



Quadcopter for Autonomous Underground Mine Mapping And Exploration

by

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Thesis presented in fulfilment of the requirements for the degree of
Master of Engineering (Electronic) in the Faculty of Engineering at
Stellenbosch University

Supervisor: Dr Callen Fisher

September 2025

Declaration

By submitting this thesis electronically, I declare that the entirety of the work contained therein is my own, original work, that I am the sole author thereof (save to the extent explicitly otherwise stated), that reproduction and publication thereof by Stellenbosch University will not infringe any third party rights and that I have not previously in its entirety or in part submitted it for obtaining any qualification.

Date: September 2025

Abstract

The English abstract.

Opsomming

Die Afrikaanse uittreksel.

Acknowledgements

I would like to thank my dog, Muffin. I also would like to thank the inventor of the incubator; without him/her, I would not be here. Finally, I would like to thank Dr Herman Kamper for this amazing report template.

Contents

Declaration	i
Abstract	ii
Opsomming	iii
Nomenclature	vii
1. Introduction	1
1.1. Section heading	1
1.2. Contributions	2
2. Literature Review	3
2.1. Section heading	3
2.2. Contributions	4
3. Methodology	5
3.1. Section heading	5
3.2. Contributions	6
4. Quadcopter Mechanical Design and Software Setup	7
4.1. Section heading	7
4.2. Contributions	8
5. Simultaneous Localisation and Mapping	10
5.1. Section heading	10
5.2. Contributions	11
6. Autonomous Path Planning	12
6.1. Section heading	12
6.2. Contributions	13
7. Practical Testing and Validation	14
7.1. Section heading	14
7.2. Contributions	15
8. Conclusion and Future Work	16

Bibliography	17
A. Project Planning Schedule	18
B. Outcomes Compliance	19

Nomenclature

Variables and functions

$p(x)$	Probability density function with respect to variable x .
$P(A)$	Probability of event A occurring.
ε	The Bayes error.
ε_u	The Bhattacharyya bound.
B	The Bhattacharyya distance.
s	An HMM state. A subscript is used to refer to a particular state, e.g. s_i refers to the i^{th} state of an HMM.
\mathbf{S}	A set of HMM states.
\mathbf{F}	A set of frames.
\mathbf{o}_f	Observation (feature) vector associated with frame f .
$\gamma_s(\mathbf{o}_f)$	A posteriori probability of the observation vector \mathbf{o}_f being generated by HMM state s .
μ	Statistical mean vector.
Σ	Statistical covariance matrix.
$L(\mathbf{S})$	Log likelihood of the set of HMM states \mathbf{S} generating the training set observation vectors assigned to the states in that set.
$\mathcal{N}(\mathbf{x} \mu, \Sigma)$	Multivariate Gaussian PDF with mean μ and covariance matrix Σ .
a_{ij}	The probability of a transition from HMM state s_i to state s_j .
N	Total number of frames or number of tokens, depending on the context.
D	Number of deletion errors.
I	Number of insertion errors.
S	Number of substitution errors.

Acronyms and abbreviations

AE	Afrikaans English
AID	accent identification
ASR	automatic speech recognition
AST	African Speech Technology
CE	Cape Flats English
DCD	dialect-context-dependent
DNN	deep neural network
G2P	grapheme-to-phoneme
GMM	Gaussian mixture model
HMM	hidden Markov model
HTK	Hidden Markov Model Toolkit
IE	Indian South African English
IPA	International Phonetic Alphabet
LM	language model
LMS	language model scaling factor
MFCC	Mel-frequency cepstral coefficient
MLLR	maximum likelihood linear regression
OOV	out-of-vocabulary
PD	pronunciation dictionary
PDF	probability density function
SAE	South African English
SAMPA	Speech Assessment Methods Phonetic Alphabet

Chapter 1

Introduction

The last few years have seen great advances in speech recognition. Much of this progress is due to the resurgence of neural networks; most speech systems now rely on deep neural networks (DNNs) with millions of parameters [1, 2]. However, as the complexity of these models has grown, so has their reliance on labelled training data. Currently, system development requires large corpora of transcribed speech audio data, texts for language modelling, and pronunciation dictionaries. Despite speech applications becoming available in more languages, it is hard to imagine that resource collection at the required scale would be possible for all 7000 languages spoken in the world today.

I really like apples.

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Average cluster purity (%)	86.5	89.7	89.2	88.5	86.6
Word boundary F -score (%)	70.6	72.2	71.8	70.9	69.4
Clusters covering 90% of data	20	13	13	13	13

Table 1.2: A table with an example of using multiple columns.

Model	Accuracy (%)		
	Intermediate	Output	Bitrate
Baseline	27.5	26.4	116
VQ-VAE	26.0	22.1	190
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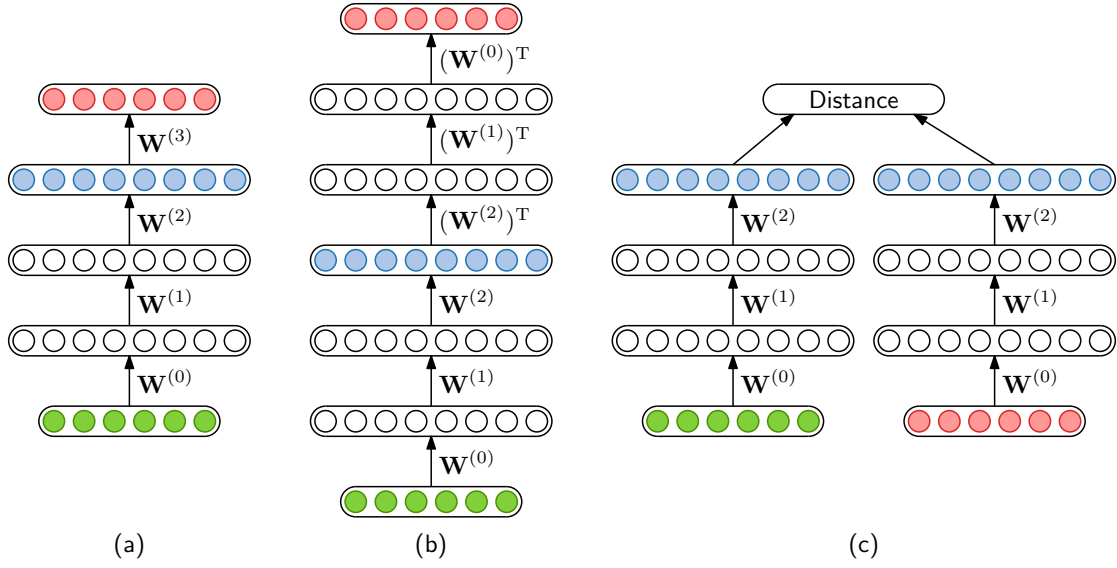


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which you can subsequently refer to as (7.1) or Equation 7.1. But make sure to consistently use the one or the other (and not mix the two ways of referring to equations).

1.2. Contributions

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Chapter 2

Literature Review

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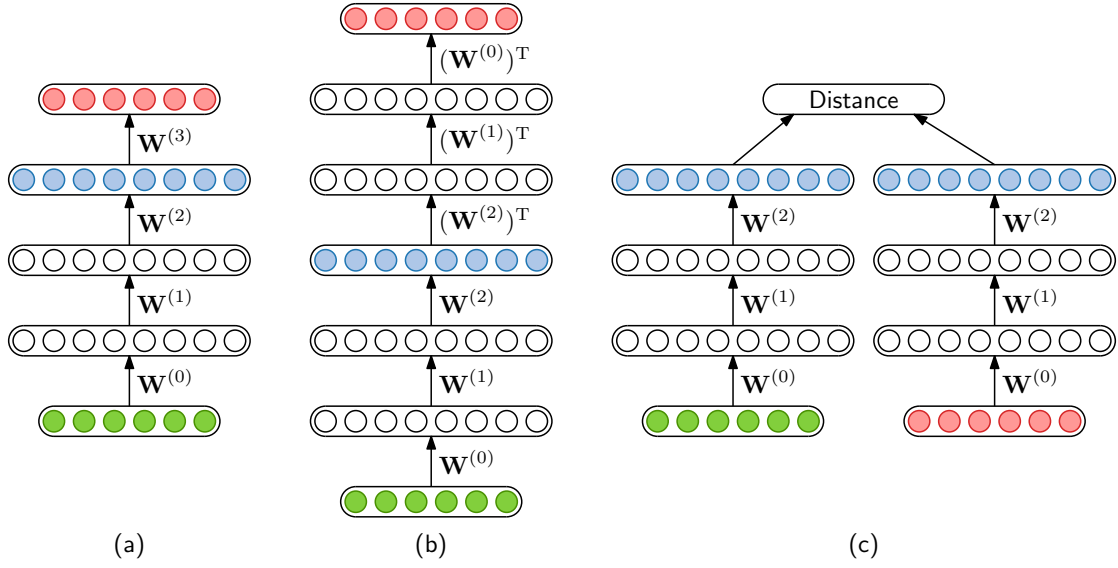


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Chapter 3

Methodology

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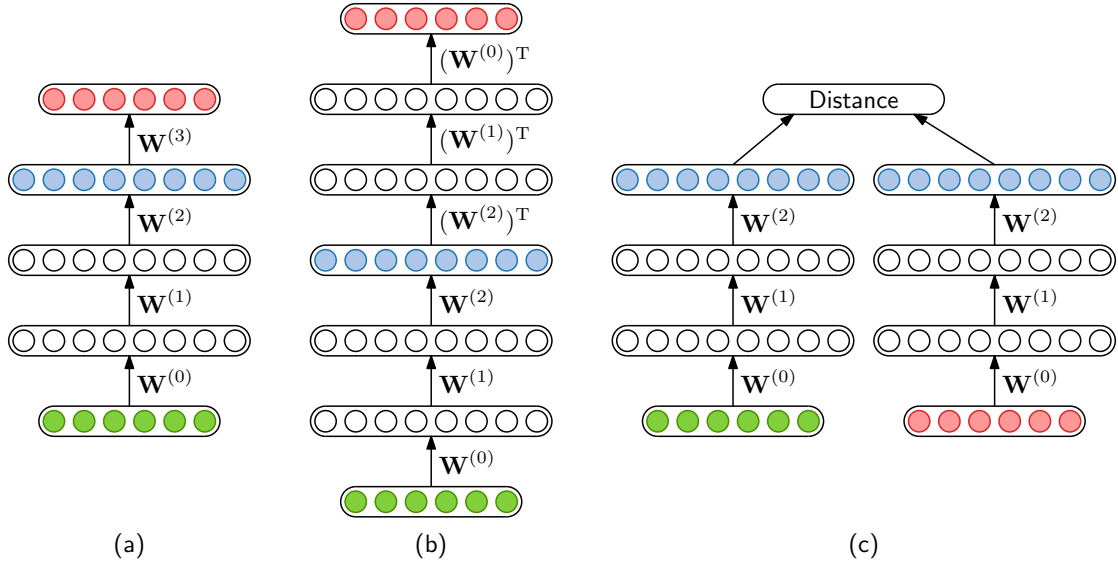


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Chapter 4

Quadcopter Mechanical Design and Software Setup

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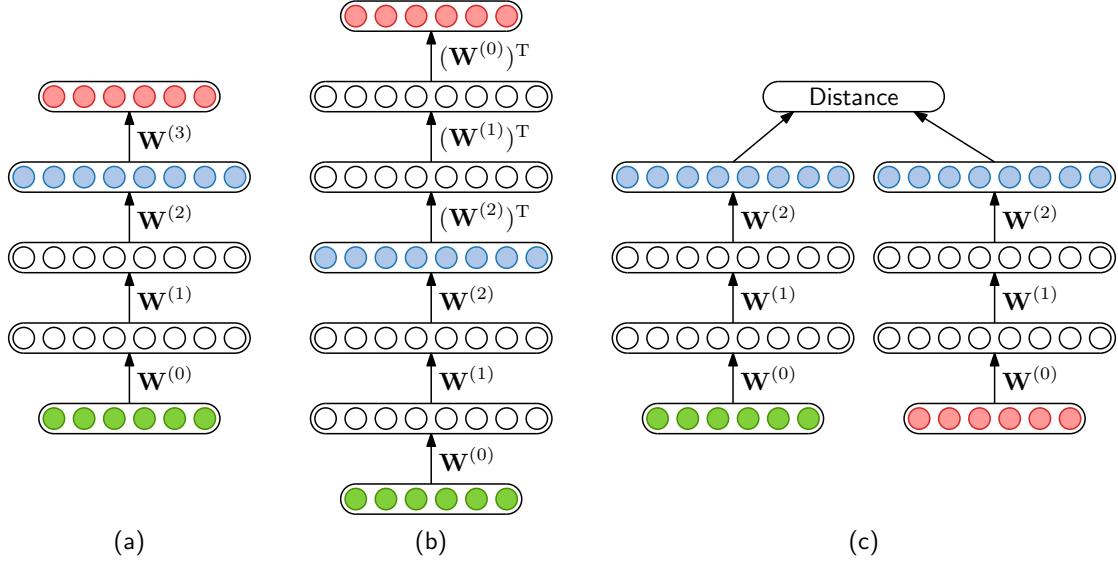


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Chapter 5

Simultaneous Localisation and Mapping

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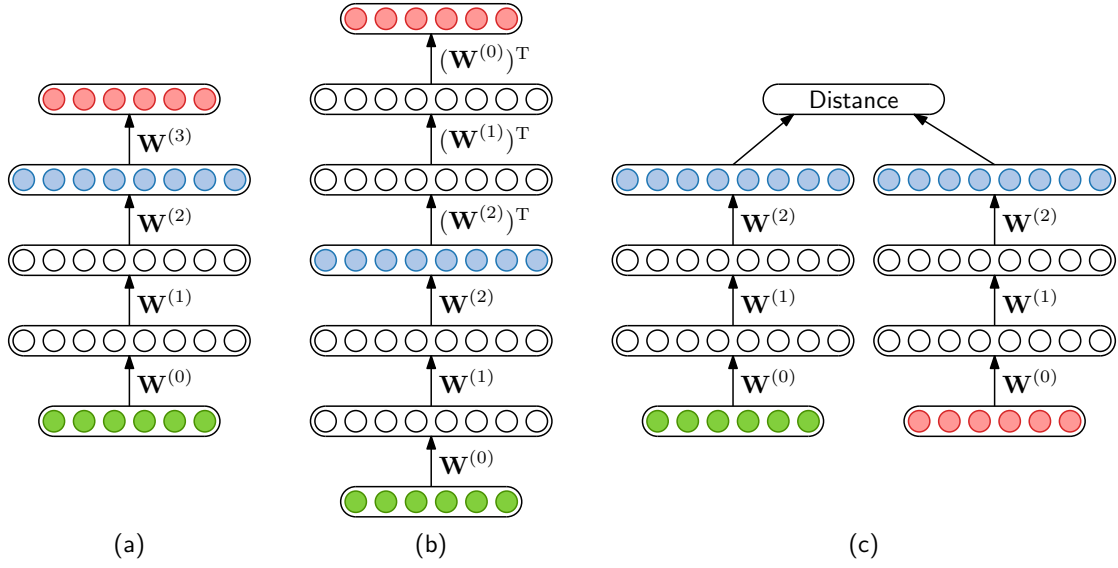


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Chapter 6

Autonomous Path Planning

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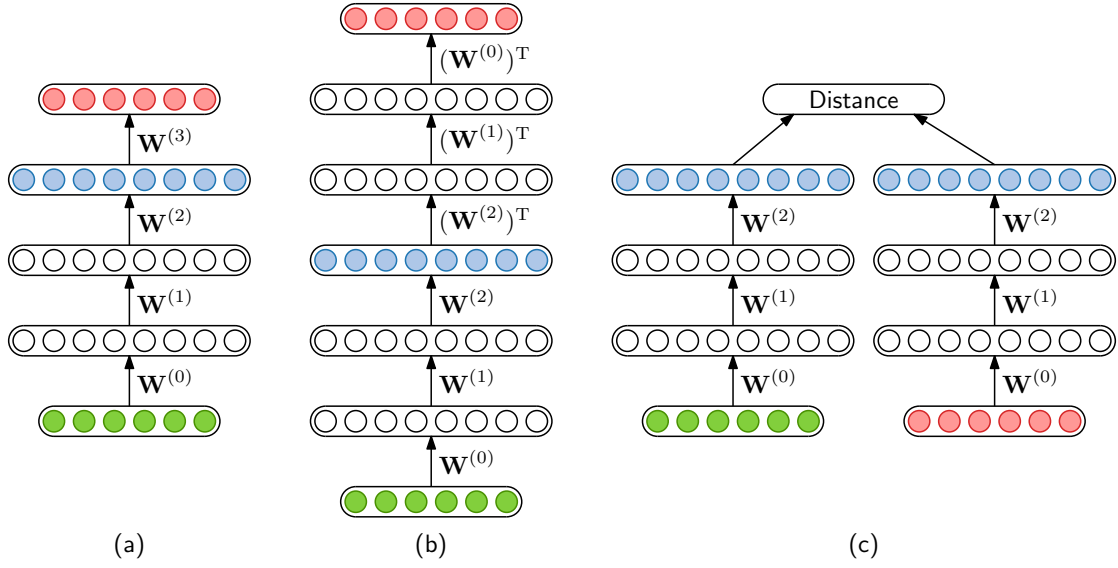


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Chapter 7

Practical Testing and Validation

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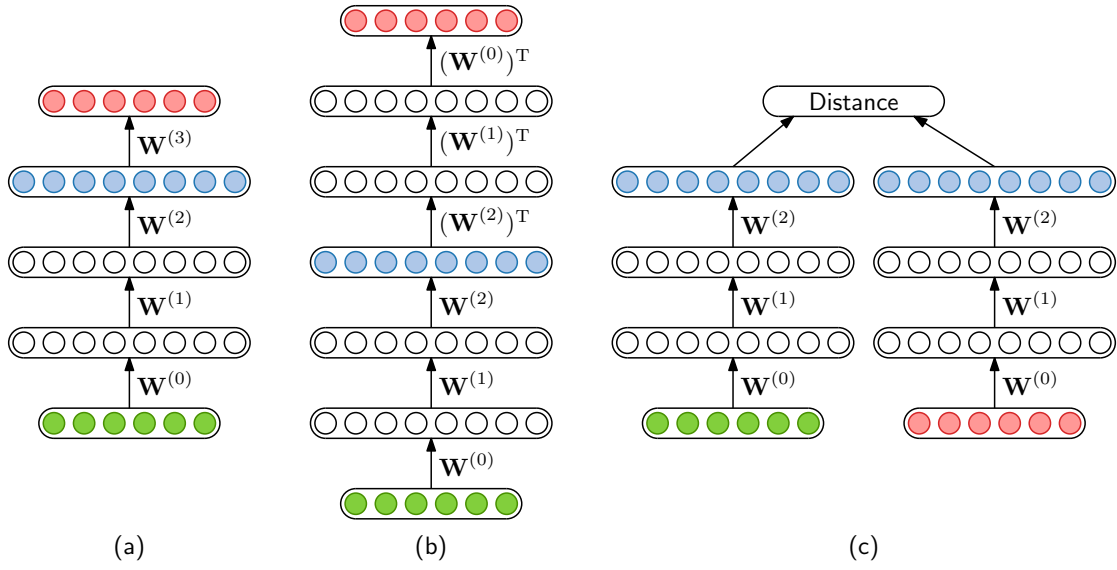


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Chapter 8

Conclusion and Future Work

Bibliography

- [1] G. E. Dahl, D. Yu, L. Deng, and A. Acero, "Context-dependent pre-trained deep neural networks for large-vocabulary speech recognition," *IEEE Trans. Audio, Speech, Language Process.*, vol. 20, no. 1, pp. 30–42, 2012.
- [2] G. Hinton, L. Deng, D. Yu, G. E. Dahl, A.-R. Mohamed, N. Jaitly, A. Senior, V. Vanhoucke, P. Nguyen, T. N. Sainath, and B. Kingsbury, "Deep neural networks for acoustic modeling in speech recognition: The shared views of four research groups," *IEEE Signal Process. Mag.*, vol. 29, no. 6, pp. 82–97, 2012.

Appendix A

Project Planning Schedule

This is an appendix.

Appendix B

Outcomes Compliance

This is another appendix.