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9.1 Solutions

- 1 (a) True (because A + B = B + A).
 - (b) False.
 - (c) True.

$$\mathbf{2} \ EFG = \left[\begin{array}{cccc} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 1 \end{array} \right] \text{ and } GFE = \left[\begin{array}{cccc} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 4 & 2 & 1 & 0 \\ 8 & 4 & 2 & 1 \end{array} \right].$$

 $\textbf{3} \ \, \text{All such matrices other than} \left[\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array} \right], \left[\begin{array}{cc} 0 & 1 \\ 1 & 0 \end{array} \right], \left[\begin{array}{cc} 0 & 1 \\ 1 & 1 \end{array} \right], \left[\begin{array}{cc} 1 & 0 \\ 1 & 1 \end{array} \right], \left[\begin{array}{cc} 1 & 1 \\ 1 & 0 \end{array} \right], \text{and} \left[\begin{array}{cc} 1 & 1 \\ 0 & 1 \end{array} \right] \text{ have columns or rows that are multiples } (-1 \text{ times or } 1 \text{ times}) \text{ of each other. So these are the only invertible ones.}$

4 A's column space is a line — all vectors of the form $\begin{bmatrix} x \\ 0 \end{bmatrix}$ (the x-axis). The column space of B is also a line generated by the $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ vector; that is all vectors of the form $\begin{bmatrix} x \\ 2x \end{bmatrix}$. For C, the column space is the entire \mathbb{R}^2 plane.

5 Since (x,y)=(2,5) lies on the y=mx+c line, we have $5=m\cdot 2+c$. Similarly, for (x,y)=(3,7) we have $7=m\cdot 3+c$. This corresponds to the system $\begin{cases} 2m+c=5\\ 3m+c=7 \end{cases}$, whose matrix form is $\begin{bmatrix} 2&1\\ 3&1 \end{bmatrix} \begin{bmatrix} m\\c \end{bmatrix} = \begin{bmatrix} 5\\7 \end{bmatrix}$ and whose solution is m=2 and c=1 (a line with slope 2).

6 Note how with successive powers of A the 2s turn to $2^2, 2^3$, etc. and move up north-east:

All higher powers of A give a 4 by 4 matrix of zeros.

7 AX will be the identity matrix $I = [Ax_1 Ax_2 Ax_3]$ when $X = [x_1 x_2 x_3]$.

8
$$A^{-1} = \frac{1}{a(a-b)} \begin{bmatrix} a & 0 & -b \\ -a & a & 0 \\ 0 & -a & a \end{bmatrix}$$
. As long as $a \neq 0$ and $a - b \neq 0, A^{-1}$ exists.

$$\begin{bmatrix} 1 & 2 & 3 & 5 & b_1 \\ 2 & 4 & 8 & 12 & b_2 \\ 3 & 6 & 7 & 13 & b_3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 5 & b_1 \\ 0 & 0 & 2 & 2 & b_2 - 2b_1 \\ 0 & 0 & -2 & -2 & b_3 - 3b_1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 5 & b_1 \\ 0 & 0 & 2 & 2 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_3 + b_2 - 5b_1 \end{bmatrix}$$

$$(9.1)$$

- (b) From (a) we get the solvability condition $b_3 + b_2 5b_1 = 0$, which makes the last row 0 = 0.
- (c) The column space is the plane in \mathbb{R}^3 containing all combinations of the pivot columns $\begin{bmatrix} 1\\2\\3 \end{bmatrix}$ and $\begin{bmatrix} 3\\8\\7 \end{bmatrix}$. The pivots are in columns 1 and 3.
- (d) The special solutions come from \mathbb{R}^4 and have free variables $x_2=1, x_4=0$ and then $x_2=0, x_4=1$:

All combinations of the two special solutions:
$$\boldsymbol{x}_n = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -2 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$
 (the nullspace $N(A)$ in \mathbb{R}^4

(e) Continue row reductions upward to find the reduced form $[R \ d]$. Starting from from 9.1 above, the right-hand side is $\begin{bmatrix} b_1 \\ b_2 - b_1 \\ b_3 + b_2 - 5b_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 6 - 0 \\ (-6) + 6 - 5 \cdot 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 6 \\ 0 \end{bmatrix}$ (because the original vector \mathbf{b} was

equal to
$$\begin{bmatrix} 0 \\ 6 \\ -6 \end{bmatrix}$$
):

$$[U\ \boldsymbol{c}] = \left[\begin{array}{ccc|c} 1 & 2 & 3 & 5 & 0 \\ 0 & 0 & 2 & 2 & 6 \\ 0 & 0 & 0 & 0 & 0 \end{array}\right] \rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 0 & 2 & -9 \\ 0 & 0 & 1 & 1 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{array}\right] = [R\ \boldsymbol{d}].$$

So the right-hand side becomes $\mathbf{d} = \begin{bmatrix} -9 \\ 3 \\ 0 \end{bmatrix}$, showing -9 and 3 in the particular solution \mathbf{x}_p (shown in part (f)).

(f) The particular solution is obtained by setting all free variables to zero and back substituting in $[R \ d]$

to find the pivots is thus
$$\boldsymbol{x}_p = \begin{bmatrix} -9 \\ 0 \\ 3 \\ 0 \end{bmatrix}$$
 The complete solution to $A\boldsymbol{x} = \begin{bmatrix} 0 \\ 6 \\ -6 \end{bmatrix}$ is then $\boldsymbol{x}_p + \boldsymbol{x}_n$:

The complete solution:
$$\mathbf{x} = \begin{bmatrix} -9\\0\\3\\0 \end{bmatrix} + x_2 \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix} + x_4 \begin{bmatrix} -2\\0\\-1\\1 \end{bmatrix}.$$

10 (a) The dimension of the nullspace is 1, so A must have 4-1=3 pivots.

- (b) The complete solution to Ax = 0 is $x = x_3 \begin{bmatrix} 2 \\ 3 \\ 1 \\ 0 \end{bmatrix}$ (for any real number x_3).
- (c) The row reduced echelon form has 3 pivots and the special solution $\boldsymbol{x} = \begin{bmatrix} 2 \\ 3 \\ 1 \\ 0 \end{bmatrix}$, so

$$R = \begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- 11 (a) The row operations are:
 - \circ E adds 10 times row 2 to row 3
 - \circ F adds 11 times row 3 to row 4
 - \circ G swaps rows 1 and 2
 - \circ H adds 4 times row 4 to row 1
 - (b) The upper right corner of A is zero because if it were anything other than zero we would never have to swap rows 1 and 2 (which is what G does).
 - (c) The upper triangular U corresponds to the upward elimination, so we have

$$U = \begin{bmatrix} 1 & 0 & 0 & 4 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

The permutation matrix P corresponds to the permutation of the first two rows, so we have

$$P = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

The lower triangular L corresponds to the first two elimination steps combined (the product FE):

12 A's characteristic equation: det $\begin{bmatrix} -\lambda & 2 & 2 \\ 2 & -\lambda & 2 \\ 2 & 2 & -\lambda \end{bmatrix} = 0 \implies (\lambda+2)^2(\lambda-4) = 0$ gives $\lambda_{1,2} = -2$ (a repeated eigenvalue of algebraic multiplicity 2) and $\lambda_3 = 4$.

$$\circ \ \textit{Eigenvectors for $\lambda_3=4$:} \left[\begin{array}{ccc} -4 & 2 & 2 \\ 2 & -4 & 2 \\ 2 & 2 & -4 \end{array} \right] \left[\begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array} \right] = \left[\begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right].$$

Gaussian elimination gives $\begin{bmatrix} -4 & 2 & 2 \\ 0 & -3 & 3 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$, and we pick the eigenvector $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.

• Eigenvectors for
$$\lambda_{1,2} = -2$$
:
$$\begin{bmatrix} 0 - (-2) & 2 & 2 \\ 2 & 0 - (-2) & 2 \\ 2 & 2 & 0 - (-2) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 & 2 & 2 \\ 2 & 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ 2 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
. Gaussian elimination of which gives
$$\begin{bmatrix} 2 & 2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
. Here we have 2 free variables (x_3) and (x_2) and one pivot (x_1) . Setting the two free variables as usual (setting one free

$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
. Gaussian elimination of which gives
$$\begin{bmatrix} 2 & 2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
. Here we have 2 free

variables $(x_3 \text{ and } x_2)$ and one pivot (x_1) . Setting the two free variables as usual (setting one free variable to 1, the other to 0, and determining the pivot), we see that the space of eigenvectors corre-

sponding to
$$\lambda_2 = -2$$
 is two-dimensional: $x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$.

So the matrix S is $\begin{bmatrix} 1 & -1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$ and $S^{-1} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$. Thus A can be diagonalized as

$$A = S\Lambda S^{-1} = \frac{1}{3} \cdot \begin{bmatrix} 1 & -1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 4 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

And A^8 can be computed as

$$A^8 = S\Lambda^8 S^{-1} = \frac{1}{3} \cdot \begin{bmatrix} 1 & -1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 4^8 & 0 & 0 \\ 0 & (-2)^8 & 0 \\ 0 & 0 & (-2)^8 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix},$$

which works out to
$$A^8 = \left[\begin{array}{cccc} 22016 & 21760 & 21760 \\ 21760 & 22016 & 21760 \\ 21760 & 21760 & 22016 \end{array} \right].$$

13 There's more than one way to argue why A = B, but one way is to note that the decompositions of $A = S\Lambda S^{-1}$ and $B = S\Lambda S^{-1}$ are identical because their S matrices are made up of the eigenvectors that are the same and their Λ matrices have the same entries because their eigenvalues are the same.

- 14 (a) Because both columns add up to 1, A has an eigenvalue $\lambda_1 = 1$. To find the other eigenvalue, recall that A's eigenvalues always add up to A's trace (which is the sum of A's diagonal entries). Checking the trace, trace(A) = .4+c, we see that the other eigenvalue must be $\lambda_2 = .4+c-\lambda_1 = .4+c-1 = c-.6$.
 - (b) If c = 1.6, then both eigenvalues of A are 1. The eigenvectors of $A = \begin{bmatrix} .4 & -.6 \\ .6 & 1.6 \end{bmatrix}$ are all multiples of $\boldsymbol{x} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ (that is, $\lambda = 1$ has geometric multiplicity equal to 1).

15 You want to make $A = S\Lambda^{1/2}S^{-1}$, where S is the eigenvector matrix shared by both A and B (recall that the eigenvalues of A^2 are the squares of the eigenvalues of A, and the eigenvectors of A^2 are the same as the eigenvectors of A). So, find the eigenvectors and put them in S to get

$$A = S\Lambda^{1/2}S^{-1} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \cdot \begin{bmatrix} 3 & \\ & 1 \end{bmatrix} \cdot \left(\frac{1}{2}\right) \cdot \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \quad \text{has } A^2 = B.$$

16 $A = S\Lambda S^{-1}$ approaches zero if and only if every $|\lambda| < 1$. A_1 is column stochastic and has an eigenvalue = 1, so it will not approach the zero matrix. But A_2 will because it has $\lambda = .9 < 1$ and $\lambda = .3 < 1$.

17 (a)

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 1 & 1 \\ 0 & 0 & 3 & 1 \\ 0 & 0 & 0 & 4 \end{bmatrix}, \quad A - 3I = \begin{bmatrix} -2 & 1 & 1 & 1 \\ 0 & -1 & 1 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Columns 1, 2 and 4 have pivots. Because of the nonzero bottom-right element in A-3I, the fourth component of x_3 is definitely zero.

(b) In the same way as above, the special solutions for the matrices A-1I, A-2I, A-3I, and A-4I must have 3, 2, 1, and 0 zeros as the last components. The eigenvector matrix S is then upper triangular.

18 $A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -11 & 6 \end{bmatrix}$. Notice that 6 = 1 + 2 + 3 (the sum of eigenvalues) and determinant is $6 = 1 \cdot 2 \cdot 3$ (the product of eigenvalues).