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1  /*****
2  * AUTHOR          : Nick Reardon
3  * Assignment #4   : Deque To Queue
4  * CLASS           : CS1D
5  * SECTION         : MW - 2:30p
6  * DUE DATE        : 02 / 10 / 20
7  *****/
8  #ifndef _ARRAYHEAP_H_
9  #define _ARRAYHEAP_H_
10 #include <exception>
11 #include "Except.h"
12
13 enum ERROR_TYPE
14 {
15     DEFAULT,
16     FULL,
17     EMPTY,
18     OUT_OF_RANGE
19 };
20
21 template <typename Type, typename Key>
22 struct heapMember
23 {
24     Type value;
25     Key key;
26
27     heapMember(const Type& newValue, const Key& newKey)
28     {
29         value = newValue;
30         key = newKey;
31     }
32
33     heapMember() {}
34
35     void swap(heapMember& other)
36     {
37         Key tempKey;
38         Type tempType;
39
40         tempKey = other.key;
41         tempType = other.value;
42
43         other.key = this->key;
44         other.value = this->value;
45
46         this->key = tempKey;
47         this->value = tempType;
48
49     }
50 }
51
52 inline bool operator< (const heapMember& other)
```

```
53     {
54         return (this->key < other.key);
55     }
56
57     inline bool operator> (const heapMember& other)
58     {
59         return (this->key > other.key);
60     }
61
62     inline void operator= (const heapMember& other)
63     {
64         this->key = other.key;
65         this->value = other.value;
66     }
67 };
68
69 template <class Type, class Key>
70 class ArrayMaxHeap
71 {
72 private:
73     heapMember<Type, Key>* heap;
74
75     int currentSize;
76
77     int capacity;
78
79 protected:
80     void sort()
81     {
82         int index = 1;
83
84         int swapIndex;
85
86         while ( (2 * index < currentSize) &&
87             ((heap[index].key < heap[2 * index].key) || (heap[index].key < heap[2 *
88             * index + 1].key)) )
89         {
90             if (heap[2 * index].key > heap[2 * index + 1].key)
91             {
92                 swapIndex = 2 * index;
93             }
94             else
95             {
96                 swapIndex = 2 * index + 1;
97             }
98
99             heap[index].swap(heap[swapIndex]);
100
101             index = swapIndex;
102         }
103     }
```

```
104
105
106 public:
107
108     ArrayMaxHeap<Type,Key>(const int newCapacity = 32)
109     {
110         heap = new heapMember<Type, Key>[newCapacity];
111         currentSize = 0;
112         capacity = newCapacity;
113     }
114
115     //VectorHeap<Type>(const VectorHeap<Type>& otherDeque);
116
117     ~ArrayMaxHeap()
118     {
119         delete[] heap;
120     }
121
122     bool empty() const { return currentSize == 0; }
123
124     bool full() const { return currentSize == capacity; }
125
126     int size() const { return size; }
127
128     void insert(const Type& element, const Key& newKey)
129     {
130         if (full())
131         {
132             throw Except("container is full", FULL, 5);
133         }
134
135         currentSize++;
136
137         heap[currentSize].value = element;
138         heap[currentSize].key = newKey;
139
140
141         int index = currentSize;
142
143         while ( (heap[index].key > heap[index / 2].key) && ((index / 2) != 0) )
144         {
145             heap[index].swap(heap[index / 2]);
146
147             index /= 2;
148
149         }
150
151     }
152
153     void remove()
154     {
155         if (empty())
```

```
156     {
157         throw(Except("Cannot remove - heap is empty", EMPTY, 5));
158     }
159
160     heap[1] = heap[currentSize];
161     currentSize--;
162     sort();
163 }
164
165
166
167 Type max() const
168 {
169     Type temp = heap[1].value;
170     return temp;
171 }
172
173 void printAll(std::ostream& output) const
174 {
175     if (empty())
176     {
177         throw(Except("Cannot print - heap is empty", EMPTY, 5));
178     }
179
180     int current = 0;
181     int levelSize = 1;
182
183     for (int i = 1; i < currentSize; i++)
184     {
185         output << heap[i].value << '(' << heap[i].key << ')' << " ";
186
187         current++;
188
189         if (current == levelSize)
190         {
191             current = 0;
192
193             levelSize = levelSize * 2;
194
195             output << '\n';
196         }
197     }
198
199     output << "\n\n";
200 }
201
202 };
203
204
205 #endif // !_ARRAYHEAP_H_
```