

Lecture 13

Ex 1.

Ex 1.  
11):  $\begin{cases} \dot{x} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} x \\ y = \begin{bmatrix} 1 & 0 \end{bmatrix} x \end{cases}; \quad O = \begin{bmatrix} C \\ A \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix}$   
 $\det(O) = 0 \Rightarrow \text{non observable}$

(6):  $\begin{cases} \dot{x} = \begin{bmatrix} -1 & 0 \\ 0 & -2 \end{bmatrix} x \\ y = \begin{bmatrix} 1 & 1 \end{bmatrix} x \end{cases}$  ;  $\mathcal{O} = \begin{bmatrix} C \\ A \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$   
 $\det(\mathcal{O}) = -1 \Rightarrow \text{Observable "}$

Ex 2.

$$\dot{x} = \begin{pmatrix} 7 & -9 \\ 6 & -8 \end{pmatrix} x + \begin{pmatrix} 4 \\ 3 \end{pmatrix} u \quad ; \quad u = Fx = \begin{pmatrix} -2 & 2 \end{pmatrix} x$$

2) Design full order observer

$$O \cdot \begin{bmatrix} C \\ CA \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 13 & -17 \end{bmatrix}$$

$$t_2 = \frac{1}{-30} \begin{bmatrix} -17 & -1 \\ -13 & 1 \end{bmatrix} \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{30} \\ -\frac{1}{30} \end{pmatrix}$$

$$t_1 = At_2 = \begin{bmatrix} 7 & -9 \\ 6 & -8 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{30} \\ -\frac{1}{30} \end{bmatrix} = \begin{bmatrix} \frac{16}{30} \\ \frac{14}{30} \end{bmatrix}$$

$$T = \begin{bmatrix} \frac{16}{30} & \frac{1}{30} \\ \frac{14}{30} & -\frac{1}{30} \end{bmatrix} \quad T^{-1} = \begin{bmatrix} 1 & 1 \\ 14 & -16 \end{bmatrix}$$

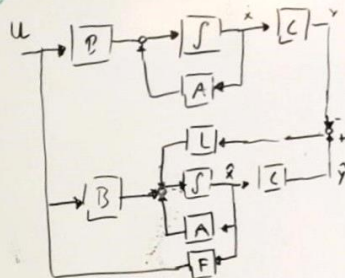
$$A_0 = T^{-1}AT = \begin{bmatrix} 1 & 1 \\ 14 & -16 \end{bmatrix} \begin{bmatrix} 7 & -9 \\ 6 & -8 \end{bmatrix} \begin{bmatrix} \frac{16}{30} & \frac{1}{30} \\ \frac{14}{50} & \frac{1}{30} \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 2 & 0 \end{bmatrix} \Rightarrow \det(\lambda I - A) = \lambda^2 + \lambda - 2$$

$$G_0 = (T = [1 \ 1] \begin{bmatrix} \frac{16}{30} & \frac{1}{30} \\ \frac{14}{30} & -\frac{1}{30} \end{bmatrix}) = [1 \ 0]$$

$$L_0 = \begin{pmatrix} 1 & -9 \\ -2 & -20 \end{pmatrix} = \begin{pmatrix} -8 \\ -22 \end{pmatrix}$$

$$L = TL_0 = \begin{bmatrix} \frac{16}{30} & \frac{1}{30} \\ \frac{14}{30} & -\frac{1}{30} \end{bmatrix} \cdot \begin{bmatrix} -8 \\ -22 \end{bmatrix} = \begin{bmatrix} -5 \\ -3 \end{bmatrix}$$

2) Draw diagram



3) Verify by computing eigenvalues

for closed loop

$$\begin{pmatrix} \dot{x} \\ \dot{\hat{x}} \end{pmatrix} = \begin{pmatrix} A & BF \\ -Lc & A+Lc+BF \end{pmatrix} \begin{pmatrix} x \\ \hat{x} \end{pmatrix}$$

$$\text{eig} \begin{pmatrix} \dot{x} \\ \dot{z} \end{pmatrix} = \lambda \begin{Bmatrix} -5 \\ -7 \\ -2 \\ -1 \end{Bmatrix} \left. \vphantom{\begin{Bmatrix} -5 \\ -7 \\ -2 \\ -1 \end{Bmatrix}} \right\} \begin{array}{l} \text{De nye polar} \\ \text{De gamle polar} \end{array}$$

$$\text{eig}(A+LC) = \begin{bmatrix} -4 \\ -5 \end{bmatrix}$$