

Set of equations

$$\alpha_l = -l(l+1), \beta_l = -1$$

$$R_l = \left(\frac{P_l}{T_0} - \frac{P_0}{T_l} \right) T_l = \frac{1}{T_0} \left(P_l - P_0 T_l \right) \quad (0)$$

$$\frac{\partial \rho}{\partial r} U_l + P_0 \left[\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + \frac{\kappa_l}{r} V_l \right] + V_0 \frac{\partial R_l}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) R_l = 0 \quad (1)$$

$$P_0 V_0 \frac{\partial U_l}{\partial r} + P_0 \frac{\partial v_0}{\partial r} U_l + V_0 \frac{\partial v_0}{\partial r} R_l = -\frac{1}{8} \frac{\partial P_l}{\partial r} \quad (2)$$

$$P_0 V_0 \frac{\partial U_l}{\partial r} + P_0 \frac{v_0}{r} V_l = \frac{\beta_l}{r} \frac{1}{8} P_l \quad (3)$$

$$\left[U_l \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + \frac{\kappa_l}{r} V_l \right] \left((x-1) \frac{1}{2} P_0 V_0^2 + P_0 \right) + \left[V_0 \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0) \right] \left((x-1) \frac{1}{2} R_l V_0^2 + (x-1) P_0 V_0 U_l + P_l \right) = \frac{2}{\lambda_*} \frac{\partial Q_l}{\partial r} \quad (4)$$

$$\frac{\partial Q_l}{\partial r} = \lambda_* \left(R_l \frac{\partial}{\partial r} \Lambda(E_0) + P_0 Q_l \Lambda(E_0) + P_0 q_* \frac{\partial \Lambda}{\partial E} \Big|_{E_0} \varepsilon_l \right) \quad (5)$$

$$\frac{\partial E_l}{\partial r} = 2 \lambda_* \left(L(E_0) R_l + P_0 \frac{\partial L}{\partial E} \Big|_{E_0} \varepsilon_l \right) \quad (6)$$

Boundary conditions

$$T_1(r_p) = 0 \quad U_1(r_p) = 0 \quad V_1(r_p) = 0 \quad Q_1(r_p) = 0 \quad E_1(r_p) = 0 ?$$

$$P_1(\infty) = 0 \quad R_1(\infty) = 0 \quad Q_1(\infty) = q_0(\infty) \quad E_1(\infty) = E_0(\infty) = \frac{E_{c1}}{q_{nl}}$$

Put ODE in matrix form $\frac{d\vec{y}}{dr} = M \vec{y}$

define $\vec{y}_1 = (P_1, T_1, U_1, V_1, Q_1, E_1)^T$ now use $\alpha_l = -l(l+1) \rightarrow \alpha_1 = -2$
 $\beta_1 = -1$
and now abbreviate $\frac{\partial}{\partial r}$ with $(')$

$$(1): \frac{\partial \rho}{\partial r} U_l + P_0 \left[\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_l) + \frac{\kappa_l}{r} V_l \right] + V_0 \frac{\partial R_l}{\partial r} + \underbrace{\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_0)}_{\vec{J} \cdot \vec{v}_0} R_l = 0$$

$$\text{with } R'_1 = \left(\frac{P_1}{T_0} \right)' P_1 - \left(\frac{P_0}{T_0} \right)' T_1 + \frac{1}{T_0} P'_1 - \frac{P_0}{T_0} T'_1$$

$$\text{and } (r^2 U_l)' = 2r U_l + r^2 U'_l$$

$$P'_1 \left[V_0 \left(\frac{1}{T_0} \right)' + (\vec{V} \cdot \vec{v}_0) \frac{1}{T_0} \right] + T'_1 \left[-V_0 \left(\frac{P_0}{T_0} \right)' - (\vec{V} \cdot \vec{v}_0) \frac{P_0}{T_0} \right] + U'_1 \left[+P'_1 + P_0 \frac{2}{r} \right] + V'_1 \left[-\frac{2 P_0}{r} \right] = P'_1 \left[-\frac{V_0}{T_0} \right] + T'_1 \left[+\frac{V_0 P_0}{T_0} \right] + U'_1 \left[P_0 \right]$$

$$(2): P_0 V_0 \frac{\partial U_l}{\partial r} + P_0 \frac{\partial v_0}{\partial r} U_l + V_0 \frac{\partial v_0}{\partial r} R_l = -\frac{1}{8} \frac{\partial P_l}{\partial r}$$

$$\Leftrightarrow P'_1 \left[V_0 V'_0 \frac{1}{T_0} \right] + T'_1 \left[-V_0 V'_0 \frac{P_0}{T_0} \right] + U'_1 \left[P_0 V'_0 \right] = P'_1 \left[-\frac{1}{8} \right] + U'_1 \left[-P_0 V_0 \right]$$

$$(3): P_0 V_0 \frac{\partial U_l}{\partial r} + P_0 \frac{v_0}{r} V_l = \frac{\beta_l}{r} \frac{1}{8} P_l$$

$$\Leftrightarrow P_0 \left[\frac{1}{r} \right] + V_0 \left[\frac{V_0 P_0}{r} \right] = V'_1 \left[-\frac{1}{8} \right] + U'_1 \left[-P_0 V_0 \right] \quad k_1 = \left(\frac{1}{r} P_0 V_0 + \frac{1}{r} V'_1 P_0 \right)$$

$$(3) \cdot \nu_0 \frac{v_0}{\partial r} + \nu_0 \frac{r}{r} V_L = \frac{1}{r} \frac{\partial}{\partial r} M_L$$

$$\Leftrightarrow P_1 \cdot \left[\frac{1}{\partial r} \right] + V_1 \cdot \left[\frac{v_0}{r} \right] = V_1 \cdot \left[-\nu_0 v_0 \right] \quad k_0 = \left(\frac{1}{2} \rho_0 v_0^2 + \frac{1}{r-1} P_0 \right) \quad \vec{V} \cdot \vec{v}_0$$

$$(4): \left[U_1 \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 U_1) + \frac{K_L}{r} V_L \right] \underbrace{\left[(r-1) \frac{1}{2} \rho_0 v_0^2 + P_0 \right]}_{\vec{V} \cdot \vec{v}_0} + \left[V_0 \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_0) \right] \underbrace{\left[(r-1) \frac{1}{2} R_L v_0^2 + (r-1) \rho_0 v_0 (U_1 + P_1) \right]}_{\vec{V} \cdot \vec{v}_0} = \frac{2}{\lambda_*} \frac{\partial Q_L}{\partial r}$$

$$P_1 \cdot \left[(\vec{V} \cdot \vec{v}_0) \left(1 + (r-1) \frac{1}{2} v_0^2 \frac{1}{r} \right) + v_0 (r-1) \frac{1}{2} \left(\frac{v_0^2}{r_0} \right)' \right] + T_1 \cdot \left[-(\vec{V} \cdot \vec{v}_0) (r-1) \frac{1}{2} \frac{\rho_0 v_0^2}{r_0} - v_0 (r-1) \frac{1}{2} \left(\frac{P_0 v_0^2}{r_0} \right)' \right] \\ + U_1 \cdot \left[K_0 + \frac{2(r-1)}{r} k_0 + v_0 (r-1) (P_0 v_0)' + (\vec{V} \cdot \vec{v}_0) (r-1) P_0 v_0 \right] + V_1 \cdot \left[\frac{2(r-1)}{r} k_0 \right] = P_1 \cdot \left[-v_0 - v_0 (r-1) \frac{1}{2} \frac{v_0^2}{r_0} \right] + T_1 \cdot \left[v_0 (r-1) \frac{1}{2} \frac{v_0^2}{r_0} \right] \\ + U_1 \cdot \left[-(r-1) P_0 v_0^2 \right] + Q_1 \cdot \left[\frac{2}{\lambda_*} \right] \quad \left| \cdot \frac{1}{r-1} \right.$$

$$\Leftrightarrow P_1 \cdot \left[(\vec{V} \cdot \vec{v}_0) \left(\frac{1}{r-1} + \frac{1}{2} \frac{v_0^2}{r_0} \right) + \frac{1}{2} v_0 \left(\frac{v_0}{r_0} \right)' \right] + T_1 \cdot \left[-(\vec{V} \cdot \vec{v}_0) \frac{1}{2} \frac{\rho_0 v_0^2}{r_0} - \frac{1}{2} v_0 \left(\frac{P_0 v_0^2}{r_0} \right)' \right] + U_1 \cdot \left[k_0 + \frac{2}{r-1} k_0 + v_0 (P_0 v_0)' + (\vec{V} \cdot \vec{v}_0) P_0 v_0 \right] + V_1 \cdot \left[-\frac{2}{r-1} k_0 \right] \\ = P_1 \cdot \left[\frac{v_0}{r-1} - \frac{1}{2} \frac{v_0^3}{r_0} \right] + T_1 \cdot \left[\frac{1}{2} \frac{\rho_0 v_0^3}{r_0} \right] + U_1 \cdot \left[-k_0 - P_0 v_0^2 \right] + Q_1 \cdot \left[\frac{2}{(r-1)\lambda_*} \right]$$

$$(5): \frac{\partial Q_L}{\partial r} = \lambda_* \left(R_L \wedge \Lambda(E_0) + P_0 Q_L \wedge \Lambda(E_0) + P_0 q_0 \frac{\partial \Lambda}{\partial E} \Big|_{E_0} \varepsilon_C \right)$$

$$\Leftrightarrow P_1 \cdot \left[\frac{q_0 \Lambda(E_0)}{r_0} \right] + T_1 \cdot \left[\lambda_* \frac{P_0 q_0 \Lambda(E_0)}{r_0} \right] + Q_1 \cdot \left[P_0 \Lambda(E_0) \right] + \varepsilon_1 \cdot \left[P_0 q_0 \frac{\partial \Lambda}{\partial E} \Big|_{E_0} \right] = Q_1'$$

$$(6): \frac{\partial E_L}{\partial r} = 2 \lambda_* \left(L(E_0) R_L + P_0 \frac{\partial L}{\partial E} \Big|_{E_0} \varepsilon_C \right)$$

$$\Rightarrow P_1 \cdot \left[2 \lambda_* \frac{L(E_0)}{r_0} \right] + T_1 \cdot \left[-2 \lambda_* \frac{\partial L}{\partial E} \Big|_{E_0} \right] + \varepsilon_1 \cdot \left[2 \lambda_* P_0 \frac{\partial L}{\partial E} \Big|_{E_0} \right] = \varepsilon_1'$$

In total as the matrix equation $A \vec{y} = B \vec{y}$

with

$$A = \begin{pmatrix} P_1 & T_1 & U_1 & V_1 & Q_1 & \varepsilon_1 \\ (1) & -\frac{v_0}{r_0} & \frac{v_0 P_0}{r_0} & -P_0 & 0 & 0 \\ (2) & -\frac{1}{r} & 0 & -P_0 v_0 & 0 & 0 \\ (3) & 0 & 0 & 0 & -P_0 v_0 & 0 \\ (4) & \left(-\frac{v_0}{r-1} - \frac{1}{2} \frac{v_0^3}{r_0} \right) & \frac{1}{2} \frac{\rho_0 v_0^3}{r_0} & -k_0 - P_0 v_0^2 & 0 & \frac{2}{(r-1)\lambda_*} 0 \\ (5) & 0 & 0 & 0 & 0 & 1 \\ (6) & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$B = \begin{pmatrix} P_1 & T_1 & U_1 & V_1 & Q_1 & \varepsilon_1 \\ (1) & v_0 \left(\frac{1}{r_0} \right)' + (\vec{V} \cdot \vec{v}_0) \frac{1}{r_0} & -v_0 \left(\frac{P_0}{r_0} \right)' - (\vec{V} \cdot \vec{v}_0) \frac{P_0}{r_0} & P_0 + \frac{2}{r} P_0 & -\frac{2}{r} P_0 & 0 \\ (2) & v_0 v_0' \frac{1}{r_0} & -v_0 v_0' \frac{P_0}{r_0} & P_0 v_0' & 0 & 0 \\ (3) & \frac{1}{r} & 0 & 0 & \frac{1}{r} v_0 P_0 & 0 \\ (4) & \left(\vec{V} \cdot \vec{v}_0 \right) \left(\frac{1}{r-1} + \frac{1}{2} \frac{v_0^2}{r_0} \right) + \frac{1}{2} v_0 \left(\frac{v_0}{r_0} \right)' & -\left(\vec{V} \cdot \vec{v}_0 \right) \frac{1}{2} \frac{\rho_0 v_0^2}{r_0} - \frac{1}{2} v_0 \left(\frac{P_0 v_0^2}{r_0} \right)' & k_0' + \frac{2}{r} k_0 + v_0 (P_0 v_0)' + (\vec{V} \cdot \vec{v}_0) P_0 v_0 & -\frac{2}{r} k_0 & 0 \\ (5) & \lambda_* \frac{q_0 \Lambda(E_0)}{r_0} & -\lambda_* \frac{P_0 q_0 \Lambda(E_0)}{r_0} & 0 & 0 & \lambda_* P_0 \Lambda(E_0) \\ (6) & 2 \lambda_* \frac{L(E_0)}{r_0} & -2 \lambda_* \frac{\partial L}{\partial E} \Big|_{E_0} & 0 & 0 & 2 \lambda_* P_0 \frac{\partial L}{\partial E} \Big|_{E_0} \end{pmatrix}$$