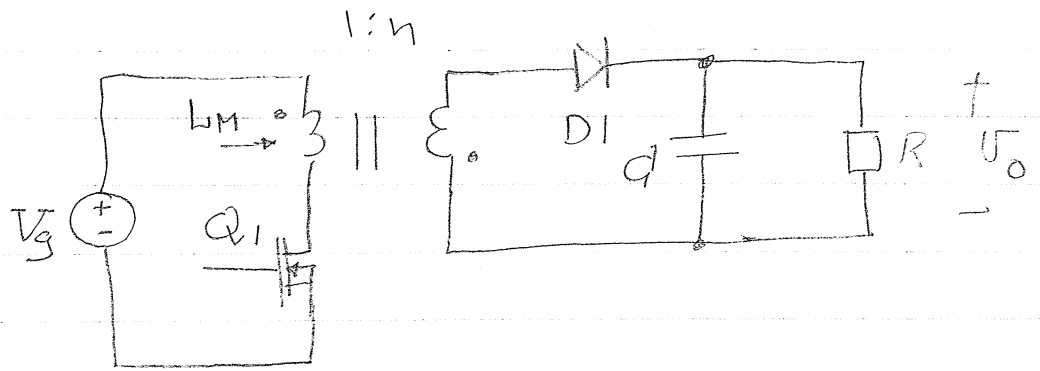
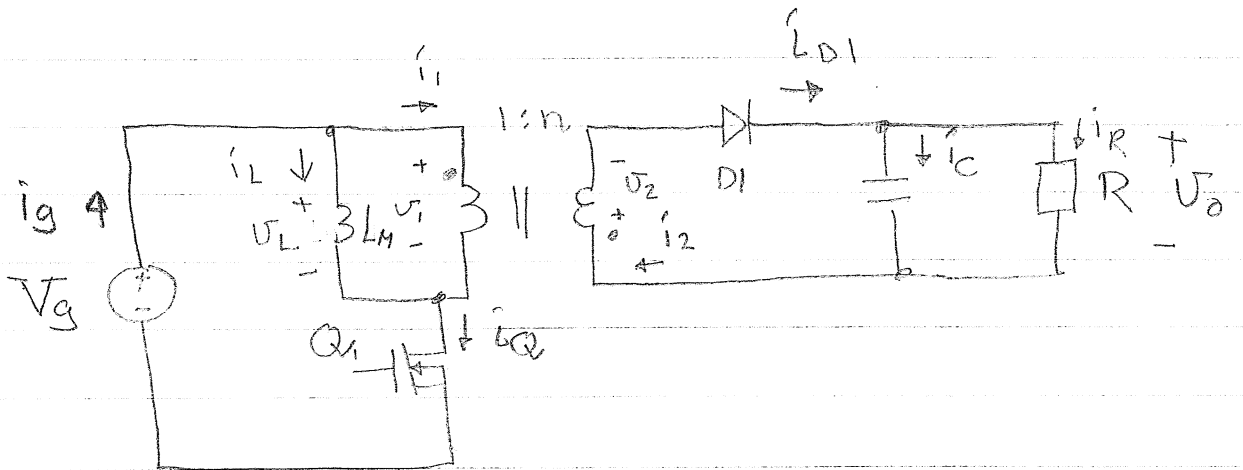


Problem 6.2 (b) + (a)

Fig 6.30 (d)

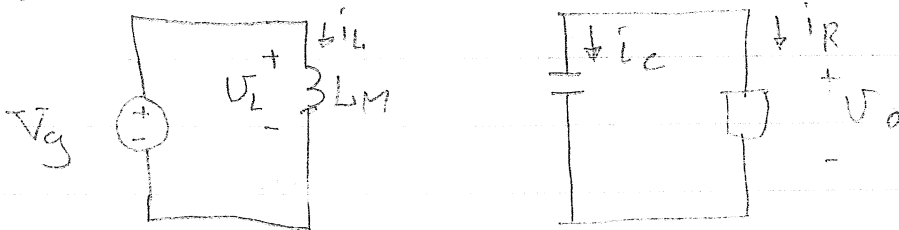


(a)

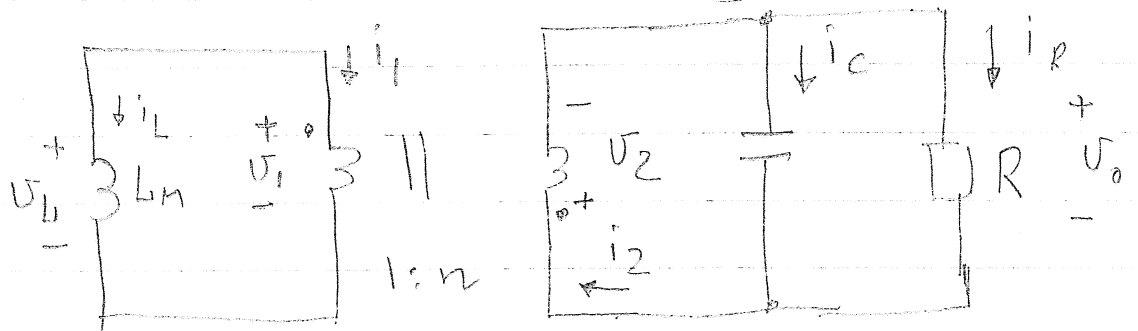


subintervals (show elements conducting current)

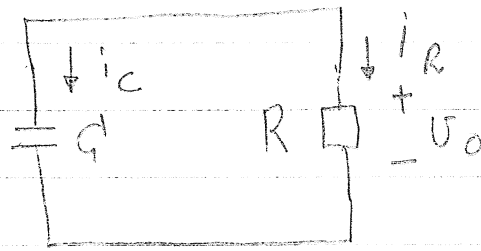
1) $Q_1 = \text{ON} - \text{conducting}$



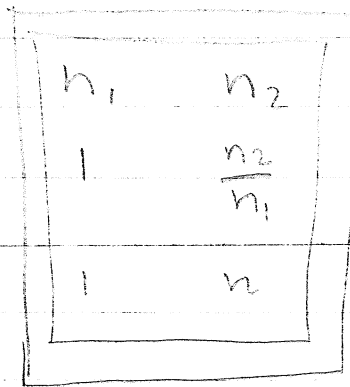
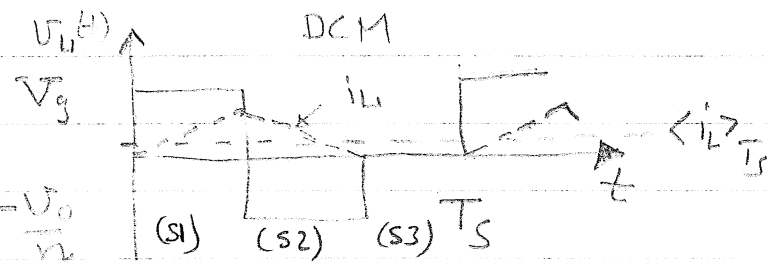
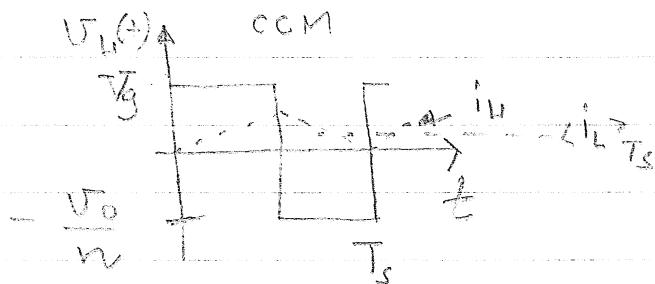
2) $Q_1 = \text{OFF}$ $D_1 = \text{ON} - \text{conducting}$



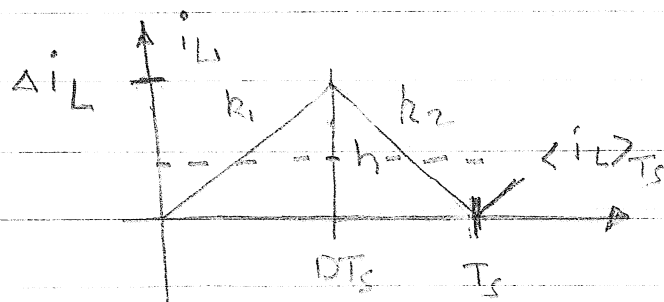
3) $Q_1 = \text{OFF}$ $D1 = \text{OFF}$



(b) CONDITION FOR DCM



$$\Rightarrow n = \frac{n_2}{n_1}$$



AT LIMIT OF DCM and CCM
is $\langle i_L \rangle_{T_s} = \frac{1}{2} \Delta i_L$

$$\Delta i = \frac{V_g}{L_M} D T_s$$

$$\Delta i = k_2 (1-D) T_s$$

$$\text{IN DCM } \left[\langle i_L \rangle_{T_s} < \frac{1}{2} \Delta i_L \right]$$

i_L and i_R are connected

$$i_1 = -i_2 n$$

$$\langle i_R \rangle_{T_s} = \frac{\langle V_o \rangle_{T_s}}{R}$$

$$\langle i_1 \rangle_{T_s} = -\langle i_2 \rangle_{T_s} n$$

$$\langle i_2 \rangle_{T_s} = \frac{\langle V_o \rangle_{T_s}}{R} + C \frac{d\langle V_o \rangle_{T_s}}{dt}$$

P6.2 (b)

$$\langle i_1 \rangle_{T_s} = -n \frac{\langle v_o \rangle_{T_s}}{R} - nG \frac{d\langle v_o \rangle_{T_s}}{dt}$$

IDEAL TRANSFORMER

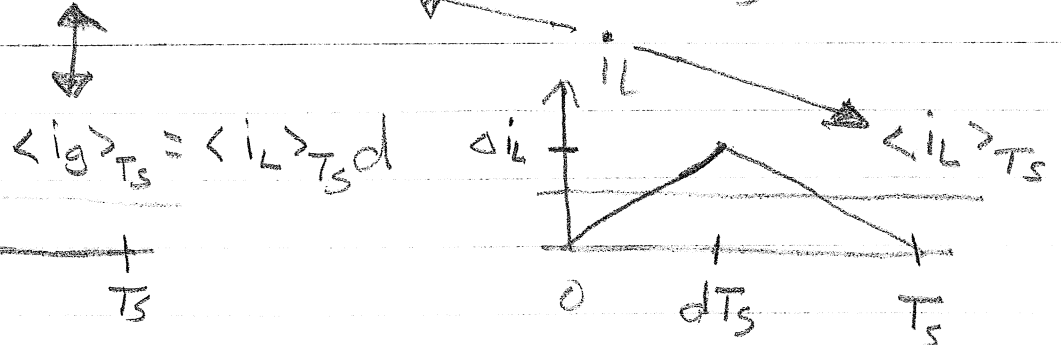
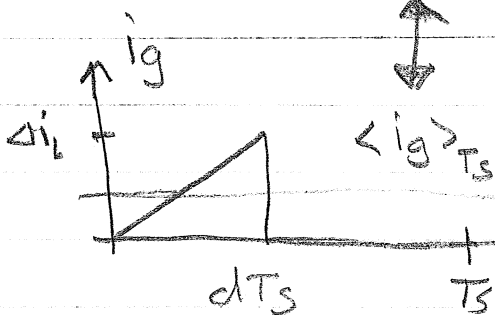
$$i_1 n_1 + i_2 n_2 = 0$$

$$i_1 = -i_2 n$$

$$\langle i_1 \rangle_{T_s} = -\langle i_2 \rangle_{T_s} n$$

From input side:

$$\langle i_g \rangle_{T_s} - \langle i_L \rangle_{T_s} - \langle i_1 \rangle_{T_s} = 0$$

COLLECT

$$0 = \langle i_L \rangle_{T_s} d - \langle i_L \rangle_{T_s} + n \frac{\langle v_o \rangle_{T_s}}{R} + nG \frac{d\langle v_o \rangle_{T_s}}{dt}$$

$$\langle i_L \rangle_{T_s} = \frac{n \frac{\langle v_o \rangle_{T_s}}{R} + nG \frac{d\langle v_o \rangle_{T_s}}{dt}}{(1-d)} \quad \left. \vphantom{\frac{n \frac{\langle v_o \rangle_{T_s}}{R} + nG \frac{d\langle v_o \rangle_{T_s}}{dt}}{(1-d)}}} \right\} \langle i_L \rangle_{T_s} < \frac{1}{2} \Delta i_L$$

And

$$\Delta i_L = \frac{V_s}{L} d T_s$$

P6.2 (b)
SO - FOR DCM

$$\frac{n \frac{\langle V_o \rangle_{T_s}}{R} + n C \frac{d\langle V_o \rangle_{T_s}}{dt}}{1-d} < \frac{1}{2} \frac{V_d}{L} dT_s$$

$$\langle V_o \rangle_{T_s} < \frac{V_d R (1-d) dT_s}{2 L n} - R C \frac{d\langle V_o \rangle_{T_s}}{dt}$$

OR

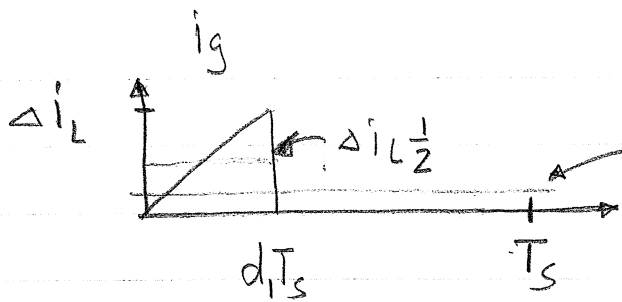
$$\langle i_o \rangle_{T_s} < \frac{V_d (1-d) dT_s}{2 L n} - C \frac{d\langle V_o \rangle_{T_s}}{dt}$$

In steady-state

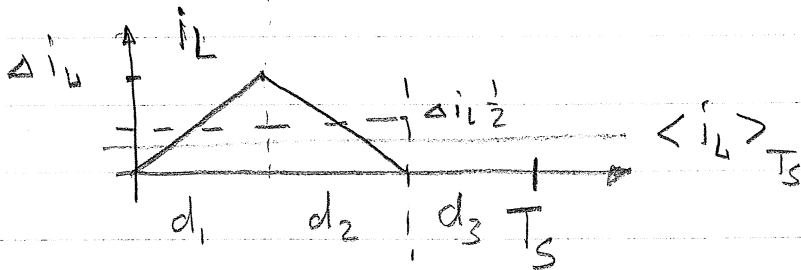
$$I_o < \frac{V_d (1-D) D T_s}{2 L n}$$

P. 6.2 (c)

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$$d_1 \frac{1}{2} \Delta i_L = \langle i_g \rangle_{T_s}$$



$$\langle i_L \rangle_{T_s} = (d_1 + d_2) \frac{1}{2} \Delta i_L \quad d_1 + d_2 + d_3 = 1$$

$$- \langle i_L \rangle_{T_s} - \langle i_1 \rangle_{T_s} + \langle i_g \rangle_{T_s} = 0 \quad \text{Front side}$$

$$\langle i_1 \rangle_{T_s} = d_1 \frac{1}{2} \Delta i_L - (d_1 + d_2) \frac{1}{2} \Delta i_L$$

$$\langle i_1 \rangle_{T_s} = -d_2 \frac{1}{2} \Delta i_L \quad \leftarrow \text{YES :-)}$$

$$\langle i_2 \rangle_{T_s} = - \langle i_1 \rangle_{T_s} / n$$

$$\langle i_2 \rangle_{T_s} = \frac{1}{n} d_2 \frac{1}{2} \Delta i_L$$

P.6.2 (c)


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IN STEADY STATE $V_o = \text{CONSTANT}$

SO $I_c = 0$

THUS

$$I_2 = \frac{1}{n} D_2 \frac{1}{2} \Delta i_L$$


$$V_o = I_2 R$$

$$V_o = \frac{1}{n} R D_2 \frac{1}{2} \Delta i_L$$

$$V_o = \frac{1}{n} R D_2 \frac{V_g}{2L} D_1 T_s$$

$$D_2 = \frac{V_o 2L n}{R V_g D_1 T_s}$$

ABOVE IS V_o UNKNOWN

SO WE ARE NOT ABLE

TO CALCULATE D_2

NEED ANOTHER EQUATION:

P. 6.2 (c)

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IN SS, IS AVERAGE VOLTAGE OF LM = 0,

INTEGRATING

$$0 = V_g D_1 - \frac{V_o}{n} D_2$$

VOLTAGE OF V_{LM}

AND MULTIPLY

WITH $\frac{1}{T_s} = \text{AVERAGE VOLTAGE}$

$$0 = V_g D_1 - \frac{V_o}{\cancel{n}} \frac{V_o \cancel{n} 2L}{R V_g D_1 T_s}$$

$$0 = V_g D_1 - \frac{V_o^2 2L}{R V_g D_1 T_s}$$

$$0 = V_g^2 D_1 - \frac{V_o^2 2L}{R D_1 T_s}$$

$$V_g^2 D_1^2 = \frac{V_o^2 2L}{R T_s}$$

$$\left(\frac{V_o}{V_g}\right)^2 = D_1^2 \frac{R T_s}{2L}$$

$$\frac{V_o}{V_g} = D_1 \sqrt{\frac{R T_s}{2L}}$$

STEADY STATE

P6.2(c)

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WE KNOW FROM PAGE 6

$$D_2 = \frac{V_0 2 L n}{R V_g D_1 T_s} \text{ and } V_0 = V_g D_1 \sqrt{\frac{RT_s}{2L}}$$

SO

$$D_2 = \frac{\cancel{V_g D_1} \sqrt{\frac{RT_s}{2L}}}{R \cancel{V_g D_1} T_s}$$

$$D_2 = \frac{1}{RT_s} \sqrt{\frac{RT_s}{2L}}$$

$$D_2 = \sqrt{\frac{RT_s}{2L} \frac{1}{R^2 T_s^2}}$$

$$\underline{\underline{D_2 = \sqrt{\frac{1}{2L R T_s}}}}$$