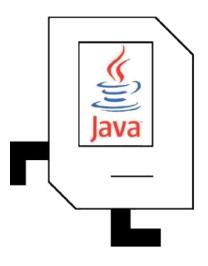
CS 106A, Lecture 2 Programming with Karel

suggested reading:

Karel, Ch. 3-4

Plan For Today

- Announcements
- (Re) Meet Karel the Robot
- Control Flow
 - –For loops
 - -While loops
 - -If/else statements



Plan For Today

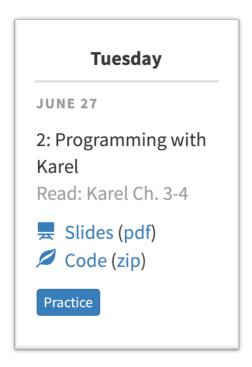
•Announcements



- (Re) Meet Karel the Robot
- Control Flow
 - -For loops
 - -While loops
 - -If/else statements

Announcements

- Section assignments
- Office Hours
- Karel Handout (#3)
- Lecture Feedback
- Extra Practice



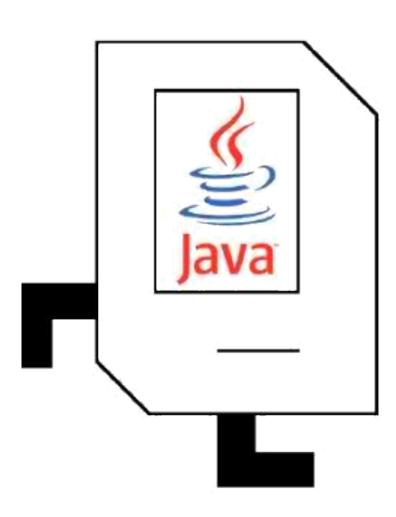
Plan For Today

- Announcements
- •(Re)Meet Karel the Robot

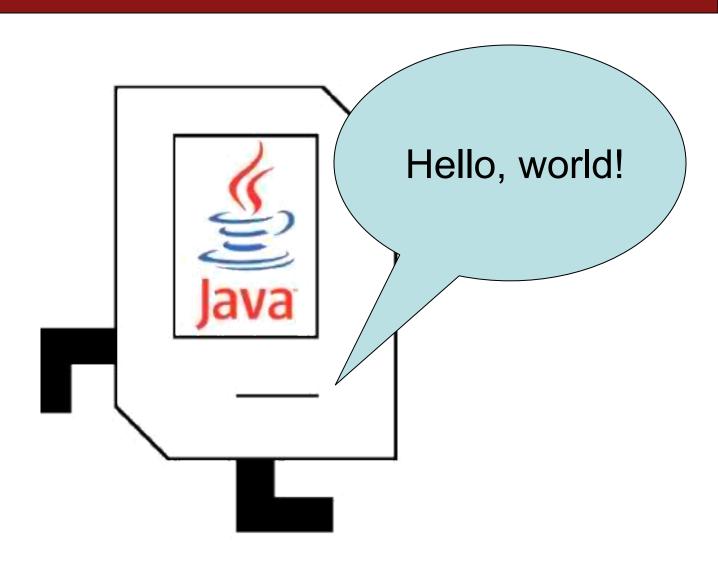


- Control Flow
 - -For loops
 - -While loops
 - -If/else statements

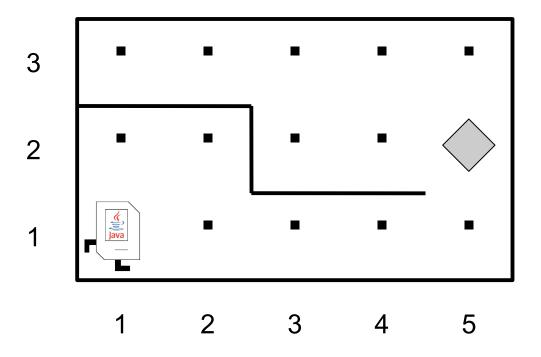
Meet Karel the Robot!



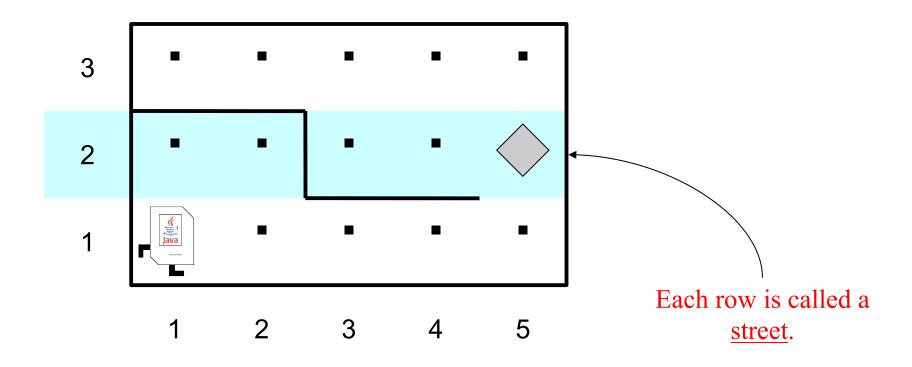
Meet Karel the Robot!



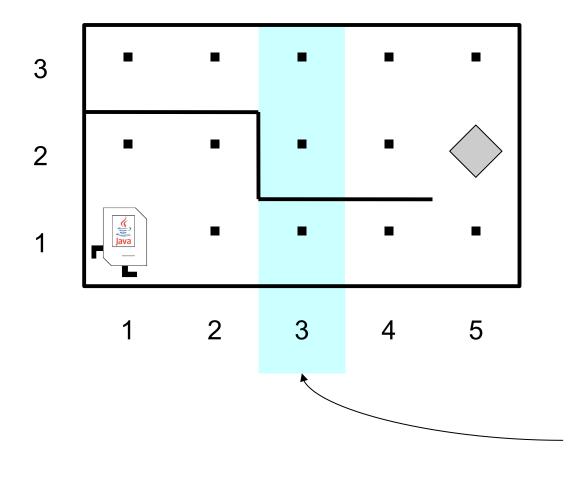
Karel's World



Streets (rows)

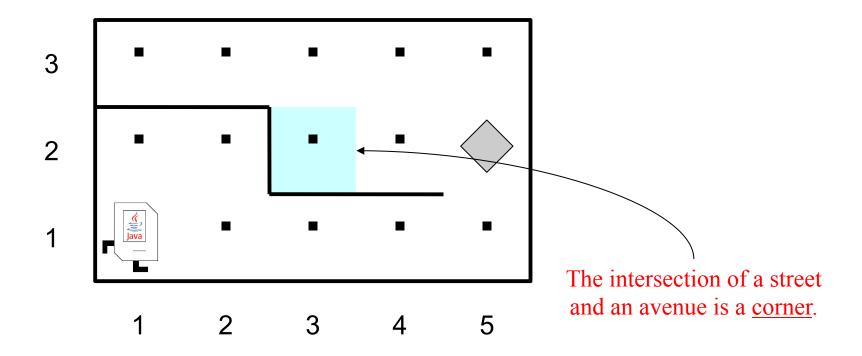


Avenues (columns)

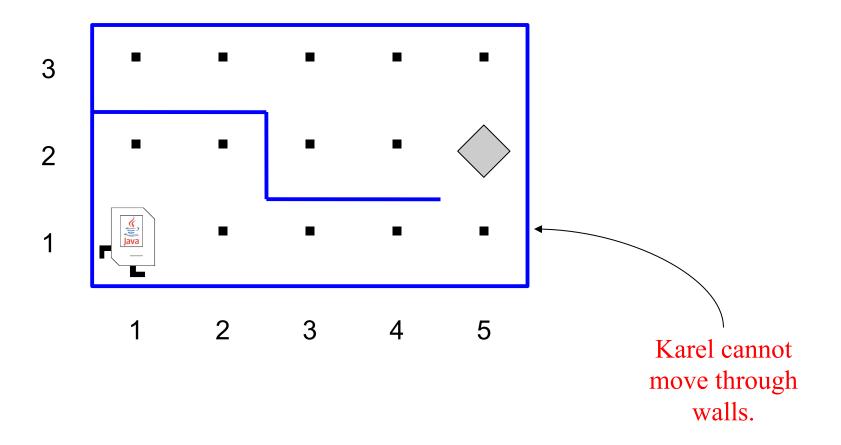


Each column is called an avenue.

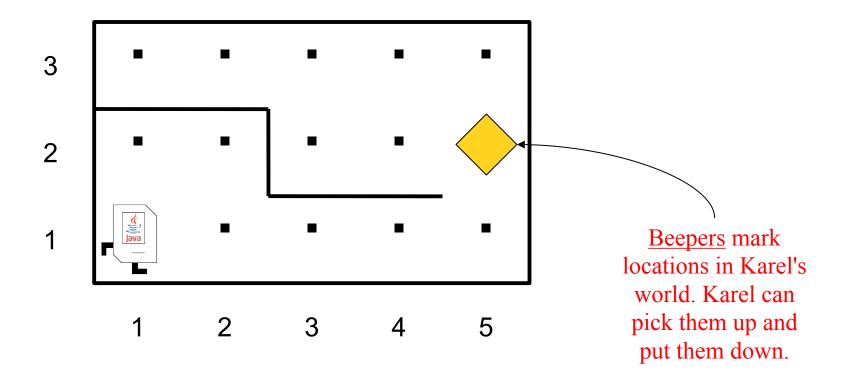
Corners (locations)



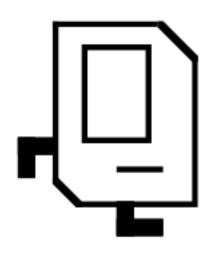
Walls



Beepers



Karel Knows 4 Commands



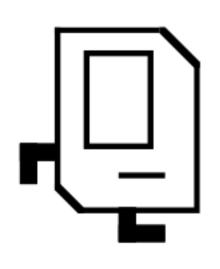
move

turnLeft

putBeeper

pickBeeper

Karel Knows 4 Commands



move

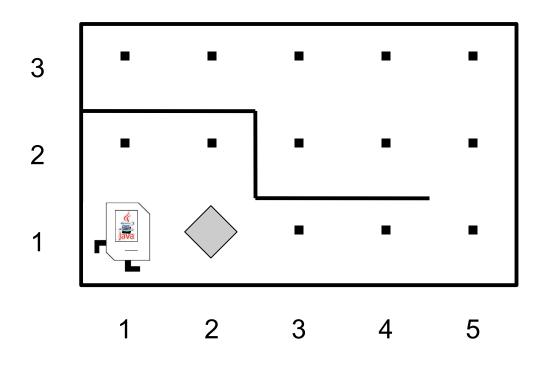
turnLeft

putBeeper

pickBeeper

"methods"

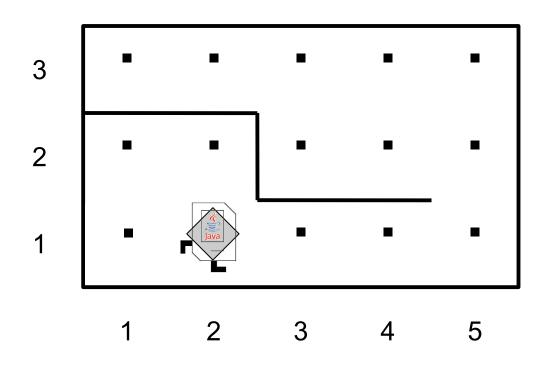
Commands: move



move turnLeft pickBeeper putBeeper

- move makes Karel move forward one square in the direction it is facing.

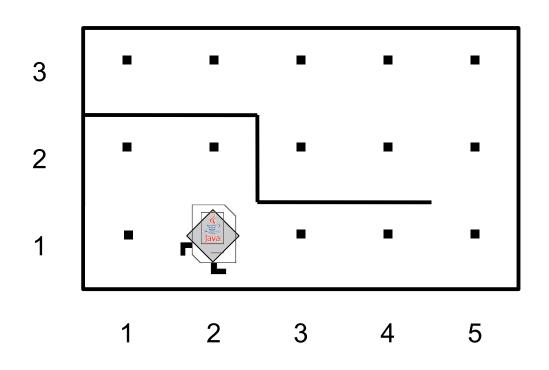
Commands: move



move turnLeft pickBeeper putBeeper

- move makes Karel move forward one square in the direction it is facing.

Commands: turnLeft

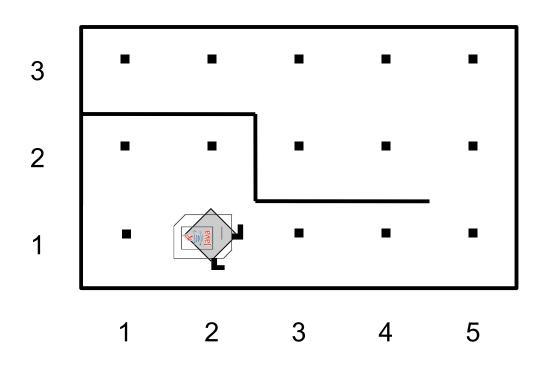


move turnLeft pickBeeper

putBeeper

- turnLeft makes Karel rotate 90° counter-clockwise.
- There is no turnRight command. (Why not?)

Commands: turnLeft

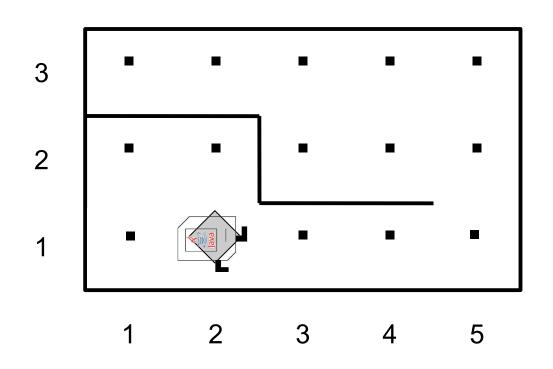


move turnLeft pickBeeper

putBeeper

- turnLeft makes Karel rotate 90° counter-clockwise.
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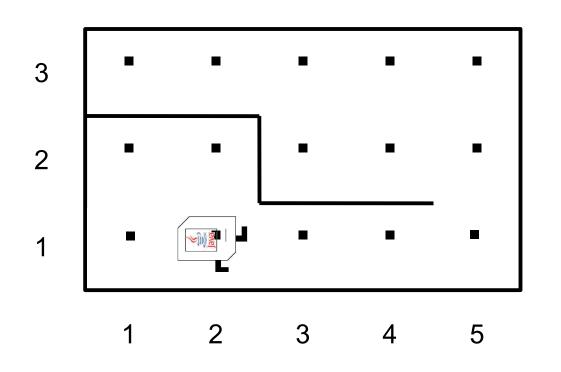
Commands: pickBeeper



move turnLeft pickBeeper putBeeper

pickBeeper makes Karel pick up the beeper at the current corner.
 Karel can hold multiple beepers at a time in its "beeper bag".

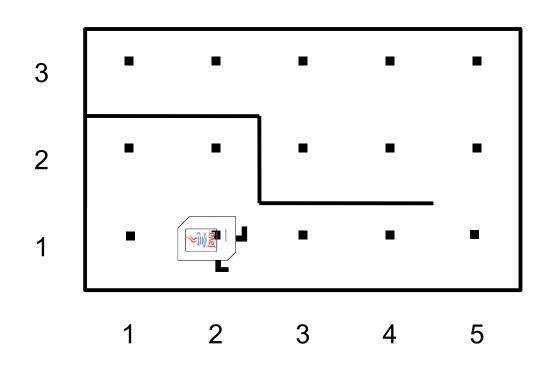
Commands: pickBeeper



move
turnLeft
pickBeeper
putBeeper

pickBeeper makes Karel pick up the beeper at the current corner.
 Karel can hold multiple beepers at a time in its "beeper bag".

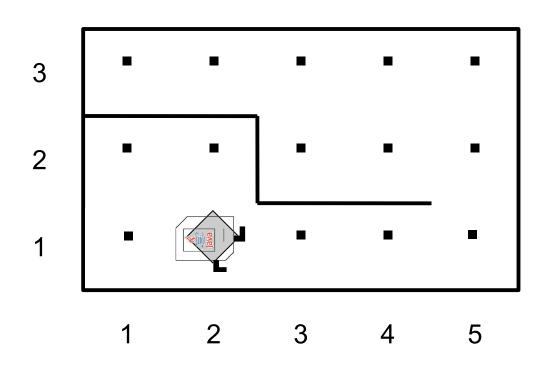
Commands: putBeeper



move turnLeft pickBeeper putBeeper

- putBeeper makes Karel put a beeper down at its current location.
 - pickBeeper and putBeeper are used to move beepers around.

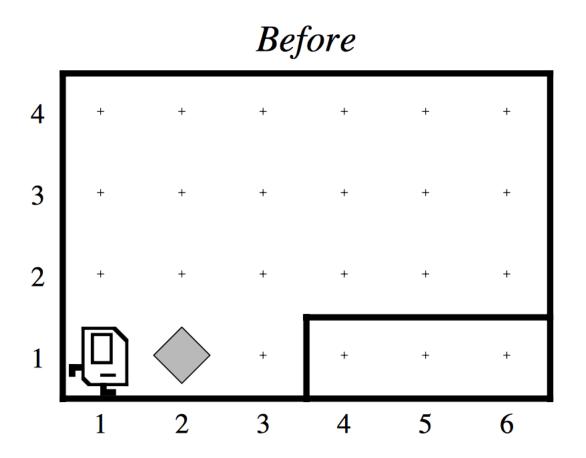
Commands: putBeeper



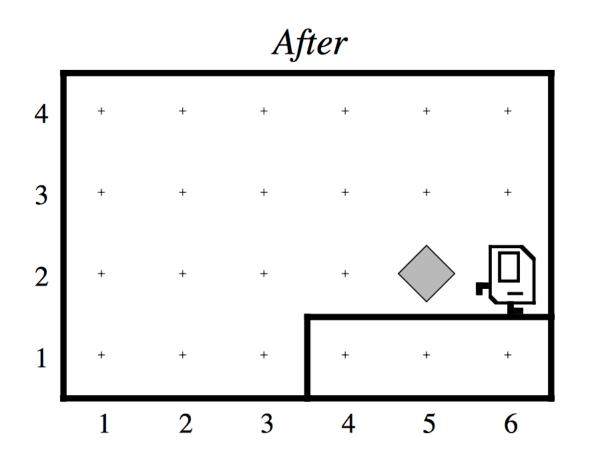
move turnLeft pickBeeper putBeeper

- putBeeper makes Karel put a beeper down at its current location.
 - pickBeeper and putBeeper are used to move beepers around.

Our First Karel Program



Our First Karel Program



Demo

Defining New Commands

We can make new commands (or **methods**) for Karel. This lets us decompose our program into smaller pieces that are easier to understand.

```
private void name() {
    statement;
    statement;
}
```

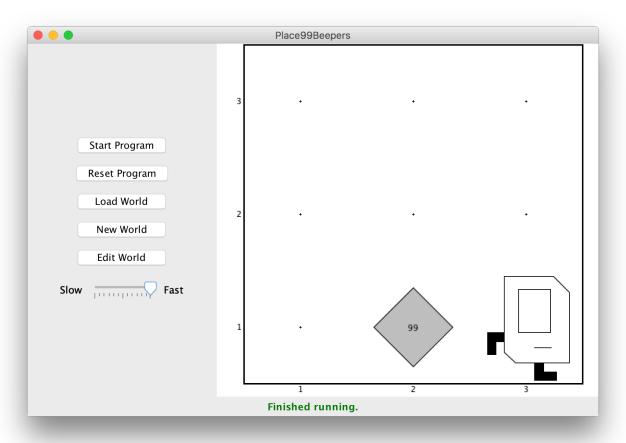
```
For example:
```

```
private void turnRight() {
    turnLeft();
    turnLeft();
    turnLeft();
}
```

Plan For Today

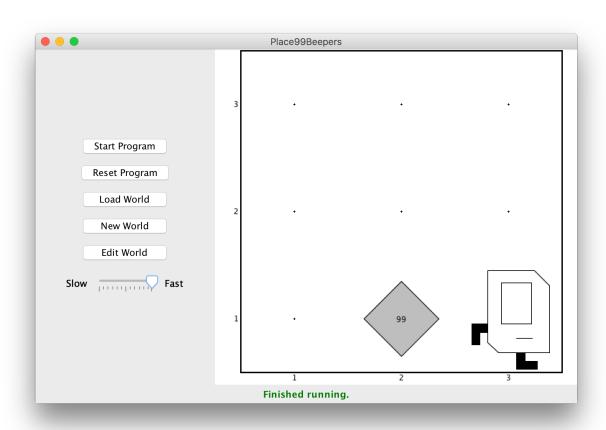
- Announcements
- (Re) Meet Karel the Robot
- Control Flow
 - -For loops
 - -While loops
 - -If/else statements

 I want to make Karel put 99 beepers down on a corner. How do I do this?



Can't just say:

```
move();
putBeeper();
putBeeper();
putBeeper();
...
move();
```



This is too repetitive! Plus, it's difficult to change (e.g. to 25 beepers).

```
Instead, use a for loop:
   for (int i = 0; i < max; i++) {
      statement;
      statement;
      ...
}</pre>
```

Repeats the statements in the body *max* times.

```
Now we can say:
   move();
   for (int i = 0; i < 99; i++) {
        putBeeper();
   move();
                                                Start Program
                                                Reset Program
                                                 Load World
                                                 New World
                                                 Edit World
                                              Slow Fast
```

This is less repetitive, and is easier to change (e.g. to 25 beepers).

Finished running

Some examples of using for loops:

```
// turns Karel right
for (int i = 0; i < 3; i++) {
     turnLeft();
// Moves Karel in a square
for (int i = 0; i < 4; i++) {
     move();
     turnLeft();
```

Plan For Today

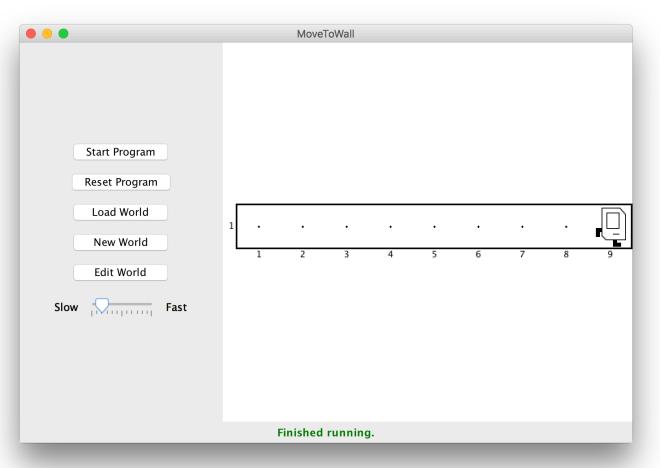
- Announcements
- (Re) Meet Karel the Robot
- Control Flow
 - -For loops
 - -While loops



-If/else statements

Control Flow: While Loops

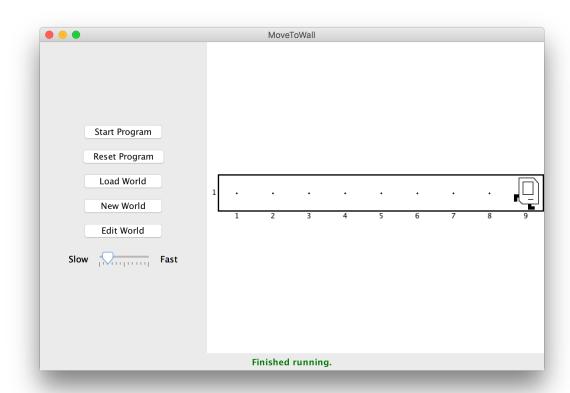
• I want Karel to move until it gets to a wall. How do I do this?



Control Flow: While Loops

Can't just say:

```
move();
move();
move();
move();
```



This is too repetitive! Also, we might not know how far away a wall is. Plus, we want our program to be as *generalized* as possible and work in many different worlds.

Control Flow: While Loops

```
Instead, use a while loop:
  while (condition) {
    statement;
    statement;
}
```

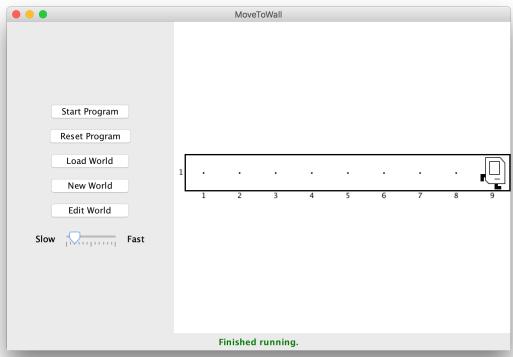
Repeats the statements in the body until *condition* is no longer true. Each time, Karel executes *all statements*, and **then** checks the condition.

Possible Conditions

Test	Opposite	What it checks
<pre>frontIsClear()</pre>	<pre>frontIsBlocked()</pre>	Is there a wall in front of Karel?
leftIsClear()	leftIsBlocked()	Is there a wall to Karel's left?
rightIsClear()	rightIsBlocked()	Is there a wall to Karel's right?
beepersPresent()	noBeepersPresent()	Are there beepers on this corner?
beepersInBag()	noBeepersInBag()	Any there beepers in Karel's bag?
<pre>facingNorth()</pre>	notFacingNorth()	Is Karel facing north?
<pre>facingEast()</pre>	notFacingEast()	Is Karel facing east?
facingSouth()	notFacingSouth()	Is Karel facing south?
<pre>facingWest()</pre>	notFacingWest()	Is Karel facing west?

This is **Table 1** on page 18 of the Karel coursereader.

Control Flow: While Loops



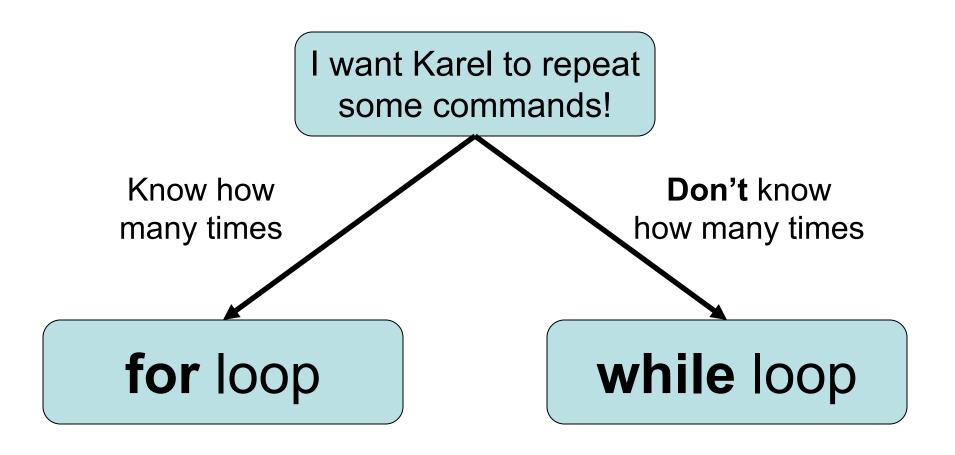
This is less repetitive, and it works in any size world!

Control Flow: While Loops

while loops can have compound conditions as well:

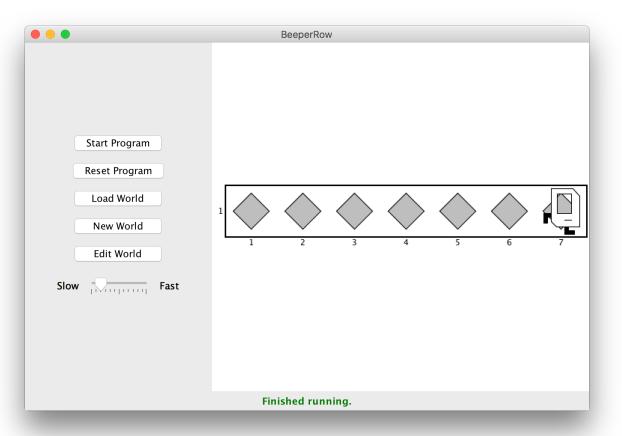
```
// "and"
while (frontIsClear() && beepersPresent()) {
// "or"
while (leftIsClear() | rightIsClear()) {
```

Loops Overview



Loops Overview

• I want Karel to put down a row of beepers until it reaches a wall. How do I do this?



Demo

Fencepost Problem



8 fence segments, but 9 posts!

Fencepost Structure

The fencepost structure is useful when you want to loop a set of statements, but do one part of that set 1 additional time.

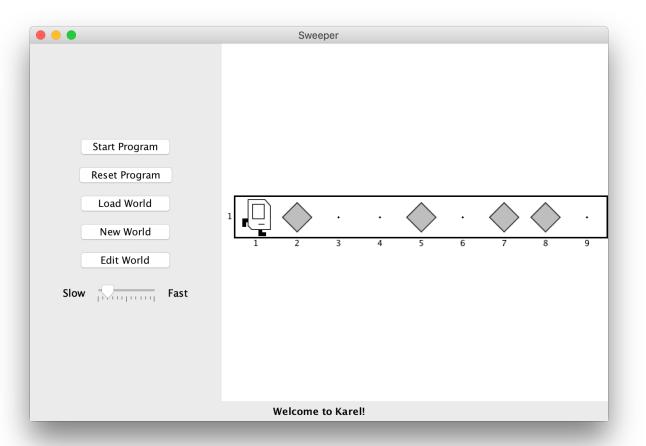
```
// post
putBeeper();
while (frontIsClear()) {
                           // fence
   move();
                           // post
   putBeeper();
while (frontIsClear()) {
   putBeeper();
                           // post
                           // fence
   move();
putBeeper();
                           // post
```

Plan For Today

- Announcements
- (Re) Meet Karel the Robot
- Control Flow
 - -For loops
 - -While loops
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• I want to make Karel clean up all beepers in front of it until it reaches a wall. How do I do this?



```
Can't just say:
   while (frontIsClear()) {
        move();
        pickBeeper();
                                             Error: pickBeeper: No beepers on this corner
                                             Sweeper.run(), line 15
                                                         OK
```

This may crash, because Karel cannot pick up beepers if there aren't any. We don't always want Karel to pick up beepers; just when there is a beeper to pick up.

```
Instead, use an if statement:
   if (condition) {
      statement;
      statement;
      ...
}
```

Runs the statements in the body *once* if *condition* is true.

You can also add an **else** statement:

```
if (condition) {
   statement;
   statement;
} else {
   statement;
   statement;
```

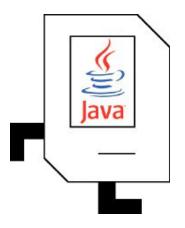
Runs the first group of statements if *condition* is true; otherwise, runs the second group of statements.

```
Now we can say:
   while (frontIsClear()) {
         move();
         if (beepersPresent()) {
                  pickBeeper();
                                                   Start Program
                                                   Reset Program
                                                   Load World
                                                    New World
                                                    Edit World
                                                 Slow Fast
                                                                Welcome to Karel!
```

Now, Karel won't crash because it will only pickBeeper if there is one.

Recap

- Announcements
- (Re) Meet Karel the Robot
- Control Flow
 - -For loops
 - -While loops
 - -If/else statements



Next time: Karel Problem-Solving