# MAS-1 Study Review

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- Probability Review
- Stochastic Processes
- Life Contingencies
- Simulation
- Statistics
- Extended Linear Model
- Time Series

# Lesson 1 : Probability Review

> Bernouilli Shortcut: If a random variable can only assume two values a and b with probability q and 1 - q, then is variance is  $q(1-q)(b-a)^2$ 

#### Lesson 2: Parametric Distri**butions**

- > Transformations:
  - Transformed:  $\tau > 0$
  - Inverse:  $\tau = -1$
  - Inverse-Transformed :  $\tau$  < 0,  $\tau$  ≠ 1

#### Lesson 4: Markov Chains

$$P_{ij}^{(n+m)} = \sum_{k=0}^{\infty} P_{ik}^{(n)} P_{kj}^{(m)}$$

> Gambler's ruin: Let N the target and j the actual status.

$$p_j = \begin{cases} \frac{j}{N}, & r = 1\\ \frac{r^j - 1}{r^N - 1}, & r \neq 1 \end{cases}$$

où  $r = \frac{q}{p}$ , p: winning prob.

> **Algorithmic efficency:** with  $N_i$  = number of steps from  $j^{th}$  solution to best solution.

$$\mathrm{E}[N_j] = \sum_{i=1}^{j-1} \frac{1}{i}$$

$$\begin{split} \operatorname{Var}(N_j) &= \sum_{i=1}^{j-1} \left(\frac{1}{i}\right) \left(1 - \frac{1}{i}\right) \\ \operatorname{As}\ j \to \infty, \operatorname{E}(N_j) &\to \ln j, \operatorname{Var}(N_j) \to \ln j \end{split}$$

# Lesson 5 : Markov Chain Classification

- > An **absorbing** state is one that cannot be exi-
- > State j is **accessible** $(i \rightarrow j)$  from state i if  $p_{ij}^n$  > 0,  $\forall n \geq 0.$
- > Two states **communicate** if  $i \leftrightarrow j$ .
- > A **class** of states is a maximal set of state that communicate with each other.
- > A Markov chain is **irreductible** if it has only one class.
- > A state (class) is **recurrent** if the probability of reentering the state is 1.  $\sum_{n=1}^{\infty} p_{ii}^{(n)} = \infty$
- > A state (class) si **transcient** if it is not recur-
  - $\textstyle \sum_{n=1}^{\infty} p_{ii}^{(n)} < \infty$
- > A finite Markov Chain must have at least one recurrent class. If it is irreductible, then it is recurrent.

# Lesson 6: Markov Chains Li- Lesson 9: Time Reversible miting Probability

- > A chain is **positive recurrent** is the expected number of transitions until the state occur is finite, null recurrent otherwise. Null recurrent mean that the long-term proportion of time in each state is 0.
- > A chain is **periodic** when states occur every n periods for n > 1.
- > A chain is aperiodic when the period is 1. In other world,  $P_{ii}^{(1)} > 0$ ,  $\forall i$
- > A chain is **ergodic** when the chain is aperiodic and positive irreductible recurrent.
- > Stationary probability:

$$\pi_j = \sum_{i=1}^n P_{ij} \pi_i \quad \sum_{i=1}^n \pi_i = 1$$

> **Limiting probabilities:** if the chain is ergodic,

$$\mathbf{P}^{(\infty)} = \begin{pmatrix} \pi_1 & \pi_2 & \pi_3 \\ \pi_1 & \pi_2 & \pi_3 \\ \pi_1 & \pi_2 & \pi_3 \end{pmatrix}$$

## **Lesson 7: Time in Transient States**

- > Tips: ??
- >  $\mathbf{S} = (\mathbf{I} \mathbf{P}_{\text{transcient}})^{-1}$ , where  $s_{ij}$  is the time in state j given that the current state is i.
- $\Rightarrow f_{ij} = \frac{s_{ij} \delta_{i,j}}{s_{jj}} = \sum_{n=1}^{\infty} f_{ij}^{(n)}$ , where  $f_{ij}$  is the probability that state i ever transitions to state j.

# Lesson 8: Branching Processes

- > A branching process is a special type of Markov chain representing the growth or extinction of a population.
- $> E[X_n] = E[Z]^n$ , where E[Z] is the expected number of people born in a generation.
- $\rightarrow \operatorname{Var}(X_n) = \operatorname{Var}(Z) \cdot \operatorname{E}[Z]^{n-1} \sum_{k=1}^n \operatorname{E}[Z]^{k-1}$
- > If  $X_0 \neq 1$  mean and variance of  $X_n$  need to be multiplicated by  $X_0$ .
- > Probability of extinction:

$$\pi_0 = \sum_{j=1}^{\infty} p_j \pi_0^j$$

- $\mu \le 1 \Rightarrow \pi_0 \ge 1$ , if  $X_0 = 1$ .
- $-\mu > 1 \Rightarrow \pi_0 < 1$ , if  $X_0 = 1$ .

For cubic equation, it guaranteed to factor  $(\pi_0 - 1)$ . Tips : ??

ightarrow If  ${f Q}$  is the reverse-time Markov chain for ergodic P, then

 $\pi_i Q_{ij} = \pi_j P_{ji}$ with  $P_{ii} = Q_{ii}$  and if  $p_{ij} = 0 \Leftrightarrow Q_{ji} = 0$ 

> If Q = P, then P is said to be **time-reversible**.

# Lesson 10: Exponential Distribution

> Lack of memory:

$$\Pr(X > k + x | X > k) = \Pr(X > x)$$

> **Minimum**: if  $X_i \sim \text{Exp}(\lambda_i)$ , then

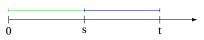
$$\min(X_1, X_2, ..., X_n) \sim \exp\left(\sum_{i=1}^n \lambda_i\right)$$

> The sum of 2 Exponentials randoms variables is the sum of the maximum and the minimum, since one must be the min and the other the

$$X_1 + X_2 = \min(X_1, X_2) + \max(X_1, X_2)$$

#### Lesson 11: Poisson Process

- >  $X(t) \sim \text{Poisson}[m(t)]$ , where m(t) is **mean va**lue function representing the mean of the number events before time t.
- > Poisson process can't decrease over time.  $N(t) \ge N(s)$  for  $t \ge s$
- N(0) = 0
- > Increament are **independent**:



 $\Pr[N(t) - N(s) = n | N(s) = k] = \Pr[N(t) - N(s) = n]$ 

> Non-homogeneous Poisson process:

$$m(t) = \int_0^t \lambda(u) \, \mathrm{d}u$$

where  $\lambda(t)$  is the **intensity function** 

Homogeneous Poisson process: The Poisson process is said to be homogeneous when the intensity function is a constant.

$$m(t) = \int_0^t \lambda \, \mathrm{d}u = \lambda t$$

We then say that the process have stationary increments.

 $\Pr[N(s-t)] = \Pr[N(t) - N(s)]$ 

# **Lesson 12: Poisson Process Time To Next Events**

- $T_n$  is the time between the n<sup>th</sup> event and the (n-1)th event.
- $> S_n = \sum_{i=1}^n T_i$ , is the time for the n<sup>e</sup> event.
- >  $F_{T_1}(t) = 1 e^{-\int_0^t \lambda(u) \, du}$
- > For homogeneous process:

$$T_n \sim \operatorname{Exp}(\lambda)$$

 $S_n \sim \text{Gamma}(n, \lambda)$ 

# **Lesson 13: Poisson Process** > If N(t) is a Poisson process, then S(t) is a com- > Inclusion/exclusion bounds using minimal **Counting Special Type**

> If event of type 1 occur with probability  $\alpha_1(t)$ , then the event follow a Poisson process with

$$m(t) = \int_0^{t} \lambda(u) \alpha_1(u) \, \mathrm{d}u$$

# Lesson 14: Poisson Process **Other Characteristics**

- > Only for homogeneous Poisson processes.
- $\rightarrow$  The probability of k event from process 1 is given by:

$$k \sim \text{Binomial}\left(k+l-1,\frac{\lambda_1}{\lambda_1+\lambda_2}\right)$$
 Then the probability that  $k$  event from process

1 occur before l from process 2 is :

$$\sum_{i=k}^{k+l-1} \binom{k+l-1}{i} \left(\frac{\lambda_1}{\lambda_1 + \lambda_2}\right)^i \left(\frac{\lambda_2}{\lambda_1 + \lambda_2}\right)^{k+l-1-i}$$

 $\rightarrow$  Given that exactly N(t) = k Poisson events occured before time t, the joint distribution of event time is the joint distribution of k independent uniform random variables on (0, t).

$$F_{S_1,...,S_n|n(t)}(s_1,...s_n|k) = \frac{k!}{t^k}$$

- $\rightarrow$  For k independent uniform random variable on (0, t), the expected value of the  $j^{th}$  order statistics is :  $E[T^{[j]}] = \frac{jt}{(k+1)}$ .
- > Tips: ??

#### Lesson 15: Poisson Process **Sums and Mixtures**

- > A Sums of independent Poisson random variables is a Poisson random with intensify function  $\lambda(t) = \sum \lambda_i(t)$ . Warning: Substraction don't give a Poisson random variable.
- > A Mixture of Poisson processes is not a Poisson processes.
  - Discrete mixture :

$$F_{X(t)}(t) = \sum_i w_i F_{X_i(t)}(t) \label{eq:fitting}$$
 where  $w_i > 0$  ,  $\sum w_i = 1$ 

- Continuous mixture :

$$F_{X(t)}(t) = \int F_{\{X_u(t)\}}(t) f(u) du$$

- If  $N(t)|\lambda$  is a Poisson random variable and  $\lambda \sim \text{Gamma}(\alpha, \theta)$ , then  $N(t) \sim$ NegBin( $r = \alpha, \beta = \theta t$ ).

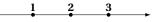
# **Lesson 16: Compound Pois**son Processes

> A **compound** random variable *S* is define by  $S = \sum_{i=1}^{N} X_i$  where N is the **primary** distribution and X the **secondary** distribution.

- pound Poisson process with:
  - $E[S(t)] = \lambda t E[X]$
  - $Var(S(t)) = \lambda t E[X^2]$
- $\rightarrow$  If  $X_i$  is discrete, we can separate the process into a sum of subprocess view in ??.
- > Sums of compound homogeneous Poisson process is also a Poisson process with:
  - $N(t) \sim \text{Pois}(\sum \lambda_i)$
  - $\ F_X(x) = \sum_i w_i F_{X_i(t)}(t), \quad w_i = \frac{\lambda_i}{\sum \lambda_i}$

#### **Lesson 17: Reliability Struc**ture Functions

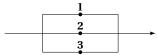
- $\Rightarrow \phi(\mathbf{x})$  is the **structure** function for a systeme. It equal 1 if the systeme work, 0 otherwise.
- A series system is define as a minimal path set. The system is working if all components are working.



The serie structure function is define as

$$\phi(\mathbf{x}) = \prod_{i=1}^{n} x_i$$

> A parallel system is define as a minimal cut set. The systeme is working if at least 1 components is working.



The parallel structure function is define as

$$\phi(\mathbf{x}) = 1 - \prod_{i=1}^{n} (1 - x_i)$$

- > Tips: Minimal path set is all way for the system to work, and the minimal cut set is all the way for the system to not work.
- $\rightarrow$  Tips: If set is  $\{1,2,3\}$  and  $\{1,2\}$ , the minimal mean we only take {1,2}.
- > Tips: Minimal cut is a serie of parallel structure and minimal path is a parallel of serie structure.

#### Lesson 18: Reliability Proba**bilities**

- $r(\mathbf{p})$  is the same polynomial as  $\phi(\mathbf{x})$ .
- > Inclusion/exclusion bounds using minimal path:

$$\begin{split} r(\mathbf{p}) &\leq \sum A_i \\ r(\mathbf{p}) &\geq \sum A_i - \sum A_i \cup A_j \end{split}$$

$$r(\mathbf{p}) \leq \sum A_i - \sum A_i \cup A_j + \sum A_i \cup A_j \cup A_k$$
 Force of mortality: where  $A_i = \sum p_i$  is the probability of the i<sup>e</sup> minimal path set work.  $\mu_{x+t} = \frac{f_{T_x}(t)}{t p_x}$ 

cut:

$$\begin{split} 1-r(\mathbf{p}) &\leq \sum A_i \\ 1-r(\mathbf{p}) &\geq \sum A_i - \sum A_i \cup A_j \\ 1-r(\mathbf{p}) &\leq \sum A_i - \sum A_i \cup A_j + \sum A_i \cup A_j \cup A_k \\ \text{where } A_i &= \sum (1-p_i) \text{ is the probability of the } i^c \\ \text{minimal cut set work.} \end{split}$$

> Bounds using intersections :

$$\prod \phi(\mathbf{X})^{\mathbf{min. cut}} \leq r(\mathbf{p}) \leq \prod \phi(\mathbf{X})^{\mathbf{min. path}}$$

$$1 - P_n = \sum_{k=1}^{n-1} {n-1 \choose k-1} q^{k(n-k)} P_k$$

$$1 - P_n \le (n+1)q^{n-1}$$

$$P_1 = 1$$

#### **Lesson 19: Reliability Time** to Failure

> Expected amound of time to failure :

$$E[\mathbf{system\ life}] = \int_0^\infty r(\tilde{\mathbf{F}}(\mathbf{t})) \, dt$$
 where,

- For serie system:

$$r(\bar{\mathbf{F}}(\mathbf{t})) = \prod_{i=1}^{n} \bar{F}_i(t)$$

$$r(\bar{\mathbf{F}}(\mathbf{t})) = \prod_{i=1}^{n} \bar{F}_{i}(t)$$
 - For parallel system : 
$$r(\bar{\mathbf{F}}(\mathbf{t})) = 1 - \prod_{i=1}^{n} F_{i}(t)$$

- > *Shortcut* : k out of n system with exponentials( $\theta$ ) :  $E[T] = \theta \sum_{i=k}^{n} \frac{1}{i}$
- > **Hazard rate function** (failure rate function):

$$h(t) = \frac{f(t)}{\bar{F}(t)}$$

and we say that the distribution

- is an increasing failure rate if h(t) is nondeacreasing function of t.
- is an deacreasing failure rate if h(t) is non-increasing function of t.
- > Cumulatice hazard function :

$$H(t) = \int_0^t h(u) \, \mathrm{d}u = -\ln \bar{F}(t)$$

with  $\frac{H(t)}{t}$  the average of the hazard rate.

#### Lesson 20: Survival Models

$$\Rightarrow t p_x = \frac{\ell_{x+t}}{\ell_x}, \quad t q_x = \frac{\ell_x - \ell_{x+t}}{\ell_x}$$

- $> t|u q_x = \frac{\ell_{x+t} \ell_{x+t+u}}{\ell_x}$
- $\rightarrow t+up_x = up_x \cdot tp_{x+u}$
- $\rightarrow t|uq_x = t + uq_x tq_x = tp_x \cdot uq_{x+t}$
- > Let be  $N_x$  the number of life surviving to age x, then

$$(N_{x+t}|N_x=n) \sim \text{Bin}(n, {}_tp_x)$$

$$\mu_{x+t} = \frac{f_{T_x}(t)}{t p_x} = -\frac{\mathrm{d}}{\mathrm{d}t} \ln t p_x$$

#### > Linear interpolation(D.U.D):

$$\ell_{x+t} = (1-t)\ell_x + t\ell_{x+1}$$

$$tq_x = t \cdot q_x$$

$$\mu_{x+t} = \frac{q_x}{1 - t \cdot q_x}$$

> **Expected life time :** Let  $k_x = \lfloor T_x \rfloor$ , the *full years* until death. Then  $e_x$  is the **curtate life** expectancy and  $\mathring{e}_x$  the complete life expec**tancy**.  $\omega$  is the age where  $\ell_{\omega} = 0$  and  $\omega = \infty$ by convention is nothing is said.

$$e_{x} = E[K_{x}] = \sum_{k=1}^{\omega - x - 1} {}_{k} p_{x}$$

$$\dot{e}_{x} = E[T_{x}] = \int_{0}^{\omega - x} {}_{t} p_{x} dt \stackrel{\text{D.U.D}}{=} e_{x} + 0.5$$

# **Lesson 21: Contingent Payments**

The contract here are define with  $K_x$  to pay at the end of death year. All same contract can be define with  $T_x$  to pay at the moment of death. Then we use integral instead of sum and use

$$\Pr(K = k) = {}_{k} p_{x} q_{x+k} \Rightarrow f_{T_{x}}(t) = {}_{t} p_{x} \mu_{x+t}$$

#### > Life Insurance:

- Whole Life insurance:

$$A_x = \sum_{k=0}^{\infty} v^{k+1}{}_k p_x q_{x+k}$$

- Term Life insurance:
$$A_{x:\overline{n}|}^{1} = \sum_{k=0}^{n} v^{k+1}{}_{k} p_{x} q_{x+k}$$

- Deferred insurance:
$$m_{|A_{x}} = \sum_{k=m}^{\infty} v^{k+1}{}_{k} p_{x} q_{x+k}$$

- Endowment insurance :

$$A_{x:\overline{n}|} = A_{x:\overline{n}|}^1 + {}_n E_x$$

- Pure Endowment:

$$_{n}E_{x}=v^{n}{}_{n}p_{x}$$

#### > Life Annuities:

- Whole Life annuity

$$\ddot{a}_{x} = \sum_{k=0}^{\infty} v^{k}_{k} p_{x}$$

- Temporary Life annuity

$$\ddot{a}_{x:\overline{n}|} = \sum_{k=0}^{n} v^k{}_k p_x$$

- Deferred annuity
$$m_{l}\ddot{a}_{x} = \sum_{k=m}^{\infty} v^{k}_{k} p_{x}$$

- Certain and life annuity  $\ddot{a}_{\overline{x:\overline{n}|}} = \ddot{a}_{\overline{n}|} + {}_{m|}\ddot{a}_x$ 

#### > Illustrative Life Table :

 $- A_x = v q_x + v p_x A_{x+1}$ 

$$-\ddot{a}_{r} = 1 + v p_{r} \ddot{a}_{r+1}$$

- 
$$\ddot{a}_x = 1 + v p_x \ddot{a}_{x+1}$$
  
-  $A_{x:\overline{n}|}^1 = A_x - n E_x A_{x+n}$ 

$$- \ddot{a}_{x:\overline{n}|} = \ddot{a}_x - {}_{n}E_x \ddot{a}_{x+n}$$

$$- m|A_X = mE_X A_{X+m}$$

$$- m \ddot{a}_x = m E_x \ddot{a}_{x+m}$$

$$- \ddot{a}_X = 1 + a_X$$

$$- A_x = 1 - d\ddot{a}_x$$

> **Joint life annuity**( $\ddot{a}_{xy}$ ) make payments until the earliest death pf two lives.

Shortcut:  $\forall t \in (0,1), \ \forall x \in \mathbb{N}, \ x < x + t < x + 1: \Rightarrow$  Last survivor annuity( $\ddot{a}_{\overline{xy}}$ ) make payments until the last death of two lives.

$$\ddot{a}_x + \ddot{a}_y = \ddot{a}_{xy} + \ddot{a}_{\overline{xy}}$$

> Premiums:

$$M \cdot A_{x} = P \ddot{a}_{x}$$

$$P = \frac{M \cdot A_{x}}{\ddot{a}_{x}} = \frac{M}{\ddot{a}_{x}} - M \cdot d$$

# **Lesson 22: Simulation Inverse Method**

> Linear congruential generators:

$$x_k = (ax_{k-1} + c) \bmod m$$

$$x_k = b - \left\lfloor \frac{b}{m} \right\rfloor m$$

where  $b = (ax_{i-k} + c)$  and  $x_0 \equiv \text{seed}$ 

> Inverse transformation method:

 $\Pr(F^{-1}(u) \le x) = \Pr(u \le F(x)) = F(x)$ then  $x = F^{-1}(u)$  where  $U \sim \text{Unif}(0, 1)$ 

- Normal Case :  $x = \mu + \sigma z$
- Log-Normal Case :  $x = e^{\mu + \sigma z}$

where  $z = \Phi^{-1}(u)$ , with linear interpolation.

- > Tips: ??
- > Tips: if  $\uparrow U \equiv \downarrow X$  then  $(1 u_i) \Rightarrow u_i$

# **Lesson 23: Simulation Application**

$$ightarrow \Pr(X \le x) \simeq \frac{1}{m} \sum_{j=1}^{m} \mathbb{1}_{\left\{x^{(j)} \le x\right\}}$$

> 
$$E[X^k] \simeq \frac{1}{m} \sum_{j=1}^{m} [x^{(j)}]^k$$

 $\rightarrow \operatorname{VaR}_k(X) \simeq X^{[j_0]}$ 

> TVaR<sub>k</sub>(X) 
$$\simeq \frac{1}{m(1-k)} \sum_{j=j_0+1}^{m} X^{(j)} \mathbb{1}_{\left\{X^{(j)} > X^{[j_0]}\right\}}$$
  
 $\simeq \frac{1}{m-j_0} \sum_{j=j_0+1}^{m} X^{[j]}$ 

where

- $-i_0 = \lfloor m \cdot k \rfloor$
- *m* is the number of simulations.
- $X^{(j)}$  is the j<sup>th</sup> simulations.
- $X^{[j]}$  is the j<sup>th</sup> simulations in order statis-

# **Lesson 24: Simulation Rejection Method**

**> General method :** Let f(x) be the density function of variable to simulate, and let g(x)be the base distribution, a random density function that is easy-to-simulate with nonzero > Some estimator: wherever  $f(x) \neq 0$ .

$$c = \max \frac{f(x)}{g(x)}$$

Generate two uniform number  $u_1, u_2$ . Let  $x_1 = G^{-1}(u_1)$ . Accept  $x_1$  only if

$$u_2 \le \frac{f(x_1)}{c \cdot g(x_1)}$$

> Simulating gamma distribution : Use

 $\text{Exp}(\alpha \cdot \theta)$  as the base distribution and  $x = \alpha \cdot \theta$ that maximize c.

Simulating standard normal distribution:

Generate 3 uniform  $u_1$ ,  $u_2$ ,  $u_3$ . Let  $y_1 = -\ln u_2$ and  $y_2 = -\ln u_2$ . Accept  $y_1$  if

and 
$$y_2 = -\ln u_2$$
. Accept y
$$y_2 \ge \frac{(y_1 - 1)^2}{2}$$
and add (-) if  $u_3 \ge 0.5$ 

> The **Number of iteration** is a Ross-geometric distribution with mean c. Let be  $\beta$  the mean of a geometric distribution given in the exam appendix:

$$E[N] = 1 + \beta = c$$

$$Var(N) = \beta(1+\beta)$$

#### **Lesson 25: Estimator Quality**

> **Bias:** This quality measures if, on average, the estimator is on the expected value of the parameter.

$$E[\hat{\theta}] = \theta + bias_{\hat{\theta}}(\theta)$$

- If bias<sub> $\hat{\theta}$ </sub>( $\theta$ ) = 0, then  $\hat{\theta}$  is **unbiased**.
- If  $\lim_{n\to\infty} \text{bias}_{\hat{\theta}}(\theta) = 0$ , then  $\hat{\theta}$  is **asympto**tically unbiased.
- If  $bias_{\hat{\theta}}(\theta) \neq 0$ , then  $\hat{\theta}$  is **biased**.
- > Consistency: This quality measures if the probability that the estimator is different from the parameter by more than  $\varepsilon$  goes to 0 as n goes to infinity.

$$\lim_{n\to\infty} \Pr(|\hat{\theta} - \theta| > \varepsilon) \to 0, \ \forall \varepsilon > 0$$

In other word, as  $n \to \infty$ ,  $E[\hat{\theta}] \to \theta$ ,  $Var(\hat{\theta}) \to 0$ 

> **Efficiency:** This quality measures the variance of the estimator. Lower the variance is, more efficient is the estimator.

Efficiency of 
$$\hat{\theta} = \frac{\text{Var}(\hat{\theta})^{\text{rao}}}{\text{Var}(\hat{\theta})}$$

Relative efficiency of  $\hat{\theta}_1$  to  $\hat{\theta}_2 = \frac{\text{Var}(\hat{\theta}_2)}{\text{Var}(\hat{\theta}_1)}$ 

See the rao-cramer lower bound

**Mean Square Error:** This quality measures the expected value of the square difference between the estimator and the parameter.

$$MSE_{\hat{\theta}}(\theta) = E\left[(\hat{\theta} - \theta)^2\right] = \left(bias_{\hat{\theta}}(\theta)\right)^2 + Var(\hat{\theta})$$

- > An estimator is called a uniformly minimum variance unbiased estimator(UMVUE) if it's unbiased and if there is no other unbiased estimator with a smaller variance for any true value  $\theta$ .
- - $\bar{x} = \frac{1}{n} \sum x_i$  is a unbiased estimator of the mean  $\mu$ .  $Var(\bar{x}) = \frac{1}{n} Var(x)$

- $s^2 = \sum \frac{(x_i \bar{x})^2}{n-1}$  is a unbiased estimator of the variance  $\sigma^2$ .
- $\hat{\sigma}^2 = \sum \frac{(x_i \bar{x})^2}{n}$  is an asymptotically unbiased of the variance  $\sigma^2$ .
- $\hat{\mu}'_k = \frac{1}{n} \sum x_i^k$ , where  $\hat{\mu}'_1 = \bar{x}$  and  $\hat{\mu}_k = \frac{1}{n} \sum (x_i \bar{x})^k$ , where  $\hat{\mu}_1 = 0$  and  $\hat{\mu}_2 = \hat{\sigma}^2$ .

# **Lesson 26 : Kernel Density Estimation**

> **Empirical distribution :** All data is assigning a probability of  $\frac{1}{n}$ . This is the same method used for simulation, see ??.

$$F_e(x) = \frac{1}{n} \sum_{i=1}^{n} \mathbb{1}_{\{x_i \le x\}}$$

$$f_e(x) = \frac{1}{n} \sum_{i=1}^{n} \mathbb{1}_{\{x_i = x\}}$$

$$= F_e(x) - F_e(x_{i-1})$$

- > **Kernel Density** is a empirical distribution smoothed with a base fonction. Let define the scaling factor *b* called **bandwith**.
  - The kernel-density estimate of the density function is:  $\hat{f}(x) = \frac{1}{n} \sum k \left( \frac{x x_i}{b} \right)$  $\Leftrightarrow \sum f_e(x) k \left( \frac{x - x_i}{b} \right)$
  - The kernel-density estimate of the distribution is :  $\hat{F}(x) = \frac{1}{n} \sum_{i} K\left(\frac{x x_i}{h}\right)$
- > Rectangular(uniform, box) kermel:

$$k(x) = \begin{cases} \frac{1}{2b}, & -1 \le x \le 1\\ 0, & \text{otherwise} \end{cases}$$

$$K(x) = \begin{cases} 0, & x < -1\\ 0.5(x+1), & -1 \le x \le 1\\ 1, & x > 1 \end{cases}$$

$$\hat{f}(x) = \frac{F_e(x+b) - F_e(x-b^-)}{2b}$$

> Triangular kernel :

$$K(x) = \begin{cases} -\frac{b}{b}, & -1 \le x \le 1 \\ 0, & \text{otherwise} \end{cases}$$

$$K(x) = \begin{cases} 0, & x < -1 \\ \frac{(1+x)^2}{2}, & -1 \le x \le 0 \\ 1 - \frac{(1-x)^2}{2}, & 0 \le x \le 1 \\ 1, & x > 1 \end{cases}$$

**Gaussian kernel :** The distribution become normal with  $\mu = x_i$  and  $\sigma = b$ .

$$k(x) = \frac{e^{-x^2/2}}{b\sqrt{2\pi}}$$

$$K(x) = \Phi(x)$$

- $K(x) = \Phi(x)$
- $\rightarrow$  Other kernel:  $k(x) = \beta(x)$  and k(x) = B(x)
- $\rightarrow$  **kernel moments :** Let X be the kernel density estimate and  $x_i$  the empirical estimate.

We then condition on  $x_i$ .

Efficient of 
$$X_i$$
:
$$E[X] = E[E[X|x_i]] = E[x_i]$$

$$Var(X_R) = Var(x_i) + \frac{b^2}{3}$$

$$Var(X_T) = Var(x_i) + \frac{b^2}{6}$$

$$Var(X_G) = Var(x_i) + b^2$$

> Tips : For rectangular kernel,  $E[x|x_i]$  is a uniform $(x_i - b, x_i + b)$ .

# Lesson 27 : Method of Moments

- > Types of data:
  - Complete data: Data is complete if we are given the exact value of each observation.
  - Grouped data: Set of interval and we know how many observation are in each.
  - Censored data: Value that are in a interval, but we don't know the exact value.
     Like limits (min(X, u)).
  - Truncated data: We have data only when it in certain range, otherwise we don't know. Like deductible (X|X > d).
- > **Method of Moments :** We match  $\hat{\mu}'_k = \mathbb{E}\left[X^k\right]$  and find the parameters. If data is Censored or Truncated, we need to match the censored or truncated moment :  $\hat{\mu}'_k = \mathbb{E}\left[\min(X, u)^k\right]$  or  $\hat{\mu}'_k = \mathbb{E}\left[X^k|X > d\right]$ .
- > For pareto distribution, if  $\hat{\mu}'_2 = \hat{\sigma}^2 + \bar{x}^2 \le 2\bar{x}^2$ , the method of moment is unstable and can't be used.

# Lesson 28 : Percentile Matching

- > **Percentile Matching :** We match  $F_e(\hat{\pi}_p) = p$  and find the parameters.
  - For censored data, we need select percentiles within the range of the uncensored portion of the data.
  - For truncated data, we need to match the percentiles of the conditional distribution:

button:  

$$F(x|X > d) = \frac{\Pr(d < X \le x)}{\Pr(X > d)} = \frac{F(x) - F(d)}{1 - F(d)}$$

$$S(x|X > d) = \frac{S(x)}{S(d)}$$

> Smoothed empirical percentile:

$$\hat{\pi}_n = (1 - h)X^{[j]} + hX^{[j+1]}$$

where

- $j = \lfloor (n+1)p \rfloor$
- h = (n+1)p j
- $X^{[j]}$  is the j<sup>th</sup> order statistics.

#### Lesson 29 : Maximum Likehood Estimators

> **Maximum Likehood Estimators :** We maximize the probability of observing the data.

$$L(\theta) = \prod_{i} g(x_i; \theta)$$
  
$$l(\theta) = \sum_{i} \ln_{i} g(x_i; \theta)$$

- Individual data :  $g(x_i; \theta) = f(x_i)$
- Grouped data:  $g(x_i; \theta) = F(x_i) F(x_{i-1})$
- Censored data :  $g(x_i; \theta) = S(x_i)$
- Truncated data :  $g(x_i; \theta) = \frac{f(x)}{s(x)}$

# Lesson 30 : MLE Special Techniques

- > Case MLE equals MME
  - For Exponential,  $\hat{\theta}^{\text{MLE}} = \bar{x}$
  - For Gamma with fixed  $\alpha$ ,  $\hat{\theta}^{\text{MLE}} = \hat{\theta}^{\text{MME}}$
  - For Normal,  $\hat{\mu}^{\text{MLE}} = \bar{x}$  and  $(\hat{\sigma}^2)^{\text{MLE}} = \frac{1}{n} \sum (x_i \hat{\mu})^2$
  - For Binomial,  $mq = \bar{x}$  then given m,  $\hat{q}^{\text{MLE}} = \frac{\bar{x}}{m}$
  - For Poisson,  $\hat{\lambda}^{\text{MLE}} = \hat{\lambda}^{\text{MME}}$
  - For Binomial Negative, given r or  $\beta$ ,  $(r\beta)^{\text{MLE}} = \bar{x}$
- > Parametrization and Shifting:
  - Parametrization : MLE's are independent of parametrization  $\lambda = \frac{1}{\theta} \Leftrightarrow \hat{\lambda}^{\text{MLE}} = \frac{1}{\hat{\theta}^{\text{MLE}}}$
  - Shifting the distribution is equivalent of shifting the data.
- > Transformations: MLE's are invariant under one-to-one transformation. Then if we have a transformed variable, we can untransform the data and find the parameter of the untransform distribution.

Tips: **??** 

> Weibull distribution: If the data is censored(u)

$$\left(\hat{\theta}^{\text{MLE}}\right)^{\tau} = \frac{\sum x_i^{\tau} - \sum d_i^{\tau}}{\sum \mathbb{1}_{\{x_i \le u\}}}$$

if  $\tau = 1$ , then the distribution is Exponential.

> Pareto distribution with fixed  $\theta$  :  $\hat{\alpha} = -\frac{n}{V}$ 

$$K = \sum_{i=1}^{n+c} \ln(\theta + d_i) - \sum_{i=1}^{n+c} \ln(\theta + x_i)$$

where  $n \equiv$  number of non-censored(c) data.

> Single-parameter Pareto :  $\hat{\alpha} = -\frac{n}{K}$ 

$$K = \sum_{i=1}^{n+c} \ln \max(\theta, d_i) - \sum_{i=1}^{n+c} \ln x_i$$

where  $n \equiv \text{number of non-censored(c)}$  data

- > Uniform(0,  $\theta$ ): We take the smalest  $\theta$  possible,  $\hat{\theta}^{\text{MLE}} = \max(x_1, ..., x_n)$ 
  - Censored(u):  $\hat{\theta}^{\text{MLE}} = \frac{nd}{\sum \mathbb{1}_{\{x_i < d\}}}$

- Grouped : We take the heighest interval(L, U).  $\hat{\theta}^{\text{MLE}} = \min(U, \hat{\theta}^{\text{MLE}}_{\text{Censored(L)}})$
- > Bernouilli : Let have a random variable that can take 2 values, n and m. Then

$$\hat{p} = \frac{n}{n+m}$$

- > Tips : If  $L(\theta)$  look like a density distribution,  $\hat{\theta}^{\text{MLE}} \equiv \text{mode}$  of this distribution.
- > **Ground-up loss** is define as (x|x>d).

#### **Lesson 31: Variance of MLE**

> Fisher information matrix :

$$I(\theta) = n\mathbb{E}\left[\left(\frac{\mathrm{d}\ln f(x;\theta)}{\mathrm{d}\theta}\right)^{2}\right]$$

$$= -n\mathbb{E}\left[\frac{\mathrm{d}^{2}\ln f(x;\theta)}{\mathrm{d}\theta^{2}}\right]$$
using the loglikehood function
$$I(\theta) = \mathbb{E}\left[\left(\frac{\mathrm{d}l(x_{1},...,x_{n};\theta)}{\mathrm{d}\theta}\right)^{2}\right]$$

$$I(\theta) = E\left[\left(\frac{\mathrm{d}l(x_1, ..., x_n; \theta)}{\mathrm{d}\theta}\right)^2\right]$$
$$= -E\left[\frac{\mathrm{d}^2l(x_1, ..., x_n; \theta)}{\mathrm{d}\theta^2}\right]$$

> Rao-Cramer lower bound is the lowest possible variance for a unbiased estimator  $\hat{\theta}$  of  $\theta$ . Then  $\hat{\theta} \sim \text{Normal}(0, \text{Var}(\hat{\theta})^{\text{rao}})$ 

$$\operatorname{Var}(\hat{\theta})^{\operatorname{rao}} \ge \frac{1}{I(\theta)}$$

under certains regularity conditions

- The seconde derivative of the loglikehood exist.
- The support of the density function is not function of  $\theta$ .

# Lesson 32: Sufficient **Statistics**

- > A sufficient statistics are statistics that capture all the information about the parameter we are estimating that the sample as to offer.
- > A statistics is sufficient when the distribution of a sample given a statistics does not depend on the parameter. Y is a sufficient statistics for a parameter  $\theta$  if and only if

$$L(x_1,...,x_n;\theta|Y)=h(x_1,...,x_n)$$

$$L(x_1,...,x_n;\theta) = g(y)h(x_1,...,x_n)$$

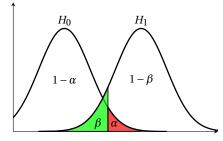
where  $h(x_1,...,x_n)$  is a function that does not involve  $\theta$ .

- > Rao-Blackwell Theorem : For any unbiased estimator  $\hat{\theta}$  and sufficient statistic Y, the estimator  $E[\hat{\theta}|Y]$  is unbiased and has variance less than or equal to  $Var(\hat{\theta})$ .
- > The maximum likehood estimator is a function of a sufficient statistic.

# **Lesson 33: Hypothesis Testing**

 $\rightarrow$  Let be  $H_0$  the **null hypothesis** and  $H_1$  the alternative hypothesis.

	Accept H <sub>0</sub>	Reject H <sub>0</sub>
H <sub>0</sub> True	$1-\alpha$	α
$H_1$ True	β	$1-\beta$



- $\rightarrow$  The  $\alpha$  value is usuly name:
  - Probability of Type I error
  - Size of critical region
  - signifiance level

The  $\beta$  value is usuly name:

- Probability of Type II error

The  $(1 - \beta)$  value is usuly name:

- The power of test.
- $\rightarrow$  We will reject  $H_0$  in favor of  $H_1$  if a certain condition occured ( $X > \gamma$ ), named the **critical region**. Then the probability of rejecting  $H_0$  is giving by

$$\Pr(X > \gamma | H_0 \equiv \text{true}) = \alpha$$

- > Lowering the probability of type I error came at the cost of raising the probability of type II error. One way to lower both is to increase sample size.
- > The **p-value** is the probability of being greater or equal to the observation if  $H_0$  is true.  $H_0$  is rejected if and only if the p-value is less then the signifiance level.

$$P_{\text{value}} < \alpha$$

# Lesson 34: Confidence **Interval and Sample Size**

 $\gt$  Let be c the **confidence coefficient**. Then we can say the we're 100c% confident that the parameter is between (a, b), called the **confi**-

dence interval. 
$$\alpha = 1 - c$$

$$\theta \in \hat{\theta} \pm z_{\frac{1+c}{2}} \sqrt{\operatorname{Var}(\hat{\theta})}$$

We can found the probability that the halfwidth of the interval is less then k.

$$\Pr(|\hat{\theta} - \theta| \le k) \ge \frac{1+c}{2}$$

$$\Phi\left(\frac{k}{\sqrt{\sigma^2/n}}\right) \ge \frac{1+c}{2}$$

> To find the sample size needed to have a certain ( $\alpha$ ) and (1 –  $\beta$ ), we resolve

$$\Pr(\bar{x} > k | H_0) = 1 - \Phi\left(\frac{k - \mu_0}{\sqrt{\sigma^2 / n}}\right) = \alpha$$

$$\Pr(\bar{x} > k | H_1) = 1 - \Phi\left(\frac{k - \mu_1}{\sqrt{\sigma^2 / n}}\right) = 1 - \beta$$

### Lesson 35: Confidence **Intervals for Means**

- > The chi-sqare is a one-parameter family distribution. In definition, it a gamma with  $\alpha = \frac{n}{2}$ and  $\theta = 2$ . The only parameter n is called **de**gree of freedom.
  - Let  $X_i$ , i = i, ..., n be normal random variable with mean  $\mu$  and varianve  $\sigma^2$ .

$$Y = \sum_{i=1}^{n} \frac{(X_i - \mu)^2}{\sigma^2} \sim \chi_{(n)}^2$$

- Let  $x_i$ , i = i, ..., n,  $n \ge 2$  be random sample from normal distribution with variance  $\sigma^2$ .

$$W = \sum_{i=1}^{n} \frac{(x_i - \bar{x})^2}{\sigma^2} \sim \chi_{(n-1)}^2$$

- Tips:  $\chi^2_{(2)} \sim \text{Exp}(\theta = 2)$
- > The **strudent** is a one-parameter family distribution. We define it as

$$T_{(n)} = \frac{Z}{\sqrt{W/r}}$$

 $T_{(n)} = \frac{Z}{\sqrt{W/n}}$  where  $Z \sim N(0,1)$  and  $W \sim \chi^2_{(n)}$ . Note that as  $n \to \infty$ ,  $T_{(n)} \to N(0,1)$ 

When the variance is unknow, we need to estimate it with the unbiased estimator  $S^2$ .  $T_{(n-1)} = \frac{\bar{x} - \mu}{\sqrt{S^2/n}}$ 

$$T_{(n-1)} = \frac{\bar{x} - \mu}{\sqrt{S^2/n}}$$

> Testing the difference of means from two population.

on.  

$$x_1, ..., x_n \sim N(\mu_x, \sigma_x^2)$$
  
 $y_1, ..., y_m \sim N(\mu_y, \sigma_y^2)$   
 $T_{(n+m-2)} = \frac{(\bar{x} + \bar{y}) - (\mu_x - \mu_y)}{S\sqrt{\frac{1}{n} + \frac{1}{m}}}$ 

where  $S^2 = \frac{(n-1)S_x^2 + (m-1)S_y^2}{m+n-2}$ 

> Testing for mean of bernouilli population. Let  $p_0$  the probability on  $H_0$ .

$$Z = \frac{\hat{p} - p_0}{\sqrt{\frac{p_0(1 - p_0)}{n}}}$$

### Lesson 36: Kolmogorov-**Smirnov Tests**

The Kolmogorov-Smirnov test is one methode for determining how well a parametric model fits its data. This test is only appropriate for continuous distribution.

$$D = \max |F_e(x) - F^*(x; \hat{\theta})|$$

where $d \le x \le u$ and $F^*(x) = \frac{F(x) - F(u)}{S(d)}$ .					
	$x_i$	$F^*(x_i)$	$F_e(x_i^-)$	$F_e(x_i)$	max
	$x_1$	0.5	0.2	0.6	0.3
	•	•	•	•	•

#### Lesson 37 : Chi Square Test

> The Chi Square look for equality of means between k group. Let  $O_i$  be the observation and  $E_i = np_i$  the expected on each group.

$$H_0: \mu_1 = ... = \mu_k$$

$$Q = \sum_{i=1}^{k} \frac{(O_i - E_i)^2}{E_i} = \sum_{i=1}^{k} \left(\frac{O_i^2}{E_i}\right) - n \sim \chi^2_{(k-1-\theta')}$$

Note: This test can be use to test the fit of as parametric model.  $\theta'$  is the number of parameter fited with the same data as the test.

> Two-dimensional chi-square:

$$Q = \sum_{i=1}^{k} \sum_{j=1}^{c} \frac{(O_{ij} - E_{ij})^2}{E_{ij}} \sim \chi^2_{(k-1)(c-1)}$$

# Lesson 38: Confience **Interval for Variances**

> To find a confidence interval for the variance, we need the following statistic.

$$W = \frac{(n-1)S^2}{\sigma^2} \sim \chi^2_{(n-1)}$$

> Warning: W is on the denominator, so for upper one-sided interval, we take the lower percentile  $\alpha$  and  $1 - \alpha$  for lower one-sided inter-

1. 
$$\left(0, \frac{(n-1)S^2}{w_\alpha}\right)$$

2. 
$$\left(\frac{(n-1)S^2}{w_{1-\alpha}},\infty\right)$$

3. 
$$\left(\frac{(n-1)S^2}{w_{1-\frac{\alpha}{2}}}, \frac{(n-1)S^2}{w_{\frac{\alpha}{2}}}\right)$$

> The **Fisher** distribution is define as

$$F_{(r_1,r_2)} = \frac{W_1/r_1}{W_2/r_2}$$

where  $r_1$  and  $r_2$  are the degree of freedom.

- > If  $T \sim \text{Strudent}$ , then  $T^2 \sim \text{Fisher}$ .
- > To find a confidence interval for variance ratio, we need the following statistic.

$$F_{(n_x-1,n_y-1)} = \frac{S_x^2/\sigma_x^2}{S_y^2/\sigma_y^2}$$

# **Lesson 39: Uniformly Most Powerful critical Regions**

> The Neyman-Pearson lemma states that for tests of one simple hypothesis against another, the best critical region for any  $(\alpha)$  is to select all that minimize the likehood ratio.  $h(x) = \frac{L(x_1, \dots, x_n; \theta | H_0)}{L(x_1, \dots, x_n; \theta | H_1)} < c$ 

$$h(x) = \frac{L(x_1, ..., x_n; \theta | H_0)}{L(x_1, ..., x_n; \theta | H_1)} < c$$

- If h(x) is increasing,  $F(k|H_0) < \alpha$ .
- If h(x) is deacreasing,  $S(k|H_0) < \alpha$ .

> If the alternative hypothesis is *composite*, then we can find the uniformly most powerful critical region with the same likehood ratio. This region only exist for one-sided test.

# Lesson 40: Likehood Ratio **Tests**

> This test is usefull when there is no uniformly most powerful critical region.

$$h(x) = \frac{g(x_1, ..., x_n; \theta | H_0)}{g(x_1, ..., x_n; \theta | H_1)}$$

where  $g(x_1,...,x_n;\theta)$  is the maximum likehood.

For large sample, we can use the asymptotic distribution of the likehood.

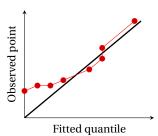
$$-2[l(\theta|H_0)-l(\theta|H_1)]\sim\chi^2_{(k-l)}$$

where k is the number of parameters specifies by  $H_0$  and l is the combinaison of numbers of parameters specifies by  $H_0$  and  $H_1$ .

> The last test can also be use to dicide if it worth to add parameter to a distribution fit.

#### Lesson 41: q-q Plots

> This plot compare quantile of two distribution. It consiste of a plot of coordinate pairs:  $(\mathbf{x_i}, \mathbf{F^{-1}}(\mathbf{p_i}))$  where  $p_i$  is the empirical percentile of  $x_i$ . Then the fit is good if the point are close to a 45° line.



#### **Lesson 42: Introduction to Extended Linear Models**

There are two purposes in building a extended linear model.

- 1. **Prediction:** We want to predic the valu of the response variable given specific values of the explanatory variables.
- 2. **Inference:** We want to understand which *ex*planatory variables explain the response variable and how much their explain it.

To evaluate the accuracy of a model, we estimate it mean square error.

MSE = 
$$\frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)$$

#### **Lesson 43: How a Generali**zed Linear Model Works

> Linear Model:

$$Y = \eta + \varepsilon = \beta_0 + \beta_1 x_1 + \dots + \beta_p x_p + \varepsilon$$

$$\varepsilon \sim N(0, \sigma^2)$$

$$Y \sim N(\eta, \sigma^2)$$

**Hypothesis**:

- $(\mathbf{H_1}) \ \mathbf{E}[\varepsilon] = 0$ (Linearity)
- (**H**<sub>2</sub>)  $Var(\varepsilon) = \sigma^2$ (Homoscedasticity)
- (**H<sub>3</sub>**)  $Cov(\varepsilon_i, \varepsilon_i) = 0$  (Independence)
- > The **Box-Cox transformation** is a general set of transformation. When the variance of the error terms is not constant(H2), we need to transforme Y.

$$Y^* = \begin{cases} \frac{Y^{\lambda} - 1}{\lambda} & \lambda \neq 0\\ \ln Y & \lambda = 0 \end{cases}$$

where  $\lambda$  is chossen to best stabilize the variance of the error terms.

- > The *feature* must be linearly independent. That mean their can't be a function of another. Ex :  $X_3 = 1 - X_2$ .
- > We need to encode categorials variables with k levels into (k-1) indicators variables (called dummy variables) to avoid feature to be dependent. For interaction with 2 categorials variables, (k-1)(l-1) dummy variables are needed.

$$g(E[Y]) = \beta_0 + \sum_{i=1}^n \beta_i x_i$$

where  $g(\cdot)$  is the link function.

> Exponential Family:

$$f(y;\theta) = \exp\{a(y)b(\theta) + c(\theta) + d(y)\}\$$

with

$$E[a(y)] = -\frac{c'(\theta)}{b'(\theta)}$$
$$Var(a(y)) = \frac{b''(\theta)c'(\theta) - c''(\theta)b'(\theta)}{[b'(\theta)]^3}$$

> **Tweedie** distribution :

$$Var(Y) = aE[y]^p$$

> link function: The GLM estimate is unbiased when the canonical link is used.

Distribution	Canonical link
Normal	g(y) = y
Binomial	$g(y) = \ln \frac{y}{1 - y}$
Poisson	$g(y) = \ln y$
Gamma	$g(y) = \frac{1}{y}$

- > **Offset**: We add  $\ln n_i$  for cell with  $n_i$  exposure.

$$RR = \frac{E[Y_i|x_j=1]}{E[Y_i|x_i=0]}$$

# **Lesson 44: Categorial** Response

#### **Binomial Response**

- > Let  $\pi_i \in (0,1)$  be the response variable. We > Linear Regression: than need to have link that map  $\eta$  into (0,1).
  - logit:  $\ln\left(\frac{\pi}{1-\pi}\right) = \eta$
  - **Probit**:  $\Phi^{-1}(\pi) = \eta$
  - **Log-log:**  $\ln(-\ln(1-\pi)) = \eta$
- > Odds Ratio :  $o = \frac{\pi}{1-\pi}$

#### **Nominal Response**

> Suppose the response can be *J* values. Then we create a model of relative odds.  $\ln \frac{\pi_j}{\pi_1} = \eta_j \Leftrightarrow \pi_j = \pi_1 e^{\eta_j}$ 

$$\ln \frac{\pi_j}{\pi_1} = \eta_j \Leftrightarrow \pi_j = \pi_1 e^{\eta_j}$$

- $-\pi_i = \frac{1}{1+\sum_{i=0}^{J} e^{\eta_i}}$
- $-\pi_{j} = \frac{e^{\eta_{j}}}{1 + \sum_{i=1}^{J} e^{\eta_{j}}}$
- $\rightarrow$  If  $x_i$  is a binary feature, then the odds ratio of this variable in the category j to the base categorie is  $e^{\beta_{ij}}$ .

#### **Ordinal Response**

Ordinal response variables have several categories in logical order.

> Cumulative logit and proportional odds mo-

$$\ln o_{j} = \ln \frac{\sum_{k=1}^{j} \pi_{k}}{1 - \sum_{k=1}^{j} \pi_{k}} = \eta_{j}$$

Tips: The model is cumulative, so to find  $\pi_2$ , we need to find  $\pi_1$  and  $\pi_1 + \pi_2$ .

This model is proportional so if we fix the categorie but consider two set of feature  $x_{i1}$  and  $x_{i2}$ , the relative odds are

$$\frac{(o_j|x_i=x_{i1})}{(o_i|x_i=x_{i2})} = e^{\sum \beta_i(x_{i1}-x_{i2})}$$

> Adjacent categorie logit model:

$$\ln \frac{\pi_j}{\pi_{j+1}} = \eta_j$$
$$\sum_{i=1}^{J} \pi_j = 1$$

> Continuation ratio logit model: 
$$\ln \frac{\pi_j}{\sum_{k=j+1}^J \pi_k} = \ln \frac{\pi_j}{1 - \sum_{k=1}^J \pi_k} = \eta_j$$
 Tips: Resolve for  $\pi_1$  then for  $\pi_2$  and so on ...

#### **Lesson 45: Estimating Para**meters

- $\rightarrow$  Let **X** be the **design matrix**, the p x n features matrix.

$$\hat{\beta}_1 = \frac{\sum x_i y_i - n\bar{x}\bar{y}}{\sum x_i^2 - n\bar{x}^2}$$

$$\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x}$$

$$\mathbf{b} = (\mathbf{X}^\mathsf{T} \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} \mathbf{v}$$

> The **score** function is define as the derivative of the loglikehood

$$\mathbf{U}(\beta) = \ell'(\beta)$$

> Newton-Raphson algorithm :

$$\beta^{(k+1)} = \beta^{(k)} - \frac{\mathbf{U}(\beta^{(k)})}{\mathbf{U}'(\beta^{(k)})}$$

> **Fisher Scoring** algorithm : 
$$\beta^{(k+1)} = \beta^{(k)} - \frac{\mathbf{U}(\beta^{(k)})}{\mathrm{E}[\mathbf{U}'(\beta^{(k)})]}$$

> The score vector has components

$$U_j = \sum_{i=1}^n \frac{y_i - \mu_i}{\text{Var}(y_i)} x_{ij} \left( \frac{\text{d}g(\mu_i)}{\text{d}\mu_i} \right)$$

- > The information matrix :  $I(\theta) = \mathbf{X}^{\mathsf{T}} \mathbf{W} \mathbf{X}$
- > Let W be the diagonal matrix with entries

$$w_{ii} = \left( \left( \frac{\mathrm{d}g(\mu_i)}{\mathrm{d}\mu_i} \right)^2 \mathrm{Var}(y_i) \right)^{-1}$$

 $\rightarrow$  Let **G** be the diagonal matrix with entries

$$G_{ii} = \frac{g(\mu_i)}{\mu_i}$$

- > The regression variable for one iteration  $\mathbf{z}^{(k-1)} = \mathbf{X}\mathbf{b}^{(k-1)} + \mathbf{G}^{(k-1)}(\mathbf{v} \boldsymbol{\mu}^{(k-1)})$
- > The Weighted Least Square :  $\mathbf{b}^{(k)} = (\mathbf{X}^\mathsf{T} \mathbf{W}^{(k-1)} \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} \mathbf{W}^{(k-1)} \mathbf{z}^{(k-1)}$

$$\mathbf{b}^{(k)} = (\mathbf{X}^\mathsf{T} \mathbf{W}^{(k-1)} \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} \mathbf{W}^{(k-1)} \mathbf{z}^{(k-1)}$$

# Lesson 46: Measures of Fit

- > The **satured** model is when we have as much feature as parameters(p = n).  $g^{-1}(\mathbf{X}^{\mathsf{T}}\mathbf{b}) = \mathbf{y}$
- > The **deviance** statistic test compare a model to the satured model.

$$D = 2[\ell(\mathbf{b}_{max}) - \ell(\mathbf{b})] \approx n - p'$$

where p' = p + 1 and p the number of feature.

$$D = 2 \sum_{i=1}^{n} \left( y_i \ln \frac{y_i}{\hat{y}_i} + (n_i - y_i) \ln \frac{n_i - y_i}{n_i - \hat{y}_i} \right)$$

- Normal (scaled deviance):  

$$\sigma^2 D = \sum_{i=1}^{n} (y_i - \hat{y}_i)^2$$

- Poisson:  

$$D = 2 \sum_{i=1}^{n} \left( y_i \ln \frac{y_i}{\hat{y}_i} - (y_i - \hat{y}_i) \right)$$

- Gamma:  

$$D = 2\alpha \sum_{i=1}^{n} \left( -\ln \frac{y_i}{\hat{y}_i} + \frac{y_i - \hat{y}_i}{\hat{y}_i} \right)$$

#### **Signifiance of Feature**

> Loglikehood ratio test: These tests compare a **unconstrained** modele with p + q parameters versus another **constrained** model with p pa-

$$\begin{split} 2(\tilde{\ell}_{p+q} - \hat{\ell}_p) \sim \chi^2_{(q)} \\ \hat{D} - \tilde{D} \sim \chi^2_{(1)} \end{split}$$

> Wald test: To test wheter a single parameter

$$W = \frac{(\hat{\beta}_j - r)^2}{\operatorname{Var}(\hat{\beta}_j)} \sim \chi^2_{(1)}$$

 $\sqrt{W} \sim N(0,1)$ , is usefull for confidence inter-

 $I(\theta)^{-1} = (\mathbf{X}^\mathsf{T} \mathbf{W} \mathbf{X})^{-1}$  is the covariance matrix.

> Score text:  $\mathbf{U}^{\mathsf{T}}I(\theta)^{-1}\mathbf{U} \sim \chi_{(\alpha)}^2$ 

If 
$$q = 1$$
,  $\frac{U}{\sqrt{I(\theta)}} \sim N(0, 1)$ .

> We want the lowest AIC and BIC.

# **Lesson 47: Standard Error,** $R^2$ , and Strudent Statistic

$$SST = SSE + SSR$$

- > Total sum of square:  $SST = \sum_{i=1}^{n} (y_i \bar{y})^2$
- > Error sum of square:  $SSE = \sum_{i=1}^{n} (y_i \hat{y}_i)^2$   $SSE = \varepsilon^{\mathsf{T}} \varepsilon = \mathbf{y}^{\mathsf{T}} \mathbf{y} \mathbf{b}^{\mathsf{T}} \mathbf{x}^{\mathsf{T}} \mathbf{y}$
- > Regression sum of square:  $SSR = \sum_{i=1}^{n} (\hat{y}_i \bar{y})^2$

		ANOVA	
SS	df	MS	F
SSR	р	MSR = SSR/df	MSR MSE
SSE	n-p'	MSE = SSE/df	
SST	n-1	MST = SST/df	

- > The standort error of the regression is  $s = \sqrt{MSE}$
- > The **coefficient of determination** is the proportion explain by the regression.

$$R^2 = \frac{SSR}{SST} = 1 - \frac{SSE}{SST}$$

> **Strudent test :** To test  $\beta_i = \beta^*$   $t_{n-p'} = \frac{\beta_i - \beta^*}{S_{\beta_i}}$ 

Matrice variance-covariance :  $\sigma^2(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}$ 

- > Simple linear regression:
  - $\operatorname{Var}(\hat{\beta}_0) = \sigma^2 \left( \frac{1}{n} + \frac{\bar{x}^2}{S_{nm}} \right)$
  - $Var(\hat{\beta}_1) = \frac{\sigma^2}{S}$
  - Cov $(\hat{\beta}_0, \hat{\beta}_1) = -\frac{\bar{x}\sigma^2}{S}$

# Lesson 48: Fisher Statistic Lesson 51: ANOVA and VIF

- > The **Fisher** statistic test the signifiance od the entire regression, in other word if all  $\beta_i = 0$ . For simple linear regression  $F = T^2$ . Tips : Divide numerator and denominator of F by SST to find  $R^2$ .
- > For simple linear regression, since p = 1, then  $T_{(n)} = \sqrt{F_{1,n}}$ .
- > **Partial Fisher test:** To test is *q* added variables have signifiance.

$$F_{\Delta_{df}, n-p'} = \frac{SSE^{(0)} - SSE^{(1)}/\Delta_{df}}{SSE^{(1)}/(n-p')}$$

> The Variance Inflation Factor test the collinearity of the features. To mesure it, we take the  $x_i$  feature and take it as the response. Let  $R_{(i)}^2$  be the  $R^2$  of this regression.

$$VIF = \frac{1}{1 - r_{(j)}^2}$$

We want the lowest VIF

> Coeficient of correlation : 
$$r = \frac{\text{Cov}(X,Y)}{\sigma_x \sigma_y} = \frac{\sum (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum (x_i - \bar{x})^2 \sum (y_i - \bar{y})^2}}$$

> For two-feature model  $R_{(v)}^2 = r^2$ .

#### Lesson 49: Validation

- > The **Hat matrix** put a hat on y since  $\hat{y} = Hy$ .  $\mathbf{H} = \mathbf{X}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{x}^{\mathsf{T}}$
- $\rightarrow$  It follow that  $Var(\hat{\varepsilon}) = (\mathbf{I} \mathbf{H})\sigma^2$
- > For simple linear regression:

$$h_{i\,i} = \frac{1}{n} + \frac{(x_i - \bar{x})^2}{S_{xx}}$$

> The **studentized residuals** are define as  $r_i = \frac{\hat{\varepsilon}_i}{\sqrt{S^2(1-h_{ii})}}$ 

$$r_i = \frac{\hat{\varepsilon}_i}{\sqrt{S^2(1-h:i)}}$$

where  $h_{ii}$  is the **leverage**. Average leverage should be at  $\frac{p'}{n}$ .  $\sum h_{ii} = p'$ 

- > A influence point is a observatio that influence a lot y. A **outliers** is a observation that have  $|r_i| > 3$ .
- > Two mesure for influence point.

- DFITS<sub>i</sub> = 
$$r_i \sqrt{\frac{h_{ii}}{1 - h_{ii}}}$$

- **Cook**: 
$$D_i = \frac{\sum (\hat{y}_j - y_{j(i)})^2}{p' S^2} = r_i^2 \frac{h_{ii}}{p'(1 - h_{ii})}$$
  
 $D_i > 1$  is too high.

#### **Lesson 50: Prediction**

- > A **confidence interval** for predicted values.  $y^* \in \hat{y}^* \pm t_{(n-2)} \sqrt{S^2 \left(\frac{1}{n} + \frac{(x^* - \bar{x})^2}{S_{vv}}\right)}$
- > A **prediction interval** for predicted values.  $y^* \in \hat{y}^* \pm t_{(n-2)} \sqrt{S^2 \left(1 + \frac{1}{n} + \frac{(x^* - \bar{x})^2}{S_{rr}}\right)}$

#### **One-factor ANOVA**

$$SST = SSE + SSTR$$

Model	Sum of square	Deviance
$Y = \mu + \varepsilon_{ij}$	SST	$D_M$
$Y = \mu_i + \varepsilon_{ij}$	SSE	$D_A$

#### > Within sum of square

SSE = 
$$\sum_{i=1}^{k} \sum_{j=1}^{n_i} (y_{ij} - \bar{y}_{i\Sigma})^2$$

> Between sum of square

$$SSTR = \sum_{i=1}^{k} n_i (\bar{y}_{i\Sigma} - \bar{y}_{\Sigma\Sigma})^2 = \sum_{i=1}^{k} \left( \frac{y_{i\Sigma}^2}{n_i} \right) - n\bar{y}_{\Sigma\Sigma}^2$$

$$SST = \sum_{i=1}^{k} \sum_{j=1}^{n_i} (y_{ij} - \bar{y}_{\Sigma\Sigma})^2 = \sum_{j=1}^{n_i} (y_{ij}^2) - n\bar{y}_{\Sigma\Sigma}^2$$

> Fishier test 
$$F_{(k-1,n-k)} = \frac{\text{SSTR}/(k-1)}{\text{SSE}/(n-k)} = \frac{(D_M - D_A)/(k-1)}{D_A/(n-k)}$$

where  $D_M$  is the *scale deviance* of the minimal

#### Two-factor ANOVA without replication

$$SST = SSE + SSTR + SSB$$

Model	Sum of square (DF)
$Y = \mu + \varepsilon_{ij}$	SST(bk-1)
$Y = \mu + \alpha_i + \varepsilon_{ij}$	SSTR $(k-1)$
$Y = \mu + \beta_i + \varepsilon_{ij}$	SSB(b-1)
$Y = \mu + \alpha_i + \beta_j + \varepsilon_{ij}$	SSE(k-1)(b-1)

> The formula are the same but  $n_i$  is k for SSTR and b for SSB.

#### Two-factor ANOVA with replication

- > To test interaction :  $F_{(I-1)(J-1),IJ(K-1)} = \frac{(D_I D_s)/(I-1)(J-1)}{D_s/IJ(k-1)}$

> To test factor A:  

$$F_{(I-1),IJ(K-1)} = \frac{(D_B - D_I)/(I-1)}{D_s/IJ(k-1)}$$

> To test factor B:  

$$F(J-1), IJ(K-1) = \frac{(D_M - D_B)/(J-1)}{D_S/IJ(K-1)}$$

where  $D_s$  is the satured model, I for additive model.

> ANCOVA

#### Lesson 52: Measures of Fit II

For contingencies table with binomial or poisson distribution.

- > Pearson:  $\chi^2 = \sum_{i=1}^{\infty} \frac{(O_i E_i)^2}{E_i} \sim \chi^2_{(n-n')}$
- > Likelihood ratio chi-square :  $C = 2[\ell - \ell_{\min}] \sim \chi^2_{(n'-1)}$
- > **Pseudo** $R^2$ : pseudo $R^2 = \frac{\ell_{\min} \ell}{\ell_{\min}}$

#### Residus

- > Pearson residual:  $X_k = \frac{y_i \hat{\mu}_i}{\sqrt{\text{Var}(\hat{\mu}_i)}}$
- > Deviance residual :  $d_k = s_k \sqrt{\text{deviance}}$ where  $s_k$  is the signe of  $y_k - \hat{y}_i$
- > To standartize them, divide by  $\sqrt{1-h_{ii}}$

#### **Lesson 53: Resampling Me**thods

> Cross-Validation:

$$\mathrm{CV}_{(K)} = \frac{1}{k} \sum_{i=1}^k MSE_i$$
 As  $k \to n$  bias  $\Downarrow \mathrm{Var}(CV_k) \Uparrow$ 

If k = n then is the LOOCV statistic.

> LOOCV for least-square regression :

$$CV_{(K)} = \frac{1}{n} \sum_{i=1}^{n} \left( \frac{\varepsilon_i}{1 - h_{ii}} \right)^2$$

> Bootstap:

$$SE_B(\alpha) = \sqrt{\frac{1}{1-B} \sum_{i=1}^{B} (\hat{\alpha} - \bar{\alpha})^2}$$

#### **Lesson 54: Subset Selection**

Using a lot of feature will result of lower standard error on training data, but poor prediction. We need to keep only the feature that truly impact the response.

- > **Subset selection** For k possible feature,  $2^k$  different model are possible.
  - For 2 model with same number of feature, we take the one with lowest SSE.
  - Otherwise, we compare with : Mallow's  $C_p$ , AIC, BIC and adjusted  $R^2$ .
- > Foward stepwise selection consist of starting with the null, then fit k models with one variable and select the best base on SSE, then fit k-1 variables and so on. We obtain k+1 model, the best for each number of predictor, and select the final one with cross-validation or the 4 statistics. For categorial variables, each categorie is added independently.
- > Total fitted model:

- Foward: 
$$1 + \sum_{i=0}^{\min(p,n)} (\min(p,n) - i)$$

- Backward: 
$$1 + \sum_{i=1}^{\min(p,n)} i$$

#### Choosing the best model

- > **Cross-validation** is the more accurate.
- > Mallow's  $C_p : C_p = \frac{1}{n}(SSE + 2p\hat{\sigma}^2)$ IF  $\hat{\sigma}^2$  is unbiased then  $C_p$  is unbiased.
- > **Adjested R<sup>2</sup>**:  $R_a^2 = 1 \frac{MSE}{MST}$
- > We want the lowest Mallow's  $C_p$ , AIC, BIC and the heighest  $R_a^2$ .

# Lesson 55: Shrinkage and Di-Lesson 58: correlation mension Reduction

#### > Ridge Regression : Minimize

$$\left(\sum_{i=1}^{n} y_{i} - \beta_{0} - \sum_{j=1}^{p'-1} \beta_{j} x_{ij}\right) + \lambda \sum_{j=1}^{p'-1} \beta_{j}^{2}$$

$$\left(\sum_{i=1}^n y_i - \beta_0 - \sum_{j=1}^{p'-1} \beta_j x_{ij}\right) + \lambda \sum_{j=1}^{p'-1} |\beta_j|$$

> Standart Predictors 
$$\tilde{x} = \frac{x_{ij}}{\sqrt{\frac{1}{n}\sum(x_{ij} - \bar{x})^2}}$$
  
 $\lambda \to \infty \Leftrightarrow \beta_j \to 0$ 

$$\lambda \to \infty \Leftrightarrow \beta_j \to 0$$

$$\lambda \to 0 \Leftrightarrow \beta_j \to \hat{\beta}_j^{\rm normal}$$

PCA	Partial Least Square	
unsupervised	supervised	
variables are linear combianaire of the original		
Higher bias	Lower bias	
Lower variance	Higher variance	

### Lesson 56 :Extension to the **Linear Model**

- > **Extention**: These type can be treate as same as GLM.  $y_i = \beta_0 + \beta_1 b_1(x_i) + \beta_2 b_2(x_i) + ... + \varepsilon_i$ For **polynomial regression**,  $b_i(x) = x^j$ .
  - For piecewise constant regression

$$b_j(x) = \mathbb{1}_{\{a \leq x < b\}}(x)$$

#### > Generalized Additive Model:

$$y_i = \beta_0 + \sum_{j=1}^p f_i(x_{ij}) + \varepsilon_i$$

- Allows nonlinear fits for each explanatory variable.
- Effet on each explanatory is separate, so easily identifiable.
- Does not allow foe effect of interaction among variable.

# Lesson 57: Trend and **Seasonality**

- > **Trend** measures the amount by which the serie increase from period to period.
- > Seasonal variation measure cycle within a year.
- > Decomposition models
  - Additive Model:  $x_t = m_t + s_t + z_t$
  - Multiplicative Seasonality :  $x_t s_t + z_t$
  - Multiplicative Model:  $x_t = m_t s_t z_t$

#### > Centered moving average:

$$\hat{m}_t = \frac{0.5m_{t-k} + m_{t-k+1} + \dots + m_t + \dots + m_{t+k-1} + 0.5m_{t+k}}{2k}$$

- > Seasonal variation factor:
  - Additive Seasonality :  $\hat{s}_t = x_t \hat{m}_t$ Ajusted so that  $\sum (s_t + c) = 0$ .
  - Multiplicative Seasonality  $\hat{s}_t = \frac{x_t}{\hat{m}_t}$ Ajusted so that  $\sum \frac{\hat{s}_t \cdot c}{n} = 1$ .

- > if  $\mu(t)$  and  $\sigma^2(t)$  does not vary with t then the time serie is second order stationnary
- > Variance:  $\sigma^2(t) = \mathbb{E}[(x_t \mu(t))^2]$

#### Stationnary Time serie

- > sample variance  $s^2 = \frac{1}{n-1} \sum_{i=1}^{n} (x_i \bar{x})^2$
- $\rightarrow$  Covariance at lag k:  $Cov(x_t, x_{t+k}) = \gamma_k = E[(x_t - \mu)(x_{t+k} - \mu)](\mathbf{acvf})$  $c_k = \frac{1}{n} \sum_{i=1}^{n-k} (x_t - \bar{x}) (x_{t+k} - \bar{x})$  (sample acvf)
- Auto-correration  $\rho_k = \frac{\text{Cov}(x_t, x_{t+k})}{\sigma^2} \quad (\text{acf})$ 
  - $r_k = \frac{c_k}{c_0}$  (sample acf)

#### Relationships of different time serie

- > A leading variable is one that impact another.
- > Cross-covariance

$$\gamma_k(x, y) = \mathbb{E}[(x_{t+k} - \mu_x)(y_t - \mu_y)]$$
 (ccvf)

$$c_k = \frac{1}{n} \sum_{i=1}^{n-k} (x_{t+k} - \bar{x})(y_t - \bar{y})$$
 (sample ccvf)

> Cross-correration

$$\rho_k(x, y) = \frac{\gamma_k(x, y)}{\sigma_x \sigma_y}$$
 (ccf)

$$\rho_k(x, y) = \frac{\gamma_k(x, y)}{\sigma_x \sigma_y} \quad (\mathbf{ccf})$$

$$r_k = \frac{c_k(x, y)}{\sqrt{c_0(x, x)c_0(y, y)}} \quad (\mathbf{sample ccf})$$

> Notice

$$\gamma_k(x, y) = \gamma_{-k}(x, y)$$

$$\rho_k(x, y) = \rho_{-k}(x, y)$$

$$c_0(x,x) = c_0$$

# **Lesson 59: White Noise and Random Walks**

- > White noise each term are independant and variance  $\sigma^2$ . The correlogram has autocorrelations all close to 0 except for  $r_0$ .
  - $w \sim N(0, \sigma^2)$
- > A Random Walks is a nonstationary time series which is the accumulation of white noise. The correlogram will decrease slowly from 1 to

$$0. x_1 = w_1$$

$$x_t = x_{t-1} + w_t$$

with

$$\mu(t) = 0$$

$$\sigma^2(t) = t\sigma_w^2$$

$$\gamma_k(t) = t\sigma_w^2$$

$$\rho_k(t) = \frac{1}{\sqrt{1 + \frac{k}{t}}}$$

> A Walk with drift drift the mean  $\mu(t) = t\delta$ by don't affect variance and autocorrelations.

$$x_t = x_{t-1} + \delta + w_t$$

#### **Lesson 60: Autoregressive Models**

 $\rightarrow$  An **autoregressive** model of order (p), or AR(p) is a time series where term may be expressed in term of previous terms plus white

$$x_t - \mu = \alpha_1(x_{t-1} - \mu) + \alpha_2(x_{t-2} - \mu)$$
  
+... + \alpha\_p(x\_{t-p} - \mu) + w\_t

 $\rightarrow$  An AR(1) process is stationary if |a| < 1. correlogram is deacreasing exponentially. For a stationary AR(1) process

$$\mu_k = 0$$

$$\gamma_k = \frac{\alpha^k \sigma_w^2}{1 - \alpha^2}$$

 $\rightarrow$  Notation :  $\mathbf{B}^k x_t = x_{t-k}$  $w_t = x_t - \alpha_1 x_{t-1} - \alpha_2 x_{t-2}$  $= (\alpha_2 \mathbf{B}^2 - \alpha_1 \mathbf{B} + 1) x_t$  $=\theta_n(\mathbf{B})x_t$ 

where  $\theta_n(\mathbf{B})$  is the **characterictic equation**.

> Testing stationarity: Root < 1

(given) 
$$x_t = \alpha_1 x_{t-1} + \alpha_2 x_{t-2} + w_t$$

(solve) 
$$\theta_n(\mathbf{B}) = 0$$

(answer) If  $|\mathbf{B}| > 1$ , the process is stationary.

> tips: For 2 param:

$$\alpha_2 - \alpha_1 < 1$$

$$\alpha_2 + \alpha_1 < 1$$

$$|\alpha_2| < 1$$

> Forecast  $\hat{x}_{n+1|n}$  is the same equation omitting  $w_t$ .

#### **Lesson 61: Regression**

> Variance of sample mean with correlation is

$$Var(\bar{x}) = \frac{\sigma^2}{n} \left( 1 + 2 \sum_{k=1}^{n-1} \left( 1 - \frac{k}{n} \right) \rho_k \right)$$

> Harmonic Seasonal model

$$x_t = m_t + \sum_{i=1}^{\lfloor S/2 \rfloor} s_i \sin(2\pi i t/s) + c_i \cos(2\pi i t/s) + z_t$$

- > Forecast correction
  - Lognormal:  $e^{\sigma^2/2}$
  - Empirical:  $\frac{\sum e^{z_t}}{n}$

# **Lesson 62: Moving Average Models**

> A **moving average** time serie (MA(q)) is alway stationary. It define as

$$x_t = \mu + w_t + \beta_1 w_{t-1} + \dots + \beta_q w_{t-q}$$
  
=  $\mu + \phi(\mathbf{B}) w_t$ 

with

$$\mu(t) = 0$$

$$\gamma_k = \sigma_w^2 \sum_{i=0}^{q-k} \beta_i \beta_{i+k} \quad \beta_0 = 1$$

and  $\gamma_k = 0$  for k > q so MA(q) may be good fit is we observe  $\gamma_q = 0$  in correlogram.

- > q beta +  $\mu$  +  $\sigma_w^2$  = q + 2 parameters fit.
- $\rightarrow$  A MA(q) is **Inversible** if all the root of  $\phi$ (**B**) are
- $\rightarrow$  Express MA(q) in form of AR( $\infty$ ). If  $\phi$ (**B**) is re-

$$\frac{1}{1+x} = 1 - x + x^2 - x^3 + x^4 + \dots$$

$$\frac{1}{1-x} = 1 + x + x^2 + x^2 + x^4 + \dots$$

- $\Rightarrow$  ARIMA with p = d = 0 is a MA(q) model.
- > conditional sum of squared residuals :  $\sum w_t^2$

#### Lesson 63: ARMA Models

> The ARMA(p,q) models:

$$\begin{aligned} x_t &= \alpha_1 x_{t-1} + \ldots + \alpha_p x_{t-p} + \beta_1 + w_{t-1} + \ldots + \\ \beta_q w_{t-q} + w_t \end{aligned}$$

 $\theta_p(\mathbf{B})x_t = \phi_q(\mathbf{B})w_t$ 

> The process is stationary if all roots of  $\theta(x)$  > 1 and the process is inversible if all roots of  $\phi(x) > 1$ 

$$\gamma_0 = \sigma_w^2 \left( \frac{1 + 2\alpha\beta + \beta^2}{1 - \alpha^2} \right)$$
$$\gamma_k = \sigma_w^2 (\alpha + \beta) \alpha^{k-1} \left( \frac{1 + \alpha\beta}{1 - \alpha^2} \right)$$

 $\rho_k = \alpha \rho_{k-1}$  for  $k \ge 2$ .

> If the process is stationary,  $E[x_t] = E[x_{t-1}]$ .

#### Lesson 64: ARIMA and SA-**RIMA models**

- $\Rightarrow \nabla x_t + x_t x_{t-1} = (1 \mathbf{B})x_t$
- > An ARIMA model is a nonstationary process. If  $x_t$  is an ARIMA model, then  $y_t = \nabla^d x_t$  is an ARMA(p,q). Then the ARIMA(p,d,q) is

$$\theta(\mathbf{B})(1-\mathbf{B})^d x_t = \phi(\mathbf{B}) w_t$$

- With no MA(q), this is ARI(p,d)
- With no AR(p), this is IMA(d,q)
- > An **SARIMA** model is a ARIMA with seasonal effect.
- > To forecast, we take the difference and then forecast ARMA(p,q) model.

# **Appendix**

#### **Inverting a matrix**

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$
About or pour une matrice 3x3

#### Synthetic Division

**Exemple:** Factorize  $x^3 - 12x^2 - 81$ 

#### **Deductible and Limite**

$$X = \min(X; d) + \max(0; X - d)$$

$$E[X] = E[\min(X; d)] + E[\max(0; X - d)]$$

$$= E[(X \land d)] + E[(x - d)]$$

$$= E[(X \land d)] + e_x(d) \cdot S_x(d)$$

#### Statistic Order

 $Y_1 = \min(X_1, ..., X_n)$ 

$$f_{Y_1}(y) = nf(y)[S(y)]^{n-1}$$

$$S_{Y_1}(y) = \prod_{i=1}^n \Pr(X_i > x)$$

>  $Y_n = \max(X_1, ..., X_n)$   $f_{Y_n}(y) = n f(y) [F(y)]^{n-1}$ 

$$JY_n(y) = nJ(y)[F(y)]$$
n

$$F_{Y_n}(y) = \prod_{i=1}^n \Pr\left(X_i \le x\right)$$
 >  $Y_k \in (Y_1, ..., Y_k, ..., Y_n)$ 

$$f_{Y_k}(y) = \frac{n! \cdot f(y) [F(y)]^{k-1} [S(y)]^{n-k}}{(k-1)! (n-k)!}$$

 $F_{Y_k}(y) = \Pr \{ \text{at least k of n } X_i \text{ are } \leq y \}$ 

$$=\sum_{i=k}^{n} \binom{n}{i} [F(y)]^{i} [S(y)]^{n-j}$$

 $\Rightarrow x + y = \min(x, y) + \max(x, y)$ , since one is for sure the max and the other the min.

# **Mode: Most likely** probability

- $\Rightarrow$  g(x) = f(x) or some time  $g(x) = \ln f(x)$
- > **Mode** is the x that respects: g'(x) = 0

#### **Normal Approximation**

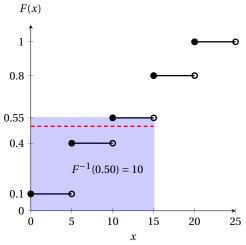
$$F_X(x) = \Phi\left(\frac{X - \mathrm{E}[X]}{\sqrt{\mathrm{Var}(X)}}\right)$$

> Continuity correction is necessary when X is discrete.  $F_X(x) = \Phi\left(\frac{(X \pm k) - E[X]}{\sqrt{\text{Var}(X)}}\right)$  where k is the mid-point of the discrete value.

#### Discrete Cumulative Function

$$\Pr(X = x) = \begin{cases} 0.10, & x = 0 \\ 0.30, & x = 5 \\ 0.15, & x = 10 \\ 0.25, & x = 15 \\ 0.20, & x = 20 \end{cases}$$

$$\Pr(X \le x) = \begin{cases} 0.10, & 0 \le x < 5 \\ 0.40, & 5 \le x < 10 \\ 0.55, & 10 \le x < 15 \\ 0.80, & 15 \le x < 20 \\ 1, & x \ge 20 \end{cases}$$



#### **Contract**

- > Deductible(d)
- > Maximum(u)
- > Inflation(r)
- $\rightarrow$  Coinsurance( $\alpha$ )

$$Y = \left\{ \begin{array}{cc} 0 & x \leq \frac{d}{1+r} \\ \alpha[(1+r)x - d] & \frac{d}{1+r} < x < \frac{u}{1+r} \\ \alpha[u - d] & x \geq \frac{u}{1+r} \end{array} \right.$$

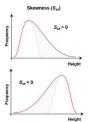
Warning: The maximal don't include the deductible.

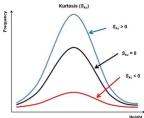
#### **Moments**

# > $k^e$ moment about the origin. $\mu'_k = E[X^k]$

- >  $k^e$  moment about the mean.  $\mu_k = E | (X \mu)^k |$
- > The **Skewness** moment give infomation about the asymmetry of the distribution. If  $S_{sk} = 0$ , the distribution is normal.

$$S_{sk} = E\left[\left(\frac{X - \mu}{\sigma^2}\right)^3\right]$$





> The **kurtosis** moment give infomation about the flattening of the distribution. If  $S_{ku} = 0$ , the distribution is normal.

$$S_{ku} = E\left[\left(\frac{X - \mu}{\sigma^2}\right)^4\right]$$

> The **coefficient of variation** give information about the dispersion of the distribution.

$$CV = \frac{\sigma}{E[X]}$$

# Transformations of distribution

- $\rightarrow$  Lognormal:  $Y = e^X$ , where
  - $Y \sim \text{Lognormal}(\mu, \sigma)$
  - $X \sim \text{Normal}(\mu, \sigma)$
- > Inverse Exponential :  $Y = \frac{1}{X}$ , where  $Y \sim \text{Inverse Exponential}(1/\theta)$ 

  - $X \sim \text{Exponential}(\theta)$
- > Weibull:  $Y = X^{1/\tau}$ , where
  - $Y \sim \text{Weibull}(\sqrt[\tau]{\theta})$
  - $X \sim \text{Exponential}(\theta)$

# Parameter interpretation

- > Scale parameter  $(\theta, \beta, \sigma)$ : Affect the spread of the distribution.
- > **Rate parameter** ( $\lambda$ ) : Affect the rate of data at mean. (1/scale)
- **Shape parameter**  $(\alpha, \tau, \gamma)$ : Affect the shape rather then simply shift the distribution.

#### Produit de convolution

The convolution of 2 random variable is difine as the sum of the two.

$$f_{X_1 + X_2}(x) = \int_{-\infty}^{\infty} f_{X_1}(x - s) f_{X_2}(s) \, \mathrm{d}s$$
$$F_{X_1 + X_2}(x) = \int_{-\infty}^{x} F_{X_1}(x - s) f_{X_2}(s) \, \mathrm{d}s$$

#### **Shifting Exponential**

$$f(x;\theta;d) = \frac{1}{\theta}e^{-(x-d)/\theta}$$
$$E[x] = \theta + d$$
$$Var(x) = \theta^{2}$$

#### Norme d'un vecteur

$$\ell_1 = x_1 + x_2 + \dots + x_n$$
  
 $\ell_2 = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$ 

# **Greedy algorithm**

A group of n peoples is to be assigned to k job, one to each job. The cost of job j is  $c_{ij}$  if person i is assigned. Select the assignement to have the minimal cost. We fixe the job or the people such as the min(n, k) and take the **minimum** cost for this personne(job).

$$\begin{aligned} c_{ij} \sim & \operatorname{Exp}(\theta) \\ \operatorname{E}[\mathbf{Total} \, \mathbf{cost}] = & \sum_{i=1}^{\min(n,k)} \frac{\theta}{\max(n,k)} \end{aligned}$$

#### **Potential outliers**

Let  $Q_1$  and  $Q_2$  be the 25° and the 75<sup>75</sup> quantile. Then  $h = 1.5(Q_3 - Q_1)$ . Observation are potential outliers if their are not in

$$(Q_1 - h, Q_3 + h)$$

#### **Test III**

Type III tests are tests on variable or set of variable that assume that all other variables are present in the model. The Wald test is type III.

#### **Overdispersion**

If the variance of the observation is higher than indicated by the binomial or poisson model. Hight diviance may indicate Overdispersion. We can solve it with **quasi-likehood** :  $\phi Var(\gamma)$ . This don't affect the fit but many statistic like Pearson. For Poison, we can use a Binomial Negative model.

#### Tail Value at Risk

$$\begin{aligned} \operatorname{TvaR}_k(x) &= \operatorname{VaR}_k(x) + \frac{\operatorname{E} \left[ (x - \operatorname{VaR}_k)_+ \right]}{S_x(\operatorname{VaR}_k)} \\ &= \operatorname{VaR}_k(x) + \frac{\operatorname{E} [x] - \operatorname{E} \left[ x \wedge \operatorname{VaR}_k \right]}{S_x(\operatorname{VaR}_k)} \end{aligned}$$