

Euler Equations for 2-D Compressible Flow (Differential Eqn. Form)

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{V}) = 0 \quad (1)$$

$$\frac{\partial(\rho u)}{\partial t} + \vec{\nabla} \cdot (\rho u \vec{V}) = -\frac{\partial p}{\partial x} \quad (2)$$

$$\frac{\partial(\rho v)}{\partial t} + \vec{\nabla} \cdot (\rho v \vec{V}) = -\frac{\partial p}{\partial y} \quad (3)$$

$$\frac{\partial(\rho e_0)}{\partial t} + \vec{\nabla} \cdot (\rho h_0 \vec{V}) = 0 \quad (4)$$

* No viscous/heat transfer terms in Euler

$$\vec{\nabla} = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} \quad (\vec{\nabla} \cdot \text{ is "divergence" operator})$$

Recall $h_0 = h + \frac{1}{2} V^2$

where $V^2 = \sqrt{u^2 + v^2}$

and $h \equiv e + \frac{p}{\rho}$

internal energy

so $h_0 = e + \frac{1}{2} V^2 + \frac{p}{\rho} = e_0 + \frac{p}{\rho}$

e_0

$e_0 = h_0 - p/\rho$

Euler equations contain 6 unknowns at each location within a flowfield =

ρ, u, v, p, e, T

above equations:

Need two more equations to supplement (1)-(4) and boxed

(ideal gas law)

$p = \rho R T$

$e = c_v T$

(calorically perfect gas)

Euler Equations in Integral Form

Use Gauss Divergence Theorem to convert from Differential Form to Integral Form:

$$\oint_{S_2} \vec{F} \cdot d\vec{S} = \int_{V_2} \vec{\nabla} \cdot \vec{F} dV \quad (\text{for any differentiable function } \vec{F})$$

S_2 SURFACE
 CONTROL
 OF CONTROL
 VOLUME

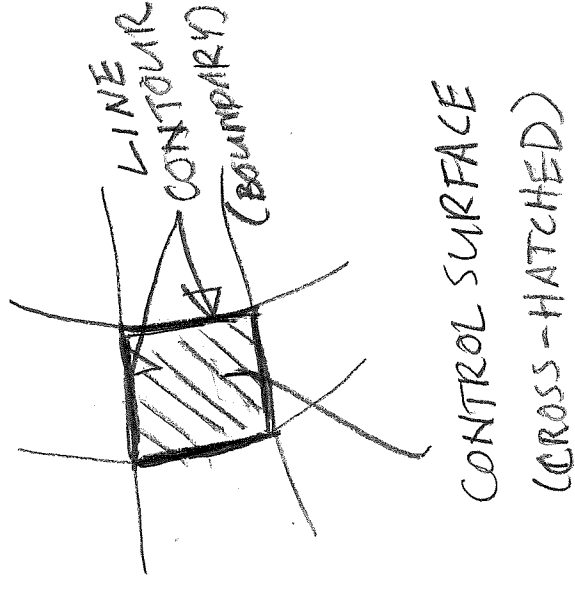
V_2 CONTROL
 VOLUME

2-D:

$$\oint_C \vec{F} \cdot d\vec{C} = \int_{S_2} \vec{\nabla} \cdot \vec{F} dS$$

C CURVE (LINE)
 CONTROL OF
 CONTROL SURFACE

S_2 CONTROL
 SURFACE



Applied to continuity eqn:

Let $\vec{F} = \rho \vec{V}$

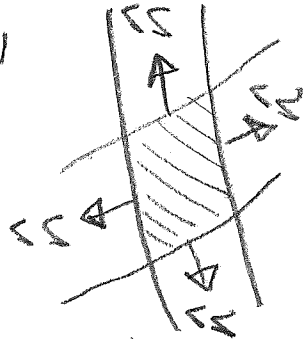
\vec{F}

\vec{F}

\Rightarrow

$$\int_V \vec{\nabla} \cdot (\rho \vec{V}) dV = \oint_C \rho \vec{V} \cdot d\vec{s}$$

$$= \oint_C \rho (\vec{V} \cdot \hat{n}) dA$$



\hat{n} : outward unit
vector normal

(along contour)
($\hat{n} = n_x \hat{i} + n_y \hat{j}$)

Continuity becomes:

$$\int_V \frac{\partial \rho}{\partial t} dV + \oint_C \rho (\vec{V} \cdot \hat{n}) dA = 0$$

time rate of
change of density
within control surface

mass flux rate
thru boundary
of control surface

Apply to all 4 equations and condense =

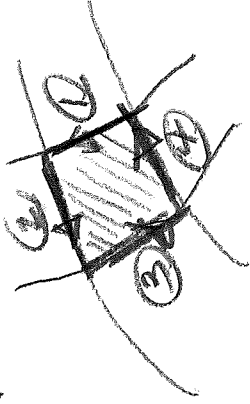
Euler Eqs in Integral Form

$$\int_S \frac{d\vec{u}}{dt} ds \cdot \int_C (\vec{F}_{INV} \cdot \vec{n}) = 0$$

\int_C inviscid flux vector

$$\text{where: } \vec{u} = \begin{bmatrix} \varphi \\ \varphi u \\ \varphi v \\ \varphi e_0 \end{bmatrix} \quad \vec{F}_{INV} = \begin{bmatrix} \varphi(\vec{V} \cdot \vec{n}) \\ \varphi u(\vec{V} \cdot \vec{n}) + n_x p \\ \varphi v(\vec{V} \cdot \vec{n}) + n_y p \\ \varphi h_0(\vec{V} \cdot \vec{n}) \end{bmatrix} \quad \begin{matrix} \text{"state vector"} \\ \text{"flux vector"} \end{matrix}$$

* can evaluate contour integral using piecewise integration of 4 sides (for a quadrilateral cell)

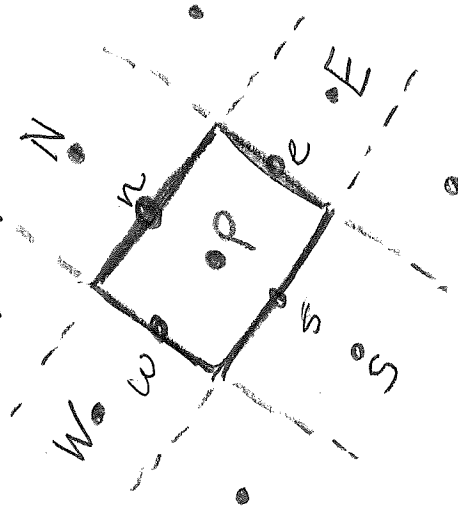


Finite-Volume Method

OK for small Δt 's

* approximate $\int_S \frac{d\vec{u}}{dt} ds \approx \sum \frac{d\vec{u}_p}{dt} \approx \sum \frac{\Delta \vec{u}_p}{\Delta t}$

where \vec{u}_p is state vector at cell center "p"



* replace contour integral with

sum over all cell sides and using

"face center" state vectors (N-E-S-W)

Euler equations become:

$$\sum \frac{\Delta \vec{u}_p}{\Delta t} = - \sum_{i=1}^4 \left(\vec{F}_{INV,i} \cdot \hat{n}_i \right)$$

(faces)

* \vec{F}_{INV} at each face is estimated based on

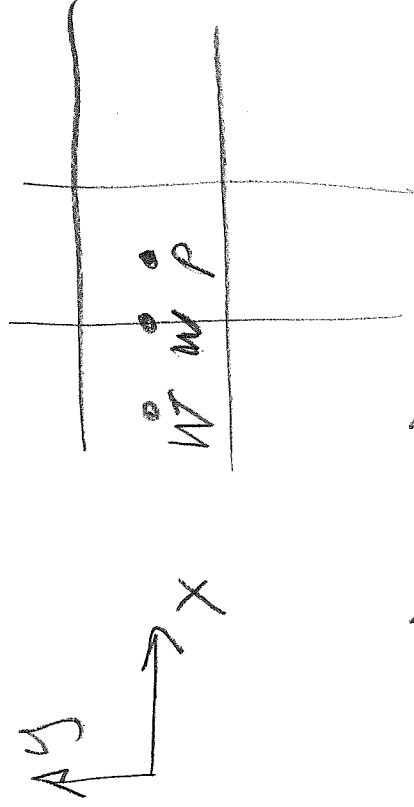
nearby cell states

* Can solve for $\frac{d\vec{u}_p}{dt}$ with $\vec{F}_{INV} \Rightarrow$ get change in \vec{u}_p

Upwinding

Using convective and/or acoustic info to estimate cell face states

Here is simple method used by Fluent's pressure based solver:



$$\vec{u}_w = \vec{u}_W \text{ if } u > 0 \text{ (flow to left)}$$

$$\vec{u}_w = \vec{u}_P \text{ if } u < 0 \text{ (flow to right)}$$

} based on
convection alone

* this is "1st order upwinding" (uses only nearest neighbor cells)

CFD (Fluent) Terminology

pressure-based scheme: solves Euler equations separately ("decoupled") during each time step (iteration)
(very efficient for low speed flows when ρ variations are weak)

density-based scheme: solves Euler equations together ("coupled") during each time step (iteration)

steady method: time step applied at each cell is different and as large as possible to converge quickly

transient method: time step at each cell is identical so that solution develops in time-accurate manner

Solution controls for density-based scheme =

AUSM ~ robust method for estimating cell face states
(captures strong shocks well)

Roe ~ precise (but less robust) method for
estimating cell face states
(not recommended for supersonic flows)

Boundary conditions needed for high speed flow over airfoil =

1. Pressure farfield at boundaries "far" from airfoil
(enforces freestream conditions with minimal "reflections")
2. Wall at airfoil surface boundaries
(enforces "no-slip" condition)