# Midterm Review Notes

#### Nickhil Sethi

# **Ordinary Linear Regression**

### estimate parameters

In OLS, we estimate the parameters by choosing  $\beta_0, \beta_1$  to minimize the sum of squares.

$$\min_{\beta_0,\beta_1} \sum_{i} (Y_i - (\beta_0 + \beta_1 X_i))^2$$

That is, the sum of squared differences between our prediction and the true values  $Y_i$ . For OLS, closed form solutions exist for the parameter estimates:

$$\hat{\beta}_{1} = \frac{\sum_{i} (X_{i} - \bar{X})(Y_{i} - \bar{Y})}{\sum_{i} (X_{i} - \bar{X})^{2}}$$

$$\hat{\beta}_{0} = \bar{Y} - \beta_{1}\bar{X}$$

# estimate variance

The variance of the noise  $\epsilon$  is estimated based on the parameters  $\beta_0$ ,  $\beta_1$  and the data set  $\{X_i, Y_i\}$ :

$$\hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 X_i$$

$$\hat{\sigma}^2 = \frac{\sum_i (\hat{Y}_i - Y_i)^2}{n - 2}$$

Notice the denominator is n-2 – the "degrees of freedom", i.e. the number of data points minus the number of estimated parameters. This estimator is unbiased, meaning  $\mathbb{E}(\hat{\sigma}^2) = \sigma^2$ .

## least squares vs MLE

Least squares and MLE estimation for linear regression are very similar; under the assumption of gaussian noise, they are nearly equivalent, with the only difference being the estimation of the sample variance.

$$\hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 X_i$$
 
$$\hat{\sigma}_{MLE}^2 = \frac{\sum_i (\hat{Y}_i - Y_i)^2}{n}$$

Notice the difference between the MLE estimator of the sample variance and the least squares estimator of the sample variance. The MLE estimator is biased i.e.  $\mathbb{E}(\hat{\sigma}^2) \neq \sigma^2$ ; however, the bias term decays to zero as the number of data points n increases.

### residuals and their properties

The residuals are defined as  $\varepsilon_i = \hat{y}_i - y_i$ . Of course, the loss is defined as the sum of squared residuals:

$$\sum_{i} \varepsilon_{i} = 0$$

$$\sum_{i} \varepsilon_{i} \cdot X_{i} = 0$$

From the above properties, it's very simple to show the following additional properties:

$$\sum_{i} \hat{Y}_{i} = \sum_{i} Y_{i}$$

$$\sum_{i} \varepsilon_{i} \cdot \hat{Y}_{i} = 0$$

Typically, we assume the noise is gaussian, in which case the residuals should be roughly normally distributed. We can check this via a q-q plot.

## Confidence intervals vs Prediction Intervals

A confidence interval estimates a range of plausible values of a parameter of interest, e.g.  $E(Y_i|X_i)$ ; a prediction interval, on the other hand, tries to estimate a range of plausible variables for a single out of sample point e.g. the a new  $Y_i$ . The difference lies in the fact that a prediction interval has to account for the variance in the distribution of  $Y_i$ .

The distribution for an single out of sample  $\hat{Y}_i$  would be gaussian with the following mean and variance

$$E[\hat{Y}_i] = \beta_0 + \beta_1 X_i$$

$$\sigma^2[\hat{Y}_i] = \hat{\sigma}^2 \left[1 + \frac{1}{n} + \frac{(X_i - \bar{X})^2}{\sum_j (X_j - \bar{X})^2}\right]$$

## Diagnostics (R squared)

$$R^{2} = 1 - \frac{RSS}{TSS} = 1 - \frac{\sum_{i} (\hat{y}_{i} - y_{i})^{2}}{\sum_{i} (\bar{y} - y_{i})^{2}}$$

- Multiple Variables
- Qualitative

-AIC

Bernoiulli/Binomial Data

- link functions
- predictions
- odds, probability
- risk ratio vs odds ratio
- goodness of fit
- Diagnostics (Pearson Residuals)
- different scoring functions
- confusion matrix and properties (sensitivity, specificity, PPV, accuracy, NPV)

- comparing nested models
- overdispersion
- $\bullet$  f statistics
- quasibinomial