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	10 Do	
	Fig. , ALIP	
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•	See if thee are ay this quekar what Q's would be fit me	
	how will / fest with people -> with sophin? better with fout gaze?	
_	The state of the s	
		and of the
	Method START DEBUG	2nd Method START CODE
	START DEBUG	START CODE
		1 7 11 1 1 - 1 -
΄,	Investigate Teuri Linchias on Git page	1. Files for distancing -> how will get between my model \$
	Get face detected from these finitions	-> how I will get between my wooded \$
∠.	See low he gets it and what:	Koloo Hans
	See low he gets it and what: * Inputs he neads	2. billet proofing he code
	* Inputs I can get from Temi	2. Our propos
	11 inports I can get from ICMI	3. look at weights -> Decide if needs re-train
3	Put my learning model onto tensi:	2. Cook at Weights " Decar if hards 18 Than
	* CV 2	4.
	* YOLO	
	,	
	GOAL	
	1. Have Vision system on Temi 2. Have a filter between my code \$ Rotoflow	
	L. Have a fifter between my code \$ holoflow	
	Considerations	
	-> If can't find eyes (glasses, hat, etc)	
	Lis Keep 'My' Model on because Roboflow might not worked	
	2	
	Put in with decision making function (Feltering)	