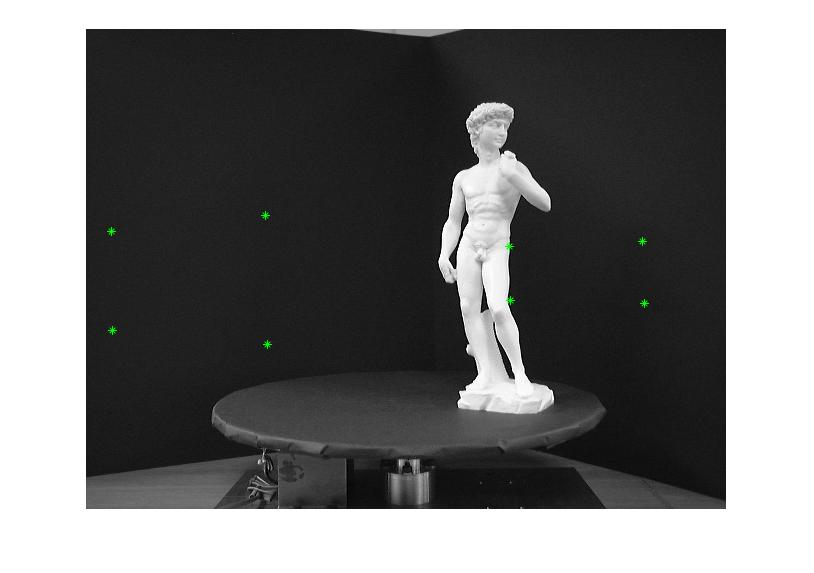
# Shape From Silhouette Project

Given: Images taken of a statue from 18 different angles

Task: Create a 3D model of the object

The first step was to extract the silhouette of the object. This was done by trial and error of the *silhouetteThreshold* variable until the statue appeared with little noise around it. This trial and error process can be seen in figures \_\_ through \_\_.

* The next step was to determine the minimum and maximum values of *bbox* to capture the entire statue. Figure \_\_ shows a very skewed rectangular prism. This was done in order to determine what are the x, y, and z directions in the image before adjusting the bounds of the box. The bounds of the box were also adjusted using trial and error to get a box that seemed to encompass the entire statue from all angles.



+x

+z

+y

* Figures \_\_ to \_\_ shows the locations of the centers of each voxel, viewed from a few different angles. This is just for demonstration purposes so that you can see the statue still. In the actual program, I used a very high number of voxels (4,760,000) to generate an accurate 3D map. When plotting the centers of the voxels, it appears to be a solid block, as is seen in Figure \_\_. This used 50, 150, and 70 voxels in the x, y, and z directions, respectively.
* The next step was to determine which voxel contained the statue. This was done by getting the individual pixel coordinates of each of the centers and seeing if they lie on a white pixel from the intensity-thresholded image.
* A high-resolution (many voxels) model was used to accurately extract the edges, as is seen in Figure \_\_.