

THEORY OF COMPILATION

LECTURE 11

~~COMPLICATED~~

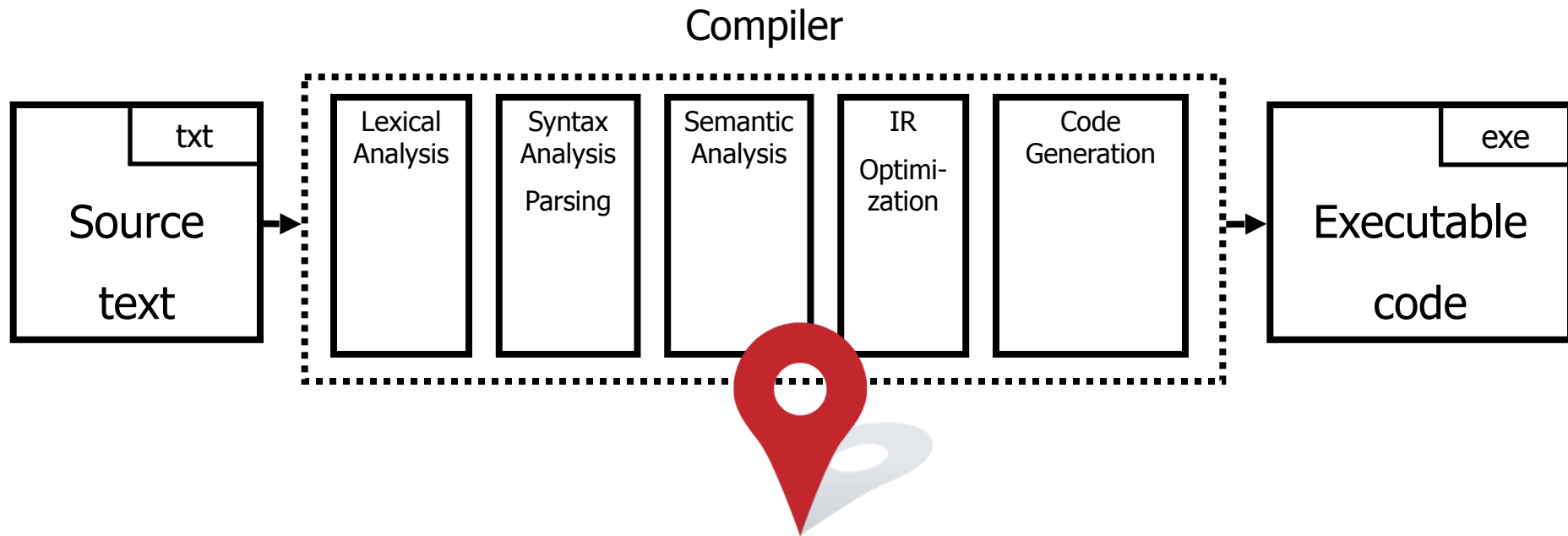
STATIC

ANALYSIS

Totally Awesome



You are here



Plan for Today

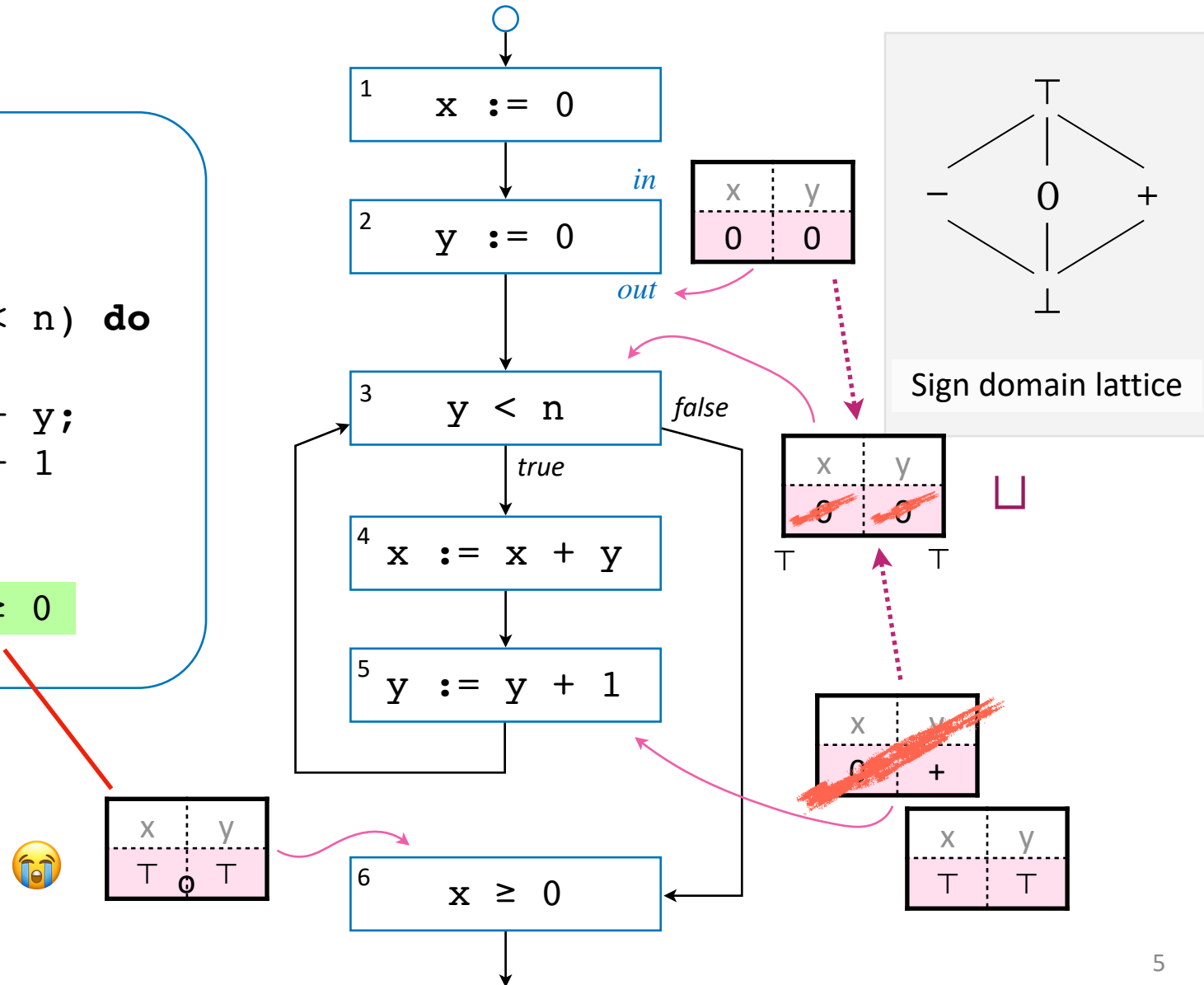
- Refresh our memory of Data Flow Analysis
- Another example: pointer analysis
- Combining domains

Data Flow Analysis (ugh, again?!)

```
1: x := 0;  
2: y := 0;  
  
3: while (y < n) do  
  (  
4:   x := x + y;  
5:   y := y + 1  
  )  
  
6: z := sqrt(x)
```

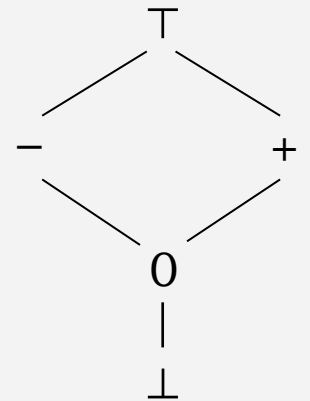
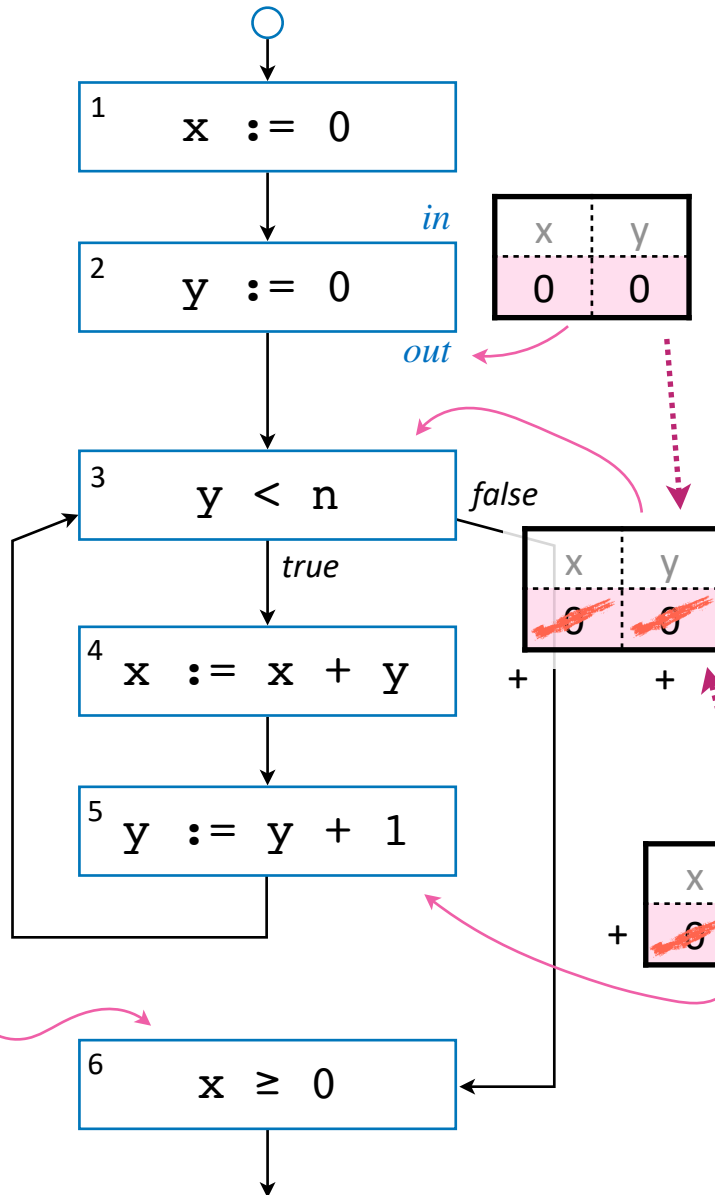
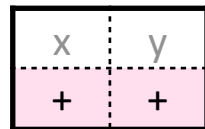
Data Flow Analysis (ugh, again?!)

```
1: x := 0;
2: y := 0;
3: while (y < n) do
4:     x := x + y;
5:     y := y + 1
6: assert x ≥ 0
```



Data Flow Analysis (ugh, again?!)

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  )  
  
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```

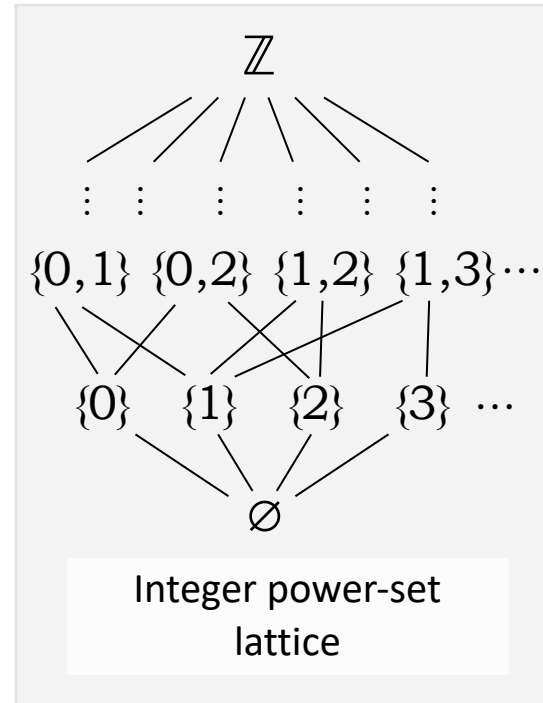
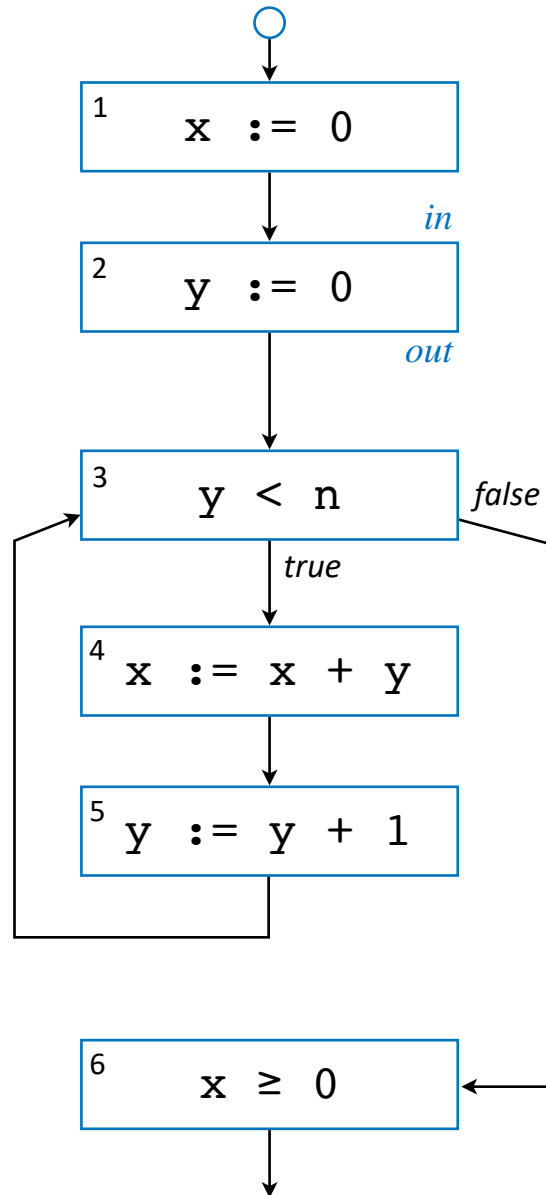


Sign domain lattice

+ means ≥ 0
- means ≤ 0

Data Flow Analysis (ugh, again?!)

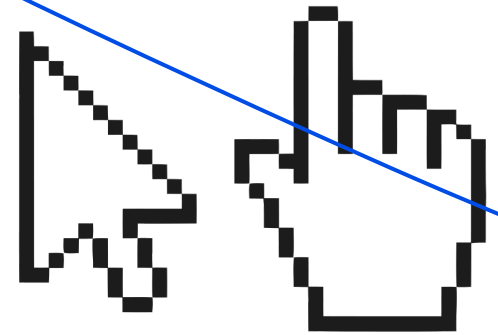
```
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```



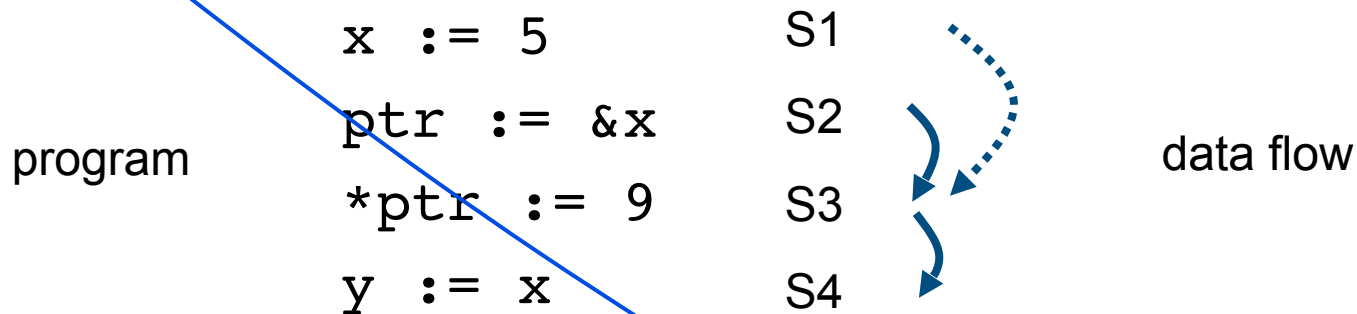
$$L = \langle \mathcal{P}(\mathbb{Z}), \subseteq \rangle$$

$$a \sqcup b = \hat{a} \cup b$$

Pointer Analysis



Simple Example



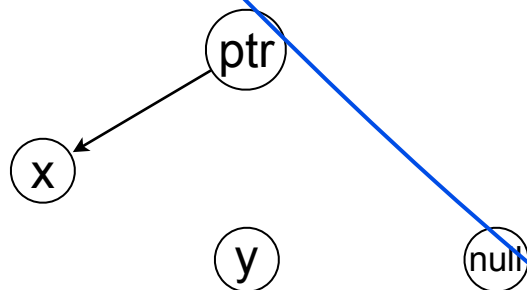
- What are the data dependencies in this program?
- Problem: just looking at variable names will not give you the correct information
 - ▶ After statement S2, program names “x” and “*ptr” are both expressions that refer to the same memory location.
 - ▶ We say that *ptr points-to x* after statement S2.
- In a C-like language that has pointers, we must know the *points-to relation* to be able to determine dependencies correctly

Program Model

- The programming language/IR has instructions that deal with pointers:
 - ▶ address: $x := \&y$
 - ▶ copy: $x := y$ (regular assignment)
 - ▶ load: $x := *y$
 - ▶ store: $*x := y$
- For now: no heap, no function calls. Allowed types are \mathbb{Z} , \mathbb{Z}^* (pointer to number), \mathbb{Z}^{**} , ...

Points-to Relation

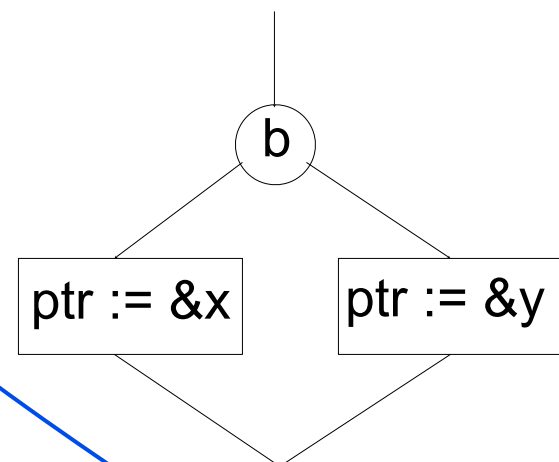
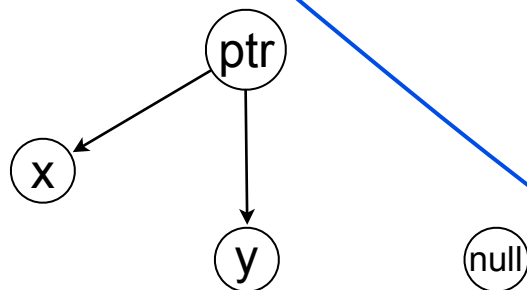
- Directed graph:
 - ▶ Nodes are program variables (+ special node for null)
 - ▶ Edge (a,b) — variable a points-to variable b



- Of course, points-to is different at different program locations

Points-to Relation

- Directed graph:
 - ▶ Nodes are program variables (+ special node for null)
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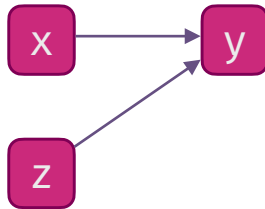


- Out-degree may be > 1
if there are multiple paths

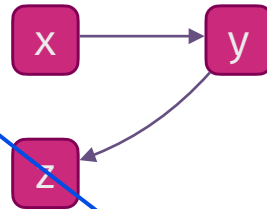
What does x
point to here?

Points-to Relation

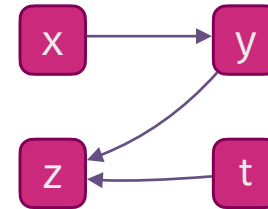
$x := \&y$
 $z := \&y$



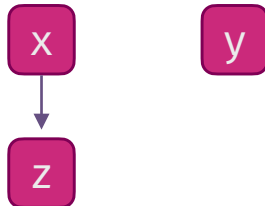
$x := \&y$
 $y := \&z$



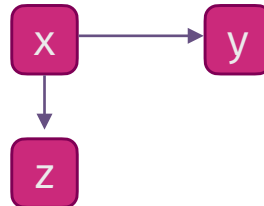
$x := \&y$
 $t := \&z$
 $*x := t$



$x := \&y$
 $x := \&z$



if (...)
 $x := \&y$
else
 $x := \&z$



Points-to Relation

- As an abstract domain (a lattice):
 - ▶ Nodes are fixed per program
 - ◇ can think of it as a power-set domain of possible edges
 - ▶ \perp is a graph with no edges
 - ▶ \sqsubseteq is the subgraph relation (edge subset)
 - ▶ \sqcup is obtain by union of edges

$$\text{pt}(u) = \{v \mid (u,v) \in E\}$$

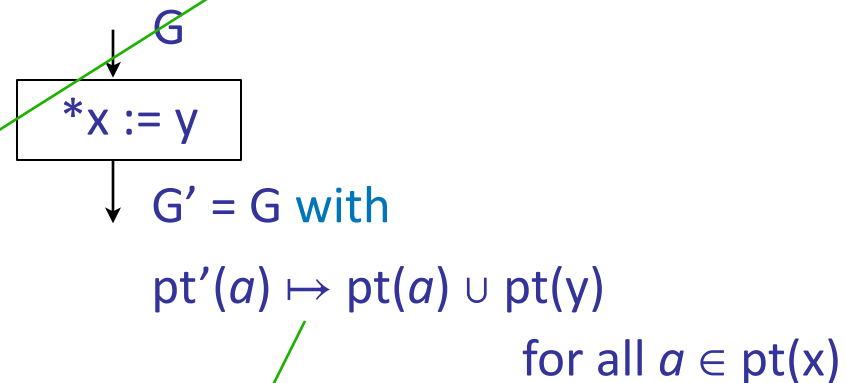
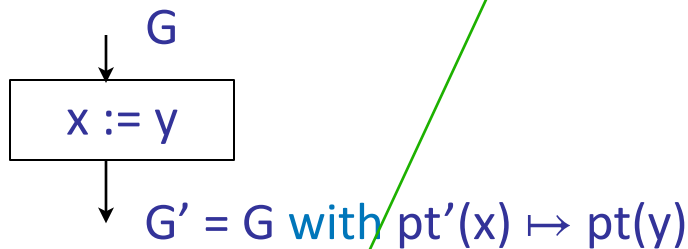
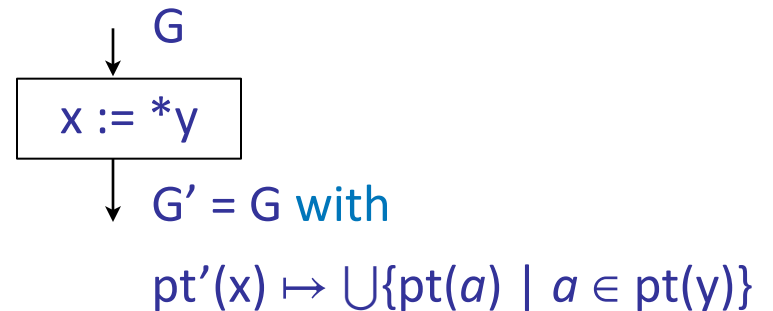
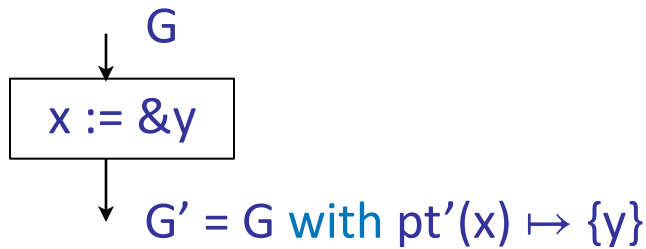
Points-to Analysis: Two Flavors

- Flow Sensitive (we'll be doing this)
 - ▶ Based on abstract interpretation / dataflow
 - ▶ Can examine behavior at different locations
- Flow Insensitive (we won't be doing this)
 - ▶ Computes a single points-to relation for the entire program
 - ▶ Works by generating constraints and solving them
 - ▶ (Andersen's algorithm / Steengards algorithm)

Points-to: Abstract Semantics

in = G , out = G'

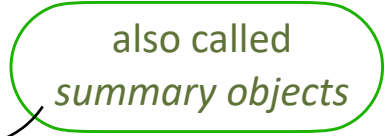
$pt(u) = \{v \mid (u,v) \in E\}$



strong updates

weak update (why?)

Dynamic Allocation

- What to do with $x := \text{new } Z[\dots]$?
 - Program can create an unbounded number of objects
 - Need some static naming scheme for dynamically allocated objects
- AbsObj — set of *abstract objects* 

Single name for the entire heap $\text{AbsObj} = \{ H \}$

Type-based

$$\text{AbsObj} = \{ H_T \mid T \text{ is a type in the program} \}$$

Allocation-site based

$$\text{AbsObj} = \{ H_\ell \mid \ell \in \text{Lab s.t. } \ell : p := \text{new } T \}$$

Dynamic Allocation: Semantics

- Basically: model every “new” as “address of”

```
1: p := new Z[5];  
2: q := new Z[5];  
3: if (p = q) then  
4:     z := p  
5: else  
6:     z := q
```



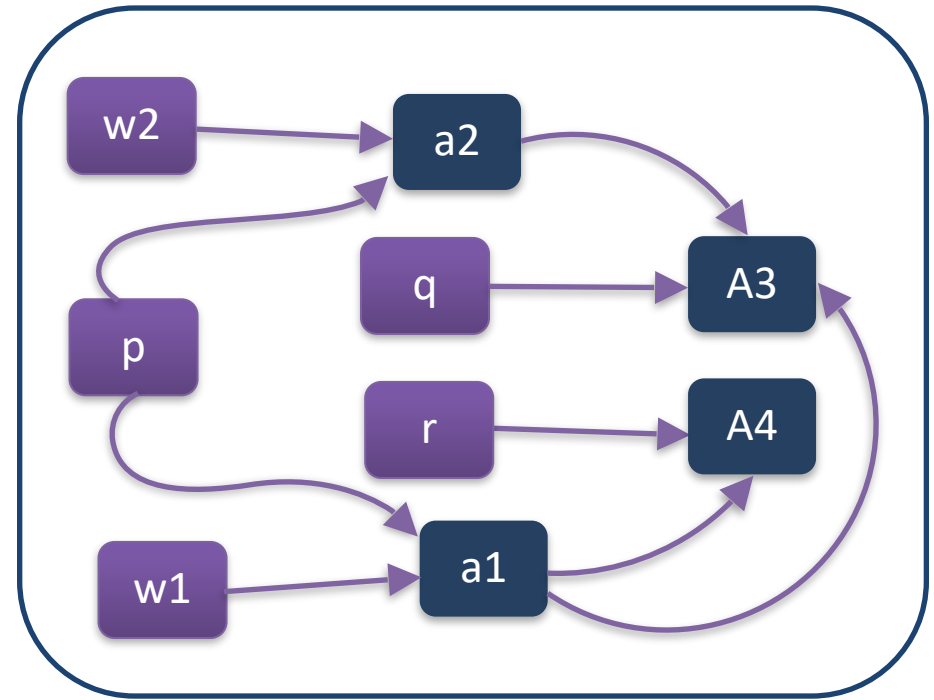
```
1: p := &A1;  
2: q := &A2;  
3: if (p = q) then  
4:     z := p  
5: else  
6:     z := q
```

- *Conservative*: may result in spurious “may point to” entries; but “must not point to” results are always sound.

Points-to Analysis: Example

```
1: w1 := &a1;  
2: w2 := &a2;  
3: q  := new Z[5];  
4: r  := new Z[5];  
5: *w1 := r;  
6: if (...) then  
7:   p := w1  
8: else  
9:   p := w2;  
10: *p := q
```

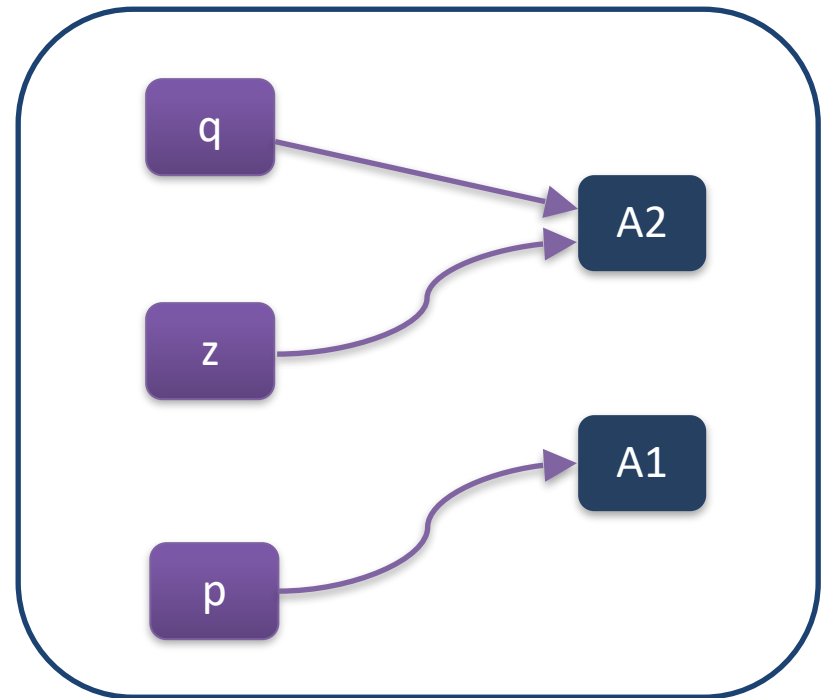
$a1, a2, q, r : Z^*$
 $w1, w2, p : Z^{**}$



Aliasing Analysis

Derived from result of point-to analysis

```
1: p := new Z[5];  
2: q := new Z[5];  
3: if (p = q) then  
4:     z := p  
5: else  
6:     z := q
```



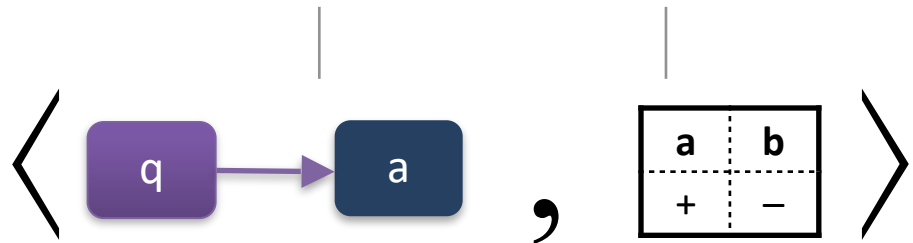
z and p **may not** alias
q and p **may not** alias
z and q **may** alias

Example: Pointers + Sign

```
1: a := 3;  
2: b := -3;  
3: q := &a;  
4: *q := *q + 1  
5: assert a + b > 0  
6: assert b < 0
```

Abstract Domain:

Points-to × Signs



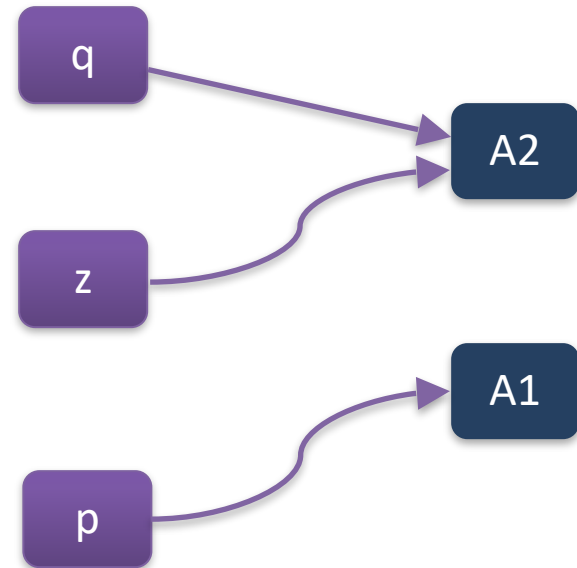
Example: Aliasing + Available Expressions

```
1: a := *q + 4 * c;
```

```
2: b := 0;
```

```
3: *p := 1;
```

```
4: b := *q + 4 * c
      a
```



Optimization is valid:
`p` and `q` are **not** aliased

Static Program Analysis

- Can automatically **prove** interesting properties
 - ▶ absence of null pointer dereferences, numerical assertions, termination, absence of data races, information flow, ...
- Nice combination of **math** and **system** building
 - ▶ combines program semantics, data structures, discrete math, logic, parallelism, decision procedures, ...

What we learned about

Static Program Analysis

- No need to run the program!
 - ▶ No concrete input needed!
 - ▶ Properties are guaranteed to hold for *any* input and *any* execution!!

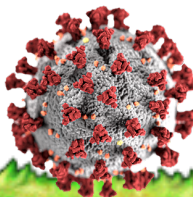
Exam

11/4/2024

13:00 – 16:00

- ★ 20% Compiler Phases
- ★ 30% Syntax, Semantics, Code generation
- ★ 20% Optimizations
- ★ 30% Static Analysis

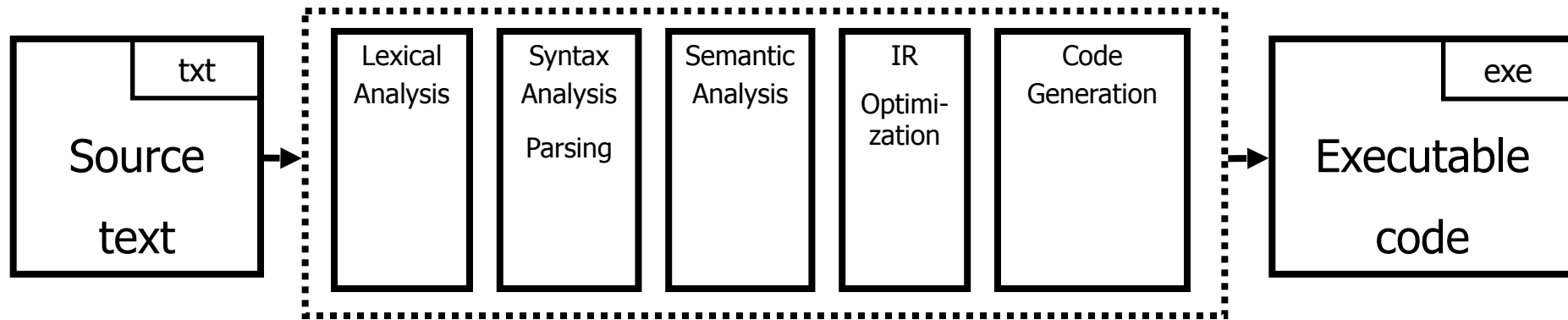
Hybrid Exam!
45% multiple choice
questions
55% open questions



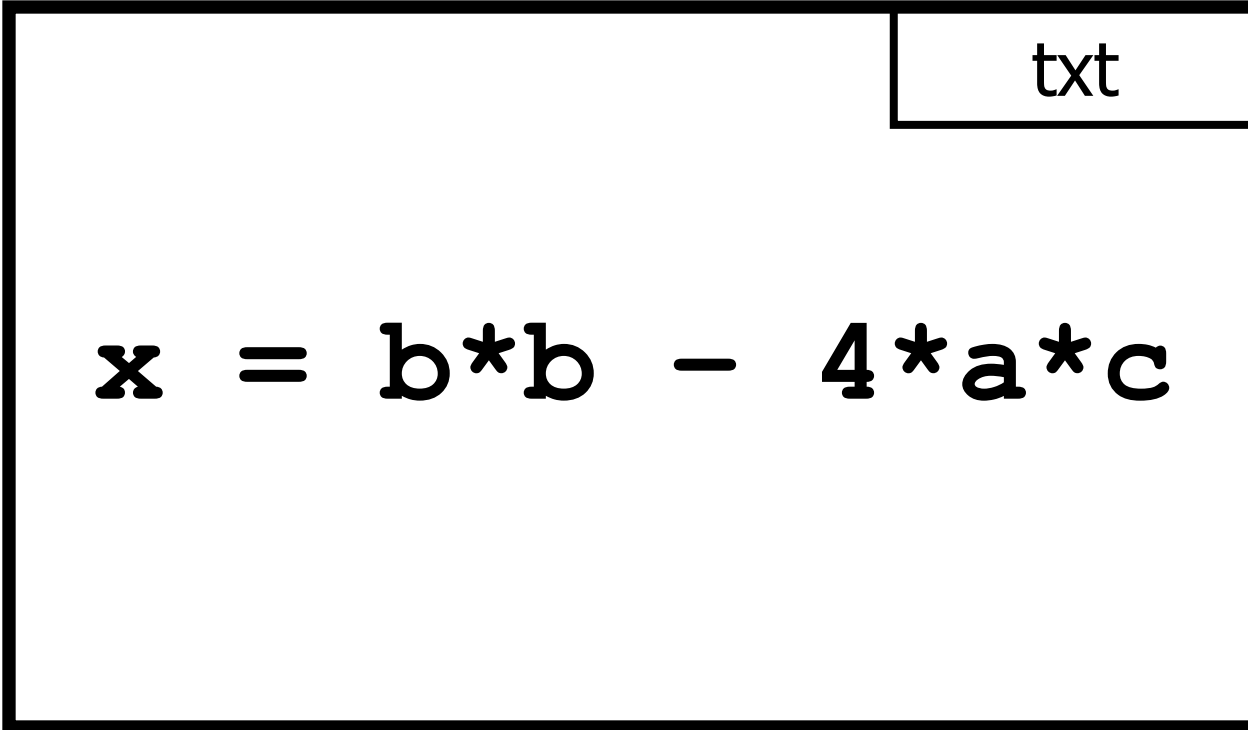
Recap



Compiler

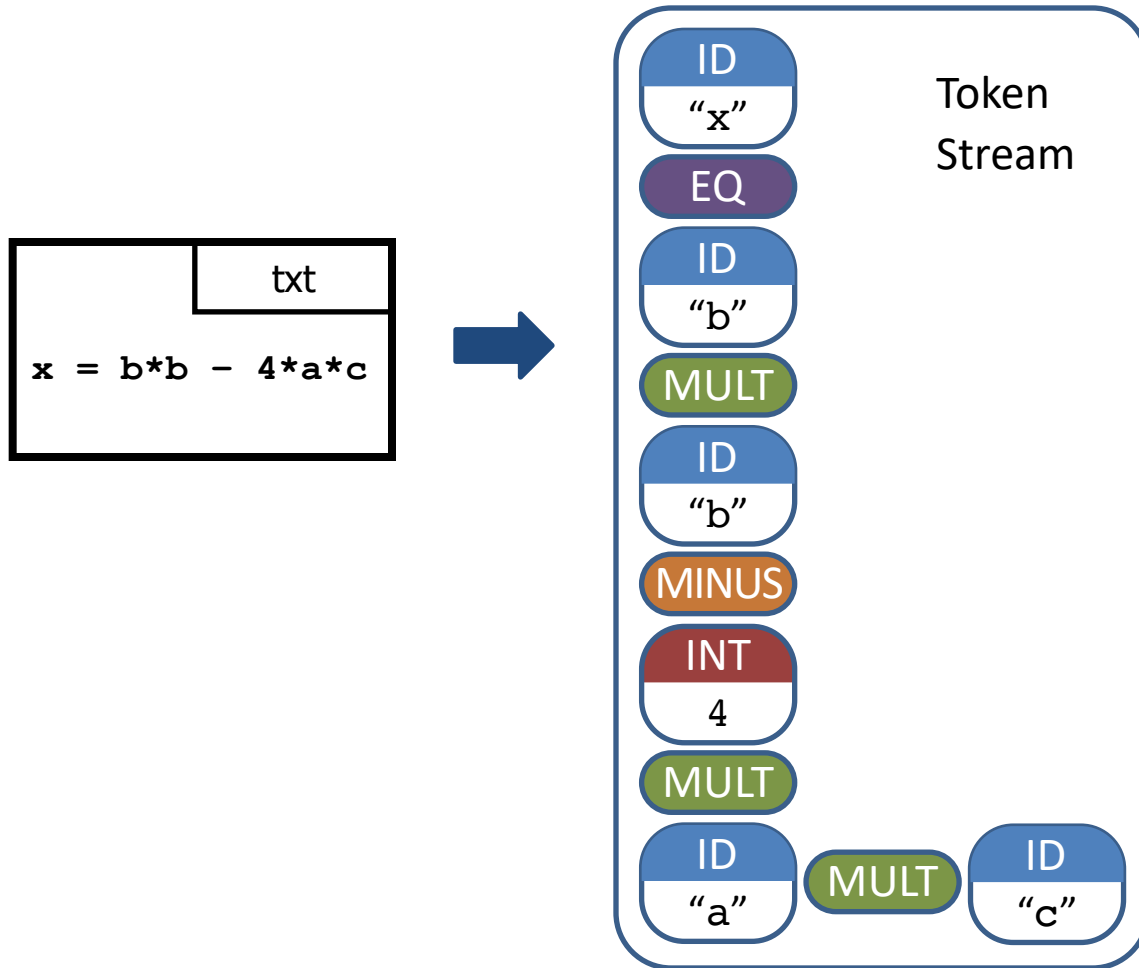


Recap

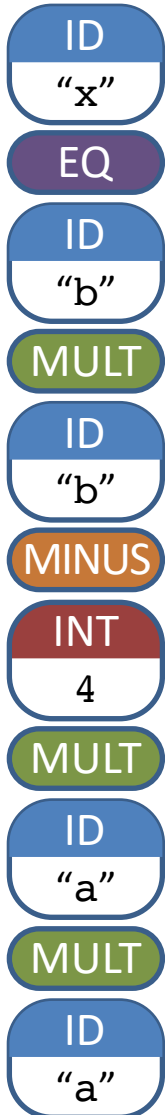


```
txt  
  
x = b*b - 4*a*c
```

Recap



Recap

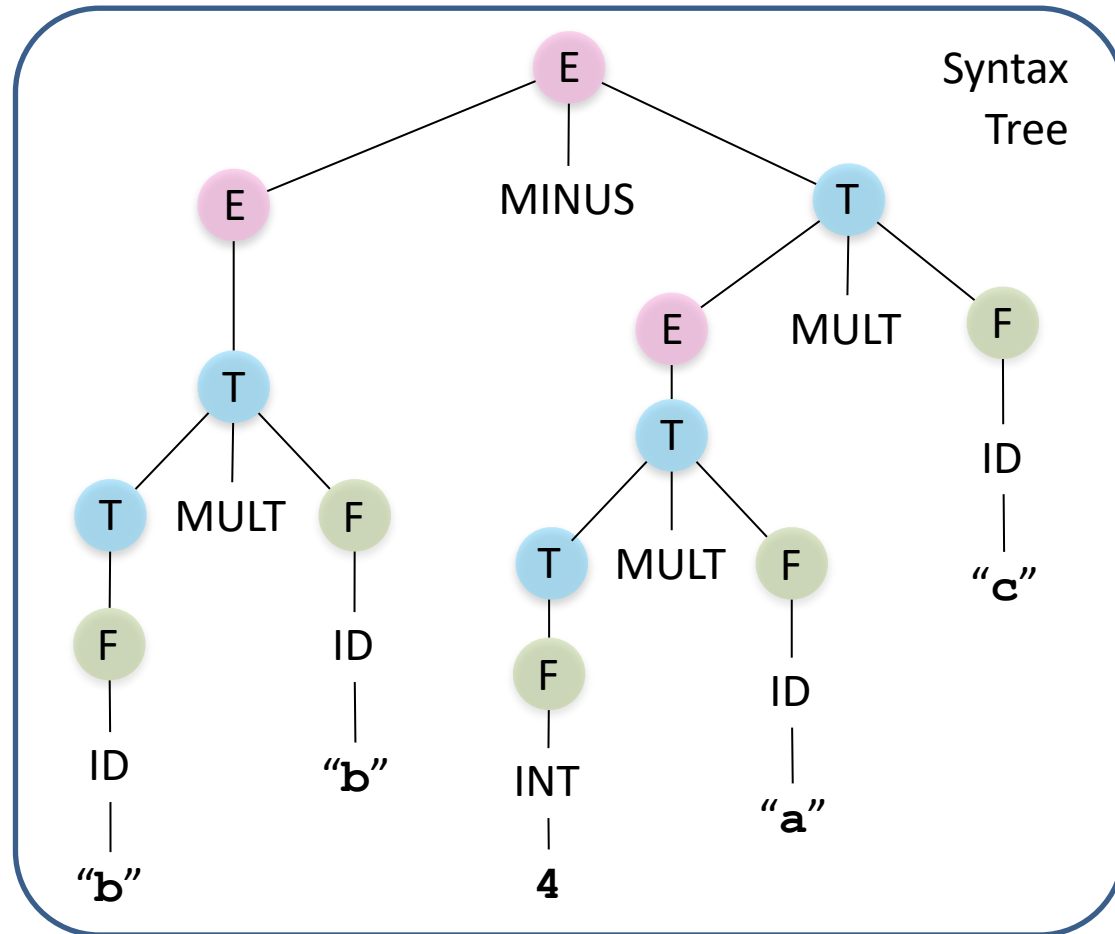


Grammar

$E \rightarrow E \text{ (PLUS) } T$
 $E \rightarrow E \text{ (MINUS) } T$
 $T \rightarrow T \text{ (MULT) } F$
 $T \rightarrow T \text{ (DIV) } F$
 $F \rightarrow (\text{ID})$
 $F \rightarrow (\text{INT})$



Token Stream



Lexical
Analysis

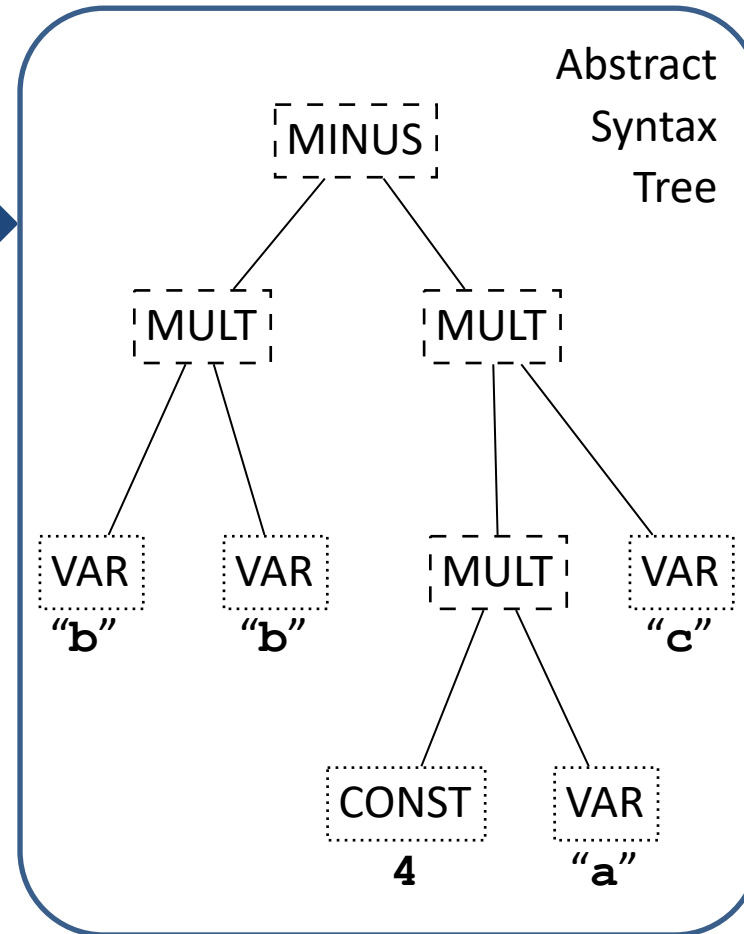
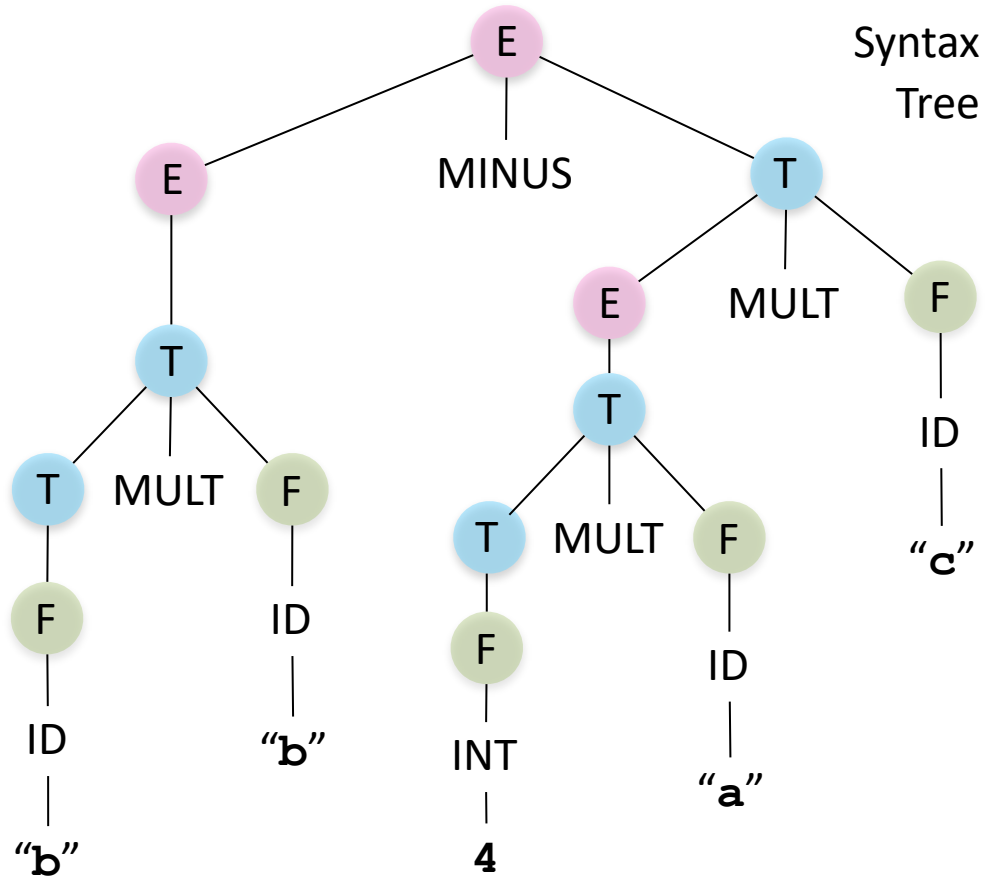
Syntax
Analysis

Semantic
Analysis

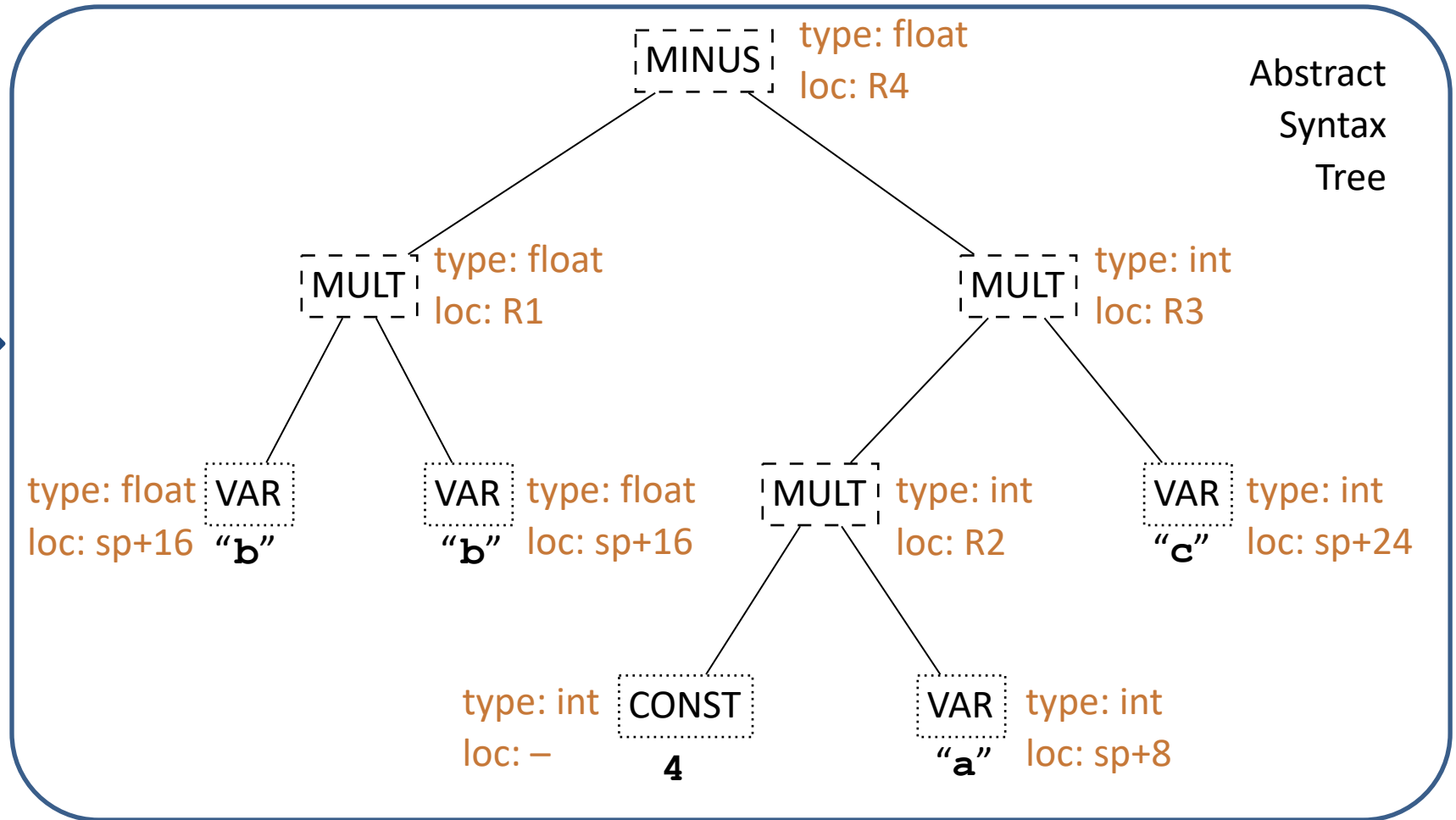
IR
Opt.

Code
Gen.

Recap

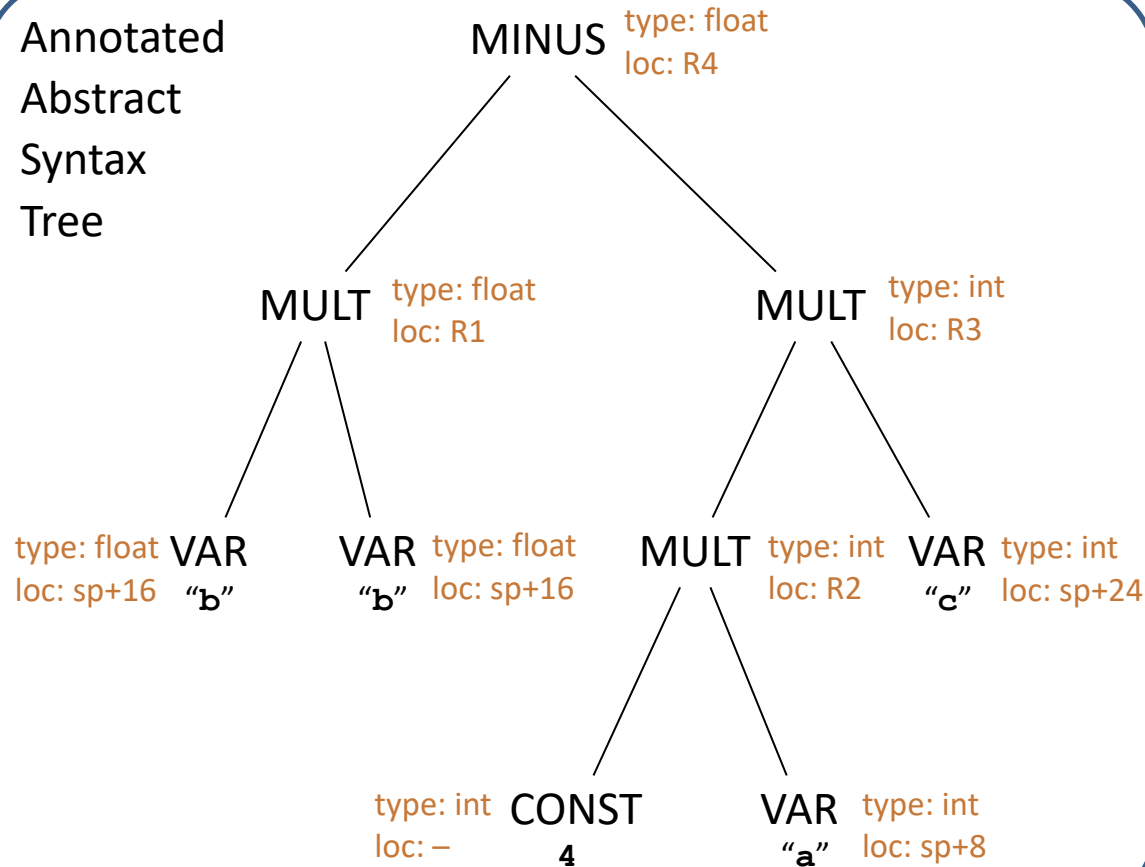


Recap



Recap

Annotated
Abstract
Syntax
Tree

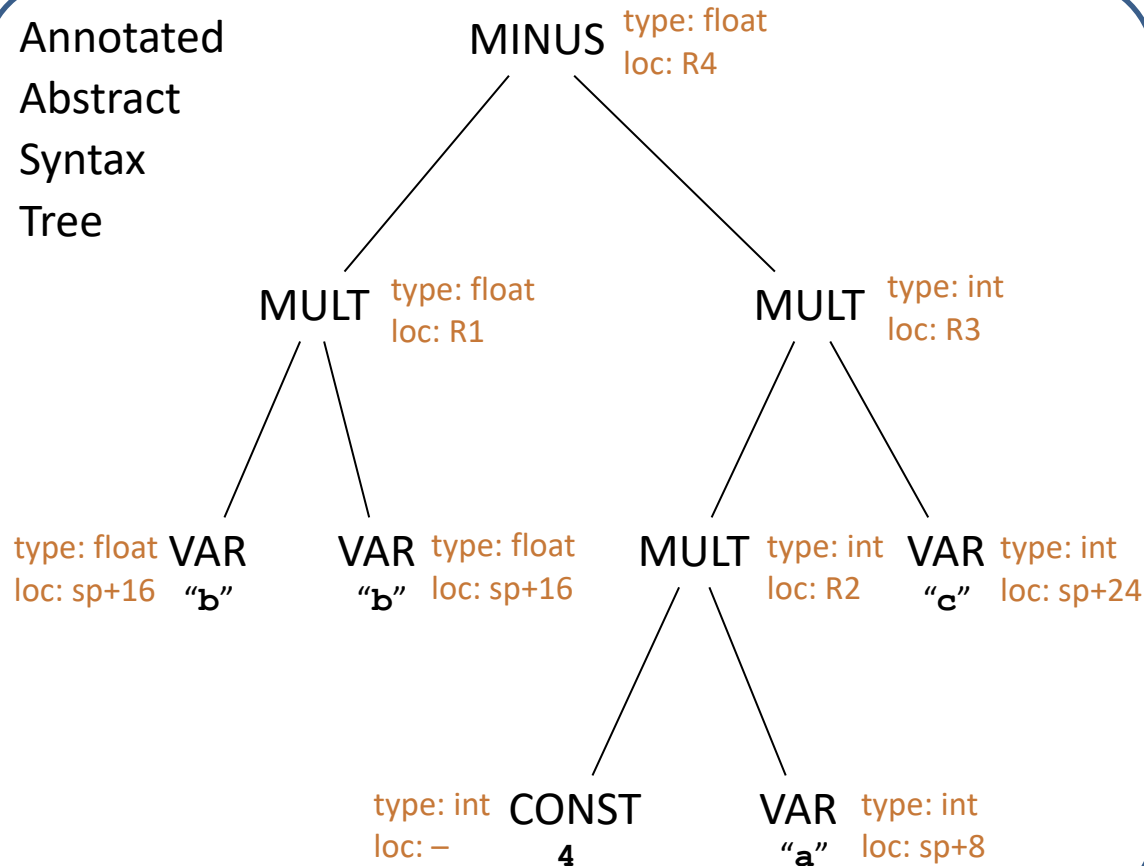


Intermediate
Representation

$R1 = b * b$
 $R2 = 4 * a$
 $R3 = R2 * c$
 $R5 = (\text{float})R3$
 $R4 = R1 - R5$

Recap

Annotated Abstract Syntax Tree



Intermediate Representation

R1 = b * b
R2 = 4 * a
R3 = R2 * c
R5 = (float)R3
R4 = R1 - R5

Assembly
Code

```
fild    [esp+16]
fmul    st0, st0
mov     ebx, [esp+8]
sal     ebx, 2
mul     ebx, [sp+24]
fild    ebx
fsub    st0, st1
```

Recap

- Runtime considerations
 - activation records (for managing function calls)
 - dynamic memory management, garbage collection
 - object oriented aspects: inheritance & dynamic dispatch

Make sure you understand:

- What happens at **compile time**
- What happens at **runtime**
- How the first affects the second!!



You Have Reached
Your Destination

