

3 February 2025

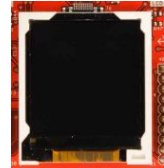
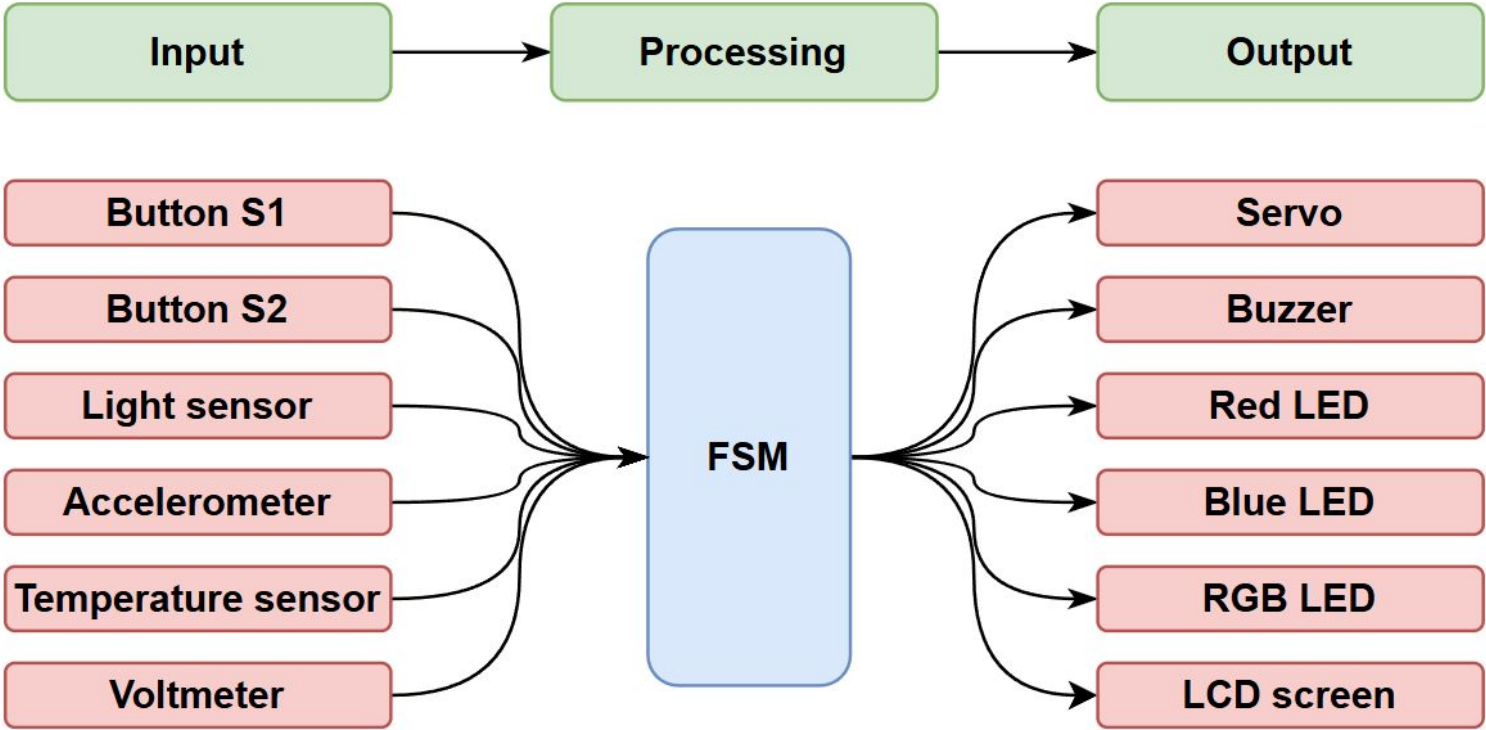
Sylvanian Tech Family

A Comprehensive Overview of Our System's Core Design and Implementation

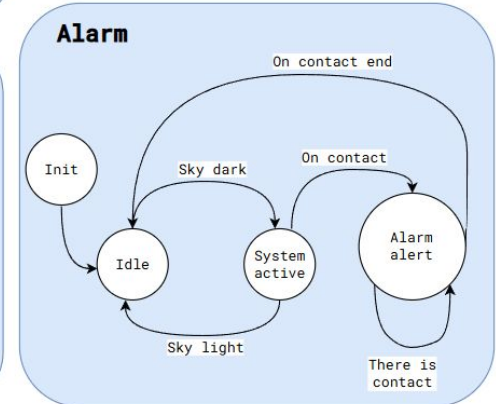
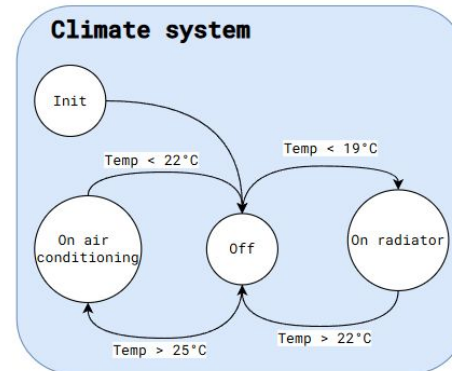
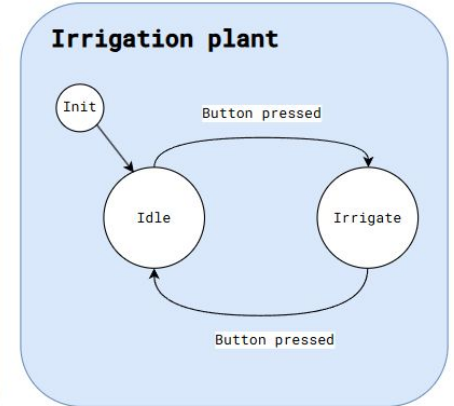
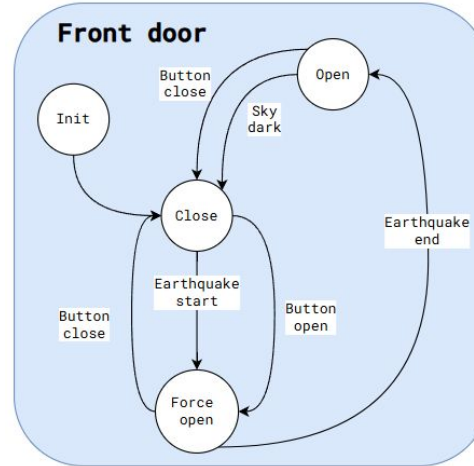
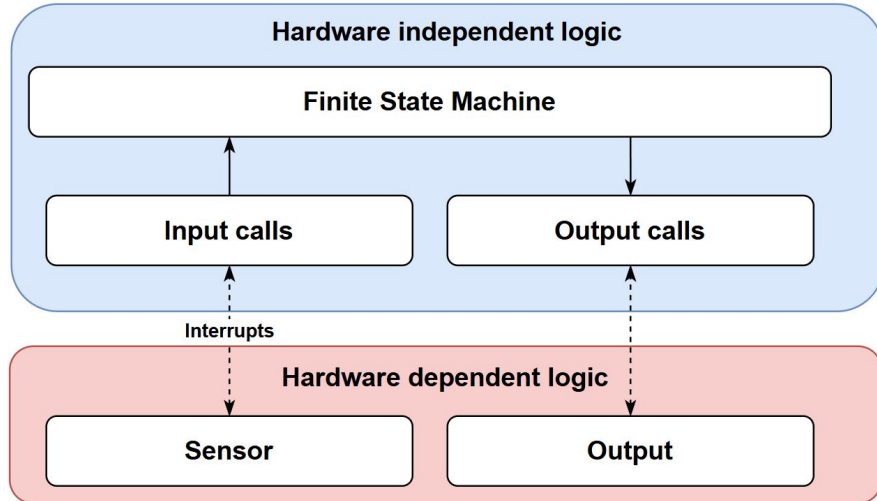


Cristiano Berardo, Martina De Piccoli, Nicola Lovo, Matilde Prati

Hardware and Software



Software Architecture



Team Member Contributions

Team member	Macro area	Implemented	Used	Most rappresentative lines of code	Approx code lines
Nicola	Front door	-Servo + Timer A0 -Button S2 -Light sensor -Accelerometer -LCD Display	-Servo + Timer A0 -Button S2 -Light sensor -Accelerometer -LCD Display	<pre>// Map 0-180 degrees to pwm pulse float dutyCycle = SERVO_MIN_DUTY_CYCLE + ((angle / 180.0f) * (SERVO_MAX_DUTY_CYCLE-SERVO_MIN_DUTY_CYCLE)); // Update the PWM duty cycle MAP_Timer_A_setCompareValue(TIMER_A0_BASE, TIMER_A_CAPTURECOMPARE_REGISTER_2, (uint16_t)dutyCycle);</pre>	232
Matilde	Climate system	-Temperature sensor -RGB led	-Temperature sensor -RGB led -LCD Display	<pre>float tempFarenheit = TMP006_getTemp(); float tempC = (tempFarenheit - 32) * 5.0/9.0;</pre>	227
Martina	Irrigation system	-Blue led -Button S1 -Accelerometer + ADC	-Blue led -Button S1 -LCD Display	<pre>resultsBuffer[0] = ADC14_getResult(ADC_MEM0); // X-axis resultsBuffer[1] = ADC14_getResult(ADC_MEM1); // Y-axis resultsBuffer[2] = ADC14_getResult(ADC_MEM2); // Z-axis // Accelerometer stats reading accelerometer_on_read(resultsBuffer);</pre>	239
Cristiano	Alarm	-Buzzer + Timer A0 -Red led -Light sensor -Voltmeter	-Buzzer + Timer A0 -Red led -Light sensor -Voltmeter -LCD Display	<pre>return GPIO_getInputPinValue(ALLIGATOR_CLIP_PORT, ALLIGATOR_CLIP_PIN) == GPIO_INPUT_PIN_LOW;</pre>	270

Testing

Testing Methods:

Assert MACRO: Each team member tested their FSM using the assert.h library.

Black-Box: Each team member tested the HW dependent part as a black-box, assessing the correctness of the result.

```
assert(door_current_state == DOOR_STATE_OPEN);  
run_door_fsm();  
  
door_event_skyDark();  
assert(door_current_state == DOOR_STATE_CLOSE);  
run_door_fsm();
```

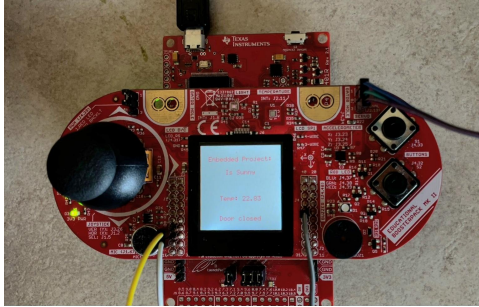
Challenges and Solution:

Accelerometer: it didn't work properly on the first MCU we used, displaying corrupted data

Door servo: the duty cycle slightly varies from the datasheet, so it needed a little bit of tweaking before working properly

Voltmeter: has been a challenge to figure out how it works. In the end, it is quite similar to a push-button

Conclusion and Future Work



Conclusion:

The system has achieved the desired goals, achieving efficient integration of hardware and software.

Future Improvements:

1. implements sensor data saving through a connection to MongoDB
2. web app and bot telegram to monitor the real-time status of the house

Thanks for the attention!

