

Portfolio Selection with Approximate Dynamic Programming

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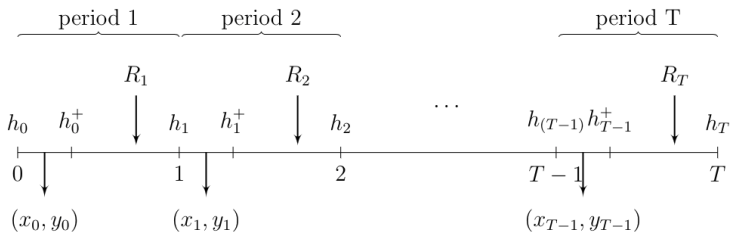
Overview

1. The portfolio selection problem
 - 1.1 Motivation
 - 1.2 Dynamic programming formulation
2. Approximated dynamic programming framework
 - 2.1 Approximations
 - 2.2 Implementation
3. Results
 - 3.1 Training Phase
 - 3.2 Testing Phase
4. Conclusion

Motivation

- Maximizing portfolio return
Through optimal strategy, maximizing the portfolio return, while minimizing risk
- Deadline
Introduction of deadline for investment to adjust for variance differences in possible stock options
- Dynamic programming approach
Using DP possible to capture the risk aversion aspect towards the end of the time horizon by rebalancing successive periods

Timeline



States, Actions & Uncertainty

■ States

Holdings of each stock n at time t with the **post-decision state**: $\mathbf{h}_t^+ = (h_{0t}^+, h_{1t}^+, \dots, h_{Nt}^+) \in \mathbb{R}_+^{N+1}$.

■ Actions

At each period, choose a vector of buyings:

$\mathbf{x}_t = (x_{1t}, \dots, x_{Nt}) \in \mathbb{R}_+^N$ and a similar vector of sellings \mathbf{y}_t

■ Uncertainty

Vector of returns at each t is uncertain:

$\mathbf{R}_t = (R_{0t}, R_{1t}, \dots, R_{Nt}) \in \mathbb{R}_+^{N+1}$

Constraints

■ Holding constraints

All asset holdings must be positive

$$-x_{it} + y_{it} \leq h_{it} \quad \forall i \in (1, \dots, N)$$

■ Budget constraints

Proportional **transaction costs** θ , equal for buying and selling

$$(1 + \theta) \sum_{i=1}^N x_{it} - (1 - \theta) \sum_{i=1}^N y_{it} \leq h_{0t}$$

■ Positive buying and selling vectors

We require $x_{it} \geq 0$ and $y_{it} \geq 0$ for all i and t .

Dynamics

For $1 \leq t \leq T - 1$:

$$\begin{cases} h_{0t}^+ = R_{0t} \left(h_{0(t-1)}^+ - (1 + \theta) \sum_{i=1}^N x_{it} + (1 - \theta) \sum_{i=1}^N y_{it} \right) \\ h_{it}^+ = R_{it} h_{i(t-1)}^+ + x_{it} - y_{it}, \quad i \in (1, \dots, N) \end{cases}$$

For $t = 0$,

$$\begin{cases} h_{00}^+ = h_{00}^+ - (1 + \theta) \sum_{i=1}^N x_{i0} + (1 - \theta) \sum_{i=1}^N y_{i0} \\ h_{i0}^+ = h_{i(0)}^+ + x_{i0} - y_{i0}, \quad i \in (1, \dots, N) \end{cases}$$

For $t = T$,

$$h_{iT}^+ = R_{iT} h_{i(T-1)}^+, i \in (0, 1, \dots, N)$$

Rewards

$$\gamma \sum_{i=0}^N h_{iT}^+ - (1 - \gamma) CVaR(h_T^+)$$

with:

CVaR: as the expected return given that we stay within the $1 - \beta$ worst cases

γ : risk aversion parameter of the investor

Initialization and Recursion

■ Initialization:

$$V_T^+(h_T^+) = \gamma \sum_{i=0}^N h_{iT}^+ - (1 - \gamma) CVaR(h_T^+)$$

■ Recursion:

Last period h_{T-1}^+ :

$$V_{T-1}^+(h_{T-1}^+) = \mathbb{E}_{R_T}[V_T^+(h_T^+) | h_{T-1}^+]$$

For $1 \leq t \leq T - 2$,

$$V_{t-1}^+(h_{t-1}^+) = \mathbb{E}_{R_t}[\max_{(x_t, y_t)} V_t^+(h_t^+) | h_{t-1}^+]$$

For $t = 0$, we do not have returns available. Hence

$$V_0(h_0) = \max_{(x_0, y_0)} V_0^+(h_0^+)$$

"Monte Carlo" approximation

Instead of:

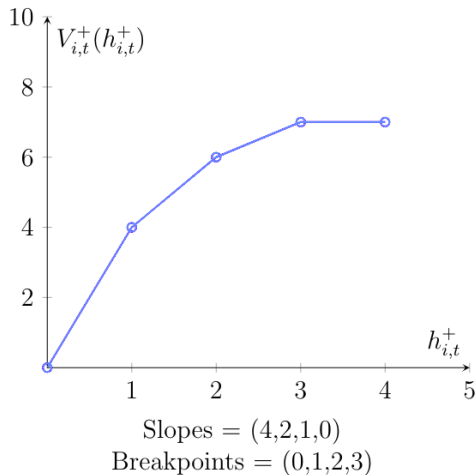
$$V_t^+ = \max_{(x_t, y_t)} \mathbb{E}_{R_t}[V_{t+1}^+ | h_t^+]$$

We use:

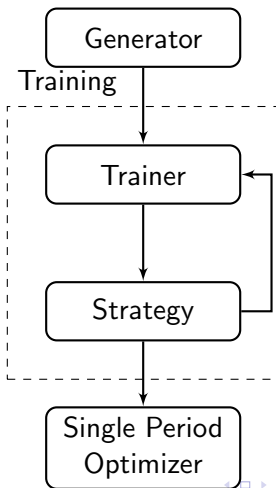
$$V_t^+ = \max_{(x_t, y_t)} [V_{t+1}^+ | h_t^+, R_t^s]$$

where R_t^s is redrawn for each training iteration s .

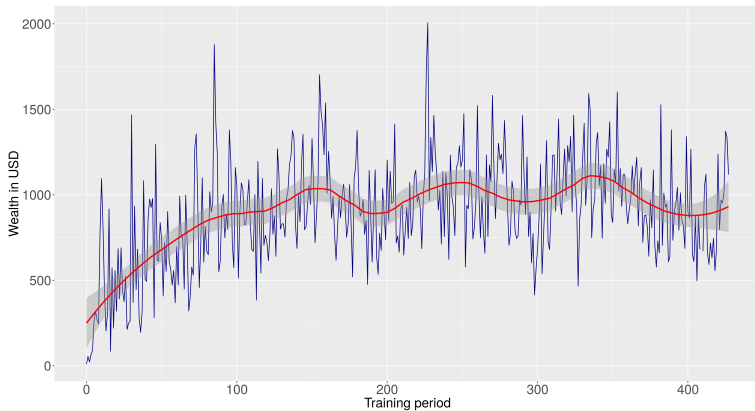
Piecewise linear approximation



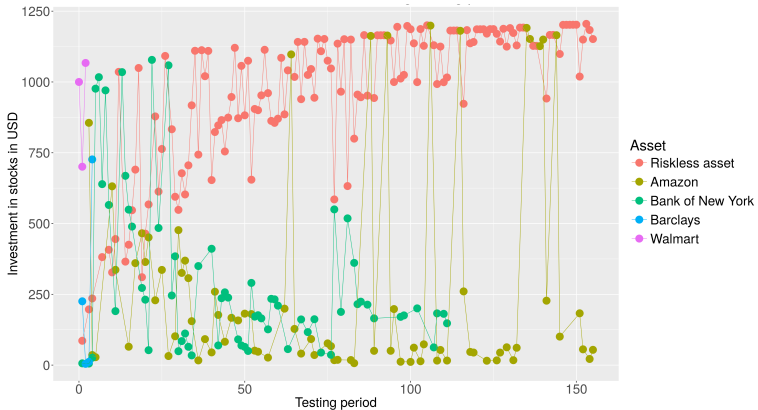
Implementation



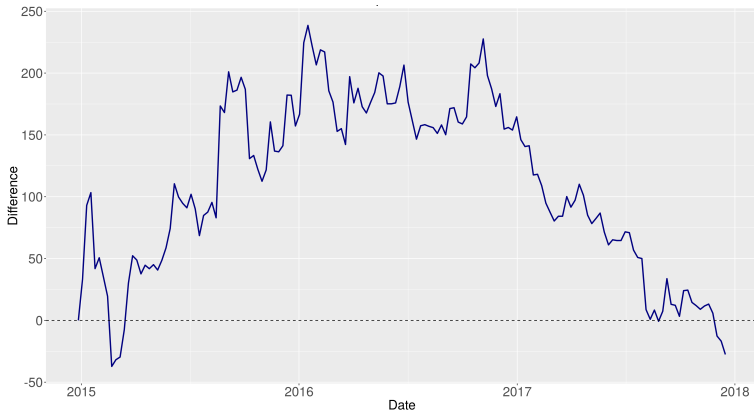
Training Process



Diversification of our Portfolio



Difference between Portfolio and Index investment



Conclusion

- Dynamic Programming useful tool for solving finite-horizon problems
- Approximations necessary to make problem computationally tractable

Improvements

- Train on more data
 1. Obtain more historical data, or
 2. Fit model to historical data, use it to generate training data
- Extend search space for value functions
 1. Include non-linear functions

References



Edouard Berthe, *Stochastic Dynamic Programming for Portfolio Selection Problem applied to CAC40*, Jun 2017



Dimitrios Karamanis, *Stochastic Dynamic Programming Methods for the Portfolio Selection Problem*, 2013