

## Problem 1.

Consider a forward SDE

$$dx_t = f(x_t, t) dt + g(x_t, t) dW_t.$$

Show that the corresponding probability flow ODE can be written as

$$dx_t = \left[ f(x_t, t) - \frac{1}{2} \frac{\partial}{\partial x} g^2(x_t, t) - \frac{g^2(x_t, t)}{2} \frac{\partial}{\partial x} \log p(x_t, t) \right] dt.$$

## Solution.

**Step 1.** Fokker–Planck equation of the SDE.

For the Itô SDE

$$dx_t = f(x_t, t) dt + g(x_t, t) dW_t,$$

the marginal density  $p(x, t)$  satisfies the Fokker–Planck equation

$$\partial_t p(x, t) = -\frac{\partial}{\partial x} (f(x, t)p(x, t)) + \frac{1}{2} \frac{\partial^2}{\partial x^2} (g^2(x, t)p(x, t)).$$

**Step 2.** Continuity equation for a deterministic ODE.

If a deterministic ODE

$$\dot{x}_t = v(x_t, t)$$

has density  $p(x, t)$ , then  $p$  satisfies the Liouville (continuity) equation

$$\partial_t p(x, t) = -\frac{\partial}{\partial x} (v(x, t)p(x, t)).$$

**Step 3.** Equating (FP) and (CE).

To reproduce the same density evolution as the SDE, we set

$$-\frac{\partial}{\partial x} (vp) = -\frac{\partial}{\partial x} (fp) + \frac{1}{2} \frac{\partial^2}{\partial x^2} (g^2 p).$$

Expanding the second derivative term:

$$\frac{\partial^2}{\partial x^2} (g^2 p) = \frac{\partial}{\partial x} \left( \frac{\partial g^2}{\partial x} p + g^2 \frac{\partial p}{\partial x} \right).$$

Thus

$$-\frac{\partial}{\partial x} (vp) = -\frac{\partial}{\partial x} \left( fp - \frac{1}{2} \frac{\partial g^2}{\partial x} p - \frac{1}{2} g^2 \frac{\partial p}{\partial x} \right).$$

**Step 4.** Solve for  $v(x, t)$ .

Since the equality holds for all  $p$ , we have

$$v(x, t)p(x, t) = f p - \frac{1}{2}(\partial_x g^2)p - \frac{1}{2}g^2 \partial_x p.$$

Dividing both sides by  $p > 0$  and noting that  $\partial_x p = p \partial_x \log p$ ,

$$v(x, t) = f(x, t) - \frac{1}{2} \partial_x g^2(x, t) - \frac{g^2(x, t)}{2} \partial_x \log p(x, t).$$

**Step 5.**

Hence the probability flow ODE is

$$dx_t = \left[ f(x_t, t) - \frac{1}{2} \partial_x g^2(x_t, t) - \frac{g^2(x_t, t)}{2} \partial_x \log p(x_t, t) \right] dt.$$