

project\_b4/reconstruction/preprocessing/feature\_generation.py  
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```
1 import numpy as np
2 import matplotlib.pyplot as plt
3
4 class FeatureGenerator():
5     """This class generates features for an event
6
7     Based on the values measured in the detector, arbitrary features
8     can be generated. These can be used for machine learning exercises
9     such as classifying the particle type or estimating energy and
10    ↪ origin.
11    """
12
13    def __init__(self, detector):
14        """Sets up the feature generator
15
16        Parameters
17        -----
18        detector : Detector object
19            A detector object for which the feature generator will be
20    ↪ set up.
21        """
22        self.detector = detector
23
24    def analyse(self, event):
25        """Reconstruct an event measured in the assigned detector.
26
27        Parameters
28        -----
29        event : Event
30            The event which we want to reconstruct.
31
32        Returns
33        -----
34        Features: Dict
35            A dictionary of arbitrary features.
36            Values are to be scalar to be fed into a random forest
37    ↪ """
38    ↪ # -----
39    ↪ # Exercise 18 (Sheet 9):
40    ↪ # -----
```

```

39     # Feature Generation (exercises/feature_generation.py)
40
41     mean = np.mean(event.pixels)
42     max = np.max(event.pixels)
43
44     features = {
45         'max_pixel_value': max,
46         'variance_pixel_value': np.var(event.pixels),
47         'mean_pixel_value': mean,
48         '(max/mean)_pixel_value': max/mean,
49         'pixels_above_half_max': (event.pixels > 0.5*max).sum(),
50         'pixels_above_mean': (event.pixels > mean).sum()
51     }
52
53
54     return features

```