to pay at the moment of death. Then we use integral instead of sum and use

$$\Pr(K = k) = {}_{k} p_{x} q_{x+k} \Rightarrow f_{T_{x}}(t) = {}_{t} p_{x} \mu_{x+t}$$

> Life Insurance:

- Whole Life insurance :
$$A_{x} = \sum_{k=0}^{\infty} v^{k+1}{}_{k} p_{x} q_{x+k}$$

- Term Life insurance:
$$A_{x:\overline{n}|}^{1} = \sum_{k=0}^{n} v^{k+1}{}_{k} p_{x} q_{x+k}$$

- Deferred insurance:
$$m|A_x = \sum_{k=m}^{\infty} v^{k+1} {}_k p_x q_{x+k}$$

- Endowment insurance :

$$A_{x:\overline{n}} = A_{x:\overline{n}}^1 + {}_{n}E_x$$

- Pure Endowment :

$$_{n}E_{x}=v^{n}{}_{n}p_{x}$$

> Life Annuities:

- Whole Life annuity

$$\ddot{a}_x = \sum_{k=0}^{\infty} v^k_{\ k} p_x$$
 – Temporary Life annuity n

$$\ddot{a}_{x:\overline{n}|} = \sum_{k=0}^{n} v^{k}{}_{k} p_{x}$$

- Deferred annuity
$$m|\ddot{a}_x = \sum_{k=m}^{\infty} v^k{}_k p_x$$

- Certain and life annuity

$$\ddot{a}_{\overline{x:\overline{n}|}} = \ddot{a}_{\overline{n}|} + {}_{m|}\ddot{a}_x$$

> Illustrative Life Table :

$$- A_x = v^n q_x + p_x A_{x+1}$$

$$-\ddot{a}_{r} = 1 + v n_{r} \ddot{a}_{r+1}$$

-
$$\ddot{a}_x = 1 + v p_x \ddot{a}_{x+1}$$

- $A_{x:\overline{n}|}^1 = A_x - n E_x A_{x+n}$

-
$$\ddot{a}_{x:\overline{n}|} = \ddot{a}_x - {}_n E_x \ddot{a}_{x+n}$$

$$- m_{\parallel} A_x = m E_x A_{x+m}$$

$$- m | \ddot{a}_X = m E_X \ddot{a}_{X+m}$$

$$- \ddot{a}_x = 1 + a_x$$

$$- A_X = 1 - d \ddot{a}_X$$

> **Joint life annuity**(\ddot{a}_{xy}) make payments until the earliest death pf two lives.

Shortcut: $\forall t \in (0,1), \forall x \in \mathbb{N}, x < x + t < x + 1: \Rightarrow$ Last survivor annuity($\ddot{a}_{\overline{xy}}$) make payments until the last death of two lives.

$$\ddot{a}_x + \ddot{a}_y = \ddot{a}_{xy} + \ddot{a}_{\overline{xy}}$$

> Premiums:

$$M \cdot A_{x} = P \ddot{a}_{x}$$

$$P = \frac{M \cdot A_{x}}{\ddot{a}_{x}} = \frac{M}{\ddot{a}_{x}} - M \cdot d$$

Simulation-Inverse Method

Normal Approximation

$$F_X(x) = \Phi\left(\frac{X - E[X]}{\sqrt{Var(X)}}\right)$$

> **Continuity correction** is necessary when X is discrete. $F_X(x) = \Phi\left(\frac{(X \pm k) - \mathrm{E}[X]}{\sqrt{\mathrm{Var}(X)}}\right)$ where k is the mid-point of the discrete value.

Appendix

Inverting a matrix

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

Ajouter pour une matrice 3x3

Synthetic Division

Exemple: Factorize $x^3 - 12x^2 - 81$

$$\begin{array}{c|ccccc}
 & 1 & -12 & 0 & -81 \\
\hline
3 & 3 & -27 & -81 \\
\hline
& 1 & -9 & -27 & 0 \\
\end{array}$$
then, $x^3 - 12x^2 - 81 = (x - 3)(x^2 - 9x - 27)$

Deductible and Limite

$$X = \min(X; d) + \max(0; X - d)$$

$$E[X] = E[\min(X; d)] + E[\max(0; X - d)]$$

$$= E[(X \land d)] + E[(x - d)_+]$$

$$= E[(X \land d)] + e_X(d) \cdot S_X(d)$$

Statistic Order

>
$$Y_1 = \min(X_1, ..., X_n)$$

 $f_{Y_1}(y) = nf(y)[S(y)]^{n-1}$
 $S_{Y_1}(y) = \prod_{i=1}^n \Pr(X_i > x)$
> $Y_n = \max(X_1, ..., X_n)$
 $f_{Y_n}(y) = nf(y)[F(y)]^{n-1}$
 $F_{Y_n}(y) = \prod_{i=1}^n \Pr(X_i \le x)$
> $Y_k \in (Y_1, ..., Y_k, ..., Y_n)$
 $f_{Y_k}(y) = \frac{n!}{(k-1)!(n-k)!} f(y)[F(y)]^{k-1} [S(y)]^{n-k}$
 $F_{Y_k}(y) = \Pr(\text{at least k of n } X_i \text{ are } \le y)$
 $= \sum_{i=k}^n \binom{n}{i} [F(y)]^i [S(y)]^{n-j}$

> $x + y = \min(x, y) + \max(x, y)$, since one is for sure the max and the other the min.

Mode: Most likely probability

 \Rightarrow g(x) = f(x) or some time $g(x) = \ln f(x)$

> **Mode** is the x that respects: g'(x) = 0