

# High-Speed Electronics in Practice

SHUAI ZHANG

SELMA LAGERLOFS VEJ 312

9220 AALBORG ØST

(sz@es.aau.dk)

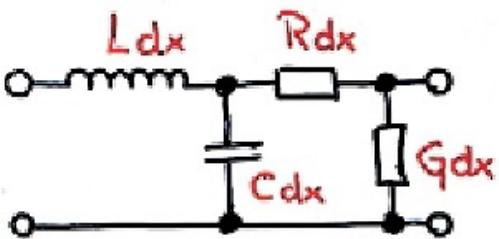
# High-Speed Electronics in Practice

## **MM10. Solution for Harmonic Signals**

# Recall for MM7

## General formula

### Model for cable



### Telegraph equation

Lossless  $R=G=0$

$$\frac{\partial V}{\partial x} = -L \cdot \frac{\partial I}{\partial t}$$

$$\frac{\partial I}{\partial x} = -C \cdot \frac{\partial V}{\partial t}$$

### Wave equation

Lossless  
 $R=G=0$   $\frac{\partial^2 V}{\partial x^2} = \frac{1}{V^2} \frac{\partial^2 V}{\partial t^2}$

$$\frac{\partial^2 I}{\partial x^2} = \frac{1}{V^2} \frac{\partial^2 I}{\partial t^2}$$

### Solutions

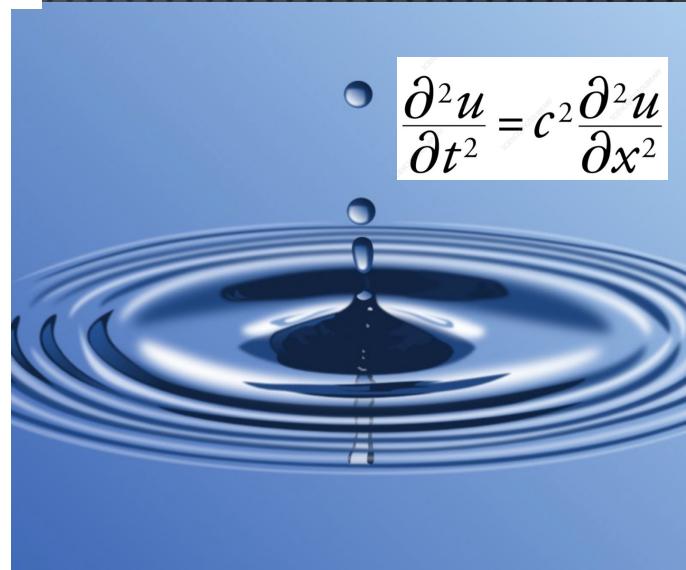
$$V = V^+(t - \frac{x}{V}) + V^-(t + \frac{x}{V})$$

$$I = I^+(t - \frac{x}{V}) + I^-(t + \frac{x}{V})$$

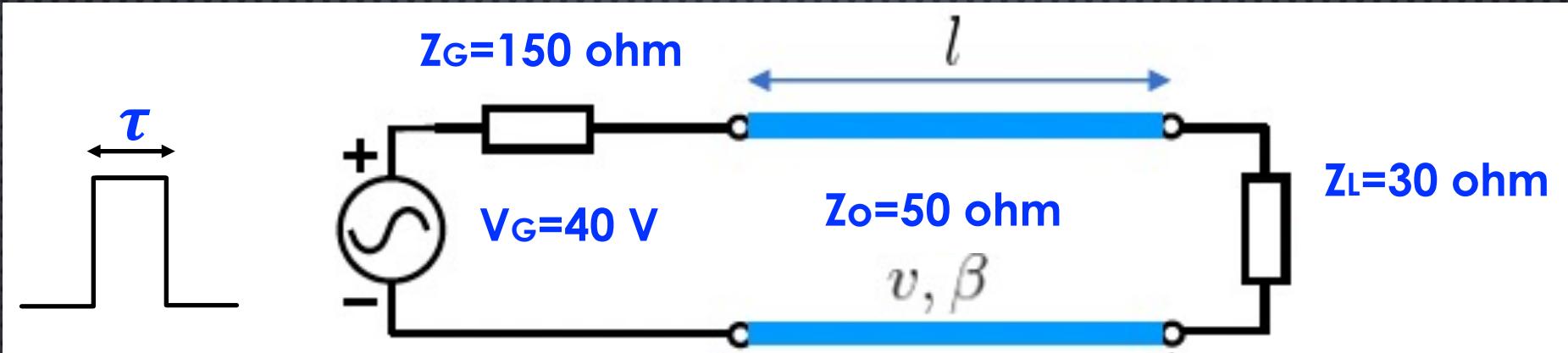
$$I = \frac{1}{Z_0} (V^+(t - \frac{x}{V}) - V^-(t + \frac{x}{V}))$$

$$V = \frac{1}{\sqrt{LC}} \quad [\text{m/s}]$$

$$Z_0 = \sqrt{\frac{L}{C}} \quad [\Omega]$$



# Transient analysis (Time-Domain)



There are many ways to calculate it. We can also apply transmission line theory that gives more details.

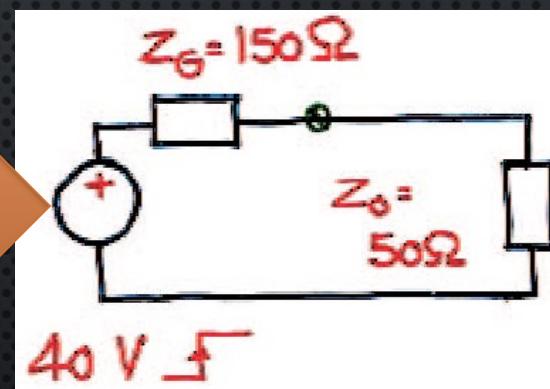
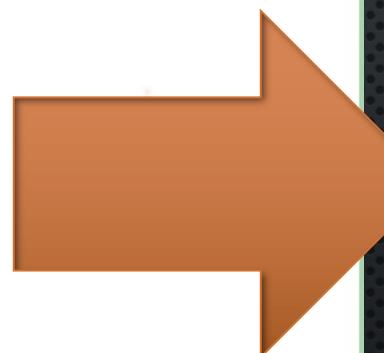
Start:

$$V^+ = 40 \cdot \frac{50}{150+50} = \frac{2000}{200} = 10 \text{ V}$$

$$I^+ = 40 \cdot \frac{1}{150+50} = \frac{40}{200} = 0,2 \text{ A}$$

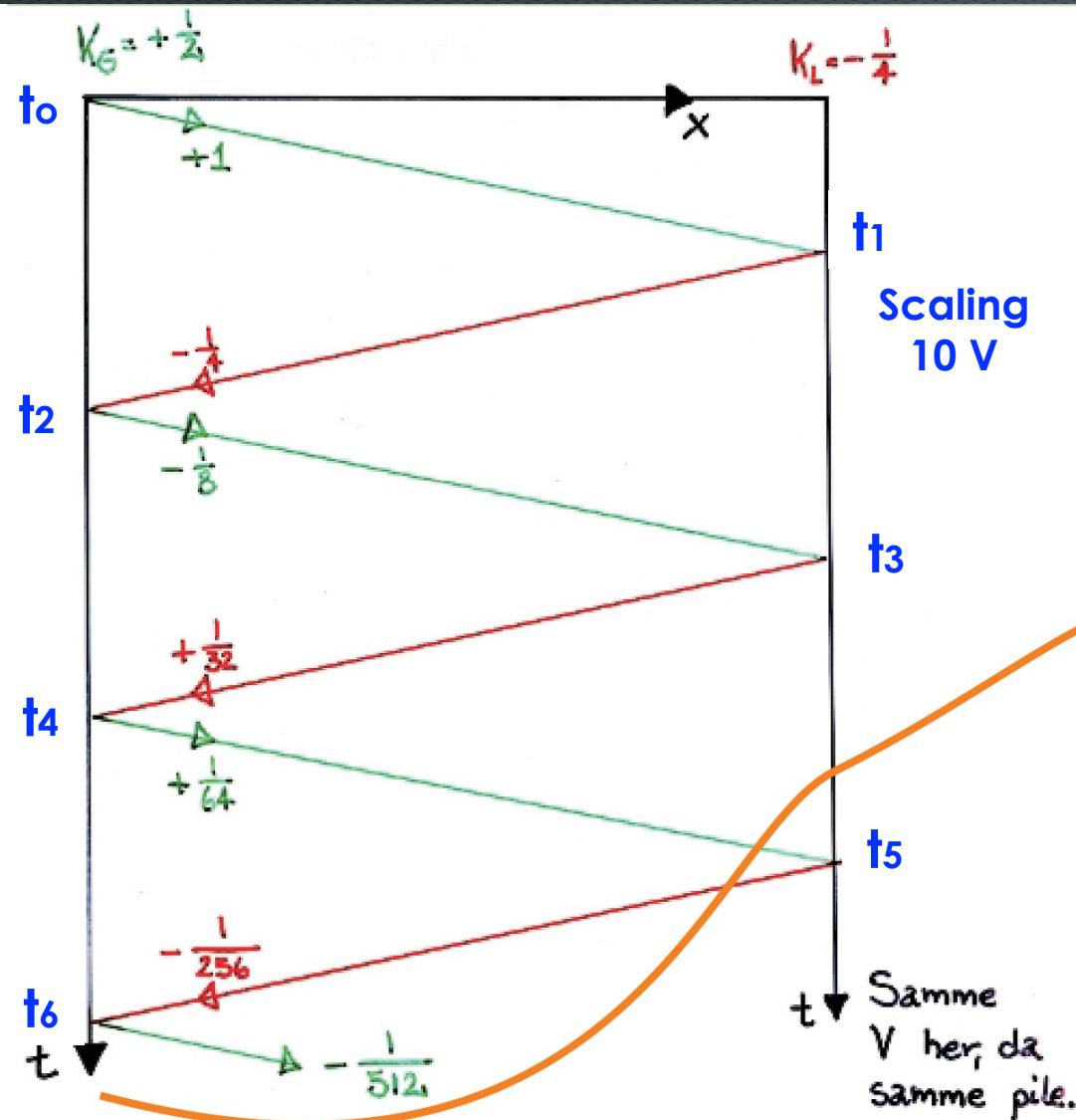
$$K_G = \frac{150 - 50}{150 + 50} = +\frac{1}{2}$$

$$K_L = \frac{30 - 50}{30 + 50} = -\frac{1}{4}$$



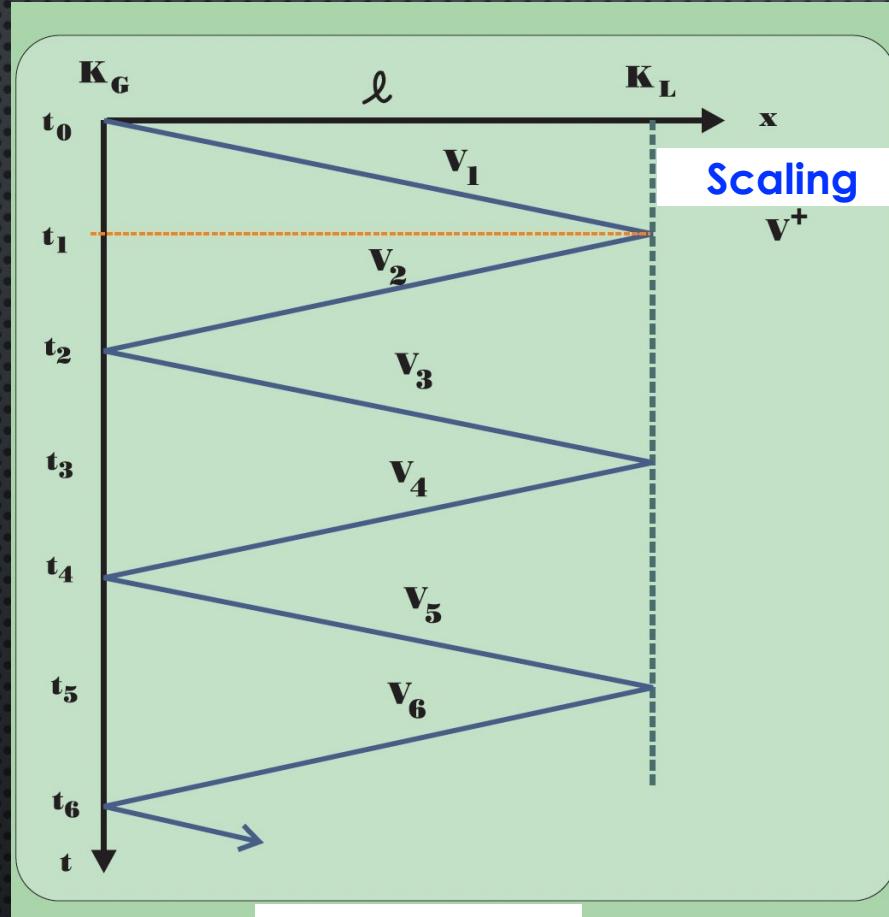
## Reflection map

# Reflection Diagram



$$\begin{aligned}
 V_{\text{TOTAL}} @ S &= 10 \cdot \\
 1 + (-\frac{1}{8}) + \frac{1}{2}(-\frac{1}{4}) + \frac{1}{2}(-\frac{1}{4})^2 + (\frac{1}{2})^2(-\frac{1}{4})^2 + \dots & \\
 = \left( \sum_{n=0}^{\infty} (-\frac{1}{8})^n + (-\frac{1}{4}) \sum_{n=0}^{\infty} (-\frac{1}{8})^n \right) \cdot 10 &= \frac{3}{4} \cdot \frac{5}{3} \cdot 10 = \frac{25}{3} \quad V
 \end{aligned}$$

## Reflection map



It is smart and clear to calculate the voltage (current) and time in same tables.

### Voltage calculation

$$V_1 = 1$$

$$V_2 = V_1 \cdot K_L$$

$$V_3 = V_2 \cdot K_G$$

$$V_4 = V_3 \cdot K_L$$

$$V_5 = V_4 \cdot K_G$$

$$V_6 = V_5 \cdot K_L$$

If it is current, it should apply:

$$K'_L = -K_L$$

$$K'_G = -K_G$$

### Voltage

### Time calculation

$$t_0 = 0$$

$$t_1 = t_0 + \Delta$$

$$t_2 = t_1 + \Delta$$

$$t_3 = t_2 + \Delta$$

$$t_4 = t_3 + \Delta$$

$$t_5 = t_4 + \Delta$$

$$t_6 = t_5 + \Delta$$

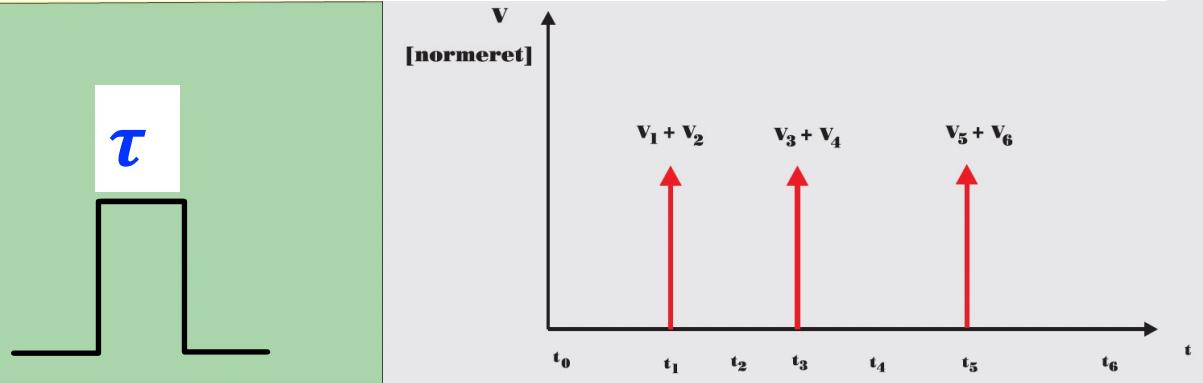
where

$$\Delta = \frac{\ell}{v} \quad [\text{s}]$$

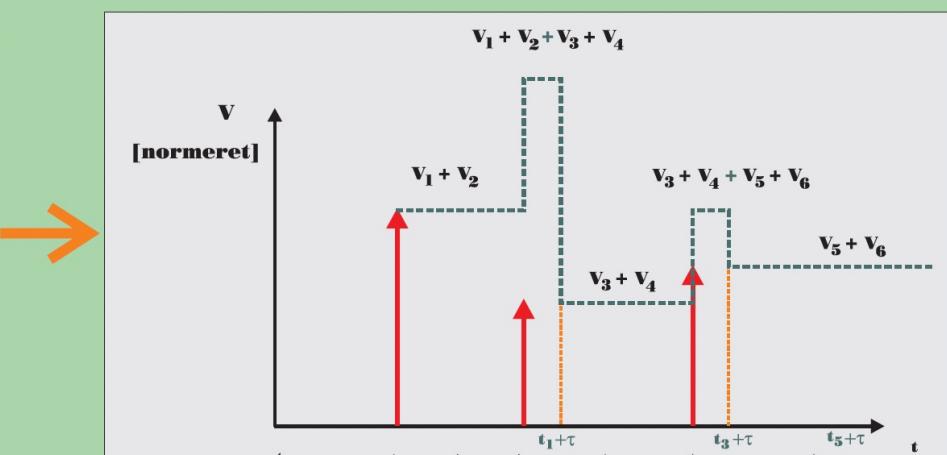
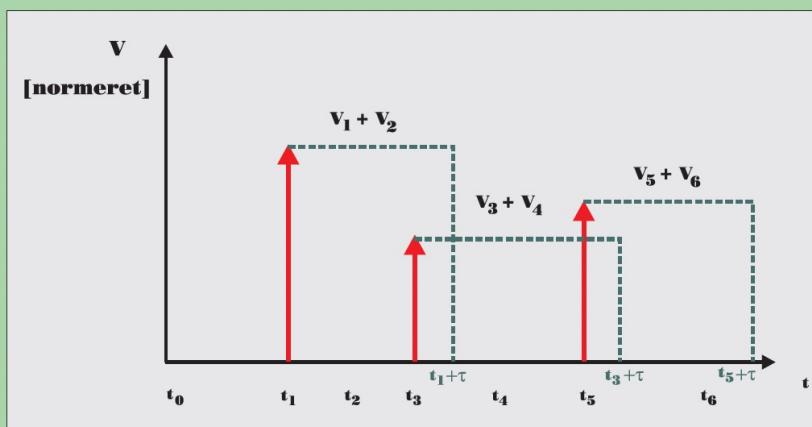
Time

## Stick diagram

Calculate the curve form with stick diagram



Make the wave leading edge with stick



Extend stick to full pulse width

Sum the impulse overlap part

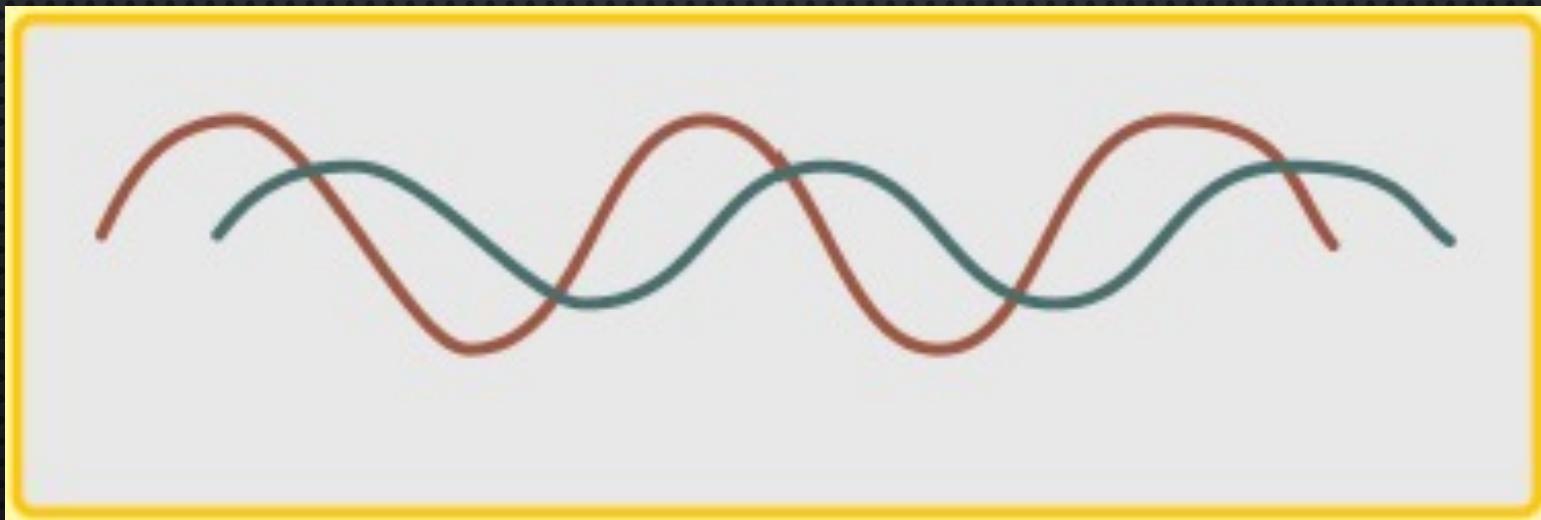
# SOLUTION FOR HARMONIC SIGNALS

Targets:

1. Read “Grundlæggende Transmissionsledningsteori” (Page 23-38, 105-108) (before or after the lecture)
2. Be able to calculate with general impedance and reflection coefficient solutions for sine signals (lecture)
3. Finish the exercise (after the lecture)

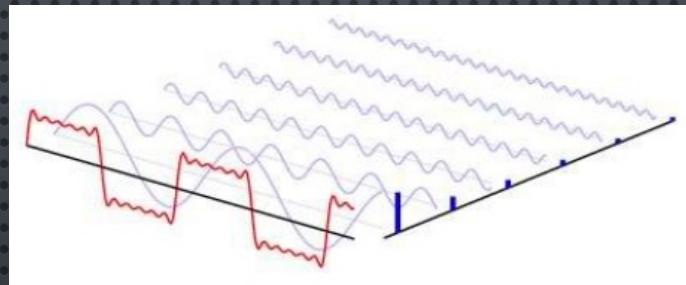
# Sine Signals

- Signals of the form  $\cos(\omega t)$  or  $\sin(\omega t)$  are called sinusoidal signals or simply sine signals.
- A weighted sum of delayed sine signals with the same frequency is also a sine signal.



# Sine Signals

- All signals can be expressed as a weighted sum of sine signals with different frequencies.



- For linear systems, the superposition principle applies.
- A sine signal that has passed through a linear system is also a sine signal.
- It is therefore interesting to investigate the behavior of systems when they are influenced by a sinusoidal signal.

# Sine Signals in KSN

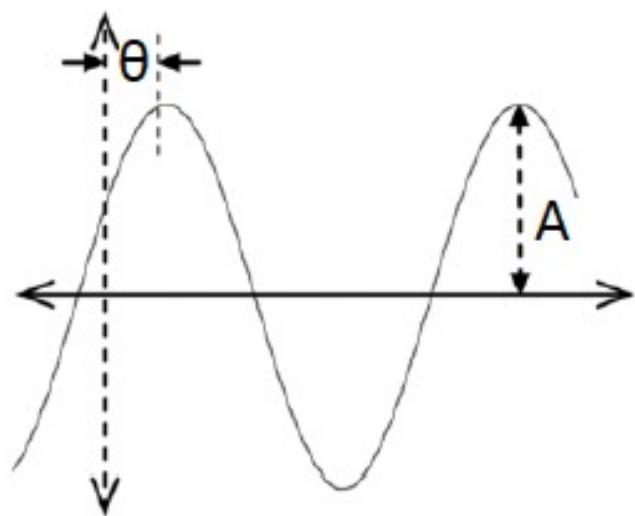
**KSN**  
**Kompleks Symbolsk Notation**

Also called “jw-method”.  
KSN is used for sine and harmonic signals.

# Sine Signals in KSN

Sine signals are mapped onto vectors in the complex number plane

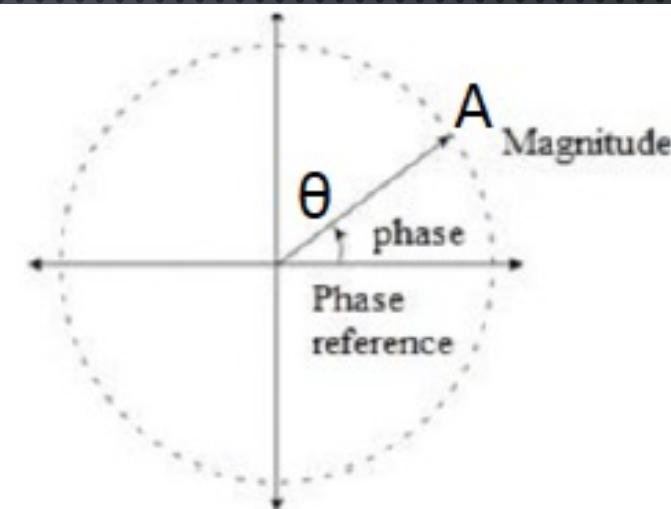
$$A \cos(\omega t + \theta)$$



a) Sinusoidal waveform of a signal

$$Ae^{j(\omega t+\theta)}$$

$$A\angle\theta$$



b) Polar representation of the same signal

$$\text{Re}\{Ae^{j(\omega t+\theta)}\} = \text{Re}\{A(\cos(\omega t + \theta) + j \sin(\omega t + \theta))\} = f(t) = A \cos(\omega t + \theta)$$

$\omega = 2\pi f$

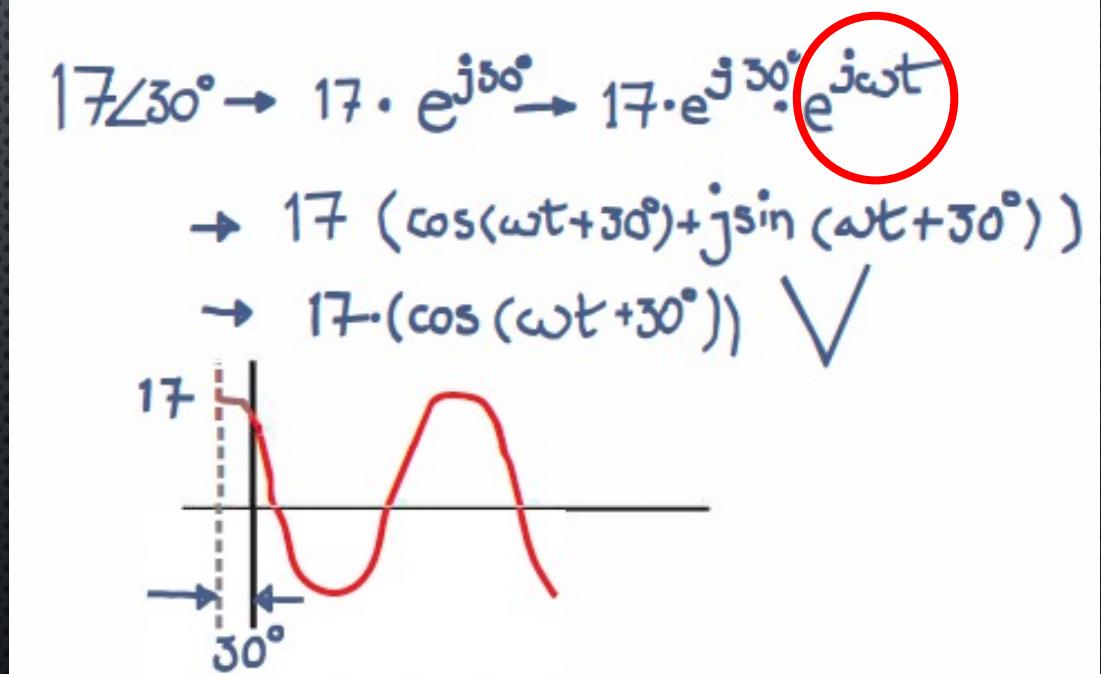
frekvens  
signal amplitude fase

$$e^{jb} = \cos b + j \sin b$$

# Sine Signals in KSN

$$17 \angle 30^\circ \text{ V}$$

- It cannot be seen from the notation what the frequency is. The phase reference is hidden.
- It is understood whether it is effective value or peak value that is indicated.
- All signals carried the same frequency.



# Solution Types

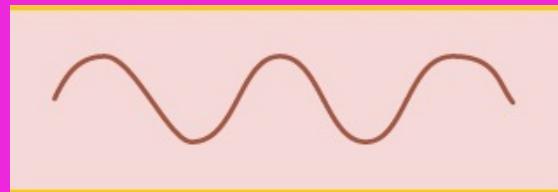
Statistic Solution

Statistic solution.  
Solution for DC signal

Stationary Solution

Stationary solution.  
Also called harmonic solution.  
Stationary AC mode is a dynamic mode where  
the signals in the system with the same series of  
values periodically to infinity.

**KSN**



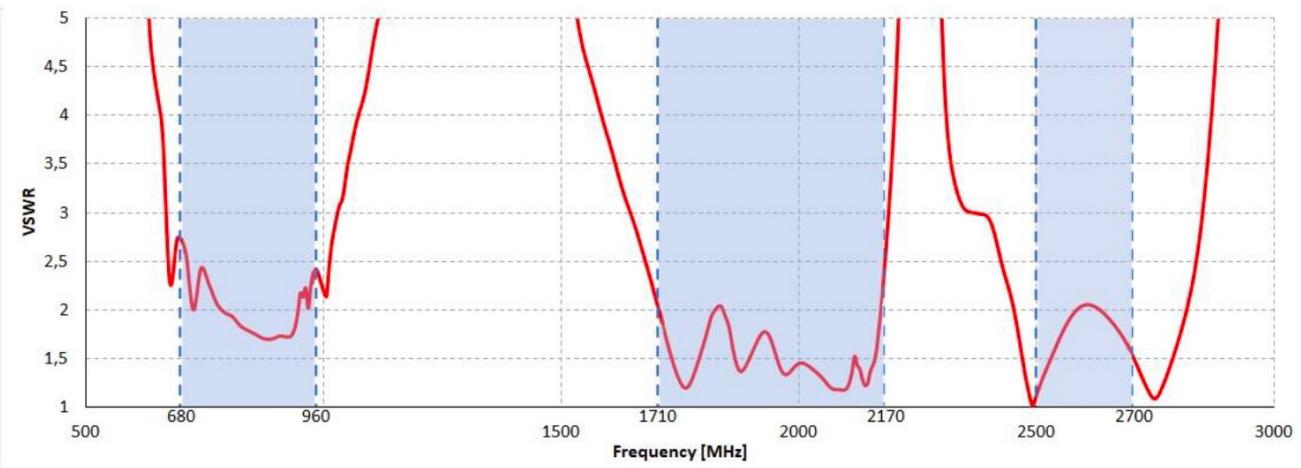
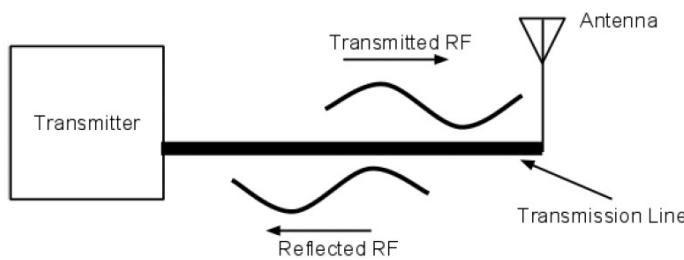
Transient Solution

Transient solution.  
Solution in time domain.  
Typically, not sine signal.



# Generalized Impedance

# Examples for PCB design



# Stubs for Load Impedance



Lukket stub

$$Z = 0$$

$$Y = \infty$$

$$K_L = \frac{Z - Z_0}{Z + Z_0} = -1$$



$$\frac{l}{\lambda} \quad Z(x)$$

$$0 \quad 0$$

$$\frac{\lambda}{8} \quad jX \text{ (spole)}$$

$$\frac{\lambda}{4} \quad \infty$$

$$\frac{3}{8}\lambda \quad -jX \text{ (kondensator)}$$

$$\frac{\lambda}{2} \quad 0$$

Quarter wavelength difference

$$Z(x) = Z_0 \cdot \frac{1 + K(x)}{1 - K(x)} \quad [\Omega]$$

$$K(x) = K_L \cdot e^{j2\pi x} \quad [-]$$

$$K_L = \frac{Z_L - Z_0}{Z_L + Z_0} \quad [-]$$



Aben stub

$$Z = \infty$$

$$Y = 0$$

$$K_L = \frac{Z - Z_0}{Z + Z_0} = +1$$



$$\frac{l}{\lambda} \quad Z(x)$$

$$0 \quad \infty$$

$$\frac{\lambda}{8} \quad -jX \text{ (kond.)}$$

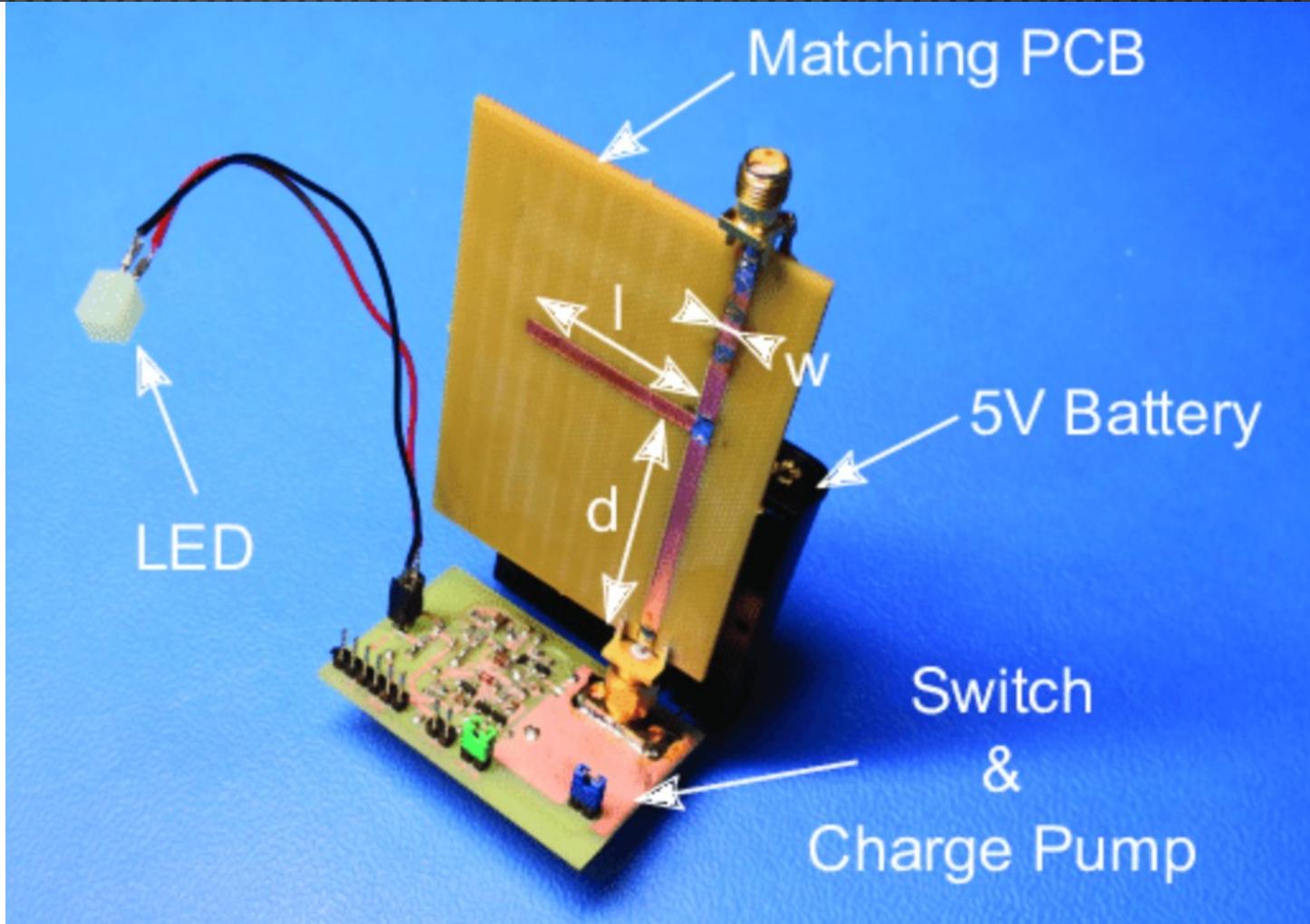
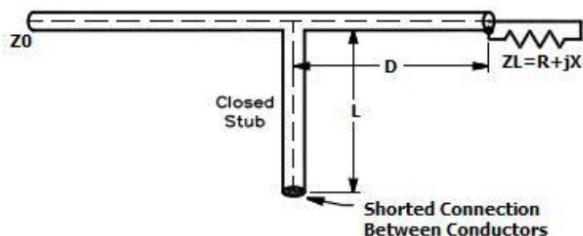
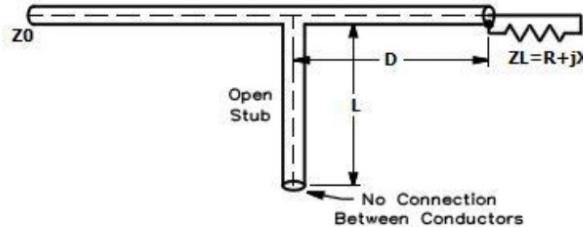
$$\frac{\lambda}{4} \quad 0$$

$$\frac{3}{8}\lambda \quad jX \text{ (spole)}$$

$$\frac{\lambda}{2} \quad \infty$$

# Stubs for Load Impedance

## Examples for PCB design



# Stubs for Load Impedance

## Example 2 for PCB design

