## Assignment Unit 5

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## May 2024

- 1. Prove the Big-O complexity for Human Sort as described in the tutorial.
- 2. Indicate, for each pair of expressions (A, B) in the table below, whether A is  $O, \Omega$ , or  $\Theta$ , of B. Assume all logarithms have base 2.
- a.  $A = \log(n!), B = \log(n^n)$
- b.  $A = 400n^{-3} + \sqrt{n} + \pi, B = 1 + \sin \frac{n}{\pi}$
- c.  $A = \log(n)^{\log(n)}, B = 4^{\log(n)}$
- d.  $A = 2^n, B = n!$
- e.  $A = n^{-5099}, B = \frac{1}{5099} \log n$
- 3. Suppose the function  $G: N \to N$  is defined recursively by setting G(0) = 0 and  $G(n) = 1 + G(\lfloor n/2 \rfloor)$  for every positive integer n. Prove that for all  $n \in \mathbb{N}$ , we have  $G(n) = 1 + \lfloor \log_2 n \rfloor$ .

Hint: If you are struggling with the inductive step, try splitting the problem into even and odd cases.

4. Write three programs that calculate the *n*th prime number: one iterative (runs without calling itself and without tables), one using recursion, and one using dynamic programming.

Write a proof that your three algorithms are correct using the guidelines in the documents. Also give a tight Big-O bound for your algorithm and quickly discuss why it's correct.

You can use the Sieve of Eratosthenes as your prime-finding algorithm:

https://en.wikipedia.org/wiki/Sieve\_of\_Eratosthenes

For your proof, you may need the fact that every finite number has a prime factorization - that is, it can be factored into a product of a finite number of primes.

5. Consider a weighted graph G with V vertices and E edges, and suppose all edge weights are nonnegative. Prove using induction that the following algorithm can find the shortest path from a vertex "source" to any other vertex of the graph.

```
function Dijkstra(Graph, source):
 create vertex priority queue Q
 dist[source] \leftarrow 0
 add source to Q
 for each vertex v in Graph. Vertices:
     dist[v] \leftarrow INFINITY
     prev[v] \leftarrow UNDEFINED
     add v to Q
 dist[source] \leftarrow 0
 while Q is not empty:
     u \leftarrow vertex in Q with minimum dist[u]
     remove u from Q
     for each neighbor v of u still in Q:
          alt \leftarrow dist[u] + Graph.Edges(u, v)
          if alt < dist[v]:
               dist[v] \leftarrow alt
               prev[v] \leftarrow u
return dist, prev
```

Also use Big-O notation to find the time and space complexity of the algorithm in terms of V and E. A short explanation will suffice.

6. Find a recurrence relation for the auxilliary space S(n) used by mergesort on an array n. Use the recurrence to prove that the space complexity of merge sort is  $\theta(n)$ 

Hint: After looking at the code, you might be tempted to think S(n) satisfies the same recurrence as T(n) from the tutorial. However, there is a slight difference that changes the space complexity.