- (1) Electromagnetic field theor
- 1. Nume, symbol, unit
- 2. Definition of the field
- 3. Rotation and divergence
- 4. Boundary condition

Electric field

Electric field intensity (E field)

DI Electric flux density
(D field)

D= E. E [[]

Permittivity or dielectric constant $\mathcal{E} = \mathcal{E}_r \cdot \mathcal{E}_o$ [$\frac{1}{m}$]
In vacuum: relative permittivity*

En = 36th. 10-9 F

Example for relative permittivity Air: 1, alus: 5~9,

FR4:4~5, PE; 2,25, Nylon: 3,4

frequency dependent, Please notice that Er and its loss are Metal: 1, Soil: 4,

Other fields

P [m3] charge density (Volum charge)

Q[c] point charge Ps [m=] surface charge density (abstract model) (area charge)

Definition:

E = [im |F] . à [N-m = J = W.s = V.A.s = V]

* Use Isa unit for calculation

Where

FENJ is force

AQ[C] is a positive testing change

add testing change point to

d [m] direction vector

 $d = \frac{d}{|d|} = \frac{d}{d} \left[\frac{m}{m} \right]$ unit direction vector

where $d = |\vec{d}| = \sqrt{dx^2 + dy^2 + dz^2}$

other s

f, f Tangent vector, unit tangent vector

Normal vector, unit normal vector

Electric field around a point charge

We let Q1 a point charge and Q2 a testing charge:

$$Q_{i}(Q_{p})$$

If spherical coordinates are applied

$$E_{QR}(R, \varphi, \varphi) = \frac{Q\varphi}{4\pi E - F^2} \cdot F \left[\frac{V}{M} \right]$$

Media independent field

So
$$E = f(r) \cdot \hat{r}$$

$$\sqrt{\chi} E = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{r} & \hat{r} & \hat{r} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \end{vmatrix}$$

$$|f(r)| = \frac{1}{r^2 \sin \theta} |f(r)| = \frac{1}{r^2 \sin \theta} |f(r)|$$

UNE = P Since of D.da = IV. Ddv = NPdV > V.D=P \$D.da = John = QFOT

E field is a sum source field

E field is conservative

Illustration of electric field

For divergence, we apply divergence

theorem for electric charge

and - Q2 We have one change point+Op that is placed in the electric field of +0.









$$\left(\begin{array}{c} E_{\overline{0}} \\ = \overline{F_1} + \overline{F_2} \end{array}\right)$$

$$\lim_{n \to \infty} \left(= \overline{F_1} + \overline{F_2} \right)$$

$$\nabla X \tilde{E} = 0 \Rightarrow \begin{cases} \tilde{E} = -\nabla V \left[\frac{V}{M} \right] \\ - \int \tilde{E} \cdot d\tilde{l} = V \left[V \right] \end{cases}$$

$$V_{AB} = -\int_A^B \overline{E} \cdot d\overline{l} = \int_A^B \nabla V_b d\overline{l} = \int_A^B dV = V(B) - V(A) [V]$$

Potential around a point charge

$$V_{\infty B} = \int_{X}^{\infty} -E \cdot dI = -\int_{X}^{\infty} \frac{dP}{4\pi(F^{2})} dF$$

$$= V(b) - V(\varphi) = V(b) - (b) = V(b)$$

Potential is a relative value. If the reference point is so, this

depotential is called absolute potential.