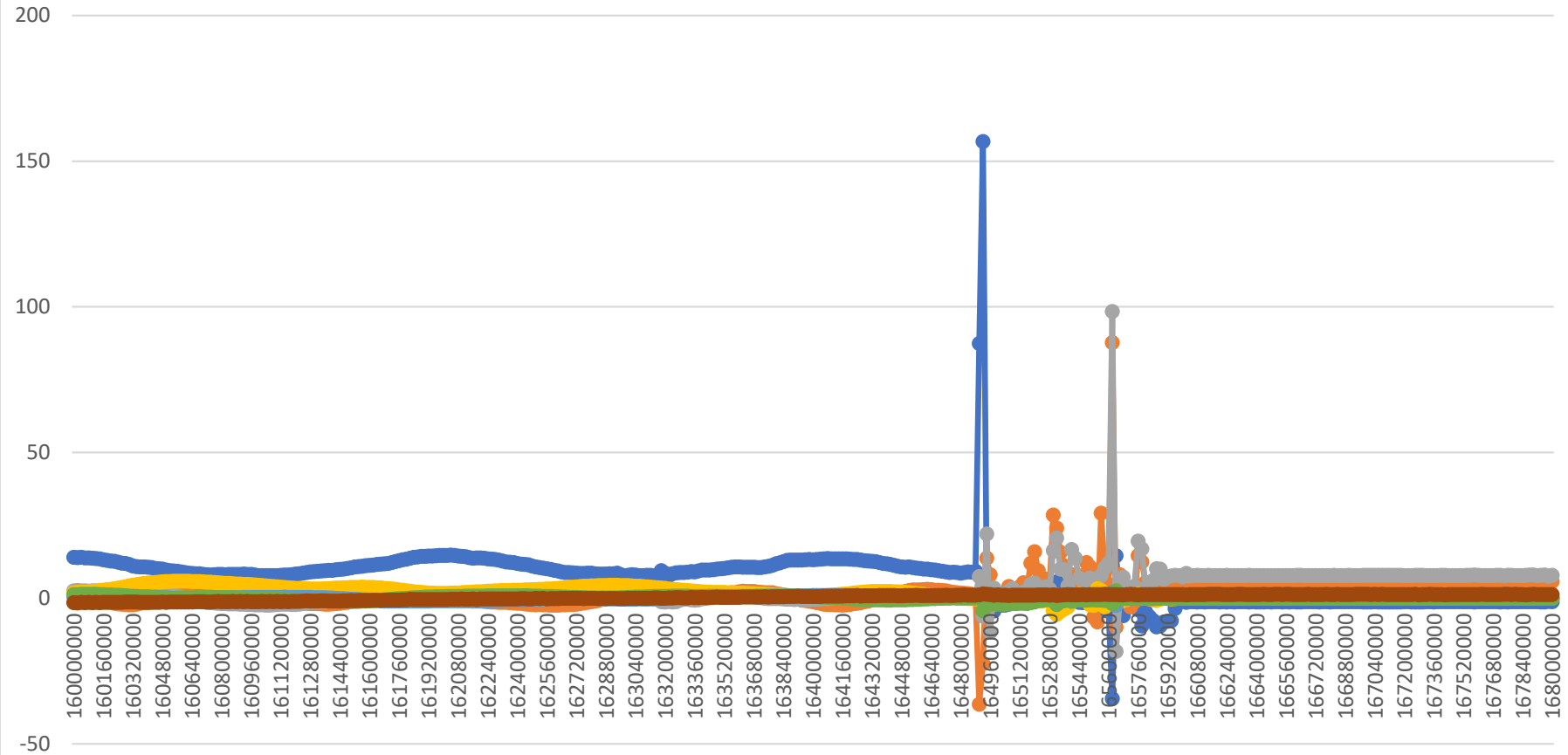


Landing



acc_x acc_y acc_z gyro_x gyro_y gyro_z Norm_baro