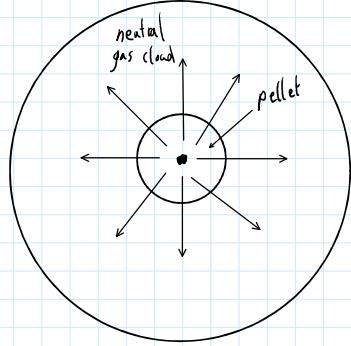


Consider the neutral gas around the pellet through fluid equations.

The pellet acts as a source of ablatant particles at the origin through boundary conditions.



To first order the characteristics of the cloud are spherically symmetric and described by the Neutral Gas Shielding model (Parks 1978).

We want to model the effect of an anisotropic heat source as a perturbation. But it should still be rotationally symmetric around Z-axis.

The gas is described by the steady state equations for an ideal gas

i.e. Euler equations (Navier Stokes without viscosity and thermal conductivity, Wikipedia)

can be derived from kinetic theory (Vlasov equation), see book Holander & Sigmund eq. 2.15, 2.16, 2.17

(steady state  $\rightarrow \frac{\partial}{\partial t} = 0$ , neutral particles  $\rightarrow e_a = 0$ , no friction force  $R_a = 0$ , no viscosity  $\eta_a = 0$ )

$$\vec{\nabla}(\rho \vec{v}) = 0 \quad (\text{I}) \quad (\text{mass conservation})$$

$$\rho \vec{v} \cdot (\vec{\nabla} \cdot \vec{v}) = -\vec{\nabla} p \quad (\text{II}) \quad (\text{momentum conservation})$$

$$\vec{\nabla} \left[ \left( \frac{\rho v^2}{2} + \frac{\gamma p}{\gamma-1} \right) \vec{v} \right] = Q \quad (\text{III}) \quad (\text{energy conservation + heat source } Q)$$

where  $\rho(\vec{r})$  is mass density,  $\vec{v}(\vec{r})$  is flow velocity,  $p(\vec{r})$  is fluid pressure

$$(\text{III}) \text{ in usual form: } \vec{v} \cdot \vec{\nabla} \rho + \frac{\rho}{p} \vec{\nabla} \vec{v} = Q$$

$$\text{equation of state ideal gas: } p = \rho e (\gamma-1) \Leftrightarrow e = \frac{p}{\rho} \frac{1}{\gamma-1}$$

$$\vec{v} \cdot \vec{\nabla} \left( \frac{p}{\rho} \frac{1}{\gamma-1} \right) + \frac{\rho}{p} \vec{\nabla} \cdot \vec{v} = Q$$

$$\frac{1}{\gamma-1} \left( \vec{v} \vec{\nabla} \left( \frac{p}{\rho} \right) + (\gamma-1) \frac{\rho}{p} \vec{\nabla} \cdot \vec{v} \right) = Q$$

Origin of (III) unclear

Treat anisotropic dynamics (index 1) as a perturbation to spherically symmetric dynamics (index 0)

$$\rho(\vec{r}) = \rho_0(r) + \rho_1(r, \theta), \quad \vec{v}(\vec{r}) = \underbrace{v_0(r)}_{\vec{v}_0} \hat{r} + \vec{v}_1(r, \theta), \quad p(\vec{r}) = p_0(r) + p_1(r, \theta), \quad Q(\vec{r}) = Q_0(r) + Q_1(r, \theta)$$

with  $\rho_0 \gg \rho_1$ ,  $v_0 \gg v_1$ ,  $p_0 \gg p_1$ ,  $Q_0 \gg Q_1$

System of equations for isotropic part: with  $\vec{\nabla}(f(r) \hat{r}) = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 f(r))$  and  $\vec{\nabla} f(r) = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 f(r)) \hat{r}$  (0th order)

$$\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \rho_0(r) v_0(r)) = 0 \quad (\text{I}_0)$$

$$\rho_0(r) v_0(r) \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0(r)) = -\frac{1}{r^2} \frac{\partial}{\partial r} p_0(r) \quad (\text{II}_0)$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left[ \frac{\rho_0(r) v_0^2(r)}{2} + \frac{\gamma}{\gamma-1} p_0(r) v_0(r) \right] = Q_0(r) \quad (\text{III}_0)$$

This can be solved through the Neutral Gas Shielding model.

System of equations for perturbation (linearization):  
(1st order)

$$(I): \vec{\nabla}((P_0 + P_1)(\vec{V}_0 + \vec{V}_1)) = \vec{\nabla}\left(\underbrace{P_0 \vec{V}_0}_{\text{0th order}} + \underbrace{P_1 \vec{V}_0}_{\text{2nd order}} + P_0 \vec{V}_1 + P_1 \vec{V}_1\right) = 0$$

$$\Rightarrow \vec{\nabla}(P_1 \vec{V}_0 + P_0 \vec{V}_1) = 0 \quad (I_1, a)$$

$$(II): (P_0 + P_1)(\vec{V}_0 + \vec{V}_1) \vec{\nabla}(\vec{V}_0 + \vec{V}_1) = -\vec{\nabla}P_0 - \vec{\nabla}P_1 \quad \text{with } P_0 V_0 \hat{\nabla}(\vec{V}_0 \hat{r}) = -\vec{\nabla}P_0$$

and linearization

$$\Leftrightarrow P_0 \vec{V}_0 (\vec{\nabla} \vec{V}_1) + P_0 \vec{V}_1 (\vec{\nabla} \vec{V}_0) + P_1 \vec{V}_0 (\vec{\nabla} \vec{V}_0) = -\vec{\nabla} P_1 \quad (II_1, a)$$

$$(III): \vec{\nabla} \left[ \left( \frac{1}{2} (P_0 + P_1)(\vec{V}_0 + \vec{V}_1)^2 + \frac{1}{\delta-1} (P_0 + P_1) \right) (\vec{V}_0 + \vec{V}_1) \right] = Q_0 + Q_1 \quad \text{with } \vec{\nabla} \left[ \left( \frac{1}{2} P_0 V_0^2 + \frac{1}{\delta-1} P_0 \right) \vec{V}_0 \right] = Q_0$$

and linearization

$$\Leftrightarrow \vec{\nabla} \left[ \left( \frac{1}{2} P_0 V_0^2 + \frac{1}{\delta-1} P_0 \right) \vec{V}_1 + \left( \frac{1}{2} P_1 V_0^2 + P_0 \vec{V}_0 \cdot \vec{V}_1 + \frac{1}{\delta-1} P_1 \right) \vec{V}_0 \right] = Q_1 \quad (III_1, a)$$

Assume the perturbations take the form

$$A(r, \theta) = P_r(r) P_\theta(\theta), \quad P_r(r, \theta) = p_r(r) p_\theta(\theta), \quad \vec{V}_1(r, \theta) = U_r(r) U_\theta(\theta) \hat{r} + V_r(r) V_\theta(\theta) \hat{\theta}$$

In spherical coordinates: (Jackson)

$$\vec{\nabla} \psi = \hat{r} \frac{\partial \psi}{\partial r} + \hat{\theta} \frac{\partial \psi}{\partial \theta} + \hat{\phi} \frac{\partial \psi}{\partial \phi}, \quad \vec{\nabla} \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta) + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

$$\Rightarrow \vec{\nabla} \vec{V}_1 = \frac{1}{r^2} U_\theta \frac{\partial}{\partial r} (r^2 U_r) + \frac{1}{r \sin \theta} V_r \frac{\partial}{\partial \theta} (\sin \theta V_\theta)$$

$$\vec{\nabla} P_1 = \hat{r} P_\theta \frac{\partial}{\partial r} P_r + \hat{\theta} P_r \frac{\partial}{\partial \theta} P_\theta$$

$$(I_1, a) \Rightarrow \frac{1}{r^2} U_\theta \frac{\partial}{\partial r} (r^2 P_r V_0) + \frac{1}{r^2} U_\theta \frac{\partial}{\partial r} (r^2 P_0 U_r) + \frac{1}{r \sin \theta} P_0 V_r \frac{\partial}{\partial \theta} (\sin \theta V_\theta) = 0$$

Assume the perturbations take the form

$$A(r, \theta) = P_r(r) P_\theta(\theta), \quad P_r(r, \theta) = p_r(r) p_\theta(\theta), \quad \vec{V}_1(r, \theta) = U_r(r) U_\theta(\theta) \hat{r} + V_r(r) V_\theta(\theta) \hat{\theta}$$

Use Fourier expansion

$$P_\theta(\theta) = \sum_{k=0}^{\infty} \alpha_{p,k} \cos(k\theta), \quad p_\theta(\theta) = \sum_{k=0}^{\infty} \alpha_{p,k} \cos(k\theta), \quad U_\theta(\theta) = \sum_{k=0}^{\infty} \alpha_{v,k} \cos(k\theta), \quad V_\theta(\theta) = \sum_{k=1}^{\infty} \beta_{v,k} \sin(k\theta)$$

$$\text{and renaming } P_r(r) = R(r), \quad p_r(r) = p(r), \quad U_r(r) = U(r), \quad V_r(r) = V(r)$$

$$\Rightarrow P_1(r, \theta) = R(r) \sum_{k=0}^{\infty} \alpha_{p,k} \cos(k\theta), \quad p_1(r, \theta) = p(r) \sum_{k=0}^{\infty} \alpha_{p,k} \cos(k\theta)$$

$$V_1(r, \theta) = \hat{r} U(r) \sum_{k=0}^{\infty} \alpha_{v,k} \cos(k\theta) + \hat{\theta} V(r) \sum_{k=1}^{\infty} \beta_{v,k} \sin(k\theta)$$

$$\Rightarrow \vec{\nabla} P_1 = \hat{r} \frac{\partial P_1}{\partial r} + \hat{\theta} \frac{\partial P_1}{\partial \theta} = \hat{r} \frac{\partial R}{\partial r} \sum_k \alpha_{p,k} \cos(k\theta) - \hat{\theta} R \sum_k \alpha_{p,k} k \cos(k\theta)$$

$$\vec{\nabla} \vec{V}_1 = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U) \sum_k \alpha_{v,k} \cos(k\theta) + \frac{1}{r \sin \theta} V \frac{\partial}{\partial \theta} (\sin \theta \sum_k \beta_{v,k} \sin(k\theta))$$

$$= \left( \frac{2}{r} U + \frac{\partial U}{\partial r} \right) \sum_k \alpha_{v,k} \cos(k\theta) + \frac{\cos \theta}{r \sin \theta} V \sum_k \beta_{v,k} \sin(k\theta) + \frac{1}{r} V \sum_k \beta_{v,k} k \cos(k\theta)$$

Use strong assumption (Per's notes):

$$Q_1(r, \theta) = q(r) \cos \theta \quad (\text{this is an approximation/assumption for the external heat source})$$

$$P_1(r, \theta) = R(r) \cos \theta, \quad p_1(r, \theta) = p(r) \cos \theta,$$

$$\vec{V}_1(r, \theta) = \hat{r} U(r) \cos \theta + \hat{\theta} V(r) \sin \theta$$

Are those guesses or assumptions?

$$\Rightarrow \vec{\nabla} P_1 = \hat{r} \frac{\partial R}{\partial r} \cos \theta - \hat{\theta} R \sin \theta$$

$$\vec{\nabla} \vec{V}_1 = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U) \cos \theta + \frac{1}{r \sin \theta} V \frac{\partial}{\partial \theta} (\sin \theta \sin \theta) \quad \text{with } \frac{\partial}{\partial \theta} \sin^2 \theta = 2 \sin \theta \cos \theta$$

$$\Rightarrow \vec{\nabla} \cdot \vec{v}_1 = \hat{r} \frac{\partial}{\partial r} \cos \theta - \hat{\theta} R \sin \theta$$

$$\begin{aligned}\vec{\nabla} \cdot \vec{v}_1 &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U) \cos \theta + \frac{1}{r \sin \theta} V \frac{\partial}{\partial \theta} (\sin \theta \sin \theta) \quad \text{with } \frac{\partial}{\partial \theta} \sin^2 \theta = 2 \sin \theta \cos \theta \\ &= \left[ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U) + \frac{2}{r} V \right] \cos \theta\end{aligned}$$

$$\begin{aligned}(I_{1,a}) \Rightarrow \vec{\nabla} (\rho_0 \vec{v}_1 + \rho_1 \vec{v}_0) &= \vec{\nabla} \rho_0 \cdot \vec{v}_1 + \rho_0 \vec{\nabla} \cdot \vec{v}_1 + \vec{\nabla} \rho_1 \cdot \vec{v}_0 + \rho_1 \vec{\nabla} \cdot \vec{v}_0 \\ &= \frac{\partial \rho_0}{\partial r} U \cos \theta + \rho_0 \left[ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U) + \frac{2}{r} V \right] \cos \theta + \frac{\partial \rho_1}{\partial r} \cos \theta v_0 + R \cos \theta \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) \\ \Leftrightarrow \frac{\partial \rho_1}{\partial r} U + \rho_0 \frac{1}{r^2} \frac{\partial}{\partial r}\end{aligned}$$

Expand using general orthogonal basis  $\{X_l(\theta)\}$  and  $\{Y_l(\theta)\}$

$$Q_1(r, \theta) = \sum_l q_l(r) X_l(\theta)$$

$$\rho_1(r, \theta) = \sum_l R_l(r) X_l(\theta), \quad p_1(r, \theta) = \sum_l T_l(r) Y_l(\theta)$$

$$\vec{v}_1(r, \theta) = \hat{r} \sum_l U_l(r) X_l(\theta) + \hat{\theta} \sum_l V_l(r) Y_l(\theta)$$

$$\vec{\nabla} \rho_1(r, \theta) = \hat{r} \sum_l \frac{\partial R_l}{\partial r} X_l + \hat{\theta} \sum_l R_l \frac{\partial X_l}{\partial \theta}$$

$$\vec{\nabla} \vec{v}_1 = \frac{1}{r^2} \sum_l \frac{\partial}{\partial r} (r^2 U_l) X_l + \frac{1}{r \sin \theta} \sum_l V_l \frac{\partial}{\partial \theta} (\sin \theta Y_l)$$

$$\begin{aligned}(I_{1,a}) \Rightarrow \vec{\nabla} (\rho_0 \vec{v}_1 + \rho_1 \vec{v}_0) &= \vec{\nabla} \rho_0 \cdot \vec{v}_1 + \rho_0 \vec{\nabla} \cdot \vec{v}_1 + \vec{\nabla} \rho_1 \cdot \vec{v}_0 + \rho_1 \vec{\nabla} \cdot \vec{v}_0 \\ &= \frac{\partial \rho_0}{\partial r} \sum_l U_l X_l + \rho_0 \left[ \frac{1}{r^2} \sum_l \frac{\partial}{\partial r} (r^2 U_l) X_l + \frac{1}{r \sin \theta} \sum_l V_l \frac{\partial}{\partial \theta} (\sin \theta Y_l) \right] + v_0 \sum_l \frac{\partial R_l}{\partial r} X_l + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) \sum_l R_l X_l = 0\end{aligned}$$

assume that each mode  $l$  is independent ?

$$\Rightarrow \left[ \frac{\partial \rho_0}{\partial r} (U_l + \rho_0 \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + v_0 \frac{\partial R_l}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) R_l) \right] X_l + \rho_0 \left[ \frac{1}{r} V_l \right] \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (\sin \theta Y_l) = 0$$

$\Rightarrow$  to be able to factor out the theta dependence require ?

$$\alpha_l X_l = \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (\sin \theta Y_l) \quad (2) \quad (\alpha_l \text{ same constant} \neq 0)$$

$$\Rightarrow \frac{\partial \rho_0}{\partial r} U_l + \rho_0 \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + v_0 \frac{\partial R_l}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) R_l + \alpha_l \frac{\rho_0}{r} V_l = 0 \quad (1)$$

$$(II_{1,a}): \rho_0 \vec{v}_0 (\vec{\nabla} \cdot \vec{v}_1) + \rho_0 \vec{v}_1 (\vec{\nabla} \cdot \vec{v}_0) + \rho_1 \vec{v}_0 (\vec{\nabla} \cdot \vec{v}_0) = -\vec{\nabla} \rho_1$$

$$\Rightarrow \rho_0 v_0 \hat{r} \left[ \frac{1}{r^2} \sum_l \frac{\partial}{\partial r} (r^2 U_l) X_l + \frac{1}{r \sin \theta} \sum_l V_l \frac{\partial}{\partial \theta} (\sin \theta Y_l) \right] + \rho_0 \left[ \hat{r} \sum_l U_l X_l + \hat{\theta} \sum_l V_l Y_l \right] \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) + \left( \sum_l R_l X_l \right) v_0 \hat{r} \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) = -\hat{r} \sum_l \frac{\partial R_l}{\partial r} X_l - \hat{\theta} \sum_l T_l \frac{\partial X_l}{\partial \theta}$$

again: each mode is independent, and separate  $\hat{r}$  and  $\hat{\theta}$  terms

$$\hat{r}: \rho_0 v_0 \left[ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) X_l + \frac{1}{r \sin \theta} V_l \frac{\partial}{\partial \theta} (\sin \theta Y_l) \right] + \rho_0 U_l X_l \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) + R_l X_l v_0 \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) = -\frac{\partial R_l}{\partial r} X_l \quad (3)$$

$\Rightarrow$  same requirement to factor out  $\theta$ -dependence

$$\hat{\theta}: \rho_0 V_l Y_l \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) = -T_l \frac{\partial X_l}{\partial \theta} \quad (\text{separate } r \text{ and } \theta \text{ dependence})$$

$$\Leftrightarrow \rho_0 V_l \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) \frac{1}{T_l} = -\frac{1}{Y_l} \frac{\partial X_l}{\partial \theta} = \text{const} = \beta_l$$

$\Rightarrow$  2 separate equations:

$$\frac{1}{T_l} \rho_0 V_l \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) = \beta_l \quad (4)$$

$$Y_l = -\frac{1}{\beta_l} \frac{\partial X_l}{\partial \theta} \quad (5)$$

$$(2) \text{ and } (5) \Rightarrow \alpha_l X_l = \frac{1}{r^2} \frac{\partial}{\partial r} (\sin \theta (-\frac{1}{\beta_l} \frac{\partial X_l}{\partial \theta}))$$

$$(2) \text{ank}(S) \Rightarrow \alpha_l X_l = \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \left( -\frac{1}{\beta_l} \frac{\partial X_l}{\partial \theta} \right))$$

$$\Leftrightarrow \frac{1}{X_l} \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial X_l}{\partial \theta}) = -\alpha_l \beta_l = -\lambda_l \quad (6)$$

according to Wikipedia on spherical harmonics

the Sturm-Liouville theorem (imposing  $X_l$  to be regular at the poles)

$$\text{requires } \lambda_l = l(l+1) = \alpha_l \beta_l$$

without loss of generality let  $X_l(\theta) = P_l(\cos \theta)$

and  $P_l(\cos \theta)$  are the solutions to (6) if they are the ( $m=0$ ) associated Legendre polynomials

$\rightarrow \theta$  dependence of mode  $l$  is fixed (spherical harmonics with  $m=0$ )

$r$ -dependence (after factoring out theta dependence and requiring  $X_l \neq 0$ )

$$(1) \Rightarrow \frac{\partial U_l}{\partial r} + P_0 \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + V_0 \frac{\partial R_l}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_l) R_l + \alpha_l \frac{P_0}{r} V_l = 0 \quad (I_1, b) \quad (\text{A in Per's notes})$$

$$(3) \Rightarrow P_0 V_0 \left[ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + \frac{1}{r} V_l \right] + P_0 U_l \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) + R_l V_0 \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) = - \frac{\partial U_l}{\partial r} \quad (II_1, b_1) \quad (\text{corresponds to his B, but wrong})$$

$$(4) \Rightarrow \frac{1}{\pi_l} P_0 V_0 \left[ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) \right] = \frac{l(l+1)}{\alpha_l} \quad \alpha_l \neq 0 \text{ is arbitrary} \quad (II_1, b_2) \quad (" " " C, but wrong)$$

(Per's notes correspond to  $(=1, \alpha_l=2)$ )

$(III_1, a)$  to  $(III_1, b)$  on next page

$$(III_1, a): \vec{\nabla} \left[ \left( \frac{1}{2} P_0 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) \vec{V}_1 + \left( \frac{1}{2} P_1 V_0^2 + P_0 \vec{V}_0 \cdot \vec{V}_1 + \frac{\delta}{\delta-1} P_1 \right) \vec{V}_0 \right] = Q_1$$

$$Q_1(r, \theta) = \sum_l q_{l1}(r) X_l(\theta)$$

$$P_1(r, \theta) = \sum_l R_l(r) X_l(\theta), \quad p_1(r, \theta) = \sum_l T_l(r) X_l(\theta)$$

$$\vec{V}_1(r, \theta) = \hat{r} \sum_l U_l(r) X_l(\theta) + \hat{\theta} \sum_l V_l(r) Y_l(\theta)$$

$$\vec{\nabla} P_1(r, \theta) = \hat{r} \sum_l \frac{\partial R_l}{\partial r} X_l + \hat{\theta} \sum_l R_l \frac{\partial X_l}{\partial \theta}$$

$$\vec{\nabla} \vec{V}_1 = \frac{1}{r^2} \sum_l \frac{\partial}{\partial r} (r^2 U_l) X_l + \frac{1}{r \sin \theta} \sum_l V_l \frac{\partial}{\partial \theta} (\sin \theta Y_l)$$

$$(III_1, a) \Leftrightarrow \vec{\nabla} \left[ \left( \frac{1}{2} P_0 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) \vec{V}_1 + \left( \frac{1}{2} P_1 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) \vec{V}_0 + \vec{\nabla} \left( \frac{1}{2} P_1 V_0^2 + P_0 \vec{V}_0 \cdot \vec{V}_1 + \frac{\delta}{\delta-1} P_1 \right) \vec{V}_0 + \left( \frac{1}{2} P_1 V_0^2 + P_0 \vec{V}_0 \cdot \vec{V}_1 + \frac{\delta}{\delta-1} P_1 \right) \vec{\nabla} \vec{V}_0 \right] = Q_1$$

$$\Leftrightarrow \frac{\partial}{\partial r} \left( \frac{1}{2} P_0 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) \sum_l U_l X_l + \left( \frac{1}{2} P_1 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) \left[ \frac{1}{r^2} \sum_l \frac{\partial}{\partial r} (r^2 U_l) X_l + \frac{1}{r \sin \theta} \sum_l V_l \frac{\partial}{\partial \theta} (\sin \theta Y_l) \right] \\ + \frac{\partial}{\partial r} \left( \frac{1}{2} P_1 V_0^2 + P_0 \vec{V}_0 \cdot \vec{V}_1 + \frac{\delta}{\delta-1} P_1 \right) V_0 + \left( \frac{1}{2} P_1 V_0^2 + P_0 \vec{V}_0 \cdot \vec{V}_1 + \frac{\delta}{\delta-1} P_1 \right) \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) = Q_1$$

$$\Leftrightarrow \frac{\partial}{\partial r} \left( \frac{1}{2} P_0 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) \sum_l U_l X_l + \left( \frac{1}{2} P_1 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) \left[ \frac{1}{r^2} \sum_l \frac{\partial}{\partial r} (r^2 U_l) X_l + \frac{1}{r \sin \theta} \sum_l V_l \frac{\partial}{\partial \theta} (\sin \theta Y_l) \right] \\ + V_0 \sum_l \frac{\partial}{\partial r} \left( \frac{1}{2} R_l V_0^2 + P_0 V_0 U_l + \frac{\delta}{\delta-1} T_l \right) X_l + \sum_l \left( \frac{1}{2} R_l V_0^2 + P_0 V_0 U_l + \frac{\delta}{\delta-1} T_l \right) X_l \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) = \sum_l q_{l1} X_l$$

again each mode independent and same condition to factor out  $\theta$ -dependence (don't forget  $\alpha_l$  factor here)

$$\Leftrightarrow U_l \frac{\partial}{\partial r} \left( \frac{1}{2} P_0 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) + \left( \frac{1}{2} P_1 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) \left[ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + \frac{\kappa_l}{r} V_l \right] \\ + \frac{\partial}{\partial r} \left( \frac{1}{2} R_l V_0^2 + P_0 V_0 U_l + \frac{\delta}{\delta-1} T_l \right) V_0 + \left( \frac{1}{2} R_l V_0^2 + P_0 V_0 U_l + \frac{\delta}{\delta-1} T_l \right) \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) = q_{l1} \quad (\text{eq. (D) in Per's notes})$$

$$\Leftrightarrow \left[ U_l \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + \frac{\kappa_l}{r} V_l \right] \left( \frac{1}{2} P_0 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) + \left[ V_0 \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) \right] \left( \frac{1}{2} R_l V_0^2 + P_0 V_0 U_l + \frac{\delta}{\delta-1} T_l \right) = q_{l1} \quad (III_1, b)$$

### Full system of equations

#### relations to the physical perturbations

$$Q_1(r, \theta) = \sum_l q_{l1}(r) X_l(\theta), \quad P_1(r, \theta) = \sum_l R_l(r) X_l(\theta), \quad p_1(r, \theta) = \sum_l T_l(r) X_l(\theta)$$

$$\vec{V}_1(r, \theta) = \hat{r} \sum_l U_l(r) X_l(\theta) + \hat{\theta} \sum_l V_l(r) Y_l(\theta)$$

#### $\theta$ -dependence

$$Y_l(\theta) = -\frac{\alpha_l}{l(l+1)} \frac{\partial X_l}{\partial \theta}, \quad X_l(\theta) = P_l(\cos \theta) = \text{associated Legendre polynomial with } m=0$$

$\alpha_l \neq 0$  and arbitrary (in Per's notes  $l=1, \alpha_1=2$ ) (either  $\kappa_l=-2$  or there is some sign error somewhere)

#### radial part of the mode $l$

$$\frac{\partial}{\partial r} U_l + P_0 \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + V_0 \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) R_l + \alpha_l \frac{P_l}{r} V_l = 0 \quad (I_1, b) \quad (\text{A in Per's notes})$$

$$P_0 V_0 \left[ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + \frac{1}{r} V_l \right] + P_0 U_l \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) + R_l V_0 \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) = -\frac{\delta T_l}{\delta r} \quad (II_1, b_1) \quad (\text{corresponds to his B, but wrong})$$

$$\frac{1}{\pi_l} P_0 V_0 \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) = \frac{l(l+1)}{\alpha_l} \quad (II_1, b_2) \quad (" " " " C, but wrong)$$

$$\left[ U_l \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + \frac{\kappa_l}{r} V_l \right] \left( \frac{1}{2} P_0 V_0^2 + \frac{\delta}{\delta-1} P_0 \right) + \left[ V_0 \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) \right] \left( \frac{1}{2} R_l V_0^2 + P_0 V_0 U_l + \frac{\delta}{\delta-1} T_l \right) = q_{l1} \quad (III_1, b) \quad (\text{D in Per's notes})$$