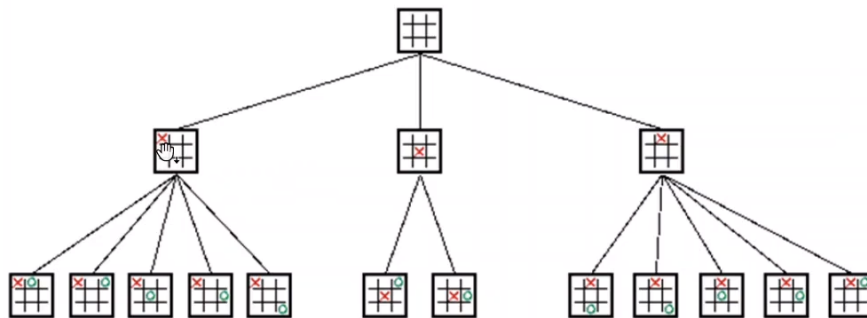
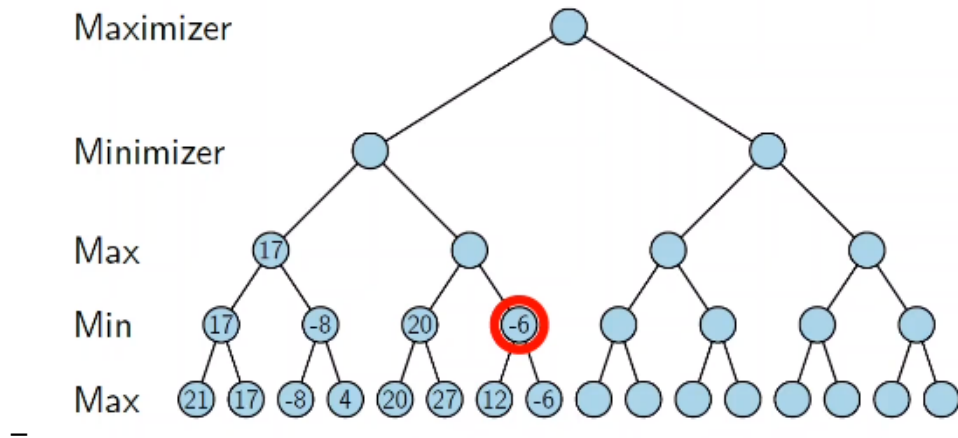


## Classical Approach

- starting position as root
  - during game the current position
- states as nodes
- possible moves as edges to child nodes
  - states may be reached by multiple move sequences
  - performance improvement possible
    - \* no longer a tree
- tree depth is bounded
  - exponential overhead
  - combinatorial explosion
- half move
  - own move + opponents move = full move
  - must also consider the opponents answer move
  - k half moves
    - \*  $\lfloor \frac{k}{2} \rfloor (+1)$  moves per player

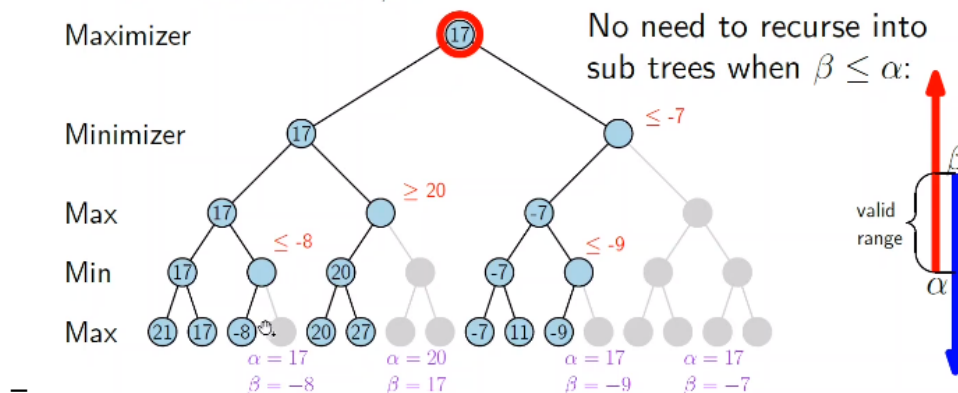


- - not shown possible moves are symmetrical
- leaves nodes are evaluated using heuristics
  - heuristic scores the game state
  - terminal states (win, lose) have extreme values
  - non-leave nodes evaluated by traversing the tree downwards
    - \* chooses maximum/minimum score of available moves
- maximizer and minimizer
  - one player wants to maximize the value of all child nodes
  - other player wants to minimize the value of all child nodes



### $\alpha$ - $\beta$ Pruning

- prevents combinatorial explosion
  - reduces states to consider
    - combines states with identical outcome
  - more efficient and equal results as the classical approach
  - stops traversing tree downwards upon reaching
    - a minimum value smaller than current maximum
    - a maximum value larger than current minimum
- $\alpha$ : Lower bound for maximizer: no need to consider states with scores below  $\alpha$ .
- $\beta$ : Upper bound for minimizer: no need to consider states with scores above  $\beta$ .



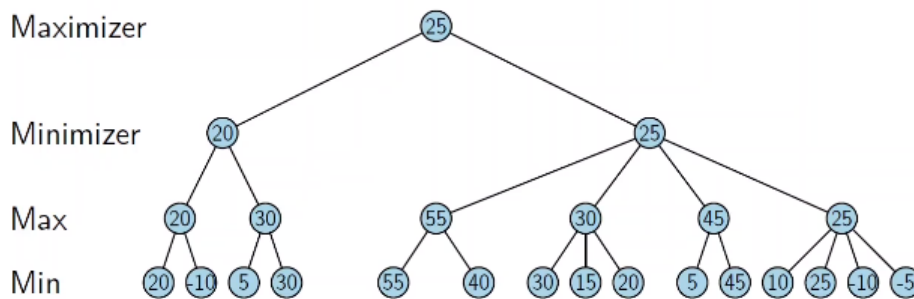
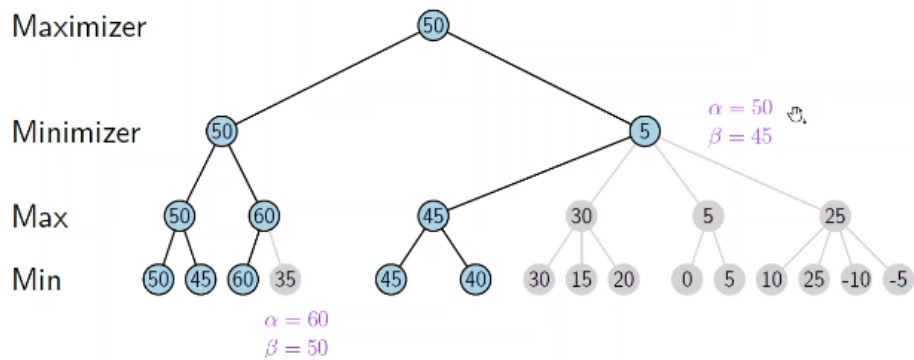
- pseudo code

```

evaluate (node, alpha, beta)
  if node is a leaf
    return (heuristic value of node)
  if node is a minimizing node
    for each child of node
      beta = min (beta, evaluate (child, alpha, beta))
      if beta <= alpha
        return (alpha)
    return (beta)
  if node is a maximizing node
    for each child of node
      alpha = max (alpha, evaluate (child, alpha, beta))
      if beta <= alpha
        return (beta)
    return (alpha)
_ evaluate(root,  $-\infty$ ,  $\infty$ );

```

- examples



How much can we save with  $\alpha$ - $\beta$  pruning?

– Sometimes nothing!

- pre-sorted  $\alpha$  –  $\beta$  pruning

– efficiency depends on order of states

Consider potentially best states first (large values for maximizer, small (large negativ) for minimizer)