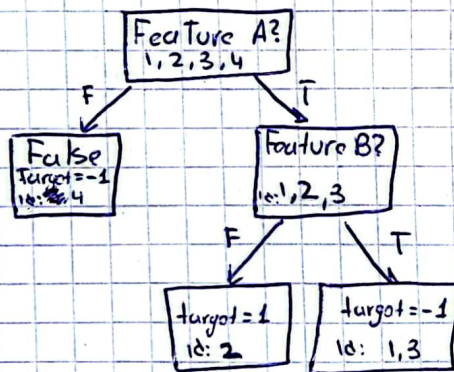


1.1)

Attribute	$\frac{ V_a=T }{ V }$	$\frac{ V_a=F }{ V }$	$H(V_a=T)$	$H(V_a=F)$	$IG(V,a) - H(V)$
Feature A Feature A	$\frac{3}{4}$	$\frac{1}{4}$	$H(\frac{2}{3})$	$H(\frac{0}{1})$	$-\frac{3}{4}H(\frac{2}{3}) - \frac{1}{4}H(\frac{0}{1}) = -0.689$
Feature B Feature B	$\frac{2}{4}$	$\frac{2}{4}$	$H(\frac{1}{2})$	$H(\frac{1}{2})$	$-\frac{2}{4}H(\frac{1}{2}) - \frac{2}{4}H(\frac{1}{2}) = -1$
Feature C Feature C	$\frac{2}{4}$	$\frac{2}{4}$	$H(\frac{1}{2})$	$H(\frac{1}{2})$	$-\frac{2}{4}H(\frac{1}{2}) - \frac{2}{4}H(\frac{1}{2}) = -1$

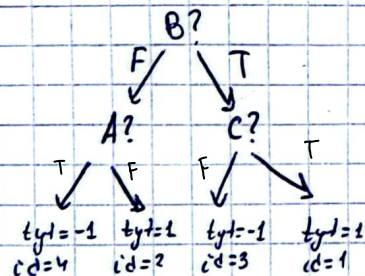
"T" = 1
"F" = 0



Attribute	$\frac{ V_a=T }{ V }$	$\frac{ V_a=F }{ V }$	$H(V_a=T)$	$H(V_a=F)$	$IG(V,a) - H(V)$
Feature B	$\frac{2}{3}$	$\frac{1}{3}$	$H(\frac{1}{2})$	$H(\frac{1}{2})$	$-\frac{2}{3}(H(\frac{1}{2})) - \frac{1}{3}(H(\frac{1}{2})) = -\frac{2}{3}$
Feature C	$\frac{1}{3}$	$\frac{2}{3}$	$H(\frac{1}{3})$	$H(\frac{2}{3})$	$-\frac{1}{3}H(\frac{1}{3}) - \frac{2}{3}H(\frac{2}{3}) = -\frac{2}{3}$
Feature B or C	$\frac{1}{3}$	$\frac{2}{3}$	$H(\frac{1}{3})$	$H(\frac{2}{3})$	$-\frac{1}{3}H(\frac{1}{3}) - \frac{2}{3}H(\frac{2}{3}) = -\frac{2}{3}$

הסיכויים כי רק id=1 מופיעים לא נכון. אולי יש משהו של 25% $(\frac{1}{4})$

1.2)



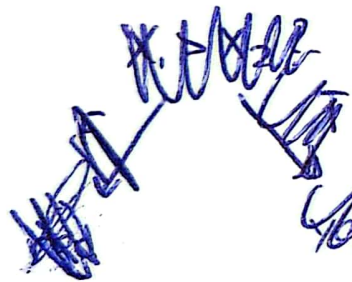
2.1

$$h(x_1, x_2) = \text{Sign}(x_1 - x_2) = \text{Sign}\left(\begin{pmatrix} 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + 0\right)$$

(pink) $x_1 < x_2$ -1 (yellow) $x_1 > x_2$ 1 (blue) $x_1 = x_2$ 0

red = -1

yellow = 1

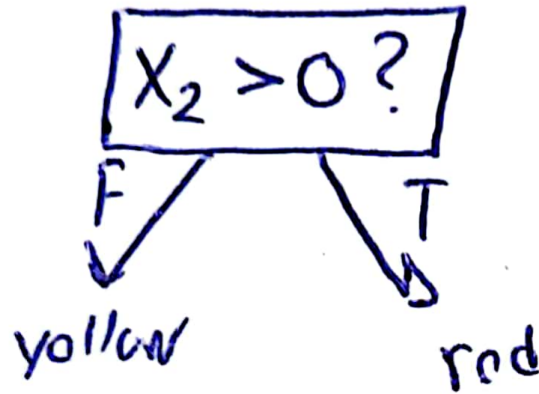


2.2) there's no way to ~~have~~ solve the problem with a depth 1 decision tree because we can only draw lines that are parallel to the x axis or y axis (one line)

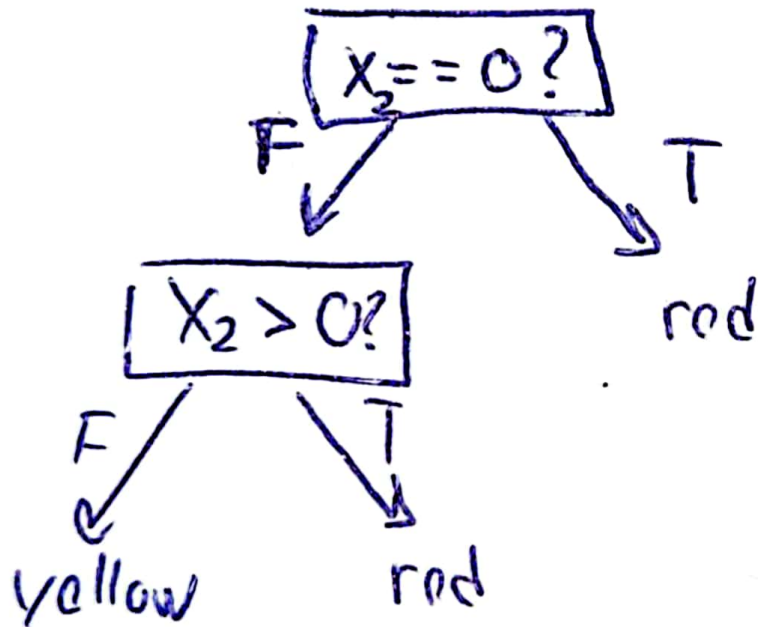
2.3) ~~same reason~~ same answer with the same reason except this time we have a depth of 2 which still isn't enough (2 lines)

2.4.1. $h(x_1, x_2) = \text{Sign}(-x_2) = \text{Sign}((0, -1) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + 0)$

2.4.2.



2.4.3.



3.1. the problem with the 'proof' is that it didn't contradict anything:
 having both $\text{Entropy}(D)$ and $\text{Entropy}(D_v)$ be non-negative does NOT
 contradict the assumption that $\text{IG}(A) < 0$ because

$$\underbrace{\text{Entropy}(D)}_I < \underbrace{\sum \left(\frac{|D_v|}{|D|} \text{Entropy}(D_v) \right)}_{II}$$
 and the subtraction
 of II from I will be negative ($\text{IG}(A) < 0$ still).

3.2. $\text{IG}(v, a) = H(v) - \frac{|V_{a=T}|}{|V|} H(V_{a=T}) - \frac{|V_{a=F}|}{|V|} H(V_{a=F}) =$

$$= H(v) - \underbrace{\frac{|V_{a=T}|}{|V|}}_{\alpha} H \left(\underbrace{\frac{|\{(x,y) \in V_{a=T} | y=1\}|}{|V_{a=T}|}}_{\beta_1} \right) - \underbrace{\frac{|V_{a=F}|}{|V|}}_{1-\alpha} H \left(\underbrace{\frac{|\{(x,y) \in V_{a=F} | y=1\}|}{|V_{a=F}|}}_{\beta_2} \right) =$$

Handwritten note: α is the fraction of V with $a=T$ and $y=1$.

$$\stackrel{||}{=} H(v) - \alpha H(\beta_1) - (1-\alpha) H(\beta_2) \geq H(v) - H(\alpha \beta_1 + (1-\alpha) \beta_2) =$$

$$= H(v) - H \left(\frac{|V_{a=T}|}{|V|} \frac{|\{(x,y) \in V_{a=T} | y=1\}|}{|V_{a=T}|} + \frac{|V_{a=F}|}{|V|} \frac{|\{(x,y) \in V_{a=F} | y=1\}|}{|V_{a=F}|} \right) =$$

Handwritten note: $\frac{|V_{a=T}|}{|V|} \frac{|\{(x,y) \in V_{a=T} | y=1\}|}{|V_{a=T}|}$ is the fraction of V with $a=T$ and $y=1$.

$$= H(v) - H \left(\frac{|\{(x,y) \in V_{a=T} | y=1\}| + |\{(x,y) \in V_{a=F} | y=1\}|}{|V|} \right) = H(v) - H(v) = 0$$

In conclusion; $\text{IG}(v, a) \geq 0$

4.1 Both ~~not~~ 'w' and 'b' can be scaled by the same positive constant λ without affecting the classifier's decision rule, thus having ~~the~~ ^{same} ~~bigger~~ degree of "freedom" ~~than~~ ^{as} a homogeneous classifier.

4.2 A is b_1 ; B is b_4 ; C is b_2 ; D is b_3

5.1

M/D	A	B
i	No, because the (0,0) dot will be classified as blue instead of red	No, because the (0,0) dot will be classified as red instead of blue
ii	No, will not classify all dots as blue because since the majority (2 out of 3) are always blue	yes
iii	yes no	No, because the (0,0) will be classified as red instead of blue

5.2

M/D	A	B
i	unchanged because rotation doesn't change the values of the 2 nd norm	U
ii	U	U
iii	rotated by 45° and the answer changes s.t the dot in the middle will be classified as blue instead of red	might change for a 45° , everything including the middle dot will be classified correctly