Project Report for Programming

Group B2

Number Extrapolation

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Members of our group and their duties:

Basso Nick - Technical Lead & Project Manager (main algorithm)

Petranis Ann - Project Reviewer and Manager (report)

Pascaru Stefan-Alin – Developer (Newton's Interpolation algorithm implementation)

Chisnicean Ivan – Tester (analysis of the results)

Corman Daniel – Quality Assurance (final review)

• The task of our project is estimating the 101st number of the set given to us from A groups, using the extrapolation method. We were able to use 3 algorithms: linear, polynomial and conic. Linear extrapolation is to create a tangent line at the end of the known data and to extend it beyond that limit. Polynomial extrapolation is to use Lagrange interpolation or Newton's method of finite differences to create a Newton series that fits the data. Conic extrapolation could be done with a conic sections template, which can be created using five points near the end of the known data. Thus, we decided to implement all this methods to obtain the most exact result.

Algorithm

Our code begins with the declaration of libraries that are necessary for successful compilation and launch. So, we used #include <stdio.h> which stands for "standard input output" header file.

Our program contains 5 functions for the number extrapolation:

```
void linearTwoPointsExtr();
void linearDeltaSumExtr();
void linearDeltaCoefExtr();
void conicSectionExtr();
void polynomLagrExtr();
```

These functions will be invoked next in main function of the program.

Of course, we used global variables int numElem for the number of elements which gave us A groups and float arr[10000 + 5] that represents a float-type array of 10000 + 5 elements for the input.

Our program begins with the data input. All necessary values are stored in the file input.txt.

Next starts first function linearTwoPointsExtr() - linear extrapolation for two last numbers in the array. In this function we used variables: y1 - value of the array element at a lower index (lower index = first point index), longXDelta - difference between index at which value to be extrapolated and first point index, shortXDelta - difference between index at second point and index at first point yDelta - difference between array values at first and second point indices and result - answer given basing on that function value dependency of argument is linear.

After that linearDeltaSumExtr() function is induced. It fulfills linear delta sum extrapolation. For this function work next variables: **delta** - sum of all differences between two consecutive array elements, **averageDelta** - average of all differences between two consecutive array elements, **result** - averageDelta + last array element value.

```
void linearDeltaSumExtr(){
    int i;
    float delta = 0.0, averageDelta, result;

for(i = 1; i < numElem; i++){
        delta += arr[i] - arr[i - 1];
    }

averageDelta = delta / (numElem - 1);

result = arr[numElem - 1] + averageDelta;

printf("Linear delta sum extrapolation result:\t\t\t\t\t\t\\t\\)
}</pre>
```

Then program invokes the function of linear delta coefficient extrapolation (linearDeltaCoefExtr()). In this function are used variables: **delta** - sum of all coefficients that represent, division of current array element on the previous, **averageDelta** - average of all coefficients described in delta, **result** - last array element value multiplied by averageDelta.

```
averageDelta = delta \ / \ (numElem - 1); result = arr[numElem - 1] * averageDelta; printf("Linear delta average multiplication cofficient extrapolation result: \ \%f\n", result); }
```

Next runs conic section extrapolation function conicSectionExtr(). In this function we used following variables: **xt** - stores the sum of all five last x coordinates (which is sum of all array element indices from 1 to number of elements inclusive in this specific task), **yt** - stores the sum of last five numbers given in the input, **xAvg** - average x-coordinate value obtained from the numbers in xt, **yAvg** - average y-coordinate value obtained from the numbers in yt (five last numbers in the input), **result** - multiplication of x and y coordinate averages multiplied by the number of points taken in examination.

```
void conicSectionExtr() {
    float result, xt = 0, yt = 0;
    float yAvg = 0.0, xAvg = 0.0;
    int i;

for(i = numElem - 1; i >= numElem - 5; i--) {
        xt += i + 1;
        yt += arr[i];
    }

xAvg = (numElem + 1) / xt;
    yAvg = yt / 5;

result = yAvg * xAvg * 5;

printf("Conic section extrapolation result:\t\t\t\t\t\t\\t\\\
} % f\n", result);
}
```

Finally, our program calls polynomLagrExtr() function, which means Lagrange polynomial extrapolation. For this function work next variables: \mathbf{x} - point, value at which needs to be extrapolated, \mathbf{k} - Lagrange coefficient obtained by multiplying results between all pairs of x-coordinates where one is obligatory not equal to the other, **result** - equals to the sum of all k-coefficients multiplied by the current y-coordinate value.

```
void polynomLagrExtr(){
//FILE *out1 = fopen("test1.txt", "w");
         float result = 0.0;
         float k;
         float x = numElem + 1;
         int i, j;
         for(j = 0; j < numElem; j++){
                  k = 1;
                   for(i = 0; i < numElem; i++){
                            if(i != j){
                                      k *= (x - (i + 1)) / ((j + 1) - (i + 1));
                                      //fprintf(out1, "%d %d %f %f\n", i + 1, j + 1, x, k);
                   result += arr[j] * k;
         }
         printf("Lagrange extrapolation result:\t\t\t\t\t\t
                                                             %f\n", result);
}
```

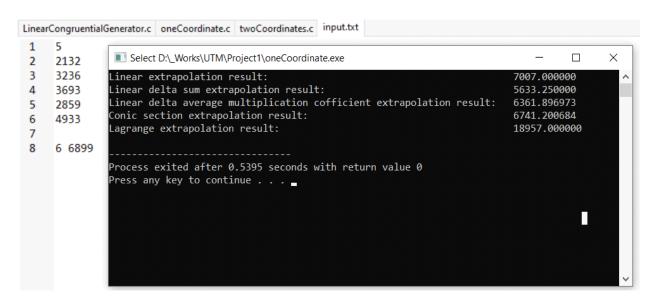
There is also a side task implementation of Newton's interpolation algorithm made by Stefan-Alin Pascaru.

```
void polynomNewtIntr(){
    float p[10000], f=arr[0], f1=1, f2=0;
    int k=numElem-1,i,j=1;
    do
    {
           for (i=0;i<numElem-1;i++)</pre>
                   p[i] = ((arr[i+1]-arr[i])/j);
                   arr[i]=p[i];
           f1=1;
           for(i=0;i<j;i++)</pre>
            {
                   f1*=(k-i+1);
           f2+=(arr[0]*f1);
           numElem--;
            j++;
    }
    while(numElem!=1);
    f+=f2;
    printf("Newton Polynomial result:\t\t\t\t
                                                        %f", f);
```

Results

After all these operations we get 5 results. Each result provided may differ from the others because of different extrapolation algorithms used and inputs generated in various ways. Next image will provide an example of the result which we have received after some tests.

Image 1

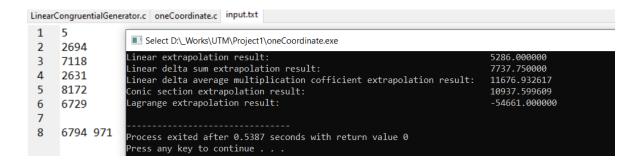


Analysis of the results

In the process of solving the code problem, our team decided to do more tests. From our point of view, it is best to compare more results in order to understand exactly where and which procedures work better than others. As a result, we decided to do 5 tests that helped us in the analysis and the first one have been provided in previous section. Every test have 5 results, because of the 5 algorithms that are used in the Extrapolation method. In the TEST 1 there are 5 pseudorandom numbers that are given to us. The task is to find the next one in the most precisely way. We can see that the real NEXT NUMBER is 6899, but unfortunately we do not have such a number as a result. Nevertheless, we can find the most accurate result available. In this case it is number 7007.000000, which is a result of the linear extrapolation. The worst result is the result of the Lagrange extrapolation algorithm.

The next one is TEST 2. It is very similar to the first one, but the results are different. Next image will provide information about TEST 2.

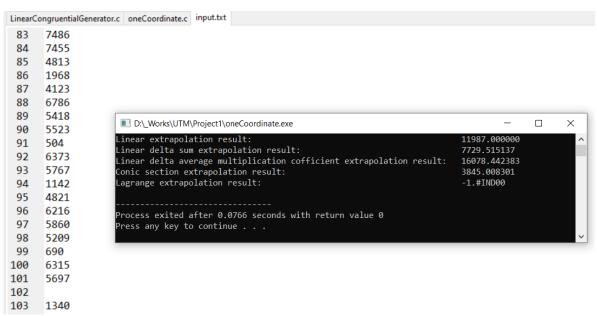
Image 2



In this case the best result is given by the Linear delta sum extrapolation algorithm, still a linear one. In other words, linear extrapolation and its variations work not bad for the small quantity of numbers, just like in the TEST 1 and TEST 2, while Lagrange extrapolation algorithm is the worst.

The TEST 3 is different from TEST 1 and 2, because it is a particular case, in which there are more than 5 pseudo-random numbers. The next image presents the information about TEST 3.

Image 3



The first thing that we observe is the fact than Lagrange result is not at all the one that should be. However we can find the most accurate result. After some

mathematic calculation we can say that Conic section extrapolation result is the best one. Still we need other test to proof or disproof that Conic extrapolation can find the most accurate answer for an example, which contains more numbers.

The TEST 4 is similar to the TEST 3. It looks like this:

Image 4

```
LinearCongruentialGenerator.c oneCoordinate.c input.txt
 83
       5644
       2177
 84
       4604
 85
 86
       7984
       4269
                                                                                                                                        ■ D:\_Works\UTM\Project1\oneCoordinate.exe
 88
       800
                   inear extrapolation result
 89
       4637
                   inear delta sum extrapolation result:
                                                                                             5242.454590
 90
       5199
                  linear delta average multiplication cofficient extrapolation result:
Conic section extrapolation result:
       5710
 91
                   agrange extrapolation result:
                                                                                              -1 #TND00
 92
       4799
 93
       7486
 94
        7790
                   rocess exited after 3.266 seconds with return value 0
 95
                   ress any key to continue .
       1775
 96
       5982
 97
       4959
 98
       7565
 99
       656
100
       4349
101
       5248
102
103
       4524
```

The situation is very interesting, because it is similar to the TEST 3. The best result is given by the Conic section extrapolation algorithm. The difference is only ~170 and that is amazing, because it cannot be accidental. The Lagrange extrapolation result are absolutely not the best one.

The last test, TEST 5 looks like previous two. The next image provides the results of the last test.

Image 5

```
LinearCongruentialGenerator.c oneCoordinate.c input.txt
 83
       1277
 84
       3854
 85
       3919
 86
       7325
 87
       480
                   D:\_Works\UTM\Project1\oneCoordinate.exe
                                                                                                                                       4587
 88
 89
       7346
                   inear delta sum extrapolation result:
                  linear delta average multiplication cofficient extrapolation result:
Conic section extrapolation result:
 90
        3834
 91
       8131
                   agrange extrapolation result:
                                                                                             -1.#TND00
 92
       5064
       2837
 93
 94
       87
 95
                   ress any key to continue \dots
       7846
 96
       5285
 97
       6776
 98
       4276
 99
       7817
100
       5250
101
       2779
102
103
       17
```

TEST 5 is identical in the efficiency of the algorithms with TEST 3 and TEST 4. The Lagrange's result is the same in the last three examples, but the most important thing is the fact that the Conic section extrapolation gives us the best result, again.

Conclusion

In conclusion, our team decided to use the result of the Conic section extrapolation method as the most efficient way to find the next number of a pseudo-random set of numbers, because it gives the best results in the TEST 3, TEST 4 and TEST 5.