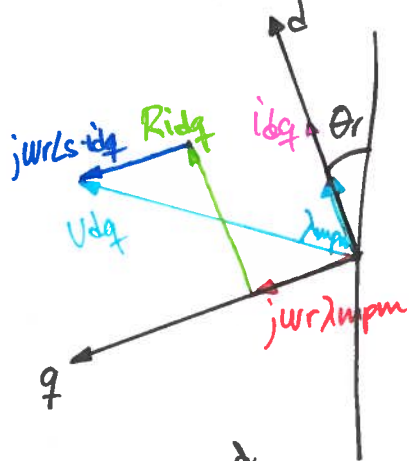


Scalar Control. PM workshop

Simulink finished → models ACABATS

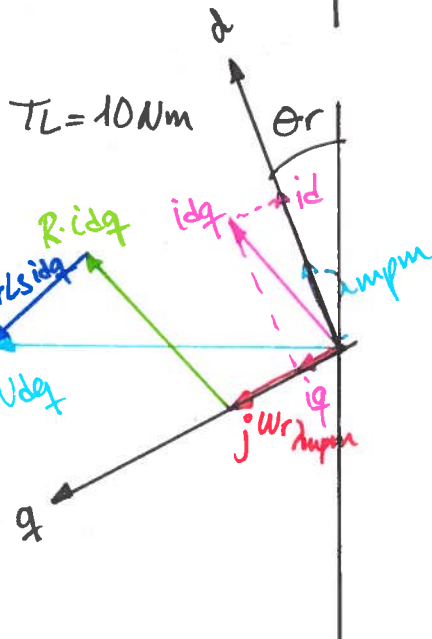
Task 2 → Draw phasor diagram

Case 1. $T_L = 0 \text{ Nm}$



① λ_{mpm} — always

② i_{dq} → only d component



$$U_{dq} = \underbrace{R i_{dq}}_{(2)} + \underbrace{j \omega_r L_s i_{dq}}_{(3)} + \underbrace{j \omega_r \lambda_{mpm}}_{(1)}$$

(4)

$\lambda_{mpm} \rightarrow \text{Real} \rightarrow d$

$i_d \& i_q \rightarrow \text{In the simulink} \rightarrow i_{dq}$

$i_{dq} \cdot R$

$\omega_r \cdot \lambda_{mpm} \cdot (j) \rightarrow 90^\circ$

$j \omega_r L_s \cdot i_{dq} \rightarrow 90^\circ \text{ respect } i_{dq}$

$U_{dq} \rightarrow \text{sum } 1, 2 \& 3$