MAS-1 Study Review

Nicholas Langevin

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- Probability Review
- Stochastic Processes
- → Life Contingencies
- Simulation
- Statistics
- Extended Linear Model
- Time Series

Lesson 1 : Probability Review

> Bernouilli Shortcut: If a random variable can only assume two values a and b with probability q and 1 - q, then is variance is $q(1-q)(b-a)^2$

Lesson 2: Parametric Distri**butions**

- > Transformations:
 - Transformed: $\tau > 0$
 - Inverse: $\tau = -1$
 - Inverse-Transformed : τ < 0, τ ≠ 1

Lesson 4: Markov Chains

$$P_{ij}^{(n+m)} = \sum_{k=0}^{\infty} P_{ik}^{(n)} P_{kj}^{(m)}$$

> Gambler's ruin: Let N the target and j the actual status.

$$p_{j} = \begin{cases} \frac{j}{N}, & r = 1\\ \frac{r^{j} - 1}{r^{N} - 1}, & r \neq 1 \end{cases}$$

où $r = \frac{q}{p}$, p: winning prob.

> **Algorithmic efficency:** with N_i = number of steps from j^{th} solution to best solution.

$$\mathrm{E}[N_j] = \sum_{i=1}^{j-1} \frac{1}{i}$$

$$\begin{split} \operatorname{Var}(N_j) &= \sum_{i=1}^{j-1} \left(\frac{1}{i}\right) \left(1 - \frac{1}{i}\right) \\ \operatorname{As}\ j &\to \infty, \operatorname{E}[N_j] \to \ln j, \operatorname{Var}(N_j) \to \ln j \end{split}$$

Lesson 5 : Markov Chain Classification

- > An **absorbing** state is one that cannot be exi-
- > State j is **accessible** $(i \rightarrow j)$ from state i if p_{ij}^n > 0, $\forall n \geq 0.$
- > Two states **communicate** if $i \leftrightarrow j$.
- > A **class** of states is a maximal set of state that communicate with each other.
- > A Markov chain is **irreductible** if it has only one class.
- > A state (class) is **recurrent** if the probability of reentering the state is 1. $\sum_{n=1}^{\infty} p_{ii}^{(n)} = \infty$
- > A state (class) si **transcient** if it is not recur-

 $\textstyle \sum_{n=1}^{\infty} p_{ii}^{(n)} < \infty$

> A finite Markov Chain must have at least one recurrent class. If it is irreductible, then it is recurrent.

Lesson 6: Markov Chains Li- Lesson 9: Time Reversible miting Probability

- > A chain is **positive recurrent** is the expected number of transitions until the state occur is finite, null recurrent otherwise. Null recurrent mean that the long-term proportion of time in each state is 0.
- > A chain is **periodic** when states occur every n periods for n > 1.
- > A chain is aperiodic when the period is 1. In other world, $P_{ii}^{(1)} > 0$, $\forall i$
- > A chain is **ergodic** when the chain is aperiodic and positive irreductible recurrent.
- > Stationary probability:

$$\pi_j = \sum_{i=1}^n P_{ij} \pi_i \quad \sum_{i=1}^n \pi_i = 1$$

> **Limiting probabilities:** if the chain is ergodic,

$$\mathbf{P}^{(\infty)} = \begin{pmatrix} \pi_1 & \pi_2 & \pi_3 \\ \pi_1 & \pi_2 & \pi_3 \\ \pi_1 & \pi_2 & \pi_3 \end{pmatrix}$$

Lesson 7: Time in Transient States

- > Tips: Inverting a matrix
- > $\mathbf{S} = (\mathbf{I} \mathbf{P}_{\text{transcient}})^{-1}$, where s_{ij} is the time in state j given that the current state is i.
- $\Rightarrow f_{ij} = \frac{s_{ij} \delta_{i,j}}{s_{jj}} = \sum_{n=1}^{\infty} f_{ij}^{(n)}$, where f_{ij} is the probability that state i ever transitions to state j.

Lesson 8: Branching Processes

- > A branching process is a special type of Markov chain representing the growth or extinction of a population.
- \gt $E[X_n] = E[Z]^n$, where E[Z] is the expected number of people born in a generation.
- $\Rightarrow \operatorname{Var}(X_n) = \operatorname{Var}(Z) \cdot \operatorname{E}[Z]^{n-1} \sum_{k=1}^n \operatorname{E}[Z]^{k-1}$
- > If $X_0 \neq 1$ mean and variance of X_n need to be multiplicated by X_0 .
- > Probability of extinction:

$$\pi_0 = \sum_{j=1}^{\infty} p_j \pi_0^j$$

- $\mu \le 1 \Rightarrow \pi_0 \ge 1$, if $X_0 = 1$.
- $-\mu > 1 \Rightarrow \pi_0 < 1$, if $X_0 = 1$.

For cubic equation, it guaranteed to factor $(\pi_0 - 1)$. Tips : Synthetic Division

ightarrow If ${f Q}$ is the reverse-time Markov chain for ergodic P, then

 $\pi_i Q_{ij} = \pi_j P_{ji}$ with $P_{ii} = Q_{ii}$ and if $p_{ij} = 0 \Leftrightarrow Q_{ji} = 0$

> If Q = P, then P is said to be **time-reversible**.

Lesson 10: Exponential Distribution

> Lack of memory:

$$\Pr(X > k + x | X > k) = \Pr(X > x)$$

> **Minimum**: if $X_i \sim \text{Exp}(\lambda_i)$, then

$$\min(X_1, X_2, ..., X_n) \sim \exp\left(\sum_{i=1}^n \lambda_i\right)$$

> The sum of 2 Exponentials randoms variables is the sum of the maximum and the minimum, since one must be the min and the other the

$$X_1 + X_2 = \min(X_1, X_2) + \max(X_1, X_2)$$

Lesson 11: Poisson Process

- > $X(t) \sim \text{Poisson}[m(t)]$, where m(t) is **mean va**lue function representing the mean of the number events before time t.
- > Poisson process can't decrease over time. $N(t) \ge N(s)$ for $t \ge s$
- N(0) = 0
- > Increament are **independent**:



$$\Pr[N(t) - N(s) = n | N(s) = k] = \Pr[N(t) - N(s) = n]$$

> Non-homogeneous Poisson process:

$$m(t) = \int_0^t \lambda(u) \, \mathrm{d}u$$

where $\lambda(t)$ is the **intensity function**

Homogeneous Poisson process: The Poisson process is said to be homogeneous when the intensity function is a constant.

$$m(t) = \int_0^t \lambda \, \mathrm{d}u = \lambda t$$

We then say that the process have stationary increments.

 $\Pr[N(s-t)] = \Pr[N(t) - N(s)]$

Lesson 12: Poisson Process Time To Next Events

- T_n is the time between the nth event and the (n-1)th event.
- $> S_n = \sum_{i=1}^n T_i$, is the time for the n^e event.
- > $F_{T_1}(t) = 1 e^{-\int_0^t \lambda(u) \, du}$
- > For homogeneous process:

$$T_n \sim \operatorname{Exp}(\lambda)$$

 $S_n \sim \text{Gamma}(n, \lambda)$

Lesson 13: Poisson Process > If N(t) is a Poisson process, then S(t) is a com- > Inclusion/exclusion bounds using minimal **Counting Special Type**

> If event of type 1 occur with probability $\alpha_1(t)$, then the event follow a Poisson process with

$$m(t) = \int_0^{\bar{t}} \lambda(u) \alpha_1(u) \, \mathrm{d}u$$

Lesson 14: Poisson Process **Other Characteristics**

- > Only for homogeneous Poisson processes.
- \rightarrow The probability of k event from process 1 is given by:

$$k \sim \text{Binomial}\left(k+l-1,\frac{\lambda_1}{\lambda_1+\lambda_2}\right)$$
 Then the probability that k event from process

1 occur before l from process 2 is :

$$\sum_{i=k}^{k+l-1} \binom{k+l-1}{i} \left(\frac{\lambda_1}{\lambda_1 + \lambda_2}\right)^i \left(\frac{\lambda_2}{\lambda_1 + \lambda_2}\right)^{k+l-1-i}$$

 \rightarrow Given that exactly N(t) = k Poisson events occured before time t, the joint distribution of event time is the joint distribution of k independent uniform random variables on (0, t).

$$F_{S_1,...,S_n|n(t)}(s_1,...s_n|k) = \frac{k!}{t^k}$$

- > For *k* independent uniform random variable on (0, t), the expected value of the jth order statistics is : $E[T^{[j]}] = \frac{jt}{(k+1)}$.
- > Tips: Statistic Order

Lesson 15: Poisson Process Sums and Mixtures

- > A Sums of independent Poisson random variables is a Poisson random with intensify function $\lambda(t) = \sum \lambda_i(t)$. Warning: Substraction don't give a Poisson random variable.
- > A Mixture of Poisson processes is not a Poisson processes.
 - Discrete mixture :

$$F_{X(t)}(t) = \sum_i w_i F_{X_i(t)}(t) \label{eq:fitting}$$
 where $w_i > 0$, $\sum w_i = 1$

- Continuous mixture :

$$F_{X(t)}(t) = \int F_{\{X_u(t)\}}(t) f(u) du$$

- If $N(t)|\lambda$ is a Poisson random variable and $\lambda \sim \text{Gamma}(\alpha, \theta)$, then $N(t) \sim$ NegBin($r = \alpha, \beta = \theta t$).

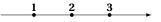
Lesson 16: Compound Poisson Processes

> A **compound** random variable S is define by $S = \sum_{i=1}^{N} X_i$ where N is the **primary** distribution and X the **secondary** distribution.

- pound Poisson process with:
 - $E[S(t)] = \lambda t E[X]$
 - $Var(S(t)) = \lambda t E[X^2]$
- \rightarrow If X_i is discrete, we can separate the process into a sum of subprocess view in Lesson 13: Poisson Process Counting Special Type.
- > Sums of compound homogeneous Poisson process is also a Poisson process with:
 - $N(t) \sim \text{Pois}(\sum \lambda_i)$
 - $-F_X(x) = \sum_i w_i F_{X_i(t)}(t), \quad w_i = \frac{\lambda_i}{\sum_i \lambda_i}$

Lesson 17: Reliability Structure Functions

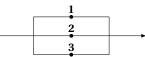
- $\rightarrow \phi(\mathbf{x})$ is the **structure** function for a systeme. It equal 1 if the systeme work, 0 otherwise.
- series system is define as a minimal path set. The system is working if all components are working.



The serie structure function is define as

$$\phi(\mathbf{x}) = \prod_{i=1}^{n} x$$

> A parallel system is define as a minimal cut set. The systeme is working if at least 1 components is working.



The parallel structure function is define as

$$\phi(\mathbf{x}) = 1 - \prod_{i=1}^{n} (1 - x_i)$$

- > Tips: Minimal path set is all way for the system to work, and the minimal cut set is all the way for the system to not work.
- \rightarrow Tips: If set is $\{1,2,3\}$ and $\{1,2\}$, the minimal mean we only take {1,2}.
- > Tips: Minimal cut is a serie of parallel structure and minimal path is a parallel of serie structure.

Lesson 18 : Reliability Proba- $\Rightarrow {}_{t}p_{x} = \frac{\ell_{x+t}}{\ell_{x}}, \quad {}_{t}q_{x} = \frac{\ell_{x}-\ell_{x+t}}{\ell_{x}}$ **bilities**

- $r(\mathbf{p})$ is the same polynomial as $\phi(\mathbf{x})$.
- > Inclusion/exclusion bounds using minimal path:

$$r(\mathbf{p}) \le \sum A_i$$

 $r(\mathbf{p}) \ge \sum A_i - \sum A_i \cup A_j$

$$r(\mathbf{p}) \leq \sum A_i - \sum A_i \cup A_j + \sum A_i \cup A_j \cup A_k$$
 Force of mortality: where $A_i = \sum p_i$ is the probability of the i^e minimal path set work. $\mu_{x+t} = \frac{f_{T_x}(t)}{t p_x}$

cut:

$$\begin{split} 1-r(\mathbf{p}) &\leq \sum A_i \\ 1-r(\mathbf{p}) &\geq \sum A_i - \sum A_i \cup A_j \\ 1-r(\mathbf{p}) &\leq \sum A_i - \sum A_i \cup A_j + \sum A_i \cup A_j \cup A_k \\ \text{where } A_i &= \sum (1-p_i) \text{ is the probability of the } i^\circ \\ \text{minimal cut set work.} \end{split}$$

> Bounds using intersections :

$$\prod \phi(\mathbf{X})^{\mathbf{min. cut}} \le r(\mathbf{p}) \le \prod \phi(\mathbf{X})^{\mathbf{min. path}}$$

$$1 - P_n = \sum_{k=1}^{n-1} {n-1 \choose k-1} q^{k(n-k)} P_k$$

$$1 - P_n \le (n+1) q^{n-1}$$

$$P_1 = 1$$

Lesson 19: Reliability Time to Failure

> Expected amound of time to failure:

$$E[\mathbf{system \, life}] = \int_0^\infty r(\bar{\mathbf{F}}(\mathbf{t})) \, \mathrm{d}t$$

where,

- For serie system:

$$r(\bar{\mathbf{F}}(\mathbf{t})) = \prod_{i=1}^{n} \bar{F}_i(t)$$

$$r(\bar{\mathbf{F}}(\mathbf{t})) = \prod_{i=1}^{n} \bar{F}_{i}(t)$$
- For parallel system :
$$r(\bar{\mathbf{F}}(\mathbf{t})) = 1 - \prod_{i=1}^{n} F_{i}(t)$$

- Shortcut: k out of n system with exponentials (θ) : $\mathrm{E}[T] = \theta \sum_{i=k}^n \frac{1}{i}$
- > Hazard rate function (failure rate function) : $h(t) = \frac{f(t)}{\bar{F}(t)}$

$$h(t) = \frac{f(t)}{\bar{F}(t)}$$

and we say that the distribution

- is an increasing failure rate if h(t) is nondeacreasing function of t.
- is an deacreasing failure rate if h(t) is non-increasing function of t.
- > Cumulatice hazard function :

$$H(t) = \int_0^t h(u) du = -\ln \bar{F}(t)$$

with $\frac{H(t)}{t}$ the average of the hazard rate.

Lesson 20: Survival Models

$$t p_x = \frac{\ell_{x+t}}{\ell_x}, \quad t q_x = \frac{\ell_x - \ell_{x+t}}{\ell_x}$$

- $\Rightarrow _{t|u}q_{x}=rac{\ell _{x+t}-\ell _{x+t+u}}{\ell _{x}}$
- $\rightarrow t+up_x = up_x \cdot tp_{x+u}$
- $\rightarrow t|uq_x = t + uq_x tq_x = tp_x \cdot uq_{x+t}$
- > Let be N_x the number of life surviving to age x, then

$$(N_{x+t}|N_x=n)\sim \mathrm{Bin}(n,t\,p_x)$$

$$\mu_{x+t} = \frac{f_{T_x}(t)}{t p_x} = -\frac{\mathrm{d}}{\mathrm{d}t} \ln t p_x$$

> Linear interpolation(D.U.D):

$$\ell_{x+t} = (1-t)\ell_x + t\ell_{x+1}$$

Shortcut: $\forall t \in (0,1), \forall x \in \mathbb{N}, x < x + t < x + 1$

 $tq_x = t \cdot q_x$

$$\mu_{x+t} = \frac{q_x}{1 - t \cdot q_x}$$

> **Expected life time :** Let $k_x = \lfloor T_x \rfloor$, the *full* years until death. Then e_x is the curtate life expectancy and e_x the complete life expec**tancy**. ω is the age where $\ell_{\omega} = 0$ and $\omega = \infty$ by convention is nothing is said.

$$e_{x} = E[K_{x}] = \sum_{k=1}^{\omega - x - 1} {}_{k} p_{x}$$

$$\mathring{e}_{x} = E[T_{x}] = \int_{0}^{\omega - x} {}_{t} p_{x} dt \stackrel{\text{D.U.D}}{=} e_{x} + 0.5$$

Lesson 21 : Contingent **Payments**

The contract here are define with K_x to pay at the end of death year. All same contract can be define with T_x to pay at the moment of death. Then we use integral instead of sum and use

$$\Pr(K = k) = {}_{k} p_{x} q_{x+k} \Rightarrow f_{T_{x}}(t) = {}_{t} p_{x} \mu_{x+t}$$

> Life Insurance:

- Whole Life insurance :

$$A_x = \sum_{k=0}^{\infty} v^{k+1}{}_k p_x q_{x+k}$$

- Term Life insurance:
$$A_{x:\overline{n}|}^{1} = \sum_{k=0}^{n} v^{k+1}{}_{k} p_{x} q_{x+k}$$

- Deferred insurance:

$$m_{\parallel}A_{x} = \sum_{k=m}^{\infty} v^{k+1}{}_{k}p_{x}q_{x+k}$$
- Endowment insurance:

$$A_{x:\overline{n}|} = A_{x:\overline{n}|} + {}_{n}E_{x}$$

$$A_{\mathbf{r}\cdot\mathbf{n}} = A_{\mathbf{r}\cdot\mathbf{n}}^{1} + nE_{\mathbf{r}}$$

- Pure Endowment :

$$_{n}E_{x}=v^{n}_{n}p_{x}$$

> Life Annuities:

- Whole Life annuity

$$\ddot{a}_x = \sum_{k=0}^{\infty} v^k_{\ k} p_x$$
 – Temporary Life annuity

$$\ddot{a}_{x:\overline{n}|} = \sum_{k=0}^{n} v^k{}_k p_x$$

- Deferred annuity
$$m | \ddot{a}_x = \sum_{k=m}^{\infty} v^k{}_k p_x$$

- Certain and life annuity $\ddot{a}_{\overline{\chi};\overline{n}|} = \ddot{a}_{\overline{n}|} + {}_{m|}\ddot{a}_{\chi}$

> Illustrative Life Table :

 $- A_x = v^n q_x + p_x A_{x+1}$

$$-\ddot{a}_{r} = 1 + v p_{r} \ddot{a}_{r+1}$$

-
$$\ddot{a}_x = 1 + v p_x \ddot{a}_{x+1}$$

- $A_{x:\overline{n}|}^1 = A_x - {}_n E_x A_{x+n}$

$$- \ddot{a}_{x:\overline{n}|} = \ddot{a}_x - {}_{n}E_x \ddot{a}_{x+n}$$

$$- m|A_x = mE_x A_{x+m}$$

$$- m_{\parallel} \ddot{a}_{x} = {}_{m} E_{x} \ddot{a}_{x+m}$$

 $- \ddot{a}_x = 1 + a_x$

 $- A_x = 1 - d\ddot{a}_x$

- > **Joint life annuity**(\ddot{a}_{xy}) make payments until the earliest death pf two lives.
- Shortcut: $\forall t \in (0,1), \forall x \in \mathbb{N}, x < x + t < x + 1: \Rightarrow$ Last survivor annuity($\ddot{a}_{\overline{xy}}$) make payments until the last death of two lives.

$$\ddot{a}_x + \ddot{a}_y = \ddot{a}_{xy} + \ddot{a}_{\overline{xy}}$$

> Premiums:

$$M \cdot A_{x} = P \ddot{a}_{x}$$

$$P = \frac{M \cdot A_{x}}{\ddot{a}_{x}} = \frac{M}{\ddot{a}_{x}} - M \cdot d$$

Lesson 22: Simulation Inverse Method

> Linear congruential generators:

$$x_k = (ax_{k-1} + c) \bmod m$$

$$x_k = b - \left\lfloor \frac{b}{m} \right\rfloor m$$

where $b = (ax_{i-k} + c)$ and $x_0 \equiv \text{seed}$

> Inverse transformation method:

 $\Pr(F^{-1}(u) \le x) = \Pr(u \le F(x)) = F(x)$ then $x = F^{-1}(u)$ where $U \sim \text{Unif}(0, 1)$

- Normal Case : $x = \mu + \sigma z$
- Log-Normal Case : $x = e^{\mu + \sigma z}$

where $z = \Phi^{-1}(u)$, with linear interpolation.

- > Tips: Discrete Cumulative Function
- > Tips: if $\uparrow U \equiv \downarrow X$ then $(1 u_i) \Rightarrow u_i$

Lesson 23: Simulation Application

$$ightarrow \Pr(X \le x) \simeq \frac{1}{m} \sum_{j=1}^{m} \mathbb{1}_{\left\{x^{(j)} \le x\right\}}$$

$$> E[X^k] \simeq \frac{1}{m} \sum_{j=1}^{m} [x^{(j)}]^k$$

 $\rightarrow \operatorname{VaR}_k(X) \simeq X^{[j_0]}$

> TVaR_k(X)
$$\simeq \frac{1}{m(1-k)} \sum_{j=j_0+1}^{m} X^{(j)} \mathbb{1}_{\left\{X^{(j)} > X^{[j_0]}\right\}}$$

 $\simeq \frac{1}{m-j_0} \sum_{j=j_0+1}^{m} X^{[j]}$

where

- $-j_0 = \lfloor m \cdot k \rfloor$
- *m* is the number of simulations.
- $X^{(j)}$ is the jth simulations.
- $X^{[j]}$ is the jth simulations in order statis-

Lesson 24: Simulation Rejection Method

General method: Let f(x) be the density function of variable to simulate, and let g(x)be the base distribution, a random density function that is easy-to-simulate with nonzero > Some estimator: wherever $f(x) \neq 0$.

$$c = \max \frac{f(x)}{g(x)}$$

Generate two uniform number u_1, u_2 . Let $x_1 = G^{-1}(u_1)$. Accept x_1 only if

$$u_2 \le \frac{f(x_1)}{c \cdot g(x_1)}$$

> Simulating gamma distribution : Use

 $\text{Exp}(\alpha \cdot \theta)$ as the base distribution and $x = \alpha \cdot \theta$ that maximize c.

Simulating standard normal distribution:

Generate 3 uniform u_1 , u_2 , u_3 . Let $y_1 = -\ln u_2$ and $y_2 = -\ln u_2$. Accept y_1 if

and
$$y_2 = -\ln u_2$$
. Accept y
$$y_2 \ge \frac{(y_1 - 1)^2}{2}$$
and add (-) if $u_3 \ge 0.5$

> The **Number of iteration** is a Ross-geometric distribution with mean c. Let be β the mean of a geometric distribution given in the exam appendix:

$$E[N] = 1 + \beta = c$$

$$Var(N) = \beta(1+\beta)$$

Lesson 25: Estimator Quality

> **Bias:** This quality measures if, on average, the estimator is on the expected value of the parameter.

$$E[\hat{\theta}] = \theta + bias_{\hat{\theta}}(\theta)$$

- If bias_{$\hat{\theta}$}(θ) = 0, then $\hat{\theta}$ is **unbiased**.
- If $\lim_{n\to\infty} \text{bias}_{\hat{\theta}}(\theta) = 0$, then $\hat{\theta}$ is **asympto**tically unbiased.
- If $bias_{\hat{\theta}}(\theta) \neq 0$, then $\hat{\theta}$ is **biased**.
- > Consistency: This quality measures if the probability that the estimator is different from the parameter by more than ε goes to 0 as n goes to infinity.

$$\lim_{n \to \infty} \Pr(|\hat{\theta} - \theta| > \varepsilon) \to 0, \ \forall \varepsilon > 0$$

In other word, as $n \to \infty$, $E[\hat{\theta}] \to \theta$, $Var(\hat{\theta}) \to 0$

> **Efficiency:** This quality measures the variance of the estimator. Lower the variance is, more efficient is the estimator.

Efficiency of
$$\hat{\theta} = \frac{\text{Var}(\hat{\theta})^{\text{rao}}}{\text{Var}(\hat{\theta})}$$

Relative efficiency of $\hat{\theta}_1$ to $\hat{\theta}_2 = \frac{\text{Var}(\hat{\theta}_2)}{\text{Var}(\hat{\theta}_1)}$

See the rao-cramer lower bound

Mean Square Error: This quality measures the expected value of the square difference between the estimator and the parameter.

$$MSE_{\hat{\theta}}(\theta) = E[(\hat{\theta} - \theta)^2] = (bias_{\hat{\theta}}(\theta))^2 + Var(\hat{\theta})$$

- > An estimator is called a uniformly minimum variance unbiased estimator(UMVUE) if it's unbiased and if there is no other unbiased estimator with a smaller variance for any true value θ .
- - $\bar{x} = \frac{1}{n} \sum x_i$ is a unbiased estimator of the mean μ . $Var(\bar{x}) = \frac{1}{n} Var(x)$

- $s^2 = \sum \frac{(x_i \bar{x})^2}{n-1}$ is a unbiased estimator of the variance σ^2 .
- $\hat{\sigma}^2 = \sum \frac{(x_i \bar{x})^2}{n}$ is an asymptotically unbiased of the variance σ^2 .
- $\hat{\mu}'_k = \frac{1}{n} \sum x_i^k$, where $\hat{\mu}'_1 = \bar{x}$ and $\hat{\mu}_k = \frac{1}{n} \sum (x_i \bar{x})^k$, where $\hat{\mu}_1 = 0$ and $\hat{\mu}_2 = \hat{\sigma}^2$.

Lesson 26 : Kernel Density Estimation

> **Empirical distribution :** All data is assigning a probability of $\frac{1}{n}$. This is the same method used for simulation, see Lesson 23 : Simulation Application.

$$F_{e}(x) = \frac{1}{n} \sum_{i=1}^{n} \mathbb{1}_{\{x_{i} \le x\}}$$

$$f_{e}(x) = \frac{1}{n} \sum_{i=1}^{n} \mathbb{1}_{\{x_{i} = x\}}$$

$$= F_{e}(x) - F_{e}(x_{i-1})$$

- > Kernel Density is a empirical distribution smoothed with a base fonction. Let define the scaling factor b called bandwith.
 - The kernel-density estimate of the density function is : $\hat{f}(x) = \frac{1}{n} \sum k \left(\frac{x x_i}{b} \right)$ $\Leftrightarrow \sum f_e(x) k \left(\frac{x - x_i}{b} \right)$
 - The kernel-density estimate of the distribution is: $\hat{F}(x) = \frac{1}{n} \sum_{i} K\left(\frac{x x_i}{h}\right)$
- \rightarrow Rectangular(uniform, box) kermel:

$$k(x) = \begin{cases} \frac{1}{2b}, & -1 \le x \le 1\\ 0, & \text{otherwise} \end{cases}$$

$$K(x) = \begin{cases} 0, & x < -1\\ 0.5(x+1), & -1 \le x \le 1\\ 1, & x > 1 \end{cases}$$

$$\hat{f}(x) = \frac{F_e(x+b) - F_e(x-b^-)}{2b}$$

> Triangular kernel:

$$k(x) = \begin{cases} \frac{1}{|x|}, & -1 \le x \le 1\\ 0, & \text{otherwise} \end{cases}$$

$$K(x) = \begin{cases} 0, & x < -1\\ \frac{(1+x)^2}{2}, & -1 \le x \le 0\\ 1 - \frac{(1-x)^2}{2}, & 0 \le x \le 1\\ 1, & x > 1 \end{cases}$$

> **Gaussian kernel :** The distribution become normal with $\mu = x_i$ and $\sigma = b$.

$$k(x) = \frac{e^{-x^2/2}}{b\sqrt{2\pi}}$$
$$K(x) = \Phi(x)$$

- \rightarrow Other kernel: $k(x) = \beta(x)$ and k(x) = B(x)
- \rightarrow **kernel moments :** Let X be the kernel density estimate and x_i the empirical estimate.

We then condition on x_i .

en condition on
$$x_i$$
.

$$E[X] = E[E[X|x_i]] = E[x_i]$$

$$Var(X_R) = Var(x_i) + \frac{b^2}{3}$$

$$Var(X_T) = Var(x_i) + \frac{b^2}{6}$$

$$Var(X_G) = Var(x_i) + b^2$$

> Tips : For rectangular kernel, $E[x|x_i]$ is a uniform $(x_i - b, x_i + b)$.

Lesson 27 : Method of Moments

- > Types of data:
 - Complete data: Data is complete if we are given the exact value of each observation.
 - Grouped data: Set of interval and we know how many observation are in each.
 - Censored data: Value that are in a interval, but we don't know the exact value.
 Like limits (min(X, u)).
 - Truncated data: We have data only when it in certain range, otherwise we don't know. Like deductible (X|X > d).
- > **Method of Moments :** We match $\hat{\mu}'_k = \mathbb{E}\left[X^k\right]$ and find the parameters. If data is Censored or Truncated, we need to match the censored or truncated moment : $\hat{\mu}'_k = \mathbb{E}\left[\min(X, u)^k\right]$ or $\hat{\mu}'_k = \mathbb{E}\left[X^k | X > d\right]$.
- > For pareto distribution, if $\hat{\mu}'_2 = \hat{\sigma}^2 + \bar{x}^2 \le 2\bar{x}^2$, the method of moment is unstable and can't be used.

Lesson 28 : Percentile Matching

- > **Percentile Matching :** We match $F_e(\hat{\pi}_p) = p$ and find the parameters.
 - For censored data, we need select percentiles within the range of the uncensored portion of the data.
 - For truncated data, we need to match the percentiles of the conditional distribution:

button:

$$F(x|X > d) = \frac{\Pr(d < X \le x)}{\Pr(X > d)} = \frac{F(x) - F(d)}{1 - F(d)}$$

$$S(x|X > d) = \frac{S(x)}{S(d)}$$

> Smoothed empirical percentile:

$$\hat{\pi}_n = (1 - h)X^{[j]} + hX^{[j+1]}$$

where

- $j = \lfloor (n+1)p \rfloor$
- h = (n+1)p j
- $X^{[j]}$ is the jth order statistics.

Lesson 29 : Maximum Likehood Estimators

> **Maximum Likehood Estimators :** We maximize the probability of observing the data.

$$L(\theta) = \prod_{i} g(x_i; \theta)$$

$$l(\theta) = \sum_{i} \ln_{i} g(x_i; \theta)$$

- Individual data : $g(x_i; \theta) = f(x_i)$
- Grouped data: $g(x_i; \theta) = F(x_i) F(x_{i-1})$
- Censored data : $g(x_i; \theta) = S(x_i)$
- Truncated data : $g(x_i; \theta) = \frac{f(x)}{s(x)}$

Lesson 30 : MLE Special Techniques

- > Case MLE equals MME
 - For Exponential, $\hat{\theta}^{\text{MLE}} = \bar{x}$
 - For Gamma with fixed α , $\hat{\theta}^{\text{MLE}} = \hat{\theta}^{\text{MME}}$
 - For Normal, $\hat{\mu}^{\text{MLE}} = \bar{x}$ and $(\hat{\sigma}^2)^{\text{MLE}} = \frac{1}{n} \sum (x_i \hat{\mu})^2$
 - For Binomial, $mq = \bar{x}$ then given m, $\hat{q}^{\text{MLE}} = \frac{\bar{x}}{m}$
 - For Poisson, $\hat{\lambda}^{\text{MLE}} = \hat{\lambda}^{\text{MME}}$
 - For Binomial Negative, given r or β , $(r\beta)^{\text{MLE}} = \bar{x}$
- > Parametrization and Shifting:
 - Parametrization : MLE's are independent of parametrization $\lambda = \frac{1}{\theta} \Leftrightarrow \hat{\lambda}^{\text{MLE}} = \frac{1}{\hat{\theta}^{\text{MLE}}}$
 - Shifting the distribution is equivalent of shifting the data.
- > Transformations: MLE's are invariant under one-to-one transformation. Then if we have a transformed variable, we can untransform the data and find the parameter of the untransform distribution.

Tips: Transformations of distribution

> Weibull distribution: If the data is censored(u) or truncated(d), then_

$$\left(\hat{\theta}^{\text{MLE}}\right)^{\tau} = \frac{\sum x_i^{\tau} - \sum d_i^{\tau}}{\sum \mathbb{1}_{\{x_i \le u\}}}$$

if $\tau = 1$, then the distribution is Exponential.

> Pareto distribution with fixed θ : $\hat{\alpha} = -\frac{n}{V}$

$$K = \sum_{i=1}^{n+c} \ln(\theta+d_i) - \sum_{i=1}^{n+c} \ln(\theta+x_i)$$

where $n \equiv$ number of non-censored(c) data.

> Single-parameter Pareto : $\hat{\alpha} = -\frac{n}{K}$

$$K = \sum_{i=1}^{n+c} \ln \max(\theta, d_i) - \sum_{i=1}^{n+c} \ln x_i$$

where $n \equiv \text{number of non-censored(c)}$ data

- > Uniform(0, θ): We take the smalest θ possible, $\hat{\theta}^{\text{MLE}} = \max(x_1, ..., x_n)$
 - Censored(u): $\hat{\theta}^{\text{MLE}} = \frac{nd}{\sum \mathbb{1}_{\{x_i < d\}}}$

- Grouped : We take the heighest interval(L, U). $\hat{\theta}^{\text{MLE}} = \min(U, \hat{\theta}^{\text{MLE}}_{\text{Censored(L)}})$
- > Bernouilli : Let have a random variable that can take 2 values, n and m. Then

$$\hat{p} = \frac{n}{n+m}$$

- > Tips : If $L(\theta)$ look like a density distribution, $\hat{\theta}^{\text{MLE}} \equiv \text{mode}$ of this distribution.
- > **Ground-up loss** is define as (x|x>d).

Lesson 31: Variance of MLE

> Fisher information matrix :

$$I(\theta) = nE\left[\left(\frac{\mathrm{d}\ln f(x;\theta)}{\mathrm{d}\theta}\right)^{2}\right]$$

$$= -nE\left[\frac{\mathrm{d}^{2}\ln f(x;\theta)}{\mathrm{d}\theta^{2}}\right]$$
using the loglikehood function
$$I(\theta) = E\left[\left(\frac{\mathrm{d}l(x_{1},...,x_{n};\theta)}{\mathrm{d}\theta}\right)^{2}\right]$$

$$I(\theta) = E\left[\left(\frac{\mathrm{d}l(x_1, ..., x_n; \theta)}{\mathrm{d}\theta}\right)^2\right]$$
$$= -E\left[\frac{\mathrm{d}^2l(x_1, ..., x_n; \theta)}{\mathrm{d}\theta^2}\right]$$

> Rao-Cramer lower bound is the lowest possible variance for a unbiased estimator $\hat{\theta}$ of θ . Then $\hat{\theta} \sim \text{Normal}(0, \text{Var}(\hat{\theta})^{\text{rao}})$

$$\operatorname{Var}(\hat{\theta})^{\operatorname{rao}} \ge \frac{1}{I(\theta)}$$

under certains regularity conditions

- The seconde derivative of the loglikehood exist.
- The support of the density function is not function of θ .

Lesson 32: Sufficient **Statistics**

- > A sufficient statistics are statistics that capture all the information about the parameter we are estimating that the sample as to offer.
- > A statistics is sufficient when the distribution of a sample given a statistics does not depend on the parameter. Y is a sufficient statistics for a parameter θ if and only if

$$L(x_1,...,x_n;\theta|Y) = h(x_1,...,x_n)$$

$$L(x_1,...,x_n;\theta) = g(y)h(x_1,...,x_n)$$

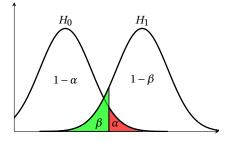
where $h(x_1,...,x_n)$ is a function that does not involve θ .

- > Rao-Blackwell Theorem : For any unbiased estimator $\hat{\theta}$ and sufficient statistic Y, the estimator $E[\hat{\theta}|Y]$ is unbiased and has variance less than or equal to $Var(\hat{\theta})$.
- > The maximum likehood estimator is a function of a sufficient statistic.

Lesson 33: Hypothesis Testing

 \rightarrow Let be H_0 the **null hypothesis** and H_1 the alternative hypothesis.

	Accept H ₀	Reject H ₀
H ₀ True	$1-\alpha$	α
H_1 True	β	$1-\beta$



- \rightarrow The α value is usuly name:
 - Probability of Type I error
 - Size of critical region
 - signifiance level

The β value is usuly name:

- Probability of Type II error

The $(1 - \beta)$ value is usuly name:

- The power of test.

 \rightarrow We will reject H_0 in favor of H_1 if a certain condition occured ($X > \gamma$), named the **critical region**. Then the probability of rejecting H_0 is giving by

$$\Pr(X > \gamma | H_0 \equiv \text{true}) = \alpha$$

- > Lowering the probability of type I error came at the cost of raising the probability of type II error. One way to lower both is to increase sample size.
- > The **p-value** is the probability of being greater or equal to the observation if H_0 is true. H_0 is rejected if and only if the p-value is less then the signifiance level.

$$P_{\text{value}} < \alpha$$

Lesson 34: Confidence **Interval and Sample Size**

 \gt Let be c the **confidence coefficient**. Then we can say the we're 100c% confident that the parameter is between (a, b), called the **confi**-

dence interval.
$$\alpha = 1 - c$$

$$\theta \in \hat{\theta} \pm z_{\frac{1+c}{2}} \sqrt{\operatorname{Var}(\hat{\theta})}$$

We can found the probability that the halfwidth of the interval is less then k.

$$\Pr(|\hat{\theta} - \theta| \le k) \ge \frac{1+c}{2}$$

$$\Phi\left(\frac{k}{\sqrt{\sigma^2/n}}\right) \ge \frac{1+c}{2}$$

> To find the sample size needed to have a certain (α) and (1 – β), we resolve

Pr(
$$\bar{x} > k|H_0$$
) = 1 - $\Phi\left(\frac{k - \mu_0}{\sqrt{\sigma^2/n}}\right) = \alpha$
Pr($\bar{x} > k|H_1$) = 1 - $\Phi\left(\frac{k - \mu_1}{\sqrt{\sigma^2/n}}\right) = 1 - \beta$

Lesson 35: Confidence **Intervals for Means**

- > The chi-sqare is a one-parameter family distribution. In definition, it a gamma with $\alpha = \frac{n}{2}$ and $\theta = 2$. The only parameter n is called **de**gree of freedom.
 - Let X_i , i = i, ..., n be normal random variable with mean μ and varianve σ^2 .

$$Y = \sum_{i=1}^{n} \frac{(X_i - \mu)^2}{\sigma^2} \sim \chi_{(n)}^2$$

- Let x_i , i = i, ..., n, $n \ge 2$ be random sample from normal distribution with variance σ^2 .

$$W = \sum_{i=1}^{n} \frac{(x_i - \bar{x})^2}{\sigma^2} \sim \chi_{(n-1)}^2$$

- Tips: $\chi^2_{(2)} \sim \text{Exp}(\theta = 2)$

> The **strudent** is a one-parameter family distribution. We define it as

$$T_{(n)} = \frac{Z}{\sqrt{W/r}}$$

 $T_{(n)} = \frac{Z}{\sqrt{W/n}}$ where $Z \sim N(0,1)$ and $W \sim \chi^2_{(n)}$. Note that as $n \to \infty$, $T_{(n)} \to N(0,1)$

When the variance is unknow, we need to estimate it with the unbiased estimator S^2 . $T_{(n-1)} = \frac{\bar{x} - \mu}{\sqrt{S^2/n}}$

$$T_{(n-1)} = \frac{\bar{x} - \mu}{\sqrt{S^2/n}}$$

> Testing the difference of means from two population.

$$x_1, ..., x_n \sim N(\mu_x, \sigma_x^2)$$

$$y_1, ..., y_m \sim N(\mu_y, \sigma_y^2)$$

$$T_{(n+m-2)} = \frac{(\bar{x} + \bar{y}) - (\mu_x - \mu_y)}{S\sqrt{\frac{1}{n} + \frac{1}{m}}}$$

where $S^2 = \frac{(n-1)S_x^2 + (m-1)S_y^2}{m+n-2}$

> Testing for mean of bernouilli population. Let p_0 the probability on H_0 .

$$Z = \frac{\hat{p} - p_0}{\sqrt{\frac{p_0(1 - p_0)}{n}}}$$

Lesson 36: Kolmogorov-**Smirnov Tests**

The Kolmogorov-Smirnov test is one methode for determining how well a parametric model fits its data. This test is only appropriate for continuous distribution.

$$D = \max |F_e(x) - F^*(x; \hat{\theta})|$$

where $d \le x \le u$ and $F^*(x) = \frac{F(x) - F(u)}{S(d)}$.					
_	x_i	$F^*(x_i)$	$F_e(x_i^-)$	$F_e(x_i)$	max
_	x_1	0.5	0.2	0.6	0.3
			•		
	:	:	:	:	:

Lesson 37 : Chi Square Test

> The Chi Square look for equality of means between k group. Let O_i be the observation and $E_i = np_i$ the expected on each group.

$$H_0: \mu_1 = ... = \mu_k$$

$$Q = \sum_{i=1}^{k} \frac{(O_i - E_i)^2}{E_i} = \sum_{i=1}^{k} \left(\frac{O_i^2}{E_i}\right) - n \sim \chi^2_{(k-1-\theta')}$$

Note: This test can be use to test the fit of as parametric model. θ' is the number of parameter fited with the same data as the test.

> Two-dimensional chi-square:

$$Q = \sum_{i=1}^{k} \sum_{j=1}^{c} \frac{(O_{ij} - E_{ij})^2}{E_{ij}} \sim \chi^2_{(k-1)(c-1)}$$

Lesson 38: Confience **Interval for Variances**

> To find a confidence interval for the variance, we need the following statistic.

$$W = \frac{(n-1)S^2}{\sigma^2} \sim \chi^2_{(n-1)}$$

> Warning: W is on the denominator, so for upper one-sided interval, we take the lower percentile α and $1 - \alpha$ for lower one-sided inter-

1.
$$\left(0, \frac{(n-1)S^2}{w_\alpha}\right)$$

2.
$$\left(\frac{(n-1)S^2}{w_{1-\alpha}},\infty\right)$$

3.
$$\left(\frac{(n-1)S^2}{w_{1-\frac{\alpha}{2}}}, \frac{(n-1)S^2}{w_{\frac{\alpha}{2}}}\right)$$

> The **Fisher** distribution is define as

$$F_{(r_1,r_2)} = \frac{W_1/r_1}{W_2/r_2}$$

where r_1 and r_2 are the degree of freedom.

- > If $T \sim \text{Strudent}$, then $T^2 \sim \text{Fisher}$.
- > To find a confidence interval for variance ratio, we need the following statistic.

$$F_{(n_x-1,n_y-1)} = \frac{S_x^2/\sigma_x^2}{S_y^2/\sigma_y^2}$$

Lesson 39: Uniformly Most Powerful critical Regions

> The Neyman-Pearson lemma states that for tests of one simple hypothesis against another, the best critical region for any (α) is to select all that minimize the likehood ratio. $h(x) = \frac{L(x_1, \dots, x_n; \theta | H_0)}{L(x_1, \dots, x_n; \theta | H_1)} < c$

$$h(x) = \frac{L(x_1, ..., x_n; \theta | H_0)}{L(x_1, ..., x_n; \theta | H_1)} < c$$

- If h(x) is increasing, $F(k|H_0) < \alpha$.
- If h(x) is deacreasing, $S(k|H_0) < \alpha$.

> If the alternative hypothesis is *composite*, then we can find the uniformly most powerful critical region with the same likehood ratio. This region only exist for one-sided test.

Lesson 40: Likehood Ratio **Tests**

> This test is usefull when there is no uniformly most powerful critical region.

$$h(x) = \frac{g(x_1, ..., x_n; \theta | H_0)}{g(x_1, ..., x_n; \theta | H_1)}$$

where $g(x_1,...,x_n;\theta)$ is the maximum likehood.

For large sample, we can use the asymptotic distribution of the likehood.

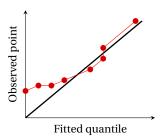
$$-2[l(\theta|H_0)-l(\theta|H_1)]\sim\chi^2_{(k-l)}$$

where k is the number of parameters specifies by H_0 and l is the combinaison of numbers of parameters specifies by H_0 and H_1 .

> The last test can also be use to dicide if it worth to add parameter to a distribution fit.

Lesson 41: q-q Plots

> This plot compare quantile of two distribution. It consiste of a plot of coordinate pairs: $(\mathbf{x_i}, \mathbf{F^{-1}}(\mathbf{p_i}))$ where p_i is the empirical percentile of x_i . Then the fit is good if the point are close to a 45° line.



Lesson 42: Introduction to Extended Linear Models

There are two purposes in building a extended linear model.

- 1. **Prediction:** We want to predic the valu of the response variable given specific values of the explanatory variables.
- 2. **Inference:** We want to understand which *ex*planatory variables explain the response variable and how much their explain it.

To evaluate the accuracy of a model, we estimate it mean square error.

MSE =
$$\frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)$$

Lesson 43: How a Generalized Linear Model Works

> Linear Model:

$$Y=\eta+\varepsilon=\beta_0+\beta_1x_1+\ldots+\beta_px_p+\varepsilon$$

$$\varepsilon \sim N(0,\sigma^2)$$

$$Y \sim N(\eta, \sigma^2)$$

Hypothesis:

- $(\mathbf{H_1}) \ \mathbf{E}[\varepsilon] = 0$ (Linearity)
- (**H**₂) $Var(\varepsilon) = \sigma^2$ (Homoscedasticity)
- (**H₃**) $Cov(\varepsilon_i, \varepsilon_i) = 0$ (Independence)
- > The **Box-Cox transformation** is a general set of transformation. When the variance of the error terms is not constant(H2), we need to transforme Y.

$$Y^* = \begin{cases} \frac{Y^{\lambda} - 1}{\lambda} & \lambda \neq 0\\ \ln Y & \lambda = 0 \end{cases}$$

where λ is chossen to best stabilize the variance of the error terms.

- > The *feature* must be linearly independent. That mean their can't be a function of another. Ex : $X_3 = 1 - X_2$.
- > We need to encode categorials variables with k levels into (k-1) indicators variables (called dummy variables) to avoid feature to be dependent. For interaction with 2 categorials variables, (k-1)(l-1) dummy variables are needed.

$$g(E[Y]) = \beta_0 + \sum_{i=1}^n \beta_i x_i$$

where $g(\cdot)$ is the link function.

> Exponential Family:

$$f(y;\theta) = \exp\{a(y)b(\theta) + c(\theta) + d(y)\}\$$

with

$$E[a(y)] = -\frac{c'(\theta)}{b'(\theta)}$$
$$Var(a(y)) = \frac{b''(\theta)c'(\theta) - c''(\theta)b'(\theta)}{[b'(\theta)]^3}$$

> **Tweedie** distribution :

$$Var(Y) = aE[y]^p$$

> link function: The GLM estimate is unbiased when the canonical link is used.

Distribution	Canonical link
Normal	g(y) = y
Binomial	$g(y) = \ln \frac{y}{1 - y}$
Poisson	$g(y) = \ln y$
Gamma	$g(y) = \frac{1}{y}$

- > **Offset**: We add $\ln n_i$ for cell with n_i exposure.

$$RR = \frac{E[Y_i|x_j=1]}{E[Y_i|x_j=0]}$$

Lesson 44: Categorial Response

Binomial Response

- > Let $\pi_i \in (0,1)$ be the response variable. We > Linear Regression: than need to have link that map η into (0,1).
 - logit: $\ln\left(\frac{\pi}{1-\pi}\right) = \eta$
 - **Probit**: $\Phi^{-1}(\pi) = \eta$
 - **Log-log:** $\ln(-\ln(1-\pi)) = \eta$
- > Odds Ratio: $o = \frac{\pi}{1-\pi}$

Nominal Response

> Suppose the response can be *J* values. Then we create a model of relative odds. $\ln \frac{\pi_j}{\pi_1} = \eta_j \Leftrightarrow \pi_j = \pi_1 e^{\eta_j}$

$$\ln \frac{\pi_j}{\pi_1} = \eta_j \Leftrightarrow \pi_j = \pi_1 e^{\eta_j}$$

- $-\pi_i = \frac{1}{1+\sum_{i=0}^{J} e^{\eta_i}}$
- $-\pi_{j} = \frac{e^{\eta_{j}}}{1 + \sum_{i=1}^{J} e^{\eta_{j}}}$
- \rightarrow If x_i is a binary feature, then the odds ratio of this variable in the category j to the base categorie is $e^{\beta_{ij}}$.

Ordinal Response

Ordinal response variables have several categories in logical order.

> Cumulative logit and proportional odds mo-

$$\ln o_{j} = \ln \frac{\sum_{k=1}^{j} \pi_{k}}{1 - \sum_{k=1}^{j} \pi_{k}} = \eta_{j}$$

Tips: The model is cumulative, so to find π_2 , we need to find π_1 and $\pi_1 + \pi_2$.

This model is proportional so if we fix the categorie but consider two set of feature x_{i1} and x_{i2} , the relative odds are

$$\frac{(o_j|x_i = x_{i1})}{(o_j|x_i = x_{i2})} = e^{\sum \beta_i (x_{i1} - x_{i2})}$$

> Adjacent categorie logit model:

$$\ln \frac{\pi_j}{\pi_{j+1}} = \eta_j$$
$$\sum_{i=1}^{J} \pi_j = 1$$

> Continuation ratio logit model:
$$\ln \frac{\pi_j}{\sum_{k=j+1}^J \pi_k} = \ln \frac{\pi_j}{1 - \sum_{k=1}^J \pi_k} = \eta_j$$
 Tips: Resolve for π_1 then for π_2 and so on ...

Lesson 45: Estimating Parameters

- \rightarrow Let **X** be the **design matrix**, the p x n features matrix.

$$\hat{\beta}_1 = \frac{\sum x_i y_i - n\bar{x}\bar{y}}{\sum x_i^2 - n\bar{x}^2}$$

$$\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x}$$

$$\mathbf{b} = (\mathbf{X}^\mathsf{T} \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} \mathbf{y}$$

> The **score** function is define as the derivative of the loglikehood

$$\mathbf{U}(\beta) = \ell'(\beta)$$

> Newton-Raphson algorithm :

$$\beta^{(k+1)} = \beta^{(k)} - \frac{\mathbf{U}(\beta^{(k)})}{\mathbf{U}'(\beta^{(k)})}$$

> **Fisher Scoring** algorithm :
$$\beta^{(k+1)} = \beta^{(k)} - \frac{\mathbf{U}(\beta^{(k)})}{\mathrm{E}[\mathbf{U}'(\beta^{(k)})]}$$

> The score vector has components

$$U_j = \sum_{i=1}^n \frac{y_i - \mu_i}{\text{Var}(y_i)} x_{ij} \left(\frac{\text{d}g(\mu_i)}{\text{d}\mu_i} \right)$$

- > The information matrix : $I(\theta) = \mathbf{X}^{\mathsf{T}} \mathbf{W} \mathbf{X}$
- > Let W be the diagonal matrix with entries

$$w_{ii} = \left(\left(\frac{\mathrm{d}g(\mu_i)}{\mathrm{d}\mu_i} \right)^2 \mathrm{Var}(y_i) \right)^{-1}$$

 \rightarrow Let **G** be the diagonal matrix with entries

$$G_{ii} = \frac{g(\mu_i)}{\mu_i}$$

- > The regression variable for one iteration $\mathbf{z}^{(k-1)} = \mathbf{X}\mathbf{b}^{(k-1)} + \mathbf{G}^{(k-1)}(\mathbf{v} \boldsymbol{\mu}^{(k-1)})$
- > The Weighted Least Square : $\mathbf{b}^{(k)} = (\mathbf{X}^\mathsf{T} \mathbf{W}^{(k-1)} \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} \mathbf{W}^{(k-1)} \mathbf{z}^{(k-1)}$

Lesson 46: Measures of Fit

- > The **satured** model is when we have as much feature as parameters(p = n). $g^{-1}(\mathbf{X}^{\mathsf{T}}\mathbf{b}) = \mathbf{y}$
- > The **deviance** statistic test compare a model to the satured model.

$$D = 2[\ell(\mathbf{b}_{max}) - \ell(\mathbf{b})] \approx n - p'$$

where p' = p + 1 and p the number of feature.

$$D = 2\sum_{i=1}^{n} \left(y_i \ln \frac{y_i}{\hat{y}_i} + (n_i - y_i) \ln \frac{n_i - y_i}{n_i - \hat{y}_i} \right)$$

- Normal (scaled deviance):

$$\sigma^2 D = \sum_{i=1}^{n} (y_i - \hat{y}_i)^2$$

- Poisson:

$$D = 2 \sum_{i=1}^{n} \left(y_i \ln \frac{y_i}{\hat{y}_i} - (y_i - \hat{y}_i) \right)$$

- Gamma:

$$D = 2\alpha \sum_{i=1}^{n} \left(-\ln \frac{y_i}{\hat{y}_i} + \frac{y_i - \hat{y}_i}{\hat{y}_i} \right)$$

Signifiance of Feature

> Loglikehood ratio test: These tests compare a **unconstrained** modele with p + q parameters versus another **constrained** model with p pa-

$$\begin{split} 2(\tilde{\ell}_{p+q} - \hat{\ell}_p) \sim \chi^2_{(q)} \\ \hat{D} - \tilde{D} \sim \chi^2_{(1)} \end{split}$$

> Wald test: To test wheter a single parameter

$$W = \frac{(\hat{\beta}_j - r)^2}{\operatorname{Var}(\hat{\beta}_j)} \sim \chi^2_{(1)}$$

 $\sqrt{W} \sim N(0,1)$, is usefull for confidence inter-

 $I(\theta)^{-1} = (\mathbf{X}^\mathsf{T} \mathbf{W} \mathbf{X})^{-1}$ is the covariance matrix.

> Score text: $\mathbf{U}^{\mathsf{T}}I(\theta)^{-1}\mathbf{U} \sim \chi_{(\alpha)}^2$

If
$$q=1$$
, $\frac{U}{\sqrt{I(\theta)}}\sim N(0,1)$.

> We want the lowest AIC and BIC.

Lesson 47: Standard Error, R^2 , and Strudent Statistic

$$SST = SSE + SSR$$

- > Total sum of square: $SST = \sum_{i=1}^{n} (y_i \bar{y})^2$
- > Error sum of square: $SSE = \sum_{i=1}^{n} (y_i \hat{y}_i)^2$ $SSE = \varepsilon^{\mathsf{T}} \varepsilon = \mathbf{y}^{\mathsf{T}} \mathbf{y} \mathbf{b}^{\mathsf{T}} \mathbf{x}^{\mathsf{T}} \mathbf{y}$
- > Regression sum of square: $SSR = \sum_{i=1}^{n} (\hat{y}_i \bar{y})^2$

		ANOVA	
SS	df	MS	F
SSR	p	MSR = SSR/df	MSR MSE
SSE	n-p'	MSE = SSE/df	
SST	n-1	MST = SST/df	

- > The standort error of the regression is $s = \sqrt{MSE}$
- > The **coefficient of determination** is the proportion explain by the regression.

$$R^2 = \frac{SSR}{SST} = 1 - \frac{SSE}{SST}$$

> **Strudent test :** To test $\beta_i = \beta^*$ $t_{n-p'} = \frac{\beta_i - \beta^*}{S_{\beta_i}}$

Matrice variance-covariance : $\sigma^2(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}$

- > Simple linear regression:
 - $\operatorname{Var}(\hat{\beta}_0) = \sigma^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{S_{nm}} \right)$
 - $Var(\hat{\beta}_1) = \frac{\sigma^2}{S}$
 - Cov $(\hat{\beta}_0, \hat{\beta}_1) = -\frac{\bar{x}\sigma^2}{S}$

Lesson 48: Fisher Statistic Lesson 51: ANOVA and VIF

- > The **Fisher** statistic test the signifiance od the entire regression, in other word if all $\beta_i = 0$. For simple linear regression $F = T^2$. Tips : Divide numerator and denominator of F by SST to find R^2 .
- > For simple linear regression, since p = 1, then $T_{(n)} = \sqrt{F_{1,n}}$.
- > **Partial Fisher test:** To test is *q* added variables have signifiance.

$$F_{\Delta_{df}, n-p'} = \frac{SSE^{(0)} - SSE^{(1)}/\Delta_{df}}{SSE^{(1)}/(n-p')}$$

> The Variance Inflation Factor test the collinearity of the features. To mesure it, we take the x_i feature and take it as the response. Let $R_{(i)}^2$ be the R^2 of this regression.

$$VIF = \frac{1}{1 - r_{(j)}^2}$$

We want the lowest VIF

> Coeficient of correlation :
$$r = \frac{\text{Cov}(X,Y)}{\sigma_x \sigma_y} = \frac{\sum (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum (x_i - \bar{x})^2 \sum (y_i - \bar{y})^2}}$$

> For two-feature model $R_{(v)}^2 = r^2$.

Lesson 49: Validation

- > The **Hat matrix** put a hat on y since $\hat{y} = Hy$. $\mathbf{H} = \mathbf{X}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{x}^{\mathsf{T}}$
- \rightarrow It follow that $Var(\hat{\varepsilon}) = (\mathbf{I} \mathbf{H})\sigma^2$
- > For simple linear regression:

$$h_{i\,i} = \frac{1}{n} + \frac{(x_i - \bar{x})^2}{S_{xx}}$$

> The **studentized residuals** are define as $r_i = \frac{\hat{\varepsilon}_i}{\sqrt{S^2(1-h_{ii})}}$

$$r_i = \frac{\varepsilon_i}{\sqrt{S^2(1 - h_{ii})}}$$

where h_{ii} is the **leverage**. Average leverage should be at $\frac{p'}{n}$. $\sum h_{ii} = p'$

- > A influence point is a observatio that influence a lot y. A **outliers** is a observation that have $|r_i| > 3$.
- > Two mesure for influence point.

- DFITS_i =
$$r_i \sqrt{\frac{h_{ii}}{1 - h_{ii}}}$$

- **Cook**:
$$D_i = \frac{\sum (\hat{y}_j - y_{j(i)})^2}{p' S^2} = r_i^2 \frac{h_{ii}}{p'(1 - h_{ii})}$$

 $D_i > 1$ is too high.

Lesson 50: Prediction

- > A **confidence interval** for predicted values. $y^* \in \hat{y}^* \pm t_{(n-2)} \sqrt{S^2 \left(\frac{1}{n} + \frac{(x^* - \bar{x})^2}{S_{v-}}\right)}$
- > A **prediction interval** for predicted values. $y^* \in \hat{y}^* \pm t_{(n-2)} \sqrt{S^2 \left(1 + \frac{1}{n} + \frac{(x^* - \bar{x})^2}{S_{rr}}\right)}$

One-factor ANOVA

$$SST = SSE + SSTR$$

Model	Sum of square	Deviance
$Y = \mu + \varepsilon_{ij}$	SST	D_M
$Y = \mu_i + \varepsilon_{ij}$	SSE	D_A

> Within sum of square

$$SSE = \sum_{i=1}^{k} \sum_{j=1}^{n_i} (y_{ij} - \bar{y}_{i\Sigma})^2$$

> Between sum of square

$$SSTR = \sum_{i=1}^{k} n_i (\bar{y}_{i\Sigma} - \bar{y}_{\Sigma\Sigma})^2 = \sum_{i=1}^{k} \left(\frac{y_{i\Sigma}^2}{n_i} \right) - n\bar{y}_{\Sigma\Sigma}^2$$

$$SST = \sum_{i=1}^{k} \sum_{j=1}^{n_i} (y_{ij} - \bar{y}_{\Sigma\Sigma})^2 = \sum_{j=1}^{n_i} (y_{ij}^2) - n\bar{y}_{\Sigma\Sigma}^2$$

> Fishier test
$$F_{(k-1,n-k)} = \frac{\text{SSTR}/(k-1)}{\text{SSE}/(n-k)} = \frac{(D_M - D_A)/(k-1)}{D_A/(n-k)}$$

where D_M is the *scale deviance* of the minimal

Two-factor ANOVA without replication

$$SST = SSE + SSTR + SSB$$

Model	Sum of square (DF)
$Y = \mu + \varepsilon_{ij}$	SST(bk-1)
$Y = \mu + \alpha_i + \varepsilon_{ij}$	SSTR(k-1)
$Y = \mu + \beta_i + \varepsilon_{ij}$	SSB(b-1)
$Y = \mu + \alpha_i + \beta_j + \varepsilon_{ij}$	SSE(k-1)(b-1)

> The formula are the same but n_i is k for SSTR and b for SSB.

Two-factor ANOVA with replication

> To test interaction : $F_{(I-1)(J-1),IJ(K-1)} = \frac{(D_I - D_s)/(I-1)(J-1)}{D_s/IJ(k-1)}$

> To test factor A: $F_{(I-1),IJ(K-1)} = \frac{(D_B - D_I)/(I-1)}{D_s/IJ(k-1)}$

> To test factor B:

$$F(J-1), IJ(K-1) = \frac{(D_M - D_B)/(J-1)}{D_S/IJ(K-1)}$$

where D_s is the satured model, I for additive model.

> ANCOVA

Lesson 52: Measures of Fit II

For contingencies table with binomial or poisson distribution.

- > Pearson: $\chi^2 = \sum_{i=1}^{\infty} \frac{(O_i E_i)^2}{E_i} \sim \chi^2_{(n-n')}$
- > Likelihood ratio chi-square : $C = 2[\ell - \ell_{\min}] \sim \chi^2_{(n'-1)}$
- > **Pseudo** R^2 : pseudo $R^2 = \frac{\ell_{\min} \ell}{\ell_{\min}}$

Residus

- > Pearson residual: $X_k = \frac{y_i \hat{\mu}_i}{\sqrt{\text{Var}(\hat{\mu}_i)}}$
- > Deviance residual : $d_k = s_k \sqrt{\text{deviance}}$ where s_k is the signe of $y_k - \hat{y}_i$
- > To standartize them, divide by $\sqrt{1-h_{ii}}$

Lesson 53: Resampling Methods

> Cross-Validation:

$$\mathrm{CV}_{(K)} = \frac{1}{k} \sum_{i=1}^k MSE_i$$
 As $k \to n$ bias $\Downarrow \mathrm{Var}(CV_k) \Uparrow$

If k = n then is the LOOCV statistic.

> LOOCV for least-square regression :

$$CV_{(K)} = \frac{1}{n} \sum_{i=1}^{n} \left(\frac{\varepsilon_i}{1 - h_{ii}} \right)^2$$

> Bootstap:

$$SE_B(\alpha) = \sqrt{\frac{1}{1-B} \sum_{i=1}^{B} (\hat{\alpha} - \bar{\alpha})^2}$$

Lesson 54: Subset Selection

Using a lot of feature will result of lower standard error on training data, but poor prediction. We need to keep only the feature that truly impact the response.

- > **Subset selection** For k possible feature, 2^k different model are possible.
 - For 2 model with same number of feature, we take the one with lowest SSE.
 - Otherwise, we compare with : Mallow's C_p , AIC, BIC and adjusted R^2 .
- > Foward stepwise selection consist of starting with the null, then fit k models with one variable and select the best base on SSE, then fit k-1 variables and so on. We obtain k+1 model, the best for each number of predictor, and select the final one with cross-validation or the 4 statistics. For categorial variables, each categorie is added independently.
- > Total fitted model:

- Foward:
$$1 + \sum_{i=0}^{\min(p,n)} (\min(p,n) - i)$$

- Backward:
$$1 + \sum_{i=1}^{\min(p,n)} i$$

Choosing the best model

- > **Cross-validation** is the more accurate.
- > Mallow's $C_p : C_p = \frac{1}{n}(SSE + 2p\hat{\sigma}^2)$ IF $\hat{\sigma}^2$ is unbiased then C_p is unbiased.
- > **Adjested R²**: $R_a^2 = 1 \frac{MSE}{MST}$
- > We want the lowest Mallow's C_p , AIC, BIC and the heighest R_a^2 .

Lesson 55: Shrinkage and Di-Lesson 58: correlation mension Reduction

> Ridge Regression : Minimize

$$\left(\sum_{i=1}^{n} y_{i} - \beta_{0} - \sum_{j=1}^{p'-1} \beta_{j} x_{ij}\right) + \lambda \sum_{j=1}^{p'-1} \beta_{j}^{2}$$

$$\left(\sum_{i=1}^n y_i - \beta_0 - \sum_{j=1}^{p'-1} \beta_j x_{ij}\right) + \lambda \sum_{j=1}^{p'-1} |\beta_j|$$

> Standart Predictors
$$\tilde{x} = \frac{x_{ij}}{\sqrt{\frac{1}{n}\sum(x_{ij} - \bar{x})^2}}$$

 $\lambda \to \infty \Leftrightarrow \beta_j \to 0$

$$\lambda \to \infty \Leftrightarrow \beta_j \to 0$$

$$\lambda \to 0 \Leftrightarrow \beta_j \to \hat{\beta}_j^{\rm normal}$$

-	PCA	Partial Least Square	
	unsupervised	supervised	
	variables are linear combianaire of the original		
	Higher bias	Lower bias	
	Lower variance	Higher variance	

Lesson 56: Extension to the **Linear Model**

- > **Extention**: These type can be treate as same as GLM. $y_i = \beta_0 + \beta_1 b_1(x_i) + \beta_2 b_2(x_i) + ... + \varepsilon_i$ For **polynomial regression**, $b_i(x) = x^j$.
 - For piecewise constant regression

$$b_j(x) = \mathbb{1}_{\{a \leq x < b\}}(x)$$

> Generalized Additive Model:

$$y_i = \beta_0 + \sum_{j=1}^p f_i(x_{ij}) + \varepsilon_i$$

- Allows nonlinear fits for each explanatory variable.
- Effet on each explanatory is separate, so easily identifiable.
- Does not allow foe effect of interaction among variable.

Lesson 57: Trend and **Seasonality**

- > **Trend** measures the amount by which the serie increase from period to period.
- > Seasonal variation measure cycle within a year.
- > Decomposition models
 - Additive Model: $x_t = m_t + s_t + z_t$
 - Multiplicative Seasonality : $x_t s_t + z_t$
 - Multiplicative Model: $x_t = m_t s_t z_t$
- > Centered moving average:
 - $\hat{m}_t = \frac{0.5m_{t-k} + m_{t-k+1} + \dots + m_t + \dots + m_{t+k-1} + 0.5m_{t+k}}{2k}$
- > Seasonal variation factor:
 - Additive Seasonality: $\hat{s}_t = x_t \hat{m}_t$ Ajusted so that $\sum (s_t + c) = 0$.
 - Multiplicative Seasonality $\hat{s}_t = \frac{x_t}{\hat{m}_t}$ Ajusted so that $\sum \frac{(\hat{s}_t + c)}{n} = 1$.

- > if $\mu(t)$ and $\sigma^2(t)$ does not vary with t then the time serie is second order stationnary
- > Variance: $\sigma^2(t) = \mathbb{E}[(x_t \mu(t))^2]$

Stationnary Time serie

- > sample variance $s^2 = \frac{1}{n-1} \sum_{i=1}^{n} (x_i \bar{x})^2$
- > Covariance at lag k: $\operatorname{Cov}(x_t, x_{t+k}) = \gamma_k = \operatorname{E}[(x_t - \mu)(x_{t+k} - \mu)]$ (acvf) $c_k = \frac{1}{n} \sum_{i=1}^{n-k} (x_t - \bar{x}) (x_{t+k} - \bar{x})$ (sample acvf)
- Auto-correration $\rho_k = \frac{\text{Cov}(x_t, x_{t+k})}{\sigma^2} \quad (\text{acf})$ $r_k = \frac{c_k}{c_0}$ (sample acf)

Relationships of different time serie

- > A leading variable is one that impact another.
- > Cross-covariance

$$\gamma_k(x, y) = \mathbb{E}[(x_{t+k} - \mu_x)(y_t - \mu_y)]$$
 (ccvf)

$$c_k = \frac{1}{n} \sum_{i=1}^{n-k} (x_{t+k} - \bar{x})(y_t - \bar{y})$$
 (sample ccvf)

> Cross-correration

$$\rho_k(x, y) = \frac{\gamma_k(x, y)}{\sigma_x \sigma_y}$$
 (ccf)

$$\rho_k(x, y) = \frac{\gamma_k(x, y)}{\sigma_x \sigma_y} \quad (\mathbf{ccf})$$

$$r_k = \frac{c_k(x, y)}{\sqrt{c_0(x, x)c_0(y, y)}} \quad (\mathbf{sample ccf})$$

> Notice

$$\gamma_k(x, y) = \gamma_{-k}(x, y)$$

$$\rho_k(x, y) = \rho_{-k}(x, y)$$

$$c_0(x,x) = c_0$$

Lesson 59: White Noise and Random Walks

> White noise each term are independant and variance σ^2 . The correlogram has autocorrelations all close to 0 except for r_0 .

$$w \sim N(0,\sigma^2)$$

> A Random Walks is a nonstationary time series which is the accumulation of white noise. The correlogram will decrease slowly from 1 to

$$x_1 = w_1$$

$$x_t = x_{t-1} + w_t$$

with

$$\mu(t) = 0$$

$$\sigma^2(t) = t\sigma_w^2$$

$$\gamma_k(t) = t\sigma_w^2$$

$$\rho_k(t) = \frac{1}{\sqrt{1 + \frac{k}{t}}}$$

> A Walk with drift drift the mean $\mu(t) = t\delta$ by don't affect variance and autocorrelations.

$$x_t = x_{t-1} + \delta + w_t$$

Lesson 60: Autoregressive Models

 \rightarrow An **autoregressive** model of order (p), or AR(p) is a time series where term may be expressed in term of previous terms plus white

$$x_t - \mu = \alpha_1(x_{t-1} - \mu) + \alpha_2(x_{t-2} - \mu)$$

+...+ $\alpha_D(x_{t-D} - \mu) + w_t$

 \rightarrow An AR(1) process is stationary if |a| < 1. correlogram is deacreasing exponentially. For a stationary AR(1) process

$$\mu_k = 0$$

$$\gamma_k = \frac{\alpha^k \sigma_w^2}{1 - \alpha^2}$$

$$\rho = \alpha^k$$

 \rightarrow Notation : $\mathbf{B}^k x_t = x_{t-k}$ $w_t = x_t - \alpha_1 x_{t-1} - \alpha_2 x_{t-2}$ $= (\alpha_2 \mathbf{B}^2 - \alpha_1 \mathbf{B} + 1) x_t$ $=\theta_n(\mathbf{B})x_t$

where $\theta_n(\mathbf{B})$ is the **characterictic equation**.

> Testing stationarity: Root < 1

(given)
$$x_t = \alpha_1 x_{t-1} + \alpha_2 x_{t-2} + w_t$$

(solve)
$$\theta_n(\mathbf{B}) = 0$$

(answer) If $|\mathbf{B}| > 1$, the process is stationary.

> tips: For 2 param:

$$\alpha_2 - \alpha_1 < 1$$

$$\alpha_2 + \alpha_1 < 1$$

$$|\alpha_2| < 1$$

> Forecast $\hat{x}_{n+1|n}$ is the same equation omitting w_t .

Lesson 61: Regression

> Variance of sample mean with correlation is

$$Var(\bar{x}) = \frac{\sigma^2}{n} \left(1 + 2 \sum_{k=1}^{n-1} \left(1 - \frac{k}{n} \right) \rho_k \right)$$

> Harmonic Seasonal model

$$x_{t} = m_{t} + \sum_{i=1}^{\lfloor S/2 \rfloor} s_{i} \sin(2\pi i t/s) + c_{i} \cos(2\pi i t/s) + z_{t}$$

- > Forecast correction
 - Lognormal: $e^{\sigma^2/2}$
 - Empirical: $\frac{\sum e^{z_t}}{n}$

Lesson 62: Moving Average Models

> A **moving average** time serie (MA(q)) is alway stationary. It define as

$$\begin{aligned} x_t &= \mu + \dot{w}_t + \beta_1 w_{t-1} + \dots + \beta_q w_{t-q} \\ &= \mu + \phi(\mathbf{B}) w_t \end{aligned}$$

with

$$\mu(t) = 0$$

$$\gamma_k = \sigma_w^2 \sum_{i=0}^{q-k} \beta_i \beta_{i+k} \quad \beta_0 = 1$$

and $\gamma_k = 0$ for k > q so MA(q) may be good fit is we observe $\gamma_q = 0$ in correlogram.

- > q beta + μ + σ_w^2 = q + 2 parameters fit.
- \rightarrow A MA(q) is **Inversible** if all the root of ϕ (**B**) are
- \rightarrow Express MA(q) in form of AR(∞). If ϕ (**B**) is re-

$$\frac{1}{1+x} = 1 - x + x^2 - x^3 + x^4 + \dots$$

$$\frac{1}{1-x} = 1 + x + x^2 + x^2 + x^4 + \dots$$

- \Rightarrow ARIMA with p = d = 0 is a MA(q) model.
- > conditional sum of squared residuals : $\sum w_t^2$

Lesson 63: ARMA Models

> The ARMA(p,q) models:

$$\begin{aligned} x_t &= \alpha_1 x_{t-1} + \ldots + \alpha_p x_{t-p} + \beta_1 + w_{t-1} + \ldots + \\ \beta_q w_{t-q} + w_t \end{aligned}$$

 $\theta_p(\mathbf{B})x_t = \phi_q(\mathbf{B})w_t$

> The process is stationary if all roots of $\theta(x)$ > 1 and the process is inversible if all roots of $\phi(x) > 1$

$$\gamma_0 = \sigma_w^2 \left(\frac{1 + 2\alpha\beta + \beta^2}{1 - \alpha^2} \right)$$
$$\gamma_k = \sigma_w^2 (\alpha + \beta) \alpha^{k-1} \left(\frac{1 + \alpha\beta}{1 - \alpha^2} \right)$$

 $\rho_k = \alpha \rho_{k-1}$ for $k \ge 2$.

> If the process is stationary, $E[x_t] = E[x_{t-1}]$.

Lesson 64: ARIMA and SA-**RIMA models**

- $\Rightarrow \nabla x_t + x_t x_{t-1} = (1 \mathbf{B})x_t$
- > An ARIMA model is a nonstationary process. If x_t is an ARIMA model, then $y_t = \nabla^d x_t$ is an ARMA(p,q). Then the ARIMA(p,d,q) is
 - $\theta(\mathbf{B})(1-\mathbf{B})^d x_t = \phi(\mathbf{B}) w_t$
 - With no MA(q), this is ARI(p,d)
 - With no AR(p), this is IMA(d,q)
- > An **SARIMA** model is a ARIMA with seasonal effect.
- > To forecast, we take the difference and then forecast ARMA(p,q) model.

Appendix

Inverting a matrix

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$
Acouser pour une matrice 3x3

Synthetic Division

Exemple: Factorize $x^3 - 12x^2 - 81$

Deductible and Limite

$$X = \min(X; d) + \max(0; X - d)$$

$$E[X] = E[\min(X; d)] + E[\max(0; X - d)]$$

$$= E[(X \land d)] + E[(x - d)_{+}]$$

$$= E[(X \land d)] + e_{x}(d) \cdot S_{x}(d)$$

Statistic Order

 $Y_1 = \min(X_1, ..., X_n)$ $f_{Y_1}(y) = nf(y)[S(y)]^{n-1}$

$$S_{Y_1}(y) = \prod_{i=1}^n \Pr(X_i > x)$$

> $Y_n = \max(X_1, ..., X_n)$ $f_{Y_n}(y) = n f(y) [F(y)]^{n-1}$

$$F_{Y_n}(y) = \prod_{i=1}^n \Pr\left(X_i \le x\right)$$
 > $Y_k \in (Y_1, ..., Y_k, ..., Y_n)$

$$f_{Y_k}(y) = \frac{n! \cdot f(y) [F(y)]^{k-1} [S(y)]^{n-k}}{(k-1)! (n-k)!}$$

 $F_{Y_k}(y) = \Pr \{ \text{at least k of n } X_i \text{ are } \leq y \}$

$$=\sum_{i=k}^n \binom{n}{i} [F(y)]^i [S(y)]^{n-j}$$

 $\Rightarrow x + y = \min(x, y) + \max(x, y)$, since one is for sure the max and the other the min.

Mode: Most likely probability

- \Rightarrow g(x) = f(x) or some time $g(x) = \ln f(x)$
- > **Mode** is the x that respects: g'(x) = 0

Normal Approximation

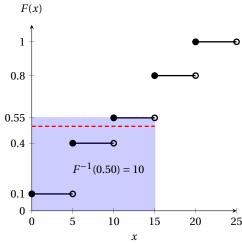
$$F_X(x) = \Phi\left(\frac{X - E[X]}{\sqrt{Var(X)}}\right)$$

> Continuity correction is necessary when X is discrete. $F_X(x) = \Phi\left(\frac{(X \pm k) - E[X]}{\sqrt{\text{Var}(X)}}\right)$ where k is the mid-point of the discrete value.

Discrete Cumulative Function

$$\Pr(X = x) = \begin{cases} 0.10, & x = 0 \\ 0.30, & x = 5 \\ 0.15, & x = 10 \\ 0.25, & x = 15 \\ 0.20, & x = 20 \end{cases}$$

$$\Pr(X \le x) = \begin{cases} 0.10, & 0 \le x < 5 \\ 0.40, & 5 \le x < 10 \\ 0.55, & 10 \le x < 15 \\ 0.80, & 15 \le x < 20 \\ 1, & x \ge 20 \end{cases}$$



Contract

- > Deductible(d)
- > Maximum(u)
- > Inflation(r)
- \rightarrow Coinsurance(α)

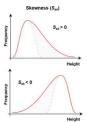
$$Y = \begin{cases} 0 & x \le \frac{d}{1+r} \\ \alpha[(1+r)x - d] & \frac{d}{1+r} < x < \frac{u}{1+r} \\ \alpha[u - d] & x \ge \frac{u}{1+r} \end{cases}$$

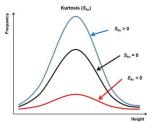
Warning: The maximal don't include the deductible.

Moments

- > k^e moment about the origin. $\mu'_k = E[X^k]$
- > k^e moment about the mean. $\mu_k = E | (X \mu)^k |$
- > The **Skewness** moment give infomation about the asymmetry of the distribution. If $S_{sk} = 0$, the distribution is normal.

$$S_{sk} = E\left[\left(\frac{X - \mu}{\sigma^2}\right)^3\right]$$





> The **kurtosis** moment give infomation about the flattening of the distribution. If $S_{ku} = 0$, the distribution is normal.

$$S_{ku} = E\left[\left(\frac{X - \mu}{\sigma^2}\right)^4\right]$$

> The **coefficient of variation** give information about the dispersion of the distribution.

$$CV = \frac{\sigma}{E[X]}$$

Transformations of distribution

- \rightarrow Lognormal: $Y = e^X$, where $Y \sim \text{Lognormal}(\mu, \sigma)$

 - $X \sim \text{Normal}(\mu, \sigma)$
- > Inverse Exponential : $Y = \frac{1}{X}$, where $Y \sim \text{Inverse Exponential}(1/\theta)$

 - $X \sim \text{Exponential}(\theta)$
- > Weibull: $Y = X^{1/\tau}$, where
 - $Y \sim \text{Weibull}(\sqrt[\tau]{\theta})$
 - $X \sim \text{Exponential}(\theta)$

Parameter interpretation

- > Scale parameter (θ, β, σ) : Affect the spread of the distribution.
- > **Rate parameter** (λ) : Affect the rate of data at mean. (1/scale)
- **Shape parameter** (α, τ, γ) : Affect the shape rather then simply shift the distribution.

Produit de convolution

The convolution of 2 random variable is difine as the sum of the two.

$$f_{X_1 + X_2}(x) = \int_{-\infty}^{\infty} f_{X_1}(x - s) f_{X_2}(s) \, \mathrm{d}s$$
$$F_{X_1 + X_2}(x) = \int_{-\infty}^{x} F_{X_1}(x - s) f_{X_2}(s) \, \mathrm{d}s$$

Shifting Exponential

$$f(x;\theta;d) = \frac{1}{\theta}e^{-(x-d)/\theta}$$
$$E[x] = \theta + d$$
$$Var(x) = \theta^{2}$$

Norme d'un vecteur

$$\ell_1 = x_1 + x_2 + \dots + x_n$$

$$\ell_2 = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

Greedy algorithm

A group of n peoples is to be assigned to k job, one to each job. The cost of job j is c_{ij} if person i is assigned. Select the assignement to have the minimal cost. We fixe the job or the people such as the min(n, k) and take the **minimum** cost for this personne(job).

$$\begin{aligned} c_{ij} \sim & \operatorname{Exp}(\theta) \\ \operatorname{E}[\mathbf{Total} \, \mathbf{cost}] = & \sum_{i=1}^{\min(n,k)} \frac{\theta}{\max(n,k)} \end{aligned}$$

Potential outliers

Let Q_1 and Q_2 be the 25° and the 75⁷⁵ quantile. Then $h = 1.5(Q_3 - Q_1)$. Observation are potential outliers if their are not in

$$(Q_1 - h, Q_3 + h)$$

Test III

Type III tests are tests on variable or set of variable that assume that all other variables are present in the model. The Wald test is type III.

Overdispersion

If the variance of the observation is higher than indicated by the binomial or poisson model. Hight diviance may indicate Overdispersion. We can solve it with **quasi-likehood** : $\phi Var(\gamma)$. This don't affect the fit but many statistic like Pearson. For Poison, we can use a Binomial Negative model.

Tail Value at Risk

$$\begin{aligned} \operatorname{TvaR}_k(x) &= \operatorname{VaR}_k(x) + \frac{\operatorname{E} \big[(x - \operatorname{VaR}_k)_+ \big]}{S_x(\operatorname{VaR}_k)} \\ &= \operatorname{VaR}_k(x) + \frac{\operatorname{E} \big[x \big] - \operatorname{E} \big[x \wedge \operatorname{VaR}_k \big]}{S_x(\operatorname{VaR}_k)} \end{aligned}$$