MEASUREMENTS AND SIGNAL CONDITIONING FOR POWER CONVERTERS

DESIGN OF SWITCH MODE CONVERTERS

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AALBORG UNIVERSITY

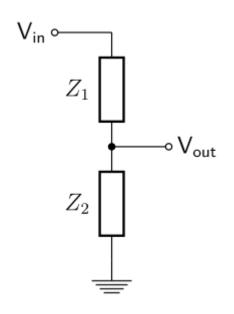
OUTLINE

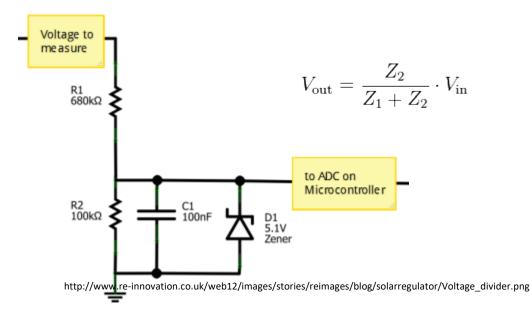
- VOLTAGE MEASUREMENT METHODS
- ☐ CURRENT MEASUREMENT METHODS
- ☐ GALVANIC ISOLATION
- PROTECTION
- ☐ ANALOGUE-TO-DIGITAL CONVERSION
- ☐ FILTERING (DIGITAL AND/OR ANALOGUE)



RESISTIVE VOLTAGE DIVIDER

- □ VOLTAGE IS A POTENTIAL <u>DIFFERENCE</u> BETWEEN TWO POINTS
- VOLTAGE DIVIDER:





☐ ADVANTAGES:

Simple
Cheap
Both DC and AC

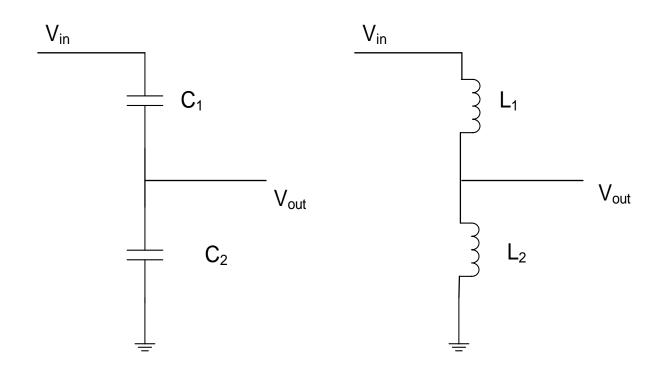
☐ DISADVANTAGES:

NO GALVANIC ISOLATION
RESISTOR VALUES CAN
CHANGE WITH TEMPERATURE



CAPACITIVE AND INDUCTIVE VOLTAGE DIVIDER

☐ FOR AC ONLY



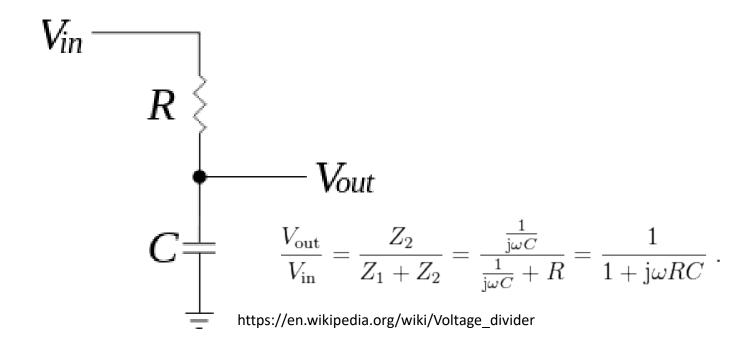
$$\Box V_{out} = V_{in} \cdot \frac{c_1}{c_1 + c_2}$$

$$V_{out} = V_{in} \cdot \frac{L_2}{L_1 + L_2}$$



VOLTAGE DIVIDER - RC

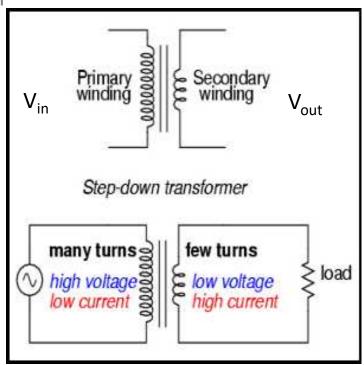
□ LOW-PASS RC FILTER





TRANSFORMER

☐ FOR AC ONLY



$$V_{out} = V_{in} \cdot \frac{N_2}{N_1}$$

■ ADVANTAGES:

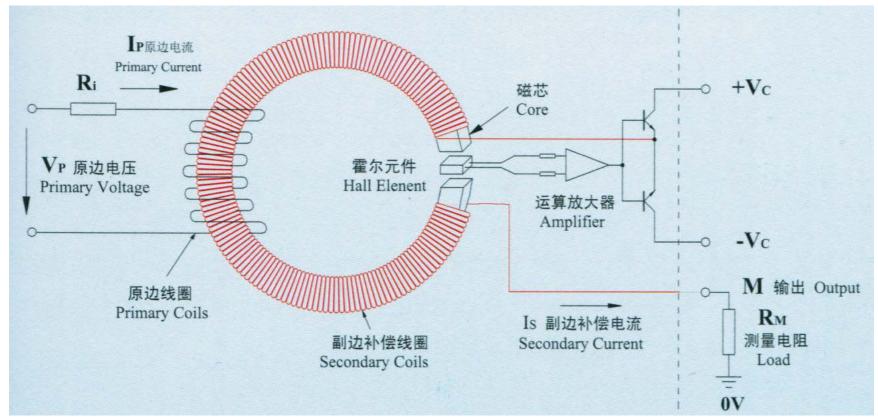
- SIMPLE
- GALVANIC ISOLATION

☐ DISADVANTAGES:

- TRANSFORMER NON-LINEARITIES
- LEAKAGE LOSSES
- MORE EXPENSIVE



HALL SENSOR



- ☐ SMALL CURRENT THROUGH PRIMARY BY MEASURED VOLTAGE
- BALANCING FLUX FROM SUPPLY CIRCUIT IN SECONDARY
- HALL DEVICE USED TO MEASURE FLUX COMPENSATE



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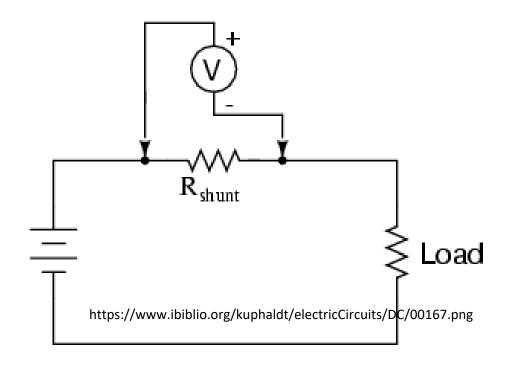


MAIN TYPES

- TWO MAIN TYPES: DIRECT AND INDIRECT SENSING
- □ DIRECT SENSING IS BASED ON OHM'S LAW SHUNT RESISTOR Low R shunt → voltage drop is normally measured by differential amplifiers Invasive - the sensing circuit is part of the power circuit No galvanic isolation Usually for lower currents (<100A) Cost effective
- Non-invasive measures the field created by electric current
 Galvanic isolated
 Typically higher currents
 Typically more expensive sensors



SHUNT RESISTOR



☐ ADVANTAGES:

Simple Linear – Vout=I*R Low-cost

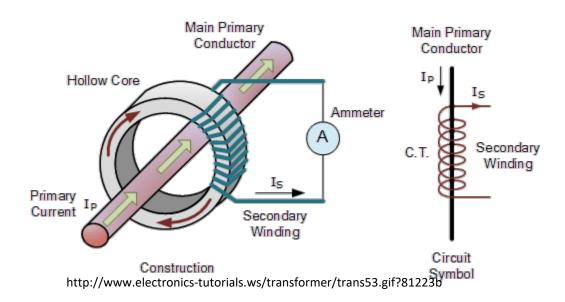
☐ DISADVANTAGES:

NO GALVANIC ISOLATION LOSSES ON R



CURRENT TRANSFORMER

☐ AC ONLY



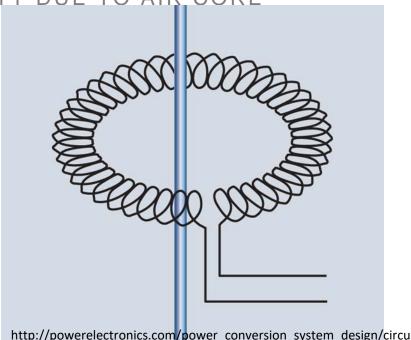
- ☐ CAN MEASURE VERY HIGH CURRENTS
- ☐ GALVANIC ISOLATION
- SECONDARY SIDE CURRENT CAN BE TRANSFORMED TO V BY E.G. SHUNT



CURRENT TRANSFORMER - ROGOWSKI COIL

□ SPECIAL DESIGNED WITH AIR CORE - LOWER INDUCTANCE AND FASTER RESPONSE

□ VERY GOOD LINEARITY DUE TO AIR CORE

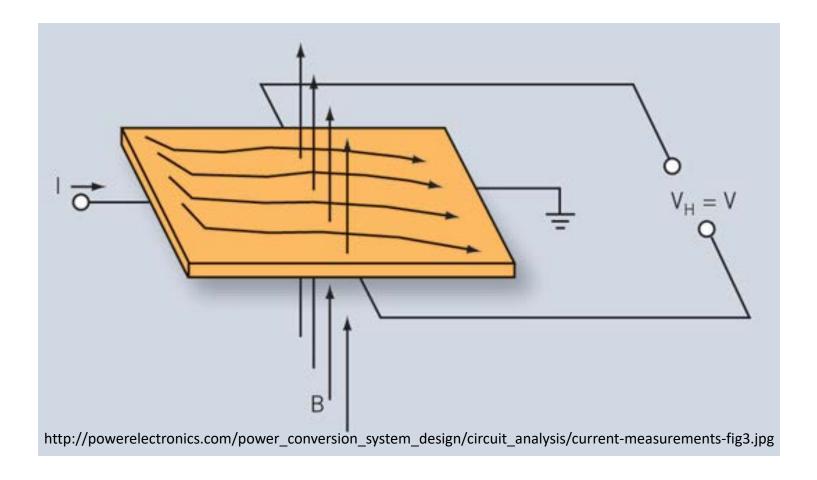


http://powerelectronics.com/power_conversion_system_design/circuit_analysis/current-measurements-fig2.ipg

TYPICALLY USED FOR MEASURING IN HIGH BANDWIDTH APPLICATIONS >1MHZ, OR FAST TRANSIENT CURRENTS

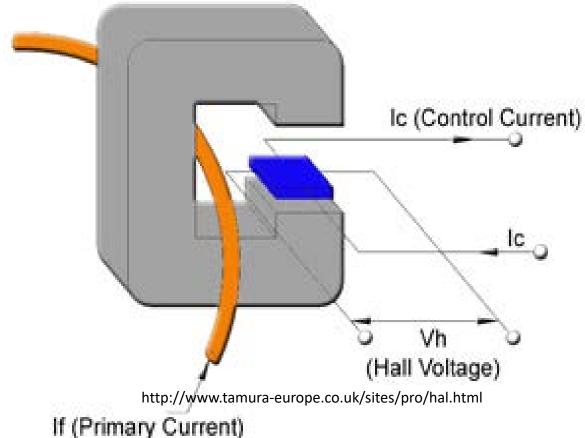


HALL-EFFECT SENSOR - PRINCIPLE





OPEN-LOOP HALL-EFFECT SENSOR

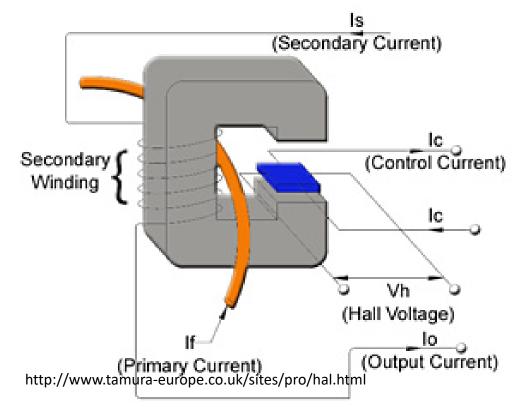


If (Primary Current)



CLOSED-LOOP HALL-EFFECT SENSOR

☐ ALSO CALLED COMPENSATED, OR ZERO-FLUX



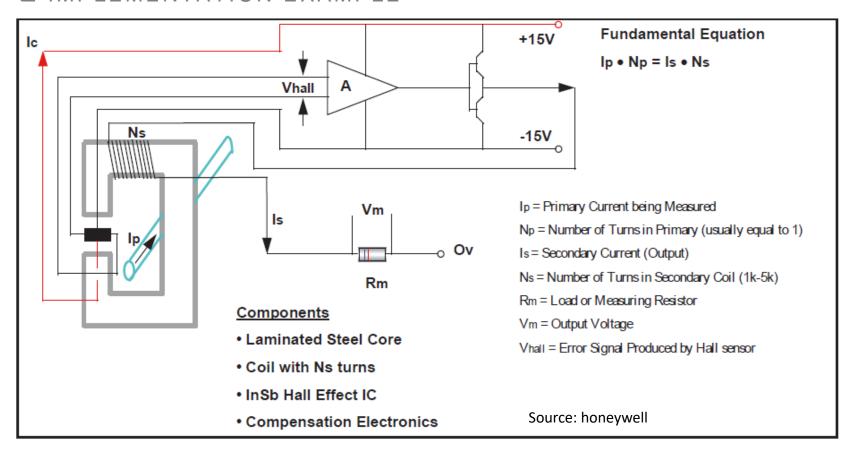
□ COMPARED TO OPEN-LOOP VERSION:

■ MORE EXPENSIVE

- Higher accuracy, no nonlinearity of Hall sensor
- Higher noise immunity
- No saturation, No temperature drift

CLOSED-LOOP HALL-EFFECT SENSOR

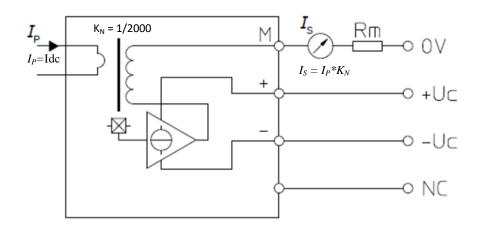
☐ IMPLEMENTATION EXAMPLE





CLOSED-LOOP HALL-EFFECT SENSOR

☐ CURRENT MEASUREMENT



Source: LEM



K_N = 2500/1000

(to ADC)

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BLOCKS DC CURRENT FLOW BETWEEN THE ISOLATED CIRCUITS

□ PURPOSE:

To be able to pass signals between circuits with different ground potentials Safety - close ground loop through a person

■ MAIN METHODS/PRINCIPLES:

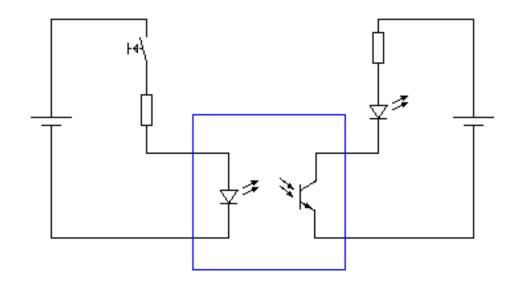
Transformer
Opto-isolator
Capacitor
Hall effect

Isolation impedance / leakage
Blocking/isolation voltage
Bandwidth



OPTICAL ISOLATION - OPTO-COUPLER

☐ PRINCIPLE



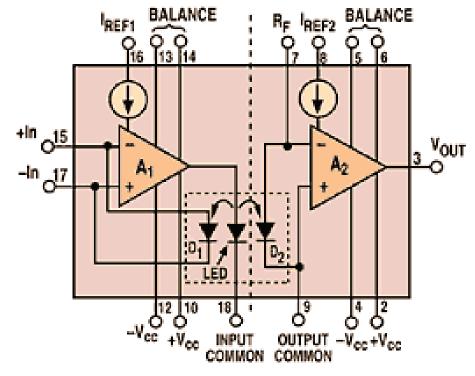
"Optokoppler" by Quark48 at the German language Wikipedia. Licensed under CC BY-SA 3.0 via Commons - https://commons.wikimedia.org/wiki/File:Optokoppler.gif#/media/File:Optokoppler.gif

- □ LED IS NON-LINEAR LIGHT SOURCE
- ☐ IN BASIC FORM IS ON/OFF (DIGITAL)
- □ OPTO-COUPLERS HAVE GENERALLY GOOD NOISE IMMUNITY



OPTICAL ISOLATION

■ IMPLEMENTATIONS - SIGNAL PASSED IN ANALOGUE FORM



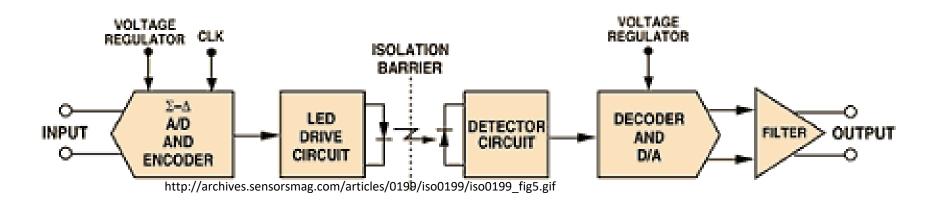
http://archives.sensorsmag.com/articles/0199/iso0199_fig4.gif

■ MATCHED PHOTODIODES



OPTICAL ISOLATION

☐ IMPLEMENTATIONS - SIGNAL PASSED IN DIGITAL FORM



□ AVOIDS THE SECOND PHOTO-DIODE BUT ADDS TO THE COMPLEXITY



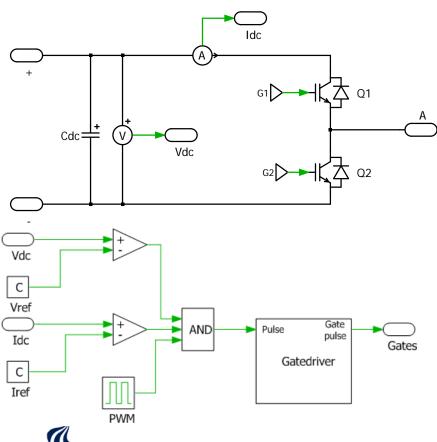
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PROTECTION

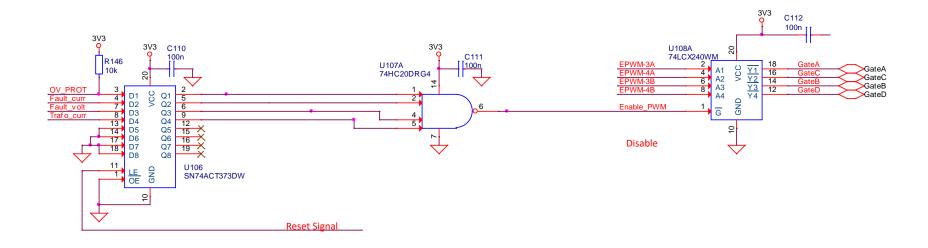
- Over voltage protection
- Over current protection



What if it happens only once?

What if it happens periodically?

LATCH AND BUFFER



- U106: Latch x fault event makes Qx=1
- U107: NAND gate output = 1 (default 0)
- U108: Buffer Disable = 1 -> gate pulses stopped
- Reset signal needed



OUTLINE

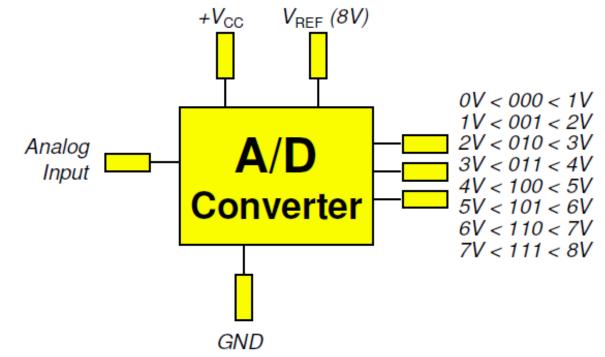
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WHAT IS AN ADC

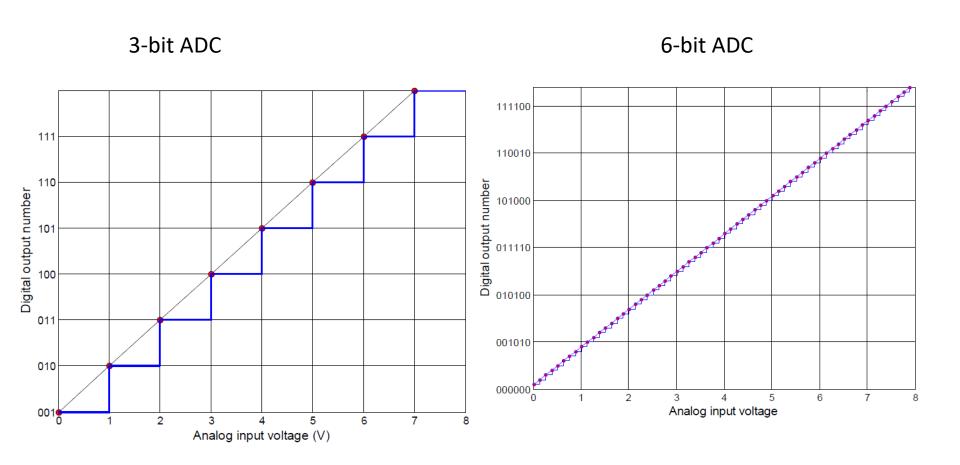
ANALOGUE-TO-DIGITAL CONVERTER

- ☐ CONVERTS AN ANALOGUE, CONTINUOUS SIGNAL AT ITS INPUT INTO A DIGITAL DISCRETE NUMBER AT ITS OUTPUT
- ☐ FOR A 3-BIT ADC, THERE ARE 8 POSSIBLE OUTPUT CODES.



□ IN THIS EXAMPLE, IF THE INPUT VOLTAGE IS 5.5V AND THE REFERENCE IS 8V, THEN THE OUTPUT WILL BE 101 (6V).

TRANSFER FUNCTION OF ADC AT DIFFERENT RESOLUTION



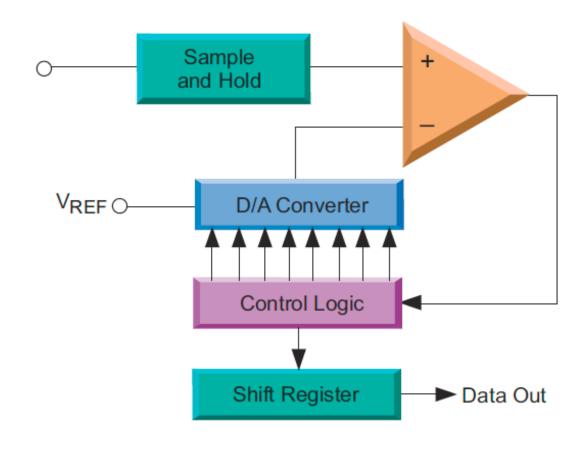


ADC RESOLUTION

- □ RESOLUTION: THE NUMBER OF DISCRETE VALUES IT CAN PRODUCE OVER THE RANGE OF ANALOGUE VALUES
- IT CAN BE GIVEN IN BITS: FOR EXAMPLE, A 12-BIT RESOLUTION ADC CAN PRODUCE 2¹²= 4096 DISCRETE DIGITAL VALUES OF ITS FULL-SCALE ANALOGUE INPUT VOLTAGE
- IT CAN BE GIVEN IN VOLTS: FOR EXAMPLE, WITH A FULL-SCALE INPUT OF 0-3V, WILL HAVE A RESOLUTION OF 3/4096 = 0.00073V



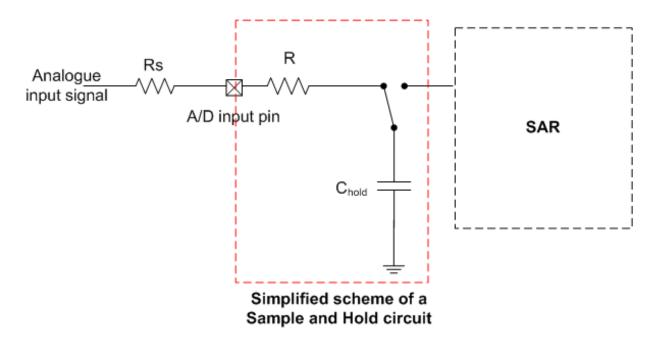
TYPICAL A/D CONVERSION SCHEME





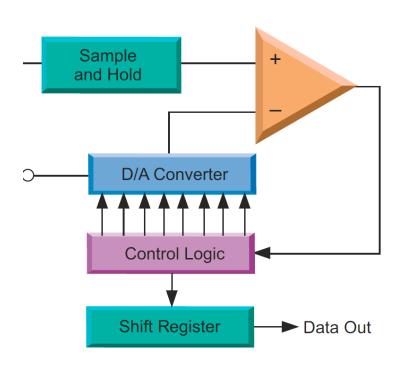
SAMPLE AND HOLD CIRCUIT

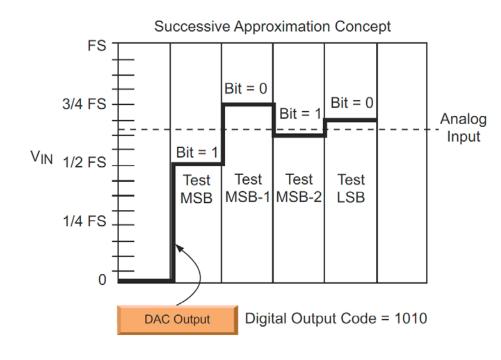
- □ THE PURPOSE THE S/H CIRCUIT IS TO KEEP THE VOLTAGE LEVEL CONSTANT DURING THE CONVERSION (MAINLY A CAPACITOR)
- ☐ THE SETTLING TIME (TIME NEEDED TO CHARGE UP THE S/H CAPACITOR) LIMITS THE MAXIMUM INPUT FREQUENCY





SUCCESSIVE APPROXIMATION



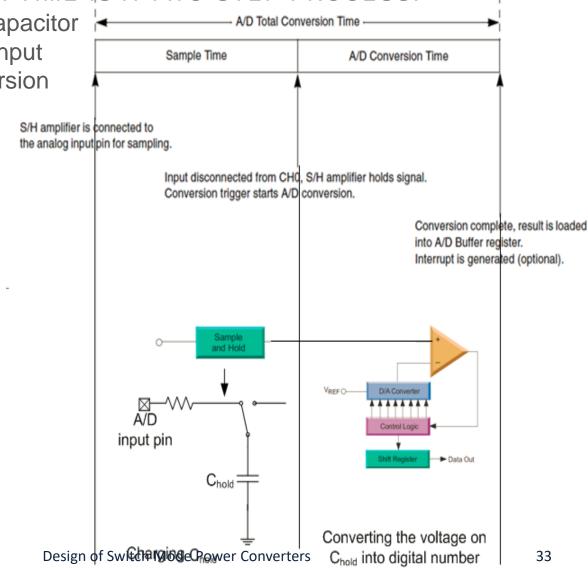


- 1 MSB of DAC input is set to '1' (half of DAC output range)
- 2 Test if DAC output is higher than analog input. If higher, MSB = 0, else MSB = 1
- 3 Repeat 1 and 2 with MSB-1

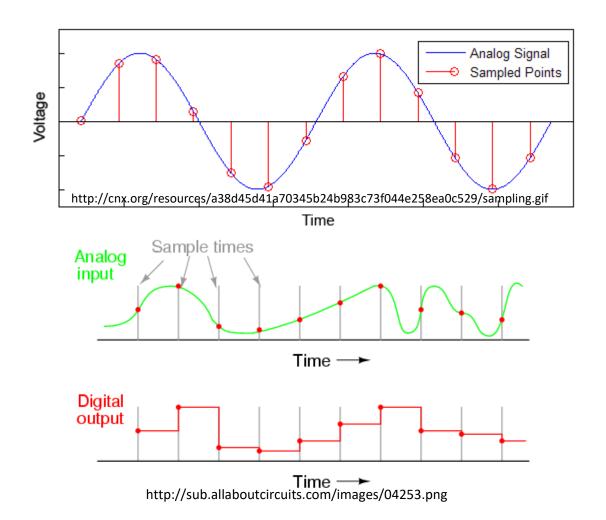


SUMMARY OF THE CHARACTERISTICS OF THE ADC

- ☐ THE FULL CONVERSION TIME IS A TWO STEP PROCESS:
 - 1. Charging the sampling capacitor
 - 2. Disconnect C hold from input pin and start the A/D conversion



PERIODIC SAMPLING





PERIODIC SAMPLING

NYQUIST'S RULE

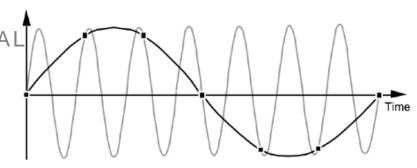
- ☐ SAMPLING OF CONTINUOUS SIGNAL WAVEFORM
- MEASURED SIGNALS WITH COMPLEX WAVEFORMS CAN BE REPRESENTED BY SUM OF SINUSOIDAL (FOURIER)

IN ORDER TO CORRECTLY REPRESENT
THE MEASURED SIGNAL:

0.866 Time

 $F_{sampling} \ge 2 * F_{max}$ F_{max} -THE HIGHEST FREQUENCY COMPONENT IN THE MEASURED SIGNAL

IF THERE ARE (UNDESIRABLE) (b) FREQUENCY COMPONENTS WITH $F > F_{sampling} \rightarrow \text{ANALOGUE FILTERING}$ PRIOR TO ADC



Understanding Digital Signal Processing, 2nd Edition, Richard G. Lyons Published Mar 15, 2004 by Prentice Hall.



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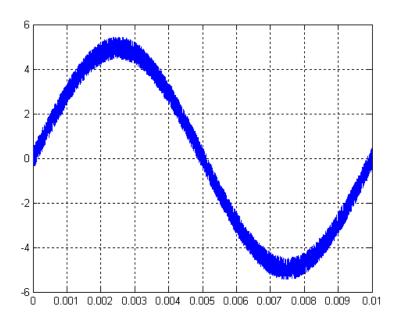


FILTERING

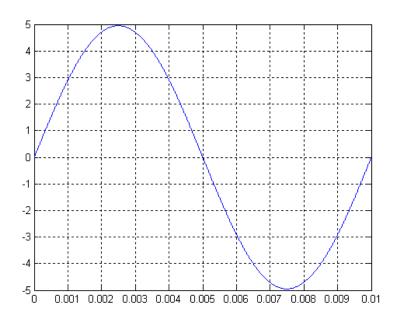
■ WHY DO WE USE FILTERING?

Reduce the amplitude of the unwanted frequency components (usually called noise) from the input (measured) signal spectrum

Unfiltered signal



Filtered signal





TYPE OF FILTERS

LOW PASS

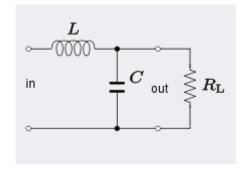
PASSES FREQUENCIES BELOW A CERTAIN FREQUENCY (CUT OFF FREQUENCY) AND REJECTS (ATTENUATES) FREQUENCY

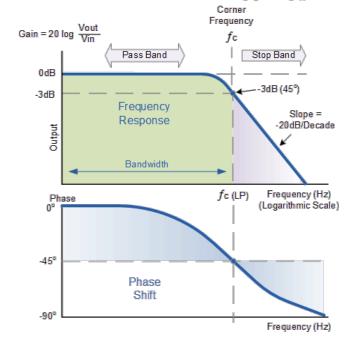
☐ EXAMPLES:

☐ FIRST ORDER

 $V_{\rm R}$ $V_{\rm in}$ $V_{\rm c}$

☐ SECOND ORDER





Pass

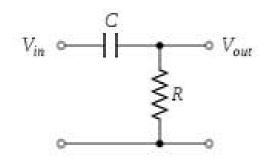
Stop

TYPE OF FILTERS - HIGH PASS

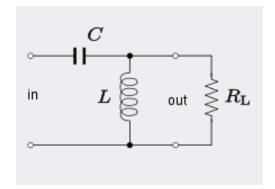
□ PASSES FREQUENCIES ABOVE A CERTAIN FREQUENCY (CUT OFF FREQUENCY) AND REJECTS (ATTENUATES) FREQUENCIES BELOW THE CUT OFF FREQUENCY

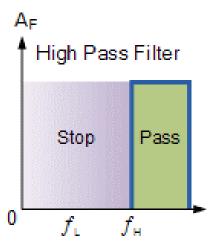


☐ FIRST ORDER









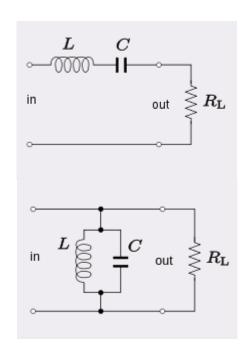


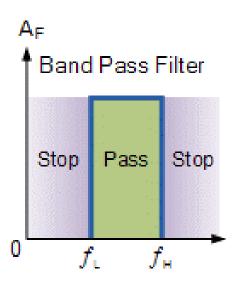
TYPE OF FILTERS - BAND PASS

□ PASSES FREQUENCIES WITHIN A CERTAIN RANGE AND REJECTS (ATTENUATES) FREQUENCIES OUTSIDE THAT RANGE

■ EXAMPLE:

☐ SECOND ORDER





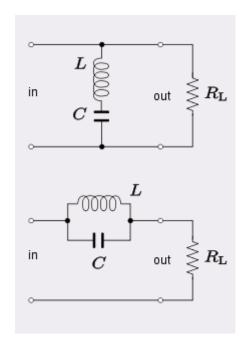


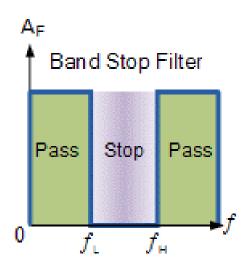
TYPE OF FILTERS - BAND STOP (NOTCH)

□ PASSES FREQUENCIES OUTSIDE A CERTAIN RANGE AND REJECTS (ATTENUATES) FREQUENCIES OUTSIDE THAT RANGE

☐ EXAMPLE:

☐ SECOND ORDER







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EXERCISE

☐ ON MOODLE

