1. Modus Ponens relativizado:

$$(\rho \Rightarrow \sigma \Rightarrow \tau) \Rightarrow (\rho \Rightarrow \sigma) \Rightarrow \rho \Rightarrow \tau$$

Llamo $\Gamma = (\rho \Rightarrow \sigma \Rightarrow \tau), (\rho \Rightarrow \sigma)$

2. Reducción al absurdo:

$$(\rho \Rightarrow \bot) \Rightarrow \neg \rho$$

$$\frac{(\rho \Rightarrow \bot), \rho \vdash \rho \Rightarrow \bot}{(\rho \Rightarrow \bot), \rho \vdash \rho} ax \qquad (\rho \Rightarrow \bot), \rho \vdash \rho \Rightarrow_{e}
\frac{(\rho \Rightarrow \bot), \rho \vdash \bot}{(\rho \Rightarrow \bot) \vdash \neg \rho} \neg_{i}
(\rho \Rightarrow \bot) \vdash \neg \rho \Rightarrow_{i}
\vdash (\rho \Rightarrow \bot) \Rightarrow \neg \rho$$

3. Introducción de la doble negación:

$$\rho \Rightarrow \neg \neg \rho$$

$$\frac{\rho, \neg \rho \vdash \rho}{\rho} \xrightarrow{ax} \frac{\rho, \neg \rho \vdash \neg \rho}{\rho, \neg \rho \vdash \bot} \xrightarrow{\neg e} \frac{\rho, \neg \rho \vdash \bot}{\rho \vdash \neg \neg \rho} \Rightarrow_{i}$$

4. Eliminación de la triple negación:

$$\neg\neg\neg\rho\Rightarrow\neg\rho$$

$$\frac{\neg \neg \neg \rho, \rho, \neg \rho \vdash \rho}{\neg \neg \neg \rho, \rho, \neg \rho \vdash \neg \rho} ax \qquad \neg \neg \neg \rho, \rho, \neg \rho \vdash \neg \rho \qquad \neg \neg \neg \rho, \rho \vdash \neg \neg \neg \rho} \neg e$$

$$\frac{\neg \neg \neg \rho, \rho, \neg \rho \vdash \bot}{\neg \neg \neg \rho, \rho \vdash \neg \neg \rho} \neg e$$

$$\frac{\neg \neg \neg \rho, \rho \vdash \bot}{\neg \neg \neg \rho, \rho \vdash \bot} \neg e$$

$$\frac{\neg \neg \neg \rho, \rho \vdash \bot}{\neg \neg \neg \rho \vdash \neg \rho} \neg e$$

$$\frac{\neg \neg \neg \rho, \rho \vdash \bot}{\neg \neg \neg \rho \vdash \neg \rho} \Rightarrow e$$

5. Contraposición:

$$(\rho \Rightarrow \sigma) \Rightarrow (\neg \sigma \Rightarrow \neg \rho)$$

$$\frac{\rho \Rightarrow \sigma, \neg \sigma, \rho \vdash \rho \Rightarrow \sigma}{\rho \Rightarrow \sigma, \neg \sigma, \rho \vdash \sigma} \xrightarrow{ax} \frac{\alpha x}{\rho \Rightarrow \sigma, \neg \sigma, \rho \vdash \rho} \Rightarrow_{e} \frac{\alpha x}{\rho \Rightarrow \sigma, \neg \sigma, \rho \vdash \neg \sigma} \xrightarrow{ax} \frac{\alpha x}{\neg e} \frac{\rho \Rightarrow \sigma, \neg \sigma, \rho \vdash \bot}{\rho \Rightarrow \sigma, \neg \sigma, \rho \vdash \bot} \xrightarrow{\neg i} \Rightarrow_{i} \frac{\rho \Rightarrow \sigma, \neg \sigma \vdash \neg \rho}{\rho \Rightarrow \sigma \vdash \neg \sigma \Rightarrow \neg \rho} \Rightarrow_{i} \vdash (\rho \Rightarrow \sigma) \Rightarrow (\neg \sigma \Rightarrow \neg \rho)$$

6. Adjunción:

$$\begin{array}{l} ((\rho \wedge \sigma) \Rightarrow \tau) \Leftrightarrow (\rho \Rightarrow \sigma \Rightarrow \tau) \\ \text{Direccion:} \Rightarrow \end{array}$$

$$\frac{(\rho \land \sigma) \Rightarrow \tau, \rho, \sigma \vdash (\rho \land \sigma) \Rightarrow \tau}{(\rho \land \sigma) \Rightarrow \tau, \rho, \sigma \vdash \rho} ax \qquad \frac{(\rho \land \sigma) \Rightarrow \tau, \rho, \sigma \vdash \sigma}{(\rho \land \sigma) \Rightarrow \tau, \rho, \sigma \vdash \sigma} \bigwedge_{i} ax \\ \frac{(\rho \land \sigma) \Rightarrow \tau, \rho, \sigma \vdash (\rho \land \sigma)}{(\rho \land \sigma) \Rightarrow \tau, \rho, \sigma \vdash \sigma} \Rightarrow_{i} \\ \frac{(\rho \land \sigma) \Rightarrow \tau, \rho \vdash \sigma \Rightarrow \tau}{(\rho \land \sigma) \Rightarrow \tau \vdash \rho \Rightarrow \sigma \Rightarrow \tau} \Rightarrow_{i} \\ \frac{(\rho \land \sigma) \Rightarrow \tau \vdash \rho \Rightarrow \sigma \Rightarrow \tau}{(\rho \land \sigma) \Rightarrow \tau} \Rightarrow_{i}$$

Direction: \Leftarrow

$$\frac{\frac{\rho, \sigma, \tau, (\rho \land \sigma) \vdash \tau}{\rho, \sigma, \tau \vdash (\rho \land \sigma) \Rightarrow \tau} \Rightarrow_{i}}{\frac{\rho, \sigma, \tau \vdash (\rho \land \sigma) \Rightarrow \tau}{\rho, \sigma \vdash \tau \Rightarrow ((\rho \land \sigma) \Rightarrow \tau)} \Rightarrow_{i}}{\frac{\rho \vdash \sigma \Rightarrow \tau \Rightarrow ((\rho \land \sigma) \Rightarrow \tau)}{\vdash \rho \Rightarrow \sigma \Rightarrow \tau \Rightarrow ((\rho \land \sigma) \Rightarrow \tau)} \Rightarrow_{i}$$

7. de Morgan (I):

$$\neg(\rho \lor \sigma) \Leftrightarrow (\neg \rho \land \neg \sigma)$$
 Direction \Rightarrow

$$\frac{\frac{\overline{\Gamma \vdash \rho} \ ax}{\Gamma \vdash (\rho \lor \sigma)} \lor_{i} 1 \qquad \frac{\overline{\Delta} \vdash \sigma}{\Gamma \vdash \neg (\rho \lor \sigma)} \overset{ax}{\neg e} \qquad \frac{\frac{\overline{\Delta} \vdash \sigma}{\Delta \vdash (\rho \lor \sigma)} \lor_{i} 2 \qquad \frac{\overline{\Delta} \vdash \neg (\rho \lor \sigma)}{\overline{\Delta} \vdash \neg (\rho \lor \sigma)} \overset{ax}{\neg e}}{\frac{\overline{\Delta} \vdash \bot}{\neg (\rho \lor \sigma) \vdash \neg \rho} \overset{\neg e}{\neg e}} \overset{\neg (\rho \lor \sigma) \vdash \neg \rho \land \neg \sigma}{\vdash \neg (\rho \lor \sigma) \Rightarrow (\neg \rho \land \neg \sigma)} \Rightarrow_{i}$$

$$\Gamma = {\neg(\rho \lor \sigma), \rho} \ y \ \Delta = {\neg(\rho \lor \sigma), \sigma}$$

 $\mathrm{Direccion} \Leftarrow$

$$\frac{ \frac{\Gamma, \sigma \vdash \neg \rho \land \neg \sigma}{\Gamma, \sigma \vdash \neg \rho} ax \qquad \frac{\overline{\Gamma, \sigma \vdash \neg \rho \land \neg \sigma}}{\Gamma, \sigma \vdash \neg \sigma} \land_{e} 2}{\frac{\Gamma, \sigma \vdash \bot}{\Gamma, \sigma \vdash \neg \sigma} \land_{e} 2} \qquad \frac{\Gamma, \sigma \vdash \bot}{\Gamma, \sigma \vdash \rho} \land_{e} 1$$

$$\frac{\Gamma \vdash \rho}{\Gamma \vdash \neg \rho} \Rightarrow_{e} 1$$

$$\frac{\Gamma \vdash \bot}{\neg \rho \land \neg \sigma \vdash \neg (\rho \lor \sigma)} \Rightarrow_{i}$$

$$\Gamma = \{ (\neg \rho \land \neg \sigma), \neg (\rho \lor \sigma) \}$$

8. De Morgan II:

$$\neg(\rho \land \sigma) \Leftrightarrow \neg\rho \lor \neg\sigma$$
 Direction \Rightarrow

$$\frac{\frac{\overline{\Gamma_{2} \vdash \neg \sigma}}{\Gamma_{1} \vdash \Delta_{0}} \stackrel{ax}{\vee_{i_{2}}} \frac{\overline{\Gamma_{1} \vdash \Delta}}{\overline{\Gamma_{1} \vdash \Delta}} \stackrel{ax}{\neg_{e}}}{\frac{\overline{\Gamma_{2} \vdash \Delta_{0}}}{\overline{\Gamma_{1} \vdash \Delta}} \stackrel{pbc}{\wedge_{i}} \frac{\overline{\Gamma_{1} \vdash \Delta}}{\overline{\Gamma_{1} \vdash \sigma}} \stackrel{pbc}{\wedge_{i}} \frac{\overline{\Gamma_{1} \vdash \sigma}}{\overline{\Gamma_{1} \vdash \sigma}} \stackrel{pbc}{\wedge_{e}} \frac{\overline{\Gamma_{1} \vdash \sigma}}{\overline{\Gamma_{1} \vdash \sigma}} \stackrel{pbc}{\neg_{e}} \frac{\overline{\Gamma_{1} \vdash \Delta}}{\overline{\Gamma_{1} \vdash \sigma}} \stackrel{pbc}{\neg_{e}} \overline{\Gamma_{1} \vdash \sigma} \stackrel{pbc}{\neg_{e}} \stackrel{pbc}{\neg_{e}} \overline{\Gamma_{1} \vdash \sigma} \stackrel{pbc}{\neg_{e}} \stackrel{pbc}{\neg_{e$$

$$\Gamma = \{\neg(\rho \land \sigma), \neg(\neg \rho \lor \neg \sigma)\}$$

$$\Gamma_0 = \{\neg(\rho \land \sigma), \neg(\neg \rho \lor \neg \sigma), \neg \rho\}$$

$$\Gamma_1 = \{\neg(\rho \land \sigma), \neg(\neg \rho \lor \neg \sigma), \rho\}$$

$$\Gamma_2 = \{\neg(\rho \land \sigma), \neg(\neg \rho \lor \neg \sigma), \rho, \neg \sigma\}$$

$$\Delta = \neg(\neg \rho \lor \neg \sigma)$$

$$\Delta_0 = \neg \rho \vee \neg \sigma$$

Direction \Leftarrow

$$\begin{array}{c|c} \text{Direction} \Leftarrow \\ \hline \frac{\Gamma_{2}, \rho \vdash \rho \land \sigma}{\Gamma_{2}, \rho \vdash \sigma} \wedge_{2} & \frac{ax}{\Gamma_{2}, \rho \vdash \neg \sigma} & ax \\ \hline \frac{\Gamma \vdash \rho \land \sigma}{\Gamma \vdash \rho} \wedge_{1} & \frac{ax}{\Gamma_{1} \vdash \neg \rho} & ax & \frac{\Gamma_{2}, \rho \vdash \bot}{\Gamma_{2} \vdash \neg \rho} \wedge_{e} \\ \hline \frac{\Gamma \vdash \bot}{\Gamma \vdash \neg \rho \lor \neg \sigma} \wedge_{1} & \frac{\Gamma \vdash \bot}{\Gamma \vdash \neg \rho \lor \neg \sigma} \wedge_{e} \\ \hline \Gamma_{1} = \{ \neg \rho \lor \neg \sigma, \rho \land \sigma \} \\ \Gamma_{1} = \{ \neg \rho \lor \neg \sigma, \rho \land \sigma, \neg \rho \} \\ \Gamma_{2} = \{ \neg \rho \lor \neg \sigma, \rho \land \sigma, \neg \sigma \} \\ \Delta = \{ \neg \rho \lor \neg \sigma \} \end{array}$$

9. Conmutatividad (\wedge):

$$(\rho \wedge \sigma) \Rightarrow (\sigma \wedge \rho)$$

$$\frac{ \overline{\rho \wedge \sigma \vdash \rho \wedge \sigma} \overset{ax}{\wedge_{e_2}} \quad \overline{\rho \wedge \sigma \vdash \rho \wedge \sigma} \overset{ax}{\wedge_{e_1}} \\ \overline{\rho \wedge \sigma \vdash \sigma} \overset{\wedge}{\wedge_{e_2}} \quad \overline{\rho \wedge \sigma \vdash \rho} \overset{\wedge}{\wedge_{e_1}} \\ \overline{\rho \wedge \sigma \vdash \sigma \wedge \rho} \Rightarrow_i$$

10. Asociatividad (\wedge):

$$((\rho \wedge \sigma) \wedge \tau) \Leftrightarrow (\rho \wedge (\sigma \wedge \tau))$$
 Direction \Rightarrow

$$\frac{\frac{\Gamma \vdash (\rho \land \sigma) \land \tau}{\Gamma \vdash \rho \land \sigma} \land_{i_{1}}}{\frac{\Gamma \vdash \rho \land \sigma}{\Gamma \vdash \rho} \land_{i_{1}}} \frac{ax}{\frac{\Gamma \vdash \rho \land \sigma}{\Gamma \vdash \sigma} \land_{i_{2}}} \frac{\Gamma \vdash (\rho \land \sigma) \land \tau}{\Gamma \vdash \sigma \land \tau} \land_{i_{2}}}{\frac{\Gamma \vdash \sigma \land \tau}{\Gamma \vdash \sigma \land \tau} \land_{e}} \land_{i_{2}} \frac{ax}{} \land_{i_{2}}$$

$$\Gamma = (\rho \wedge \sigma) \wedge \tau$$

Direction \Leftarrow

$$\frac{\frac{\Gamma \vdash \rho \land (\sigma \land \tau)}{\Gamma \vdash \rho} \alpha x}{\frac{\Gamma \vdash \rho \land (\sigma \land \tau)}{\land_{i_{1}}} \land_{i_{2}}} \xrightarrow{\frac{\Gamma \vdash \sigma \land \tau}{\Gamma \vdash \sigma} \land_{i_{1}}} \frac{\alpha x}{\frac{\Gamma \vdash \rho \land (\sigma \land \tau)}{\Gamma \vdash \tau} \land_{i_{2}}} \land_{i_{2}}} \frac{\alpha x}{\frac{\Gamma \vdash \rho \land (\sigma \land \tau)}{\Gamma \vdash \tau} \land_{i_{2}}} \land_{i_{2}}} \frac{\Gamma \vdash \rho \land (\sigma \land \tau)}{\frac{\Gamma \vdash (\rho \land \sigma) \land \tau}{\vdash \rho \land (\sigma \land \tau)} \Rightarrow (\rho \land \sigma) \land \tau}}$$

$$\Gamma = \rho \wedge (\sigma \wedge \tau)$$