

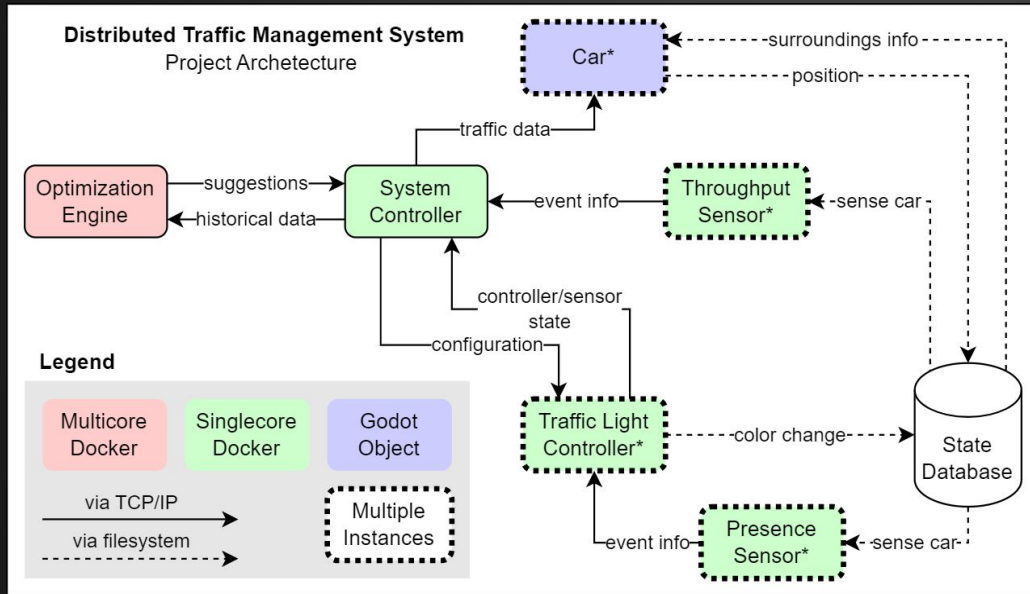
# Distributed Traffic Management

*Presented by:*  
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CPSC 5387 - Distributed Computing  
Fall 2024

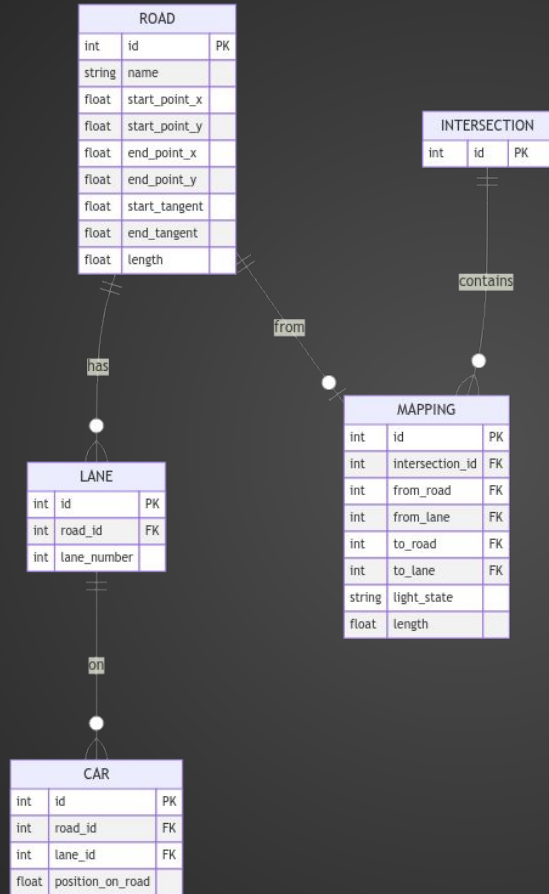


# The Plan



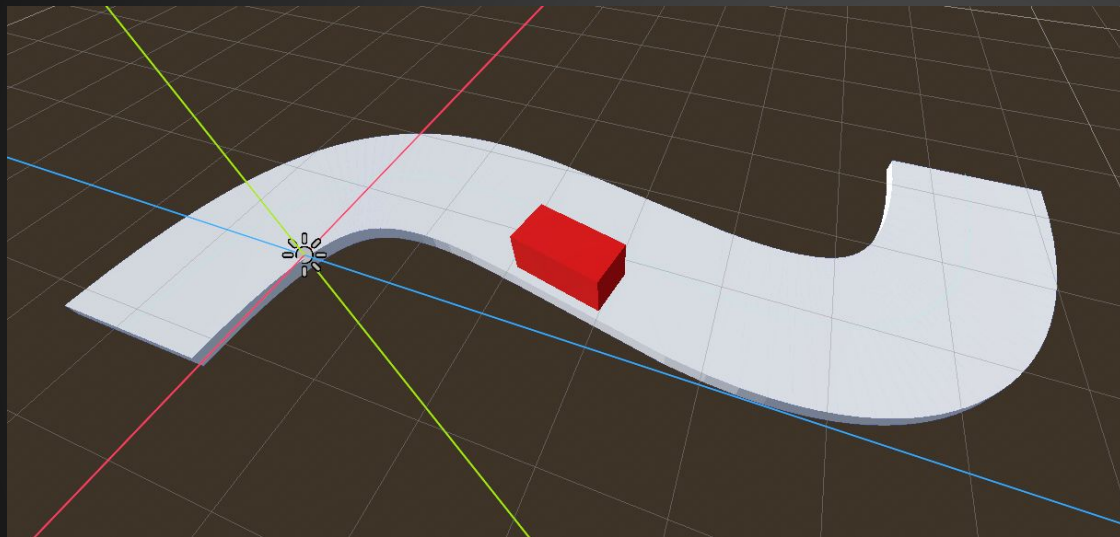
UA LITTLE ROCK

# The Plan



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# The Plan



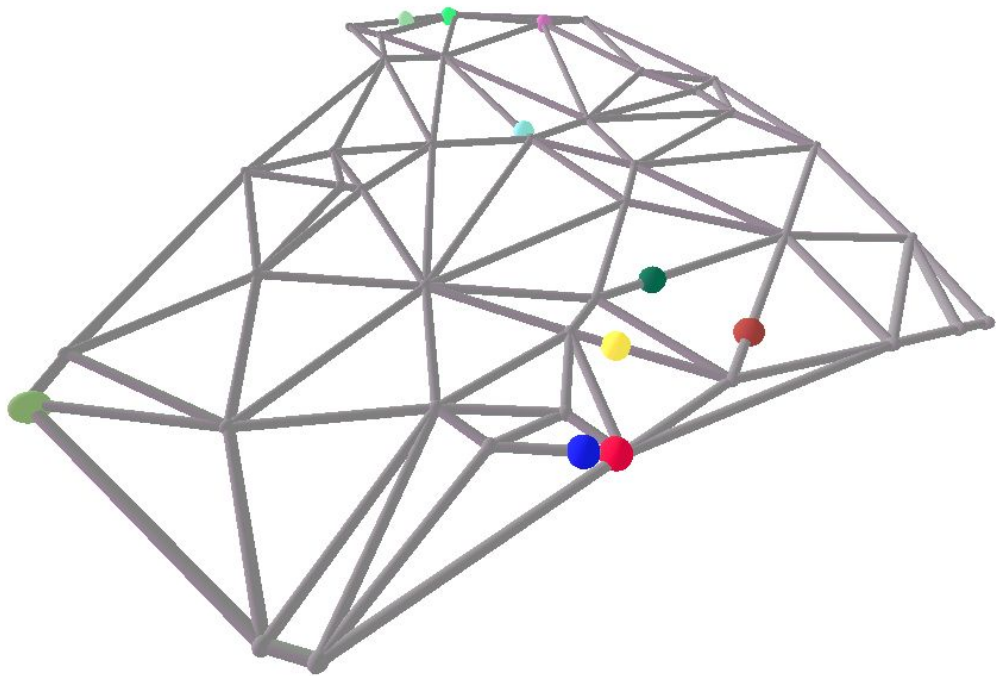
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# The Issues

- Docker Obfuscation
- Geometry
- Complexity



# The Scaled Down Prototype



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ROCK

# The Scaled Down Prototype Features

- API calls
- Multiple processes (could be wrapped in Docker later)
- Each car is responsible for their own path but can get data from global sensors.



# Features Missing

- No traffic lights
- No benchmarking on traffic throughput for different light algorithms





Demo

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ROCK