

Difeomorfismo

$$z_1 = x_1 + x_2$$

$$z_3 = -\frac{K_s x_2 - g \hbar m \sin(x_1 + x_2)}{J_l}$$

$$z_2 = x_3 + x_4$$

$$z_4 = \frac{g \hbar m x_3 \cos(x_1 + x_2)}{J_l} - x_4 \left(\frac{K_s}{J_l} - \frac{g \hbar m \cos(x_1 + x_2)}{J_l} \right)$$

Difeomorfismo Evaluado

$$z1 = x_1 + x_2$$

$$z2 = x_3 + x_4$$

$$z3 = -\frac{3600434686208869 x_2}{13194139533312} - \frac{707282807527887 \sin(x_1 + x_2)}{17592186044416}$$

$$z4 = -\frac{707282807527887 x_3 \cos(x_1 + x_2)}{17592186044416} - x_4 \left(\frac{707282807527887 \cos(x_1 + x_2)}{17592186044416} + \frac{3600434686208869}{13194139533312} \right)$$

Señal de control (FL)

u =

$$\frac{v + x_3 \sigma_1 + x_4 \sigma_1 + \sigma_2 \left(\frac{g \text{ hcm } m \sin(x_1 + x_2)}{J_l} - x_2 \left(\frac{K_s}{J_h} + \frac{K_s}{J_l} \right) + \sigma_3 \right) - \frac{g \text{ hcm } m \cos(x_1 + x_2) \left(\frac{K_s x_2}{J_h} - \sigma_3 \right)}{J_l}}{\frac{K_g K_m \sigma_2}{J_h R_m} + \frac{K_g K_m g \text{ hcm } m \cos(x_1 + x_2)}{J_h J_l R_m}}$$

where

$$\sigma_1 = \frac{g \text{ hcm } m x_3 \sin(x_1 + x_2)}{J_l} + \frac{g \text{ hcm } m x_4 \sin(x_1 + x_2)}{J_l}$$

$$\sigma_2 = \frac{K_s}{J_l} - \frac{g \text{ hcm } m \cos(x_1 + x_2)}{J_l}$$

$$\sigma_3 = \frac{K_g^2 K_m^2 x_3}{J_h R_m}$$

Señal de control (FL) Evaluada

u =

$$\begin{aligned} & \frac{39582418599936 \nu}{1062128232431616355} + \frac{6365545267750983 \cos(x_1 + x_2) \left(\frac{2300 x_2}{3} - \frac{3715129576983801 x_3}{70368744177664} \right)}{4248512929726465420} - \frac{39582418599936 x_3 \sigma_1}{1062128232431616355} - \frac{39582418599936 x_4 \sigma_1}{1062128232431616355} - \\ & - \frac{39582418599936 \left(\frac{707282807527887 \cos(x_1 + x_2)}{17592186044416} + \frac{3600434686208869}{13194139533312} \right) \left(\frac{4571980553916023 x_2}{4398046511104} - \frac{3715129576983801 x_3}{70368744177664} + \frac{707282807527887 \sin(x_1 + x_2)}{17592186044416} \right)}{1062128232431616355} \end{aligned}$$

where

$$\sigma_1 = \frac{707282807527887 x_3 \sin(x_1 + x_2)}{17592186044416} + \frac{707282807527887 x_4 \sin(x_1 + x_2)}{17592186044416}$$

Derivadas de Lie

$$L_{f1} = x_3 + x_4$$

$$L_{f2} =$$

$$\frac{K_s x_2}{J_h} - x_2 \left(\frac{K_s}{J_h} + \frac{K_s}{J_l} \right) + \frac{g_{hcm} m \sin(x_1 + x_2)}{J_l}$$

$$L_{f3} =$$

$$\frac{g_{hcm} m x_3 \cos(x_1 + x_2)}{J_l} - x_4 \left(\frac{K_s}{J_l} - \frac{g_{hcm} m \cos(x_1 + x_2)}{J_l} \right)$$

$$L_{f4} =$$

$$\frac{g_{hcm} m \cos(x_1 + x_2) \left(\frac{K_s x_2}{J_h} - \sigma_2 \right)}{J_l} - x_4 \sigma_1 - \left(\frac{K_s}{J_l} - \frac{g_{hcm} m \cos(x_1 + x_2)}{J_l} \right) \left(\frac{g_{hcm} m \sin(x_1 + x_2)}{J_l} - x_2 \left(\frac{K_s}{J_h} + \frac{K_s}{J_l} \right) + \sigma_2 \right) - x_3 \sigma_1$$

where

$$\sigma_1 = \frac{g_{hcm} m x_3 \sin(x_1 + x_2)}{J_l} + \frac{g_{hcm} m x_4 \sin(x_1 + x_2)}{J_l}$$

$$\sigma_2 = \frac{K_g^2 K_m^2 x_3}{J_h R_m}$$

Derivadas de Lie Evaluada

$$Lf_h = x_3 + x_4$$

$$Lf_{2h} = -\frac{3600434686208869 x_2}{13194139533312} - \frac{707282807527887 \sin(x_1 + x_2)}{17592186044416}$$

$$Lf_{3h} = -\frac{707282807527887 x_3 \cos(x_1 + x_2)}{17592186044416} - x_4 \left(\frac{707282807527887 \cos(x_1 + x_2)}{17592186044416} + \frac{3600434686208869}{13194139533312} \right)$$

La cuarta derivada de Lie no se puede poner por ser una ecuación demasiado extensa

Grado Relativo / Derivadas Cruzadas

$$L_{gh} = 0$$

$$L_{gLfh} = 0$$

$$L_{gLf2h} = 0$$

$$L_{gLf3h} =$$

$$\frac{K_g K_m \left(\frac{K_s}{J_l} - \frac{g h c m m \cos(x_1 + x_2)}{J_l} \right)}{J_h R_m} + \frac{K_g K_m g h c m m \cos(x_1 + x_2)}{J_h J_l R_m}$$

Grado Relativo Evaluado / Derivadas Cruzadas Evaluadas

$$L_{gh} = 0$$

$$L_{gLfh} = 0$$

$$L_{gLf2h} = 0$$

$$L_{gLf3h} = \frac{1062128232431616355}{39582418599936}$$