

a) Want to show core tensor C_j can be estimated as

$$\hat{C}_j = R_j \times_1 (Z_j^T Z_j)^{-1} Z_j^T \times_2 V_1^T \times_3 V_2^T \dots \times_{d+1} V_d^T$$

$$\arg \min_c \|R_{j(n)} - X_{j(n)} \beta_j\|_F \quad \text{use } \text{vec}(x) \quad Z_j = X_{j(n)} (U_{j,1} \otimes U_{j,2} \otimes \dots \otimes U_{j,1})$$

$$= \arg \min \| \text{vec}(R_{j(n)}) - \text{vec}(X_{j(n)} \beta_j) \|_2 \quad R_j = Y - \sum_{i \neq j} \beta_i \star X_i$$

plug in β_j

$$= \arg \min \| \text{vec}(R_{j(n)}) - \text{vec}(X_{j(n)} (U_{j,1} \otimes U_{j,2} \otimes \dots \otimes U_{j,1}) C_j (V_d \otimes \dots \otimes V_1)^T) \|_2^2$$

use def of Z_j

↑ swap + transpose

$$= \arg \min \| \text{vec}(R_{j(n)}) - \text{vec}(Z_j C_j (V_d \otimes \dots \otimes V_1)^T) \|_2^2$$

lastly, use $\text{vec}(ABC^T) = (C \otimes A) \text{vec}(B)$

$$= \arg \min \| \text{vec}(R_{j(n)}) - (V_d \otimes \dots \otimes V_1 \otimes Z_j) \text{vec}(C_j) \|_2^2$$

✓

Now, optimal soln when

$$\text{vec}(R_{j(n)}) = (V_d \otimes \dots \otimes V_1 \otimes Z_j) \text{vec}(C_j)$$

$$\text{vec}(C_j) = (V_d \otimes \dots \otimes V_1 \otimes Z_j)^{-1} \text{vec}(R_{j(n)})$$

$$\text{use 1. } (A \otimes B)^{-1} = A^{-1} \otimes B^{-1}$$

$$\text{vec}(C_j) =$$

$$2. AB^{-1} = B^{-1}A^{-1}$$

$$3. V_i^T V_i = I_{\hat{d}_i}$$

$$V_d^T \otimes V_{d-1}^T \dots \otimes V_1^T (Z_j^T Z_j)^{-1} Z_j^T \text{vec}(R_{j(n)})$$

$$\text{Now invoke } (A \otimes B)(C \otimes D) = (A \star C) \otimes (B \star D)$$

$$C_j = R_j \times_1 (Z_j^T Z_j)^{-1} Z_j \times_2 V_1^T \times_3 \dots \quad \checkmark$$

b) Tucker decomp

$$X \approx G \times_1 A \times_2 B \times_3 C = \sum_{p=1}^P \sum_{q=1}^Q \sum_{r=1}^R g_{pqr} a_p \circ b_q \circ c_r = \llbracket G; A, B, C \rrbracket$$

from online proof we can say X is 3 way tensor $\in \mathbb{R}^{I \times J \times K}$

$$\begin{aligned} \text{so } &= \sum_{p=1}^P \sum_{q=1}^Q \sum_{r=1}^R g_{pqr} a_p b_q c_r \quad \text{pull out 1 summation} \\ &= \sum_{p=1}^P \left(\sum_{q \neq p}^Q \sum_{r=1}^R g_{pqr} a_p b_q c_r + \sum_{r=1}^R g_{ppr} a_p b_p c_r \right) \end{aligned}$$

G is super diagonal

$$\begin{aligned} &= \sum_{p=1}^P \sum_{r=1}^R g_{ppr} a_p b_p c_r \quad \text{do same for } R \\ &= \sum_{p=1}^P \left(\sum_{r \neq p}^R g_{ppr} a_p b_p c_r + g_{ppp} a_p b_p c_p \right) \end{aligned}$$

G is superdiag

$$= \sum_{p=1}^P a_p b_p c_p \quad \text{so if } P=Q=R \text{ \& } G \text{ is super diag } \checkmark$$