Recorded at time: 11.100 map Broadcaster: /world_to_robot_0_tf_broadcaster Broadcaster: /world_to_robot_1_tf_broadcaster / Broadcaster: /world_to_robot_4_tf_broadcaster Broadcaster: /world_to_robot_2_tf_broadcaster Broadcaster: /world_to_robot_5_tf_broadcaster Broadcaster: /world_to_robot_3_tf_broadcaster Average rate: 5.208 Hz Most recent transform: 11.300 (-0.200 sec old) | Most recent transform: 11.300 (-0.200 sec old) \Most recent transform: 11.300 (-0.200 sec old) Buffer length: 4.800 sec robot_5/map robot_2/map robot_3/map robot_0/map robot_1/map robot_4/map Broadcaster: /robot_0/stage_slam_gmapping Broadcaster: /robot_2/stage_slam_gmapping Broadcaster: /robot_1/stage_slam_gmapping Broadcaster: /robot_5/stage_slam_gmapping Broadcaster: /robot_3/stage_slam_gmapping Broadcaster: /robot_4/stage_slam_gmapping Average rate: 20.408 Hz Most recent transform: 11.150 (-0.050 sec old) Most recent transform: 11.150 (-0.050 sec old) Most recent transform: 11.150 (-0.050 sec old) | Most recent transform: 11.150 (-0.050 sec old) Most recent transform: 11.150 (-0.050 sec old) Most recent transform: 11.150 (-0.050 sec old) Buffer length: 4.900 sec robot_0/odom robot_4/odom robot_2/odom robot_1/odom robot_5/odom robot_3/odom Broadcaster: /Stage Broadcaster: /Stage Broadcaster: /Stage Broadcaster: /Stage Broadcaster: /Stage Broadcaster: /Stage Average rate: 10.204 Hz Most recent transform: 11.100 (0.000 sec old) Most recent transform: 11.100 (0.000 sec old) \ Most recent transform: 11.100 (0.000 sec old) Buffer length: 4.900 sec robot_0/base_footprint robot_1/base_footprint robot_4/base_footprint robot_5/base_footprint robot_2/base_footprint robot_3/base_footprint Broadcaster: /Stage Broadcaster: /Stage Broadcaster: /Stage Broadcaster: /Stage Broadcaster: /Stage Broadcaster: /Stage Average rate: 10.204 Hz Most recent transform: 11.100 (0.000 sec old) Most recent transform: 11.100 (0.000 sec old) Most recent transform: 11.100 (0.000 sec old) Buffer length: 4.900 sec robot_0/base_link robot_1/base_link robot_4/base_link robot_5/base_link robot_2/base_link robot_3/base_link Broadcaster: /Stage Average rate: 10.204 Hz Most recent transform: 11.100 (0.000 sec old) Mos Most recent transform: 11.100 (0.000 sec old) \ Most recent transform: 11.100 (0.000 sec old) \ Most recent transform: 11.100 (0.000 sec old) \ \ Most recent transform: 11.100 (0.000 sec old) Most recent transform: 11.100 (0.000 sec old recent transform: 11.100 (0.000 sec old) st recent transform: 11.100 (0.000 sec old) Most recent transform: 11.100 (0.000 sec old) Mo recent transform: 11.100 (0.000 sec old) Most recent transform: 11.100 (0.000 sec old) ecent transform: 11.100 (0.000 sec old) Buffer length: 4.900 sec robot_1/base_laser_link_1 robot_4/base_laser_link_1 robot_5/base_laser_link_0 robot_5/base_laser_link_1 robot_2/base_laser_link_0 robot_2/base_laser_link_1 robot_3/base_laser_link_0 robot_3/base_laser_link_1 robot_0/base_laser_link_1 robot_1/base_laser_link_0 robot_4/base_laser_link_0 robot_0/base_laser_link_0

view_frames Result