

Nicolai Häni

✉ haeni001@umn.edu

🌐 <https://nicolai-haeni.github.io/>

🌐 www.linkedin.com/in/nicolai-haeni

RSN Lab
133 Shepherd Laboratories
100 Union S.E.
Minneapolis, MN 55455, USA

Education

2017–Current	Ph.D. Computer Science, University of Minnesota, Minneapolis, USA Advisor: Professor Volkan Isler
2013–2015	M.Sc. Industrial Technologies, Zurich University of Applied Sciences, Zurich, Switzerland Thesis title: <i>Development of an Eye-in-Hand Vision System for Orchard Inspection</i>
2009–2012	B.Sc. System Engineering, Zurich University of Applied Sciences, Zurich, Switzerland

Employment History

2017–Current	Graduate Research Assistant , Robotic Sensor Networks Laboratory (RSN), University of Minnesota, Minneapolis, USA.
2015–2016	Software Engineer , Pix4D SA, Lausanne, Switzerland
2012–2015	Graduate Research Assistant , Institute of Mechatronic Systems, Zurich University of Applied Sciences, Zurich, Switzerland

Selected Publications

Häni, N., Roy, P., & Isler, V. (2018a, October). A Comparative Study of Fruit Detection and Counting Methods for Yield Mapping in Apple Orchards. *arXiv:1810.09499 [cs]*. arXiv: 1810.09499. January 27, 2019, <http://arxiv.org/abs/1810.09499>

Häni, N., Roy, P., & Isler, V. (2018b, October). Apple Counting using Convolutional Neural Networks. In *2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)* (pp. 2559–2565). Madrid, Spain: IEEE. doi:10.1109/IROS.2018.8594304

Becker, C., Häni, N., Rosinskaya, E., d'Angelo, E., & Strecha, C. (2017, May). Classification of Aerial Photogrammetric 3D Point Clouds. *ISPRS Annals of Photogrammetry, Remote Sensing and Spatial Information Sciences, IV-1/W1*, 3–10. doi:10.5194/isprs-annals-IV-1-W1-3-2017

Häni, N. & Isler, V. (2016, October). Visual servoing in orchard settings. In *2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)* (pp. 2946–2953). Daejeon, South Korea: IEEE. doi:10.1109/IROS.2016.7759456

Research & Industry Projects

2017–Current	Research at RSN Lab, University of Minnesota <ul style="list-style-type: none">• Proposed a new end-to-end deep learning method to count clustered fruits from images in orchard environments.• Designed a hand-in-eye robotic manipulator system for close up fruit inspection in apple orchards.
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Research & Industry Projects (continued)

- 2015-2016 **Pix4D SA**
- Implemented a novel machine learning pipeline to classify aerial point clouds using local descriptive features in C++.
 - Implemented a real-time image processing algorithm to remove sky pixels from the Structure-from-Motion (SfM) pipeline in C++.
- 2012-2015 **Institute of Mechatronic Systems (IMS), Zurich University of Applied Sciences**
- Implemented a virtual reality-based approach to guide a robotic catheter for cardiovascular surgery.
 - Developed a high-performance and low-cost mobile mapping device to enable autonomous navigation of a weeding robot

Awards and Achievements

- 2019 **ASPRS Talbert Abrams Award** for the paper: *Classification of Aerial Photogrammetric 3D Point Clouds*, Lausanne, Switzerland
- 2018 **Quality Metrics Fellowship**, Department of Computer Science and Engineering, University of Minnesota, USA
- 2017 **Best Poster Award** for *Robotic Monitoring of Apple Orchards*, 11th Biennial Research Showcase, Department of Computer Science and Engineering, University of Minnesota, USA
- 2016 **Best Master Thesis Award**, Swiss Society of Advanced Control, Switzerland

Teaching

- 2017 CSCI 2033, Elementary Computational Linear Algebra

Technical Skills

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| Programming Languages | C/C++, Python, MATLAB, R, Java, HTML |
| Software & Libraries | OpenCV, PCL, PyTorch, Tensorflow, LaTeX, Github, SVN, Robot Operating System (ROS) |