

# Pregunta 8

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#### Programe la eliminación de Gauss Jordan Muestre una base para el espacio columna de cualquier matriz A, Por ejemplo la matriz del problema 10.

A

```
In [1]: from toolNick import *  
import numpy as np
```

toolNick se ha importado correctamente.

```
In [2]: def gauss_Jordan(a, b, p = False, v = False, i = False):  
    # v nos muestra el procedimiento detallado de la eliminacion  
    # p se utiliza si requiere pivotacion total al inicio  
    # i si se quiere hallar la inversa de la matriz "a"  
    A_b = np.c_[a, b] # Matriz aumentada  
    (fil, col) = A_b.shape #Guarda el #filas y #columnas  
    line = "===== "  
  
    # Creamos una lista para almacenar las matrices T  
    T_list = []  
    print("Matriz aumentada [A|b] al inicio:\n{}\n{}".format(A_b,line))  
  
    if p: A_b = pivoteo_Total(A_b, v)  
  
    for i in range(fil): # se condiera dim(a)  
        if A_b[i, i] == 0 :  
            P = pivoteo(A_b, i)  
            if v : print("P_{}\n{}".format(P))  
            A_b = P @ A_b  
  
    # Obtenemos el T_i  
    T_i = get_T(A_b, i, v)  
    T_list.append(T_i) # Agregamos para hallar la inversa
```

```

A_b = T_i @ A_b

# Mostrar T(i) * (A/b)
if v : print("T_{} * [A|b]:\n{}\n{}".format(i+1,A_b,line))

if not(i):
    A_inv = np.identity(fil)
    for i in range(fil):
        A_inv = T_list[i] @ A_inv
    print("La matriz inversa de A es:\n{}\n{}".format(A_inv,line))

print("Matriz aumentada [A|b] al final: \n", A_b)
x = A_b[:, col - 1]
return x

```

### Eliminacion Gauss Jordan

```

In [3]: A = np.array([[2, 1, 1, 0],
                      [4, 3, 3, 1],
                      [8, 7, 9, 5],
                      [6, 7, 9, 8]])

print("Matriz de coeficientes A:\n", A); (fil,col) = A.shape
b = np.array([1, 1, 1, 1]); b.reshape(fil,1)
print("Matriz b: \n", b)

```

Matriz de coeficientes A:

```

[[2 1 1 0]
 [4 3 3 1]
 [8 7 9 5]
 [6 7 9 8]]

```

Matriz b:

```

[1 1 1 1]

```

```

In [4]: gauss_Jordan(A, b, v=True, i = False)

```

Matriz aumentada [A|b] al inicio:

```

[[2 1 1 0 1]
 [4 3 3 1 1]
 [8 7 9 5 1]
 [6 7 9 8 1]]

```

alpha\_1:

```

[[0.5]
 [2. ]
 [4. ]
 [3. ]]

```

alpha\_1 \* e\_1:

```

[[0.5 0.  0.  0. ]
 [2.  0.  0.  0. ]
 [4.  0.  0.  0. ]
 [3.  0.  0.  0. ]]
T_1:
[[ 0.5  0.  0.  0. ]
 [-2.   1.  0.  0. ]
 [-4.   0.  1.  0. ]
 [-3.   0.  0.  1. ]]
T_1 * [A|b]:
[[ 1.  0.5  0.5  0.  0.5]
 [ 0.   1.   1.   1.  -1. ]
 [ 0.   3.   5.   5.  -3. ]
 [ 0.   4.   6.   8.  -2. ]]
=====
alpha_2:
[[0.5]
 [0. ]
 [3. ]
 [4. ]]
alpha_2 * e_2:
[[0.  0.5  0.  0. ]
 [0.  0.  0.  0. ]
 [0.  3.  0.  0. ]
 [0.  4.  0.  0. ]]
T_2:
[[ 1.  -0.5  0.  0. ]
 [ 0.   1.  0.  0. ]
 [ 0.  -3.  1.  0. ]
 [ 0.  -4.  0.  1. ]]
T_2 * [A|b]:
[[ 1.  0.  0.  -0.5  1. ]
 [ 0.  1.  1.  1.  -1. ]
 [ 0.  0.  2.  2.  0. ]
 [ 0.  0.  2.  4.  2. ]]
=====
alpha_3:
[[0. ]
 [0.5]
 [0.5]
 [1. ]]
alpha_3 * e_3:
[[0.  0.  0.  0. ]
 [0.  0.  0.5  0. ]
 [0.  0.  0.5  0. ]
 [0.  0.  1.  0. ]]
T_3:
[[ 1.  0.  0.  0. ]

```

```

[ 0.  1. -0.5  0. ]
[ 0.  0.  0.5  0. ]
[ 0.  0. -1.  1. ]]
T_3 * [A|b]:
[[ 1.  0.  0. -0.5  1. ]
 [ 0.  1.  0.  0. -1. ]
 [ 0.  0.  1.  1.  0. ]
 [ 0.  0.  0.  2.  2. ]]
=====
alpha_4:
[[-0.25]
 [ 0. ]
 [ 0.5 ]
 [ 0.5 ]]
alpha_4 * e_4:
[[-0.  -0.  -0.  -0.25]
 [ 0.   0.   0.   0. ]
 [ 0.   0.   0.   0.5 ]
 [ 0.   0.   0.   0.5 ]]
T_4:
[[ 1.  0.  0.  0.25]
 [ 0.  1.  0.  0. ]
 [ 0.  0.  1. -0.5 ]
 [ 0.  0.  0.  0.5 ]]
T_4 * [A|b]:
[[ 1.  0.  0.  0.  1.5]
 [ 0.  1.  0.  0. -1. ]
 [ 0.  0.  1.  0. -1. ]
 [ 0.  0.  0.  1.  1. ]]
=====
Matriz aumentada [A|b] al final:
[[ 1.  0.  0.  0.  1.5]
 [ 0.  1.  0.  0. -1. ]
 [ 0.  0.  1.  0. -1. ]
 [ 0.  0.  0.  1.  1. ]]

```

```
Out[4]: array([ 1.5, -1. , -1. ,  1. ])
```