

High-Speed Electronics in Practice

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SELMA LAGERLOFS VEJ 312

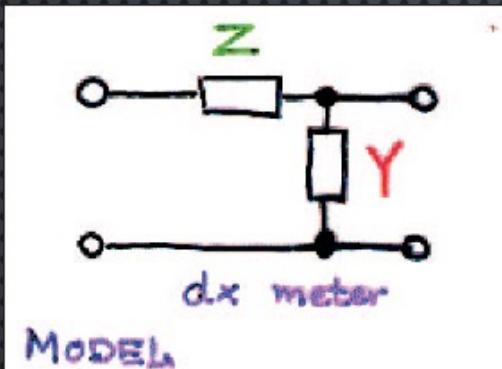
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High-Speed Electronics in Practice

MM12. Smith Chart

Recall



MODEL

KSN

$$Z = R + j\omega L \quad [\Omega/m]$$

$$Y = G + j\omega C \quad [S/m]$$

For Lossless model

$$Z = j\omega L$$

$$Y = j\omega C$$

Primary cable constant $L, C \quad [H/m, F/m]$

Secondary cable constant

$$Z_0 = \sqrt{\frac{L}{C}} \quad [\Omega]$$

$$\gamma = \alpha + j\beta \quad [m^{-1}]$$

$$\alpha = 0$$

$$\beta = \omega \sqrt{LC} = \frac{\omega}{V} \quad [Np/m] \\ \quad [rad/m]$$

Solutions

$$V(x) = V^+ e^{-j\beta x} + V^- e^{+j\beta x}$$

$$I(x) = I^+ e^{-j\beta x} + I^- e^{+j\beta x}$$

$$= \frac{1}{Z_0} [V^+ e^{-j\beta x} - V^- e^{+j\beta x}]$$

Recall

$$K_L = \frac{Z_L - Z_0}{Z_L + Z_0}$$

$$K(x) = K_L \cdot e^{2\gamma x}$$

$$K(x) = \frac{Z(x) - Z_0}{Z(x) + Z_0}$$

$$Z(x) = Z_0 \cdot \frac{1 + K(x)}{1 - K(x)}$$

[·]

Lossless
($= K_L \cdot e^{2j\beta x}$)

[·]

[Ω]

$$V = \frac{1}{\sqrt{LC}} = \frac{\omega}{\beta} \quad [m/s] \quad \text{Lossless}$$

$$\lambda = \frac{2\pi}{\beta} = \frac{V}{f} \quad [m]$$

$$V_{max} = C = 300 \text{ m/s}$$



Recall

1. Calculate between the primary and secondary cable constant

$$\mathbf{L}, \mathbf{C}, \mathbf{R}, \mathbf{G} \longleftrightarrow \mathbf{Z}_0, \gamma$$

2. Calculate K_L from Z_0 and Z_L

3. Calculate between the impedance and reflection coefficient.

$$\mathbf{K}(x) \longleftrightarrow \mathbf{Z}(x)$$

4. Calculate voltage and current

$$\mathbf{V}(x), \mathbf{I}(x), \mathbf{V}^+(x), \mathbf{V}^-(x), \mathbf{I}^+(x), \mathbf{I}^-(x)$$

5. Calculate transmission and loss power

$$\mathbf{P}_{\text{TRANS}}(x), \mathbf{P}_{\text{TAB}}(x)$$

SMITH CHART

Targets:

1. Read “Grundlæggende Transmissionsledningsteori” (Page 53-84) (before or after the lecture)
2. Be able to calculate for single stub impedance transformer (lecture)
3. Finish the exercise (after the lecture)

Smith Chart

An Improved TRANSMISSION LINE CALCULATOR

An extension of the "calculator" originally published in ELECTRONICS in January 1939.

New parameters have been added and accuracy has been improved

This was developed and has been in use in the Bell Telephone Laboratories for a number of years a particularly useful form of calculator for solving radio transmission line problems. The calculator was originally described in *ELECTRONICS*⁸ where it was presented in "cut-out" form. The impetus given to radio development by the war has promoted considerable interest in this calculator among engineers and research workers, particularly in the field of u-h-f technique where electrical measurements must be made indirectly. Accordingly, it was felt desirable to again present at this time a comprehensive description of the device. Several new and useful parameters have been added to the original design and the entire calculator has been redrawn to improve its accuracy and facilitate reading the coordinates.

The calculator is, fundamentally, a special kind of impedance coordinate system, mechanically arranged with respect to a set of movable scales to portray the relationship of impedance at any point along a uniform open wire or coaxial transmission line to the impedance at any shunt point and to the several other interesting parameters. These other parameters are plotted as scales along the radial arm and around the rim of the calculator, both of which are arranged to be independently adjustable with respect to the main impedance coordinates. All of the para-

meters are related to one another and specific solutions to a given problem are obtainable through the use of an adjustable cross-hair index along the radial arm, which extends to intersect the scales around the rim. The parameters which are plotted on the calculator include:

I. Impedance, or admittance, at any point along the line. (a) Reflection coefficient magnitude, (b) Reflection coefficient angle in degrees.

II. Length of line between any two points in wavelengths.

III. Attenuation between any two points in decibels. (a) Standing wave loss coefficient, (b) Reflection loss in decibels.

IV. Voltage or current standing

wave ratio, normally considered to be that impedance which would be measured if the line were cut at that point and measurements were made looking into the line section which is connected to the load.

Impedance—General Considerations

The impedances at any point along the line and the power reaching this point from the generator completely determine the magnitude of the current and voltage and their phase relationship at that point. For a steady state, the generator impedance itself, as well as the impedance looking towards the generator from any point along the line where it may have been considered to have been cut,



wave ratio, (a) Standing wave ratio in decibels, (b) Limits of voltage and current due to standing waves.

A brief discussion of each of the several parameters and the manner in which they may be evaluated from the calculator will be given.

The impedance at any point along a transmission line is, unless other-

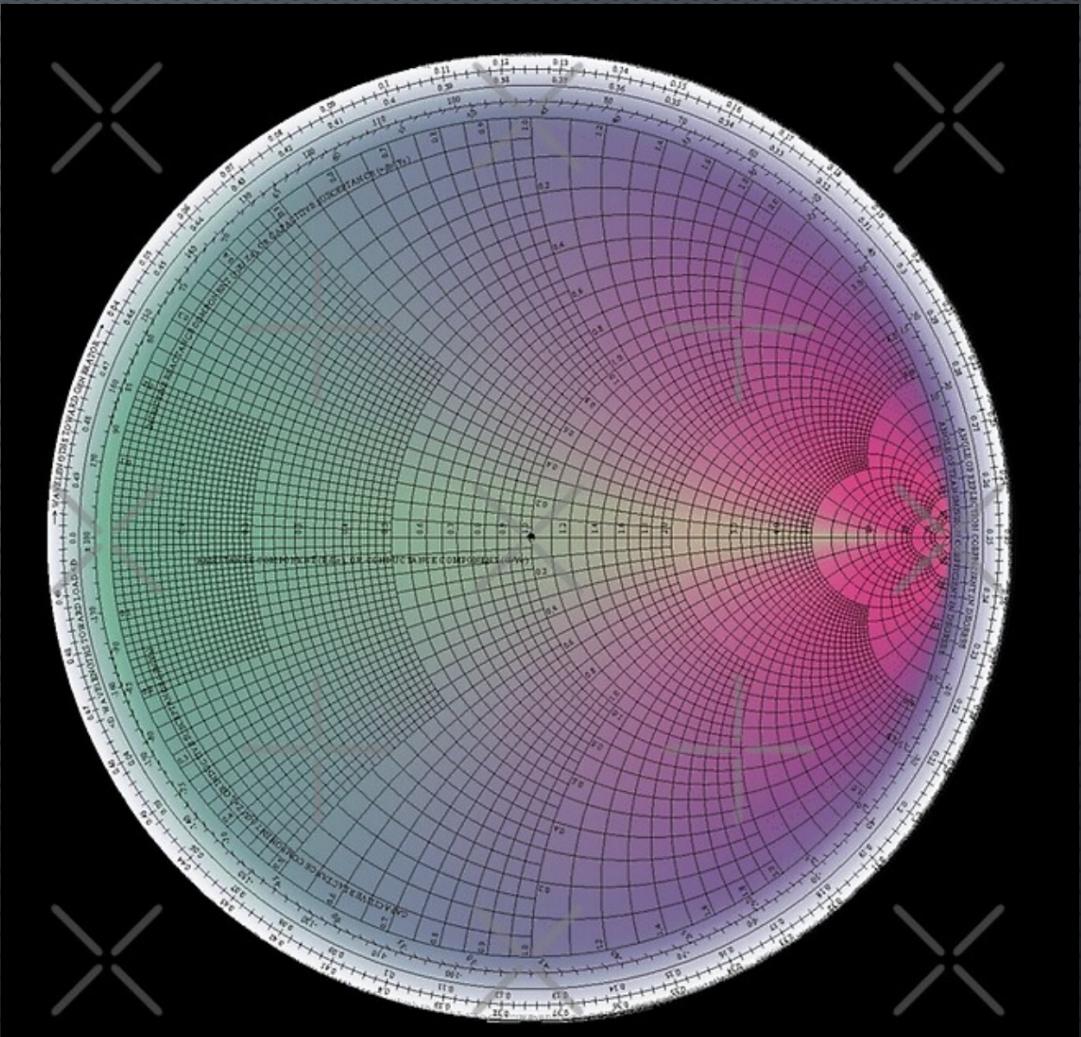
wise defined, normally considered to be that impedance which would be measured if the line were cut at that point and measurements were made looking into the line section which is connected to the load.

In other words, the generator impedance can have no effect upon the standing wave position or amplitude ratio or upon the relation of the standing wave to the impedance of

⁸ Smith, Phillip H. Transmission Line Calculator, *ELECTRONICS*, January 1939.

Article by Phillip H. Smith
in January 1939.

Smith Chart



Smith Chart

$$Z_n = \frac{1 + K}{1 - K} = \frac{(1+U) + jV}{(1-U) - jV}$$

$$r + jx = \frac{1 - U^2 - V^2}{(1-U)^2 + V^2} + j \frac{2V}{(1-U)^2 + V^2}$$

PLANER:
 $Z = r + jx$
 $K = U + jV$

Smith Chart

r-cirkler

$$r = \frac{1 - u^2 - v^2}{(1-u)^2 + v^2}$$

$$\Rightarrow (u - \frac{r}{r+1})^2 + v^2 = (\frac{1}{r+1})^2$$

CENTRUM: $(\frac{r}{r+1}, 0)$

RADIUS : $(\pm) \frac{1}{r+1}$

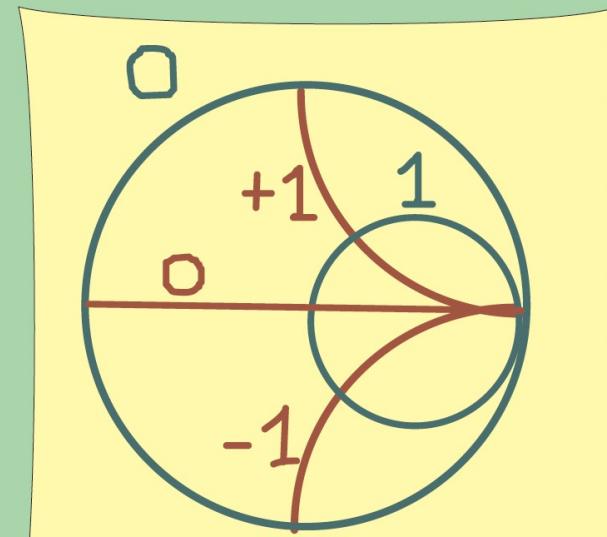
x-cirkler

$$x = \frac{2v}{(1-u)^2 + v^2}$$

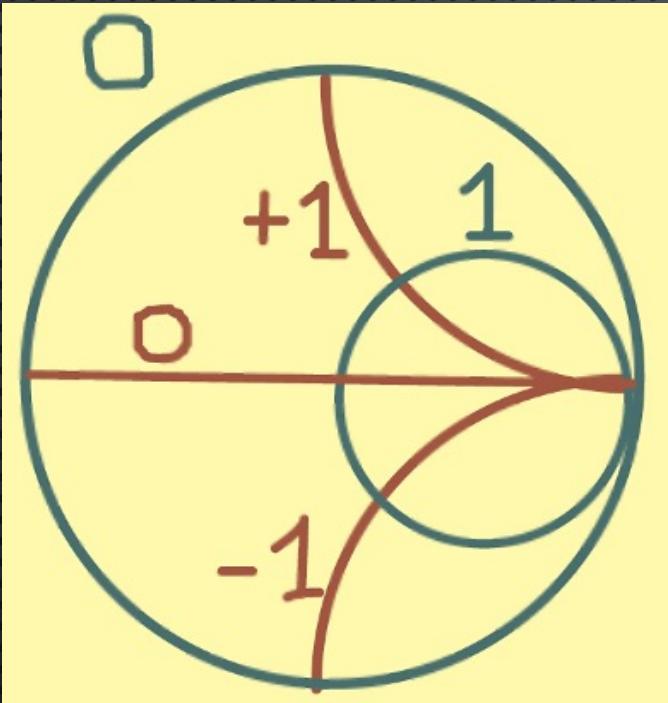
$$\Rightarrow (u-1)^2 + (v-\frac{1}{x})^2 = (\frac{1}{x})^2$$

CENTRUM: $(1, \frac{1}{x})$

RADIUS : $\pm \frac{1}{x}$

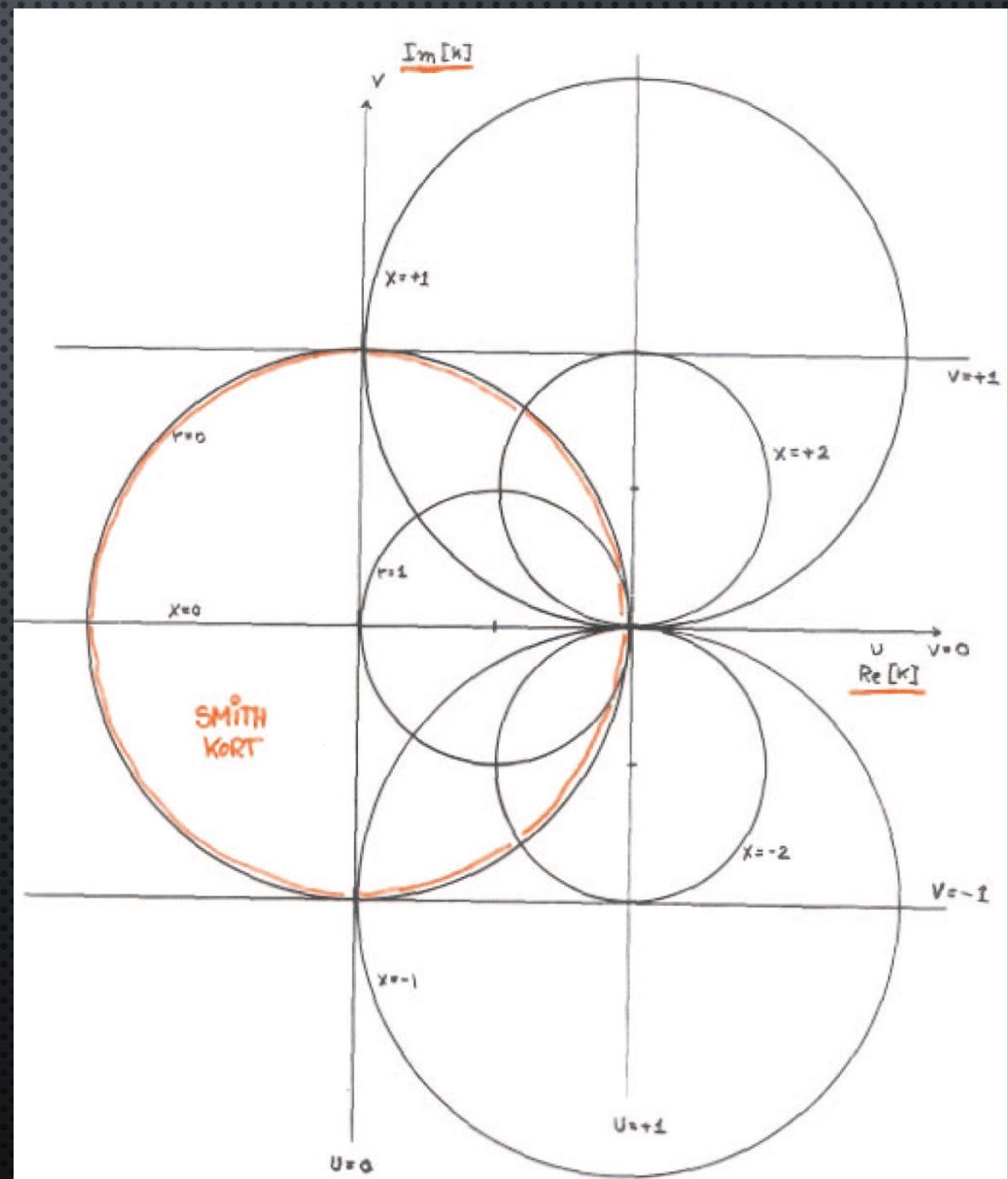


Smith Chart



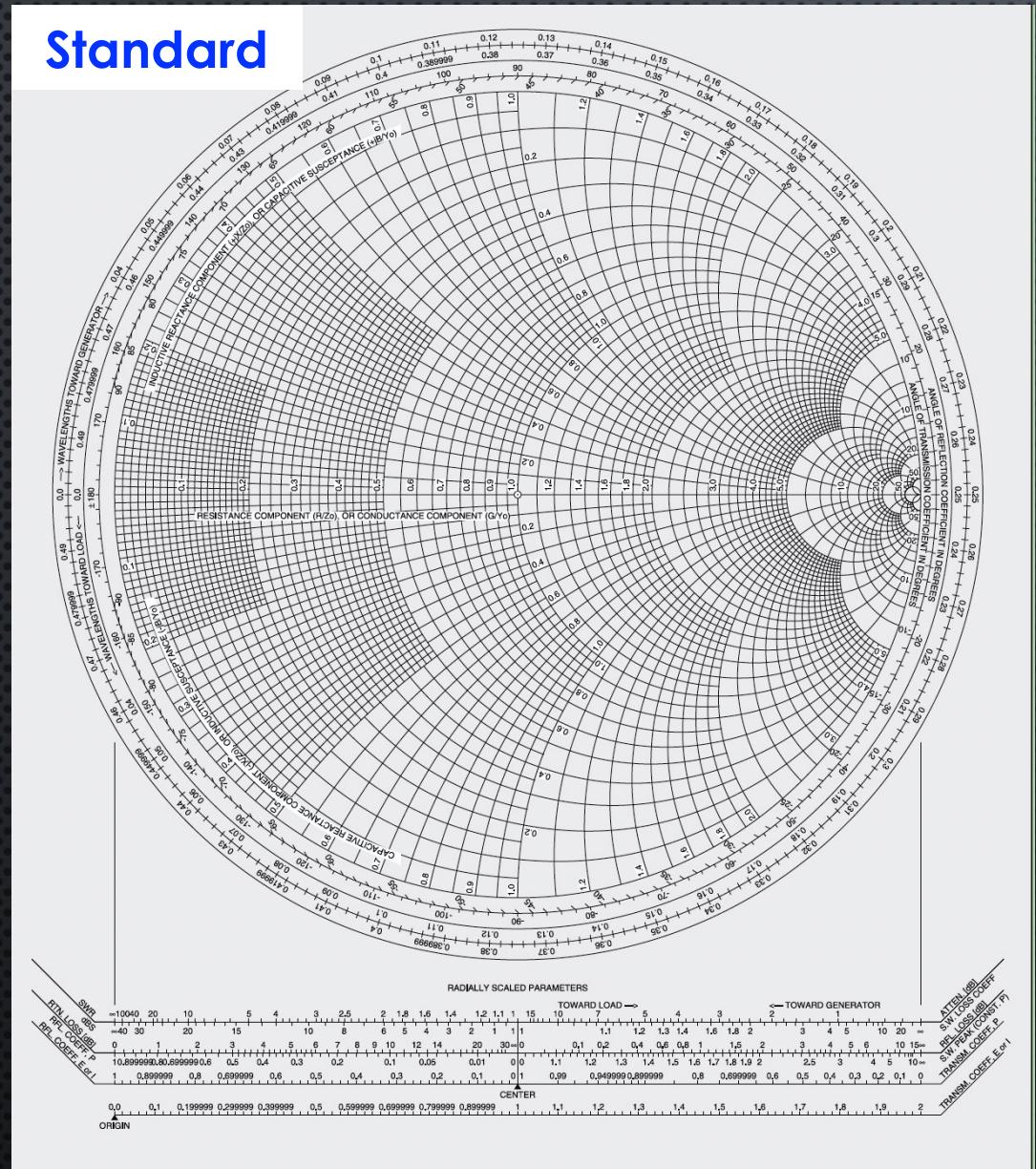
Smith chart is the expression of impedance coordinate in a K-plane

Blackboard (2)

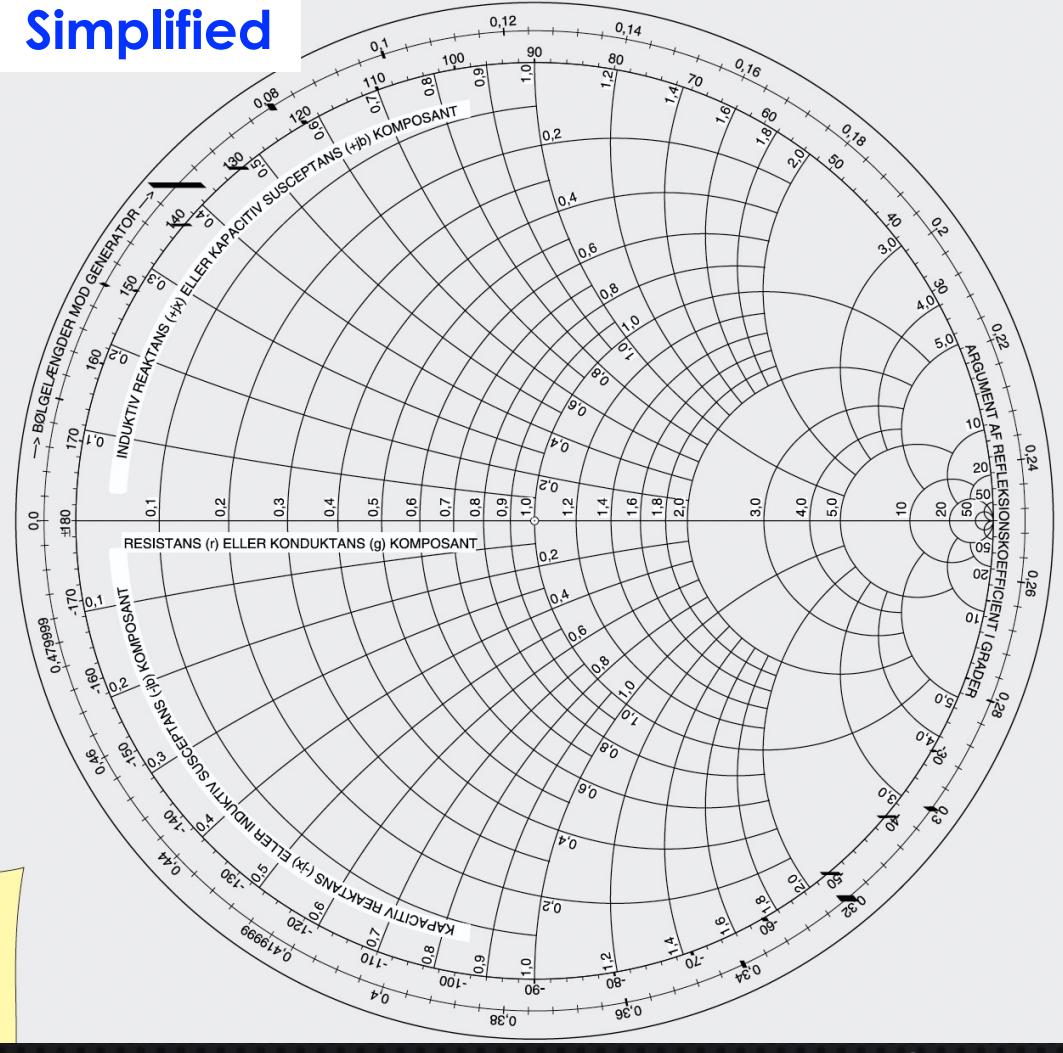


Smith Chart

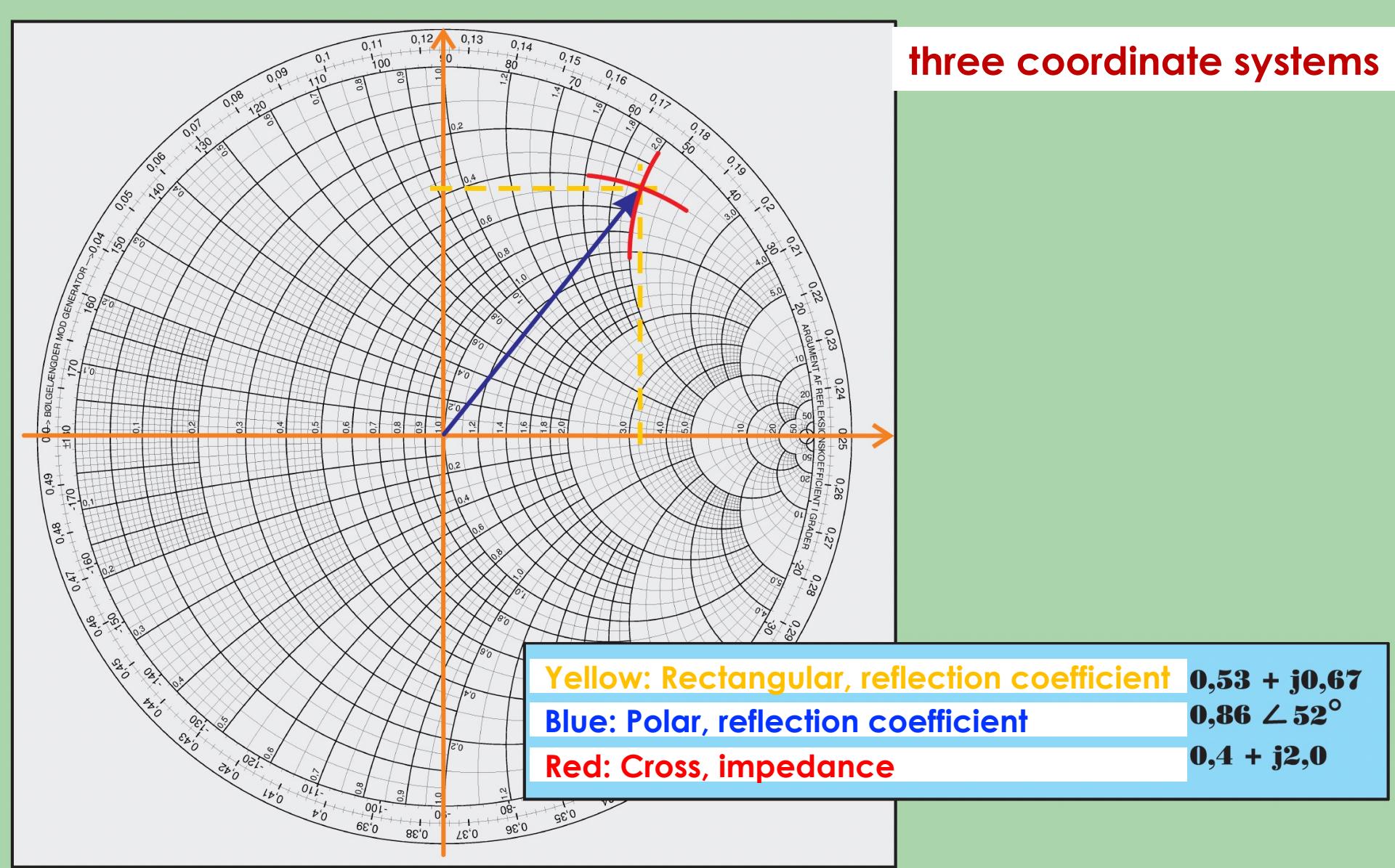
Standard



Simplified

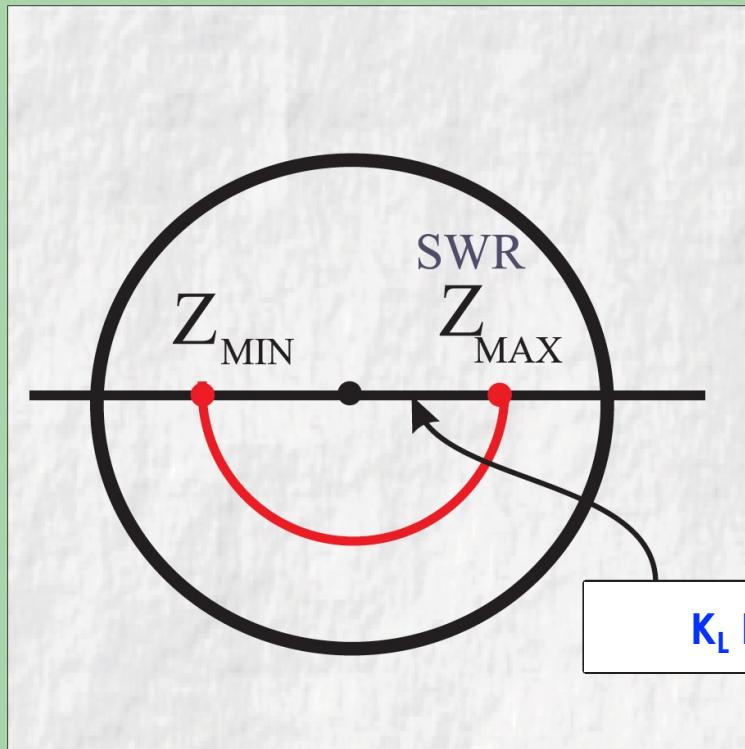


Smith Chart



Smith Chart

Maximum and minimum real impedance



$$Z_{MAX} = Z_0 \cdot SWR$$

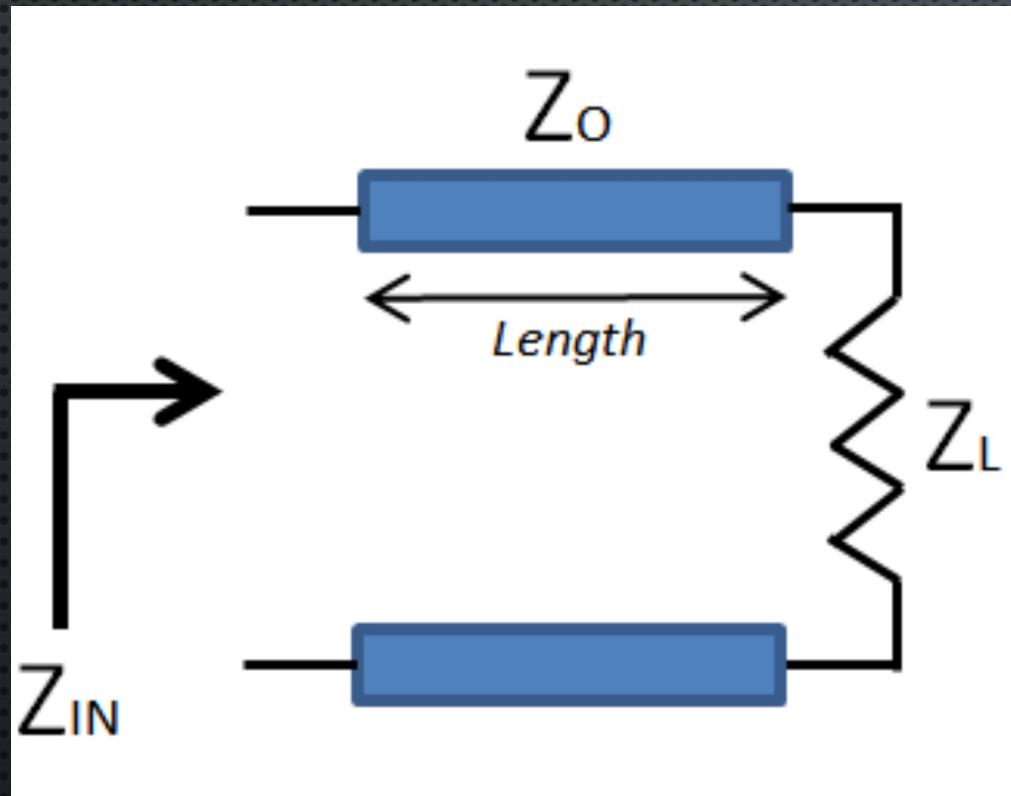
$$Z_{MIN} = \frac{Z_0}{SWR}$$

$$SWR = \frac{V_{MAX}}{V_{MIN}} = \frac{1 + |K_L|}{1 - |K_L|}$$

$$Z_{MAX} = \frac{V_{MAX}}{I_{MIN}} = Z_0 \cdot \frac{1 + |K_L|}{1 - |K_L|}$$

Calculation of Input Impedance

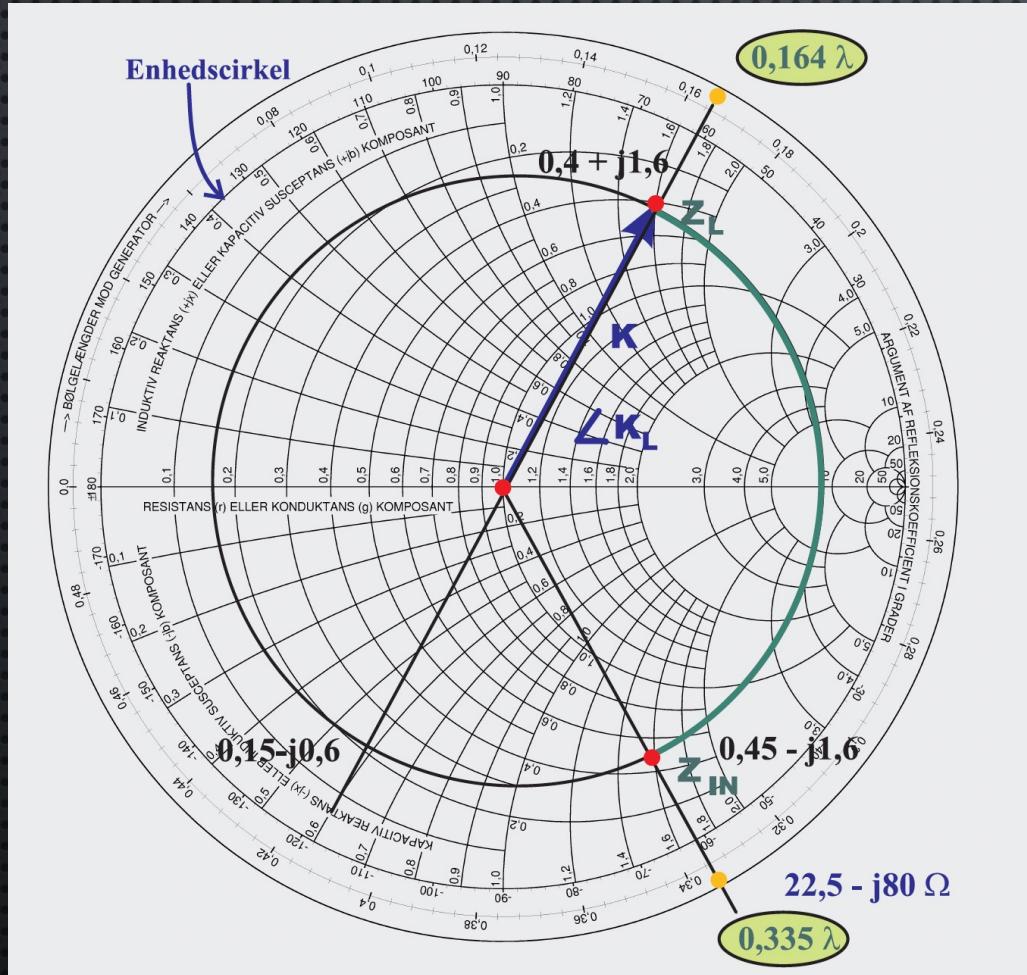
Example:



$Z_0 = 50 \text{ ohm}$, $Z_L = 20+j80 \text{ ohm}$, Length
 $L = 0.171 \lambda$
Find out Z_{in} with smith chart.

Calculation of Input Impedance

Example:



$Z_0 = 50 \text{ ohm}$, $Z_L = 20+j80 \text{ ohm}$, Length $L = 0.171 \lambda$
Find out Z_{in} with smith chart.

Solution:

Normalizing Z_L

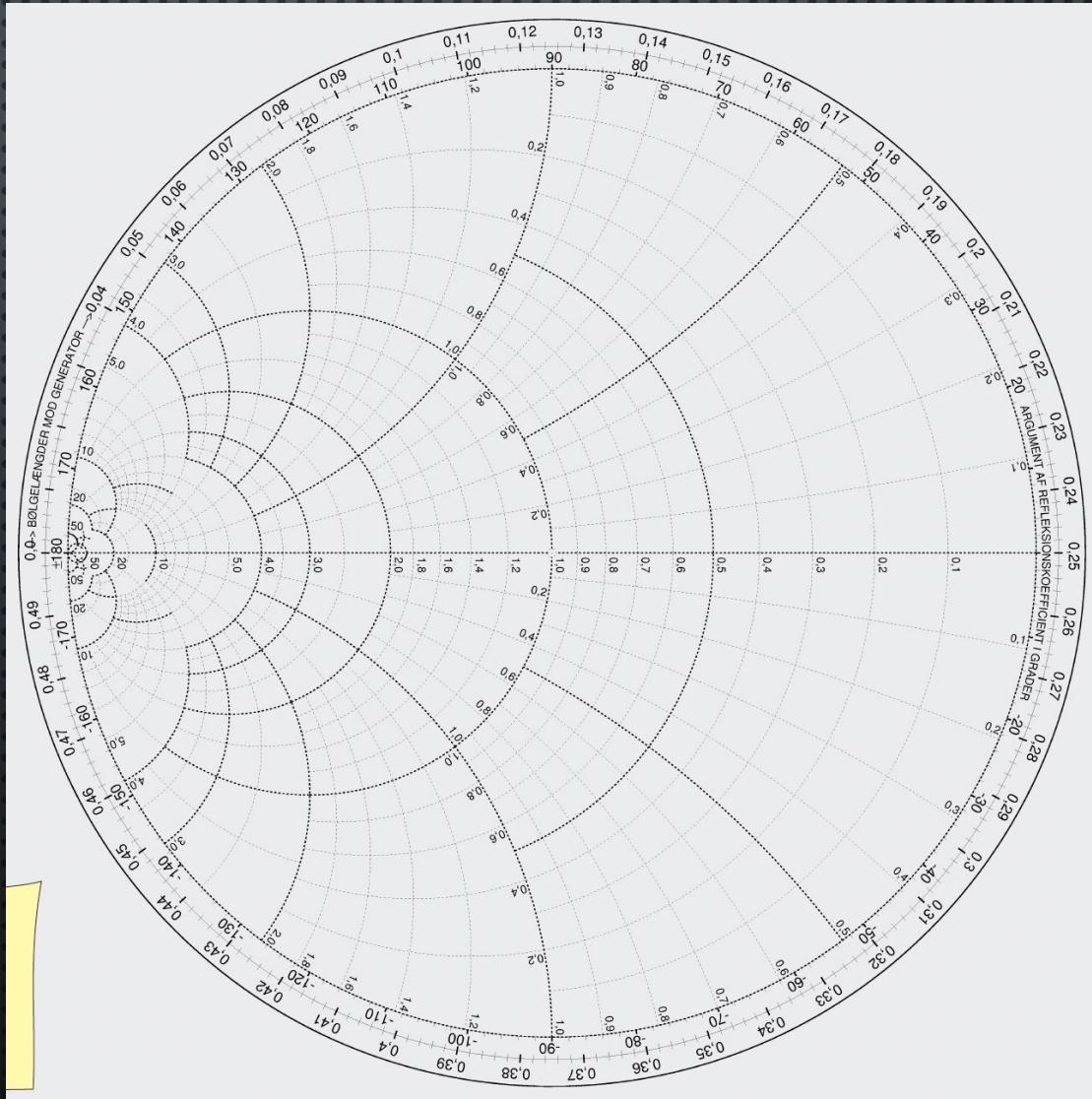
$$Z_n = Z_L / Z_0 = (20+j80)/50 = 0.4+j1.6$$

Apply smith chart and turn 0.171λ clockwise (moving from load to source direction)

$$Z_{in} = Z_0 (0.45-j1.6) = 22.5-j80 \text{ ohm}$$

Admittance chart

Blackboard (3)



Admittance Chart

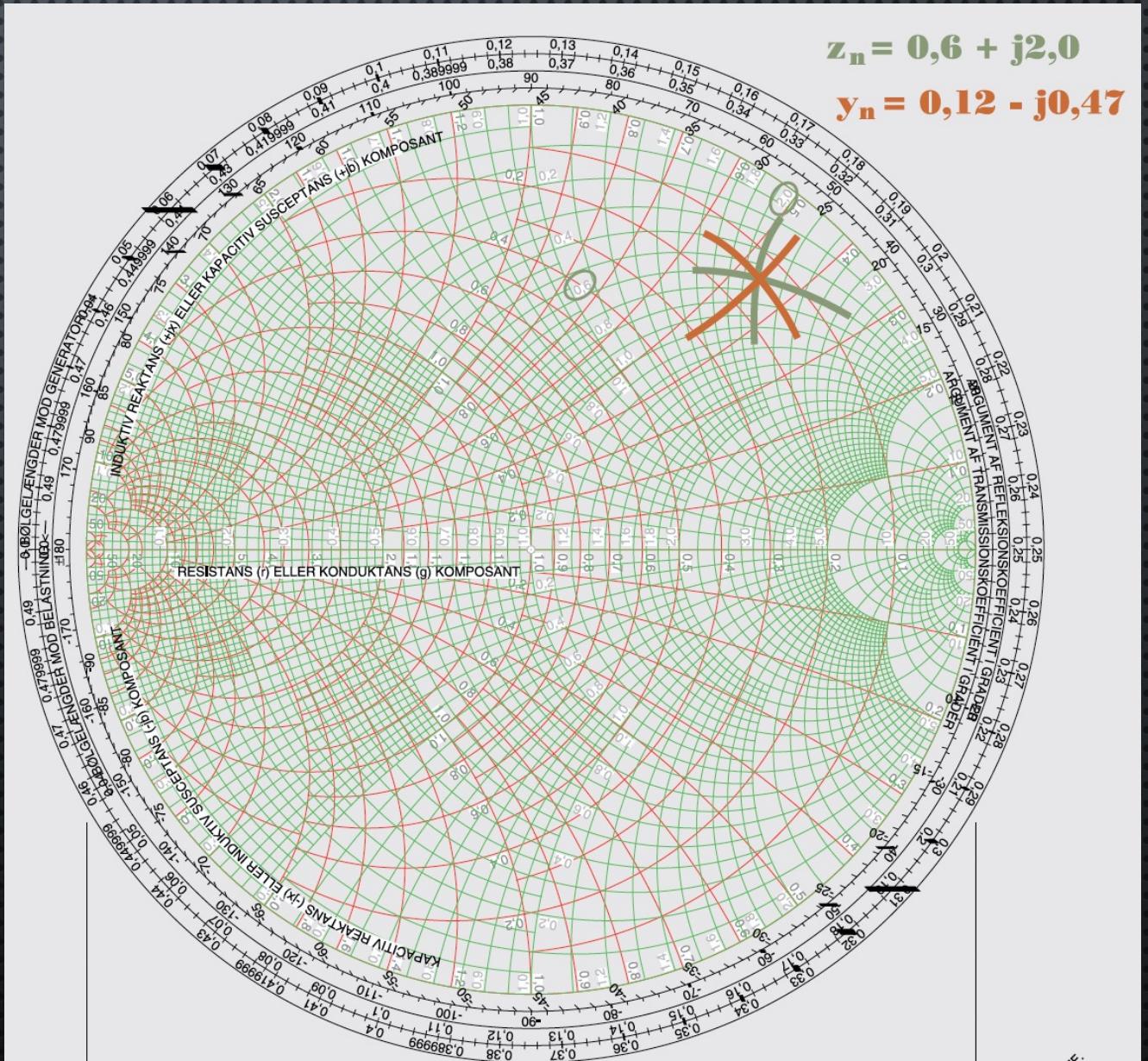
1. The mirror of impedance chart according to the center.
2. By Rotating smith impedance chart around the center by 180 degree, the impedance chart will be changed to admittance chart.

One chart for impedance and admittance

Solution1: Immittance chart

Immittance Chart
(impedance+admittance)

One point shows both impedance and its admittance



One chart for impedance and admittance

Solution 2:
Smith chart for both
impedance and
admittance

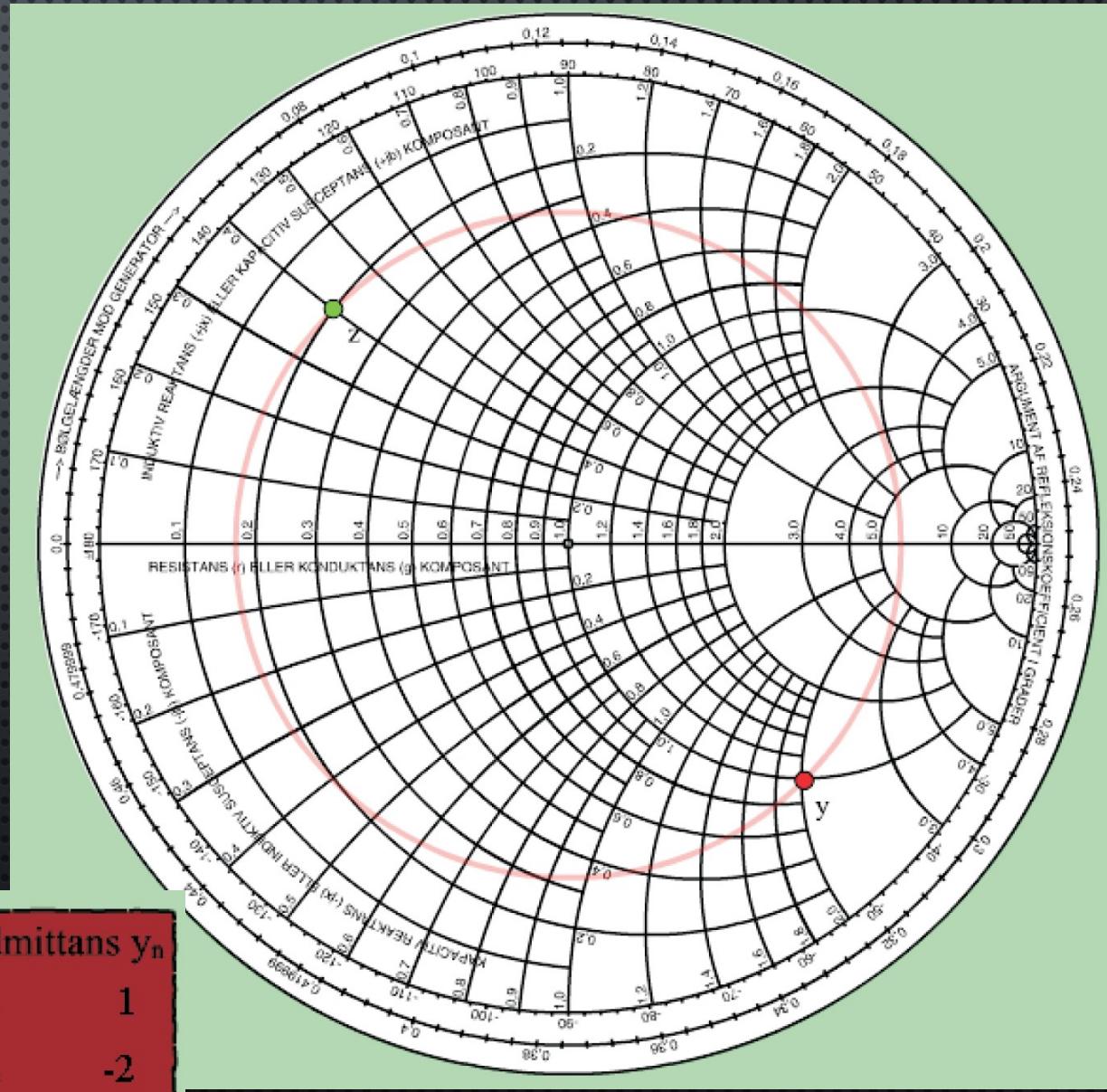
By Rotating smith impedance chart around the center by 180 degree, the impedance chart will be changed to admittance chart.

Impedans z_n

$$r = 0.2$$
$$x = 0.4$$

Admittans y_n

$$g = 1$$
$$b = -2$$



Single Stub Impedance Transformer

Lukket stub

$$Z = 0$$
$$Y = \infty$$
$$K_L = \frac{Z - Z_0}{Z + Z_0} = -1$$


$\frac{l}{\lambda}$	$Z(x)$
0	0
$\frac{\lambda}{8}$	jX (spole)
$\frac{\lambda}{4}$	∞
$\frac{3}{8}\lambda$	$-jX$ (kondensator)
$\frac{\lambda}{2}$	0

Quarter wavelength difference



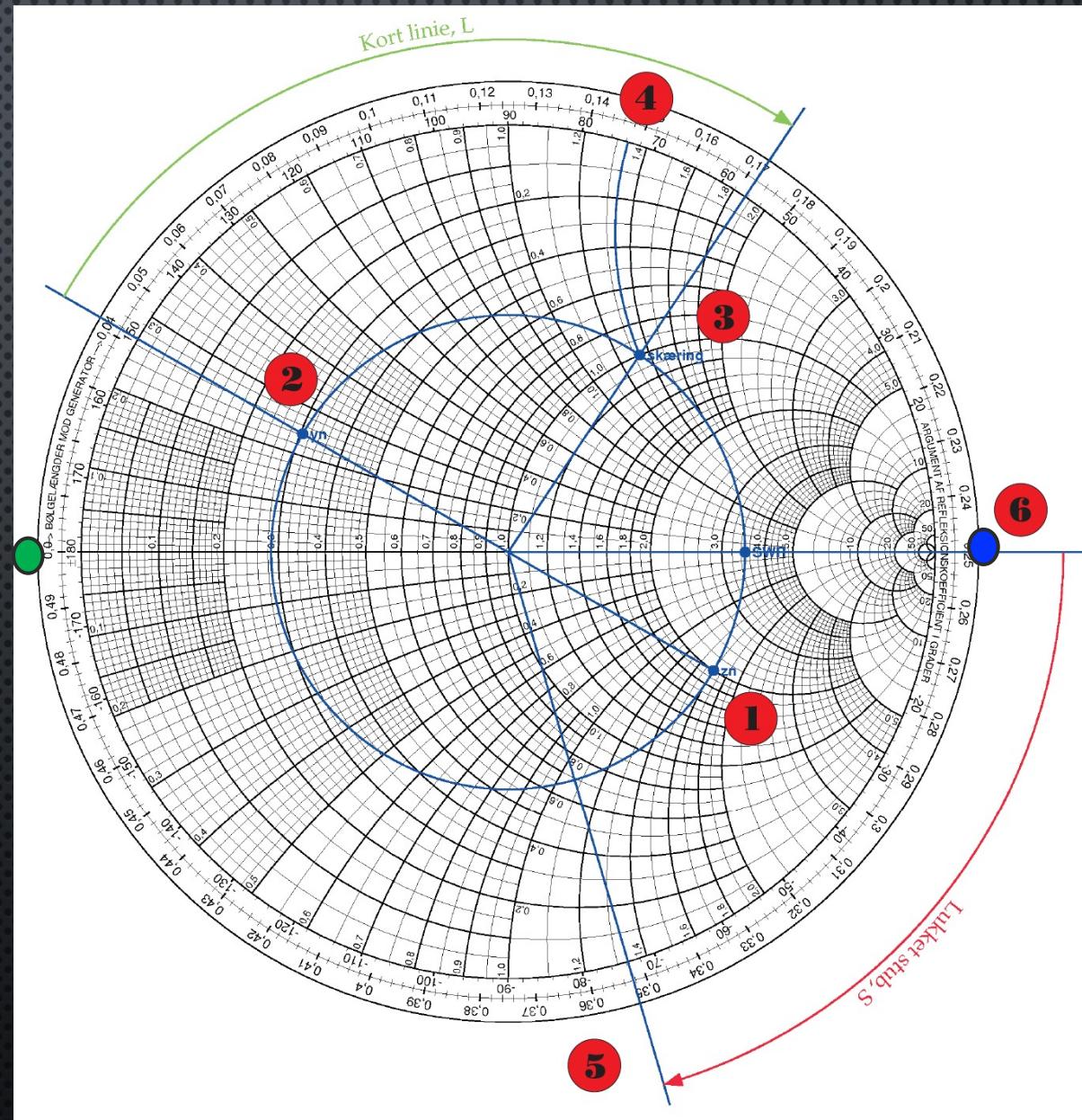
Åben stub

$$Z = \infty$$
$$Y = 0$$
$$K_L = \frac{Z - Z_0}{Z + Z_0} = +1$$

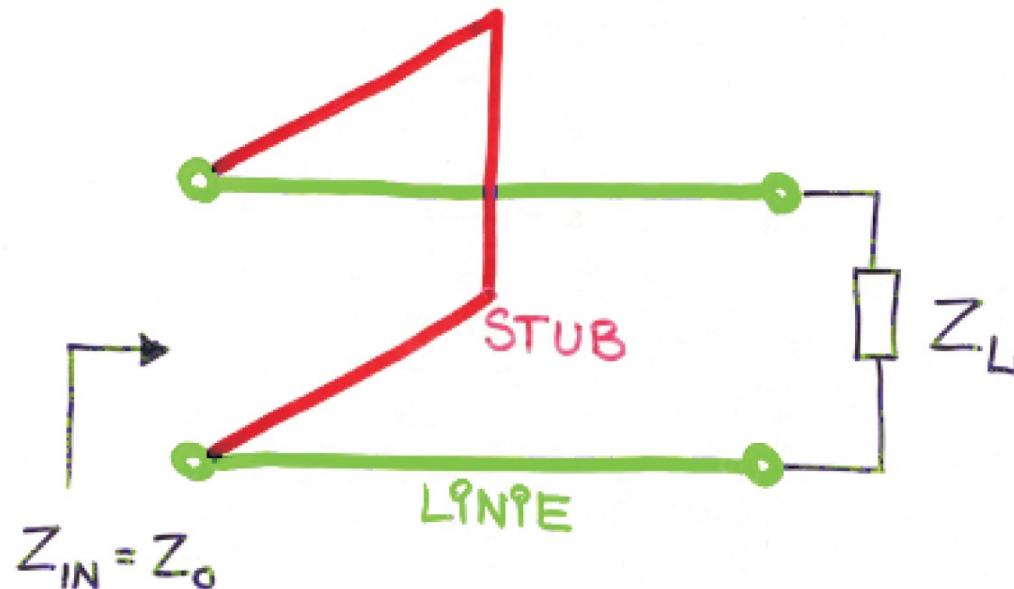

$\frac{l}{\lambda}$	$Z(x)$
0	∞
$\frac{\lambda}{8}$	$-jX$ (kond.)
$\frac{\lambda}{4}$	0
$\frac{3}{8}\lambda$	jX (spole)
$\frac{\lambda}{2}$	∞

Single Stub Impedance Transformer

1. Rotate clockwise (from load to source direction).
2. It is admittance now. If it is short-circuit stub, start from blue point. If it is open-circuit stub, start from green point.

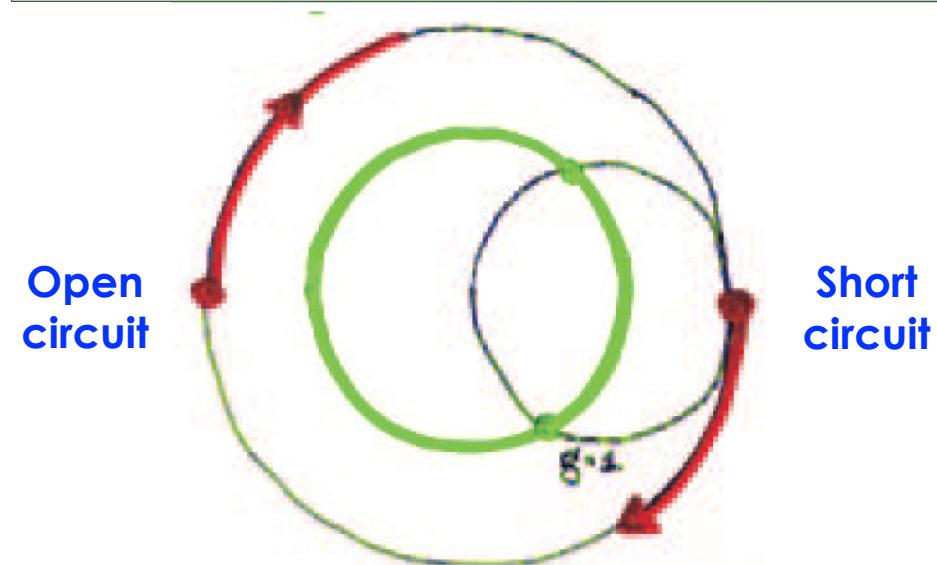


Single Stub Impedance Transformer



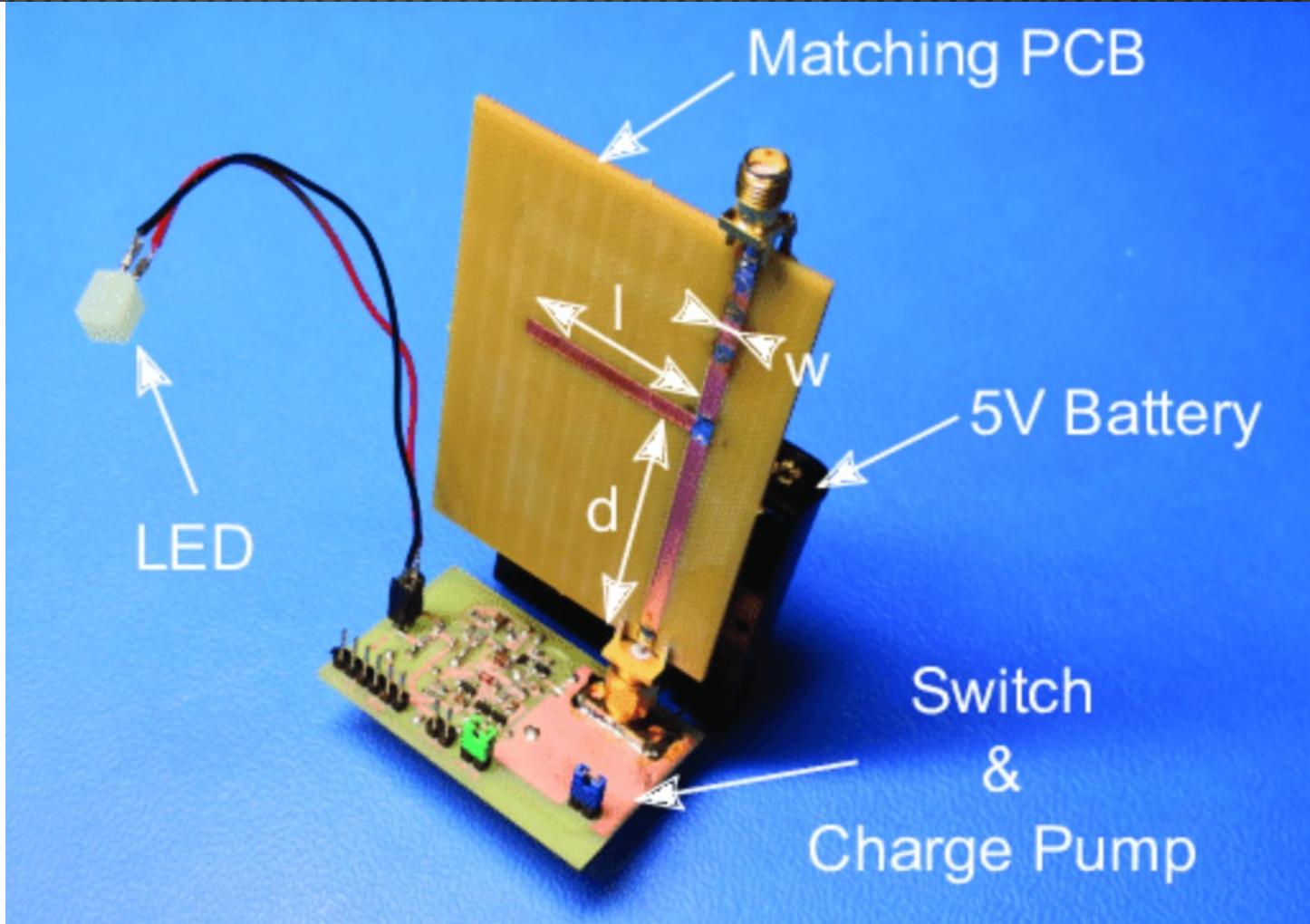
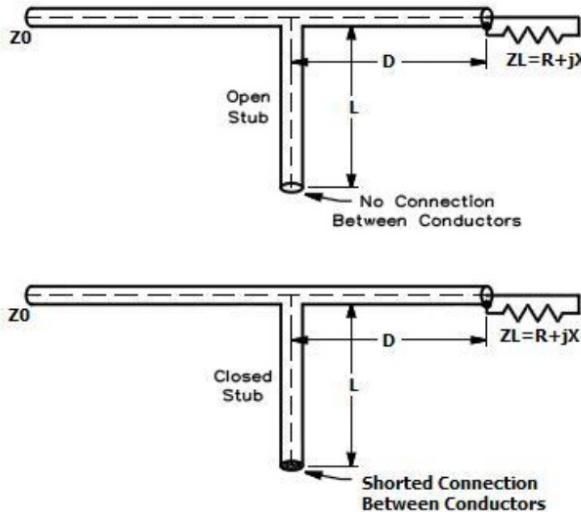
There are always 4 solutions:

1. Short line, open-circuit stub
2. Short line, short-circuit stub
3. Long line, open-circuit stub
4. Long line, short-circuit stub



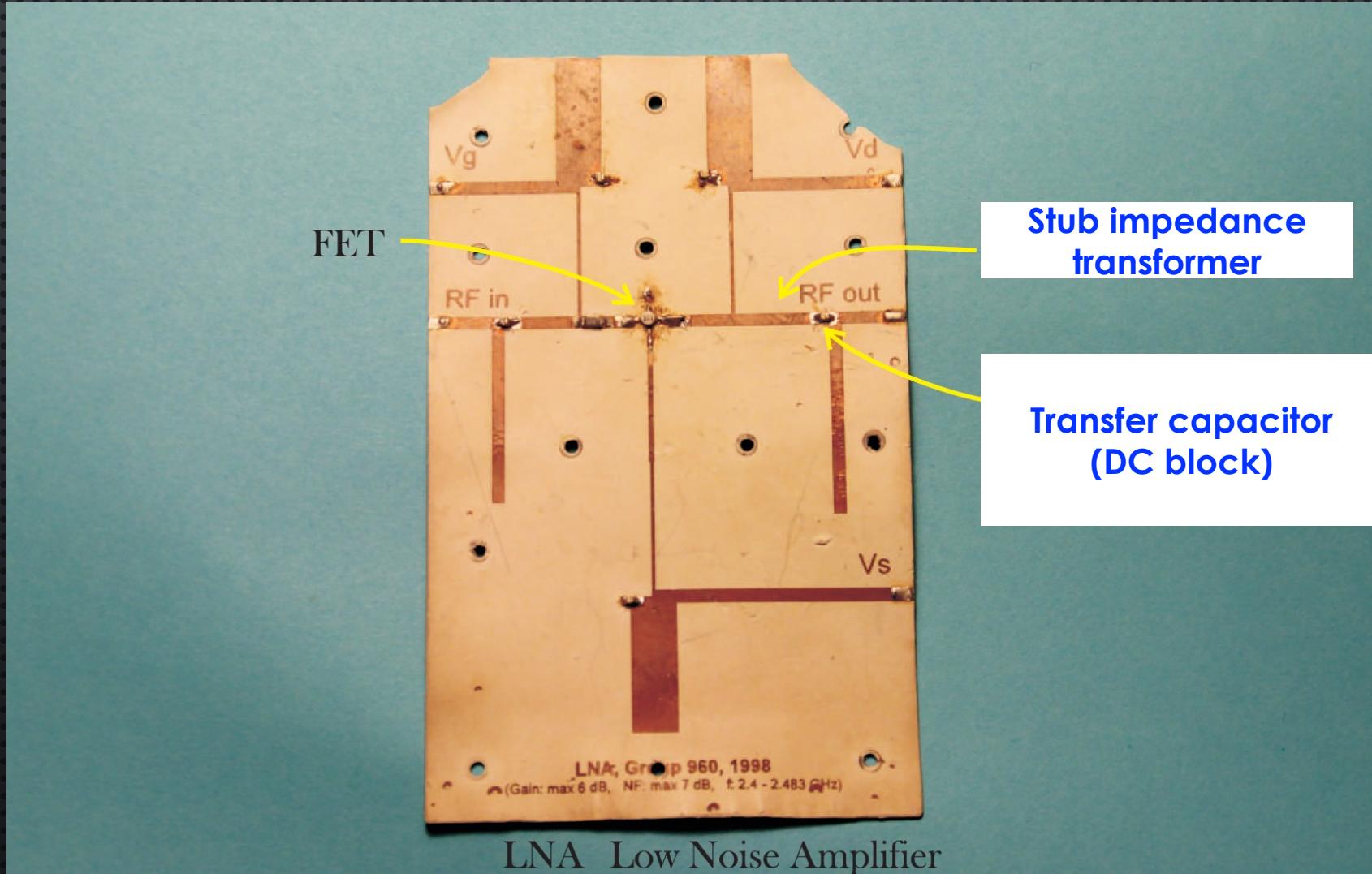
Single Stub Impedance Transformer

Examples for PCB design



Single Stub Impedance Transformer

Examples for PCB design



Smith chart with other information

CIRKLER I SMITHKORTET

Gonzales, G.:
Microwave Transistor Amplifiers, 2. ed.
Prentice Hall, 1997
ISBN 0-13-254335-4
Fig. 4.3.3 page 302

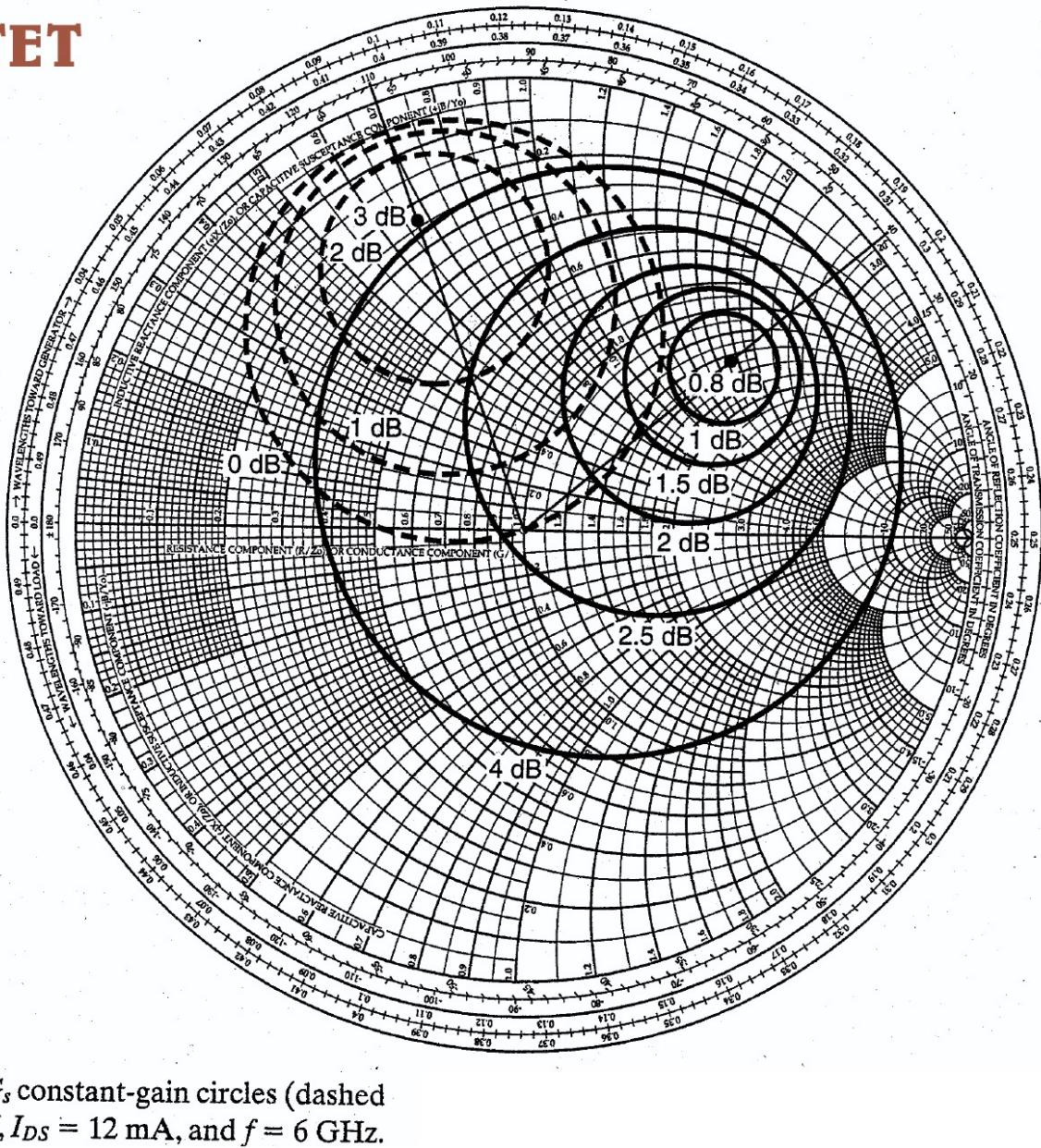


Figure 4.3.3 Noise figure circles (solid curves) and G_s constant-gain circles (dashed curves). The transistor is a GaAs FET with $V_{DS} = 4$ V, $I_{DS} = 12$ mA, and $f = 6$ GHz.