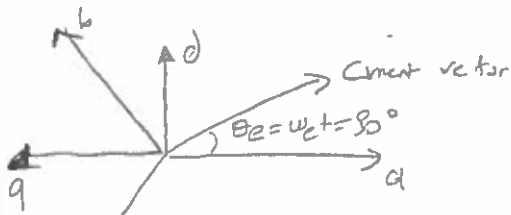


Q1) (1) $\omega_e = 2\pi 50$



$\omega_e t = 30 \quad T = \frac{T/6}{2\pi 50} = \frac{1}{600} = 1,66 \times 10^{-3} = 0,00166 \text{ s}$

$T = \frac{1}{50} = 0,02 \text{ s}$

And $I_{pk} = 10 \text{ A} \quad \omega_e t = 30^\circ$

$I_a = I_{pk} \cos(\omega_e t) = 10 \cos(30^\circ) = 8,66 \text{ A}$

$I_b = I_{pk} \cos(\omega_e t - 120^\circ) = 10 \cos(30 - 120) = 0 \text{ A}$

$I_c = I_{pk} \cos(\omega_e t + 120^\circ) = 10 \cos(30 + 120) = -8,66 \text{ A}$

(2) for current;

$$\bar{I} = \frac{2}{3} \left(I_a e^{j0} + I_b e^{j\frac{2\pi}{3}} + I_c e^{-j\frac{2\pi}{3}} \right)$$

$$\bar{I} = \frac{2}{3} I_{pk} [\cos(\omega_e t) + \cos(\omega_e t - 120) e^{j120} + \cos(\omega_e t + 120) e^{-j120}]$$

$$\bar{I} = \frac{2}{3} I_{pk} [\cos(\omega_e t) + \cos(\omega_e t - 120) \cos(120) + \cos(\omega_e t + 120) \cos(120)]$$

$$\bar{I} = \frac{2}{3} I_{pk} [\cos(\omega_e t) + \frac{1}{2} (\cos(\omega_e t - 120) + \cos(\omega_e t + 120))]]$$

$$\text{from } \cos \alpha \cdot \cos \beta = \frac{\cos(\alpha + \beta) + \cos(\alpha - \beta)}{2}$$

$$\bar{I} = \frac{2}{3} I_{pk} [\cos(\omega_e t) - \cos(\omega_e t) \cdot \cos(120^\circ)]$$

$$\bar{I} = \frac{2}{3} \cdot 10 \cdot \frac{1}{2} \cos(\omega_e t) = 10 \cos(\omega_e t) \quad (\text{Real part})$$

$$\bar{I} = \frac{2}{3} I_{pk} [\cos(\omega_e t - \frac{2\pi}{3}) e^{j\frac{2\pi}{3}} + \cos(\omega_e t + \frac{2\pi}{3}) e^{-j\frac{2\pi}{3}}] \quad (\text{Imaginary Part})$$

$$= \frac{2}{3} I_{pk} [\cos(\omega_e t - \frac{2\pi}{3}) \sin \frac{2\pi}{3} + \cos(\omega_e t + \frac{2\pi}{3}) (-\sin \frac{2\pi}{3})]$$

$$= \frac{2}{3} I_{pk} [\cos(\omega_e t - \frac{2\pi}{3}) \frac{\sqrt{3}}{2} + \cos(\omega_e t + \frac{2\pi}{3}) (-\frac{\sqrt{3}}{2})]$$

$$= \frac{2}{3} \cdot \frac{\sqrt{3}}{2} 10 \sin \dots$$

long version

(2)

$$f_a = f_m \cos(\omega + 30^\circ)$$

$$f_b = f_m \cos(\omega t - 120^\circ + 30^\circ) \quad (\omega t + 30^\circ = \omega t')$$

$$f_c = f_m \cos(\omega t + 120^\circ + 30^\circ)$$

$$f_{abc} = \frac{2}{3} \int m (\cos(\omega t) e^{j\omega} + \cos(\omega t) - 120) e^{j120} + \cos((\omega t) + 120) e^{-j120})$$

$$\bar{I}_{uk} = \frac{2}{3} I_{pk} \left(\frac{1}{2} (e^{j\omega t'} + e^{-j\omega t'}) e^{j0} + \frac{1}{2} (e^{j\omega t' - 120} + e^{-j\omega t' + 120}) e^{j120} + \dots \right. \\ \left. \dots + \frac{1}{2} (e^{j\omega t' + 120} + e^{-j\omega t' + 120}) e^{-j120} \right)$$

$$L \rightarrow = \frac{2}{3} I p k \frac{1}{2} \left[(e^{j(\omega t' + \phi_0)} + e^{-j\omega t' + 0}) + (e^{j\omega t' + 120 + 120} + e^{-j\omega t' + 120 + 120}) + \dots \right. \\ \left. \dots + (e^{j\omega t' + 120 - 120} + e^{-j\omega t' + 120 - 120}) \right]$$

$$= \frac{2}{3} I_{pk} \frac{1}{2} \cdot 3 \left(e^{j\omega t} + e^{-j\omega t} \left(\frac{1 + e^{-j120^\circ}}{1 + e^{j120^\circ}} \right) \right)$$

$$= \frac{2}{3} T_p \pm \frac{3}{2} e^{5\omega t}$$

$$\bar{I}_{abc} = I_{pk} e^{j\omega t} = \underline{I_{pk} e^{j\omega t + 90}}$$

$$I_D = \Re \left(\frac{\overline{I_{abc}}}{e^{j\omega t + 90^\circ}} \right) = \Re \left(I_{PL} \frac{e^{j(\omega t + 90^\circ)} \cdot e^{-j(\omega t + 90^\circ)}}{e^{j\omega t + 90^\circ}} \right) = \Re (I_{PL} e^{-j60^\circ}) = I_{PL} \cos(-60^\circ)$$

$$I_q = \operatorname{Re} \left(\frac{\overline{I_{abc}}}{e^{j\omega t + 180^\circ}} \right) = \operatorname{Re} \left(I_r \cdot e^{j(\omega t + 20^\circ)} \cdot e^{-j(\omega t + 180^\circ)} \right) = \operatorname{Re} (I_r \cdot e^{-j160^\circ}) = I_r \cdot \cos(-160^\circ)$$

shorter version of (2)

Q1) (3) $t = 0,05$

$$\omega_e t = 2\pi \times 0,05 = \pi = 180^\circ$$

$$\theta = \underbrace{180}_{\text{time}} + \underbrace{30}_{\text{beginning}} + \underbrace{90}_{\text{difference}} = 300^\circ$$

I. for current

$$\vec{I} = 10 (e^{j\omega t})$$

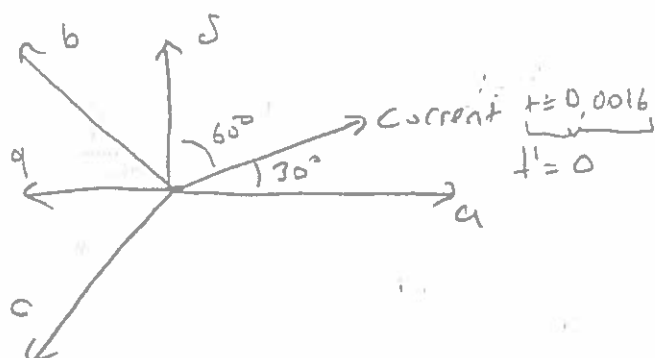
$$\vec{f_d} = \text{Re} \left(\frac{\vec{I}}{e^{j300}} \right) = \text{Re} (10 e^{j\omega t} \cdot e^{-j300})$$

$$= 10 \cos (\omega_e t - 300)$$

$$\vec{f_q} = \text{Re} \left(\frac{\vec{I}}{e^{j30}} \right) = \text{Re} (10 e^{j\omega t} \cdot e^{-j30})$$

$$= 10 \cos (\omega_e t - 30)$$

Case 1



$$\theta_{d1} = 90^\circ$$

$$\theta_{c1} = 30^\circ$$

d frame is always leading current frame

$$0,05 \text{ s} \Rightarrow \frac{0,05}{0,02} = 2,5 \text{ rotation}$$

$$\theta_{\text{lead}} = \Delta_d - \Delta_c = (300 - 90) - (210 - 30) = 30^\circ \text{ in } 2,5 \text{ rotation}$$

$$\Delta \omega_e, t = \theta_{\text{lead}}$$

$$2\pi (f_{dq} - f_c) \cdot t = \theta_{\text{lead}}$$

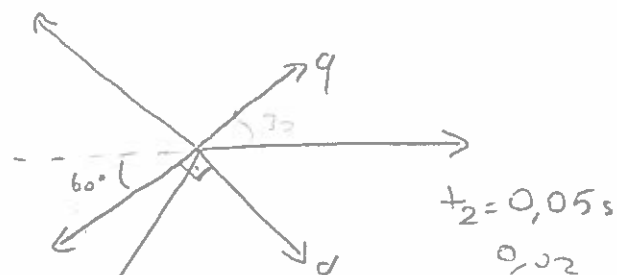
$$2\pi (f_{dq} - 50) \cdot t = 12$$

$$f_{dq} - 50 = 1,66$$

$$f_{dq} = 51,66$$

$$\omega_e = 2\pi \cdot 51,66 \text{ rad/s}$$

case 2



$$\theta_{d2} = 300^\circ$$

$$\theta_{c2} = 210^\circ$$

$$12^\circ \Leftarrow 1 \text{ rotation}$$

10-10-10

10-10-10

10-10-10

10-10-10

P2 2016

2d

$$i) m_{bscs} = L_{aa2} \operatorname{Re} \left(\frac{e^{j\theta}}{e^{j120}} \right) \operatorname{Re} \left(\frac{e^{j\theta}}{e^{j120}} \right) + L_{aad} \operatorname{Re} \left(\frac{e^{j(\theta-90)}}{e^{j120}} \right) \operatorname{Re} \left(\frac{e^{j(\theta-90)}}{e^{j120}} \right)$$

$$\cancel{L_{aad} \cos(\theta) \cos(\theta)}$$

$$= L_{aa2} \cos(\theta-120) \cos(\theta+120) + L_{aad} \sin(\theta-120) \sin(\theta+120)$$

$$= L_{aa2} \frac{\cos(2\theta) + \cos(-240)}{2} + L_{aad} \frac{\cos(-240) - \cos(2\theta)}{2}$$

$$= \frac{1}{2} (L_1 \cos(2\theta) + L_1 \cos(-240) + L_1 \cos(-240) - L_1 \cos(2\theta) - L_2 \cos(2\theta) + L_2 \cos(-240) - L_2 \cos(2\theta) + L_2 \cos(-240))$$

$$L_{aa2} = L_1 - L_2$$

$$L_{aad} = L_1 + L_2$$

$$\frac{1}{2} (-L_1 - 2L_2 \cos(2\theta)) = -\frac{1}{2} L_1 - L_2 \cos(2\theta)$$

$$\text{Max is at } \theta = \frac{\pi}{2} \Rightarrow -\frac{1}{2} L_1 + L_2$$

$$\text{Min is at } \theta = 0 \Rightarrow -\frac{1}{2} L_1 - L_2$$

$$2) m_{crsb} = ?$$

$$\text{or } m_{crsb} = ? \Rightarrow L_{aa2} \operatorname{Re} \left(\frac{e^{j\theta}}{e^{j120}} \right) \operatorname{Re} \left(\frac{e^{j\theta}}{e^{j(\theta+120)}} \right) + L_{aad} \operatorname{Re} \left(\frac{e^{j(\theta-90)}}{e^{j120}} \right) \operatorname{Re} \left(\frac{e^{j(\theta-90)}}{e^{j(\theta+120)}} \right)$$

$$\Rightarrow L_{aa2} \cos(\theta-120) \cos(-240) + L_{aad} \sin(\theta-120) \sin(-240)$$

$$\Rightarrow -0.5 L_{aa2} \cos(\theta-120) + \frac{\sqrt{3}}{2} L_{aad} \sin(\theta-120)$$

$$-0.5 (L_1 \cos(\theta-120) - L_2 \cos(\theta-120)) + \frac{\sqrt{3}}{2} (L_1 \sin(\theta-120) + L_2 \sin(\theta-120))$$

$$L_{aa2} \left(\frac{1}{2} (\cos(\theta) + \cos(\theta-240)) \right) + \frac{\sqrt{3}}{2} L_{aad} \sin(\theta-120)$$

3)

P2 2014

$$\frac{2\pi \omega}{60} = 120 \text{ rpm}$$

$$\frac{60}{2\pi} \omega = 120 \text{ rpm}$$
$$\omega = 12.57 \text{ rad/s}$$

$$p = 2$$

$$\omega_r = ?$$

$$f_{\alpha} + j f_{\beta} = \cancel{f_{\alpha}} (i_{\alpha} - j i_{\beta}) e^{j 90}$$

$$\Rightarrow \bar{v}_{qds} = (R_s (i_{\alpha s} - j i_{\beta s}) + p (i_{\alpha s} - j i_{\beta s}) + \omega_e i_{\alpha s} + j \omega_e i_{\beta s}) e^{j 90}$$

$\bar{v}_{qs-j\omega ds}$

$$\Rightarrow R_s (i_{\alpha s} - j i_{\beta s}) (\cos 90 + j \sin 90) + p (i_{\alpha s} - j i_{\beta s}) (\cos 90 + j \sin 90) + (\omega_e i_{\alpha s} + j \omega_e i_{\beta s}) (\cos 90 + j \sin 90)$$

$$F_{\alpha\beta} = R_s (j i_{\alpha s} + i_{\beta s}) + p (j i_{\alpha s} + i_{\beta s}) + \omega_e (i_{\alpha s} + j i_{\beta s})$$

$$F_{\alpha} = \text{Re} \left(\frac{j}{e^{j 90}} \right)$$

$$\frac{j}{e^{j 90}} = \frac{j}{j} = 1$$

Q4) (1) $P_{in} = \sqrt{3} \times U_{n1-1} \times I_n \times \cos \varphi = \sqrt{3} \cdot 380 \times 2.1 \times 0.6 \approx 873 \text{ W}$
 $P_{out} = 600 \text{ W}$
 $\eta = \% \frac{600}{873} = \% \frac{P_{out}}{P_{in}} = \% 68.7$

(2) $\frac{V_{n, rated}}{P_{rated}} = \frac{400/\sqrt{3}}{60} = 3.83$

(3) $|U_s| = R_s I_s + j \omega_s L_s I_s$

$|U_s| = I_s \omega_s \hat{n}_s$

$U_s = \omega_s \hat{n}_s \Rightarrow 230 = 2\pi 60 \cdot \hat{n}_s \Rightarrow \hat{n}_s = 0.61$

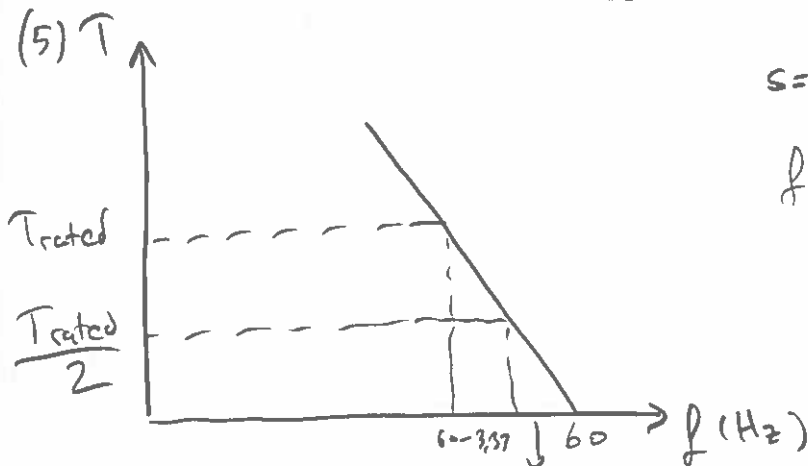
(4) Lecture 11 p.12 Muñoz-García

$U_s = r_s (I_s \cos \phi) + \sqrt{U_{s0}^2 - (r_s I_s)^2 + r_s^2 (I_s \cos \phi)^2}$

Magnitude of $U_s \Rightarrow \sqrt{r_s^2 I_s^2 \cos^2 \phi + U_{s0}^2 - r_s I_s^2 + r_s^2 I_s^2 \cos^2 \phi}$

$|U_s| = \sqrt{12^2 \cdot 0.5^2 \cdot 0.866^2 + 0.41^2 - 12 \cdot 0.5^2 + 12^2 \cdot 0.5^2 \cdot 0.866^2} = 6.57 \text{ V}$

$U_{s0} = f_{s0} \cdot \frac{U_{s, rated}}{f_{s, rated}} = 0.25 \frac{400/\sqrt{3}}{60} = 0.96 \text{ V}$



$s = \frac{n_s - n_m}{n_s} = \frac{900 - 850}{900} = 0.055$

$f_{slip} = f_s \cdot s = 3.33 \text{ Hz}$

$\frac{3.33}{2} = 1.66 \text{ Hz}$ need to be added stator frequency
 $f_{new} = f_s + f_{slip, comp} = 60 + 1.66 = 61.66 \text{ Hz}$

