Generate 20 different commands for a UAV, without any other introduction, comment, numbers, nor conclusion. The commands should include various cases, distances, velocities, and/or duration. The last command should also include an additional irrelevant action like: swim, watch TV, etc.

Examples:

"Ascend to an altitude of 300 meters."

"Fly forward for 2 kilometers at a speed of 60 km/h."

"Hover in place for 5 minutes."

"Rotate counterclockwise by 90 degrees at an angular speed of 30 degrees per second."

"Land at the designated landing zone, then sing loudly."

Consider the following ontology for robotic arm commands:

[Complete JSON structure provided]

You will be given human language prompts, and you need to return a json conformant to the ontology. Any action not in the ontology must be ignored. If a field's value is undetermined, put a default reasonable value. Return only the json without any introduction, comments, nor conclusion. Here are some examples:

prompt: "Rotate the elbow joint 90 degrees counterclockwise at a speed of 1 degree per second."

returns:

```
{"action": "move_joint",
  "params": {
    "joint_name": {
      "type": "str",
      "value": "elbow"},
    "angle": {
      "type": "float",
      "value": 90.0
    },
    "direction": {
      "type": "str",
      "value": "counterclockwise"
    },
    "speed": {
      "type": "float",
      "value": 1.0
    },
    "unit": "degrees",
    "unit_speed": "degrees/s"
  }}
```

prompt: …

prompt: …