MAS-1 Study Review

Nicholas Langevin 15 mars 2019

- Probability Review
- Stochastic Processes
- Life Contingencies
- → Simulation
- Statistics
- Extended Linear Model
- Time Series

Lesson 1 : Probability Review

> Bernouilli Shortcut: If a random variable can only assume two values a and b with probability q and 1 - q, then is variance is $a(1-a)(b-a)^2$

Lesson 2 : Parametric Distri**butions**

- > Transformations:
 - Transformed: $\tau > 0$
 - Inverse: $\tau = -1$
 - Inverse-Transformed : τ < 0, τ ≠ 1

Lesson 4: Markov Chains

> Chapman-Kolmogorov:

$$P_{ij}^{(n+m)} = \sum_{k=0}^{\infty} P_{ik}^{(n)} P_{kj}^{(m)}$$

$$p_{j} = \begin{cases} \frac{j}{N}, & r = 1\\ \frac{r^{j} - 1}{r^{N} - 1}, & r \neq 1 \end{cases}$$
où $r = \frac{q}{n}$, p: winning prob.

> **Algorithmic efficency:** with N_i = number of steps from j^{th} solution to best solution.

$$\begin{split} \mathrm{E}[N_j] &= \sum_{i=1}^{j-1} \frac{1}{i} \\ \mathrm{Var}(N_j) &= \sum_{i=1}^{j-1} \left(\frac{1}{i}\right) \left(1 - \frac{1}{i}\right) \\ \mathrm{As} \ j \to \infty, \, \mathrm{E}[N_j] \to \ln j, \, \mathrm{Var}(N_j) \to \ln j \end{split}$$

Lesson 5 : Markov Chain Classification

- > An **absorbing** state is one that cannot be exi-
- > State j is **accessible** $(i \rightarrow j)$ from state i if p_{ij}^n > 0, $\forall n \geq 0$.
- > Two states **communicate** if $i \leftrightarrow j$.
- communicate with each other.
- > A Markov chain is **irreductible** if it has only one class.
- \rightarrow A state (class) is **recurrent** if the probability of \rightarrow **Probability of extinction :** reentering the state is 1. $\sum_{n=1}^{\infty} p_{ii}^{(n)} = \infty$
- > A state (class) si **transcient** if it is not recur-

$$\sum_{n=1}^{\infty} p_{ii}^{(n)} < \infty$$

> A finite Markov Chain must have at least one recurrent class. If it is irreductible, then it is recurrent.

Lesson 6: Markov Chains Li- Lesson 9: Time Reversible miting Probability

- > A chain is **positive recurrent** is the expected number of transitions until the state occur is finite, null recurrent otherwise. Null recurrent mean that the long-term proportion of time in each state is 0.
- > A chain is **periodic** when states occur every n periods for n > 1.
- > A chain is aperiodic when the period is 1. In other world, $P_{ii}^{(1)} > 0$, $\forall i$
- > A chain is **ergodic** when the chain is aperiodic and positive irreductible recurrent.
- > Stationary probability:

$$\pi_j = \sum_{i=1}^n P_{ij} \pi_i \quad \sum_{i=1}^n \pi_i = 1$$

> **Limiting probabilities:** if the chain is ergodic, then

$$\mathbf{P}^{(\infty)} = \begin{pmatrix} \pi_1 & \pi_2 & \pi_3 \\ \pi_1 & \pi_2 & \pi_3 \\ \pi_1 & \pi_2 & \pi_3 \end{pmatrix}$$

Lesson 7: Time in Transient States

- > Tips: Inverting a matrix
- > $\mathbf{S} = (\mathbf{I} \mathbf{P}_{\text{transcient}})^{-1}$, where s_{ij} is the time in state j given that the current state is i.
- $\Rightarrow f_{ij} = \frac{s_{ij} \delta_{i,j}}{s_{jj}} = \sum_{n=1}^{\infty} f_{ij}^{(n)}$, where f_{ij} is the probability that state i ever transitions to state j.

Lesson 8: Branching Processes

- > A branching process is a special type of Markov chain representing the growth or extinction of a population.
- $> E[X_n] = E[Z]^n$, where E[Z] is the expected number of people born in a generation.
- > A **class** of states is a maximal set of state that $\operatorname{Var}(X_n) = \operatorname{Var}(Z) \cdot \operatorname{E}[Z]^{n-1} \sum_{k=1}^n \operatorname{E}[Z]^{k-1}$
 - > If X_0 ≠ 1 mean and variance of X_n need to be multiplicated by X_0 .

$$\pi_0 = \sum_{j=1}^{\infty} p_j \pi_0^j$$

- $\mu \le 1 \Rightarrow \pi_0 \ge 1$, if $X_0 = 1$.
- $-\mu > 1 \Rightarrow \pi_0 < 1$, if $X_0 = 1$.

For cubic equation, it guaranteed to factor $(\pi_0 - 1)$. Tips : Synthetic Division

ightarrow If ${f Q}$ is the reverse-time Markov chain for ergodic P, then

$$\pi_i Q_{ij} = \pi_j P_{ji}$$
with $P_{ii} = Q_{ii}$ and if $p_{ij} = 0 \Leftrightarrow Q_{ji} = 0$

> If Q = P, then P is said to be **time-reversible**.

Lesson 10: Exponential Distribution

> Lack of memory:

$$\Pr(X > k + x | X > k) = \Pr(X > x)$$

> **Minimum**: if $X_i \sim \text{Exp}(\lambda_i)$, then

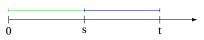
$$\min(X_1, X_2, ..., X_n) \sim \exp\left(\sum_{i=1}^n \lambda_i\right)$$

> The sum of 2 Exponentials randoms variables is the sum of the maximum and the minimum, since one must be the min and the other the

$$X_1 + X_2 = \min(X_1, X_2) + \max(X_1, X_2)$$

Lesson 11: Poisson Process

- > $X(t) \sim \text{Poisson}[m(t)]$, where m(t) is **mean va**lue function representing the mean of the number events before time t.
- > Poisson process can't deacrease over time. $N(t) \ge N(s)$
- N(0) = 0
- > Increament are **independent**:



$$\Pr[N(t) - N(s) = n | N(s) = k] = \Pr[N(t) - N(s) = n]$$

> Non-homogeneous Poisson process:

$$m(t) = \int_0^t \lambda(u) \, \mathrm{d}u$$

where $\lambda(t)$ is the **intensity function**

Homogeneous Poisson process: The Poisson process is said to be homogeneous when the intensity function is a constant.

$$m(t) = \int_0^t \lambda \, \mathrm{d}u = \lambda t$$

We then say that the process have stationary increments.

$$\Pr[N(s)] = \Pr[N(t) - N(s)]$$

Lesson 12: Poisson Process Time To Next Events

- T_n is the time between the n^e event and the (n-1)e event.
- $> S_n = \sum_{i=1}^n T_i$, is the time for the n^e event.
- > $F_{T_1}(t) = 1 e^{-\int_0^t \lambda(u) \, du}$
- > For homogeneous process:

$$T_n \sim \operatorname{Exp}(\lambda)$$

 $S_n \sim \text{Gamma}(n, \lambda)$

Lesson 13: Poisson Process > If N(t) is a Poisson process, then S(t) is a com- > Inclusion/exclusion bounds using minimal **Counting Special Type**

> If event of type 1 occur with probability $\alpha_1(t)$, then the event follow a Poisson process with

$$m(t) = \int_0^t \lambda(u) \alpha_1(u) \, \mathrm{d}u$$

Lesson 14: Poisson Process **Other Characteristics**

- > Only for homogeneous Poisson processes.
- \rightarrow The probability of k event from process 1 is given by:

$$k \sim \text{Binomial}\left(k+l-1,\frac{\lambda_1}{\lambda_1+\lambda_2}\right)$$
 Then the probability that k event from process

1 occur before l from process 2 is :

$$\sum_{i=k}^{k+l-1} \binom{k+l-1}{i} \left(\frac{\lambda_1}{\lambda_1 + \lambda_2}\right)^i \left(\frac{\lambda_2}{\lambda_1 + \lambda_2}\right)^{k+l-1-i}$$

 \rightarrow Given that exactly N(t) = k Poisson events occured before time t, the joint distribution of event time is the joint distribution of k independent uniform random variables on (0, t).

$$F_{S_1,...,S_n|n(t)}(s_1,...s_n|k) = \frac{k!}{t^k}$$

- > For *k* independent uniform random variable on (0, t), the expected value of the jth order statistics is : $E[T^{(j)}] = \frac{jt}{(k+1)}$.
- > Tips: Statistic Order

Lesson 15: Poisson Process Sums and Mixtures

- > A Sums of independent Poisson random variables is a Poisson random with intensify function $\lambda(t) = \sum \lambda_i(t)$. Warning: Substraction don't give a Poisson random variable.
- > A Mixture of Poisson processes is not a Poisson processes.
 - Discrete mixture :

$$F_{X(t)}(t) = \sum_i w_i F_{X_i(t)}(t) \label{eq:fitting}$$
 where $w_i > 0$, $\sum w_i = 1$

- Continuous mixture :

$$F_{X(t)}(t) = \int F_{\{X_u(t)\}}(t) f(u) du$$

- If $N(t)|\lambda$ is a Poisson random variable and $\lambda \sim \text{Gamma}(\alpha, \theta)$, then $N(t) \sim$ NegBin($r = \alpha, \beta = \theta t$).

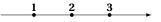
Lesson 16: Compound Poisson Processes

> A **compound** random variable S is define by $S = \sum_{i=1}^{N} X_i$ where N is the **primary** distribution and X the **secondary** distribution.

- pound Poisson process with:
 - $E[S(t)] = \lambda t E[X]$
 - $Var(S(t)) = \lambda t E[X^2]$
- \rightarrow If X_i is discrete, we can separate the process into a sum of subprocess view in Lesson 13: Poisson Process Counting Special Type.
- > Sums of compound homogeneous Poisson process is also a Poisson process with:
 - $N(t) \sim \text{Pois}(\sum \lambda_i)$
 - $-F_X(x) = \sum_i w_i F_{X_i(t)}(t), \quad w_i = \frac{\lambda_i}{\sum_i \lambda_i}$

Lesson 17: Reliability Structure Functions

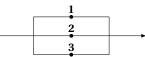
- $\rightarrow \phi(\mathbf{x})$ is the **structure** function for a systeme. It equal 1 if the systeme function, 0 otherwise.
- series system is define as a minimal path set. The system is working if all components are working.



The serie structure function is define as

$$\phi(\mathbf{x}) = \prod_{i=1}^{n} x$$

> A parallel system is define as a minimal cut set. The systeme is working if at least 1 components is working.



The parallel structure function is define as

$$\phi(\mathbf{x}) = 1 - \prod_{i=1}^{n} (1 - x_i)$$

- > Tips: Minimal path set is all way for the system to work, and the minimal cut set is all the way for the system to not work.
- \rightarrow Tips: If set is $\{1,2,3\}$ and $\{1,2\}$, the minimal mean we only take {1,2}.
- > Tips: Minimal cut is a serie of parallel structure and minimal path is a parallel of serie structure.

Lesson 18 : Reliability Proba- $\Rightarrow {}_{t}p_{x} = \frac{\ell_{x+t}}{\ell_{x}}, \quad {}_{t}q_{x} = \frac{\ell_{x}-\ell_{x+t}}{\ell_{x}}$ **bilities**

- $r(\mathbf{p})$ is the same polynomial as $\phi(\mathbf{x})$.
- > Inclusion/exclusion bounds using minimal path:

$$r(\mathbf{p}) \le \sum A_i$$

 $r(\mathbf{p}) \ge \sum A_i - \sum A_i \cup A_j$

$$r(\mathbf{p}) \leq \sum A_i - \sum A_i \cup A_j + \sum A_i \cup A_j \cup A_k$$
 Force of mortality: where $A_i = \sum p_i$ is the probability of the i^e minimal path set work. $\mu_{x+t} = \frac{f_{T_x}(t)}{t p_x}$

cut:

$$\begin{split} 1-r(\mathbf{p}) &\leq \sum A_i \\ 1-r(\mathbf{p}) &\geq \sum A_i - \sum A_i \cup A_j \\ 1-r(\mathbf{p}) &\leq \sum A_i - \sum A_i \cup A_j + \sum A_i \cup A_j \cup A_k \\ \text{where } A_i &= \sum (1-p_i) \text{ is the probability of the } i^\circ \\ \text{minimal cut set work.} \end{split}$$

> Bounds using intersections :

$$\prod \phi(\mathbf{X})^{\mathbf{min. cut}} \leq r(\mathbf{p}) \leq \prod \phi(\mathbf{X})^{\mathbf{min. path}}$$

$$1 - P_n = \sum_{k=1}^{n-1} {n-1 \choose k-1} q^{k(n-k)} P_k$$

$$1 - P_n \le (n+1)q^{n-1}$$

$$P_1 = 1$$

Lesson 19: Reliability Time to Failure

> Expected amound of time to failure:

$$E[\mathbf{system \, life}] = \int_0^\infty r(\bar{\mathbf{F}}(\mathbf{t})) \, \mathrm{d}t$$

where,

- For serie system:

$$r(\bar{\mathbf{F}}(\mathbf{t})) = \prod_{i=1}^{n} \bar{F}_i(t)$$

$$r(\bar{\mathbf{F}}(\mathbf{t})) = \prod_{i=1}^{n} \bar{F}_{i}(t)$$
- For parallel system :
$$r(\bar{\mathbf{F}}(\mathbf{t})) = 1 - \prod_{i=1}^{n} F_{i}(t)$$

- Shortcut: k out of n system with exponentials (θ) : $\mathrm{E}[T] = \theta \sum_{i=k}^n \frac{1}{i}$
- > Hazard rate function (failure rate function) : $h(t) = \frac{f(t)}{\bar{F}(t)}$

$$h(t) = \frac{f(t)}{\bar{F}(t)}$$

and we say that the distribution

- is an increasing failure rate if h(t) is nondeacreasing function of t.
- is an deacreasing failure rate if h(t) is non-increasing function of t.
- > Cumulatice hazard function :

$$H(t) = \int_0^t h(u) du = -\ln \bar{F}(t)$$

with $\frac{H(t)}{t}$ the average of the hazard rate.

Lesson 20: Survival Models

$$t p_x = \frac{\ell_{x+t}}{\ell_x}, \quad t q_x = \frac{\ell_x - \ell_{x+t}}{\ell_x}$$

- $\Rightarrow _{t|u}q_{x}=rac{\ell _{x+t}-\ell _{x+t+u}}{\ell _{x}}$
- $\rightarrow t+up_x = up_x \cdot tp_{x+u}$
- $\rightarrow t|uq_x = t + uq_x tq_x = tp_x \cdot uq_{x+t}$
- > Let be N_x the number of life surviving to age x, then

$$(N_{x+t}|N_x=n)\sim \mathrm{Bin}(n,t\,p_x)$$

$$\mu_{x+t} = \frac{f_{T_x}(t)}{t p_x} = -\frac{\mathrm{d}}{\mathrm{d}t} \ln t p_x$$

> Linear interpolation(D.U.D):

$$\ell_{x+t} = (1-t)\ell_x + t\ell_{x+1}$$
Shortcut: $\forall t \in (0,1), \forall x \in \mathbb{N}, x < x + t < x + 1$

$$tq_x = t \cdot q_x$$

$$\mu_{x+t} = \frac{q_x}{1 - t \cdot q_x}$$

> **Expected life time :** Let $k_x = \lfloor T_x \rfloor$, the *full* years until death. Then e_x is the curtate life expectancy and e_x the complete life expec**tancy**. ω is the age where $\ell_{\omega} = 0$ and $\omega = \infty$ by convention is nothing is said.

$$e_{x} = E[K_{x}] = \sum_{k=1}^{\omega - x - 1} {}_{k} p_{x}$$

$$\dot{e}_{x} = E[T_{x}] = \int_{0}^{\omega - x} {}_{t} p_{x} dt \stackrel{\text{D.U.D}}{=} e_{x} + 0.5$$

Lesson 21 : Contingent **Payments**

The contract here are define with K_x to pay at the end of death year. All same contract can be define with T_x to pay at the moment of death. Then we use integral instead of sum and use

$$\Pr(K = k) = {}_{k}p_{x}q_{x+k} \Rightarrow f_{T_{x}}(t) = {}_{t}p_{x}\mu_{x+t}$$

> Life Insurance:

- Whole Life insurance :

$$A_x = \sum_{k=0}^{\infty} v^{k+1}{}_k p_x q_{x+k}$$

- Term Life insurance:
$$A_{x:\overline{n}|}^{1} = \sum_{k=0}^{n} v^{k+1}{}_{k} p_{x} q_{x+k}$$

- Deferred insurance:

$$m_{\parallel}A_{x} = \sum_{k=m}^{\infty} v^{k+1}{}_{k}p_{x}q_{x+k}$$
- Endowment insurance:

$$A_{x:\overline{n}|} = A_{x:\overline{n}|} + {}_{n}E_{x}$$

$$A_{\mathbf{r}\cdot\overline{\mathbf{n}}} = A_{\mathbf{r}\cdot\overline{\mathbf{n}}}^{1} + nE_{\mathbf{r}}$$

- Pure Endowment :

$$_{n}E_{x}=v^{n}_{n}p_{x}$$

> Life Annuities:

- Whole Life annuity

$$\ddot{a}_x = \sum_{k=0}^{\infty} v^k_{\ k} p_x$$
 – Temporary Life annuity

$$\ddot{a}_{x:\overline{n}|} = \sum_{k=0}^{n} v^k{}_k p_x$$

- Deferred annuity
$$m | \ddot{a}_x = \sum_{k=m}^{\infty} v^k{}_k p_x$$

- Certain and life annuity $\ddot{a}_{\overline{x:\overline{n}|}} = \ddot{a}_{\overline{n}|} + {}_{m|}\ddot{a}_x$

> Illustrative Life Table :

 $- A_x = v^n q_x + p_x A_{x+1}$

$$- \ddot{a}_{x} = 1 + v p_{x} \ddot{a}_{x+1}$$

-
$$\ddot{a}_x = 1 + v p_x \ddot{a}_{x+1}$$

- $A_{x:\overline{n}|}^1 = A_x - {}_n E_x A_{x+n}$

$$- \ddot{a}_{x:\overline{n}|} = \ddot{a}_x - {}_{n}E_x \ddot{a}_{x+n}$$

$$- m_{\parallel} A_x = m E_x A_{x+m}$$

$$- m_{\parallel} \ddot{a}_{x} = {}_{m} E_{x} \ddot{a}_{x+m}$$

$$- \ddot{a}_X = 1 + a_X$$

$$- A_x = 1 - d \ddot{a}_x$$

> **Joint life annuity**(\ddot{a}_{xy}) make payments until the earliest death pf two lives.

Shortcut: $\forall t \in (0,1), \forall x \in \mathbb{N}, x < x + t < x + 1: \Rightarrow$ Last survivor annuity($\ddot{a}_{\overline{xy}}$) make payments until the last death of two lives.

$$\ddot{a}_X + \ddot{a}_V = \ddot{a}_{XV} + \ddot{a}_{\overline{XV}}$$

> Premiums:

$$M \cdot A_{x} = P \ddot{a}_{x}$$

$$P = \frac{M \cdot A_{x}}{\ddot{a}_{x}} = \frac{M}{\ddot{a}_{x}} - M \cdot d$$

Lesson 22: Simulation Inverse Method

> Linear congruential generators:

$$x_k = (ax_{k-1} + c) \bmod m$$

$$x_k = b - \left\lfloor \frac{b}{m} \right\rfloor m$$

where $b = (ax_{i-k} + c)$ and $x_0 \equiv \text{seed}$

> Inverse transformation method:

 $\Pr(F^{-1}(u) \le x) = \Pr(u \le F(x)) = F(x)$ then $x = F^{-1}(u)$ where $U \sim \text{Unif}(0, 1)$

- Normal Case : $x = \mu + \sigma z$
- Log-Normal Case : $x = e^{\mu + \sigma z}$

where $z = \Phi^{-1}(u)$, with linear interpolation.

- > Tips: Discrete Cumulative Function
- > Tips: if $\uparrow U \equiv \downarrow X$ then $(1 u_i) \Rightarrow u_i$

Lesson 23: Simulation Application

$$ightarrow \Pr(X \le x) \simeq \frac{1}{m} \sum_{j=1}^{m} \mathbb{1}_{\left\{x^{(j)} \le x\right\}}$$

>
$$E[X^k] \simeq \frac{1}{m} \sum_{j=1}^{m} [x^{(j)}]^k$$

 $\rightarrow \operatorname{VaR}_k(X) \simeq X^{[j]}$

> TVaR_k(X)
$$\simeq \frac{1}{m(1-k)} \sum_{j=j_0+1}^{m} X^{(j)} \mathbb{1}_{\left\{X^{(j)} > X^{[j_0]}\right\}}$$

 $\simeq \frac{1}{m-j_0} \sum_{j=j_0+1}^{m} X^{[j]}$

where

- $-i_0 = \lfloor m \cdot k \rfloor$
- *m* is the number of simulations.
- $X^{(j)}$ is the jth simulations.
- $X^{[j]}$ is the jth simulations in order statis-

Lesson 24: Simulation Rejection Method

> General method : Let f(x) be the density function of variable to simulate, and let g(x)be the base distribution, a random density function that is easy-to-simulate with nonzero > Some estimator: wherever $f(x) \neq 0$.

$$c = \max \frac{f(x)}{g(x)}$$

Generate two uniform number u_1, u_2 . Let $x = G^{-1}(u_i)$. Accept x_1 only if

$$u_2 \le \frac{f(x_1)}{c \cdot g(x_1)}$$

> Simulating gamma distribution : Use

 $\text{Exp}(\alpha \cdot \theta)$ as the base distribution and $x = \alpha \cdot \theta$ that maximize c.

Simulating standard normal distribution:

Generate 3 uniform u_1 , u_2 , u_3 . Let $y_1 = -\ln u_2$ and $y_2 = -\ln u_2$. Accept y_1 if

and
$$y_2 = -\ln u_2$$
. Accept y
$$y_2 \ge \frac{(y_1 - 1)^2}{2}$$
and add (-) if $u_3 \ge 0.5$

> The **Number of iteration** is a Ross-geometric distribution with mean c. Let be β the mean of a geometric distribution given in the exam appendix:

$$E[N] = 1 + \beta = c$$

$$Var(N) = \beta(1+\beta)$$

Lesson 25: Estimator Quality

> **Bias:** This quality measures if, on average, the estimator is on the expected value of the parameter.

$$E[\hat{\theta}] = \theta + bias_{\hat{\theta}}(\theta)$$

- If bias_{$\hat{\theta}$}(θ) = 0, then $\hat{\theta}$ is **unbiased**.
- If $\lim_{n\to\infty} \text{bias}_{\hat{\theta}}(\theta) = 0$, then $\hat{\theta}$ is **asympto**tically unbiased.
- If $bias_{\hat{\theta}}(\theta) \neq 0$, then $\hat{\theta}$ is **biased**.
- > Consistency: This quality measures if the probability that the estimator is different from the parameter by more than ε goes to 0 as n goes to infinity.

$$\lim_{n \to \infty} \Pr(|\hat{\theta} - \theta| > \varepsilon) \to 0, \ \forall \varepsilon > 0$$

In other word, as $n \to \infty$, $E[\hat{\theta}] \to \theta$, $Var(\hat{\theta}) \to 0$

> **Efficiency:** This quality measures the variance of the estimator. Lower the variance is, more efficient is the estimator.

Efficiency of
$$\hat{\theta} = \frac{\text{Var}(\hat{\theta})^{\text{rao}}}{\text{Var}(\hat{\theta})}$$

Relative efficiency of $\hat{\theta}_1$ to $\hat{\theta}_2 = \frac{\text{Var}(\hat{\theta}_2)}{\text{Var}(\hat{\theta}_1)}$

See the rao-cramer lower bound

Mean Square Error: This quality measures the expected value of the square difference between the estimator and the parameter.

$$MSE_{\hat{\theta}}(\theta) = E[(\hat{\theta} - \theta)^2] = (bias_{\hat{\theta}}(\theta))^2 + Var(\hat{\theta})$$

- > An estimator is called a uniformly minimum variance unbiased estimator(UMVUE) if it's unbiased and if there is no other unbiased estimator with a smaller variance for any true value θ .
- - $\bar{x} = \frac{1}{n} \sum x_i$ is a unbiased estimator of the mean μ . $Var(\bar{x}) = \frac{1}{n} Var(x)$

- $s^2 = \sum \frac{(x_i \bar{x})^2}{n-1}$ is a unbiased estimator of the variance σ^2 .
- $\hat{\sigma}^2 = \sum \frac{(x_i \bar{x})^2}{n}$ is an asymptotically unbiased of the variance σ^2 .
- $\hat{\mu}'_k = \frac{1}{n} \sum x_i^k$, where $\hat{\mu}'_1 = \bar{x}$ and $\hat{\mu}_k = \frac{1}{n} \sum (x_i \bar{x})^k$, where $\hat{\mu}_1 = 0$ and $\hat{\mu}_2 = \hat{\sigma}^2$.

Lesson 26: Kernel Density Estimation

> Empirical distribution : All data is assigning a probability of $\frac{1}{n}$. This is the same method used for simulation, see Lesson 23: Simulation Application.

$$F_{e}(x) = \frac{1}{n} \sum_{i=1}^{n} \mathbb{1}_{\{x_{i} \le x\}}$$

$$f_{e}(x) = \frac{1}{n} \sum_{i=1}^{n} \mathbb{1}_{\{x_{i} = x\}}$$

$$= F_{e}(x) - F_{e}(x_{i-1})$$

- > Kernel Density is a empirical distribution smoothed with a base fonction. Let define the scaling factor b called bandwith.
 - The kernel-density estimate of the density function is : $\hat{f}(x) = \frac{1}{n} \sum k \left(\frac{x - x_i}{h} \right)$ $\Leftrightarrow \sum f_e(x) k\left(\frac{x-x_i}{h}\right)$
 - The kernel-density estimate of the distribution is : $\hat{F}(x) = \frac{1}{n} \sum_{i} K\left(\frac{x - x_i}{h}\right)$
- \rightarrow Rectangular (uniform, box) kermel:

$$k(x) = \begin{cases} \frac{1}{2b}, & -1 \le x \le 1\\ 0, & \text{otherwise} \end{cases}$$

$$K(x) = \begin{cases} 0, & x < -1 \\ 0.5(x+1), & -1 \le x \le 1 \\ 1, & x > 1 \end{cases}$$

$$\hat{f}(x) = \frac{F_e(x+b) - F_e(x-b^{-1})}{2h}$$

> Triangular kernel:

$$k(x) = \begin{cases} \frac{1-|x|}{b}, & -1 \le x \le 1\\ 0, & \text{otherwise} \end{cases}$$

$$K(x) = \begin{cases} 0, & x < -1\\ \frac{(1+x)^2}{2}, & -1 \le x \le 0\\ 1 - \frac{(1-x)^2}{2}, & 0 \le x \le 1\\ 1, & x > 1 \end{cases}$$

> Gaussian kernel: The distribution become normal with $\mu = x_i$ and $\sigma = b$.

$$k(x) = \frac{e^{-x^2/2}}{b\sqrt{2\pi}}$$
$$K(x) = \Phi(x)$$

- $K(x) = \Phi(x)$
- \rightarrow Other kernel: $k(x) = \beta(x)$ and k(x) = B(x)
- \rightarrow **kernel moments :** Let X be the kernel density estimate and x_i the empirical estimate.

We then condition on x_i .

Efficient of
$$X_i$$
.

$$E[X] = E[E[X|x_i]] = E[x_i]$$

$$Var(X_R) = Var(x_i) + \frac{b^2}{3}$$

$$Var(X_T) = Var(x_i) + \frac{b^2}{6}$$

$$Var(X_G) = Var(x_i) + b^2$$

> Tips : For rectangular kernel, $E[x|x_i]$ is a uniform $(x_i - b, x_i + b)$.

Lesson 27: Method of **Moments**

- > Types of data:
 - Complete data: Data is complete if we are given the exact value of each obser-
 - Grouped data: Set of interval and we know how many observation are in each.
 - Censored data: Value that are in a interval, but we don't know the exact value. Like limits $(\min(X, u))$.
 - Truncated data: We have data only when it in certain range, otherwise we don't know. Like deductible (X|X > d).
- > **Method of Moments :** We match $\hat{\mu}'_{k} = E | X^{k} |$ and find the parameters. If data is Censored or Truncated, we need to match the censored or truncated moment : $\hat{\mu}'_k = \mathbb{E}\left[\min(X, u)^k\right]$ or $\hat{\mu}'_k = \mathbf{E} \left| X^k | X > d \right|.$
- > For pareto distribution, if $\hat{\mu}'_2 = \hat{\sigma}^2 + \bar{x}^2 \le 2\bar{x}^2$, the method of moment is unstable and can't be used.

Lesson 28: Percentile **Matching**

- > **Percentile Matching :** We match $F_e(\hat{\pi}_p) = p$ and find the parameters.
 - For censored data, we need select percentiles within the range of the uncensored portion of the data.
 - For truncated data, we need to match the percentiles of the conditional distribution:

bution:

$$F(x|X > d) = \frac{\Pr(d < X \le x)}{\Pr(X > d)} = \frac{F(x) - F(d)}{1 - F(d)}$$

$$S(x|X > d) = \frac{S(x)}{S(d)}$$

> Smoothed empirical percentile:

$$\hat{\pi}_{n} = (1 - h)X^{[j]} + hX^{[j+1]}$$

- $j = \lfloor (n+1)p \rfloor$
- h = (n+1)p j
- $X^{[j]}$ is the jth order statistics.

Lesson 29: Maximum Likehood Estimators

> Maximum Likehood Estimators : We maximize the probability of observing the data.

$$L(\theta) = \prod_{i=1}^{n} g(x_i; \theta)$$
$$l(\theta) = \sum_{i=1}^{n} \ln_i g(x_i; \theta)$$

- Individual data : $g(x_i; \theta) = f(x_i)$
- Grouped data: $g(x_i;\theta) = F(x_i) F(x_{i-1})$
- Censored data : $g(x_i; \theta) = S(x_i)$
- Truncated data : $g(x_i; \theta) = \frac{f(x)}{g(x)}$

Lesson 30: MLE Special Techniques

- > Case MLE equals MME
 - For Exponential, $\hat{\theta}^{\text{MLE}} = \bar{x}$
 - For Gamma with fixed α , $\hat{\theta}^{\text{MLE}} = \hat{\theta}^{\text{MME}}$
 - For Normal, $\hat{\mu}^{\text{MLE}} = \bar{x}$ and $(\hat{\sigma}^2)^{\text{MLE}} = \frac{1}{n} \sum (x_i \hat{\mu})^2$
 - For Binomial, $mq = \bar{x}$ then given m, $\hat{q}^{\text{MLE}} = \frac{\bar{x}}{m}$
 - For Poisson, $\hat{\lambda}^{\text{MLE}} = \hat{\lambda}^{\text{MME}}$
 - For Binomial Negative, given r or β , $(r\beta)^{\text{MLE}} = \bar{x}$
- > Parametrization and Shifting:
 - Parametrization : MLE's are independent of parametrization $\lambda = \frac{1}{A} \Leftrightarrow \hat{\lambda}^{\text{MLE}} = \frac{1}{\hat{\alpha}_{\text{MLE}}}$
 - Shifting the distribution is equivalent of shifting the data.
- > Transformations : MLE's are invariant under one-to-one transformation. Then if we have a transformed variable, we can untransform the data and find the parameter of the untransform distribution.

Tips: Transformations of distribution

Weibull distribution: If the data is censored(u) or truncated(d), then

$$\left(\hat{\theta}^{\text{MLE}}\right)^{\mathsf{T}} = \frac{\sum (x_i - d_i)^{\mathsf{T}}}{\sum \mathbb{1}_{\{x_i \leq u\}}}$$
 if $\tau = 1$, then the distribution is Exponential.

Pareto distribution with fixed θ : $\hat{\alpha} = \frac{n}{V}$

$$K = \sum_{i=1}^{n+c} \ln(\theta + d_i) - \sum_{i=1}^{n+c} \ln(\theta + x_i)$$
 where $n \equiv$ number of non-censored(c) data.

> Single-parameter Pareto : $\hat{\alpha} = \frac{1}{K}$

$$K = \sum_{i=1}^{n+c} \ln \max(\theta, d_i) - \sum_{i=1}^{n+c} \ln x_i$$

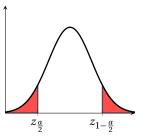
where $n \equiv$ number of non-censored(c) data.

- \rightarrow Uniform(0, θ): We take the smalest θ possible, $\hat{\theta}^{\text{MLE}} = \max(x_1,...,x_n)$
 - Censored(u): $\hat{\theta}^{\text{MLE}} = \frac{nd}{\sum \mathbb{1}_{\{x_i < d\}}}$

- Grouped : We take the heighest interval(L, U). $\hat{\theta}^{\text{MLE}} = \min(U, \hat{\theta}^{\text{MLE}}_{\text{Censored(L)}})$
- > Bernouilli : Let have a random variable that can take 2 values, *n* and *m*. Then

$$\hat{p} = \frac{n}{n+m}$$

> Tips : If $L(\theta)$ look like a density distribution, $\hat{\theta}^{\text{MLE}} \equiv \text{mode of this distribution.}$



Lesson 31: Variance of MLE

> Fisher information matrix :

$$I(\theta) = nE\left[\left(\frac{\mathrm{d}\ln f(x;\theta)}{\mathrm{d}\theta}\right)^{2}\right]$$
$$= -nE\left[\frac{\mathrm{d}^{2}\ln f(x;\theta)}{\mathrm{d}\theta^{2}}\right]$$

using the loglikehood function

$$I(\theta) = E\left[\left(\frac{\mathrm{d}l(x_1, ..., x_n; \theta)}{\mathrm{d}\theta}\right)^2\right]$$
$$= -E\left[\frac{\mathrm{d}^2l(x_1, ..., x_n; \theta)}{\mathrm{d}\theta^2}\right]$$

> **Rao-Cramer lower bound** is the lowest possible variance for a unbiased estimator $\hat{\theta}$ of θ . Then $\hat{\theta} \sim \text{Normal}(0, \text{Var}(\hat{\theta})^{\text{rao}})$

$$\operatorname{Var}(\hat{\theta})^{\operatorname{rao}} \ge \frac{1}{I(\theta)}$$

under certains regularity conditions

- The seconde derivative of the loglike-hood exist.
- The support of the density function is not function of θ .

Lesson 32 : Sufficient Statistics

- > A **sufficient statistics** are statistics that capture all the information about the parameter we are estimating that the sample as to offer.
- > A statistics is sufficient when the distribution of a sample given a statistics does not depend on the parameter. Y is a sufficient statistics for a parameter θ if and only if

$$L(x_1,...,x_n;\theta|Y)=h(x_1,...,x_n)$$

$$L(x_1,...,x_n;\theta) = g(y)h(x_1,...,x_n)$$

where $h(x_1,...,x_n)$ is a function that does not involve θ .

- > **Rao-Blackwell** Theorem : For any unbiased estimator $\hat{\theta}$ and sufficient statistic Y, the estimator $\mathrm{E}[\hat{\theta}|Y]$ is unbiased and has variance less than or equal to $\mathrm{Var}(\hat{\theta})$.
- > The maximum likehood estimator is a function of a sufficient statistic.

Lesson 33 : Hypothesis Testing

Appendix

Inverting a matrix

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$
Abouter pour une matrice 3x3

Synthetic Division

Exemple: Factorize $x^3 - 12x^2 - 81$

Deductible and Limite

$$X = \min(X; d) + \max(0; X - d)$$

$$E[X] = E[\min(X; d)] + E[\max(0; X - d)]$$

$$= E[(X \land d)] + E[(x - d)_+]$$

$$= E[(X \land d)] + e_X(d) \cdot S_X(d)$$

Statistic Order

$$\begin{array}{l} > \ Y_1 = \min(X_1,...,X_n) \\ f_{Y_1}(y) = n f(y) [S(y)]^{n-1} \\ S_{Y_1}(y) = \prod_{i=1}^n \Pr \big(X_i > x \big) \end{array}$$

>
$$Y_n = \max(X_1, ..., X_n)$$

 $f_{Y_n}(y) = n f(y) [F(y)]^{n-1}$

$$F_{Y_n}(y) = \prod_{i=1}^n \Pr\left(X_i \leq x\right)$$

>
$$Y_k \in (Y_1, ..., Y_k, ..., Y_n)$$

$$f_{Y_k}(y) = \frac{n! \cdot f(y) [F(y)]^{k-1} [S(y)]^{n-k}}{(k-1)! (n-k)!}$$

$$(k-1)!(n-k)!$$

$$F_{Y_k}(y) = \Pr\left(\text{at least k of n } X_i \text{ are } \le y\right)$$

$$(y) = \Pr\left(\text{at least k of fi } X_i \text{ are } \le y\right)$$
$$= \sum_{i=1}^n \binom{n}{i} [F(y)]^i [S(y)]^{n-j}$$

 $\Rightarrow x + y = \min(x, y) + \max(x, y)$, since one is for sure the max and the other the min.

Mode: Most likely probability

- \Rightarrow g(x) = f(x) or some time $g(x) = \ln f(x)$
- > **Mode** is the x that respects: g'(x) = 0

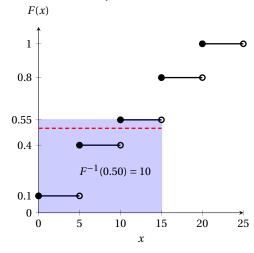
Normal Approximation

- $F_X(x) = \Phi\left(\frac{X E[X]}{\sqrt{Var(X)}}\right)$
- > Continuity correction is necessary when X is discrete. $F_X(x) = \Phi\left(\frac{(X\pm k) - E[X]}{\sqrt{\text{Var}(X)}}\right)$ where k is the mid-point of the discrete value.

Discrete Cumulative Function

$$\Pr(X = x) = \begin{cases} 0.10, & x = 0 \\ 0.30, & x = 5 \\ 0.15, & x = 10 \\ 0.25, & x = 15 \\ 0.20, & x = 20 \end{cases}$$

$$\Pr(X \le x) = \begin{cases} 0.10, & 0 \le x < 5 \\ 0.40, & 5 \le x < 10 \\ 0.55, & 10 \le x < 15 \\ 0.80, & 15 \le x < 20 \\ 1, & x \ge 20 \end{cases}$$



Contract

- > Deductible(d)
- > Maximum(u)
- > Inflation(r)
- > Coinsurance(α)

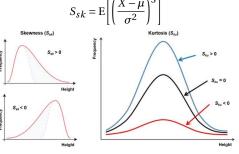
$$Y = \left\{ \begin{array}{cc} 0 & x \leq \frac{d}{1+r} \\ \alpha[(1+r)x - d] & \frac{d}{1+r} < x < \frac{u}{1+r} \\ \alpha[u - d] & x \geq \frac{u}{1+r} \end{array} \right.$$

Warning: The maximal don't include the deductible.

Moments

- \rightarrow ke moment about the origin. $\mu'_k = E |X^k|$
- > k^e moment about the mean. $\mu_k = E[(X \mu)^k]$

> The **Skewness** moment give infomation about the asymmetry of the distribution. If $S_{sk} = 0$, the distribution is normal.



> The kurtosis moment give infomation about the flattening of the distribution. If $S_{ku} = 0$,

the distribution is normal.
$$S_{ku} = \mathrm{E} \left[\left(\frac{X - \mu}{\sigma^2} \right)^4 \right]$$

> The **coefficient of variation** give information about the dispersion of the distribution.

$$CV = \frac{\sigma}{E[X]}$$

Transformations of distribution

 \rightarrow Lognormal: $Y = e^X$, where

 $Y \sim \text{Lognormal}(\mu, \sigma)$

 $X \sim \text{Normal}(\mu, \sigma)$

> Inverse Exponential : $Y = \frac{1}{X}$, where $Y \sim \text{Inverse Exponential}(1/\theta)$

 $X \sim \text{Exponential}(\theta)$

 \rightarrow Weibull : $Y = X^{1/\tau}$, where $Y \sim \text{Weibull}(\sqrt[\tau]{\theta})$

 $X \sim \text{Exponential}(\theta)$

Parameter interpretation

- > **Scale parameter** (θ , β , σ): Affect the spread of the distribution.
- > Rate parameter (λ): Affect the rate of data at mean. (1/scale)
- > **Shape parameter** (α, τ, γ) : Affect the shape rather then simply shift the distribution.