

Ugly Notes of Power Electronics Converters

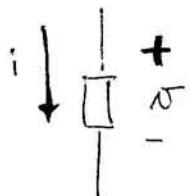
Benoît Bidoggia
bbi@et.aau.dk

Date: 7 September 2012

CAVEAT

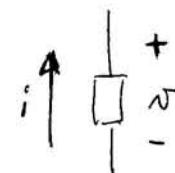
This is only to be intended as a collection of notes.
There might be (and there are!) mistakes, imprecisions and simplifications.
Some parts are also incomplete.
Please, send me an email when you find something wrong.

Turning the page and using these notes is at your own risk.
I decline all responsibilities for that :-)

"LOAD" convention

$$P = \bar{V} \cdot i$$

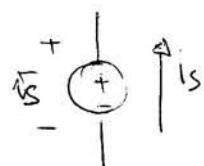
$P > 0 \Rightarrow$ consumed power
 $P < 0 \Rightarrow$ generated power

"SOURCE" convention

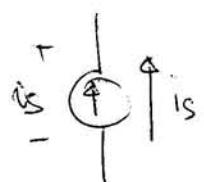
$$P = \bar{V} \cdot i$$

$P > 0 \Rightarrow$ generated power
 $P < 0 \Rightarrow$ consumed power

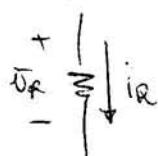
- Components "Source" convention



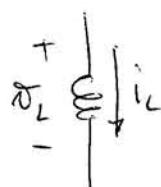
"Voltage source" $\bar{V}_S = V_S$ I_S



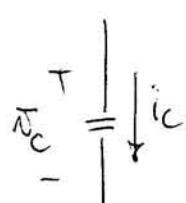
"Current source" $I_S = I_S$ \bar{V}_S

"LOAD" convention

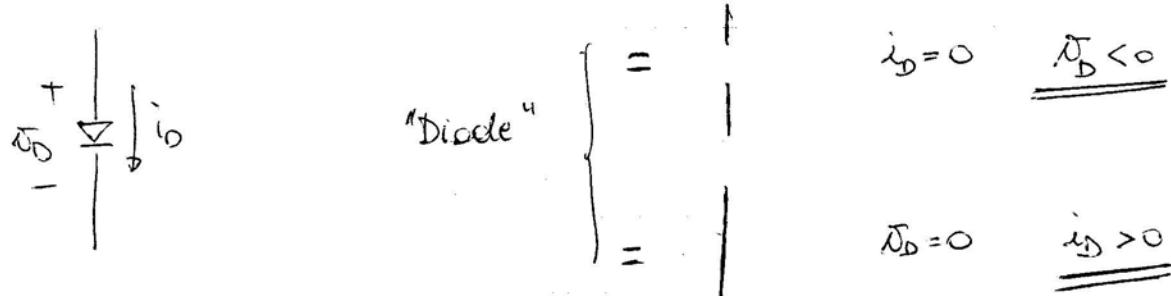
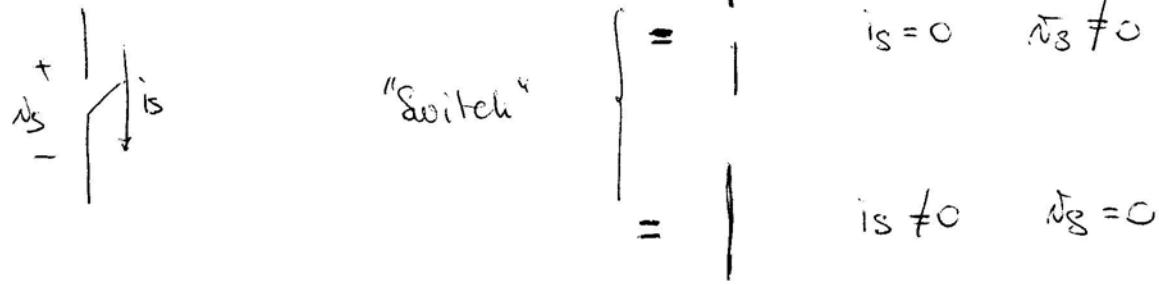
"Resistor" $\bar{V}_R = R \cdot I_R$



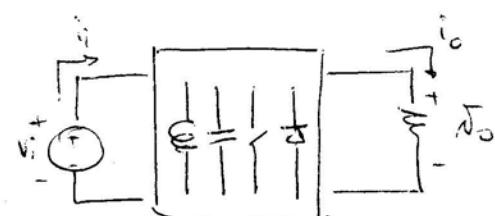
"Inductor" $\bar{V}_L = L \frac{di}{dt}$ $i_L = \frac{1}{L} \int \bar{V}_L dt + I_1$



"Capacitor" $i_C = C \frac{d\bar{V}_C}{dt}$ $\bar{V}_C = \frac{1}{C} \int i_C dt + V_1$



DC/DC CONVERTERS
THE SIMPLEST TOPOLOGIES



$$n_o \leq n_i$$

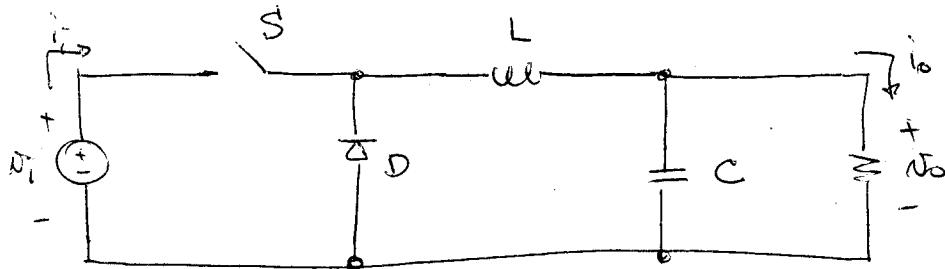
"BUCK"

$$n_o \geq n_i$$

"Boost"

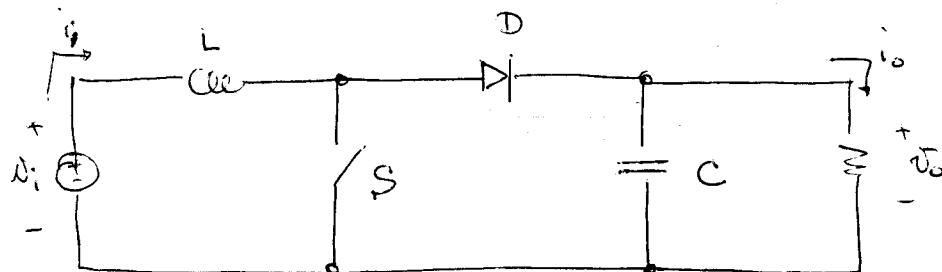
$$n_o \leq n_i$$

"BUCK-Boost"



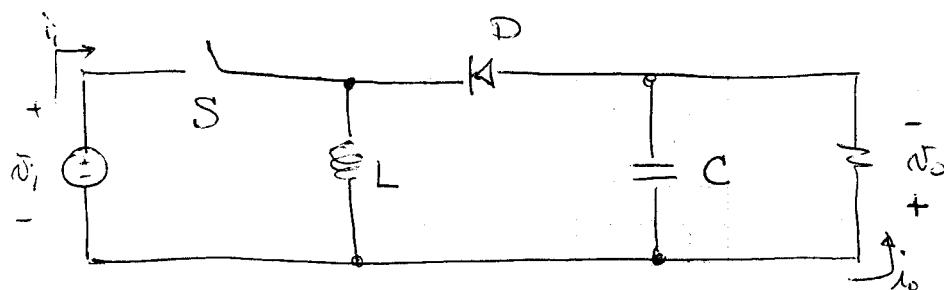
$$N_o \leq N_i$$

"BUCK"



$$N_o \geq N_i$$

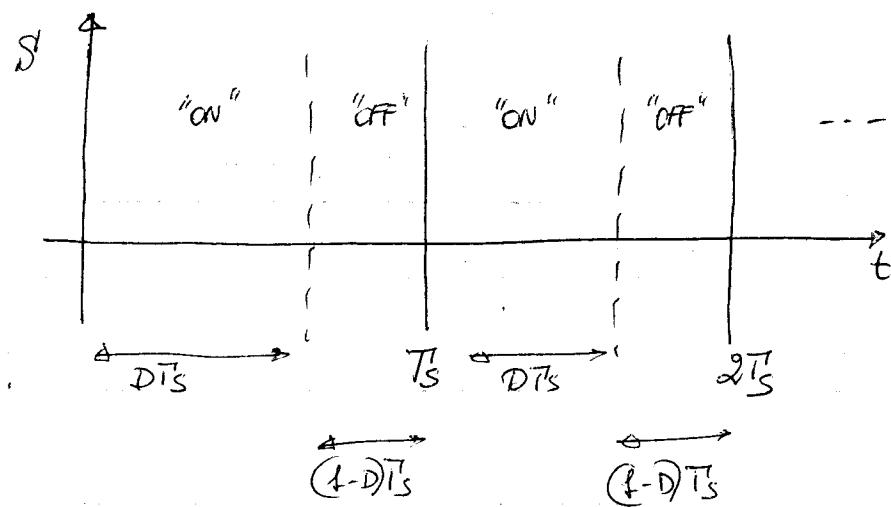
"BOOST"



$$N_o \leq N_i$$

"BUCK-BOOST"

In all of them \$S\$ is "on" and "off" regularly:



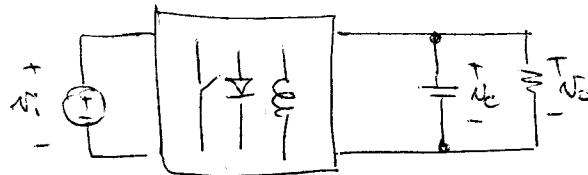
D. duty cycle $0 \leq D \leq 1$

\$T_S\$: switching period

$f_S = \frac{1}{T_S}$: switching frequency $[4\text{ kHz}; 1\text{ MHz}]$

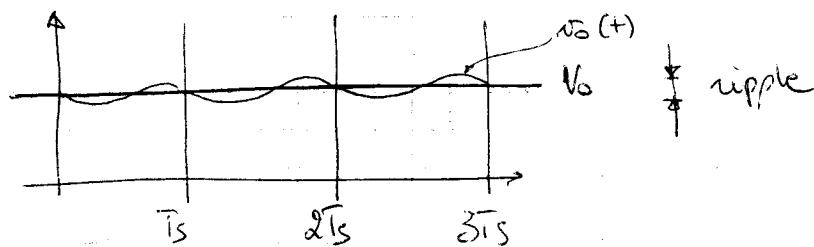
HOW TO SIMPLIFY THESE CIRCUITS

Fundamental hypotheses



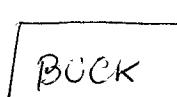
"C" is "big enough" to assume that $\bar{V}_C = \bar{V}_o \approx V_o$ (constant voltage).

Actually, $V_C = V_o = \bar{V}_o + \underbrace{\text{DC}}_{\text{constant}} + \underbrace{\text{AC}}_{\text{ripple}}$

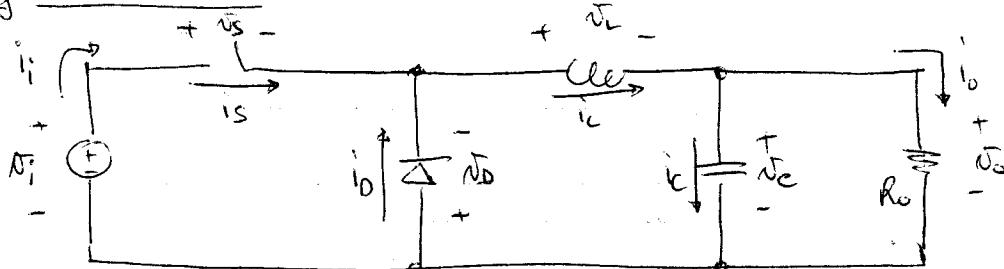


If ripple is small \rightarrow it can be neglected

"small ripple approximation" or "linear ripple approx."



D) General circuit

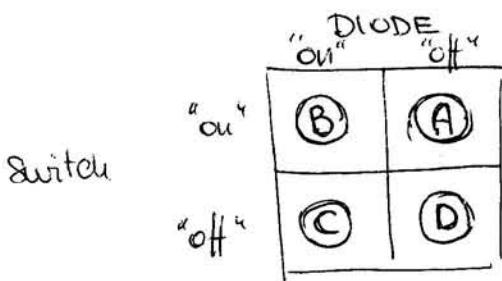


Non linear circuit because of S and D

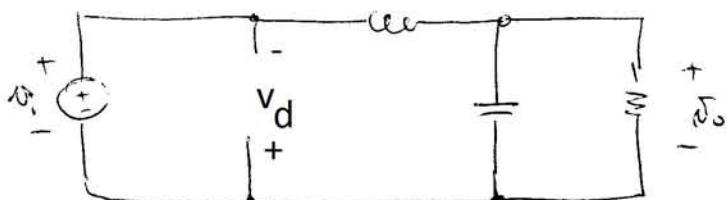
S can be		"ON" or		"OFF"
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D can be		"ON" or		"OFF"
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\Rightarrow We try all the possibilities, excluding the ones that cannot work.

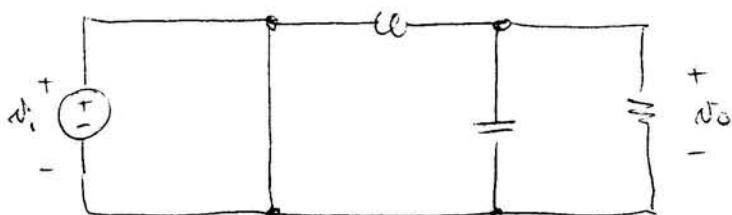


(A)



$$v_d < 0$$

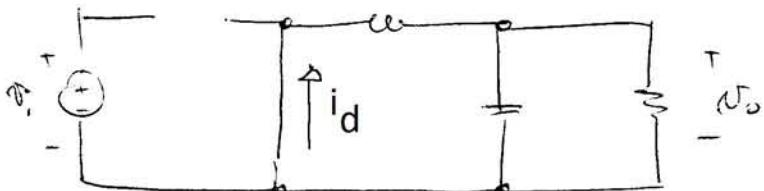
(B)



cannot work:

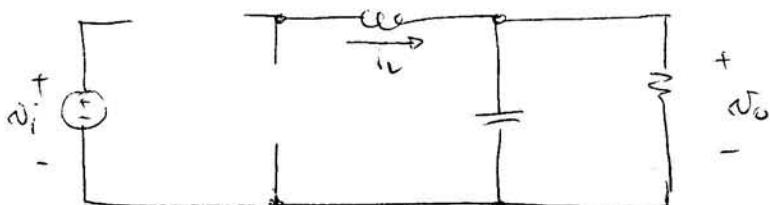
Vi is shortcircuited

(C)



$$i_d > 0$$

(D)

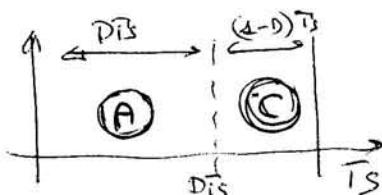


works only if $i = \infty$:
 special case we'll
 consider in the
 future

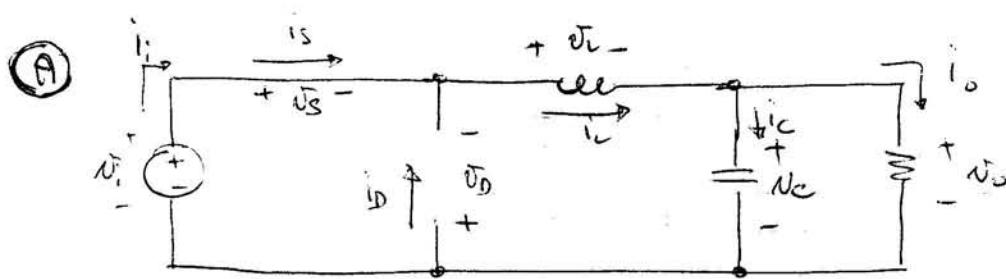
\Rightarrow Only (A) and (C) are possible:

(A) when the switch is "on" (between 0 and DiS)

(C) when the switch is "off" (between DiS and Ts)



(cont) Studying the two possible circuits.



Voltage $V_S = 0$ $N_D = -V_i$ $N_L = V_i$
(cfr v/i diaframus) $N_C = V_0 \approx V_o$

$$N_L = N_i - N_o = V_i - V_o$$

$$V_i > V_o \Rightarrow V_i - V_o > 0 \Rightarrow \boxed{N_L > 0}$$

Current

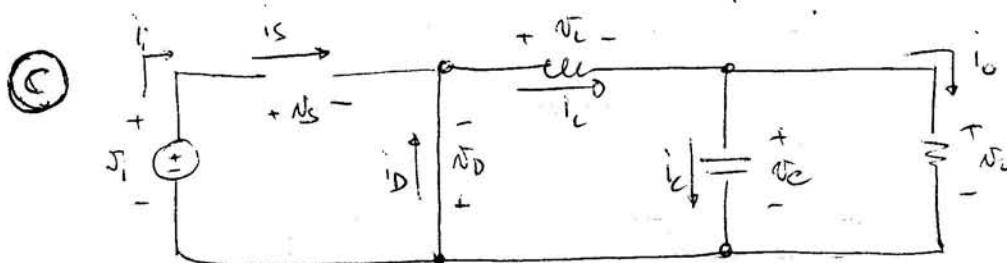
$$i_D = 0$$

$$i_i = i_s = i_L = \frac{1}{L} \int_0^t u(t) dt + I_s = \frac{1}{L} \int_0^t (V_i - V_o) dt + I_s$$

$$\underline{= \frac{V_i - V_o}{L} t + I_s}$$

$$i_o \approx \frac{V_o}{R} = I_o$$

$$i_C = i_L - i_o \approx i_L - I_o$$



Voltage $N_S = N_i = V_i$ $N_D = 0$
(cfr v/i diaframus) $N_C = N_o \approx V_o$

$$N_L = -N_o \approx -V_o$$

$$\boxed{N_L < 0}$$

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Current

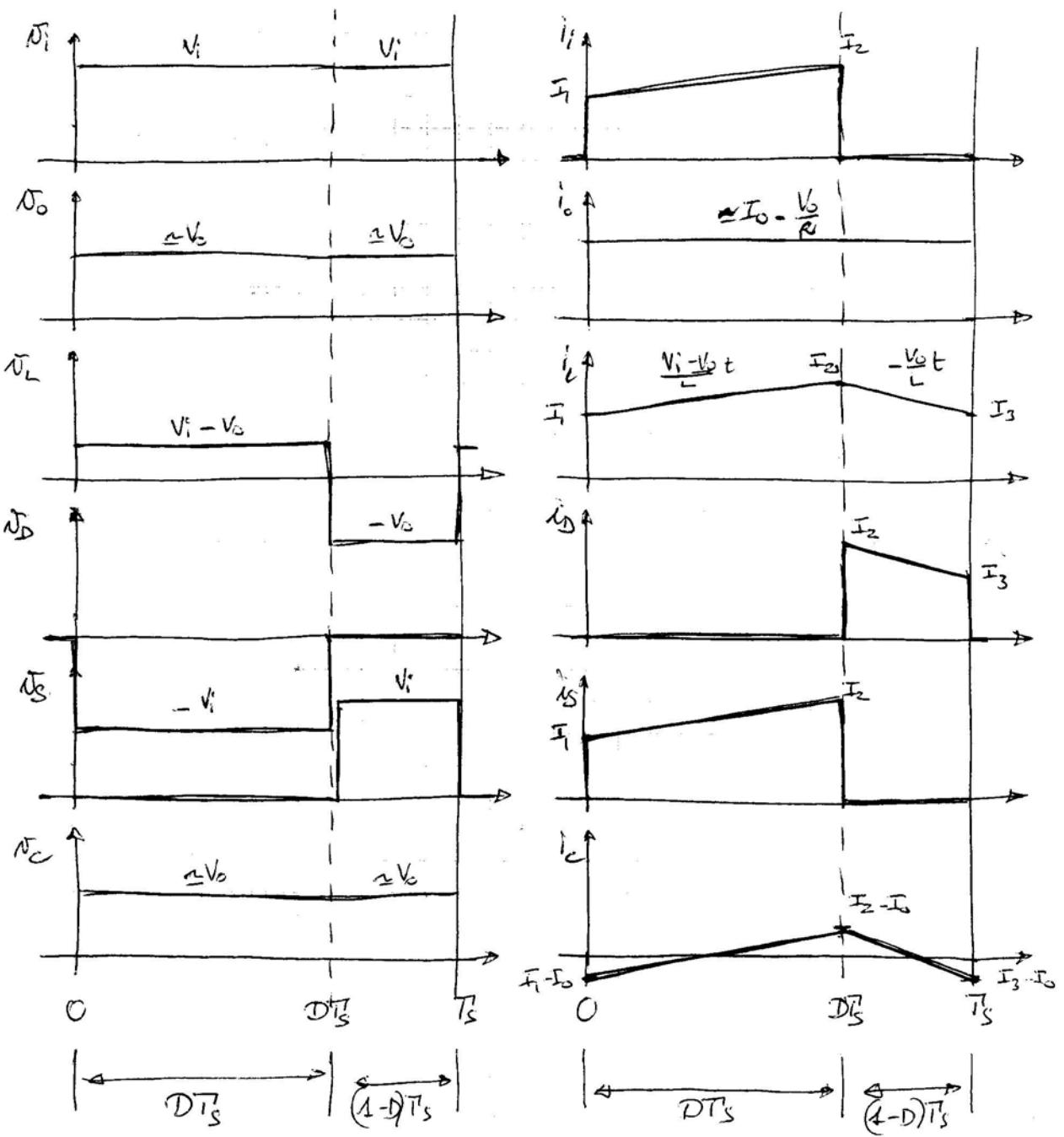
$$i_i = i_S = 0$$

$$i_D = i$$

$$i = \frac{1}{L} \int_0^t V_L dt + I_0 = \frac{1}{L} \int_0^t (-V_o) dt + I_0 = -\frac{V_o}{L} t + I_0$$

$$i_C = i_L - i_0 \approx i_L - I_0$$

— —

3) Voltage and current diagrams

4)

Steady-state conditions

11)

Inductor

$$\Delta L = L \frac{di_L}{dt}$$

$$i_L(t) = \frac{1}{L} \int_0^t \Delta L(t) dt + i_L(0)$$

$$i_L(T_S) = \frac{1}{L} \int_0^{T_S} \Delta L(t) dt + i_L(0)$$

Steady state condition: $i_L(T_S) = i_L(0)$

$$i_L(T_S) = \frac{1}{L} \int_0^{T_S} \Delta L(t) dt + i_L(0) \Rightarrow \frac{1}{L} \int_0^{T_S} \Delta L(t) dt = 0 \Rightarrow \boxed{\int_0^{T_S} \Delta L(t) dt = 0}$$

$$\int_0^{D\bar{T}_S} \Delta L(t) dt + \int_{D\bar{T}_S}^{T_S} \Delta L(t) dt = 0$$

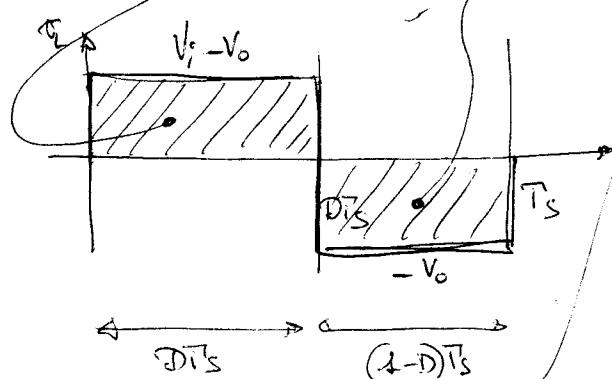
"Inductor volt-second balance"

$$\int_0^{D\bar{T}_S} \Delta L(t) dt = - \int_{D\bar{T}_S}^{T_S} \Delta L(t) dt$$

$$\int_0^{D\bar{T}_S} (V_i - V_o) dt = - \int_{D\bar{T}_S}^{T_S} (-V_o) dt$$

$$(V_i - V_o) D\bar{T}_S = (T_S - D\bar{T}_S) V_o$$

$$(V_i - V_o) D\bar{T}_S = V_o (1 - D) T_S$$



$$(V_i - V_o) D = V_o (1 - D)$$

$$V_o = D V_i$$

Multiplication:

$$\int_0^{T_S} \Delta L(t) dt = 0 \Rightarrow \langle \Delta L \rangle = \frac{1}{T_S} \int_0^{T_S} \Delta L(t) dt = 0 \quad \boxed{\langle \Delta L \rangle = 0}$$

Capacitor

8e

$$i_C = C \frac{dV_C}{dt}$$

$$\bar{V}_C(t) = \frac{1}{C} \int_0^t i_C(t) dt + \bar{V}_C(0)$$

$$\bar{V}_C(T_S) = \frac{1}{C} \int_0^{T_S} i_C(t) dt + \bar{V}_C(0)$$

Steady state condition: $\bar{V}_C(0) = \bar{V}_C(T_S)$

$$\bar{V}_C(T_S) = \frac{1}{C} \int_0^{T_S} i_C(t) dt + \bar{V}_C(0) \Rightarrow \frac{1}{C} \int_0^{T_S} i_C(t) dt = 0$$

$$\Rightarrow \boxed{\int_0^{T_S} i_C(t) dt = 0}$$

"Capacitor charge balance"

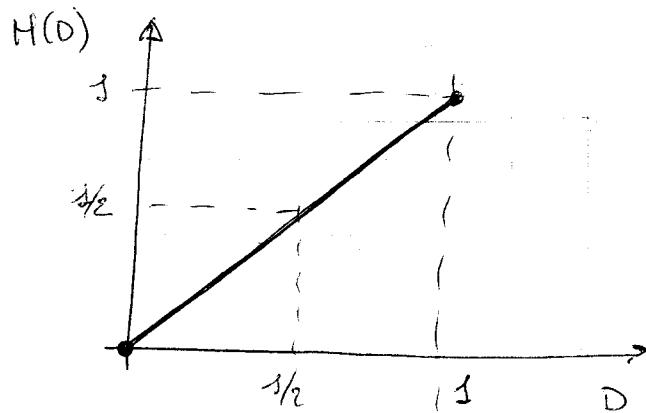
Implication:

$$\langle i_C \rangle = \frac{1}{T_S} \int_0^{T_S} i_C(t) dt = 0$$

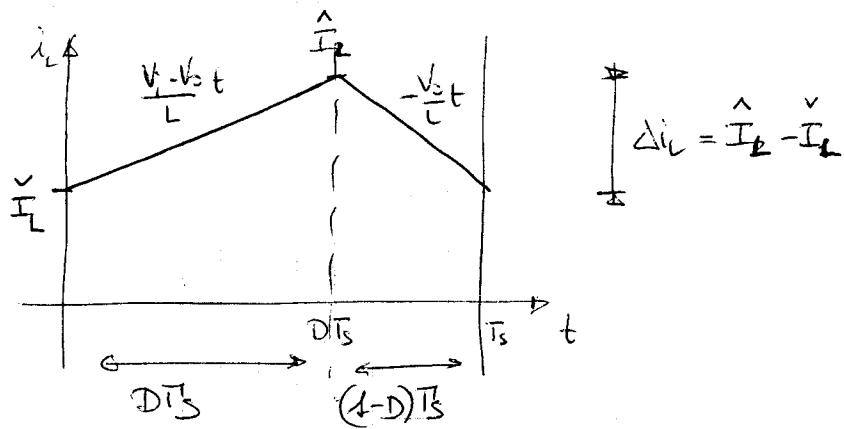
$$\boxed{\langle i_C \rangle = 0}$$

5) Conversion ratio

$$H(D) = \frac{V_o(D)}{V_i} = D$$

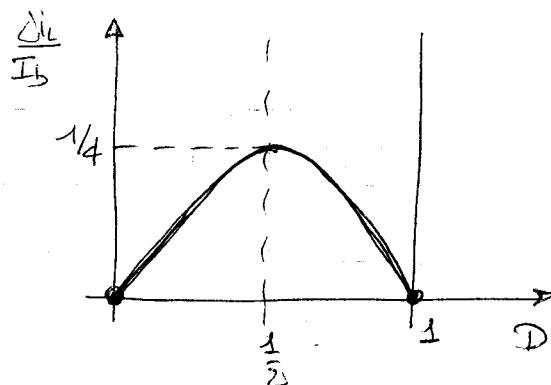


6) Current ripple (inductor)



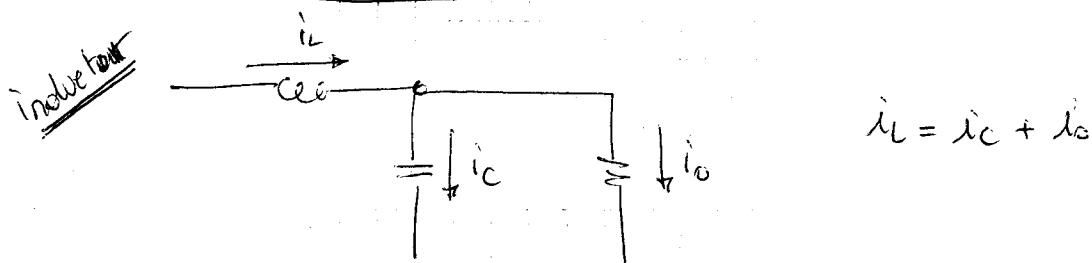
$$\Delta i_L = \frac{V_i - V_o}{L} \cdot D T_S = \frac{V_i - DV_i}{L} D T_S = \left(\frac{V_i T_S}{L} \right) (1-D) D$$

$= I_b (1-D) D$



$$\boxed{\Delta i_L = \frac{V_i T_S}{4L}}$$

7) Average and maximum current

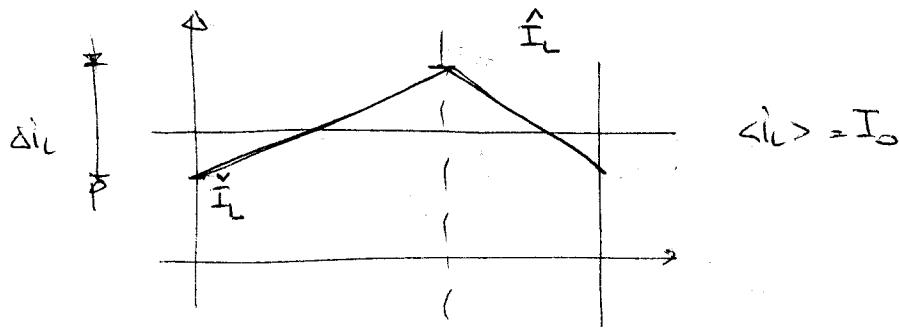


$$\frac{1}{T_S} \int i_L dt = \frac{1}{T_S} \int i_C dt + \frac{1}{T_S} \int i_o dt$$

$$\langle i_L \rangle = \langle i_C \rangle + \langle i_o \rangle$$

$$\langle i_L \rangle = \langle i_o \rangle = I_o = \frac{V_o}{R}$$

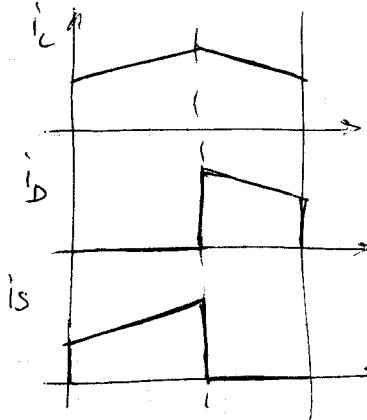
(14)

max

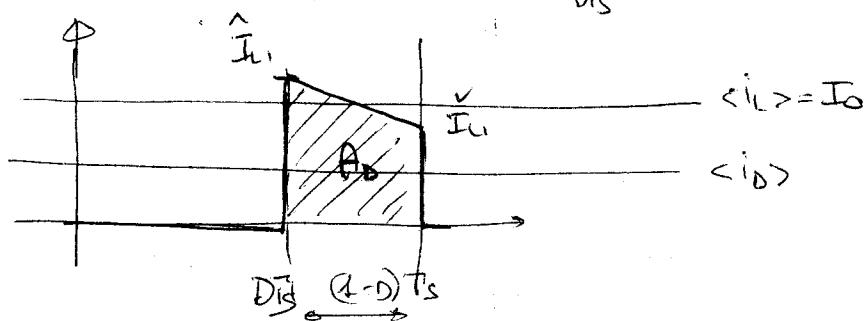
$$\langle i_L \rangle = I_0$$

$$\hat{i}_L = \langle i_L \rangle + \frac{\Delta i_L}{2} = I_0 + \frac{\sqrt{Ts}}{2L} (1-D)D$$

$$\hat{i}_L = \hat{i}_D = \hat{i}_{S_i}$$

discrete

$$\langle i_D \rangle = \frac{1}{Ts} \int_0^{Ts} i_D(t) dt = \frac{1}{Ts} \int_0^{D \cdot Ts} i_D(t) dt + \frac{1}{Ts} \int_{D \cdot Ts}^{Ts} i_D(t) dt$$



$$\langle i_D \rangle = I_0$$

$$\langle i_D \rangle$$

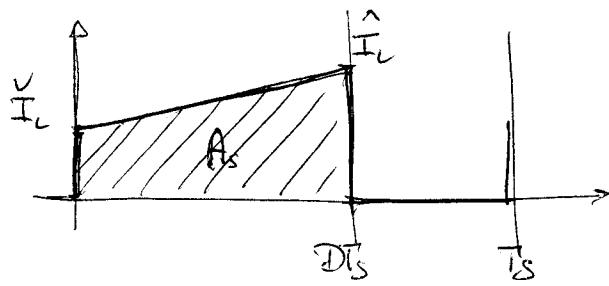
$$= \frac{1}{Ts} A_D = \frac{1}{Ts} \left[\frac{\hat{i}_L + i_L^h}{2} (1-D) Ts \right] = I_0 (1-D)$$

$$\boxed{\langle i_D \rangle = I_0 (1-D)}$$

switch

$$\langle i_S \rangle = \frac{1}{Ts} \int_0^{Ts} i_S(t) dt = \frac{1}{Ts} \int_0^{D \cdot Ts} i_S(t) dt + \frac{1}{Ts} \int_{D \cdot Ts}^{Ts} i_S(t) dt =$$

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$$= \frac{1}{T_s} A_s = \frac{1}{T_s} \left[\frac{\hat{I}_L + \hat{I}_L}{2} \cdot D T_s \right] = I_0 \cdot D$$

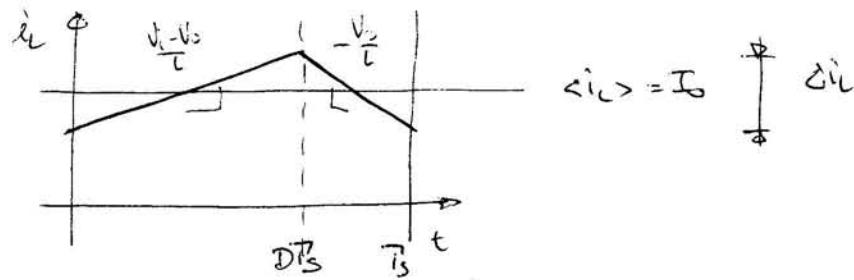
$$\langle i_s \rangle = I_0 D$$

$$\langle i_i \rangle = \langle i_s \rangle = I_0 D$$

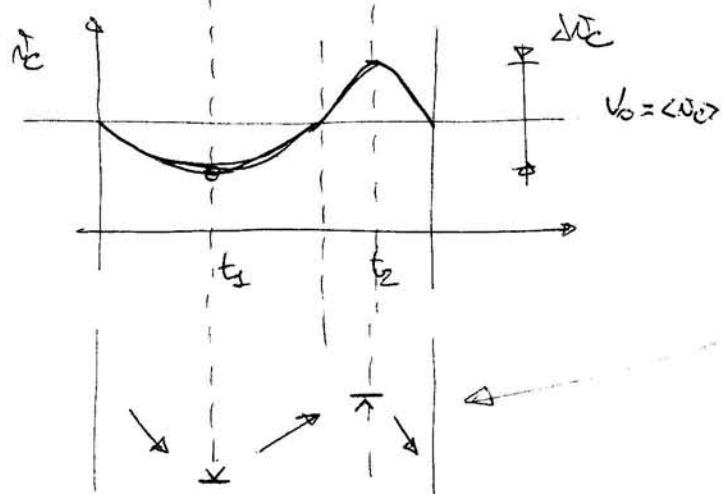
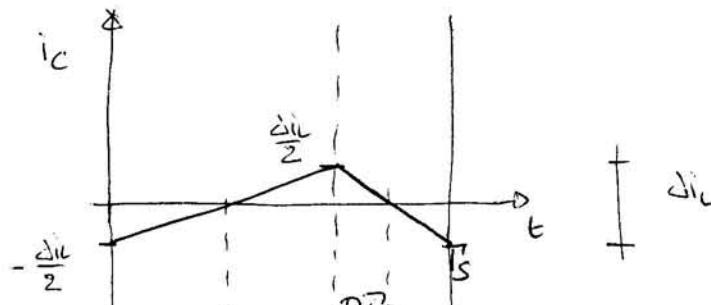
8) Maximum voltage

$$\left| \hat{V}_s \right| = V_i \quad \left| \hat{V}_D \right| = V_i$$

a) Output voltage ripple



$$i_C = i_L - I_o$$



$$\bar{v}_C = \frac{1}{C} \int_0^t i_C dt + V_0$$

$$(i_C = \frac{dv_C}{dt})$$

$$\bar{v}_C(t_2) = \frac{1}{C} \int_0^{t_2} i_C dt + V_0$$

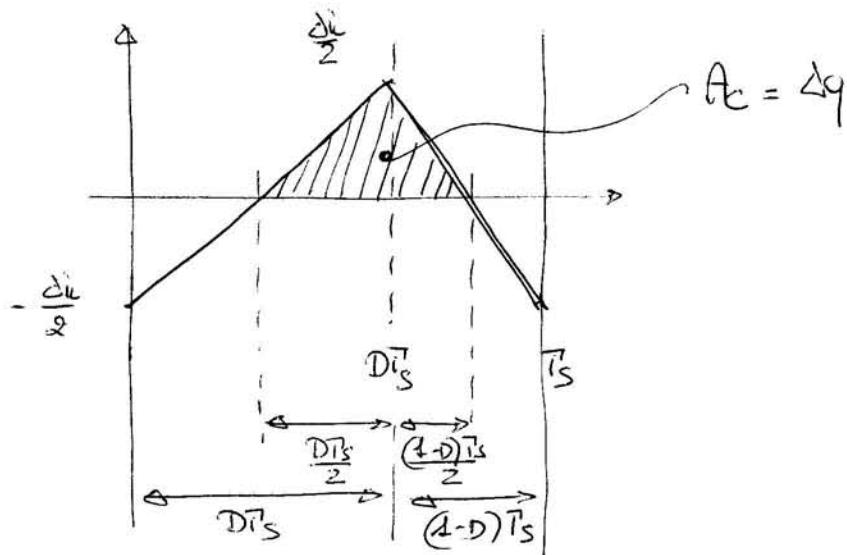
$$\bar{v}_C(t_1) = \frac{1}{C} \int_0^{t_1} i_C dt + V_0$$

$$\Delta v_C = \bar{v}_C(t_2) - \bar{v}_C(t_1) = \frac{1}{C} \int_0^{t_2} i_C dt + V_0 - \frac{1}{C} \int_0^{t_1} i_C dt - V_0$$

$$= \frac{1}{C} \int_0^{t_2} i_C dt + \frac{1}{C} \int_{t_1}^0 i_C dt$$

$$= \frac{1}{C} \int_{t_1}^0 i_C dt + \frac{1}{C} \int_0^{t_2} i_C dt = \frac{1}{C} \int_{t_1}^{t_2} i_C dt$$

$$\Delta \hat{V}_C = \frac{1}{C} \int_{t_1}^{t_2} i_C dt = \frac{l}{C} A_C = \frac{\Delta q}{C}$$



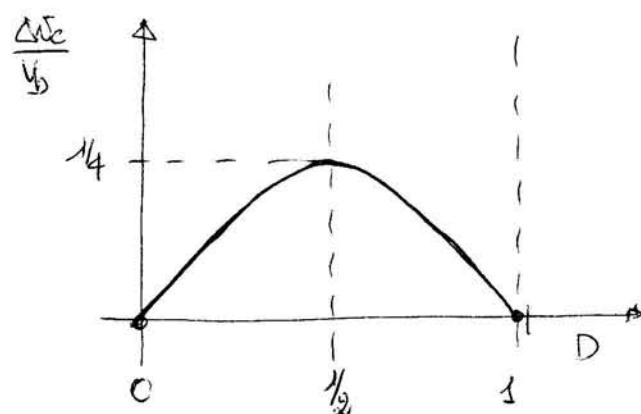
$$\begin{aligned} A_C &= \frac{1}{2} \left[\frac{D\bar{i}_S}{2} + \frac{(1-D)\bar{i}_S}{2} \right] \cdot \frac{\Delta i_C}{2} \\ &= \frac{1}{2} \cdot \frac{1}{2} [D + (1-D)] \bar{i}_S \cdot \frac{\Delta i_C}{2} = \frac{1}{8} \bar{i}_S \cdot \Delta i_C \end{aligned}$$

$$\Delta i_C = \frac{V_i \bar{i}_S}{L} (1-D) D$$

$$\Delta \hat{V}_C = \frac{1}{C} \cdot \frac{1}{8} \cdot \bar{i}_S \cdot \frac{V_i \bar{i}_S}{L} (1-D) D$$

$$\Delta \hat{V}_C = \frac{V_i \bar{i}_S^2}{8LC} (1-D) D$$

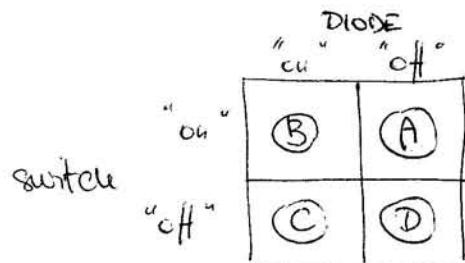
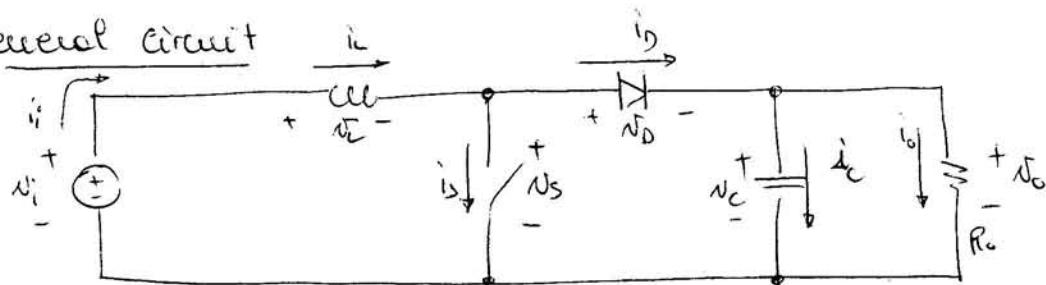
$$\frac{V_i \bar{i}_S^2}{8LC} = V_b$$



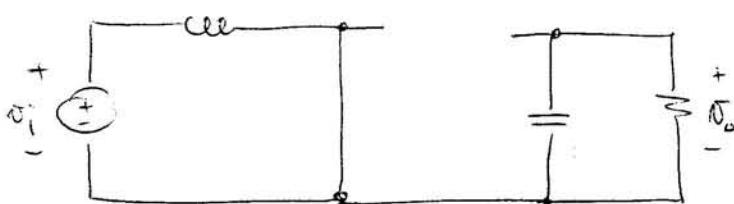
$$\begin{aligned} \hat{\Delta V}_C &= \frac{V_i \bar{i}_S^2}{8LC} \frac{1}{4} \\ &= \frac{V_i \bar{i}_S^2}{32LC} \end{aligned}$$

Basis

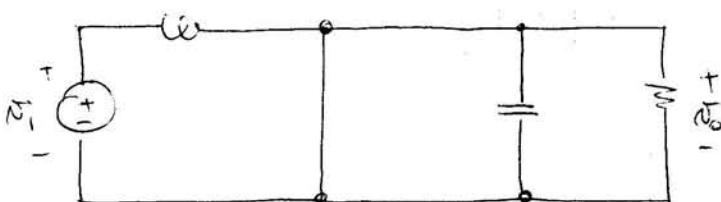
1) General circuit



(A)

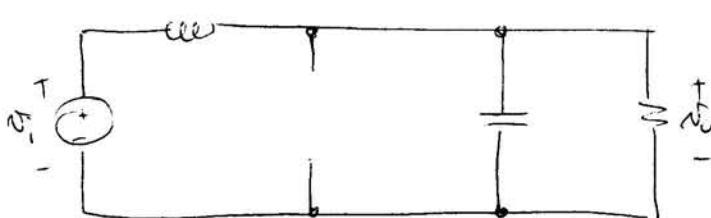


(B)

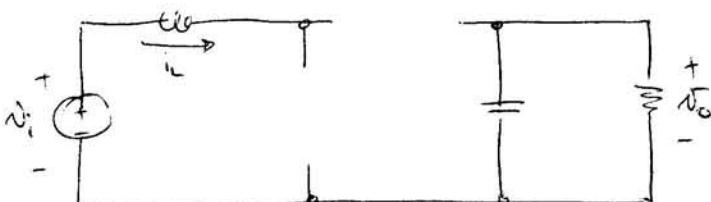


cannot work: " N_S "
shortcircuited

(C)

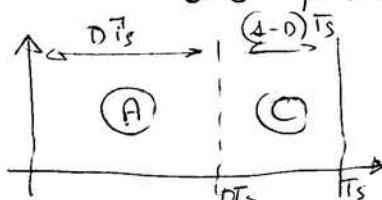


(D)

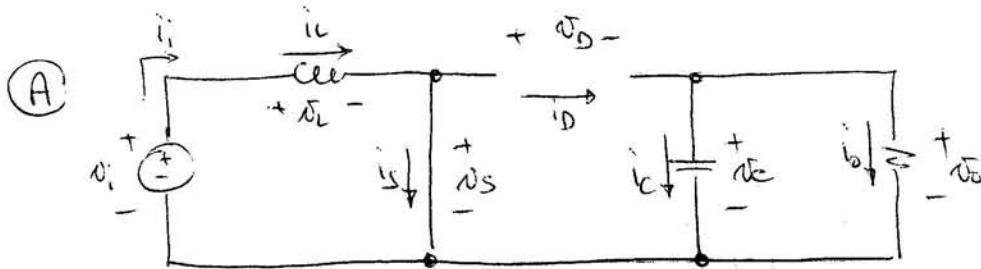


works only if $i_L = 0$
special case see |||
consider in the future

→ Only \textcircled{A} and \textcircled{C} are possible:



2) Studying the two possible circuits



Voltage: $\bar{V}_S = 0$ $\bar{V}_C = \bar{V}_D \approx V_0$ $\bar{V}_L = -\bar{V}_D \approx -V_0$
(cfr v/i diagrammi)

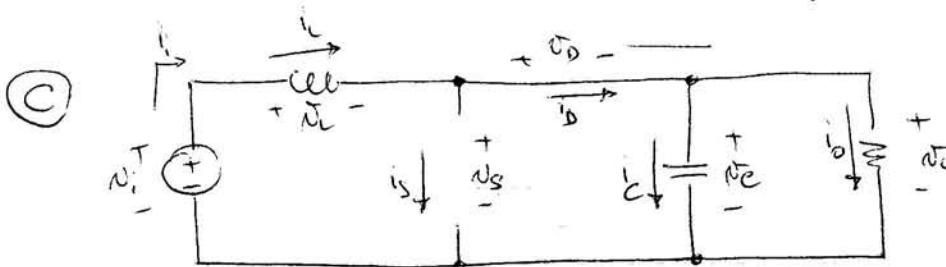
$$\bar{V}_L = \bar{V}_i = V_i \quad V_i > 0 \Rightarrow \boxed{\bar{V}_L > 0}$$

Current $i_D = 0$

$$i_i = i_S = i_L = \frac{1}{L} \int_0^t \bar{V}_L(t) dt + I_1 = \frac{1}{L} \int_0^t V_i dt + I_1 \\ = \frac{V_i}{L} t + I_1$$

$$i_0 \approx \frac{V_0}{R} = I_0$$

$$i_C = -i_0 \approx -I_0 = -\frac{V_0}{R}$$



Voltage: $\bar{V}_D = 0$ $\bar{V}_C = \bar{V}_0 \approx V_0$ $\bar{V}_S = \bar{V}_0 \approx V_0$
(cfr v/i diagrammi)

$$\bar{V}_L = \bar{V}_i - \bar{V}_0 \approx V_i - V_0$$

$$V_0 > V_i \Rightarrow V_i - V_0 < 0 \Rightarrow \boxed{\bar{V}_L < 0}$$

Current

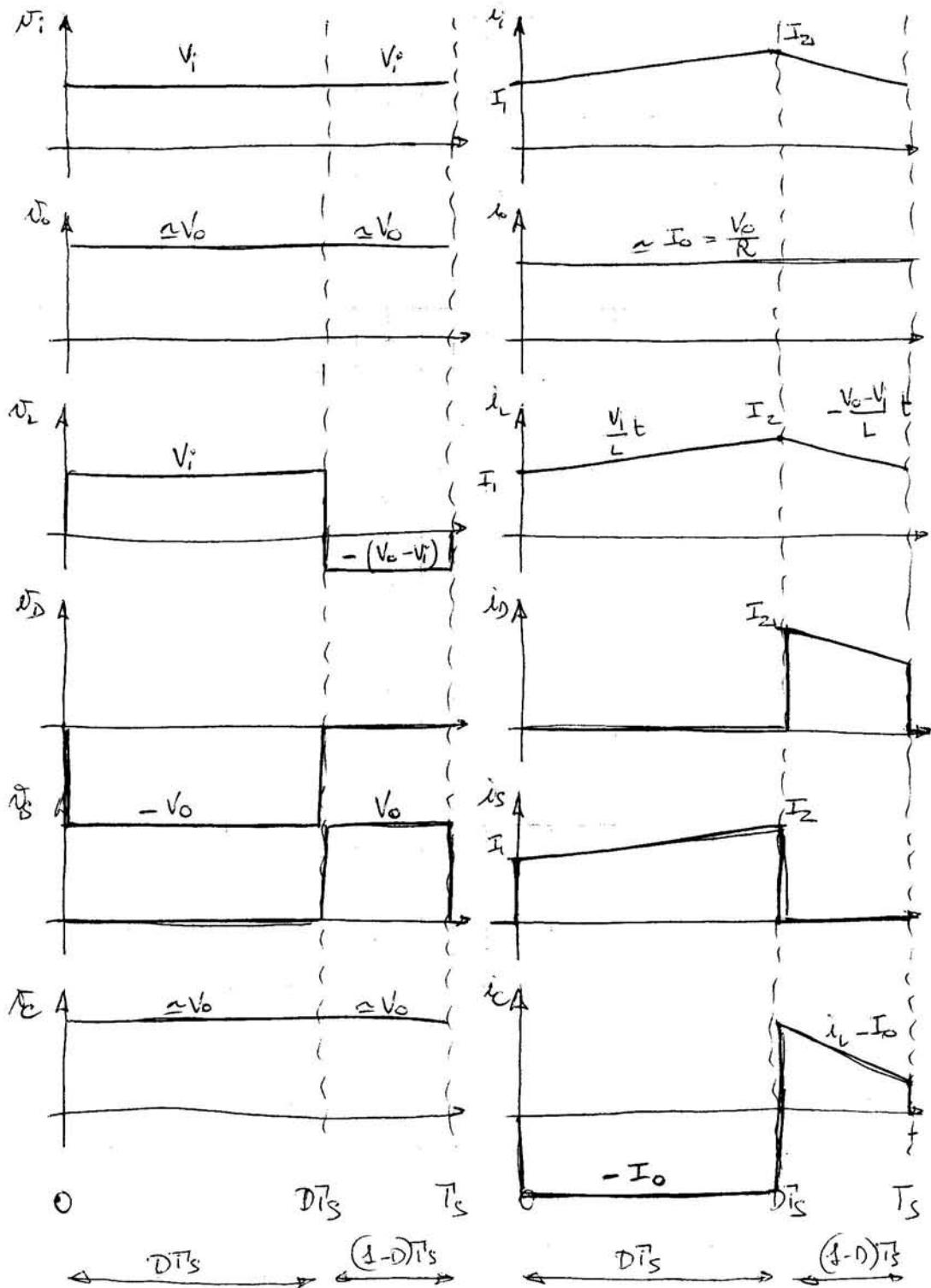
$$i_S = 0$$

$$i_i = i_D = i_L = \frac{1}{L} \int_0^t \bar{V}_L(t) dt + I_0$$

$$\int \frac{1}{L} \int_0^t (V_i - V_o) dt + I_2 = - \frac{V_o - V_i}{L} t + I_2$$

$$i_C = i_D - i_o = i_L - i_o \approx i_L - I_0$$

3) Voltage and current diagrams



4) Steady-state conditions

$$\text{Inductor} \quad \mathcal{E}_L = L \frac{di}{dt}$$

$$i_L(t) = \frac{1}{L} \int_0^t \mathcal{E}_L(t) dt + i_L(0)$$

$$i_L(T_S) = \frac{1}{L} \int_0^{T_S} \mathcal{E}_L(t) dt + i_L(0)$$

Steady state condition : $i_L(T_S) = i_L(0)$

$$i_L(T_S) = \frac{1}{L} \int_0^{T_S} \mathcal{E}_L(t) dt + i_L(0) \Rightarrow \frac{1}{L} \int_0^{T_S} \mathcal{E}_L(t) dt = 0 \Rightarrow$$

$$\boxed{\int_0^{T_S} \mathcal{E}_L(t) dt = 0}$$

$$\int_0^{D T_S} \mathcal{E}_L(t) dt + \int_{D T_S}^{T_S} \mathcal{E}_L(t) dt = 0$$

"Inductor volt-second balance"

$$\int_0^{D T_S} \mathcal{E}_L(t) dt = - \int_{D T_S}^{T_S} \mathcal{E}_L(t) dt$$

$$\int_0^{D T_S} V_i dt = - \int_{D T_S}^{T_S} -(V_o - V_i) dt$$

$$V_i D T_S = (V_o - V_i)(1-D) T_S$$

$$V_i (D + 1 - D) = V_o (1 - D)$$

$$\boxed{V_o = \frac{1}{1-D} V_i}$$

Implication

$$\int_0^{T_S} \mathcal{E}_L(t) dt \Rightarrow \langle \mathcal{E}_L \rangle = \frac{1}{T_S} \int_0^{T_S} \mathcal{E}_L(t) dt = 0$$

$$\boxed{\langle \mathcal{E}_L \rangle = 0}$$

Capacitor

$$i_c = C \frac{dv_c}{dt}$$

$$\bar{v}_c(t) = \frac{1}{C} \int_0^t i_c(t) dt + \bar{v}_c(0)$$

$$\bar{v}_c(T_s) = \frac{1}{C} \int_0^{T_s} i_c(t) dt + \bar{v}_c(0)$$

Steady-state condition. $\bar{v}_c(0) = \bar{v}_c(T_s)$

$$\bar{v}_c(T_s) = \frac{1}{C} \int_0^{T_s} i_c(t) dt + \bar{v}_c(0) \Rightarrow \frac{1}{C} \int_0^{T_s} i_c(t) dt = 0$$

$$\Rightarrow \boxed{\int_0^{T_s} i_c(t) dt = 0}$$

"Capacitor charge balance"

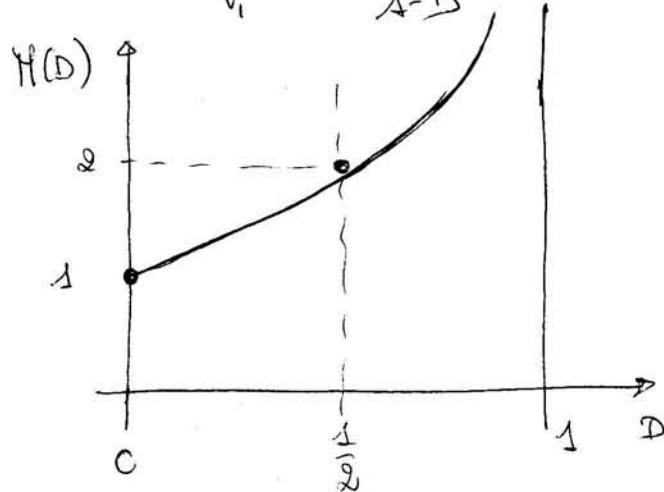
Implication

$$\langle i_c \rangle = \frac{1}{T_s} \int_0^{T_s} i_c(t) dt = 0$$

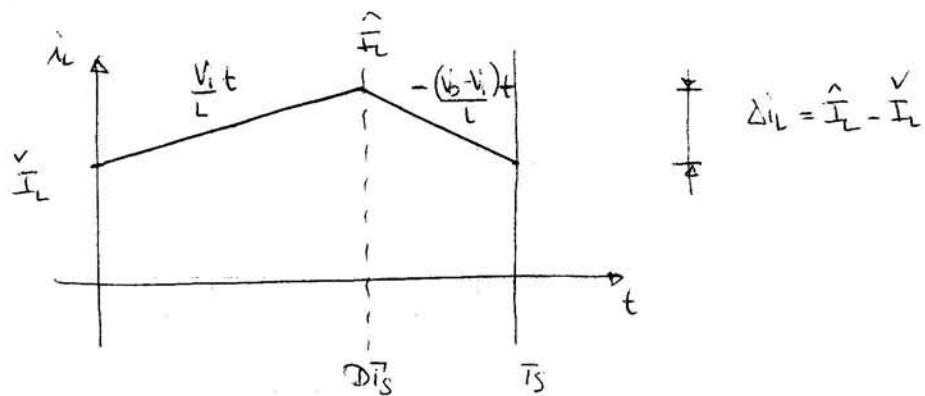
$$\boxed{\langle i_c \rangle = 0}$$

8) Conversion ratio

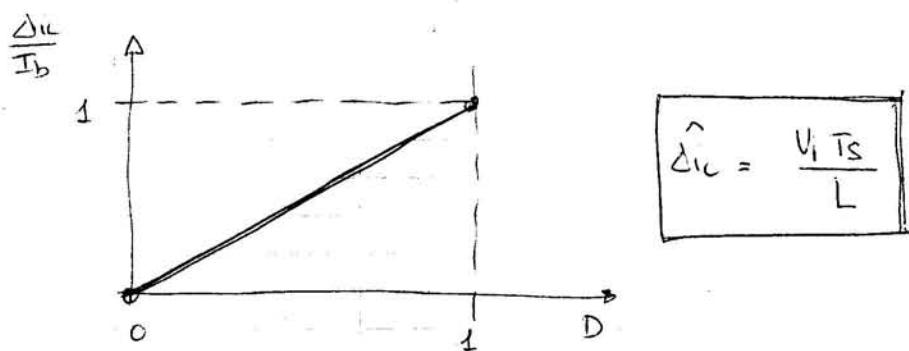
$$H(D) = \frac{V_o(D)}{V_i} = \frac{1}{A-D}$$



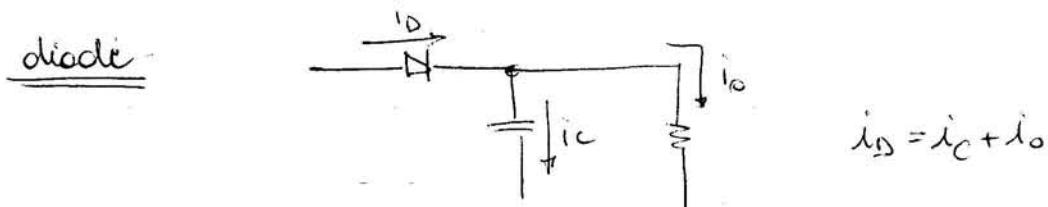
c) Current ripple (inductor)



$$\Delta i_L = \frac{V_i}{L} D T_S = \left(\frac{V_i T_S}{L} \right) D = I_b D$$

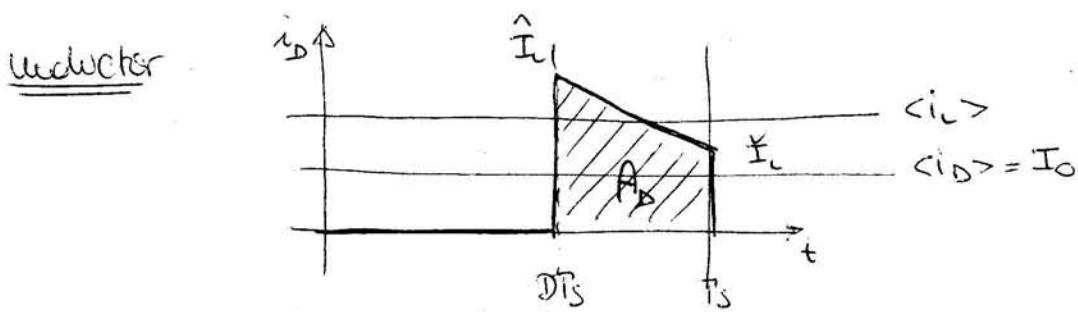


d) Average and maximum current



$$\rightarrow \langle i_D \rangle = \langle i_C \rangle + \langle i_o \rangle$$

$$\langle i_D \rangle = \langle i_o \rangle = I_o = \frac{V_o}{R}$$



$$\langle i_D \rangle = \frac{1}{T_S} \int_0^{T_S} i_D(t) dt = \frac{1}{T} \cancel{\int_{D T_S}^{T_S} i_D(t) dt} + \frac{1}{T_S} \int_{D T_S}^{T_S} i_D(t) dt = \frac{1}{T_S} A_D$$

$$\int \frac{1}{T_S} \left[\frac{\hat{I}_L + \hat{I}_S}{2} (1-D) T_S \right] = \langle i_L \rangle (1-D)$$

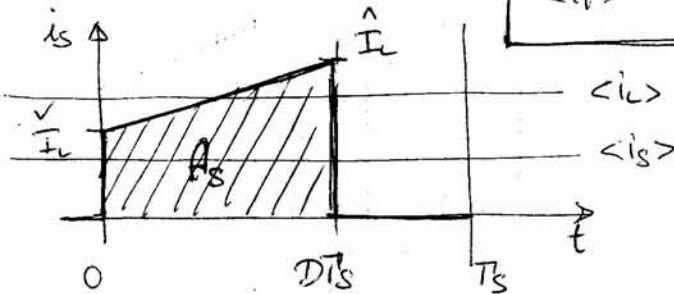
$$\langle i_D \rangle = I_0$$

$$\langle i_L \rangle (1-D) = I_0 \Rightarrow$$

$$\langle i_L \rangle = \frac{1}{1-D} I_0$$

$$\langle i_i \rangle = \langle i_L \rangle = \frac{1}{1-D} I_0$$

switch

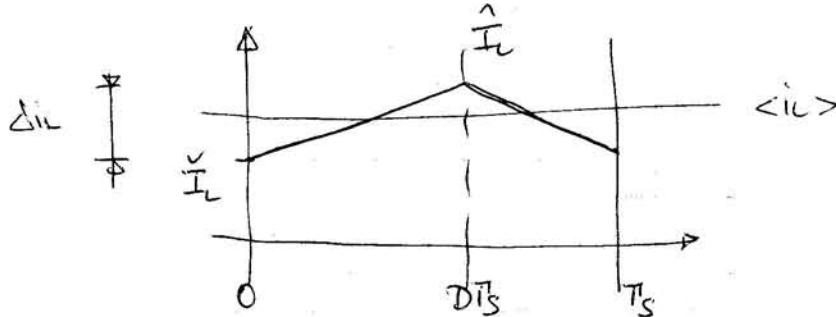


$$\langle i_S \rangle = \frac{1}{T_S} \int_0^{T_S} i_S(t) dt = \frac{1}{T_S} \int_0^{DTS} i_S(t) dt + \frac{1}{T_S} \int_{DTS}^{T_S} i_S(t) dt = \frac{1}{T_S} A_S$$

$$\int \frac{1}{T_S} \left[\frac{\hat{I}_L + \hat{I}_i}{2} D T_S \right] = \langle i_L \rangle D = \frac{D}{1-D} I_0$$

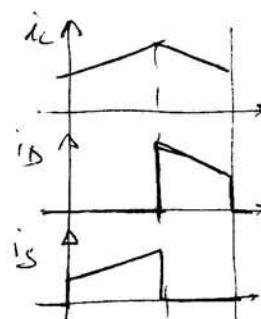
$$\langle i_S \rangle = \frac{D}{1-D} I_0$$

max



$$\hat{I}_L = \langle i_L \rangle + \frac{\Delta i_L}{2} = \frac{1}{1-D} I_0 + \frac{V_o T_S}{L} \cdot D$$

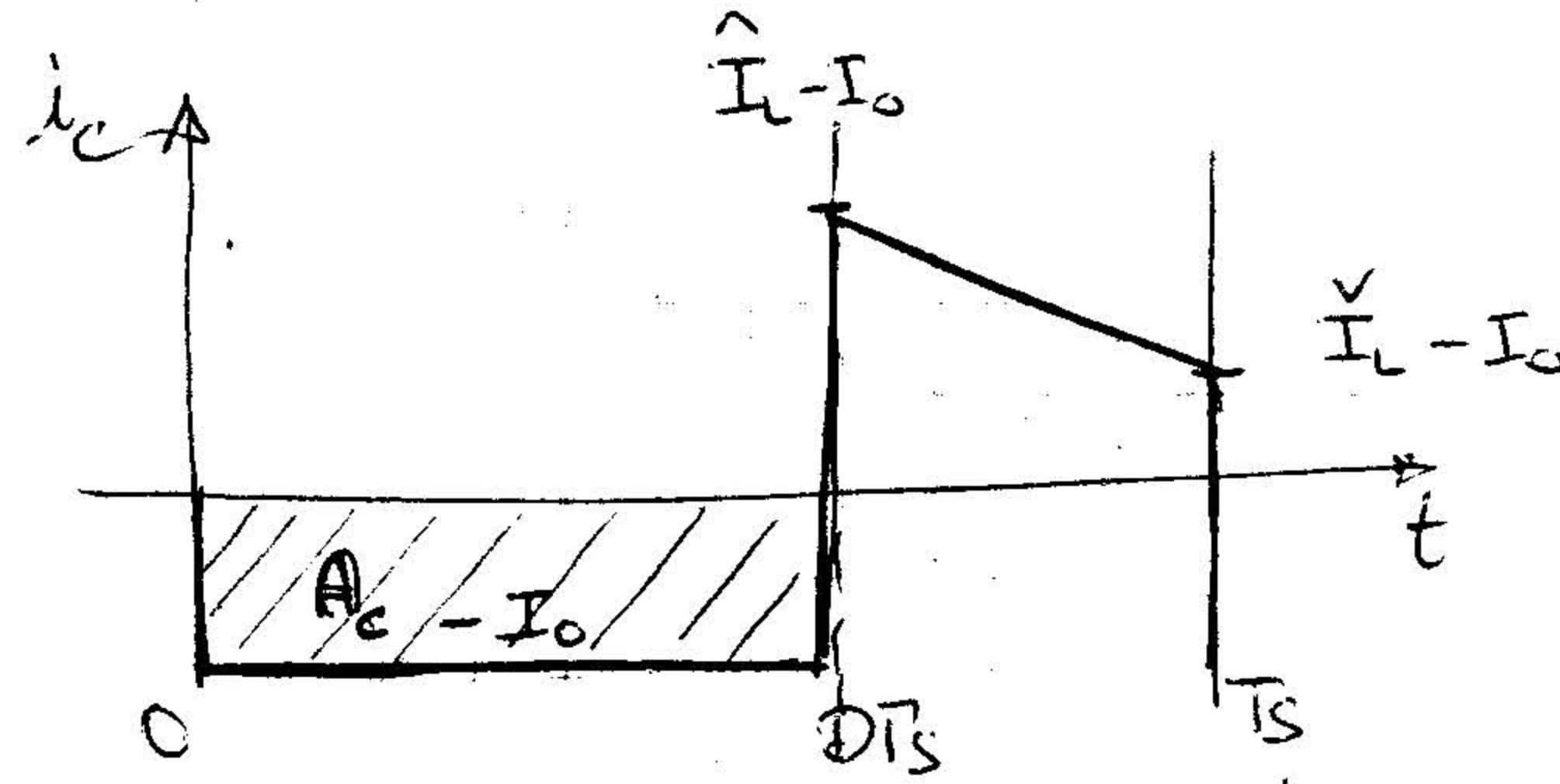
$$\hat{I}_L = \hat{I}_S = \hat{I}_D$$



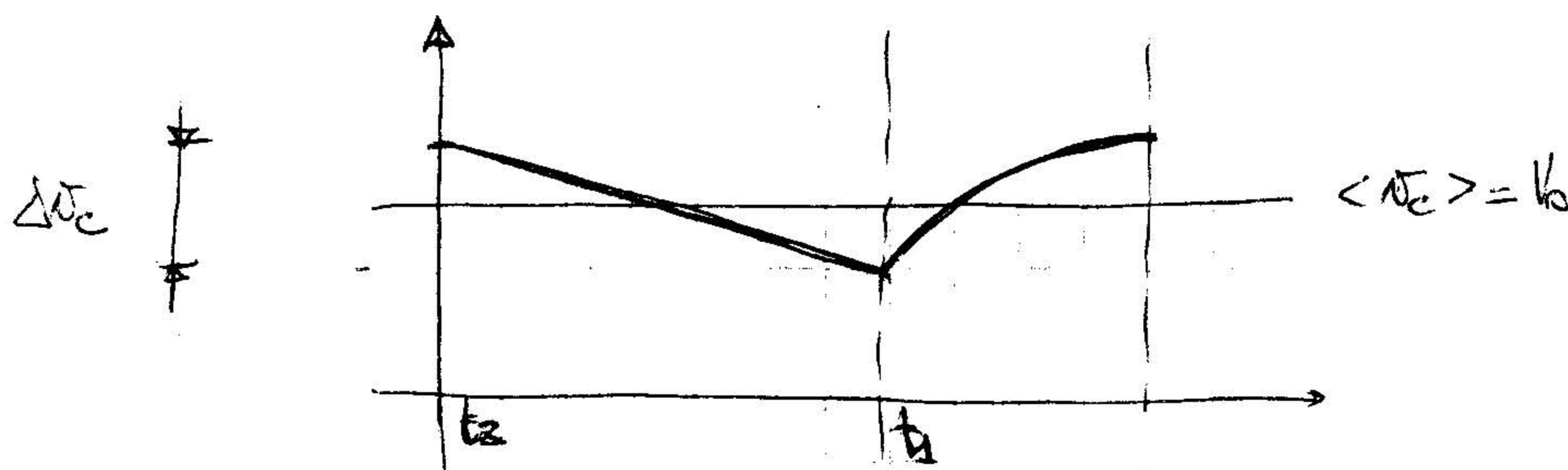
8) Maximum voltage

$$|\hat{v}_S| = V_0 \quad |\hat{v}_B| = V_0$$

9) Output voltage ripple



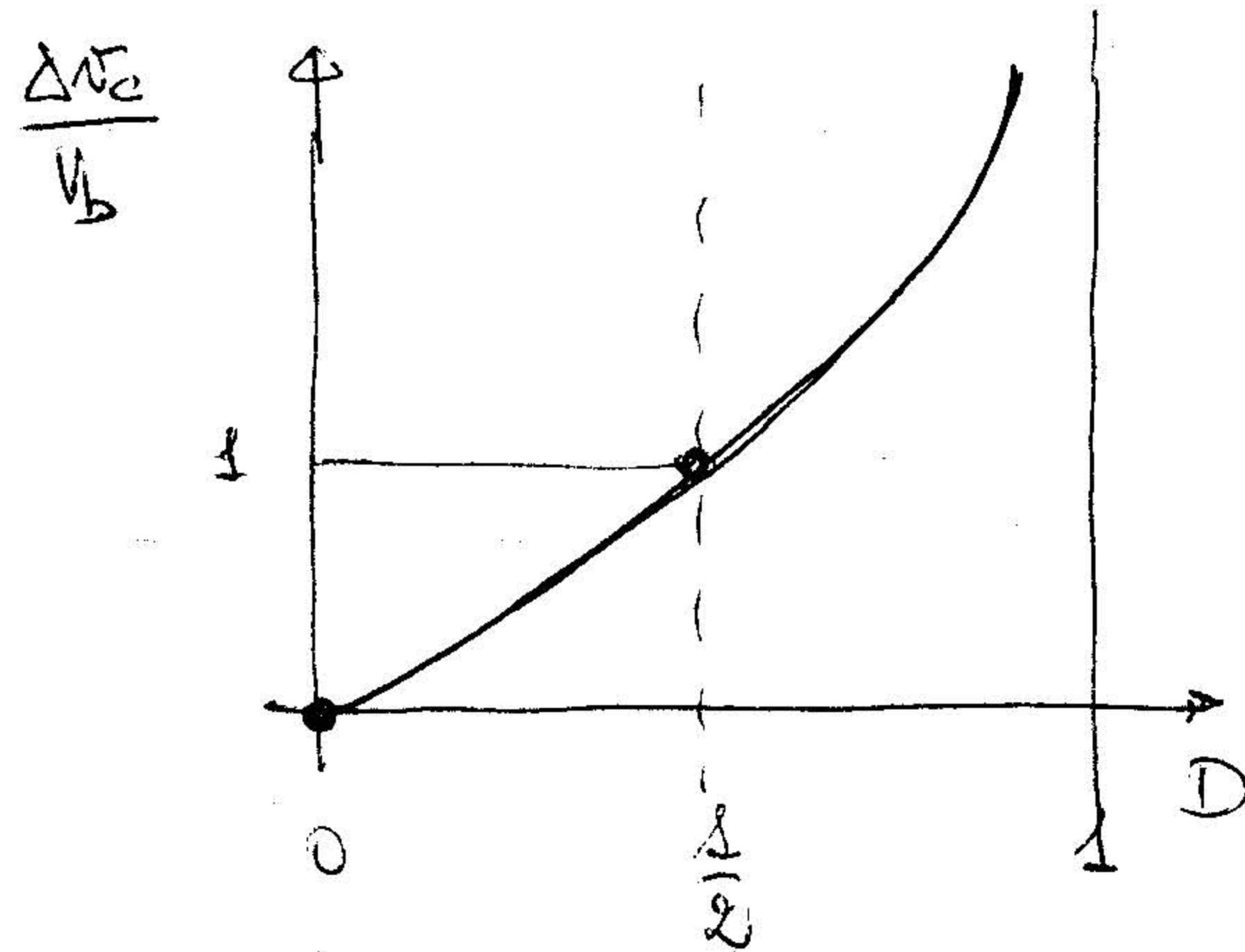
$$i_C = C \frac{dV_C}{dt} \Rightarrow V_C = \frac{1}{C} \int_{0}^t i_C dt + V_I$$



$$\Delta V_C = \frac{1}{C} \int_{t_1}^{t_2} i_C dt = \frac{1}{C} \int_{D\bar{T}_S}^{0} i_C dt = -\frac{1}{C} \int_{0}^{D\bar{T}_S} i_C dt = -\frac{1}{C} \int_{0}^{D\bar{T}_S} (-I_o) dt = \frac{I_o D\bar{T}_S}{C} = \frac{V_0 D\bar{T}_S}{R C}$$

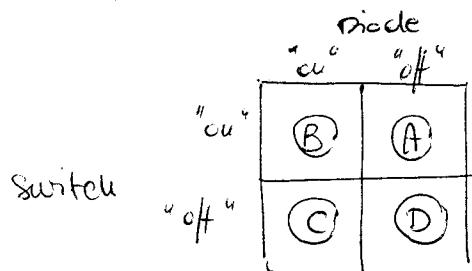
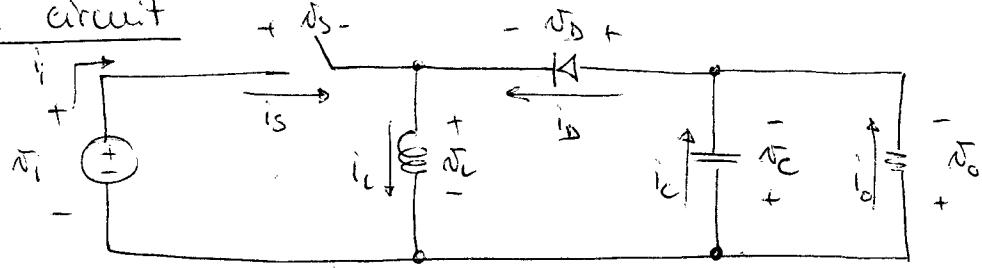
$$\downarrow V_I \frac{1}{1-D} \frac{D \bar{T}_S}{RC} = \frac{V_I \bar{T}_S}{RC} \frac{D}{1-D}$$

$$\boxed{\Delta V_C = \frac{V_I \bar{T}_S}{RC} \frac{D}{1-D}}$$

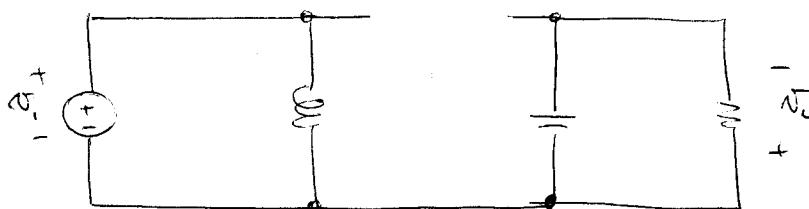


BUCK-BOOST

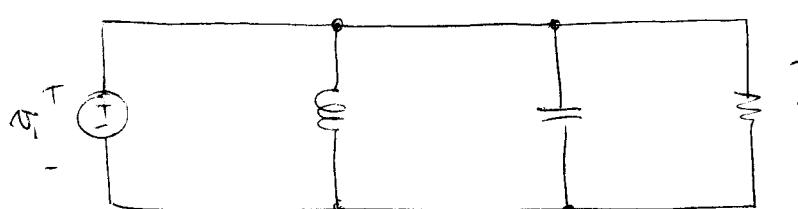
D) General circuit



(A)

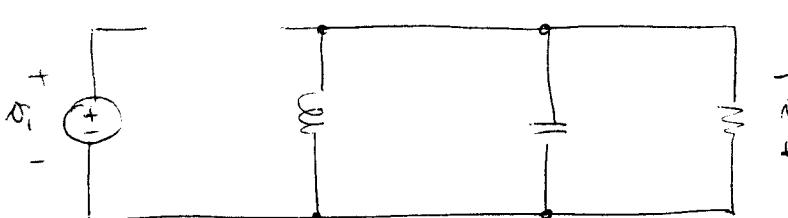


(B)

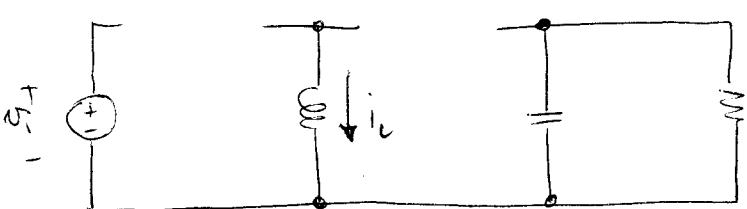


cannot work!
 $V_i = -V_o$

(C)

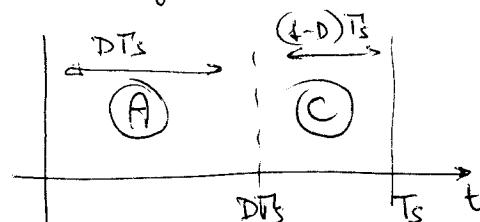


(D)



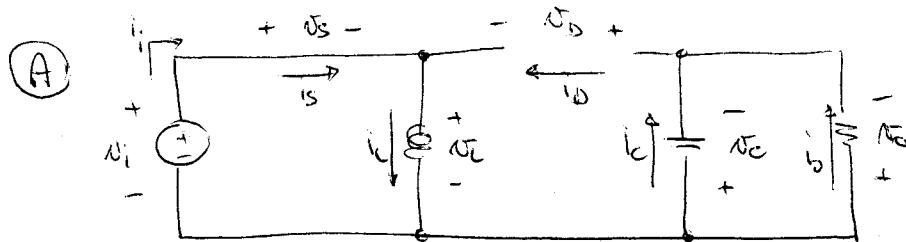
works only if $i_L = 0$
 Special case we'll
 consider in the future.

→ only (A) and (C) are possible:



2) Studying the two possible circuits

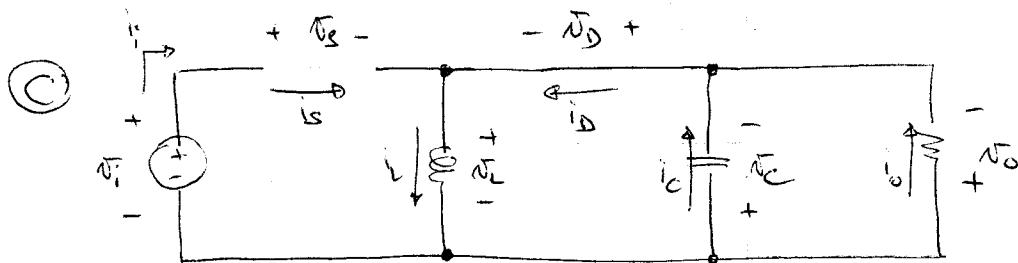
(26)



Voltage $\bar{V}_S = 0$ $\bar{V}_C = \bar{V}_o \approx V_0$ $\bar{V}_D = -\bar{V}_i - \bar{V}_o \approx -V_i - V_0$
(cfr v/diefrans) $\bar{V}_L = V_0$

Current $i_D = 0$ $i_s = i_L = i_t = \frac{1}{L} \int_0^t \bar{V}_L(t) dt + I_1$
 $= \frac{1}{L} \int_0^t V_0 dt + I_1 = \frac{V_0}{L} t + I_1$

$$i_C = -i_o \approx -I_0 = -\frac{V_0}{R}$$



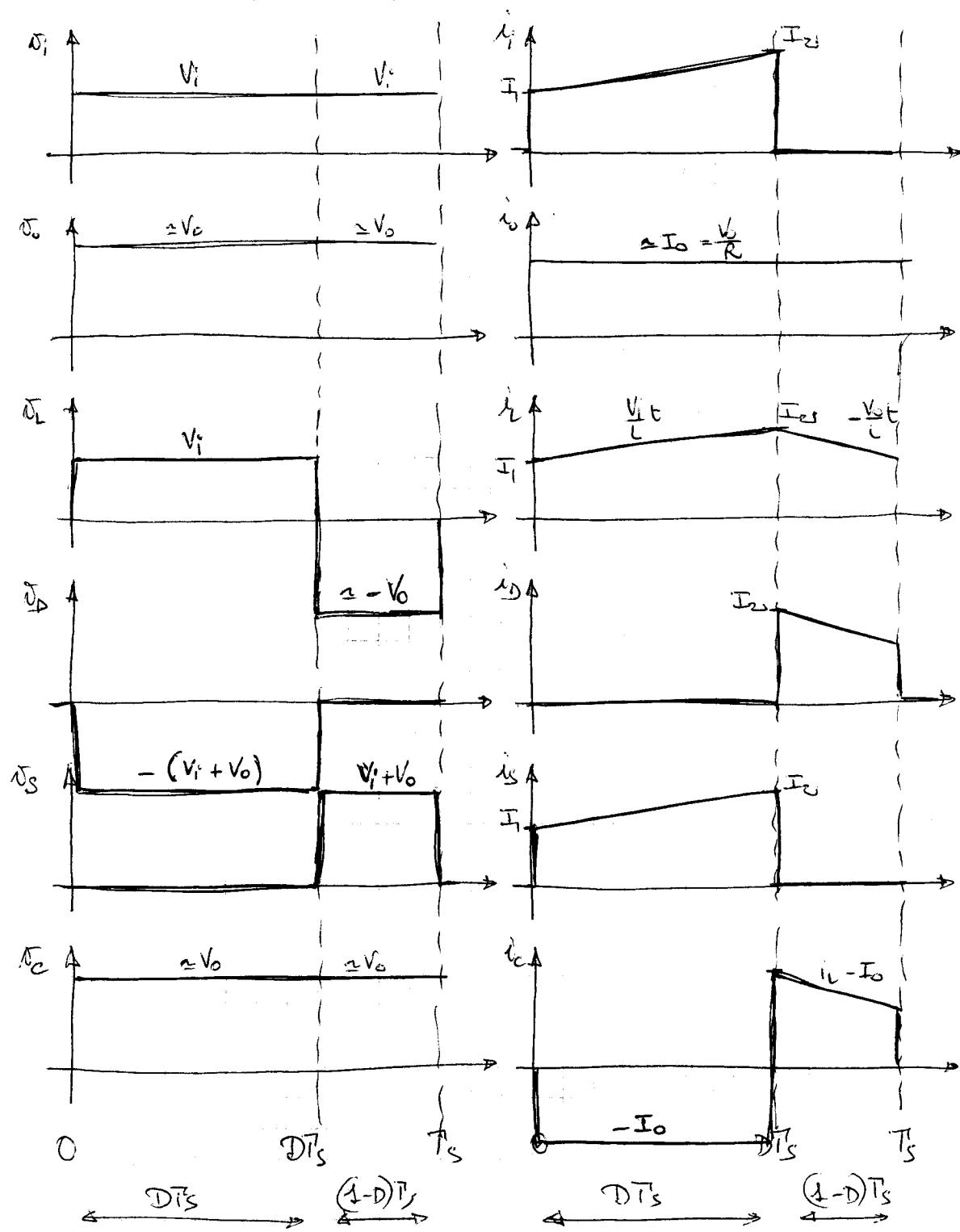
Voltage $\bar{V}_D = 0$ $\bar{V}_C = \bar{V}_o \approx V_0$
(cfr v/diefrans) $\bar{V}_S = \bar{V}_i + \bar{V}_o = V_i + V_0$

$$\bar{V}_L = -\bar{V}_0 \approx -V_0$$

Current $i_S = 0$ $i_D = i_L = i_t = \frac{1}{L} \int_0^t \bar{V}_L(t) dt + I_2 = \frac{1}{L} \int_0^t (-V_0) dt + I_2$
 $= -\frac{V_0}{L} t + I_2$

$$i_C = i_D - i_o \approx i_D - I_0$$

3) Voltage and current波形



4) Steady-state condition

Meter

$$N_L = L \frac{di_L}{dt}$$

$$i_L(t) = \frac{1}{L} \int_0^t v_L(t) dt + i_L(0)$$

$$i_L(T_S) = \frac{1}{L} \int_0^{T_S} \bar{v}_L(t) dt + i_L(0)$$

(28)

Steady-state condition: $i_L(T_S) = i_L(0)$

$$\cancel{i_L(T_S)} = \frac{1}{L} \int_0^{T_S} \bar{v}_L(t) dt + i_L(0) \Rightarrow \frac{1}{L} \int_0^{T_S} \bar{v}_L(t) dt = 0 \Rightarrow \boxed{\int_0^{T_S} \bar{v}_L(t) dt = 0}$$

$$\int_0^{D\bar{T}_S} \bar{v}_L(t) dt + \int_{D\bar{T}_S}^{T_S} \bar{v}_L(t) dt = 0$$

"Inductor volt second balance"

$$\int_0^{D\bar{T}_S} \bar{v}_i(t) dt = - \int_{D\bar{T}_S}^{T_S} \bar{v}_L(t) dt$$

$$\int_0^{D\bar{T}_S} v_i(t) dt = - \int_{D\bar{T}_S}^{T_S} (-v_o) dt$$

$$v_i D\bar{T}_S = v_o (1-D) \bar{T}_S$$

$$\boxed{V_o = \frac{D}{1-D} V_i}$$

Implication

$$\int_0^{T_S} \bar{v}_L(t) dt = 0 \Rightarrow \langle \bar{v}_L \rangle = \frac{1}{T_S} \int_0^{T_S} \bar{v}_L(t) dt = 0 \quad \boxed{\langle \bar{v}_L \rangle = 0}$$

Capacitor

$$i_C = C \frac{d\bar{v}_C}{dt}$$

$$\bar{v}_C(t) = \frac{1}{C} \int_0^t i_C(t) dt + \bar{v}_C(0)$$

$$\bar{v}_C(T_S) = \frac{1}{C} \int_0^{T_S} i_C(t) dt + \bar{v}_C(0)$$

Steady-state condition. $\bar{N}_C(0) = \bar{N}_C(T_S)$

$$\bar{N}_C(T_S) = \frac{1}{C} \int_0^{T_S} i_C(t) dt + \bar{N}_C(0) \Rightarrow \frac{1}{C} \int_0^{T_S} i_C(t) dt = 0$$

$$\Rightarrow \boxed{\int_0^{T_S} i_C(t) dt = 0}$$

"Capacitor charge balance"

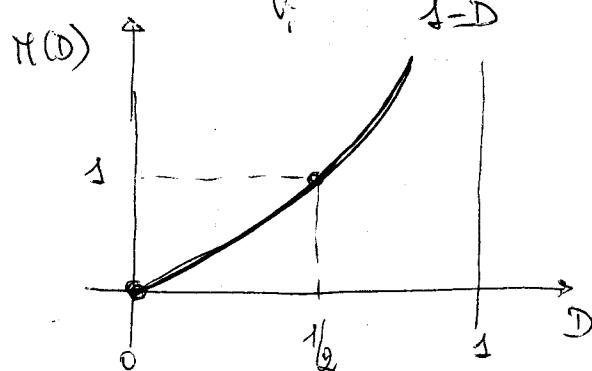
Implication

$$\langle i_C \rangle = \frac{1}{T_S} \int_0^{T_S} i_C(t) dt = 0$$

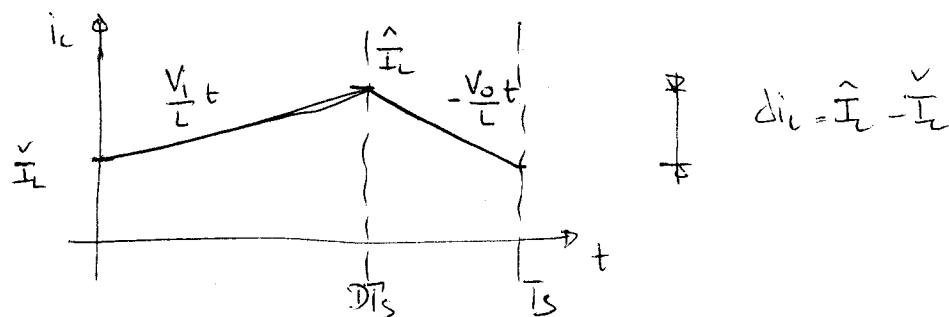
$$\boxed{\langle i_C \rangle = 0}$$

5) Conversion ratio

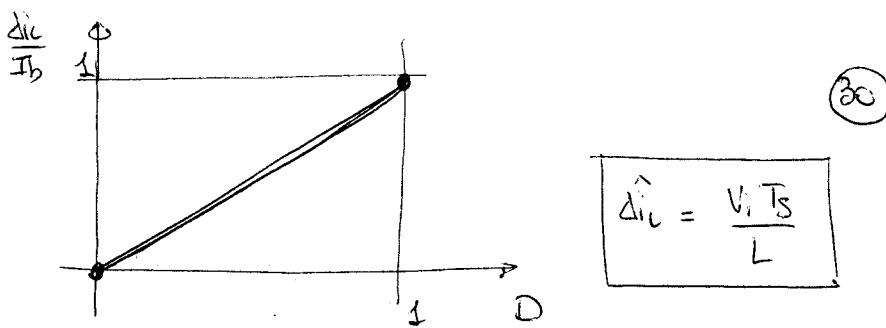
$$M(D) = \frac{V_o(D)}{V_i} = \frac{D}{1-D}$$



6) CURRENT RIPPLE (Inductor)

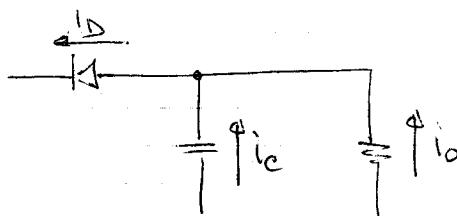


$$\Delta i_L = \frac{V_o}{L} D T_S = \frac{(V_o T_S)}{I_b} D = I_b D$$



7) Average and maximum current

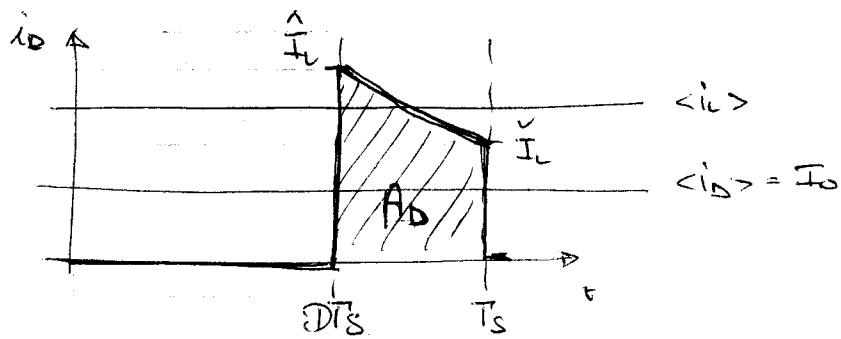
diode



$$i_D = i_C + i_O \Rightarrow \langle i_D \rangle = \langle i_C \rangle + \langle i_O \rangle$$

$$\langle i_D \rangle = \langle i_O \rangle = I_0 = \frac{V_0}{R} \quad \boxed{\langle i_D \rangle = I_0}$$

inductor



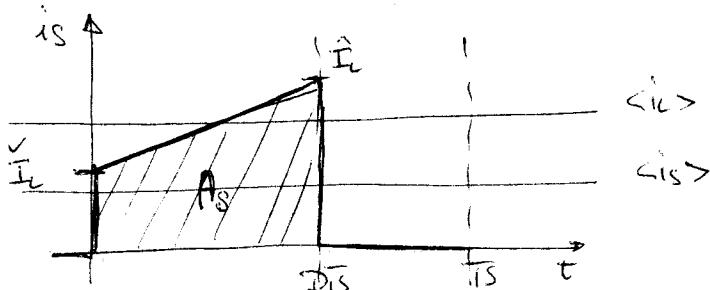
$$\langle i_D \rangle = \frac{1}{T_S} \int_0^{T_S} i_D(t) dt = \frac{1}{T} \int_0^{T_S} i_D(t) dt + \frac{1}{T_S} \int_{T_S}^{T_S} i_D(t) dt = \frac{1}{T_S} A_D$$

$$\frac{1}{T_S} \left[\frac{\hat{I}_L + \check{I}_L}{2} (1-D) T_S \right] = \langle i_L \rangle (1-D)$$

$$\langle i_D \rangle = I_0$$

$$\langle i_L \rangle (1-D) = I_0 \Rightarrow \boxed{\langle i_L \rangle = \frac{1}{1-D} I_0}$$

switch



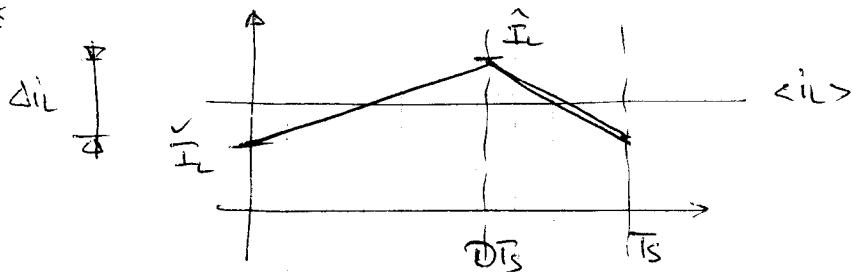
(31)

$$\langle i_S \rangle = \frac{1}{T_S} \int_0^{T_S} i_S(t) dt = \frac{1}{T_S} \int_0^{D T_S} i_S(t) dt + \frac{1}{T_S} \int_{D T_S}^{T_S} i_S(t) dt = \frac{1}{T_S} I_S$$

$$\downarrow \quad \frac{1}{T_S} \left[\frac{I_L + \hat{I}_L}{2} D T_S \right] = \langle i_L \rangle D = \frac{D}{1-D} I_0$$

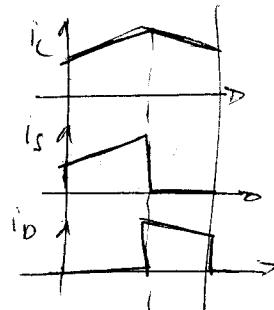
$$\boxed{\langle i_S \rangle = \frac{D}{1-D} I_0}$$

$$\boxed{\langle i_o \rangle = \langle i_S \rangle \frac{D}{1-D} I_0}$$

Max

$$\hat{I}_L = \langle i_L \rangle + \frac{\Delta i_L}{2} = \frac{1}{1-D} I_0 + \frac{V_i T_S}{L} D$$

$$\hat{I}_L = \hat{I}_S = \hat{I}_0$$



8) Maximum voltage

$$|\hat{v}_{DS}| = V_i + V_o$$

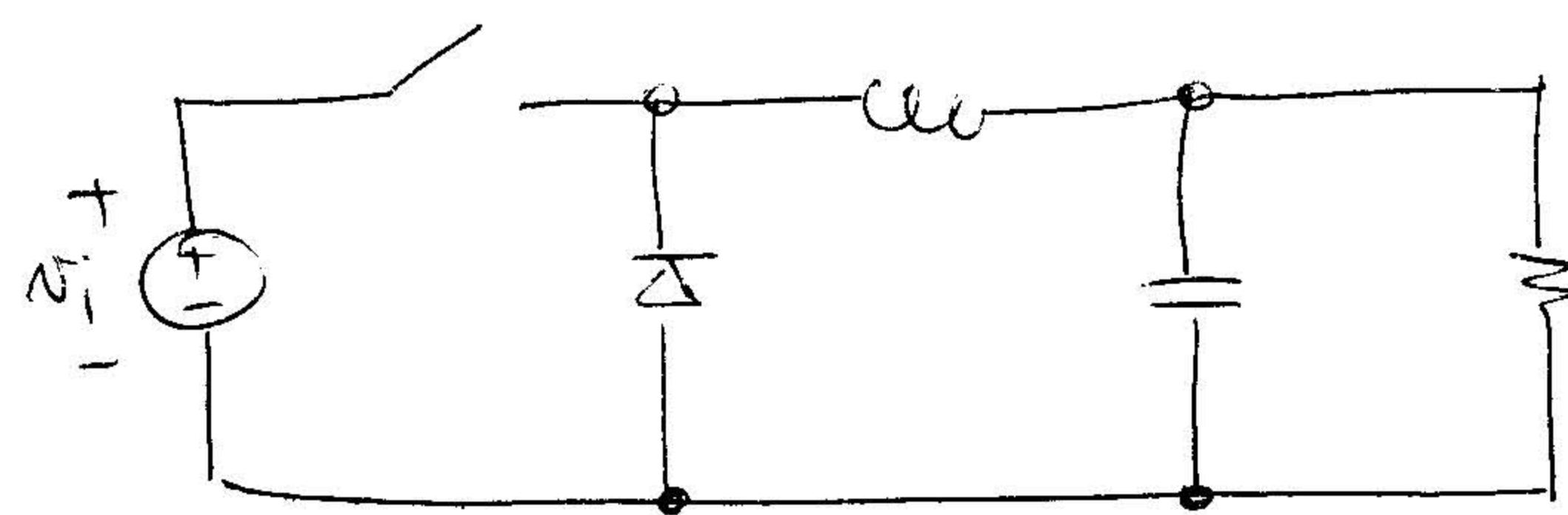
$$|\hat{v}_{OD}| = V_i + V_o$$

9) Output voltage ripple

same as boost

$$\Delta v_C = \frac{V_i T_S}{R C_0} \frac{D}{1-D}$$

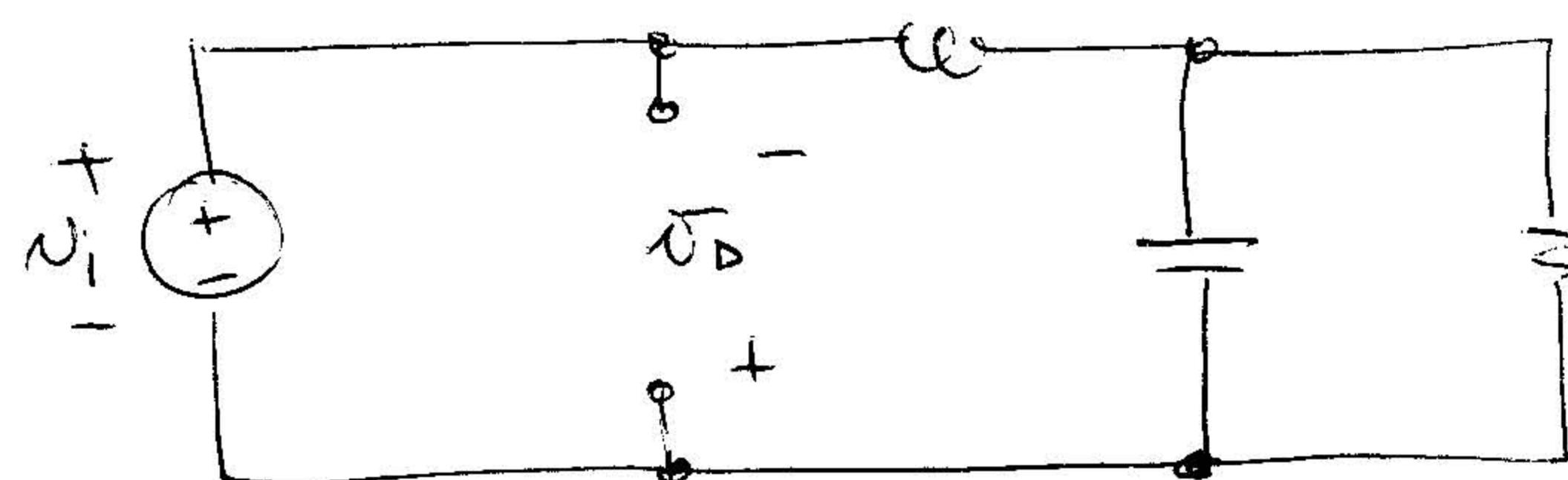
DISCONTINUOUS CONDUCTION MODE



S_{on}/D_{off} $|N_D < 0 ?$

S_{off}/D_{on} $|i_D > 0 ?$

S_{on}/D_{off}

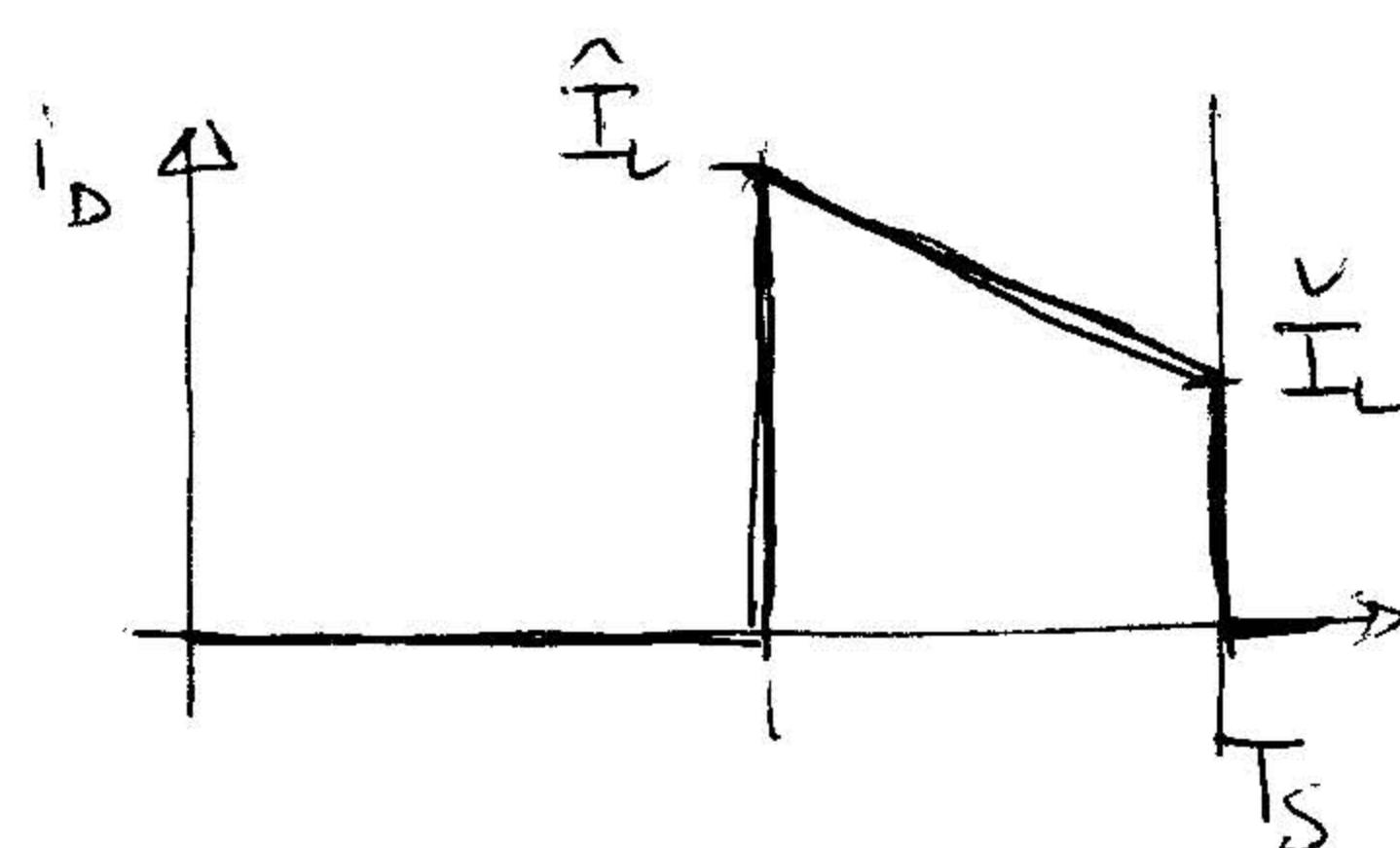
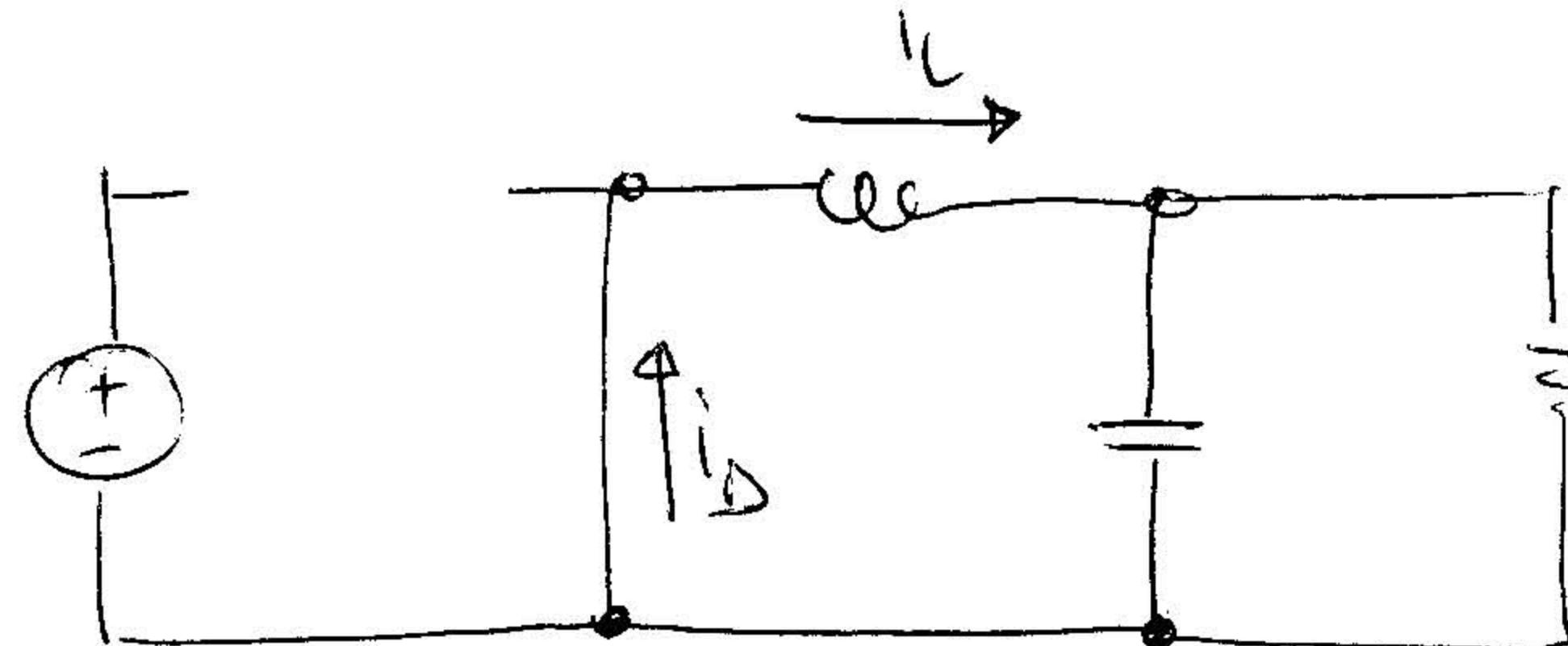


$$v_i = V_i$$

$$N_D = -V_i$$

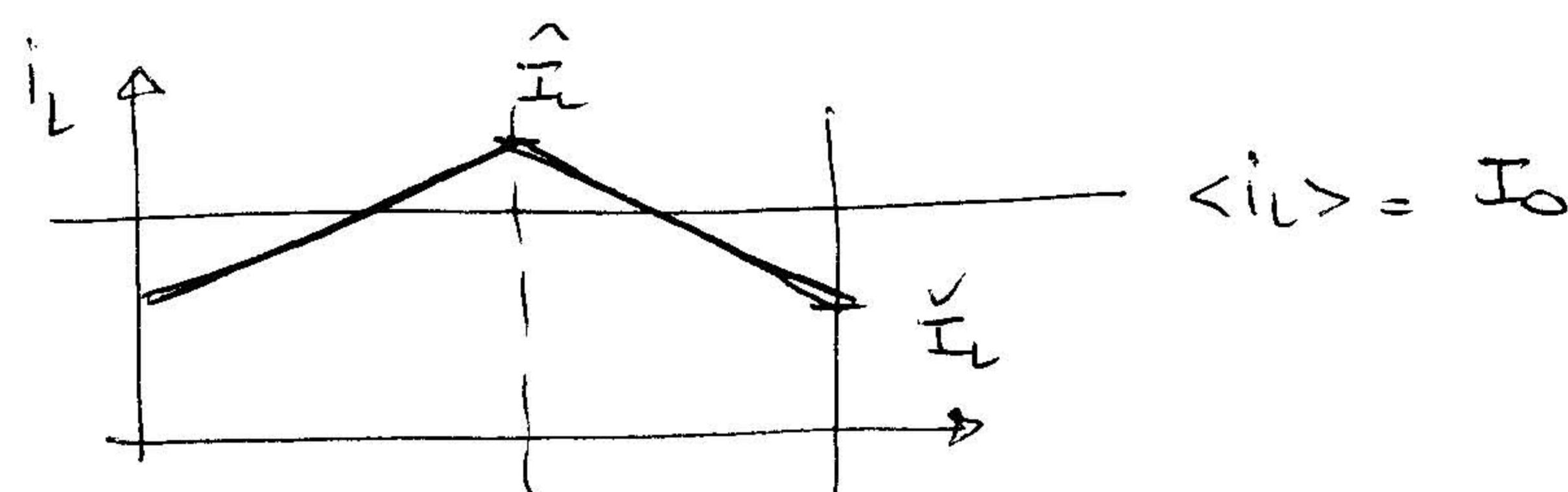
$|N_D < 0 \rightarrow OK$

S_{off}/D_{on}



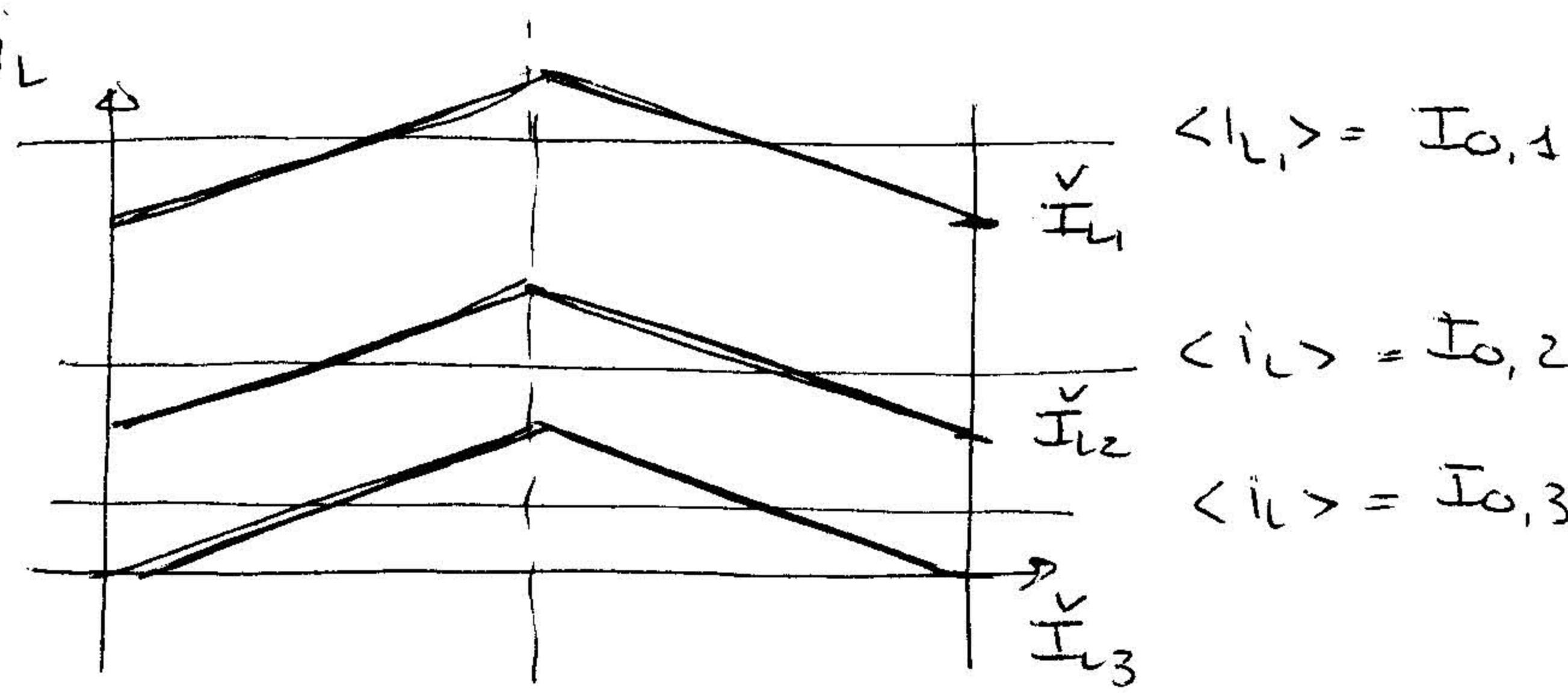
$$i_D > 0 \Leftrightarrow \dot{I}_L > 0$$

$\dot{I}_L > 0$ not always



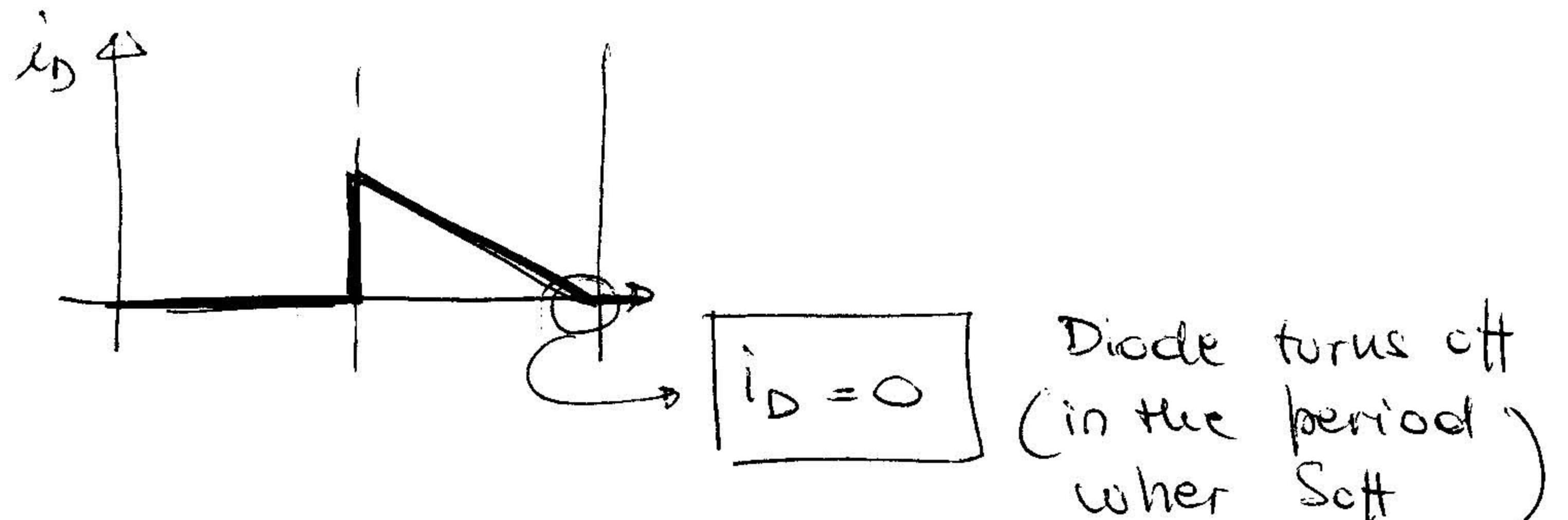
$$\dot{I}_L = I_0 - \frac{\Delta i_L}{2} \quad (I_0 : \text{output current})$$

$$I_0 \downarrow \rightarrow \dot{I}_L \downarrow$$



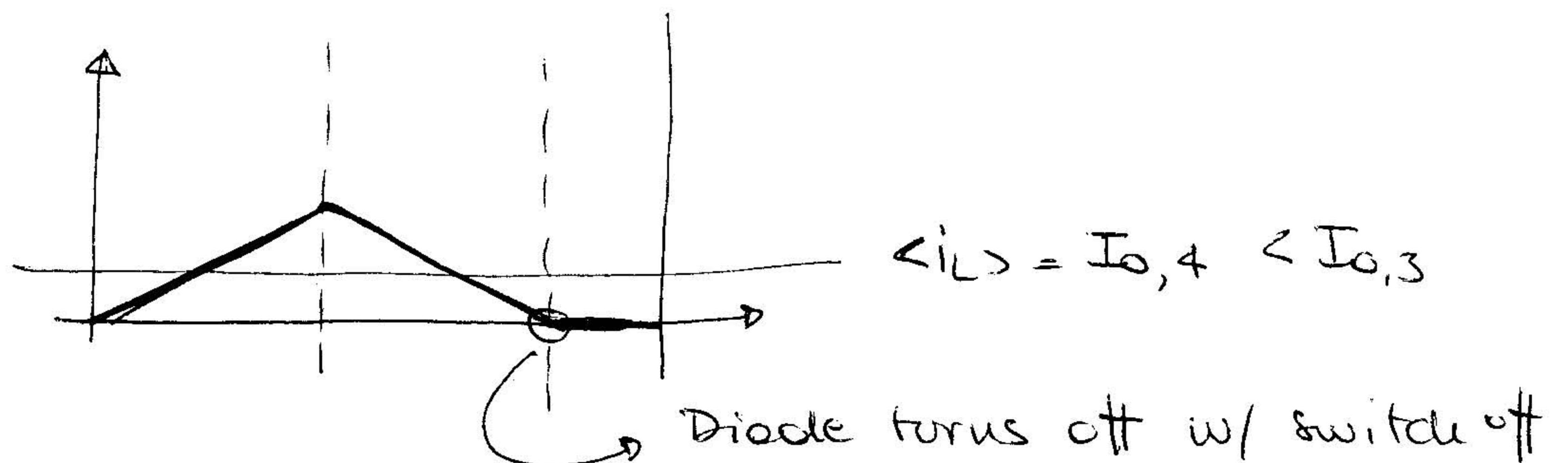
$$I_{0,3} < I_{0,2} < I_{0,1}$$

$$I_{0,3} \Rightarrow i_{L_3} = 0$$



(BUT) in this case limit,
switch turns on immediately after.

(BUT) if $I_0 \downarrow$ even more:



Doff		Don		Doff
Soft		Soft		Soft

case D

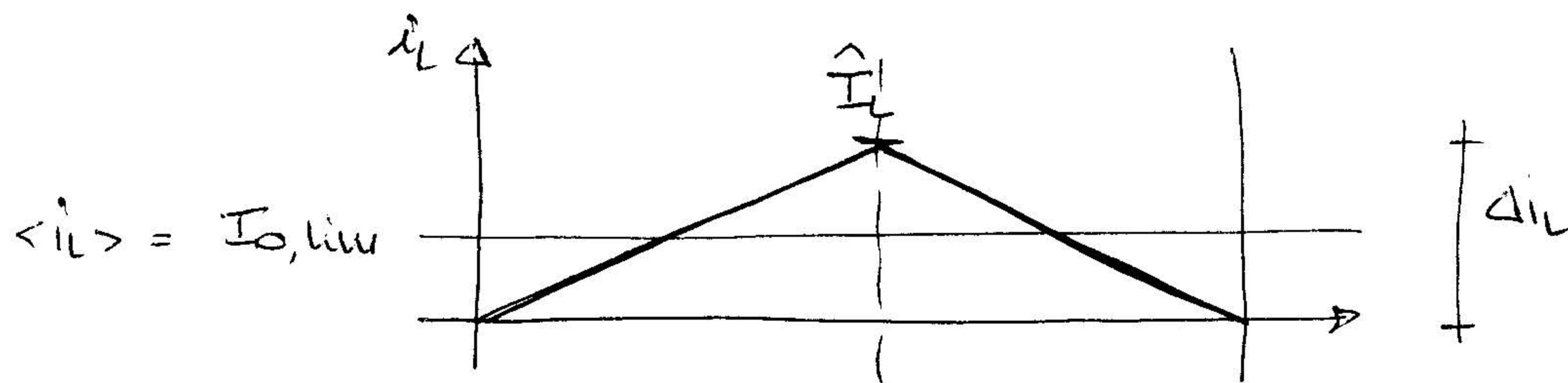
$$i_D = 0 \quad i_S = 0 \quad i_L = i_S + i_D = 0$$

the current in L goes (and stays) zero
→ "discontinuous conduction mode" (DCM)

[versus the previous on "Continuous conduction mode" (CCM)]

The case $I_o = I_{o,lim}$ is the "border" between CCM and DCM.

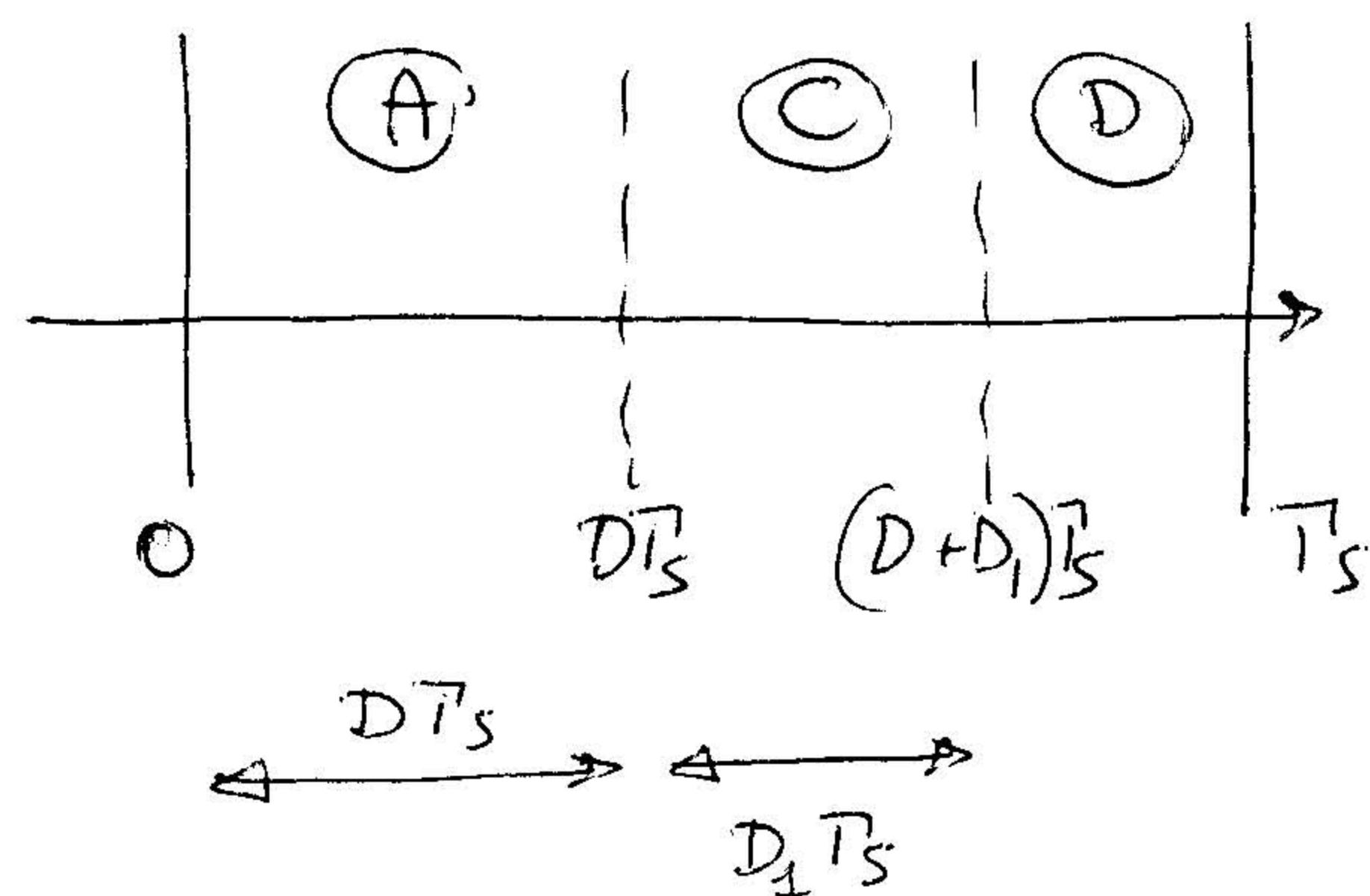
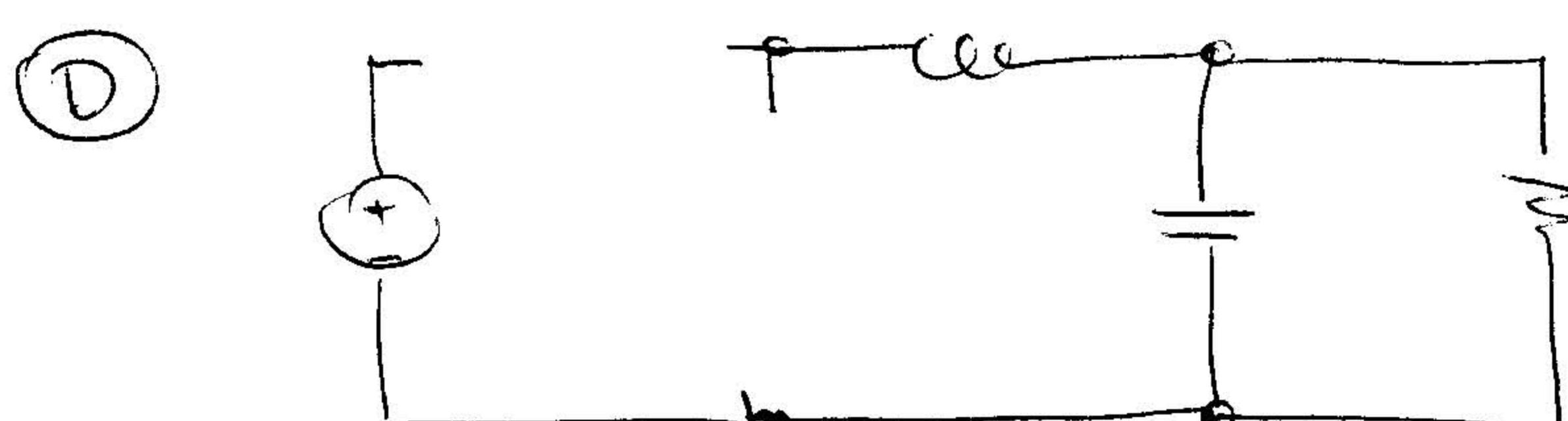
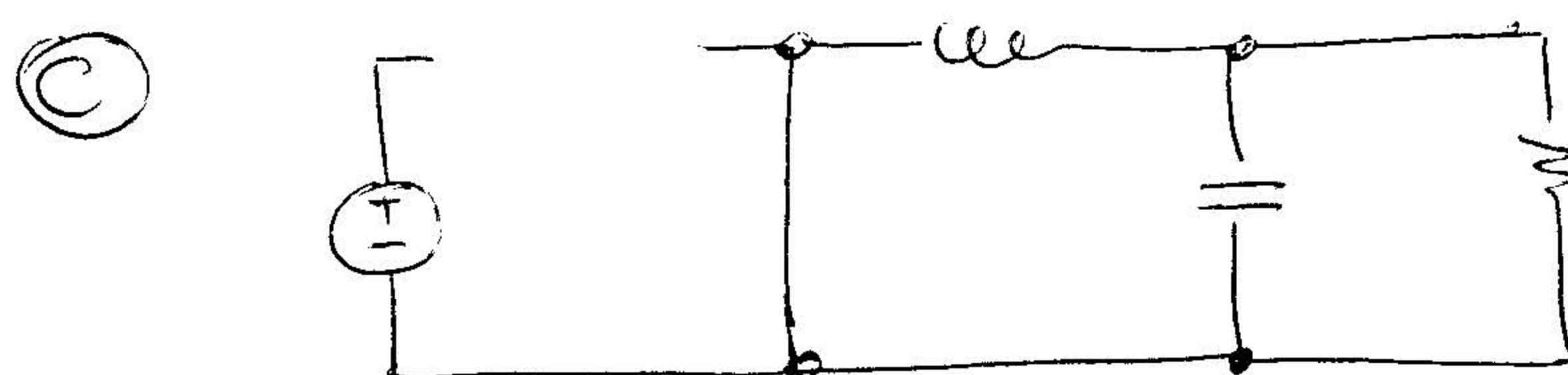
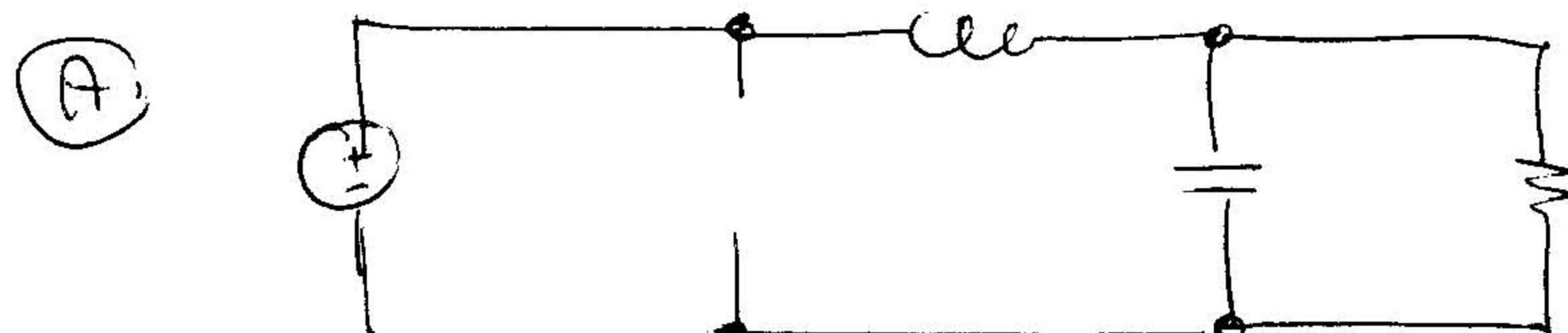
$I_{o,lim}$ is called $I_{o,lim}$ (limit current).



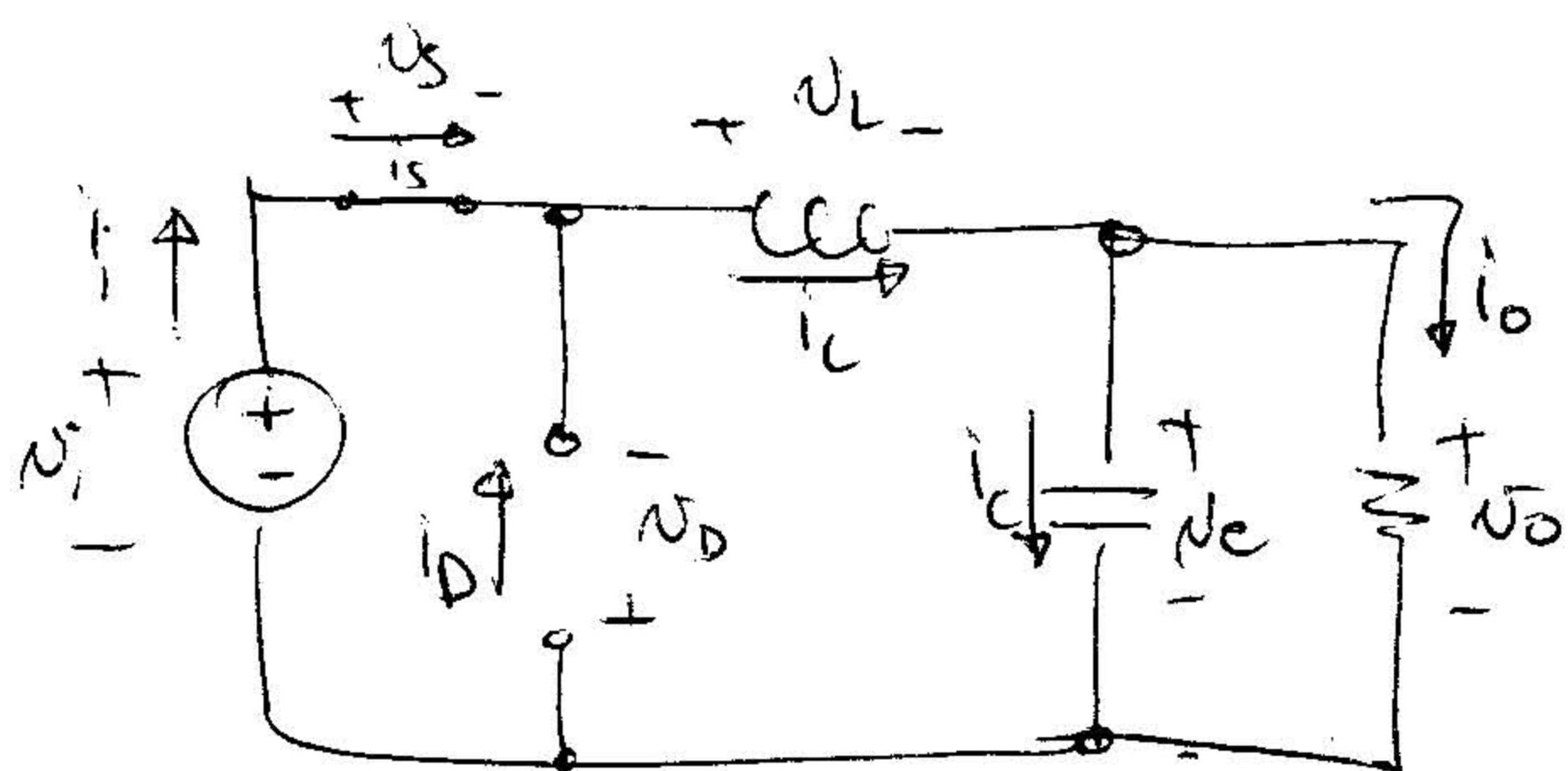
$I_o < I_{o,lim} \rightarrow \text{DCM}$ (to study)

$I_o > I_{o,lim} \rightarrow \text{CCM}$ (prev. studied)

2) Studying the three possible circuits



(A)

Voltages

$$N_i = V_i$$

$$N_0 \approx V_0$$

$$N_L = V_i - V_0$$

$$N_D = -V_i$$

$$N_S = 0$$

$$N_C \approx V_0$$

Currents

$$\dot{V}_L = 0$$

$$i_L = \frac{V_i - V_0}{L} t + \dot{I}_L$$

$$= \frac{V_i - V_0}{L} t$$

$$i_i = i_S = i_L$$

$$i_D = 0$$

$$i_o = I_0 = \frac{V_0}{R}$$

$$i_C = i_L - I_0$$

$$\dot{i}_L = -\frac{V_0}{L} t + \dot{I}_L$$

$$i_i = 0$$

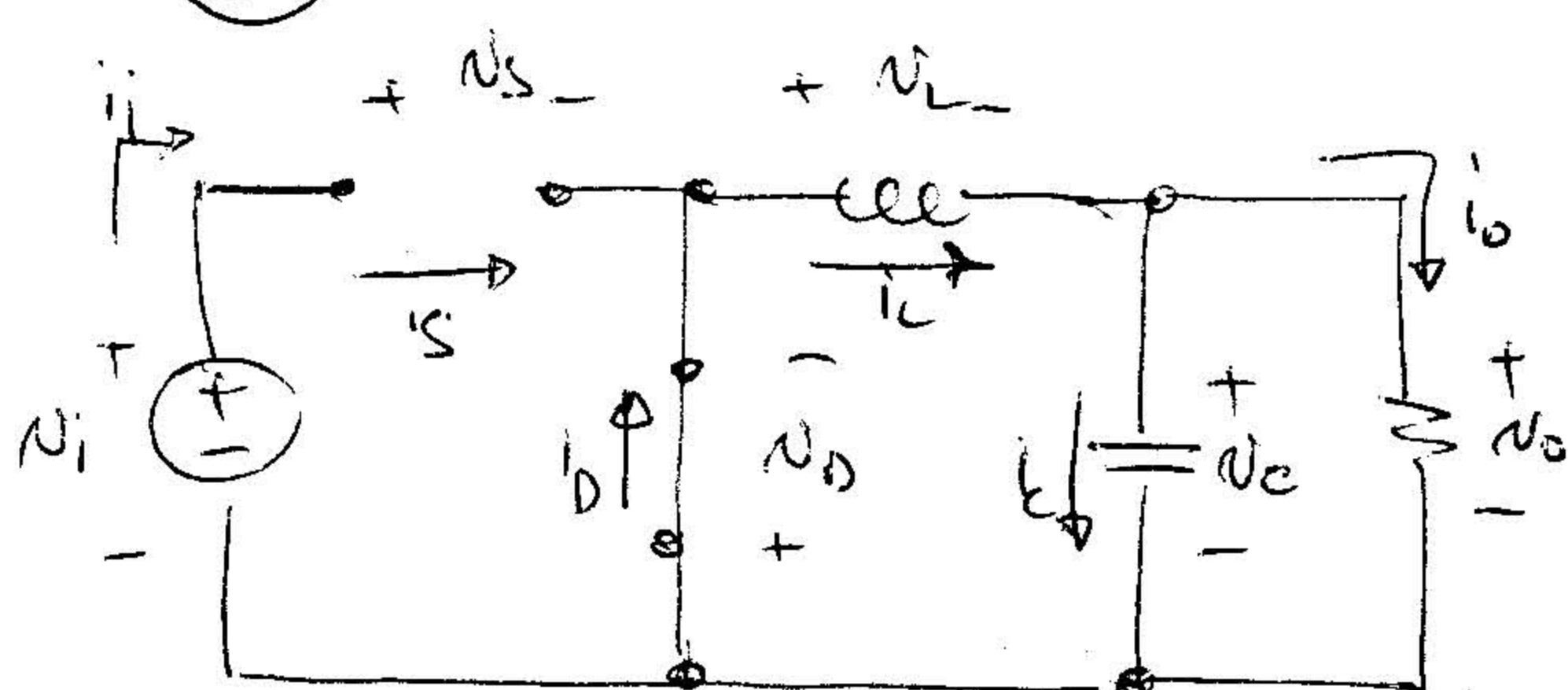
$$i_S = 0$$

$$i_D = i_L$$

$$i_o = I_0 = \frac{V_0}{R}$$

$$i_C = I_0 - i_L$$

(C)



$$N_i = V_i$$

$$N_0 \approx V_0$$

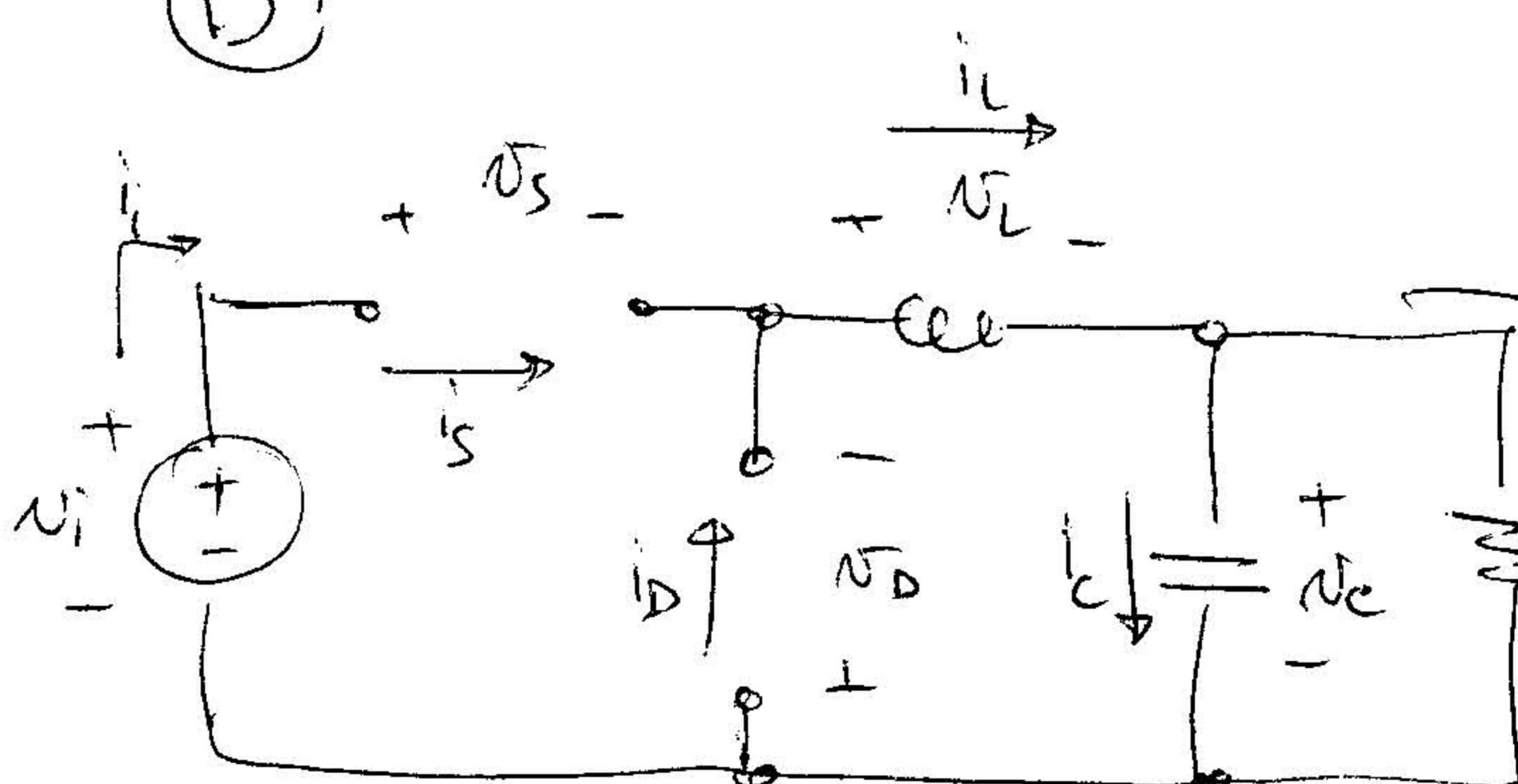
$$N_L = -V_0$$

$$N_D = 0$$

$$N_S = V_i$$

$$N_C \approx V_0$$

(D)



$$N_i = V_i$$

$$N_0 \approx V_0$$

~~$$N_L = L \frac{di}{dt}$$~~

$$N_L = L \frac{di}{dt} \neq 0$$

$$i_L = 0$$

$$i_i = 0$$

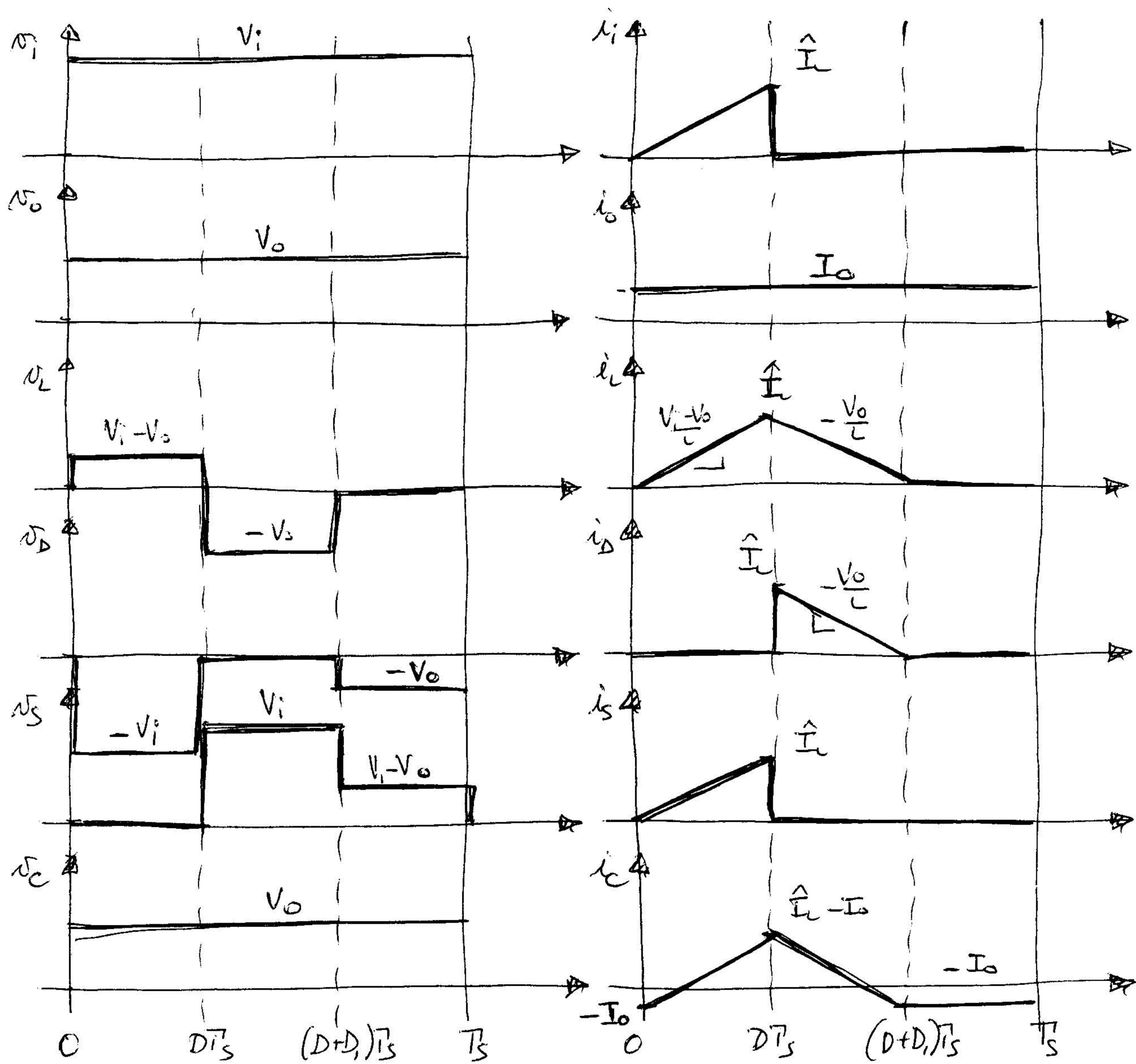
$$i_S = 0$$

$$i_D = 0$$

$$i_o = I_0 = \frac{V_0}{R}$$

$$i_C = -I_0$$

3) Voltage and current diagrams



4) Steady state conditions

Inductor $i_L(t_S) = \frac{1}{L} \int_0^{T_S} v_L(t) dt + i_L(0)$

$$\Rightarrow \boxed{\int_0^{T_S} v_L dt = 0}$$

still valid

$$\Rightarrow \langle v_L \rangle = \frac{1}{T_S} \int_0^{T_S} v_L dt = 0$$

$\boxed{\langle v_L \rangle = 0}$ still valid

$$\int_0^{T_S} v_i dt = 0$$

$$\int_0^{D\bar{T}_S} v_i dt + \int_{D\bar{T}_S}^{(D+D_1)\bar{T}_S} v_i dt + \int_{(D+D_1)\bar{T}_S}^{T_S} v_i dt = 0$$

$$\int_0^{D\bar{T}_S} (v_i - V_0) dt + \int_{D\bar{T}_S}^{(D+D_1)\bar{T}_S} (\cancel{V_0}) dt$$

$$(v_i - V_0) D\bar{T}_S = V_0 (D + D_1 - D) \bar{T}_S$$

$$(v_i - V_0) D = V_0 D_1$$

2 unknowns: D and D_1

capacitor

$$v_C(t) = \frac{1}{C} \int_0^{T_S} i_C dt + v_C(0)$$

$$\int_0^{T_S} i_C dt = 0$$

still valid

$$\Rightarrow \langle i_C \rangle = \frac{1}{T_S} \int_0^{T_S} i_C dt = 0$$

$$\langle i_C \rangle = 0$$

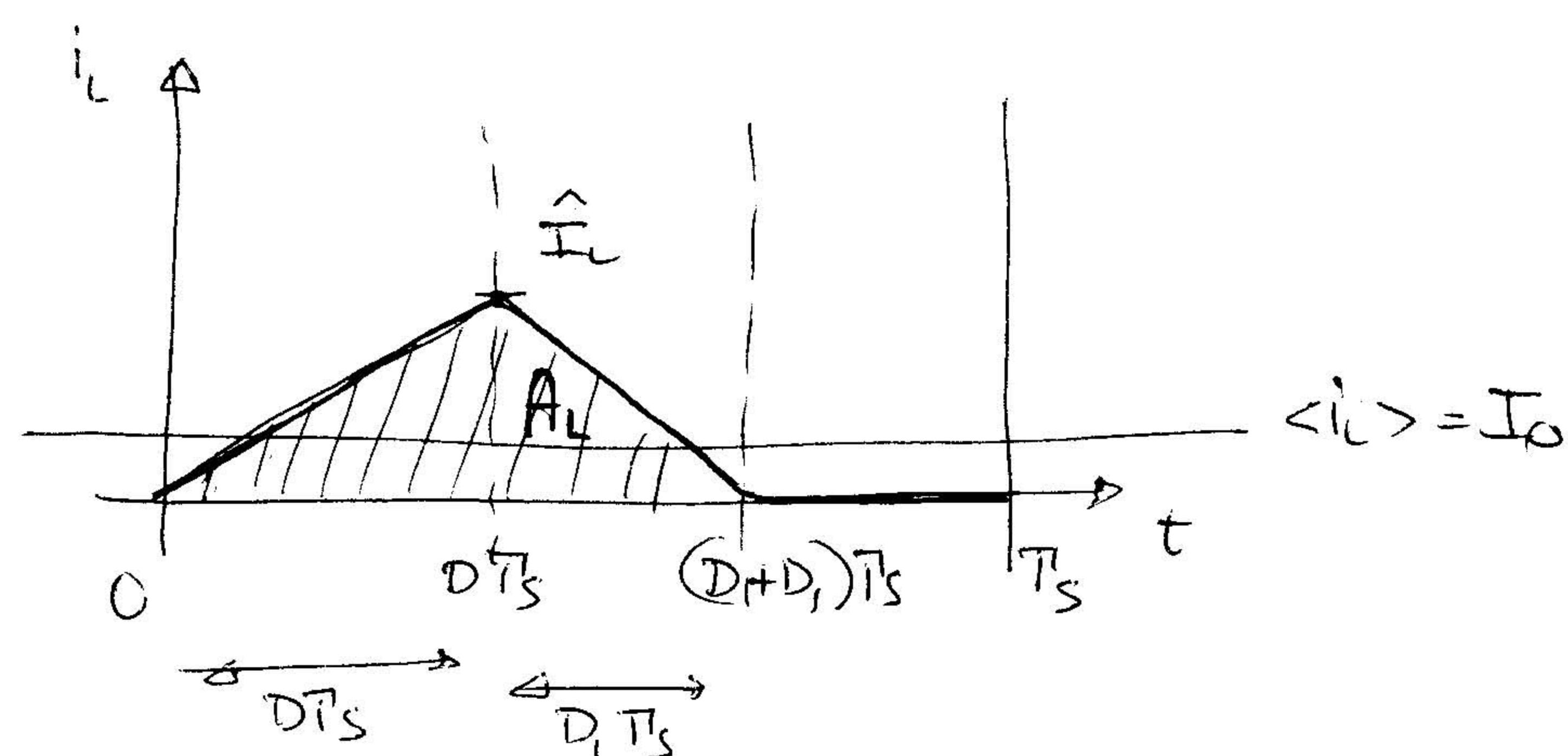
still valid

$$i_C = i_L - I_0$$

$$\cancel{\langle i_C \rangle} = \langle i_L \rangle - I_0$$

$$\langle i_L \rangle = I_0$$

still valid



$$\langle i_L \rangle = \frac{1}{T_S} \int_0^{T_S} i_L dt = \frac{1}{T_S} A_L$$

$$A_L = \frac{1}{2} (D + D_1) T_S \cdot \hat{I}_L$$

$$\langle i_L \rangle = \frac{1}{T_S} \frac{1}{2} (D + D_1) T_S \cdot \hat{I}_L = \frac{D + D_1}{2} \hat{I}_L$$

$$\langle i_L \rangle = I_0 \Rightarrow \boxed{\frac{D + D_1}{2} \hat{I}_L = I_0}$$

$$\hat{I}_L = \frac{V_i - V_o}{L} D T_S$$

$$\boxed{\frac{D + D_1}{2} \frac{V_i - V_o}{L} D T_S = I_0}$$

2 unknowns: D & D_1

5) Conversion ratio $M = \frac{V_o}{V_i}$

$$\left\{ \begin{array}{l} (V_i - V_o) D = V_o D_1 \\ \frac{D + D_1}{2} \frac{V_i - V_o}{L} D T_S = I_0 \end{array} \right.$$

$$(V_i - V_o) D = V_o D_1 \quad \frac{V_i - V_o}{V_o} \cdot D = D_1 \quad \boxed{D_1 = D \left(\frac{V_i}{V_o} - 1 \right)}$$

$$\frac{D + D \left(\frac{V_i}{V_o} - 1 \right)}{2} \cdot \frac{V_i - V_o}{L} D T_S = I_0$$

$$\frac{D \left(1 + \frac{V_i}{V_o} - 1 \right)}{2} \cdot \frac{V_i - V_o}{L} D T_S = I_0$$

$$\frac{D}{2} \cdot \frac{V_i}{V_o} \cdot (V_i - V_o) \cdot \frac{D T_S}{L} = I_0$$

$$\frac{V_i - V_o}{V_o} \cdot \frac{\frac{V_i I_S}{2L} \cdot D^2}{I_b} = I_o$$

$$\left(\frac{V_i}{V_o} - 1 \right) \frac{\frac{V_i I_S}{2L} \cdot D^2}{I_b} = I_o$$

$$\left(\frac{V_i}{V_o} - 1 \right) I_b \cdot D^2 = I_o$$

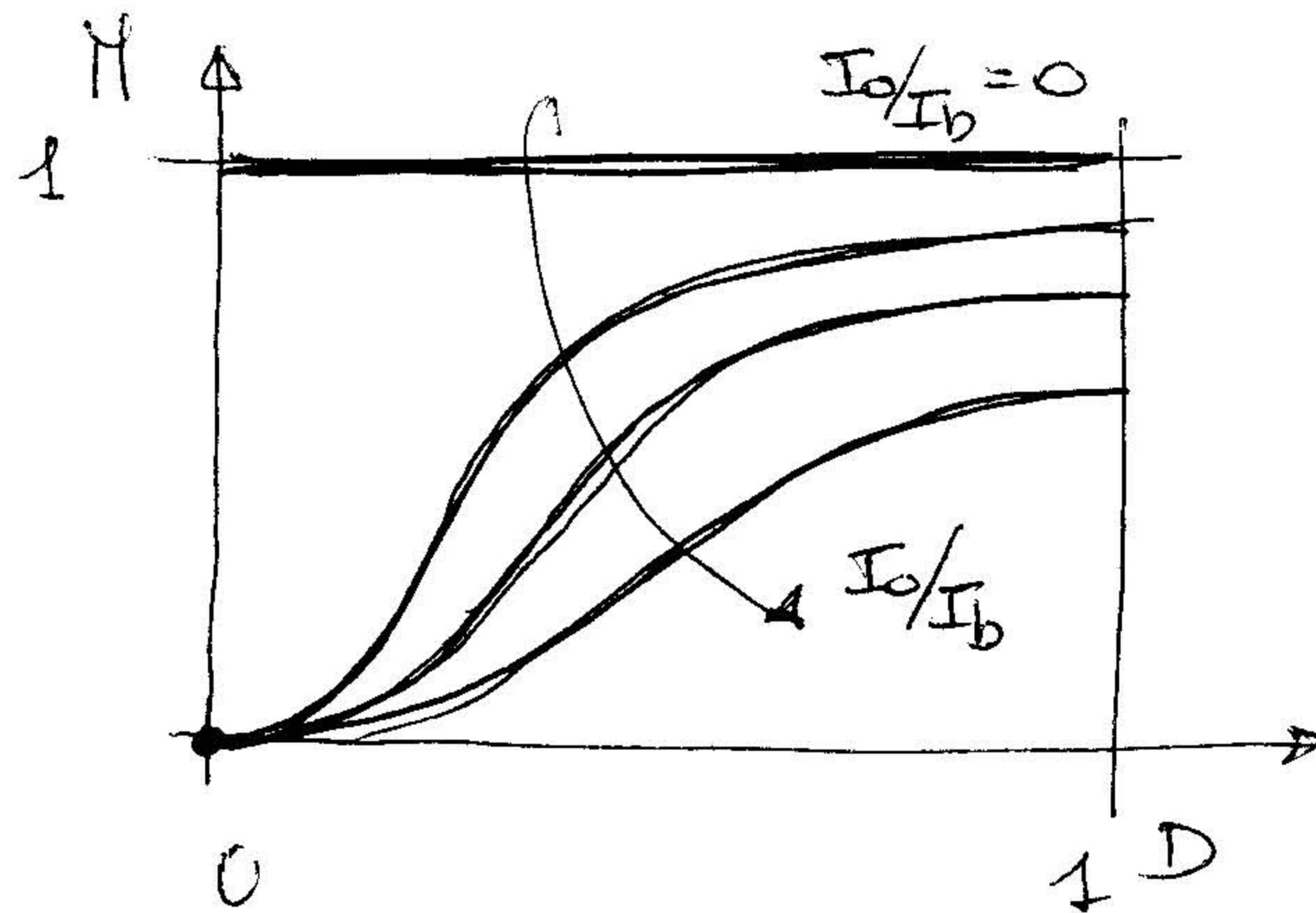
$$\left(\frac{1}{H} - 1 \right) I_b \cdot D^2 = I_o$$

$$\frac{1}{H} - 1 = \frac{I_o}{I_b} \cdot \frac{1}{D^2}$$

$$\frac{1}{H} = \frac{I_o}{I_b D^2} + 1 = \frac{I_o + I_b D^2}{I_b D^2}$$

$$H = \frac{I_b D^2}{I_o + I_b D^2} = \frac{D^2}{D^2 + \frac{I_o}{I_b}}$$

$$H = \frac{D^2}{D^2 + \frac{I_o}{I_b}}$$



$$(V_i - V_o) D = V_o D_1$$

$$D_1 = \frac{V_i - V_o}{V_o} D = \left(\frac{V_i}{V_o} - 1 \right) D = \left(\frac{1}{H} - 1 \right) D$$

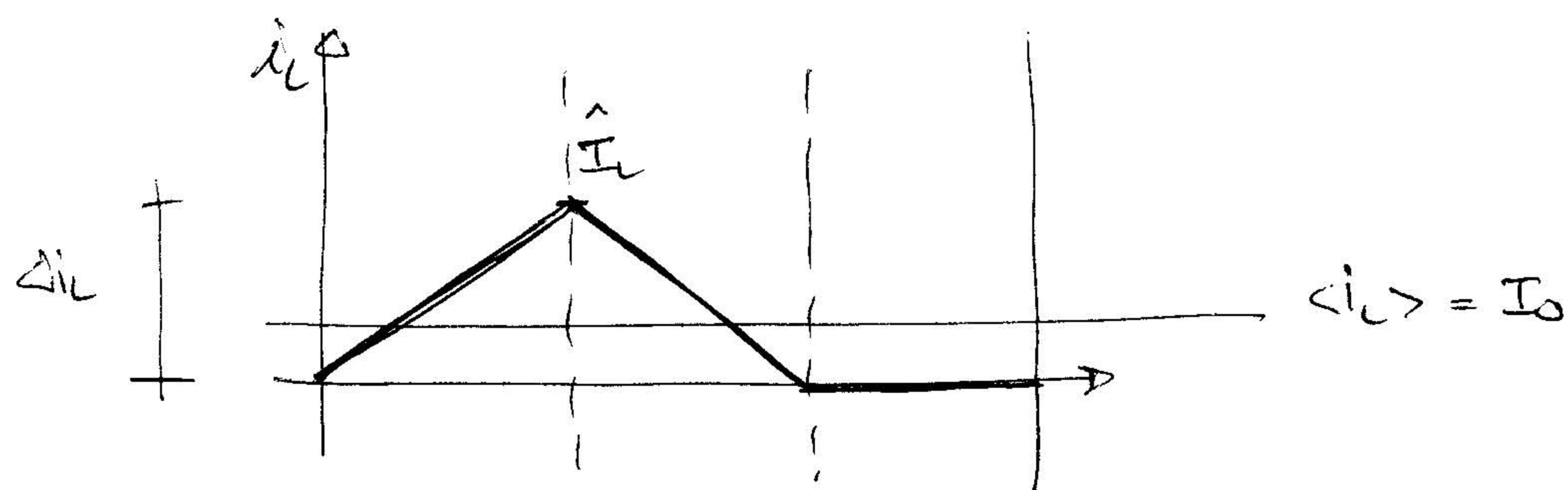
$$D_1 = \left(\frac{1}{M} - 1 \right) D = \left(\frac{1-M}{M} \right) D$$

$$\frac{\left(1 - \frac{D^2}{D^2 + I_0/I_b} \right)}{\frac{D^2}{D^2 + I_0/I_b}} \cdot D = \frac{\frac{D^2 + I_0/I_b - D^2}{D^2}}{D^2} \cdot D$$

$$\frac{I_0/I_b}{D}$$

$$D_1 = \frac{1}{D} \frac{I_0}{I_b}$$

c) Inductor current ripple and maximum current

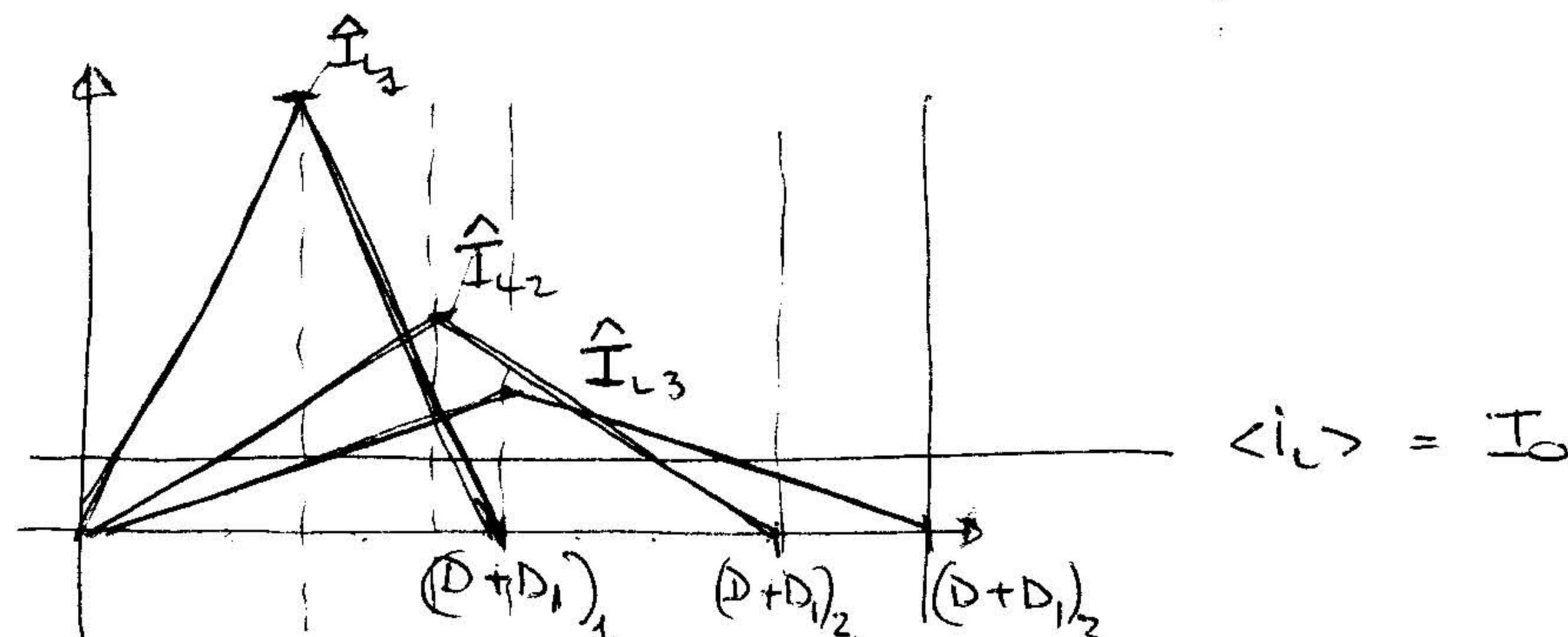


$$\langle i_L \rangle = \frac{1}{2} \hat{i}_L (D + D_1) T_S$$

$$= \frac{\hat{i}_L}{2} (D + D_1)$$

$$\langle i_L \rangle = I_0 \Rightarrow \frac{\hat{i}_L}{2} (D + D_1) = I_0$$

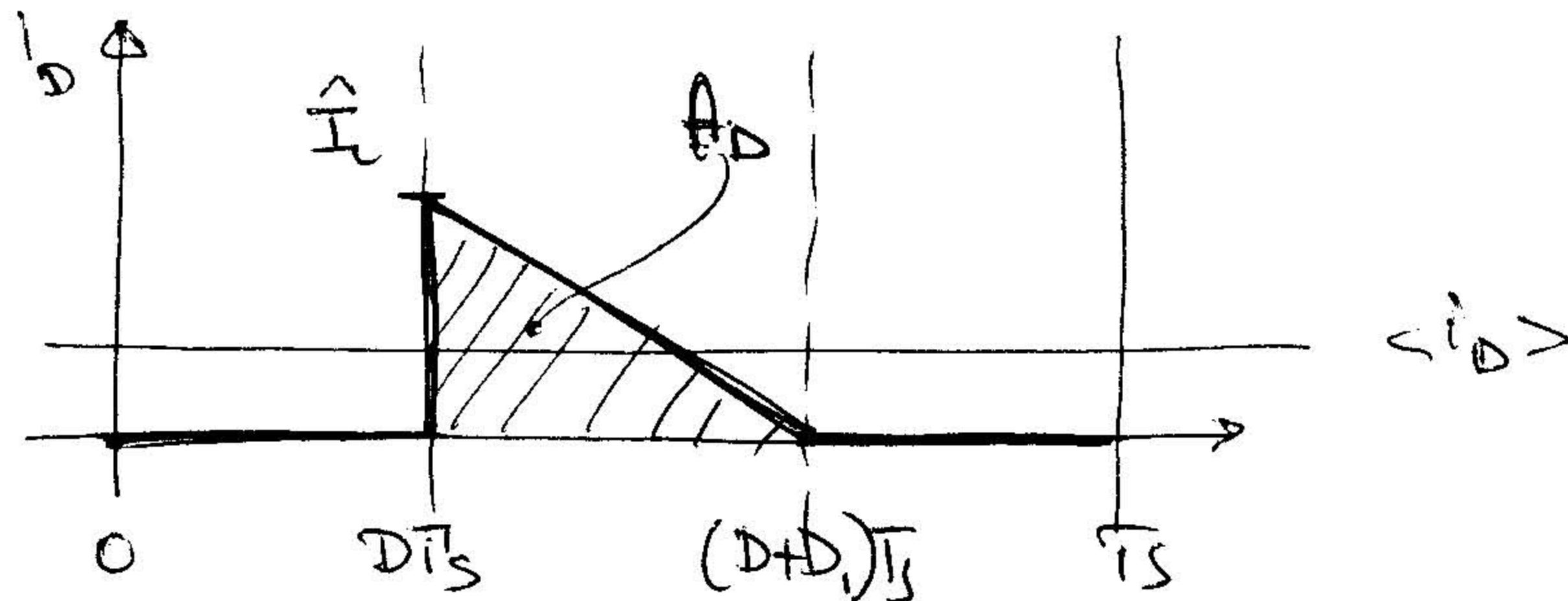
$$\Delta i_L = \hat{i}_L = 2 I_0 \frac{1}{D + D_1}$$



$$(D+D_s) \rightarrow 1 \quad \hat{I}_L = \Delta i_L \downarrow$$

$$(D+D_s) \rightarrow 0 \quad \hat{I}_L = \Delta i_L \uparrow$$

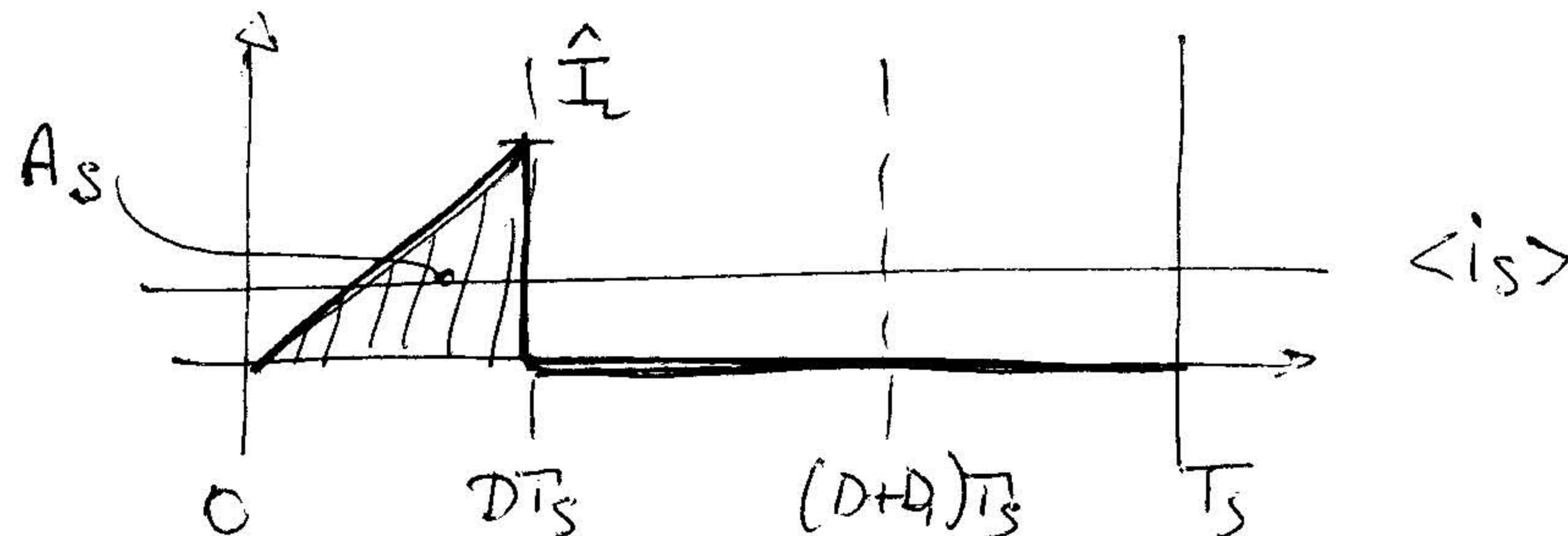
Average current in the diode



$$\begin{aligned} \langle i_D \rangle &= \frac{1}{T_S} \int_0^{T_S} i_D dt = \frac{1}{T_S} A_D = \frac{1}{T_S} \cdot \frac{1}{2} \cdot \hat{I}_L \cdot D_S T_S = \frac{\hat{I}_L}{2} \cdot D_S \\ &= 2 I_0 \frac{1}{D+D_s} \frac{1}{2} \cdot D_S = \frac{D_S}{D+D_s} I_0 \end{aligned}$$

$$\boxed{\langle i_D \rangle = \frac{D_S}{D+D_s} I_0}$$

Average current in the switch

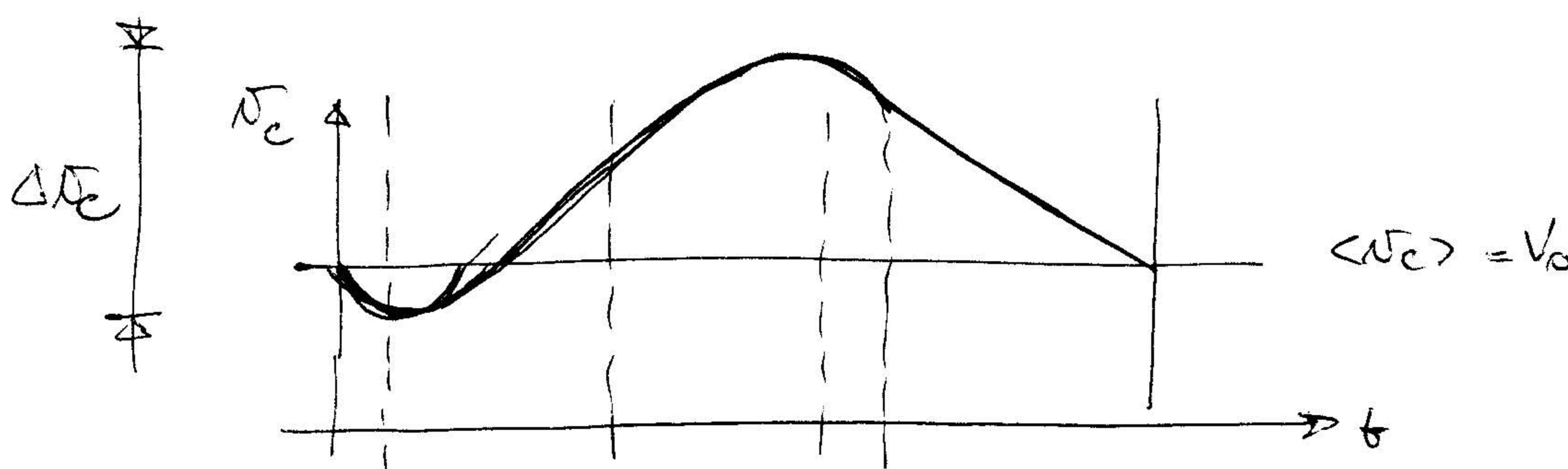
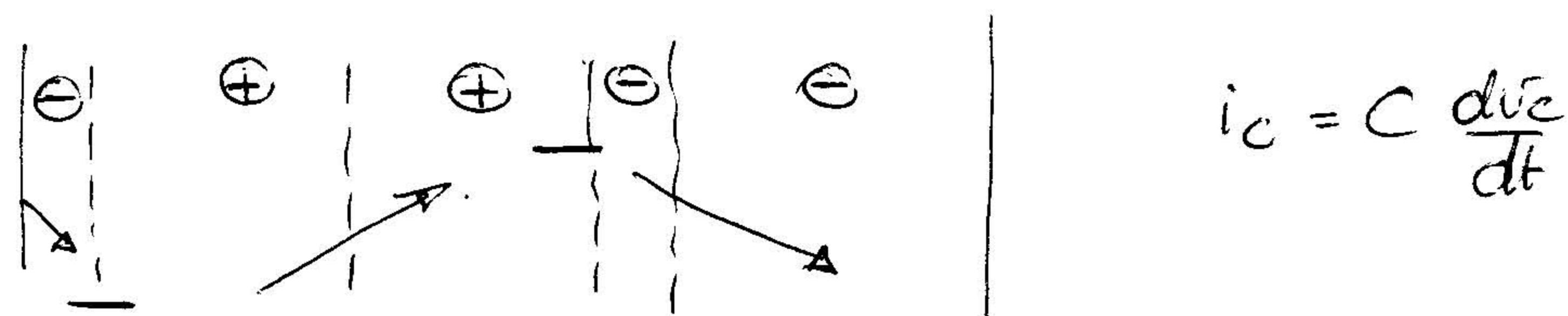
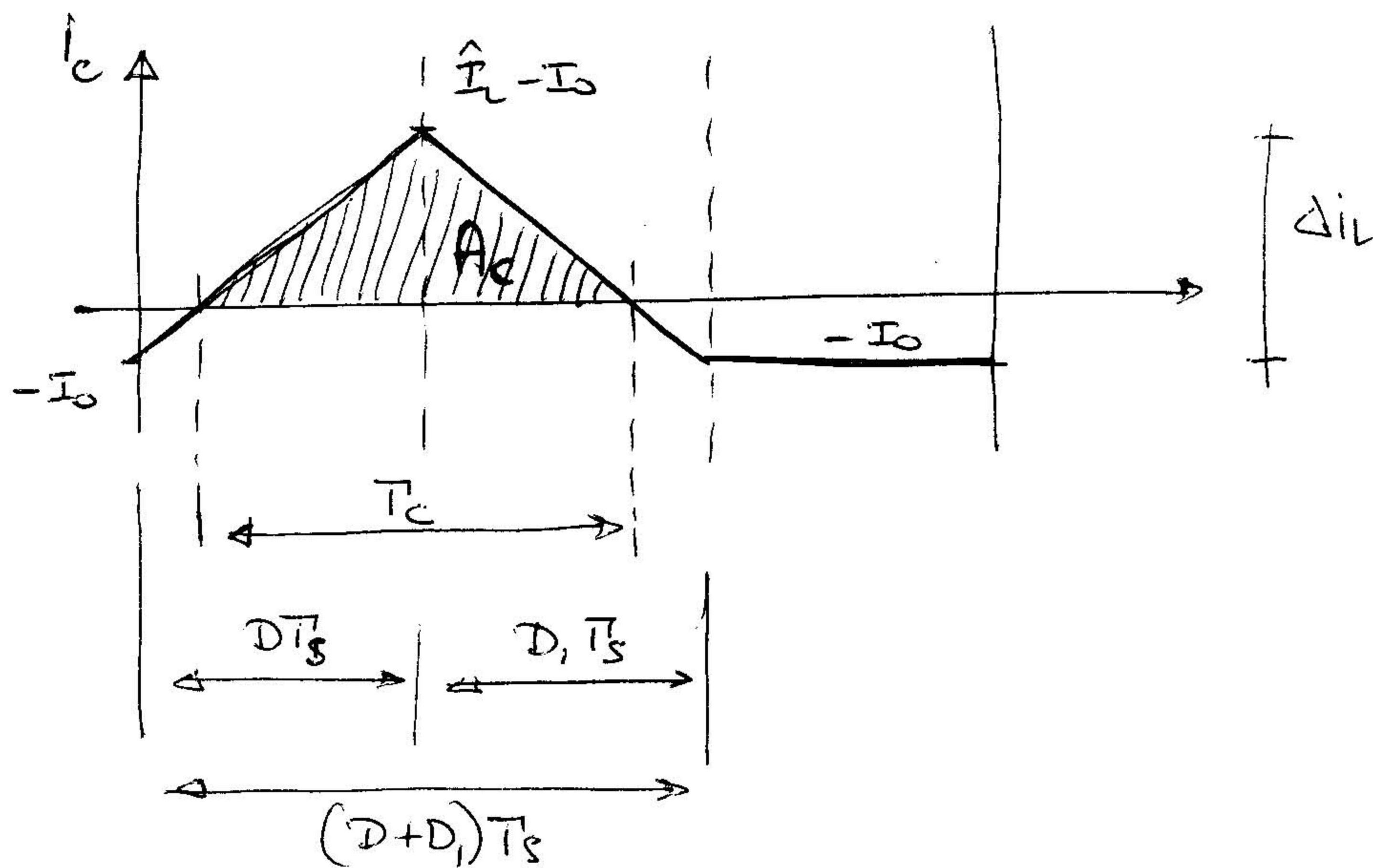


$$\begin{aligned} \langle i_S \rangle &= \frac{1}{T_S} \int_0^{T_S} i_S dt = \frac{1}{T_S} A_S = \frac{1}{T_S} \cdot \frac{1}{2} \cdot \hat{I}_L \cdot D T_S = \frac{\hat{I}_L}{2} \cdot D \\ &= 2 I_0 \frac{1}{D+D_s} \frac{1}{2} \cdot D = \frac{D}{D+D_s} I_0 \end{aligned}$$

$$\boxed{\langle i_S \rangle = \langle i \rangle = \frac{D}{D+D_s} I_0}$$

8) Maximum voltage

$$|\hat{v}_S| = V_i \quad |\hat{v}_D| = V_i$$

9) Output voltage ripple

$$\Delta v_C = \frac{\Delta q_C}{C} = \frac{A_C}{C}$$

$$A_C = \frac{1}{2} T_C (\Delta i_L - I_0)$$

$$\frac{T_C}{(D + D_1)T_S} = \frac{\Delta i_L - I_0}{\Delta i_L} \rightarrow \boxed{T_C = \frac{\Delta i_L - I_0}{\Delta i_L} (D + D_1) T_S}$$

$$(V_1 - V_0) D = V_0 D_1$$

$$D_1 = \frac{V_1 - V_0}{V_0} D = \left(\frac{V_1}{V_0} - 1\right) D$$

$$D + D_1 = D + \left(\frac{V_1}{V_0} - 1\right) D = \frac{V_1}{V_0} D = \frac{1}{H} D$$

$$\boxed{D + D_1 = \frac{1}{H} D}$$

$$\begin{aligned} A_C &= \frac{1}{2} \left[\frac{\Delta i_L - I_0}{\Delta i_L} (D + D_1) T_S \right] (\Delta i_L - I_0) \\ &= \frac{1}{2} \frac{(\Delta i_L - I_0)^2}{\Delta i_L} \cdot \frac{1}{H} D \cdot T_S \end{aligned}$$

$$\Delta N_C = \frac{A_C}{C} = \frac{1}{2C} \frac{(\Delta i_L - I_0)^2}{\Delta i_L} \cdot \frac{1}{H} D \cdot T_S$$

$$\Delta i_L = \hat{I}_L = 2 I_0 \frac{1}{D + D_1} = 2 I_0 \frac{H}{D}$$

$$\Delta N_C = \frac{1}{2C} \frac{\left(\frac{2H}{D} I_0 - I_0\right)^2}{\frac{2H}{D} I_0} \cdot \frac{1}{H} D T_S$$

$$\downarrow \frac{1}{2C} \frac{\left(\frac{2H}{D} - 1\right)^2 I_0}{\frac{2(H)}{D} I_0} T_S$$

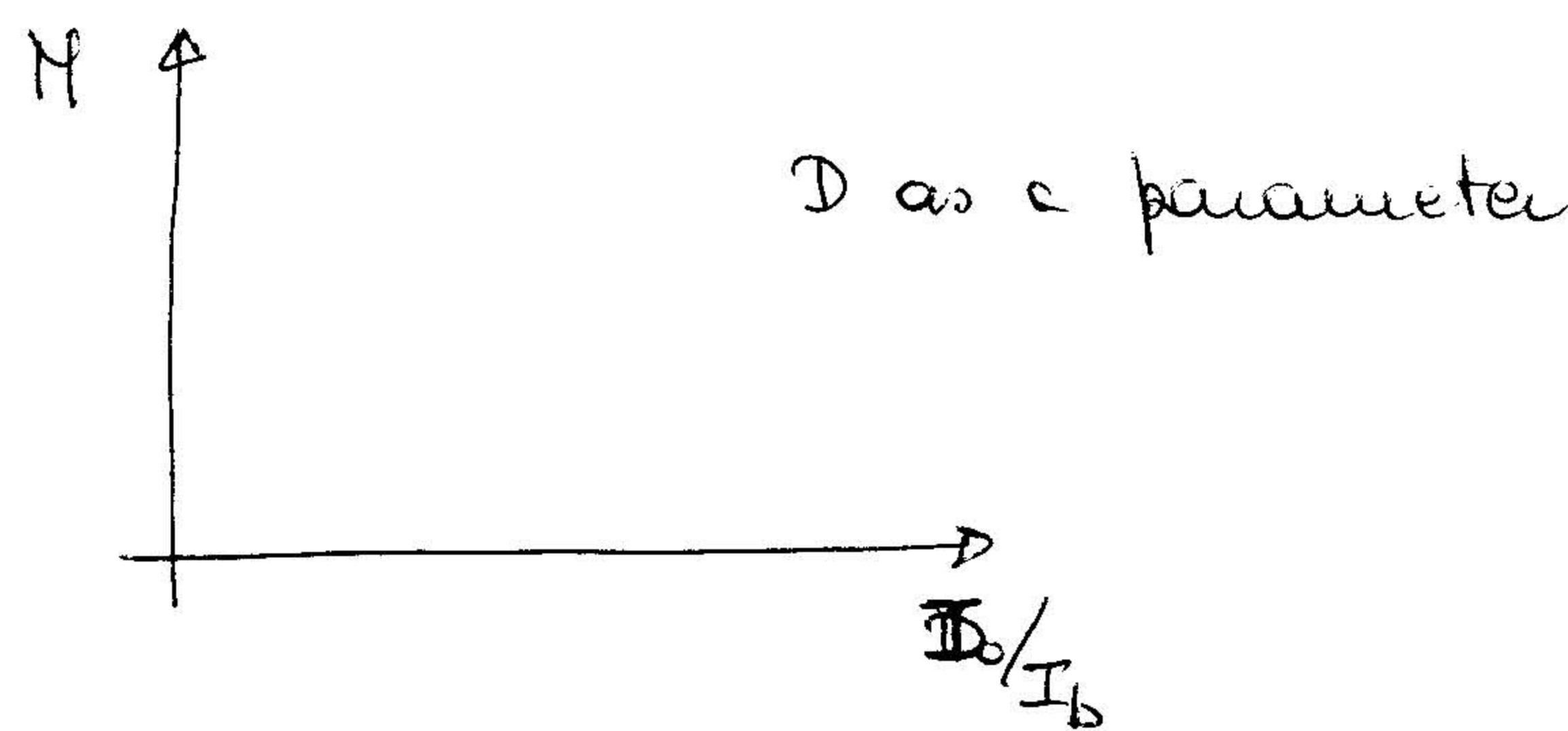
$$\downarrow \frac{1}{C} \frac{\left(\frac{2H}{D} - 1\right)^2 I_0}{\left(\frac{2H}{D}\right)^2} T_S = \frac{1}{C} \left(\frac{2H}{D} - 1\right)^2 I_0 T_S$$

$$\downarrow \frac{1}{C} \left(1 - \frac{D}{2H}\right)^2 I_0 T_S$$

$$\boxed{\Delta N_C = \frac{T_S \cdot I_0}{C} \left(1 - \frac{D}{2H}\right)^2}$$

DCM AND CCM TOGETHER

① Output characteristic



1. CCM

if $I_o > I_{o\text{lim}} \Rightarrow \text{CCM}$

$$M = D \quad \forall I_o/I_b$$

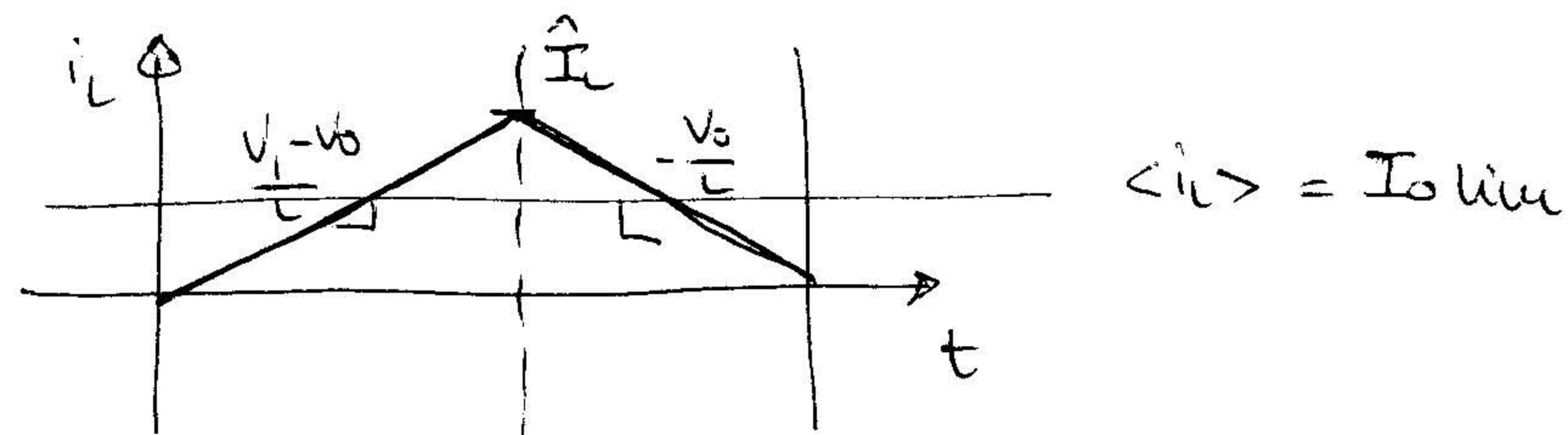
2. DCM

if $I_o < I_{o\text{lim}} \Rightarrow \text{DCM}$

$$M = \frac{D^2}{D^2 + I_o/I_b}$$

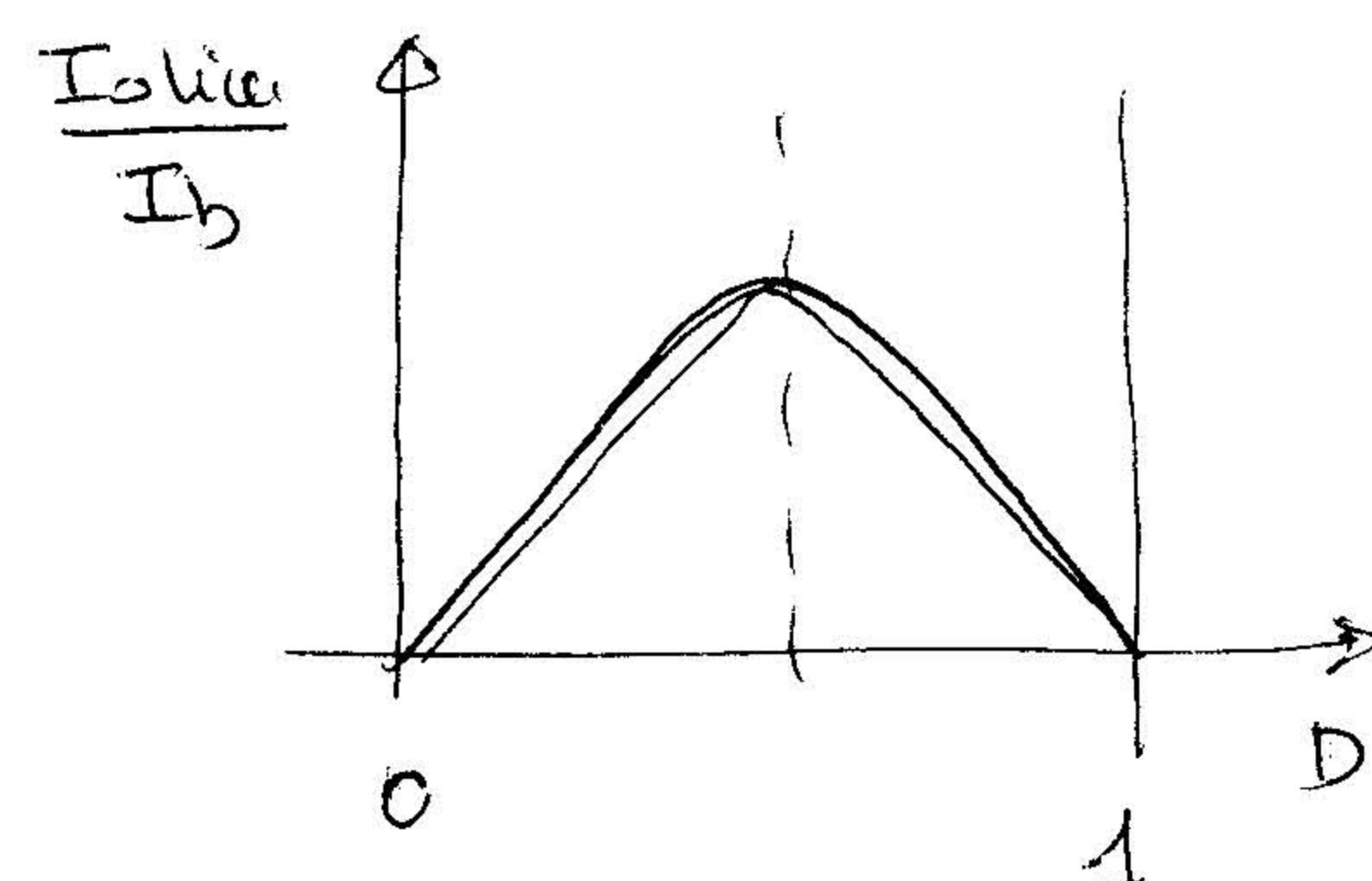
Border between CCM and DCM

$$I_o = I_{o\text{lim}}$$



$$I_{o\text{lim}} = \frac{\Delta i_L}{2} = \frac{\hat{I}}{2} = \frac{V_i - V_o}{2L} \cdot D \bar{t}_S = \frac{V_i (1-D)}{2L} \cdot D \bar{t}_S$$

$$= \frac{V_i \bar{t}_S}{2L} (1-D) D = I_b (1-D) D$$



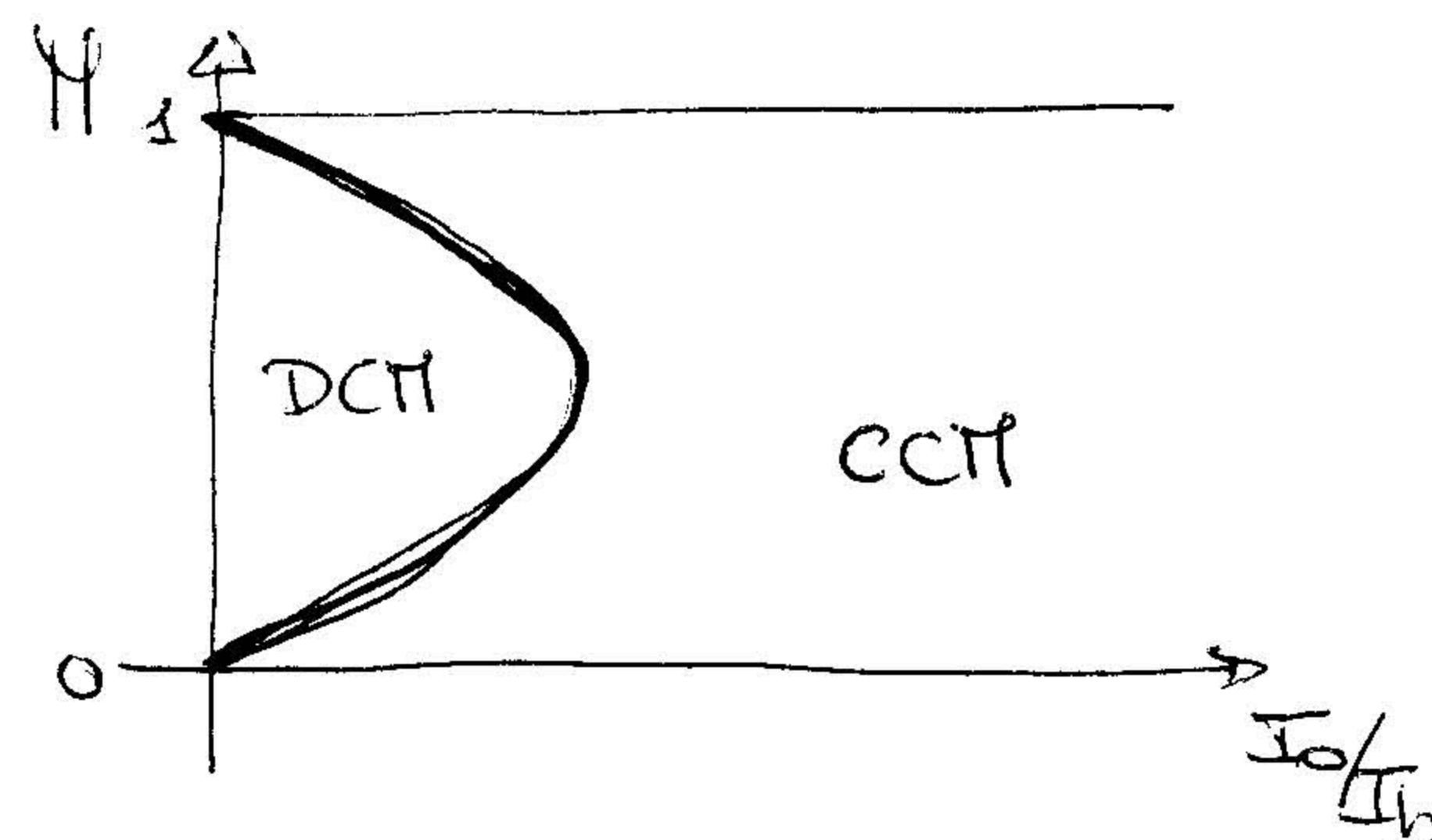
$$I_o = I_{o\text{lim}}$$

$$I_o = I_b (1-D) D$$

$$\frac{I_o}{I_b} = (1-D) D$$

At the border $H=D$ is still valid:

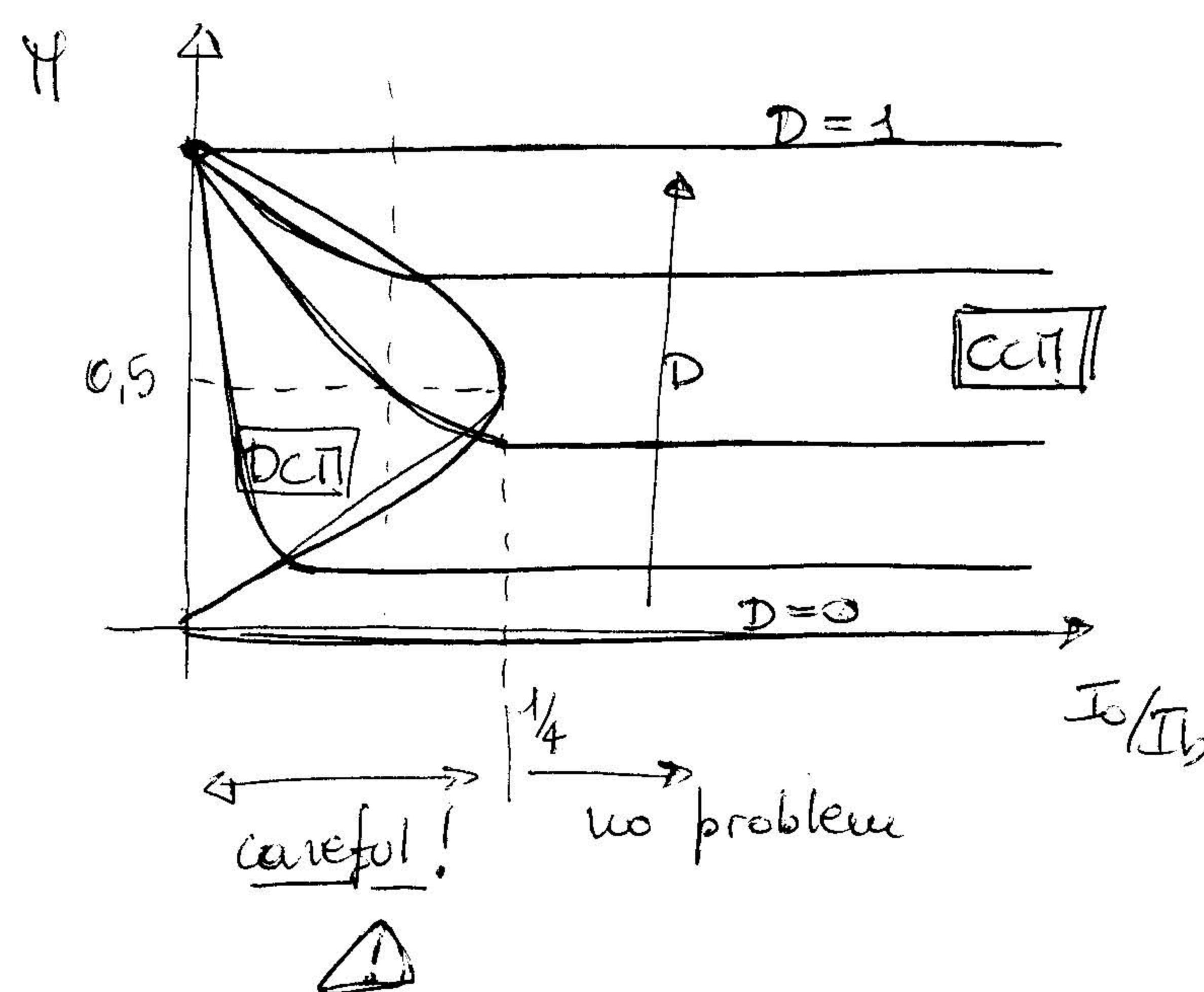
$$\hookrightarrow \frac{I_o}{I_b} = (1-H) H$$



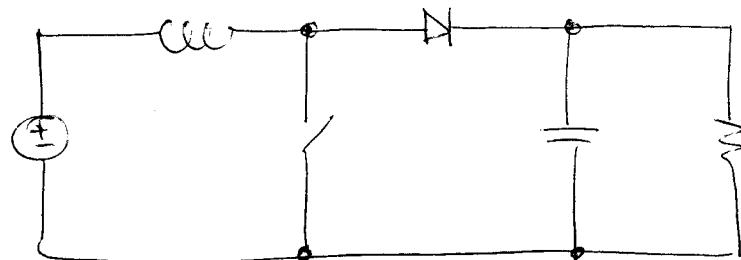
$$\text{CCII} \Leftrightarrow I_b > I_{o\text{lim}} \Leftrightarrow I_o > I_b (1-D) D$$

$$I_o > I_b (1-\pi) \pi$$

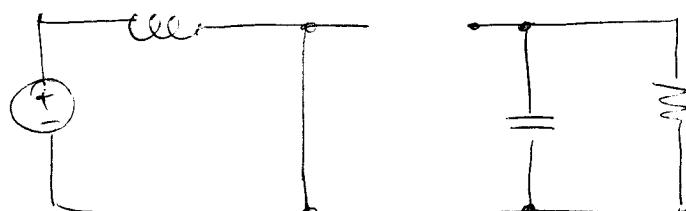
$$\frac{I_o}{I_b} > (1-\pi) \pi$$



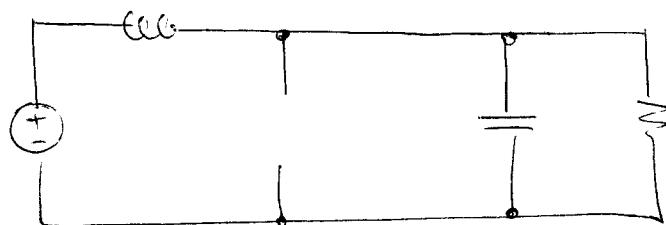
(1)

1) General circuit2) Study of the three possible circuits

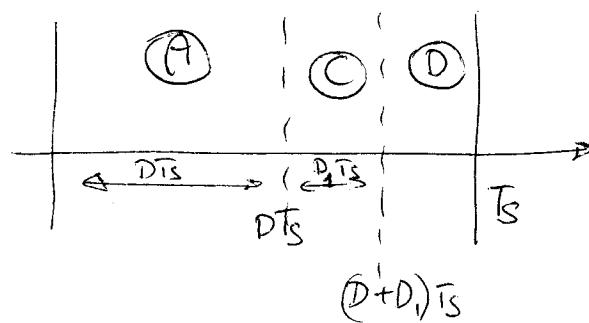
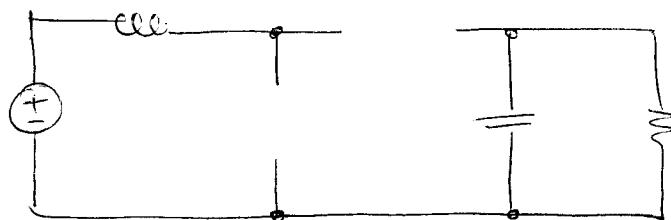
(A)



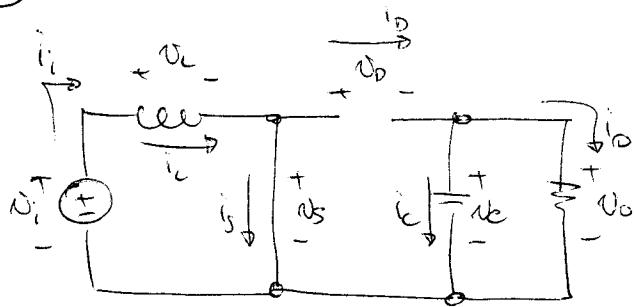
(C)



(D)



(A)

Voltages

$$V_i = V_i$$

$$N_o \approx V_o$$

$$N_L = V_i$$

$$N_D = -V_o$$

$$N_S = 0$$

$$N_C = V_o$$

Circuits

$$\dot{I}_L = 0$$

$$\dot{I}_C = \frac{V_i}{L} t + I_0$$

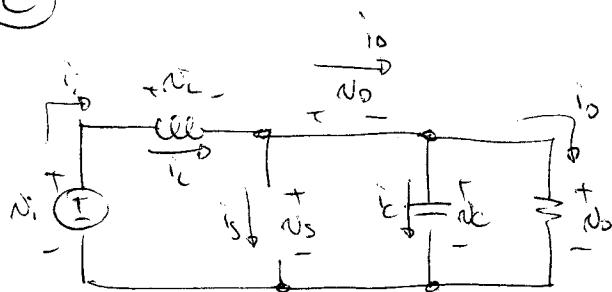
$$i_L = i_C = i_S$$

$$i_0 = 0$$

$$i_o = I_0 = \frac{V_o}{R}$$

$$i_C = -I_0$$

(C)



$$V_i = V_i$$

$$N_o \approx V_o$$

$$N_L = -(V_o - V_i)$$

$$N_D = 0$$

$$N_S = V_o$$

$$N_C = V_o$$

$$i_L = -\frac{V_o - V_i}{L} t + I_0$$

$$i_L = i_C$$

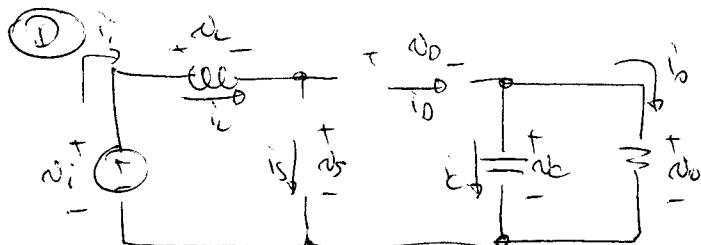
$$i_S = 0$$

$$i_0 = i_L$$

$$i_o = I_0 = \frac{V_o}{R}$$

$$i_C = i_L - I_0$$

(D)



$$V_i = V_i$$

$$N_o \approx V_o$$

$$N_L = L \frac{di_L}{dt} = 0$$

$$N_D = -(V_o - V_i)$$

$$N_S = V_i$$

$$N_C = V_o$$

$$i_L = 0$$

$$i_L = 0$$

$$i_S = 0$$

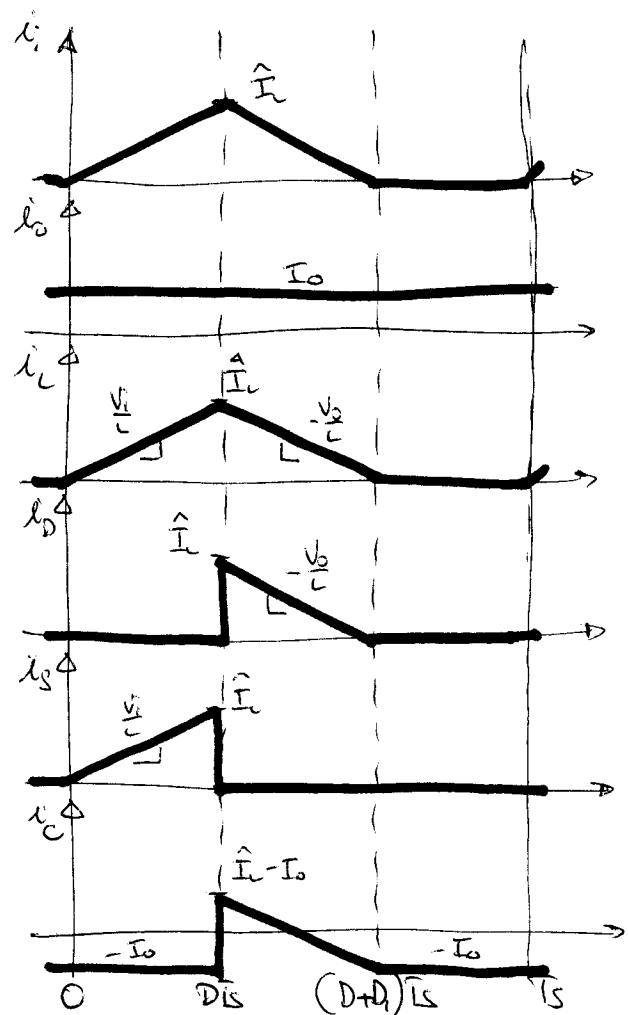
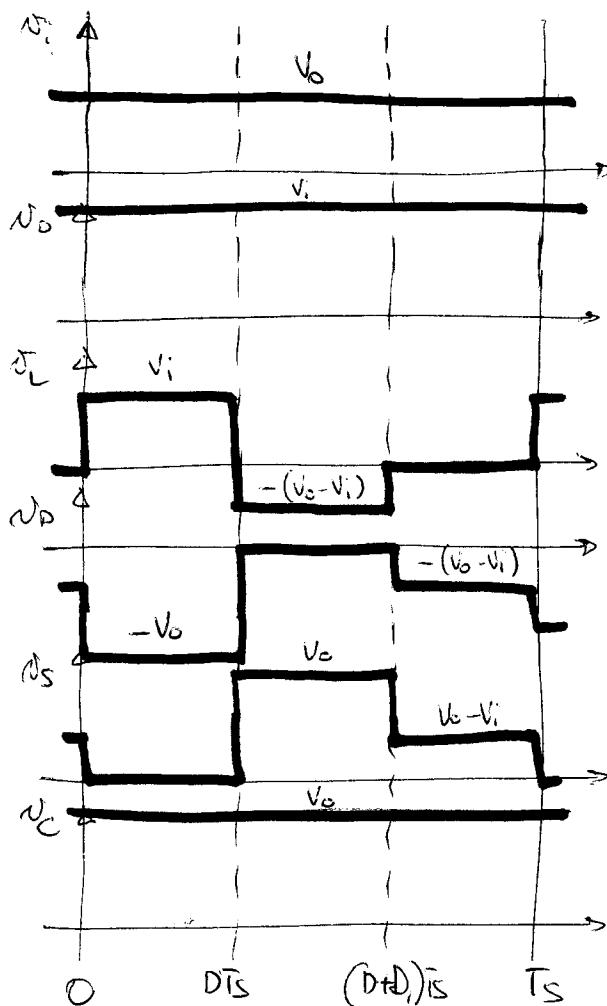
$$i_0 = 0$$

$$i_o = I_0 = \frac{V_o}{R}$$

$$i_C = -I_0$$

(3)

3) Voltage and current diagrams



4) Steady state conditions

inductor $i_L(\bar{T}_S) = \frac{1}{\hat{L}} \int_0^{\bar{T}_S} v_L(t) dt + i_L(0)$

$$\Rightarrow \boxed{\int_0^{\bar{T}_S} i_L dt = 0} \quad \text{still valid}$$

$$\Rightarrow \langle i_L \rangle = \frac{1}{\bar{T}_S} \int_0^{\bar{T}_S} i_L dt = 0 \quad \boxed{\langle i_L \rangle = 0} \quad \text{still valid}$$

4

$$\int_0^T \Delta_i dt = 0$$

$$\int_0^{D\bar{T}_S} V_L dt + \int_{D\bar{T}_S}^{(D+D_1)\bar{T}_S} V_L dt + \cancel{\int_{D\bar{T}_S}^{T_S} V_L dt} = 0$$

$$\int_0^{D\bar{T}_S} V_i dt = + \int_{D\bar{T}_S}^{(D+D_1)\bar{T}_S} + (V_0 - V_i) dt$$

$$V_i D \bar{T}_S = (V_0 - V_i)(D + D_1 - D) \bar{T}_S$$

$$V_i D = (V_0 - V_i) D_1 \quad \boxed{2 \text{ unknowns. } D \text{ and } D_1}$$

capacitor

$$V_C(\bar{T}_S) = \frac{1}{C} \int_0^{\bar{T}_S} i_C dt + \Delta_C(t)$$

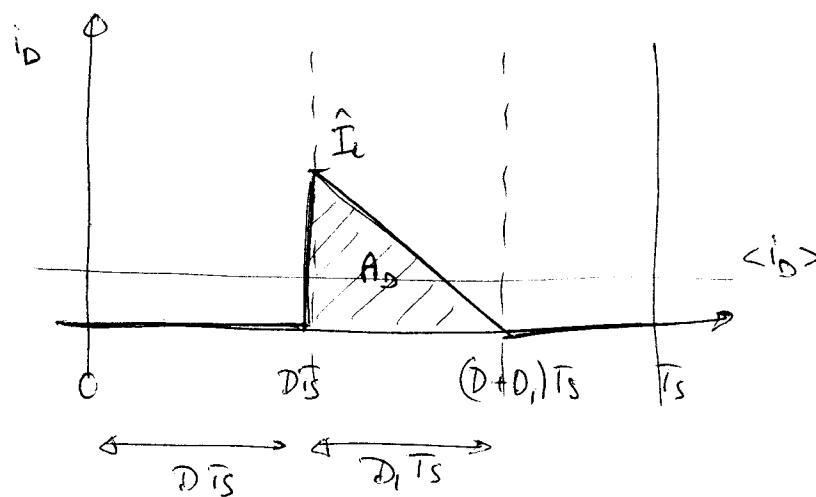
$$\Rightarrow \boxed{\int_0^{\bar{T}_S} i_C dt = 0} \quad \text{still valid}$$

$$\Rightarrow \langle i_C \rangle = \frac{1}{\bar{T}_S} \int_0^{\bar{T}_S} i_C dt = 0 \quad \boxed{\langle i_C \rangle = 0} \quad \text{still valid}$$

$$i_D = i_C + I_0$$

$$\langle i_D \rangle = \cancel{\langle i_C \rangle} + I_0$$

$$\boxed{\langle i_D \rangle = I_0} \quad \text{still valid}$$



(5)

$$\langle i_D \rangle = \frac{l}{T_S} \int_0^{T_S} i_D dt = \frac{l}{T_S} A_D$$

$$A_D = \frac{l}{2} D_s T_S \hat{I}_L$$

$$\langle i_D \rangle = \frac{l}{T_S} \frac{l}{2} D_s T_S \hat{I}_L = \frac{D_s}{2} \hat{I}_L$$

$$\langle i_D \rangle = I_o \Rightarrow \frac{D_s}{2} \hat{I}_L = I_o$$

$$\hat{I}_L = \frac{V_i}{L} D T_S$$

$$\boxed{\frac{D_s}{2} \frac{V_i}{L} D T_S = I_o}$$

2 unknowns: D & D_s

5) Conversion ratio $\eta = \frac{V_o}{V_i}$

$$\left\{ \begin{array}{l} V_i D = (V_o - V_i) D_s \\ \frac{D_s}{2} \frac{V_i}{L} D T_S = I_o \end{array} \right.$$

$$V_i D = (V_o - V_i) D_s$$

$$\boxed{D_s = \frac{V_i}{V_o - V_i} D}$$

$$\frac{V_i}{V_o - V_i} \frac{D}{2} \frac{V_i}{L} D T_S = I_o$$

$$\frac{V_i}{V_o - V_i} D^2 \frac{V_i T_S}{2L} = I_o$$

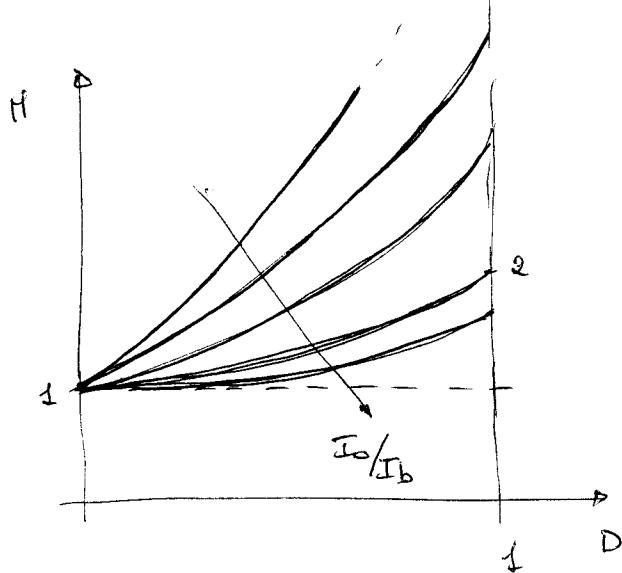
$$\frac{V_i}{V_o - V_i} D^2 = \frac{I_o}{I_b}$$

(6)

$$\frac{D^2}{\frac{I_0}{I_b}} = \frac{V_o}{V_i} - 1$$

$$H = \frac{V_o}{V_i} = 1 + \frac{D^2}{\frac{I_0}{I_b}}$$

$$H = 1 + \frac{D^2}{\frac{I_0}{I_b}}$$



$$V_i D = (V_o - V_i) D_1$$

$$D_1 = \frac{V_i}{V_o - V_i} D = \frac{D}{\frac{V_o - V_i}{V_i}} = \frac{D}{\frac{1}{I_0/I_b} - 1}$$

$$\frac{D}{1 + \frac{D}{\frac{I_0}{I_b}}} = \frac{1}{D} \frac{I_0}{I_b}$$

$$D_1 = \frac{1}{D} \frac{I_0}{I_b}$$

(7)

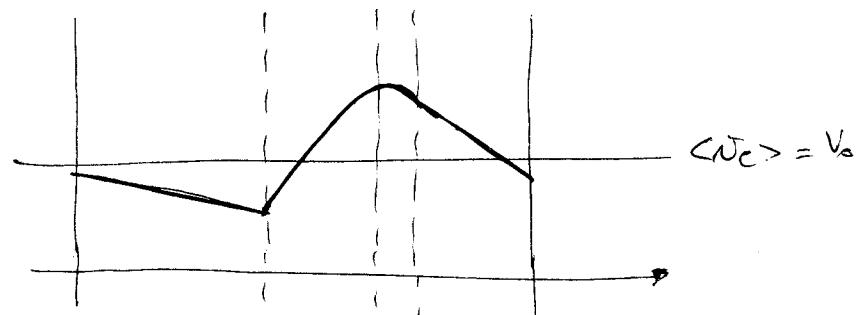
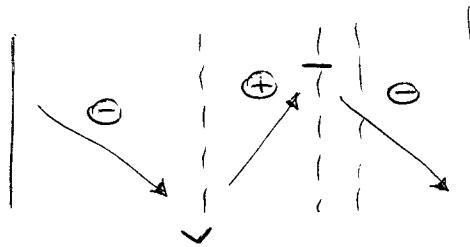
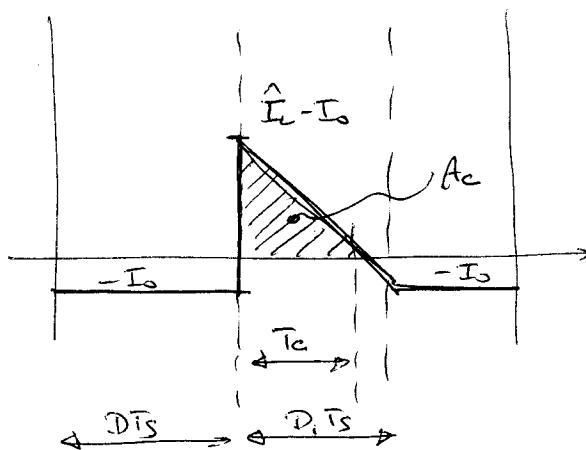
6) Inductor current ripple and maximum current
(omitted)

7) Average and maximum current
(omitted)

8) Maximum voltage

$$|\hat{v}_s| = V_0 \quad |\hat{v}_o| = V_0 \quad |\hat{v}_c| = V_0$$

9) Output voltage ripple



$$\Delta v_c = \frac{\Delta q_c}{C} = \frac{A_c}{C}$$

$$A_c = \frac{1}{2} T_C (\hat{I}_L - I_o)$$

$$\frac{T_C}{D_1 T_S} = \frac{\hat{I}_L - I_0}{\hat{I}_L}$$

$$\hookrightarrow T_C = \frac{\hat{I}_L - I_0}{\hat{I}_L} \cdot D_1 \cdot T_S$$

$$\hat{I}_L = 2 \frac{I_0}{D_1}$$

$$\hookrightarrow T_C = \frac{2 \frac{I_0}{D_1} - I_0}{2 \frac{I_0}{D_1}} \cdot D_1 \cdot T_S = \frac{\frac{2-D_1}{D_1}}{\frac{2}{D_1}} \cdot D_1 \cdot T_S$$

$$\boxed{T_C = \frac{1}{2} (2-D_1) D_1 \cdot T_S}$$

$$\begin{aligned} A_C &= \frac{1}{2} T_C (\hat{I}_L - I_0) = \frac{1}{2} \left[\frac{1}{2} (2-D_1) D_1 T_S \right] \left[\frac{2 I_0}{D_1} - I_0 \right] \\ &\stackrel{!}{=} \frac{1}{4} (2-D_1) T_S \left(\frac{2-D_1}{D_1} \right) I_0 \\ &\stackrel{!}{=} \frac{1}{4} (2-D_1)^2 \cdot T_S \cdot I_0 \end{aligned}$$

$$\begin{aligned} \Delta U_C &= \frac{A_C}{C} = \frac{1}{4C} (2-D_1)^2 \cdot T_S \cdot I_0 \\ &\stackrel{!}{=} \frac{T_S \cdot I_0}{C} \left(\frac{2-D_1}{2} \right)^2 = \frac{T_S \cdot I_0}{C} \left(1 - \frac{D_1}{2} \right)^2 \end{aligned}$$

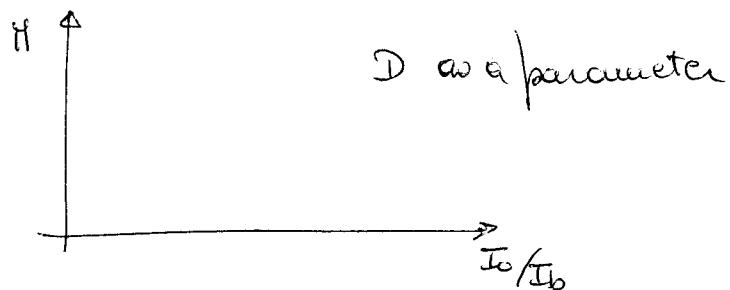
$$\left\{ \begin{array}{l} D_1 = \frac{1}{D} \frac{I_0}{I_B} \\ n = 1 + \frac{D^2}{\frac{I_0}{I_B}} \end{array} \right. \rightarrow \frac{I_0}{I_B} = \frac{D^2}{n-1}$$

$$D_1 = \frac{1}{D} \frac{D^2}{n-1} = \frac{D}{n-1}$$

$$\Delta V_C = \frac{T_S I_0}{C} \left(1 - \frac{D}{1-D} \right)^2$$

DC₁ AND CC₁ TOGETHER

i) Output characteristic

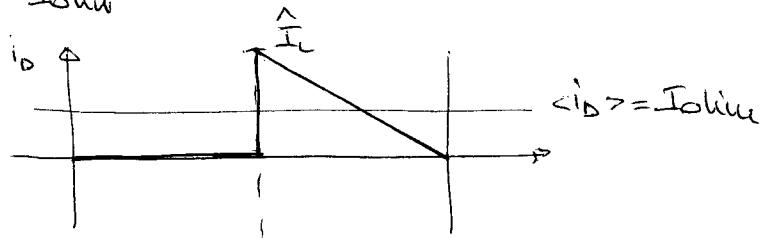


1. CC₁ | if $I_0 > I_{0\text{lim}} \Rightarrow \text{CC}_1 \quad H = \frac{1}{1-D} + \frac{I_0}{I_b}$

2. DC₁ | if $I_0 < I_{0\text{lim}} \Rightarrow \text{DC}_1 \quad H = 1 + \frac{D^2}{I_0/I_b}$

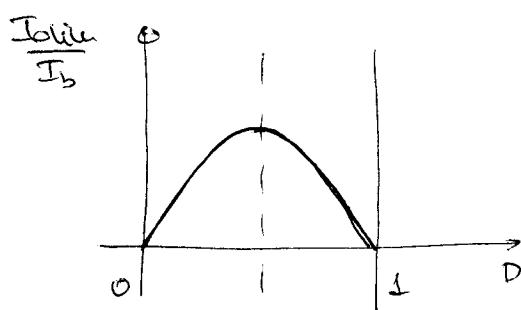
Border between CC₁ and DC₁

$$I_0 = I_{0\text{lim}}$$



$$I_{0\text{lim}} = \frac{\hat{V}_i}{2L} (1-D) = \frac{V_i T_S}{2L} \cdot D \cdot (1-D) = \frac{V_i T_S}{2L} (1-D)D$$

$$\therefore I_b (1-D)D$$



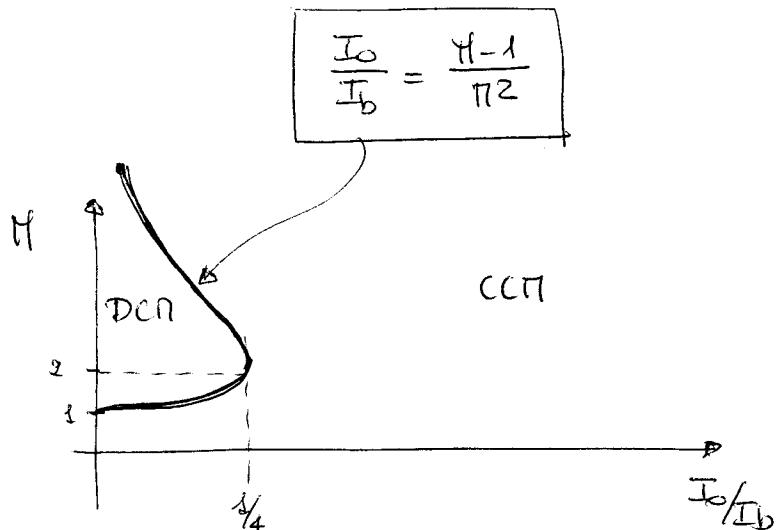
10

$$I_0 = I_{0 \text{ min}} = I_b (1-D)D$$

At the border $H = \frac{1}{1-D}$ is still valid:

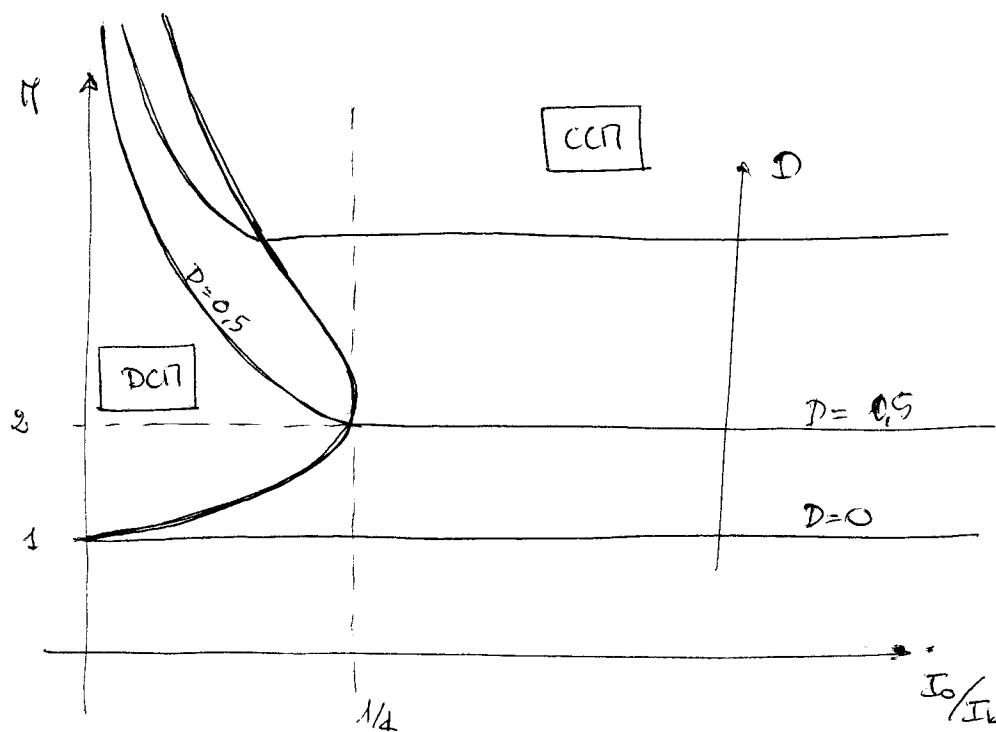
$$\hookrightarrow D = \frac{\pi-1}{H} \rightarrow \frac{I_0}{I_b} = (1-D)D = \left(1 - \frac{\pi-1}{\pi}\right) \frac{\pi-1}{\pi}$$

$$\frac{I_0}{I_b} = \left(\frac{\pi-\pi+1}{\pi}\right) \frac{\pi-1}{\pi} = \frac{\pi-1}{\pi^2}$$



$$\text{CCN} \Leftrightarrow I_0 > I_{0 \text{ min}} \Leftrightarrow I_0 > I_b (1-D)D$$

$$I_0 > I_b \frac{\pi-1}{\pi^2}$$



BUCK-BOOST DCN

(11)

(omitted)

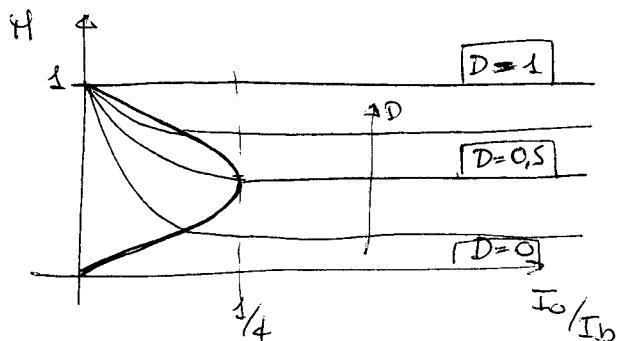
SUMMARY

Buck

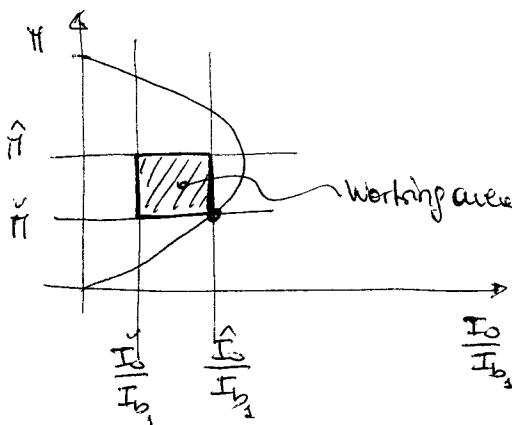
in CCR: $\eta = D$

$$\text{in DCN: } \eta = \frac{D^2}{D^2 + \frac{I_0}{I_b}}$$

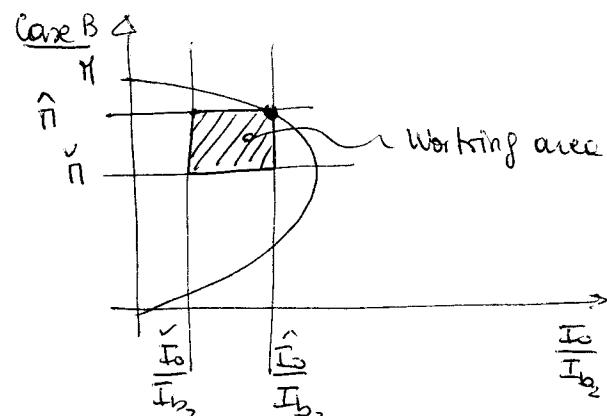
$$\text{limit: } \frac{I_0}{I_b} = \eta(1-\eta)$$



Case A



$$I_{b1} = \frac{\hat{I}_0}{\eta(1-\eta)}$$



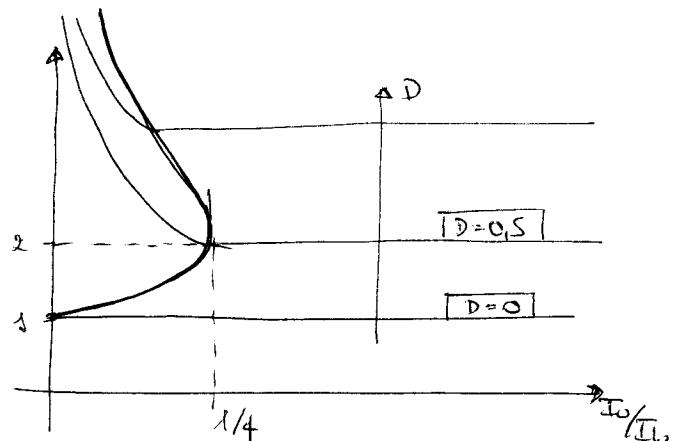
$$I_{b2} = \frac{\hat{I}_0}{\eta(1-\eta)}$$

Boost

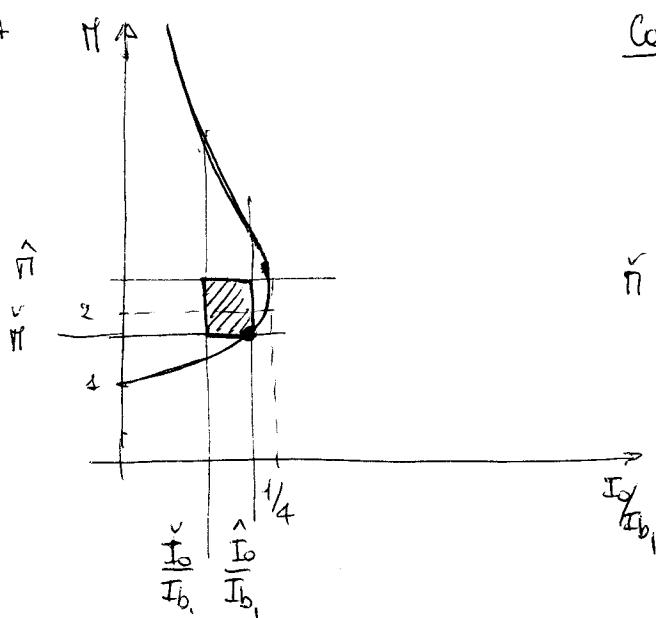
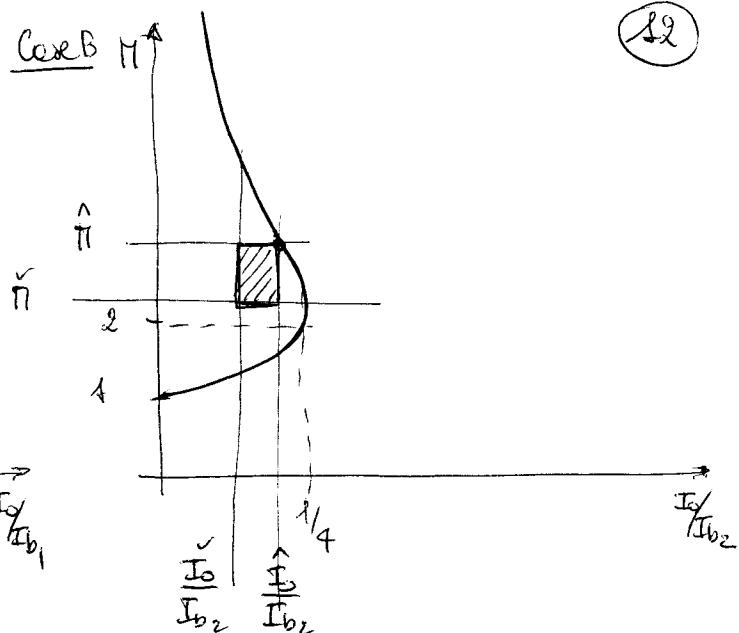
$$\text{in CCR: } \eta = \frac{1}{1-D}$$

$$\text{in DCN: } \eta = 1 + \frac{D^2}{I_0/I_b}$$

$$\text{limit: } \frac{I_0}{I_b} = \frac{\eta-1}{\eta^2}$$



82

Case ACase B

$$I_{b_1} = \hat{I}_0 \frac{\hat{n}^2}{\hat{n}-1}$$

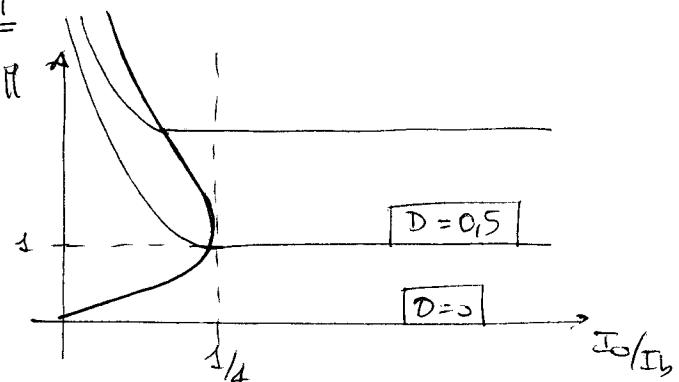
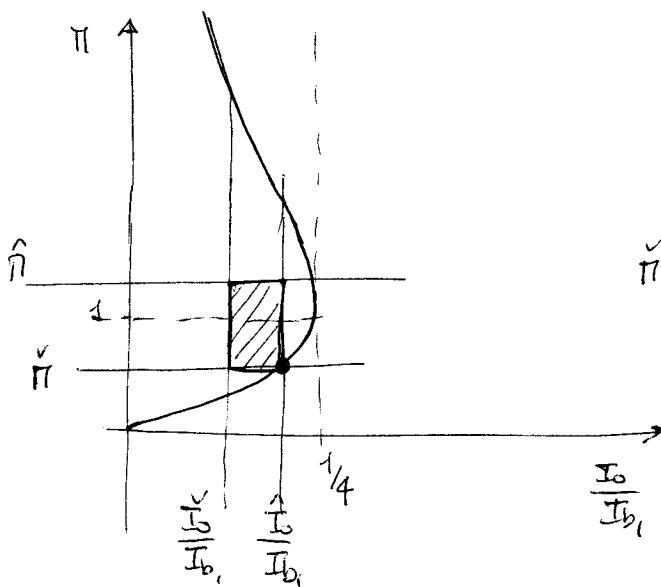
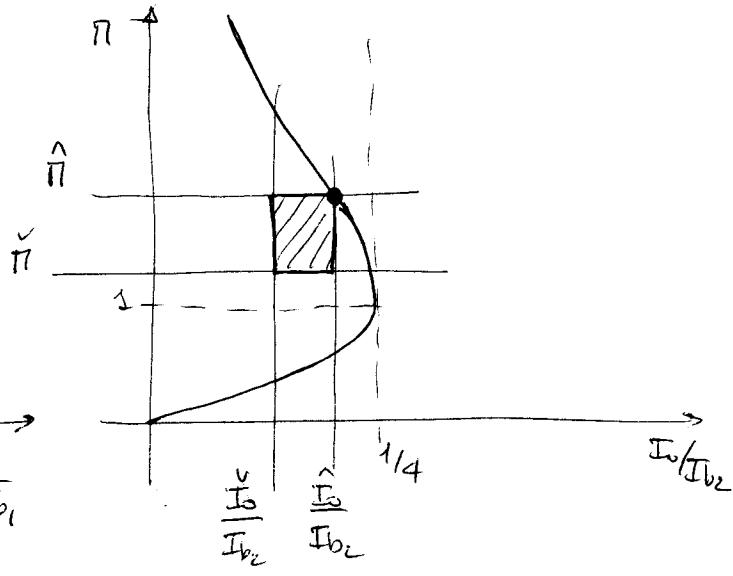
$$I_{b_2} = \hat{I}_0 \frac{\hat{n}^2}{\hat{n}-1}$$

Buck boost

$$\text{in CCM: } \Pi = \frac{D}{s-D}$$

$$\text{in DCM: } \Pi = \frac{D^2}{I_0/I_b}$$

$$\text{limit: } \frac{I_0}{I_b} = \frac{\Pi}{(\Pi+1)^2}$$

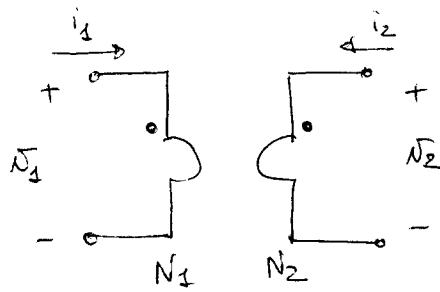
Case ACase B

$$I_{b_1} = \hat{I}_0 \left(\frac{\hat{n}+1}{\hat{n}} \right)^2$$

$$I_{b_2} = \hat{I}_0 \left(\frac{\hat{n}+1}{\hat{n}} \right)^2$$

TRANSFORMERS

Ideal transformer w/ 2 windings



⚠ Always "load" convention!

Def:

$$\frac{V_1}{N_1} = \frac{V_2}{N_2}$$

$$V_1 = \frac{N_1}{N_2} V_2$$

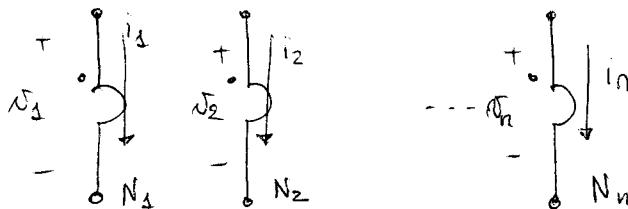
$$P_1 + P_2 = 0 \quad N_1 i_1 + N_2 i_2 = 0 \quad V_1 = \frac{N_1}{N_2} V_2$$

$$\frac{N_1}{N_2} V_2 i_1 + V_2 i_2 = 0$$

$$N_1 i_1 + N_2 i_2 = 0$$

$$i_1 = -\frac{N_2}{N_1} i_2$$

Ideal transformer w/ "n" windings



Def:

$$\frac{N_1}{N_1} = \frac{N_2}{N_2} = \dots = \frac{N_n}{N_n}$$

$$V_1 = \frac{N_1}{N_2} V_2$$

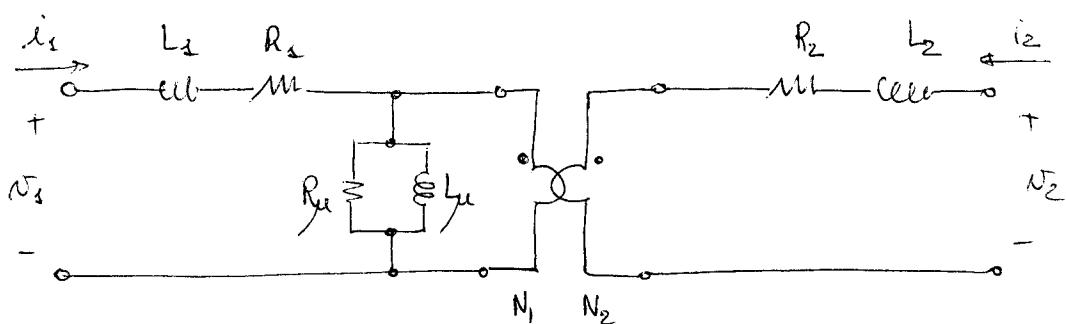
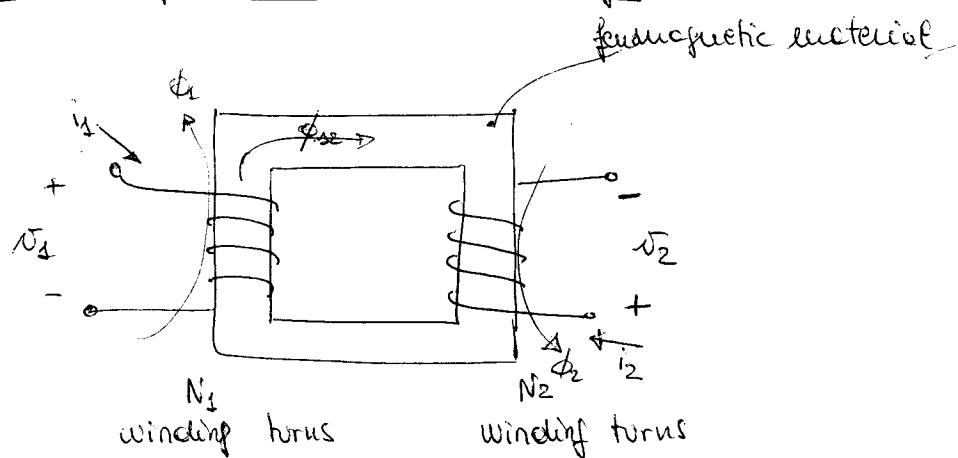
$$V_n = \frac{N_n}{N_2} V_2$$

$$P_1 + P_2 + \dots + P_n = 0 \quad N_1 i_1 + N_2 i_2 + \dots + N_n i_n = 0$$

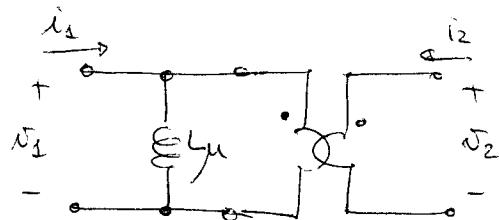
$$\frac{N_1}{N_2} V_2 i_1 + V_2 i_2 + \dots + \frac{N_n}{N_2} V_2 i_n = 0$$

$$N_1 i_1 + N_2 i_2 + \dots + N_n i_n = 0$$

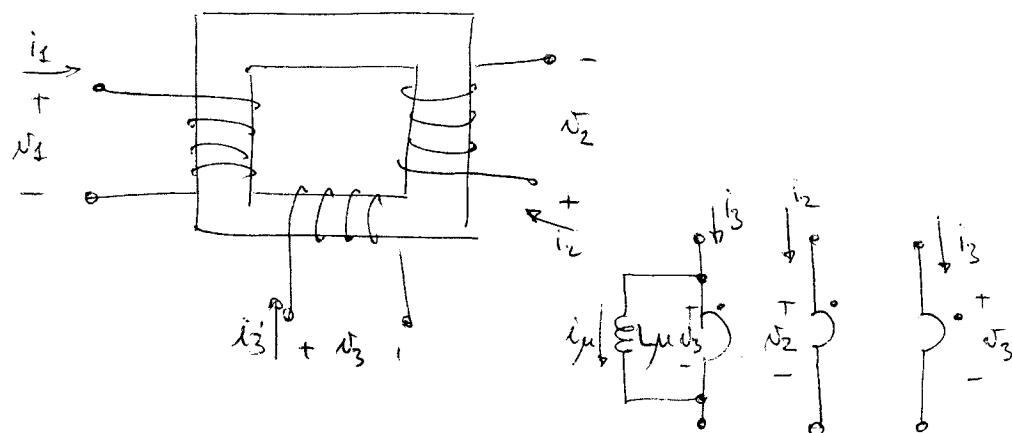
Real transformer with 2 windings



It can be simplified in order to study power converters w/ transf.:



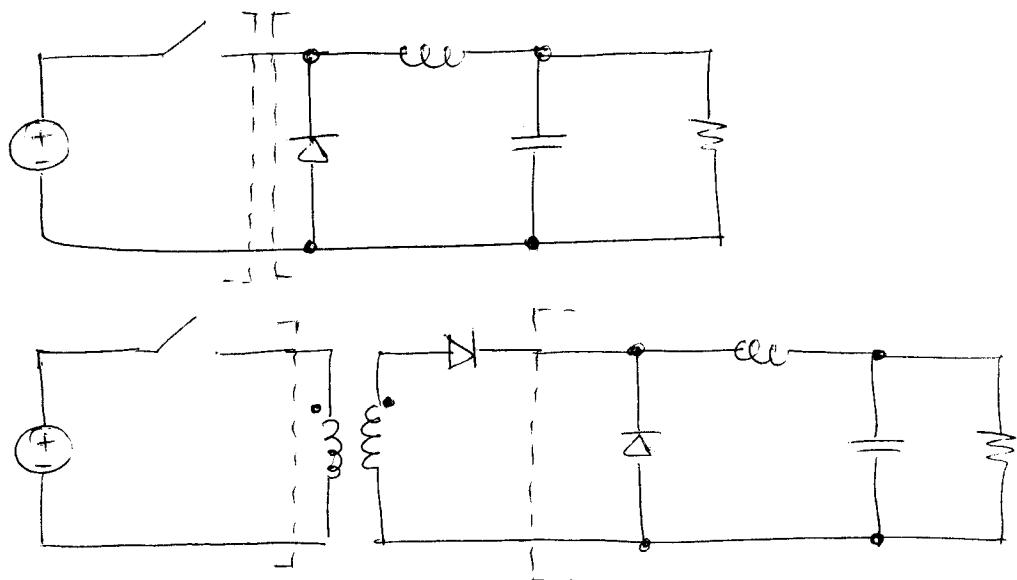
Real transformer with 3 windings



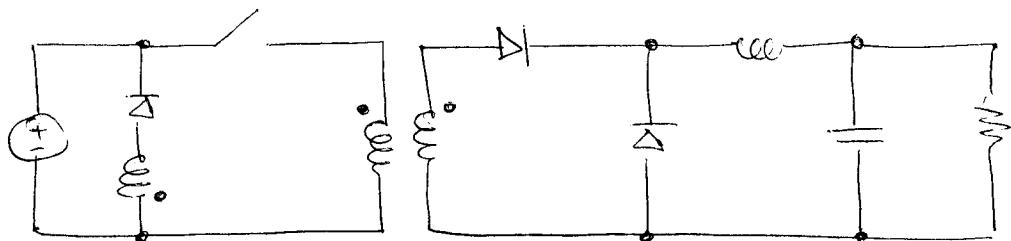
FORWARD

- Topology derived from the buck
- Transformer
- Different variations on the theme, we present the one with "third demagnetizing winding".

c) Derivation from buck

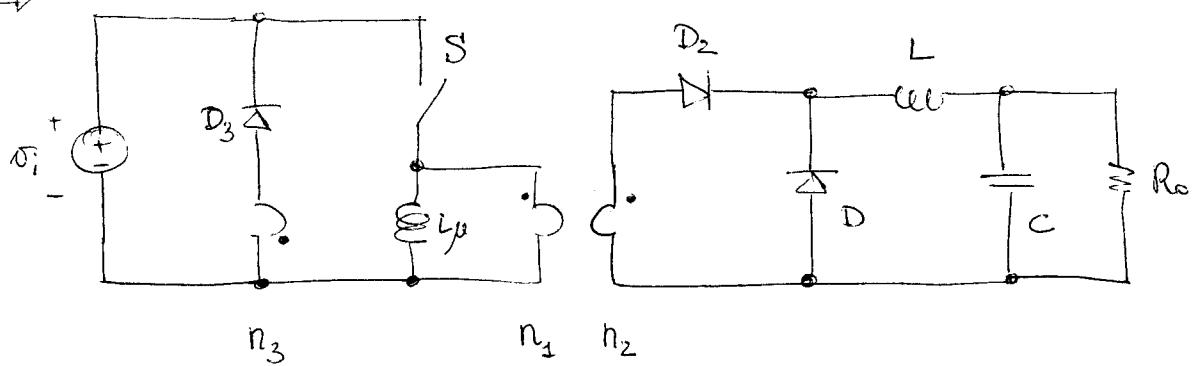


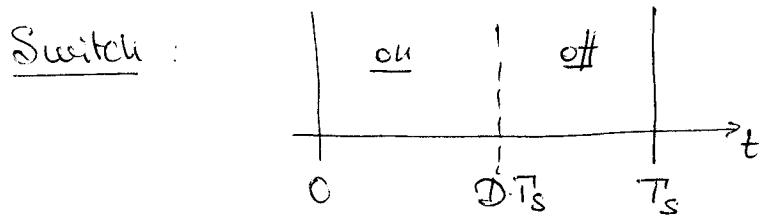
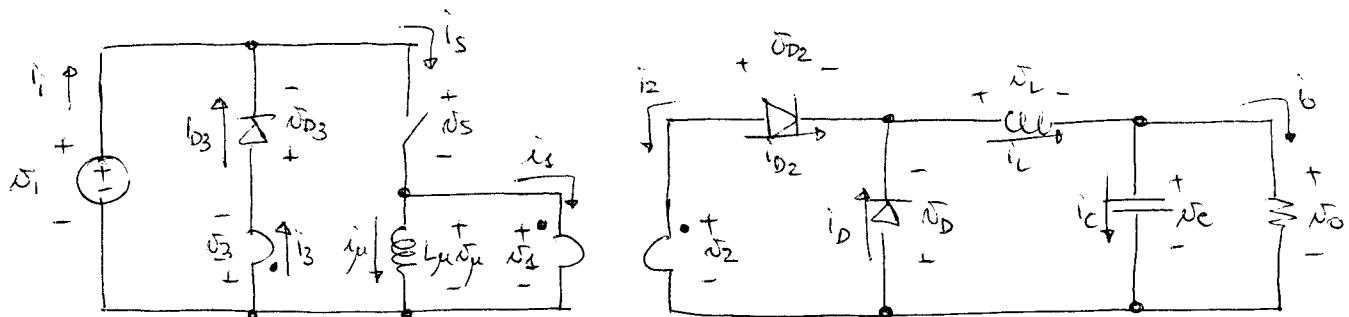
It still cannot work: the core cannot be demagnetized
 → we need circuit to demagnetize the transformer.



- Now with model (the simplest) of the real transformer

⇒



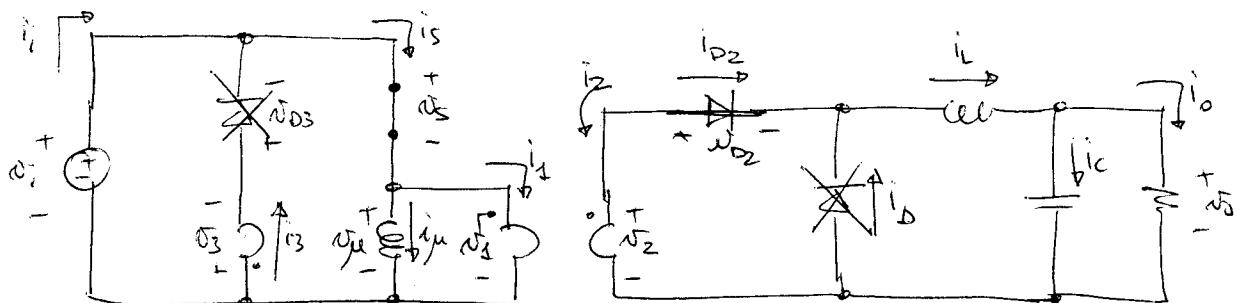
1) General circuit

Diodes : 3 diodes + 1 switch = 16 cases.

→ let's try a more intuitive way

2) Studying the possible circuits

(A) Son, D_3 ?, D_2 ?, D ?



$$N_S = 0 \quad N_{\bar{u}} = V_i \quad N_{\bar{4}} = V_i \quad N_2 = \frac{N_2}{N_4} N_4 \quad N_3 = \frac{N_3}{N_4} N_4 \\ = \frac{N_2}{N_3} V_i \quad = \frac{N_3}{N_4} V_i$$

$$N_{D3} = -V_i - N_3 = -V_i - \frac{N_3}{N_4} V_i = -\left(1 + \frac{N_3}{N_4}\right) V_i \quad N_{D3} < 0 \rightarrow D_3 \text{ off}$$

$$\rightarrow i_{D3} = 0 \quad i_3 = 0$$

(58)

$$i_L > 0 \Rightarrow \begin{cases} i_{D_2} > 0 \Leftrightarrow D_2 \text{ on} \\ i_D > 0 \Leftrightarrow D \text{ on} \\ i_D > 0 \wedge i_{D_2} > 0 \Leftrightarrow D_2 \wedge D \text{ on} \end{cases}$$

$$\boxed{D_2 \wedge D \text{ on}} \Leftrightarrow \bar{N}_{D_2} = 0 \Rightarrow \frac{N_2}{N_1} V_i = 0 \Rightarrow V_i = 0 \Rightarrow \underline{N_D}$$

$$\boxed{D \text{ on}} \Rightarrow \bar{N}_{D_2} = \bar{N}_2 = \frac{N_2}{N_1} V_i > 0 \Rightarrow \underline{N_D}$$

Conclusion: $D_2 \text{ on}$

$$\bar{N}_{D_2} = 0 \Rightarrow \bar{N}_D = -\bar{N}_2 = -\frac{N_2}{N_1} V_i < 0 \Rightarrow \text{OK } D \text{ off}$$

$$V'_i = \frac{N_2}{N_1} V_i \quad \bar{N}_D = V'_i$$

$$\bar{N}_L = \bar{N}_2 - \bar{N}_D = \frac{N_2}{N_1} V_i - V_0 = V'_i - V_0 \quad \text{if must be } V'_i - V_0 > 0$$

$$i_L = \frac{1}{L} \int_0^t \bar{N}_L dt = \frac{1}{L} \int (V'_i - V_0) dt = \frac{V'_i - V_0}{L} t + \bar{I}_L$$

$$i_{D_2} = i_L$$

$$i_D = \frac{V_0}{R} = I_0$$

$$i_C = i_L - i_D = i_L - I_0$$

$$i_2 = -i_{D_2} = -i_L$$

$$N_1 i_1 + N_2 i_2 + \cancel{N_3 i_3} = 0 \rightarrow i_2 = -\frac{N_2}{N_1} i_1 = \frac{N_2}{N_1} i_L$$

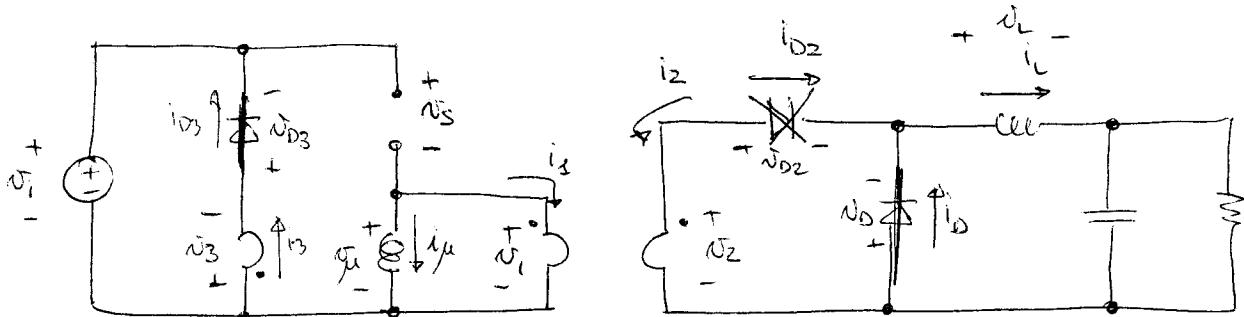
$$\bar{N}_U = V_i \rightarrow i_{\bar{N}_U} = \frac{1}{\bar{N}_U} \int_0^t \bar{N}_U dt = \frac{V_i}{\bar{N}_U} t$$

$$i_S = i_1 + i_{\bar{N}_U} = \frac{N_2}{N_1} i_L + \frac{V_i}{\bar{N}_U} t$$

$$i_1 = i_S$$

Conclusion: A) S_{OU} , D_{OFF} , D_{2OU} , D_{OFF}

C₄) S_{OFF} , $D_3?$, $D_2?$, $D?$



$$D_{3OFF} \Leftrightarrow i_3 = 0 \quad i_1 = -i_\mu \quad i_2 = -\frac{N_1}{N_2} i_1 = \frac{N_1}{N_2} i_\mu$$

$$i_{D2} = -i_2 = -\frac{N_1}{N_2} i_\mu \Rightarrow D_2 \text{ off} \Rightarrow i_2 = 0 \Rightarrow i_\mu = 0$$

\hookrightarrow not possible

$\hookrightarrow D_3 \text{ on}$

$$N_3 = -V_i \quad \bar{v}_3 = \frac{N_1}{N_3} N_3 = -\frac{N_1}{N_3} V_i \quad \bar{v}_2 = \frac{N_2}{N_3} V_i = -\frac{N_2}{N_3} V_i$$

$$\bar{v}_\mu = \bar{v}_1 = -\frac{N_1}{N_3} V_i < 0$$

$$i_\mu = \frac{1}{L_\mu} \int_0^t \bar{v}_\mu + \hat{I}_\mu = -\frac{N_1}{N_3} \frac{V_i}{L_\mu} t + \hat{I}_\mu$$

$$i_L > 0 \quad \begin{cases} i_{D2} > 0 \Leftrightarrow D_2 \text{ on} \\ i_D > 0 \Leftrightarrow D \text{ on} \\ i_D > 0 \wedge i_{D2} > 0 \Leftrightarrow D \text{ or } D_2 \text{ on} \end{cases}$$

$D \wedge D_2 \text{ on}$ $\Leftrightarrow \bar{v}_2 = 0 \Rightarrow \frac{N_2}{N_3} V_i = 0 \Rightarrow V_i = 0 \Rightarrow \underline{N_2}$

$D_2 \text{ on}$ $N_D = -\bar{v}_2 = -\left(-\frac{N_2}{N_3}\right) V_i = \frac{N_2}{N_3} V_i > 0 \quad \underline{w}$

$D \text{ on } (D_2 \text{ off})$

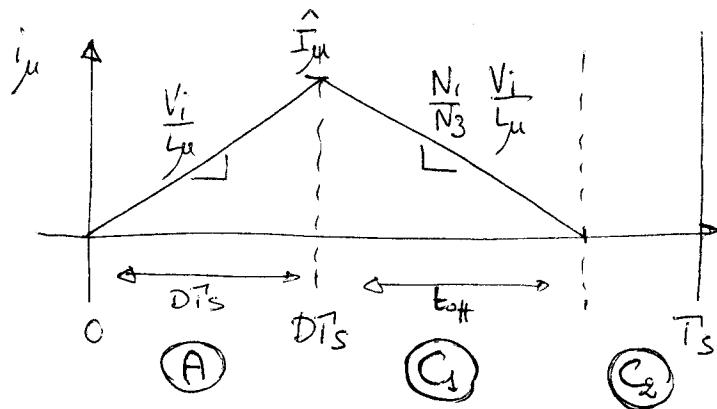
$$i_{D2} = 0 \quad i_2 = -i_{D2} = 0 \quad i_1 N_1 + \cancel{i_2 N_2} + i_3 N_3 = 0$$

$$\bar{v}_{D2} = \bar{v}_2 = -\frac{N_2}{N_3} V_i < 0 \rightarrow \underline{\text{OK}}$$

$$\Delta L = -V_0 \quad i_L = \frac{1}{L} \int_0^t N_L dt + \hat{I}_L = -\frac{V_0}{L} t + \hat{I}_L \quad (60)$$

$$i_s = -i_\mu$$

$$\begin{aligned} i_3 &= -i_s \frac{N_1}{N_3} = i_\mu \frac{N_1}{N_3} = \left[-\frac{N_1}{N_3} \frac{V_i}{L_\mu} t + \hat{I}_\mu \right] \frac{N_1}{N_3} \\ &\downarrow \quad \frac{N_1}{N_3} \hat{I}_\mu - \left(\frac{N_1}{N_3} \right)^2 \frac{V_i}{L_\mu} t \quad i_{D3} = i_3 \end{aligned}$$



$$t_{off} : \hat{I}_\mu - \frac{N_1}{N_3} \frac{V_i}{L_\mu} t_{off} = 0$$

$$\hat{I}_\mu = \frac{N_1}{N_3} \frac{V_i}{L_\mu} t_{off} \quad \hat{I}_\mu = \frac{V_i}{L_\mu} \bar{D}\bar{T}_S$$

$$\cancel{\frac{V_i}{L_\mu}} \bar{D}\bar{T}_S = \frac{N_1}{N_3} \cancel{\frac{V_i}{L_\mu}} t_{off}$$

$$t_{off} = \frac{N_3}{N_1} \bar{D}\bar{T}_S$$

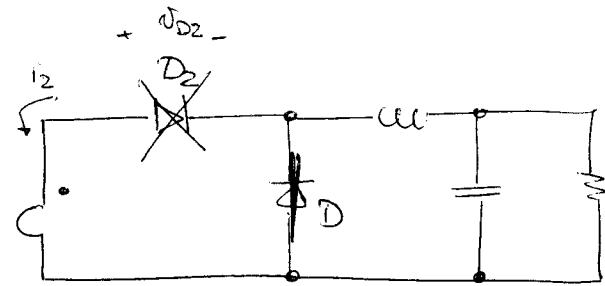
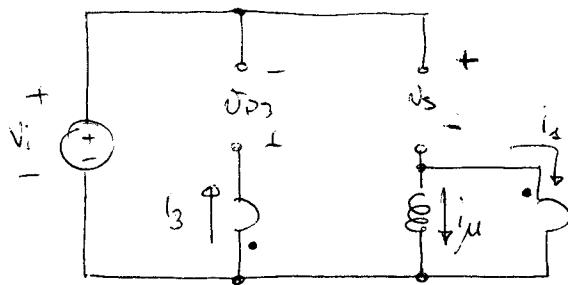
Conclusion. $\textcircled{C_1}$ $S_{off}, D_{3on}, D_{2off}, D_{on}$

$$\Delta S = \Delta_i - \Delta_s = V_i - \left(-\frac{N_1}{N_3} \right) V_i = \left(1 + \frac{N_1}{N_3} \right) V_i$$

(C2)

Soft, D_3 off, D_2 ?, D?

(61)



$$i_3 = 0 \quad i_\mu = 0 \quad i_4 = -i_\mu = 0 \quad i_{N_1} + i_2 N_2 + i_3 N_3 = 0 \quad i_2 = 0$$

$\rightarrow D_2$ off

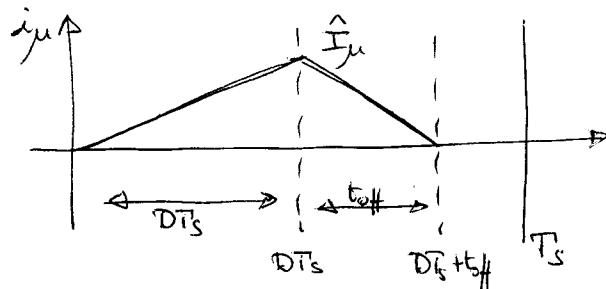
$$i_\mu = 0 \Rightarrow v_\mu = 0 \Rightarrow v_4 = 0 \quad v_2 = 0 \quad v_3 = 0$$

$i_1 > 0$ Don

$$v_{D_3} = -V_i \quad v_s = V_i \quad v_{D_2} = 0$$

Conclusion : (C2) Soft, D_3 off, D_2 off, Don

IMPORTANT CONDITION



$$DT_S + t_{off} < T_S$$

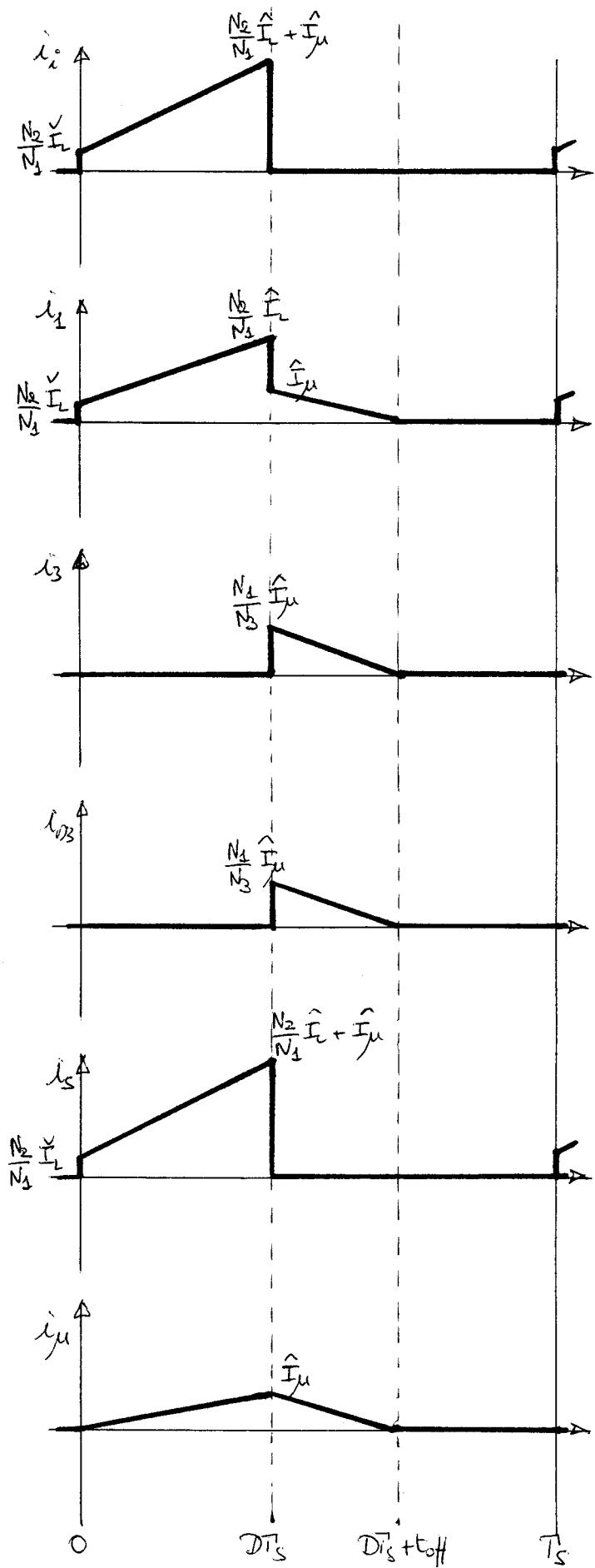
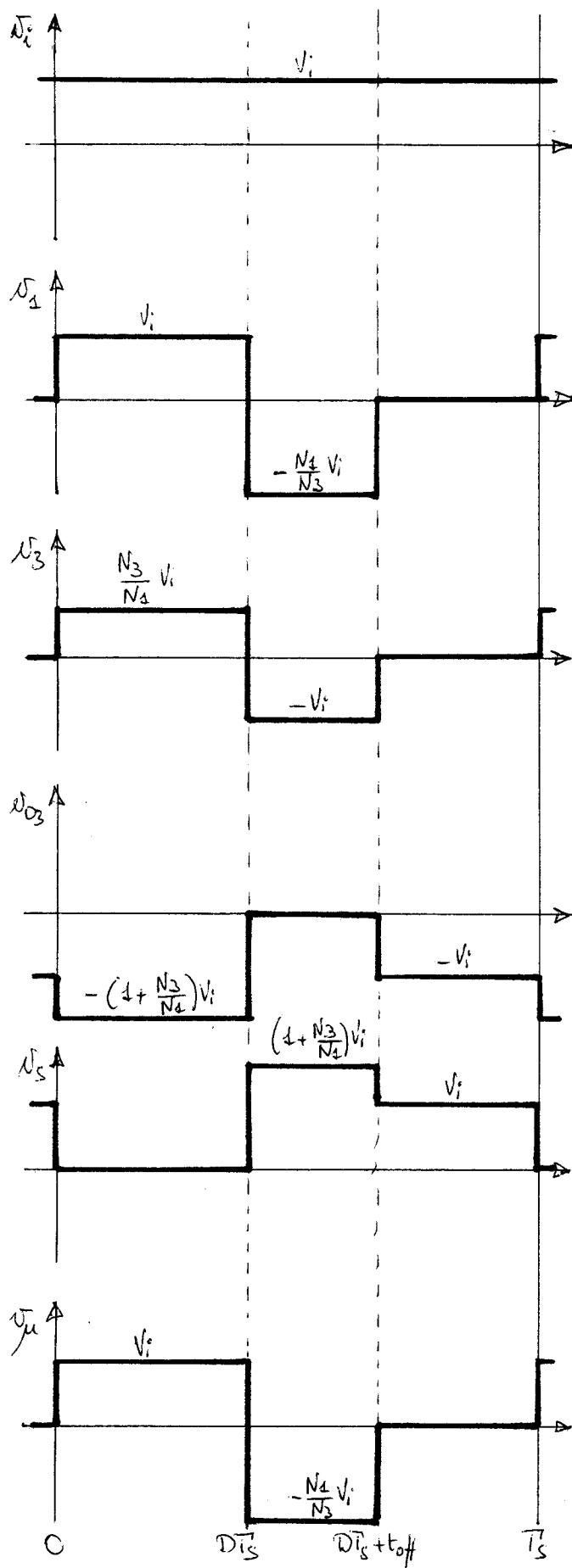
$$t_{off} = \frac{N_3}{N_1} DT_S$$

$$DT_S + \frac{N_3}{N_1} DT_S < T_S$$

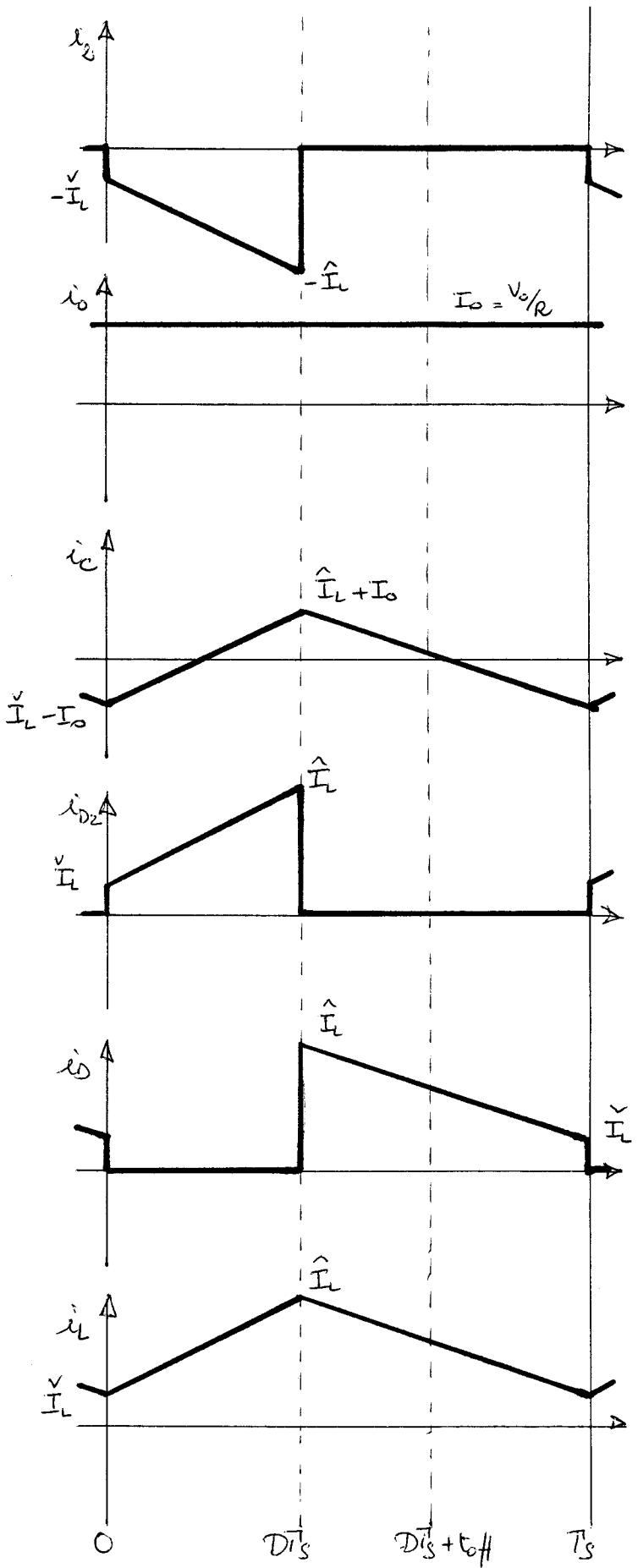
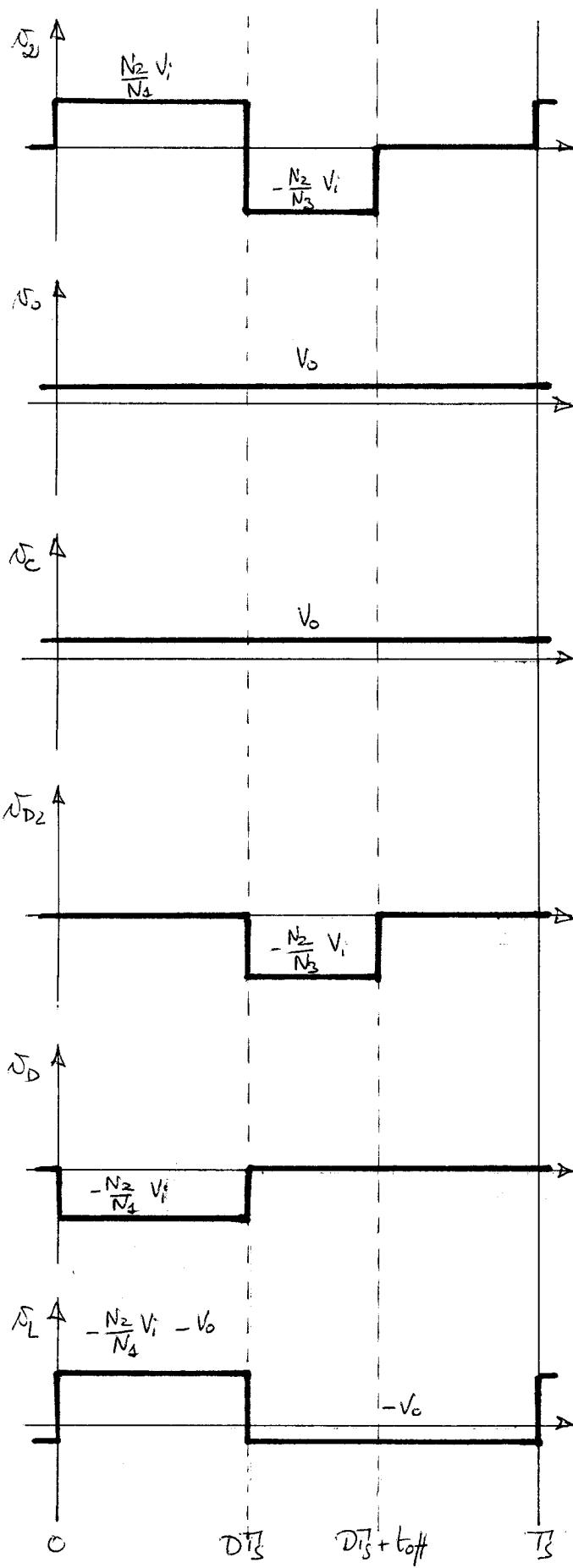
$$D \left(1 + \frac{N_3}{N_1} \right) < 1 \quad 1 + \frac{N_3}{N_1} < \frac{1}{D} \quad \frac{N_3}{N_1} < \frac{1}{D} - 1$$

$$\frac{N_3}{N_1} < \frac{1-D}{D}$$

(2)



(63)



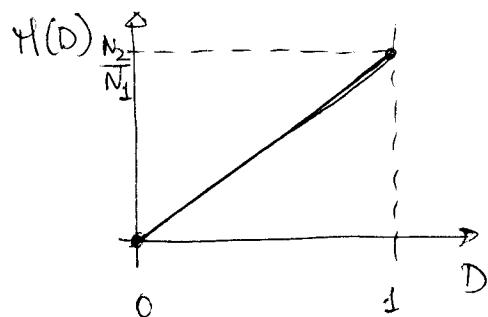
4) Steady-state conditions

Defined $V_i' = \frac{N_2}{N_1} V_i$, the second part of the converter behaves like a buck with an input voltage V_i' . All the equations are then the same.

$$V_o = D V_i' = D \frac{N_2}{N_1} V_i$$

5) Conversion ratio

$$M(D) = \frac{V_o}{V_i} = D \frac{N_2}{N_1}$$

6) Current ripple (inductor)

$$\begin{aligned} \Delta i_L &= \frac{V_i' - V_o}{L} D T_S = \frac{V_i' - D V_i'}{L} D T_S = \frac{V_i' T_S}{L} (s-D)D \\ &= \frac{N_2}{N_1} \frac{V_i T_S}{L} (s-D)D \end{aligned}$$

7) Average and maximum current

$$\langle i_L \rangle = I_o = \frac{V_o}{R}$$

$$\begin{aligned} \hat{i}_L &= I_o + \frac{\Delta i_L}{2} = I_o + \frac{V_i' T_S}{L} (s-D)D \\ &= I_o + \frac{N_2}{N_1} \frac{V_i T_S}{L} (s-D)D \end{aligned}$$

(65)

$$\hat{I}_D = \hat{I}_{D_2} = \hat{I}_L$$

$$\hat{I}_i = \hat{I}_S = \frac{N_2}{N_1} \hat{I}_L + \hat{I}_\mu$$

$$\hat{I}_{D_3} = \frac{N_3}{N_1} \hat{I}_\mu$$

$$|\hat{I}_2| = \hat{I}_L \quad |\hat{I}_3| = \frac{N_2}{N_1} \hat{I}_L \quad |\hat{I}_3| = \frac{N_1}{N_3} \hat{I}_\mu$$

$$\langle i_D \rangle = I_0 (1-D)$$

$$\langle i_{D_2} \rangle = I_0 D$$

$$\langle i_S \rangle = - \langle i_{D_2} \rangle = - I_0 D$$

$$\langle i_i \rangle = \langle i_S \rangle = \frac{1}{T_S} \int_0^t i_S(t) dt = \frac{1}{T_S} A_S =$$

$$= \frac{1}{T_S} \left[\frac{N_2}{N_1} \hat{I}_L + \frac{N_2}{N_1} \hat{I}_L + \hat{I}_\mu \right] \frac{1}{2} \cdot D/T_S$$

$$= \frac{N_2}{N_1} \langle i_L \rangle + \frac{\hat{I}_\mu}{2} = \frac{N_2}{N_1} I_0 + \frac{\hat{I}_\mu}{2}$$

8) Maximum voltage

$$|\hat{v}_S| = \left(1 + \frac{N_3}{N_1} \right) V_i$$

$$|\hat{v}_D| = \frac{N_2}{N_1} V_i$$

$$|\hat{v}_{D_2}| = \frac{N_2}{N_3} V_i$$

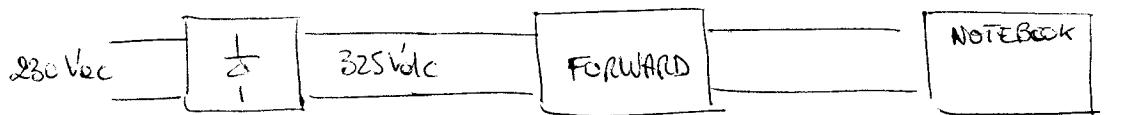
$$|\hat{v}_{D_3}| = \left(1 + \frac{N_3}{N_1} \right) V_i$$

9) Output voltage ripple

$$\Delta v_C = \frac{V_i T_S^2}{8LC} (1-D)D = \frac{N_2}{N_1} \frac{V_i T_S^2}{8LC} (1-D)D$$

Exercise

- 1) Complete study of forward
- 2) Study of forward in DCT
- 3) Design of a forward



$$N_2 = 325$$

$$L_\mu = 60 \mu H$$

$$f_S = 40 \text{ kHz}$$

$$V_o = 20 \text{ V}$$

$$P = (40 \div 90) \text{ W}$$

$$\Delta V_C = 0,2 \text{ V}$$

CCM operation

D: free choice

$$N_2 = ? \quad N_3 = ? \quad I_0 = ? \quad I_{0\lim} = ?$$

$$D = ? \quad L = ? \quad C = ? \quad \Delta i_L = ?$$

$$\langle i_L \rangle = ? \quad \langle i_S \rangle = ? \quad \langle i_D \rangle = ? \quad \langle i_{D3} \rangle = ?$$

$$\langle i_{D2} \rangle = ? \quad \hat{I}_L = ? \quad \hat{I}_S = ? \quad \hat{I}_0 = ?$$

$$|\hat{I}_{D3}| = ? \quad |\hat{I}_{D2}| = ? \quad |\hat{i}_S| = ? \quad |\hat{i}_0| = ?$$

$$|\hat{v}_{D3}| = ? \quad |\hat{v}_{D2}| = ?$$

Compare your choice and your results with
your colleagues and decide on the best choice.

LECTURE 4

RMS (Root Mean Square) Values

For all the topologies we have found

$$\begin{array}{lll} \hat{I}_D & \langle i_D \rangle & |\hat{V}_D| \\ \hat{I}_S & \langle i_S \rangle & |\hat{V}_S| \\ & & |\hat{V}_C| \end{array}$$

This is not enough for choosing a comp. & evolving losses. \rightarrow We also need the RMS

\hookrightarrow Generally related with ohmic losses.

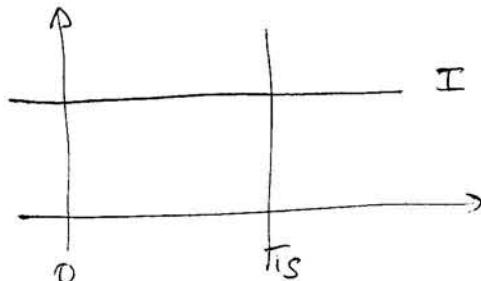
Calculation of RMS Root MEAN SQUARE

$$i(t)$$

$$I_{RMS} = \sqrt{\frac{1}{T_S} \int_0^{T_S} i^2(t) dt}$$

Example

$$\Rightarrow i(t) = I$$

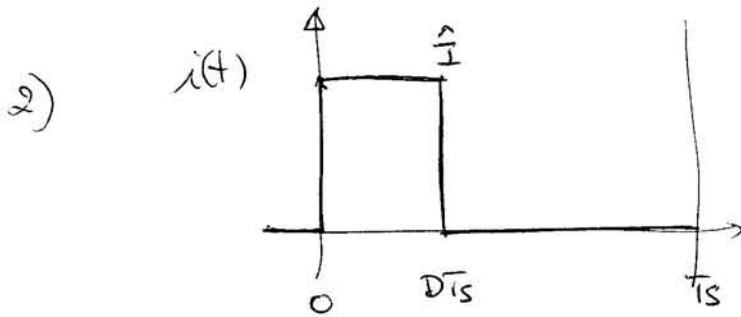


$$I_{RMS} = \sqrt{\frac{1}{T_S} \int_0^{T_S} I^2 dt} = \sqrt{\frac{1}{T_S} I^2 T_S} = I$$

$$I_{RMS} = |i(t)|$$

~~2~~

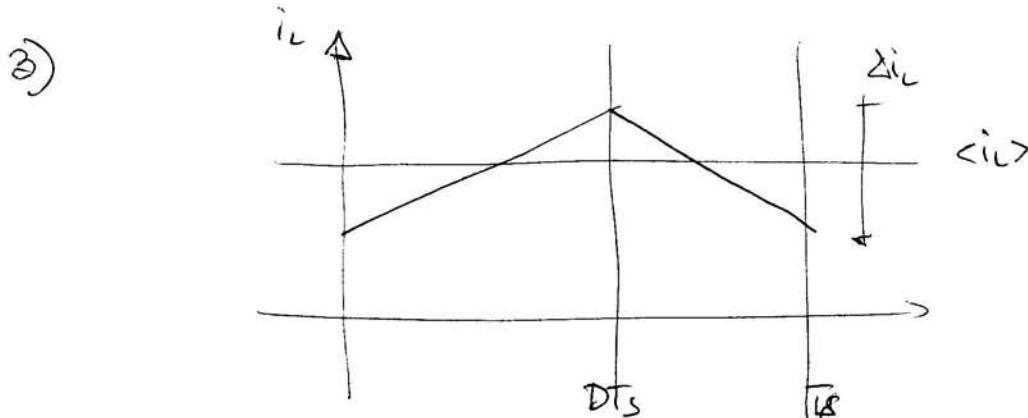
$$\langle i \rangle = I$$



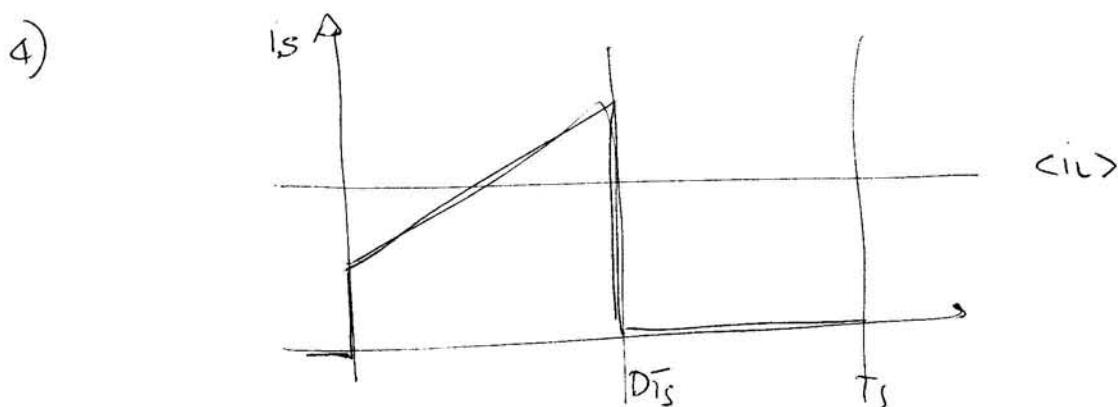
$$I_{RMS} = \sqrt{\frac{1}{T_S} \int_0^{T_S} i^2(t) dt} = \sqrt{\frac{1}{T_S} \int_0^{D\bar{T}_S} \hat{I}^2 dt + \frac{1}{T_S} \int_{D\bar{T}_S}^{T_S} \hat{I}^2 dt} =$$

$$= \sqrt{\frac{1}{T_S} \int_0^{D\bar{T}_S} \hat{I}^2 dt} = \sqrt{\frac{1}{T_S} \hat{I}^2 D\bar{T}_S} = |\hat{I}| \sqrt{D}$$

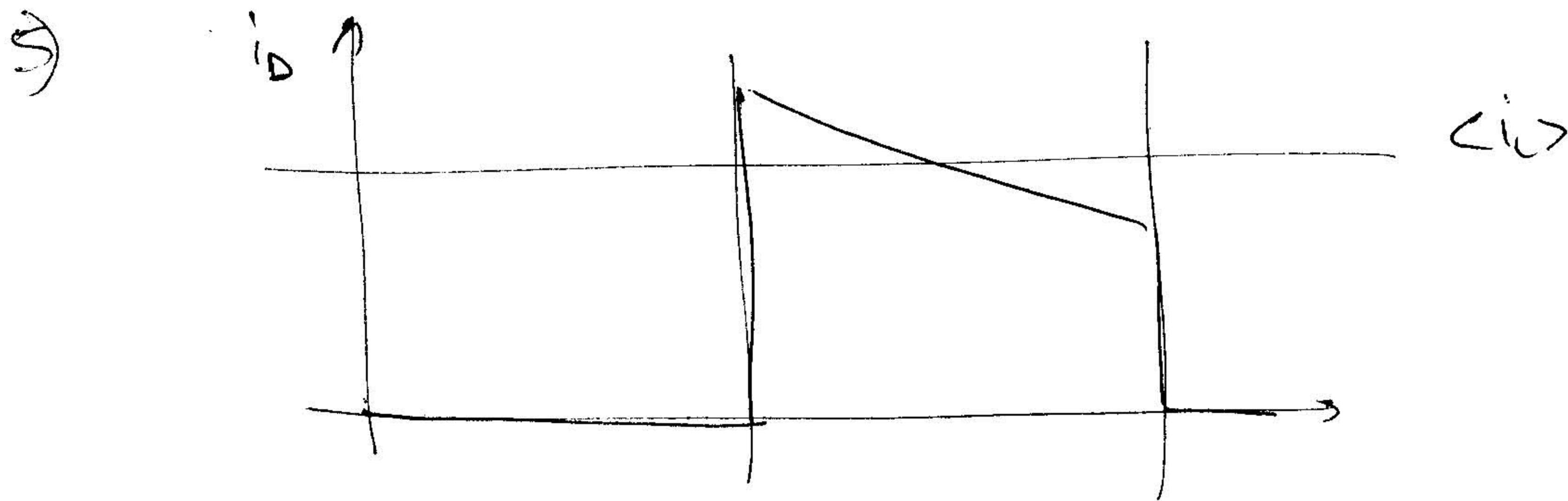
$$\langle i \rangle = \frac{1}{T_S} \int_0^{T_S} i(t) dt = \frac{1}{T_S} \int_0^{D\bar{T}_S} \hat{I} dt = D \hat{I}$$



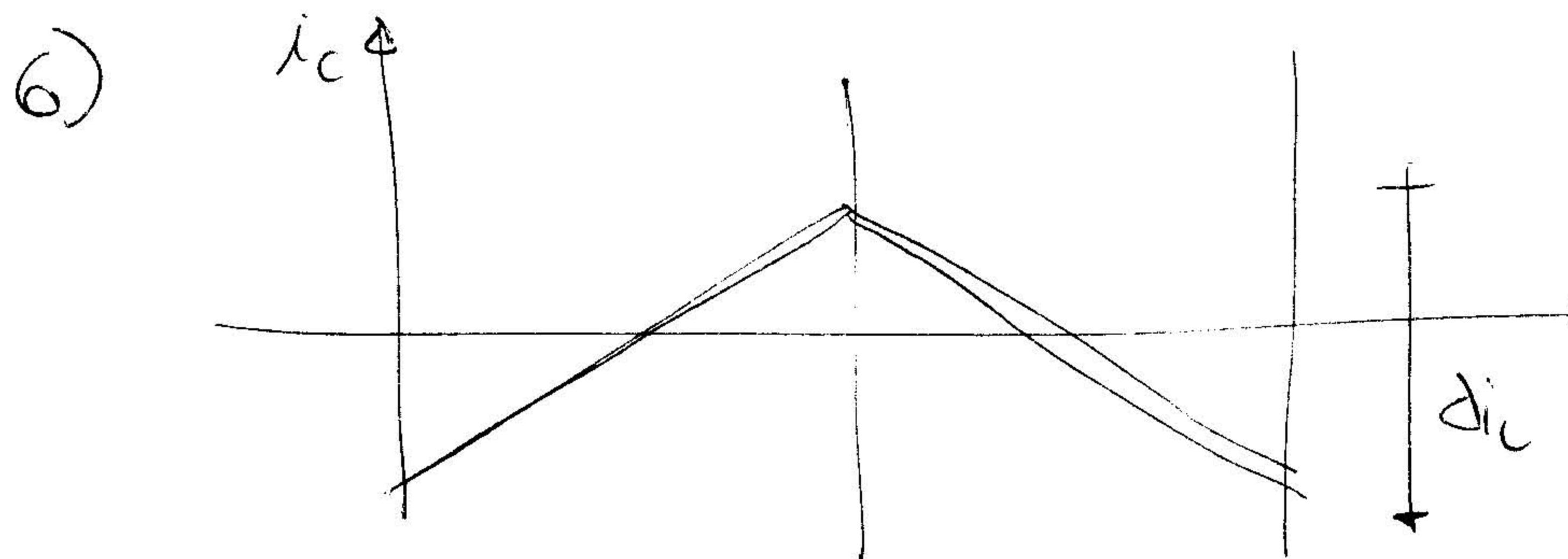
$$I_{RMS} = \langle i_L \rangle \sqrt{1 + \frac{1}{42} \left(\frac{\Delta i_L}{\langle i_L \rangle} \right)^2}$$



$$I_{S,\text{rms}} = \langle i_c \rangle \sqrt{D} \sqrt{1 + \frac{1}{\delta_2} \left(\frac{\Delta i_c}{\langle i_c \rangle} \right)^2}$$



$$I_{D,\text{rms}} = \langle i_c \rangle \sqrt{1-D} \sqrt{1 + \frac{1}{\delta_2} \left(\frac{\Delta i_c}{\langle i_c \rangle} \right)^2}$$



$$I_{CRMS} = \frac{1}{\sqrt{3}} \left(\frac{\Delta i_c}{2} \right) = \frac{\Delta i_c}{2\sqrt{3}}$$

7) GENERAL PIECEWISE WAVEFORM

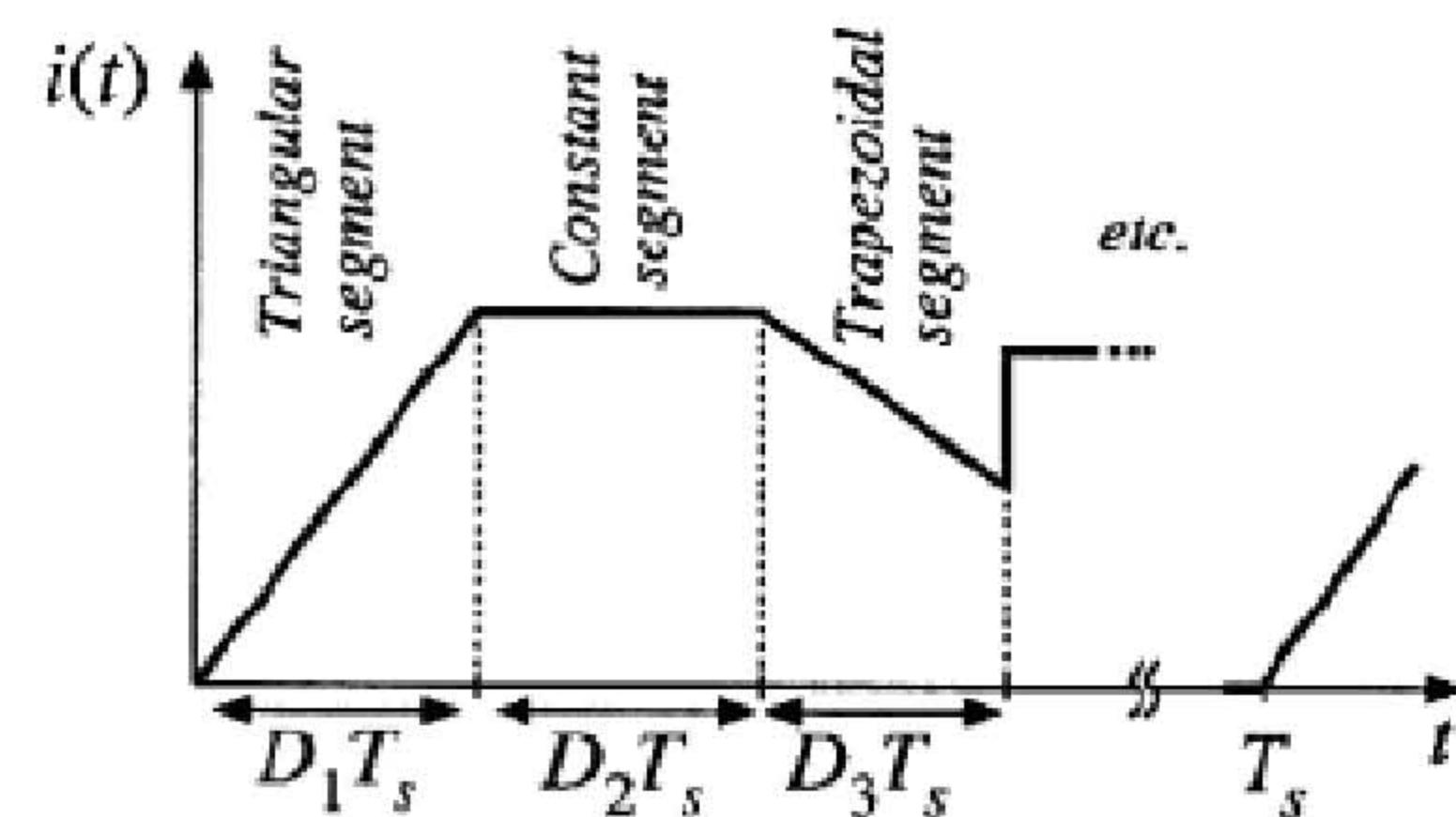


Fig. A.12

For a periodic waveform composed of n piecewise segments as in Fig. A.12, the rms value is

$$rms = \sqrt{\sum_{k=1}^n D_k u_k} \quad (\text{A.12})$$

where D_k is the duty cycle of segment k , and u_k is the contribution of segment k . The u_k s depend on the shape of the segments—several common segment shapes are listed in **Erickson, Maksimovic, Fundamentals of Power Electronics, Appendix A.2** (available at www.aub.aau.dk).

Components

- (Power) Diodes
- (Power) Switches
- Switch drivers
- Capacitors

Power diodes

- Slightly different from normal diodes
 - They have one more layer to block higher voltages
- Manufacturers
 - ST Microelectronics www.st.com
 - Microsemi www.microsemi.com
 - International rectifiers www.irf.com
 - Vishay www.vishay.com
 - many others...

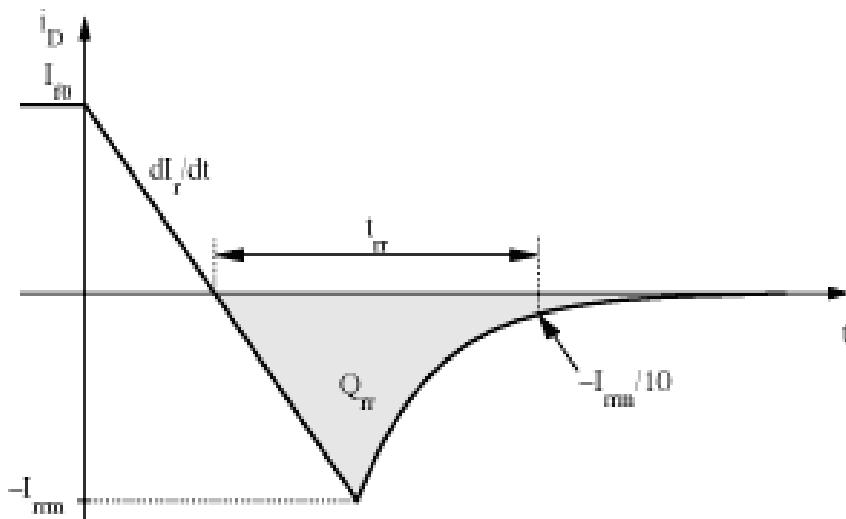
Criteria

- Diode's maximum reverse voltage $V_r > |V_{D,max}|$ (with margin)
- Diode's nominal current $I_D > I_{D,max}$ (with margin)
 - Can be $I_D < i_{D,max}$ (but other limitations also on $I_{D,max}$)
- Diode's forward voltage V_F "low enough"
 - Related to power losses
- Recovery time t_{rr} compatible with f_s
- Temperature can be higher than 25 °C
- Package/Modules
- Cost

Schottky diodes

- Special diodes (metal-semiconductor junction)
- Advantages
 - Extremely fast
- Disadvantages
 - Low reverse voltage
 - High reverse leakage current

Recovery time (diode's turn-off)



Example of a power diode datasheet
(www.microsemi.com)

Ultra Fast Recovery Rectifiers UFR30, 31 & 32

Notes:

1. 10-32 UNF3A threads
2. Full threads within 2 1/2 threads Standard Polarity: Stud is Cathode Reverse Polarity: Stud is Anode

	Dim. Inches		Millimeter		Notes
	Minimum	Maximum	Minimum	Maximum	
A	---	---	---	---	1
B	.424	.437	10.77	11.10	
C	---	.505	---	12.82	
D	.600	.800	15.24	20.32	
E	.422	.453	10.72	11.50	
F	.075	.175	1.91	4.44	
G	---	.405	---	10.29	
H	.163	.189	4.15	4.80	2
J	.100	.310	2.54	7.87	
M	---	.350	---	8.89	Dia.
N	.020	.065	.510	1.65	
P	.070	.100	1.78	2.54	Dia.

DO203AA (D04)

Microsemi Catalog Number

UFR3010*	Working Peak Reverse Voltage	Peak Reverse Voltage
UFR3015*	100V	100V
UFR3020*	150V	150V
UFR3120*	200V	200V
UFR3130*	300V	300V
UFR3140*	400V	400V
UFR3150*	500V	500V
UFR3260*	600V	600V
UFR3270*	700V	700V
UFR3280*	800V	800V

- Ultra Fast Recovery Rectifier
- 175°C Junction Temperature
- V_{RRM} 100 to 800V
- High Reliability
- 30 Amps current rating
- t_{RR} 35 to 60 nsec maximum

*Add Suffix R For Reverse Polarity

Electrical Characteristics		
Average forward current	UFR30	UFR31
Case Temperature	T_C	127°C
Maximum surge current	$IFSM$	500A
Max peak forward voltage	V_{FM}	.975V
Max reverse recovery time	t_{RR}	35 ns
Max peak reverse current	IRM	1.0 mA
Max peak reverse current	IRM	15 μA
Typical Junction Capacitance	C_J	140 pF
	115 pF	100 pF
Square wave, $R_{BJC} = 1.8^\circ\text{C/W}$		
8.3 ms, half sine, $T_J = 175^\circ\text{C}$		
$IFM = 30\text{A}; T_J = 25^\circ\text{C}^*$		
$1/2\text{A}, 1\text{A}, 1/4\text{A}, T_J = 25^\circ\text{C}$		
$V_{RRM}, T_J = 125^\circ\text{C}$		
$V_{RRM}, T_J = 25^\circ\text{C}$		
$VR = 10\text{V}, f = 1\text{MHz}, T_J = 25^\circ\text{C}$		
*Pulse test: Pulse width 300 μsec , Duty cycle 2%		
Thermal and Mechanical Characteristics		
Storage temp range	T_{STG}	-65°C to 175°C
Operating junction temp range	T_J	-65°C to 175°C
Max thermal resistance	$R_{\theta JC}$	1.8°C/W
Typical thermal resistance	$R_{\theta JC}$	1.3°C/W
Typical thermal resistance (greased)	$R_{\theta CS}$	0.4°C/W
Mounting torque		Case to sink 12-15 inch pounds
Weight		0.2 ounces (6.0 grams) typical

LAWRENCE
Microsemi

6 Lake Street
Lawrence, MA 01841
PH: (978) 620-2600
FAX: (978) 689-0803
www.microsemi.com

05-07-07 Rev. 2

Figure 1
Typical Forward Characteristics

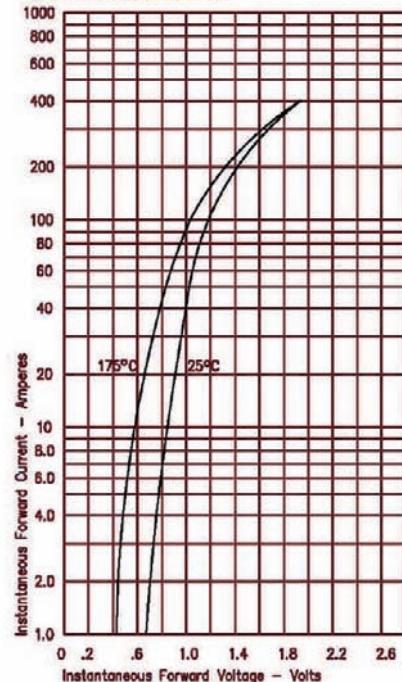


Figure 3
Typical Junction Capacitance

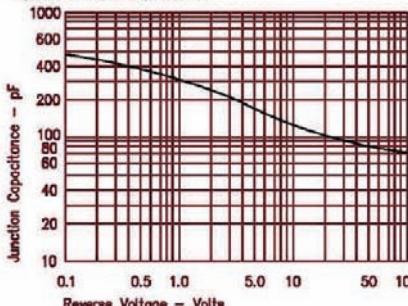


Figure 4
Forward Current Derating

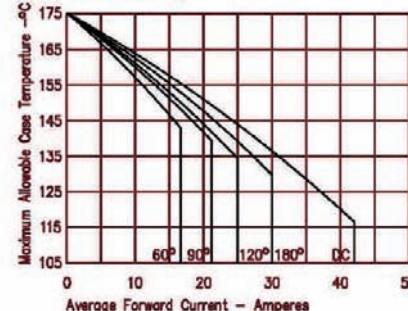


Figure 2
Typical Reverse Characteristics

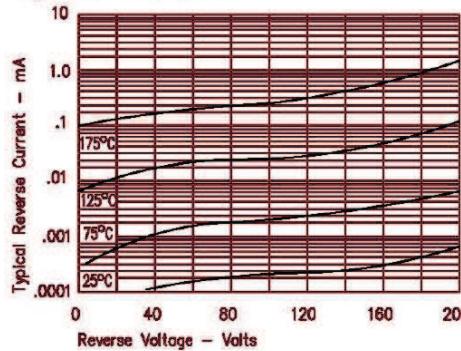
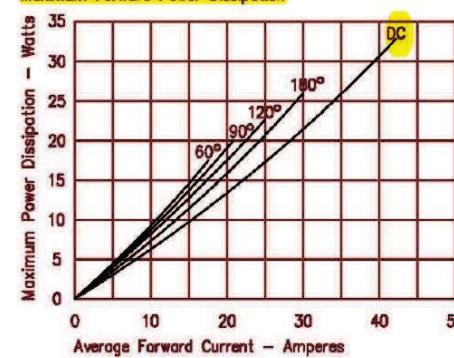
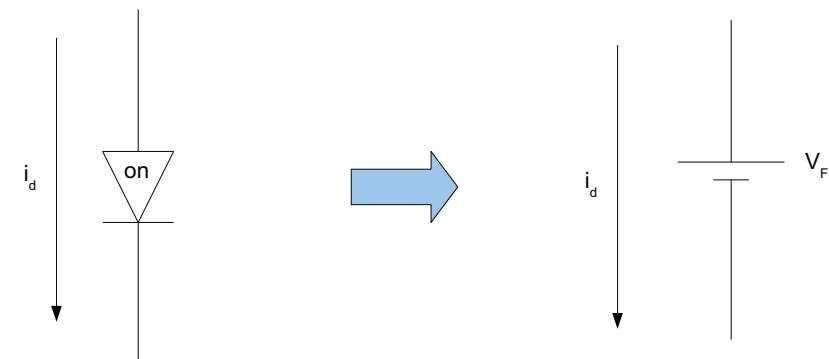


Figure 5
Maximum Forward Power Dissipation



Conduction losses

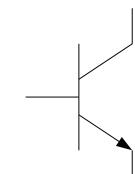


$$P_d = V_F * \langle i_d \rangle$$

Power switches

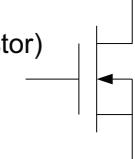
- **BJT** (Bipolar Junction Transistor)

- (Almost) not used anymore



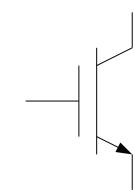
- **MOSFET** (Metal Oxide Semiconductor Field Effect Transistor)

- Currently used (lower voltage, higher frequency)
-



- **IGBT** (Insulated Gate Bipolar Transistor)

- Currently used (higher voltage, lower frequency)



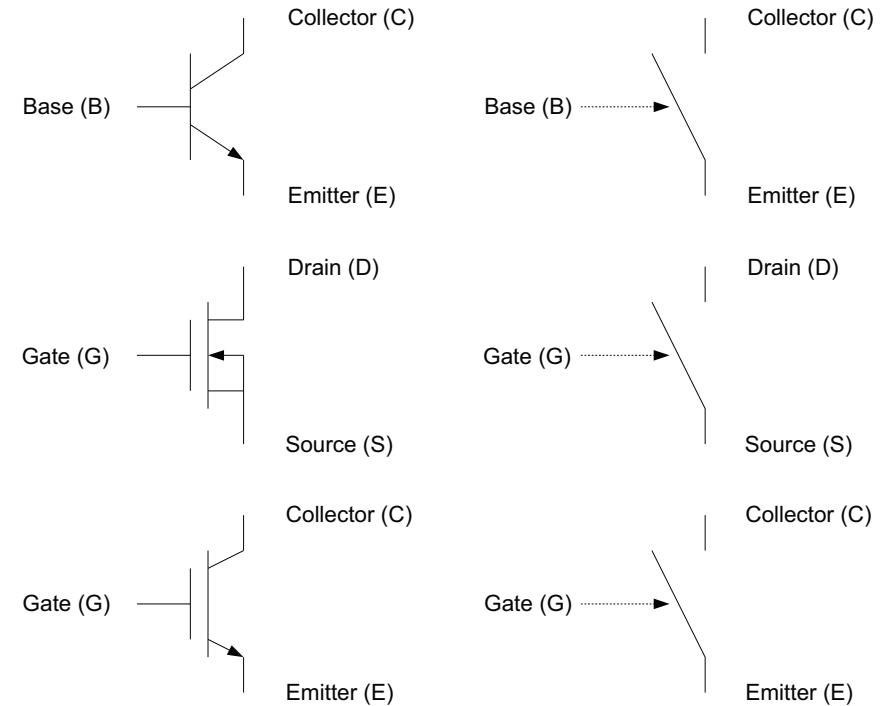
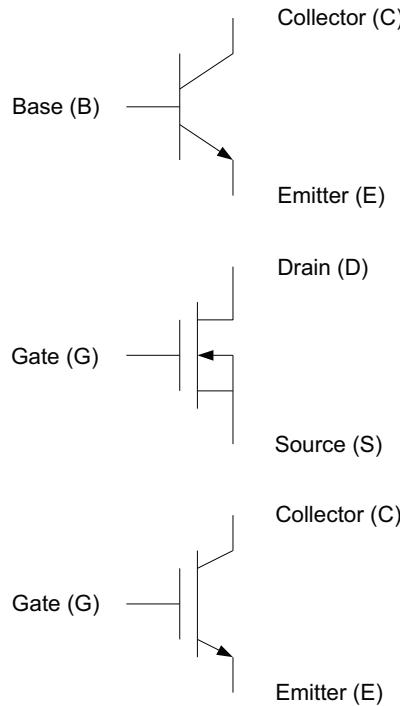
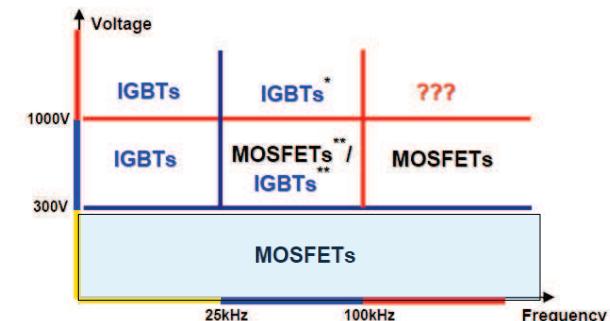


Table 1: Charge Technology Comparison

COMPARISON CRITERIA	BJTs	MOSFETs	IGBTs
Drive Method	Current	Voltage	Voltage
Drive Circuit Complexity	High	Low	Low
Switching Speeds	Slow (μ s)	Very Fast (ns)	Medium
Switching Frequencies	few kHz	Up to 1 MHz	< 50 kHz
Forward Voltage Drop	Low	Medium	Low
Current Carrying Capability	High	Medium	High
Breakdown Voltage	High	Medium (<1500V)	Very High (~5000V)

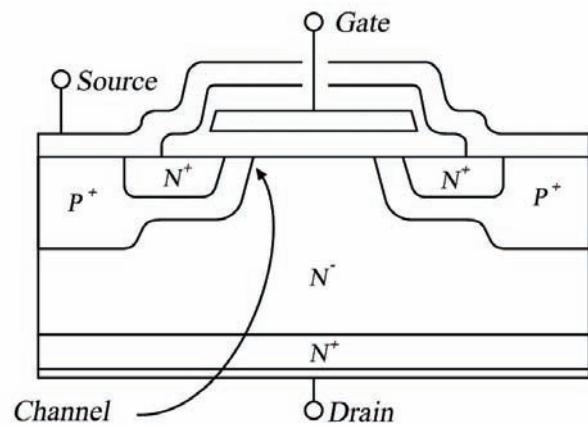


* Switching frequencies above 25kHz only achievable with soft switching techniques

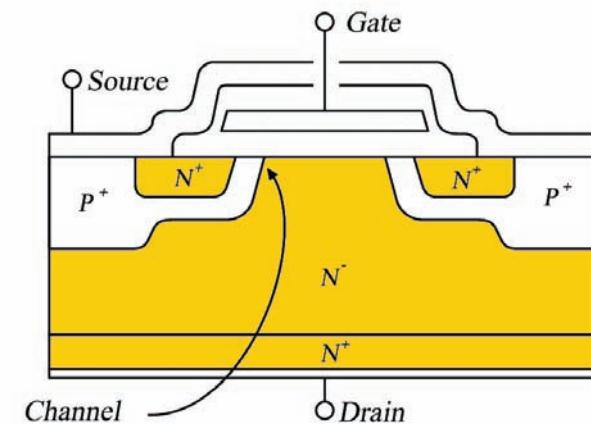
** The choice of MOSFETs vs IGBTs depends mainly on the application requirements

Fig. 6: MOSFETs and IGBTs Application Range

Structure of a MOSFET



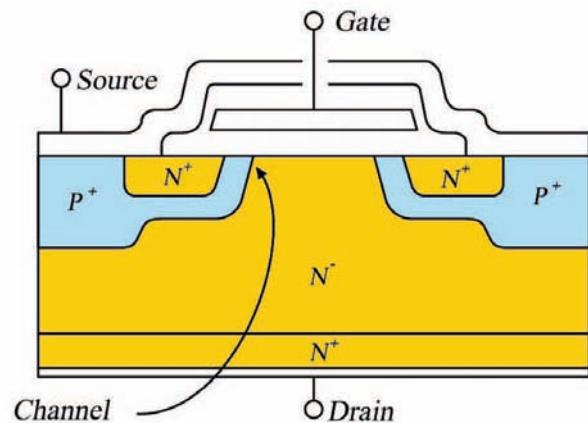
Structure of a MOSFET



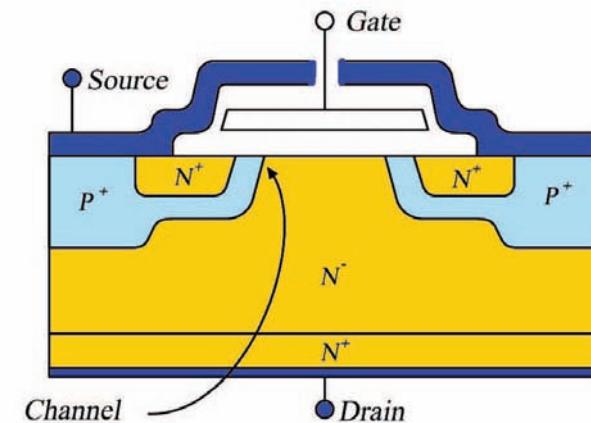
http://upload.wikimedia.org/wikipedia/commons/1/1e/dmos_cross_section_en.svg, Modified by Benoit Bidoggia

http://upload.wikimedia.org/wikipedia/commons/1/1e/Vdmos_cross_section_en.svg, Modified by Benoit Bidoggia

Structure of a MOSFET



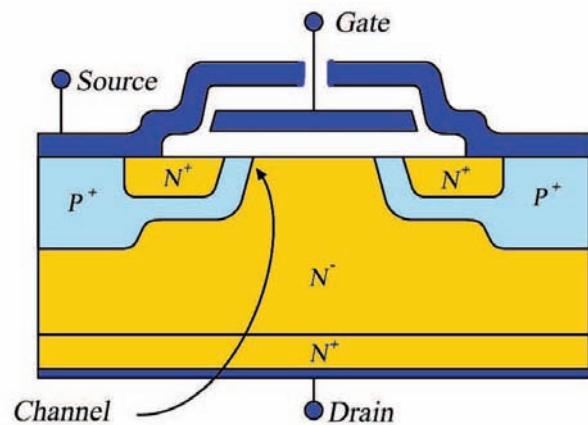
Structure of a MOSFET



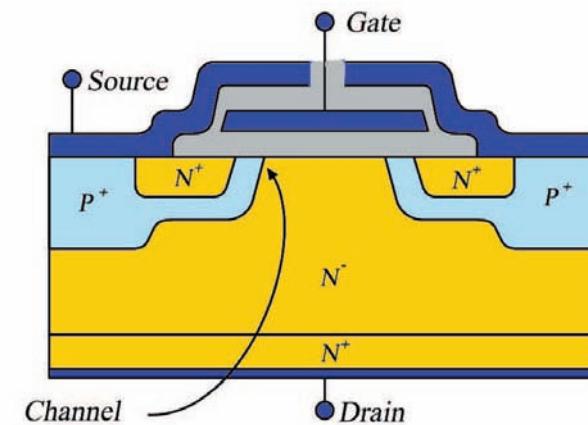
http://upload.wikimedia.org/wikipedia/commons/1/1e/dmos_cross_section_en.svg, Modified by Benoit Bidoggia

http://upload.wikimedia.org/wikipedia/commons/1/1e/Vdmos_cross_section_en.svg, Modified by Benoit Bidoggia

Structure of a MOSFET



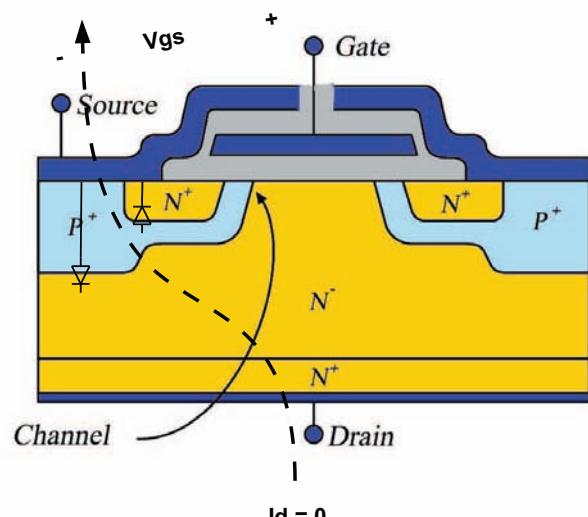
Structure of a MOSFET



http://upload.wikimedia.org/wikipedia/commons/1/1e/dmos_cross_section_en.svg, Modified by Benoit Bidoggia

Operation of a MOSFET

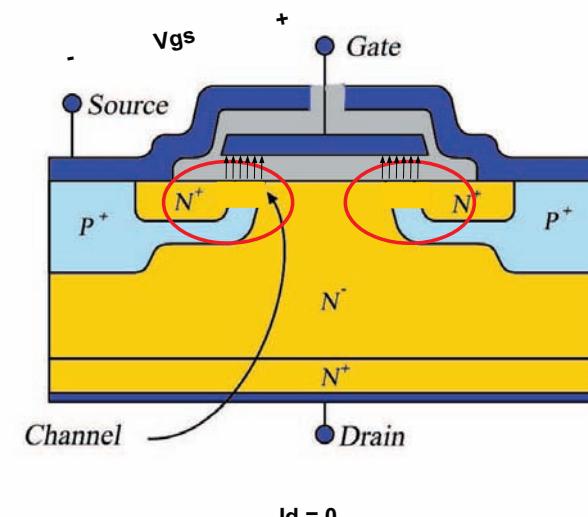
$$V_{gs} < V_{th} \Rightarrow OFF$$



http://upload.wikimedia.org/wikipedia/commons/1/1e/Vdmos_cross_section_en.svg, Modified by Benoit Bidoggia

Operation of a MOSFET

$$V_{gs} > V_{th} \Rightarrow On$$

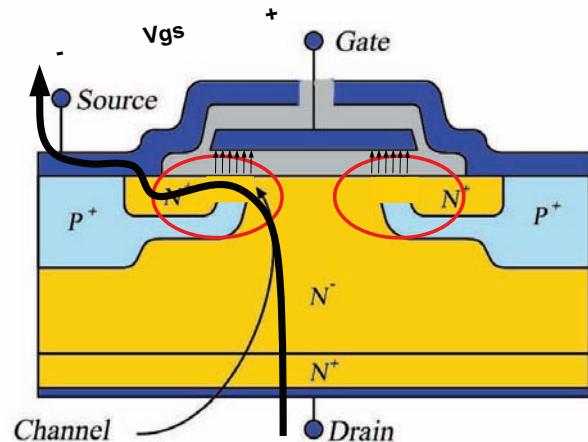


http://upload.wikimedia.org/wikipedia/commons/1/1e/dmos_cross_section_en.svg, Modified by Benoit Bidoggia

http://upload.wikimedia.org/wikipedia/commons/1/1e/Vdmos_cross_section_en.svg, Modified by Benoit Bidoggia

Operation of a MOSFET

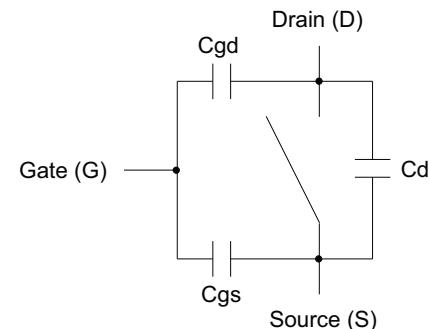
$V_{gs} > V_{th} \Rightarrow On$



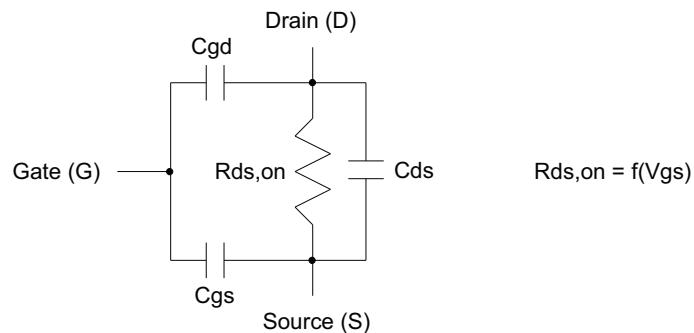
$$I_d = 0$$

http://upload.wikimedia.org/wikipedia/commons/1/1e/Vdmos_cross_section_en.svg, Modified by Benoit Bidoggia

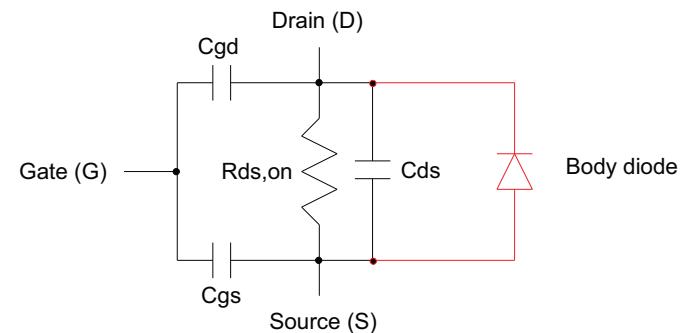
Off behavior ($V_{gs} < V_{th}$)



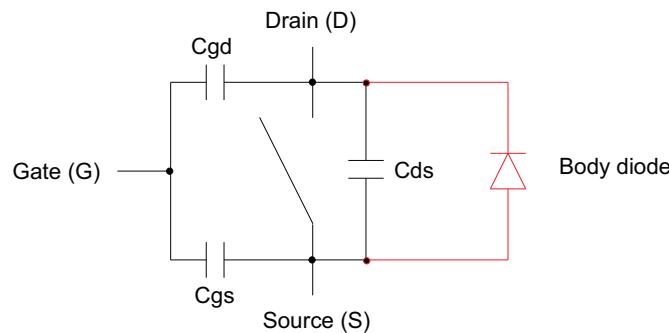
On behavior ($V_{gs} > V_{th}$)



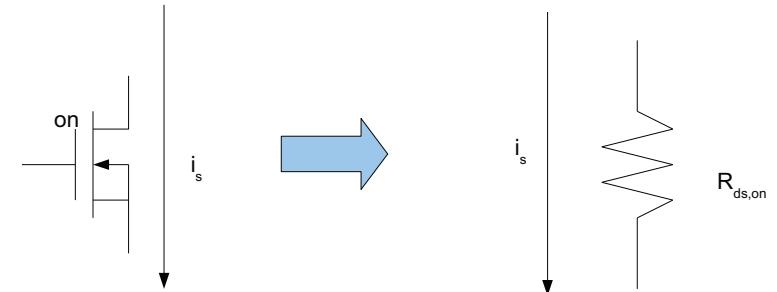
On behavior ($V_{gs} > V_{th}$)



Off behavior ($V_{gs} < V_{th}$)



Conduction losses



$$P_s = R_{ds,on} * i_{s,rms}^2$$

MOSFETs

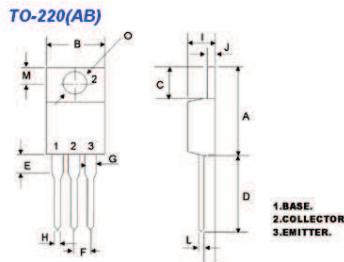
- Two types:
 - N-channel (most commonly used)
 - P-channel (less commonly used)
- Manufacturers:
 - International Rectifiers www.irf.com
 - Microsemi www.microsemi.com
 - many others...

Criteria

- Mosfet's breakdown voltage $V_{DSS} > |V_{S,max}|$ (with margin)
- Mosfet's max drain current $I_D < I_{S,max}$ (with margin)
- $R_{DS,on}$ "low enough"
 - Related to power losses
 - Temperature can be higher than 25 °C
 - Package/Modules
 - Cost

TO220 Package

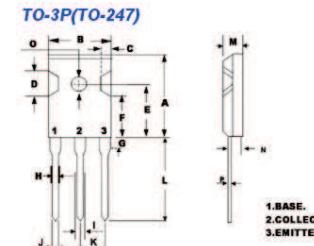
- Through hole component



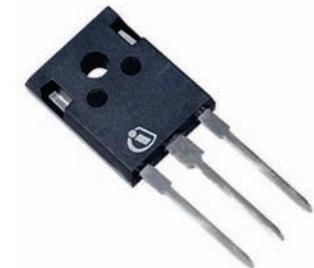
<http://www.mospec.com.tw/package.htm>

TO247 Package

- Through hole component



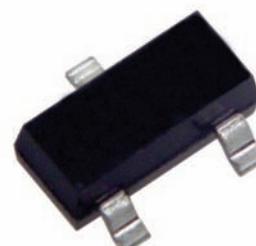
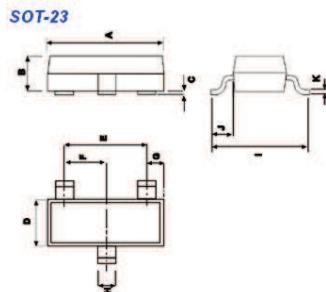
DIM	MILLIMETERS
A	20.63 22.38
B	15.38 16.20
C	1.90 2.70
D	5.10 6.10
E	14.81 15.22
F	11.72 12.84
G	4.20 4.50
H	1.82 2.46
I	2.92 3.23
J	0.89 1.53
K	5.26 5.66
L	18.50 21.50
M	4.68 5.36
N	2.40 2.80
O	3.25 3.65
P	0.55 0.70



<http://www.mospec.com.tw/package.htm>

SOT23 Package

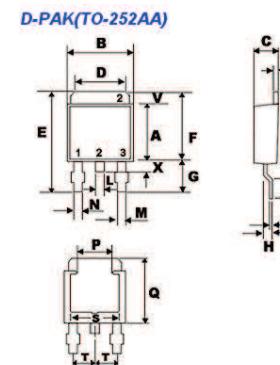
- Surface Mounted Technology (SMT)



<http://www.mospec.com.tw/package.htm>

D-PAK Package

- Surface Mounted Technology (SMT)



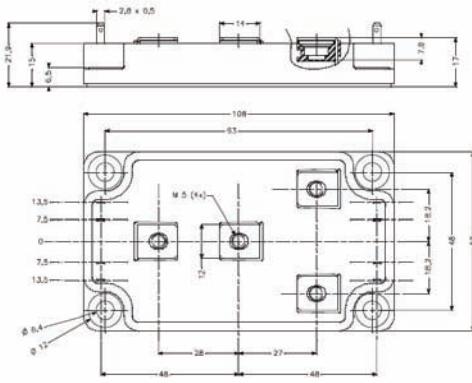
DIM	MILLIMETERS
A	5.40 5.60
B	6.30 6.70
C	2.20 2.40
D	5.20 5.50
E	9.00 10.00
F	6.60 7.00
G	2.40 3.00
H	0.90 1.50
I	0.45 0.50
J	0.45 0.60
K	0.90 1.50
L	0.70 0.90
M	0.50 0.70
N	0.60 0.90
P	2.70 3.10
Q	5.00 5.40
S	4.80 5.20
T	---
V	1.20 1.40
X	0.80 1.20



<http://www.mospec.com.tw/package.htm>

Specific modules

- Connection with screws (very high currents)



<http://www.microsemi.com/PackagePDFs/SP6Mechanical.pdf>



International
IR Rectifier

- Logic-Level Gate Drive
 - Advanced Process Technology
 - Isolated Package
 - High Voltage Isolation = 2.5KV(RMS) ⓒ
 - Sink to Lead Creepage Dist. = 4.8mm
 - Fully Avalanche Rated
 - Lead-Free

Description

Description

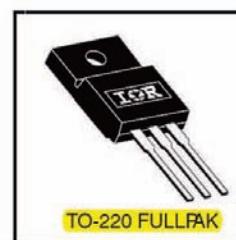
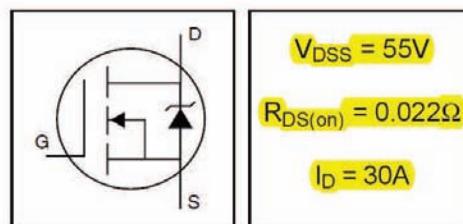
Fifth Generation HEXFETs from International Rectifier utilize advanced processing techniques to achieve extremely low on-resistance per silicon area. This benefit, combined with the fast switching speed and ruggedized device design that HEXFET Power MOSFETs are well known for, provides the designer with an extremely efficient and reliable device for use in a wide variety of applications.

The TO-220 Fullpak eliminates the need for additional insulating hardware in commercial-industrial applications. The moulding compound used provides a high isolation capability and a low thermal resistance between the tab and external heatsink. This isolation is equivalent to using a 100 micron mica barrier with standard TO-220 product. The Fullpak is mounted to a heatsink using a single clip or by a single screw fixing.

PD-95456

IRLIZ44NPbF

H HEXFET® Power MOSFET



Example of a MOSFET datasheet (www.irf.com)

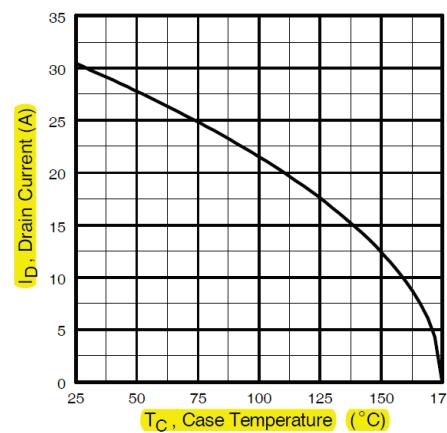
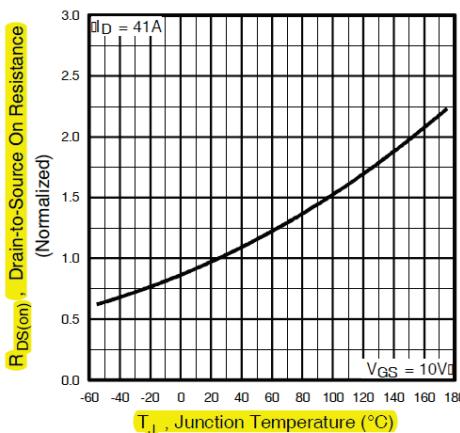
Absolute Maximum Ratings			
	Parameter	Max.	Units
$I_D @ T_C = 25^\circ\text{C}$	Continuous Drain Current, $V_{GS} @ 10\text{V}$	30	
$I_D @ T_C = 100^\circ\text{C}$	Continuous Drain Current, $V_{GS} @ 10\text{V}$	22	A
I_{DM}	Pulsed Drain Current ①⑥	160	
$P_D @ T_C = 25^\circ\text{C}$	Power Dissipation	45	W
	Linear Derating Factor	0.3	W/ $^\circ\text{C}$
V_{GS}	Gate-to-Source Voltage	± 16	V
E_{AS}	Single Pulse Avalanche Energy ②⑥	210	mJ
I_{AR}	Avalanche Current ①⑥	25	A
E_{AR}	Repetitive Avalanche Energy ①	4.5	mJ
dv/dt	Peak Diode Recovery dv/dt ③⑥	5.0	V/ns
T_J	Operating Junction and	-55 to +175	
T_{STG}	Storage Temperature Range		$^\circ\text{C}$
	Soldering Temperature, for 10 seconds	300 (1.6mm from case)	
	Mounting torque, 6-32 or M3 screw	10 lbf-in (1.1N·m)	

Thermal Resistance

	Parameter	Typ.	Max.	Units
R _{8JC}	Junction-to-Case	—	3.3	°C/W
R _{8JA}	Junction-to-Ambient	—	65	°C/W

Electrical Characteristics @ $T_J = 25^\circ\text{C}$ (unless otherwise specified)

	Parameter	Min.	Typ.	Max.	Units	Conditions
$V_{(\text{BR})\text{DSS}}$	Drain-to-Source Breakdown Voltage	55	—	—	V	$V_{GS} = 0V, I_D = 250\mu\text{A}$
$\Delta V_{(\text{BR})\text{DSS}/\Delta T_J}$	Breakdown Voltage Temp. Coefficient	—	0.070	—	V/ $^\circ\text{C}$	Reference to 25°C , $I_D = 1\text{mA}$ ®
$R_{DS(on)}$	Static Drain-to-Source On-Resistance	—	0.022	—	Ω	$V_{GS} = 10V, I_D = 17\text{A}$ ④
		—	0.025	—	Ω	$V_{GS} = 5.0V, I_D = 17\text{A}$ ④
		—	0.035	—	Ω	$V_{GS} = 4.0V, I_D = 14\text{A}$ ④
$V_{GS(\text{th})}$	Gate Threshold Voltage	1.0	—	2.0	V	$V_{DS} = V_{GS}, I_D = 250\mu\text{A}$
g_{fs}	Forward Transconductance	21	—	—	S	$V_{DS} = 25V, I_D = 25\text{A}$ ®
I_{DSS}	Drain-to-Source Leakage Current	—	—	25	μA	$V_{DS} = 55V, V_{GS} = 0V$
		—	—	250	μA	$V_{DS} = 44V, V_{GS} = 0V, T_J = 150^\circ\text{C}$
I_{GSS}	Gate-to-Source Forward Leakage	—	—	100	nA	$V_{GS} = 16V$
	Gate-to-Source Reverse Leakage	—	—	-100	nA	$V_{GS} = -16V$
Q_g	Total Gate Charge	—	—	48	nC	$I_D = 25\text{A}$
Q_{gs}	Gate-to-Source Charge	—	—	8.6	nC	$V_{DS} = 44V$
Q_{gd}	Gate-to-Drain ("Miller") Charge	—	—	25	nC	$V_{GS} = 5.0V$, See Fig. 6 and 13 ④®
$t_{d(on)}$	Turn-On Delay Time	—	—	11	ns	$V_{DD} = 28V$
t_r	Rise Time	—	—	84	ns	$I_D = 25\text{A}$
$t_{d(off)}$	Turn-Off Delay Time	—	—	26	ns	$R_G = 3.4\Omega, V_{GS} = 5.0V$
t_f	Fall Time	—	—	15	ns	$R_D = 1.1\Omega$. See Fig. 10 ④®
L_D	Internal Drain Inductance	—	4.5	—	nH	Between lead, 6mm (0.25in.) from package and center of die contact
L_S	Internal Source Inductance	—	7.5	—	nH	
C_{iss}	Input Capacitance	—	1700	—	pF	$V_{GS} = 0V$
C_{oss}	Output Capacitance	—	400	—	pF	$V_{DS} = 25V$
C_{rss}	Reverse Transfer Capacitance	—	150	—	pF	$f = 1.0\text{MHz}$, See Fig. 5®
C	Drain to Sink Capacitance	—	12	—	pF	$f = 1.0\text{MHz}$



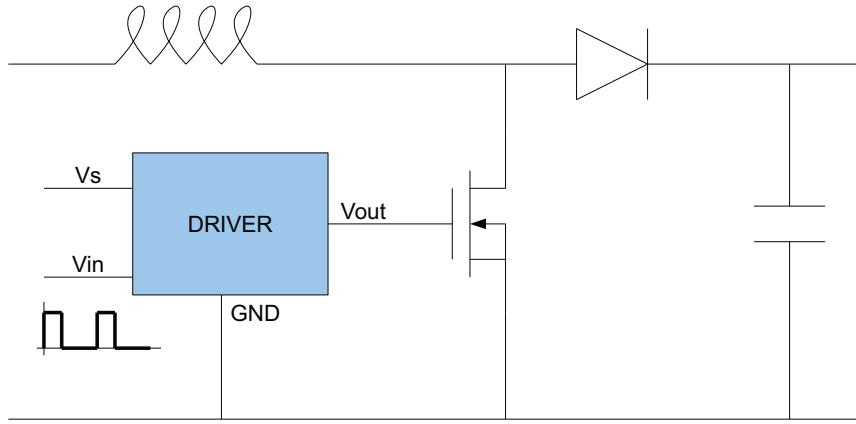
Source-Drain Ratings and Characteristics

	Parameter	Min.	Typ.	Max.	Units	Conditions
I_S	Continuous Source Current (Body Diode)	—	—	30	A	MOSFET symbol showing the integral reverse p-n junction diode.
I_{SM}	Pulsed Source Current (Body Diode) ④®	—	—	160	A	
V_{SD}	Diode Forward Voltage	—	—	1.3	V	$T_J = 25^\circ\text{C}, I_S = 17\text{A}, V_{GS} = 0V$ ④
t_{rr}	Reverse Recovery Time	—	80	120	ns	$T_J = 25^\circ\text{C}, I_F = 25\text{A}$
Q_{rr}	Reverse Recovery Charge	—	210	320	μC	$dI/dt = 100\text{A}/\mu\text{s}$ ④®
t_{on}	Forward Turn-On Time	Intrinsic turn-on time is negligible (turn-on is dominated by L_S+L_D)				

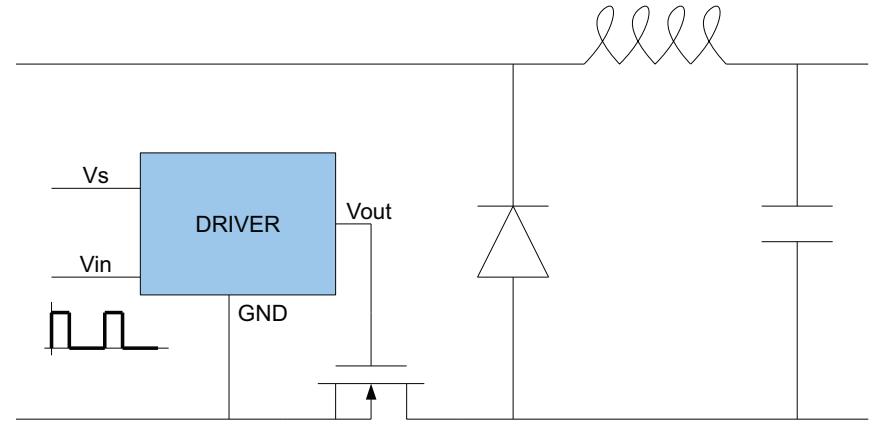
MOSFET Drivers

- Mosfet off if $V_{gs} < V_{th}$
- Mosfet turns on if $V_{gs} > V_{th}$
- Then, $R_{ds,\text{on}} = f(V_{gs}) \quad V_{gs} \uparrow \leftrightarrow R_{ds,\text{on}} \downarrow$
- Turning on: $V_{gs} = 0 \rightarrow 10 \text{ V}$ (charging eq. capacitor)
- Turning off: $V_{gs} = 10 \rightarrow 0 \text{ V}$ (discharging eq. cap.)
- MOSFET drivers provides energy to turn on/off

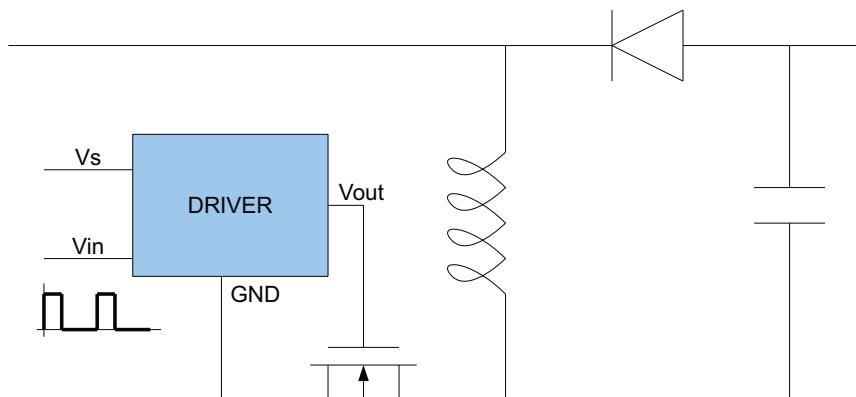
Example of connection of a driver (Boost)



Example of connection of a driver (Buck)



Example of connection of a driver (Buck-boost)



Drivers

- Manufacturers:
 - Microchip www.microchip.com
 - International rectifier www.irf.com
 - Maxim www.maxim-ic.com
 - Micrel www.micrel.com
 - many others...
- Peak current: $I_{pk} = \frac{dQ}{dt}$

Criteria

- High-side/Low-side
- Peak output current
- Max supply voltage
- Temperature can be higher than 25 °C
- Package/Modules
- Cost

Example of a MOSFET driver datasheet
(www.micrel.com)



MIC4126/27/28

Dual 1.5A-Peak Low-Side MOSFET Drivers in Advanced Packaging

General Description

The MIC4126, MIC4127, and MIC4128 family are highly-reliable dual 1.5A low-side MOSFET drivers fabricated on Micrel's BiCMOS/DMOS process. The devices feature low power consumption and high efficiency. The MIC4126/27/28 translate TTL or CMOS input logic levels to output voltage levels that swing within 25mV of the positive supply or ground whereas comparable bipolar devices are capable of swinging only to within 1V of the supply. The MIC4126/7/8 is available in three configurations: dual inverting, dual non-inverting, and complimentary output.

The MIC4126/27/28 offer pin-compatible as well as smaller footprint replacements for the MIC4426/27/28 with improved packaging and electrical performance. The MIC4126/27/28 are available in exposed pad, EPAD, SOIC-8L and MSOP-8L options as well as a small-size 3mm x 3mm MLF™-8L option. The devices have an input operating range of 4.5V to 20V.

Primarily intended for driving power MOSFETs, MIC4426/7/8 drivers are suitable for driving other loads (capacitive, resistive, or inductive) which require low-impedance, high peak current, and fast switching time. The devices can withstand up to 500mA of reverse current (either polarity) without latching and up to 5V noise spikes (either polarity) on ground pins.

Data sheets and support documentation can be found on Micrel's web site at www.micrel.com.

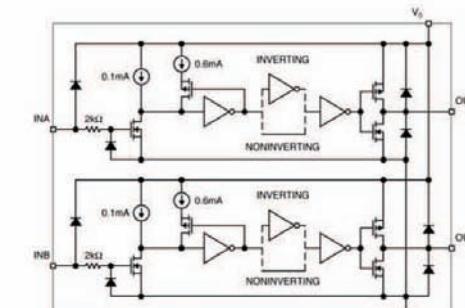
Features

- Dual 1.5A-peak drivers
- 4.5V to 20V operating range
- Exposed backside pad packaging reduces heat
 - ePAD SOIC-8L ($\theta_{JA} = 58^{\circ}\text{C}/\text{W}$)
 - ePAD MSOP-8L ($\theta_{JA} = 60^{\circ}\text{C}/\text{W}$)
 - 3mm x 3mm MLF™-8L ($\theta_{JA} = 60^{\circ}\text{C}/\text{W}$)
- Bipolar/CMOS/DMOS construction
 - 25mV maximum output offset from supply or ground
- Latch-up protection to >200mA reverse current
- Switches 1000pF in 25ns
- Logic-input threshold independent of supply voltage
- Logic-input protection to -5V
- 6pF typical equivalent input capacitance
- Dual inverting, dual non-inverting, and complementary configurations
- -40°C to +125°C operating junction temperature range

Applications

- DC/DC converters
- Motor drivers
- Clock line driver

Functional Diagram



MIC4126/27/28 Block Diagram

Absolute Maximum Ratings⁽¹⁾

Supply Voltage (V_S).....	+24V
Input Voltage (V_{IN}).....	$V_S + 0.3\text{V}$ to GND - 5V
Junction Temperature (T_J)	150°C
Storage Temperature	-65°C to +150°C
Lead Temperature (10 sec.)	300°C
ESD Rating, Note 3	

Operating Ratings⁽²⁾

Supply Voltage (V_S)	+4.5V to +20V
Temperature Range (T_J)	-40°C to +125°C
Package Thermal Resistance	
3X3 MLF™ θ_{JA}	60°C/W
EPAD MSOP-8L θ_{JA}	60°C/W
EPAD SOIC-8L θ_{JA}	58°C/W

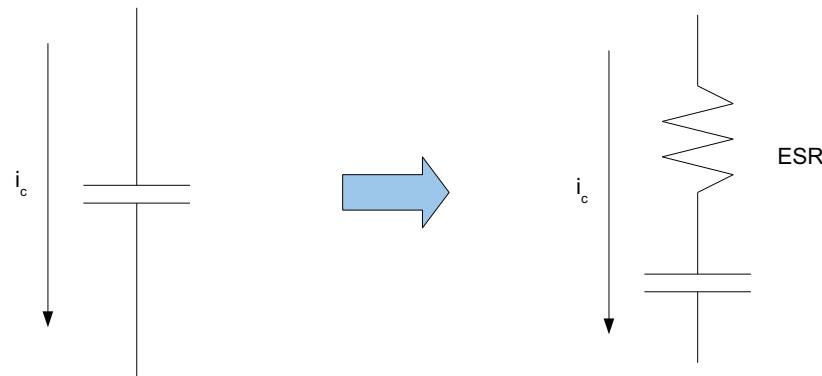
Capacitors

- One of the most unreliable components
- Types:
 - Aluminium electrolytic (cheap but unreliable)
 - Film (more expensive but more reliable)
 - Ceramic
 - Tantalum
- Manufacturers:
 - Kemet, AVX...

Criteria

- Rated voltage $> V_{c,max}$
- Maximum rms current $> I_{c,RMS,max}$
- Peak current $> I_{c,max}$
- ESR (Eq. Series Resistance) “low enough”
 - Related to power losses
- Cost

(Conduction) Losses



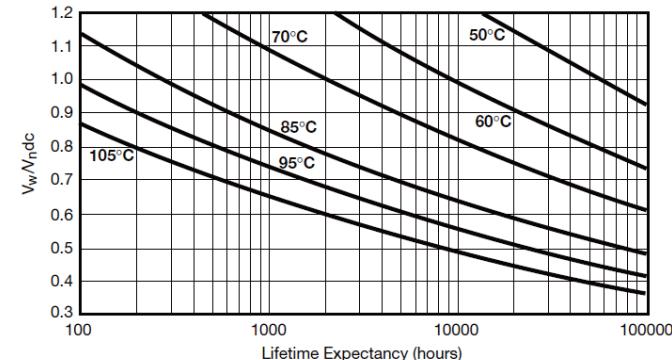
Example of a Capacitor datasheet
(www.avx.com)

$$P_c = ESR \cdot I_{c,rms}^2$$

RATINGS AND PART NUMBER REFERENCE – POLYESTER DIELECTRIC

Part Number	Capacitance (μ F)	Case Style	I_{max} max. (A)	R_s (m Ω)	R_{th} (°C/W)	Typical Weight (g)
V_{ndc} 75V Vrms max.: 45 volts Voltage Code: D						
FFB14D0336K--	33	PO	3	3	40.7	15
FFB24D0476K--	47	18	4.3	2	33.3	20
FFB34D0686K--	68	19	6.2	1.7	29.9	25
FFB44D0826K--	82	26	7.4	1.6	26.7	32
FFB54D0117K--	110	R68 (2 terminals)	10	1.4	22.9	40
FFB54D0117KJC	110	R68 (4 terminals)	10	1.4	22.9	40
V_{ndc} 100V Vrms max.: 60 volts Voltage Code: E						
FFB14E0206K--	20	PO	2.6	3	40.5	15
FFB24E0276K--	27	18	3.5	2.5	33.3	20
FFB34E0396K--	39	19	5	2	29.8	25
FFB44E0476K--	47	26	6	1.7	26.6	32
FFB54E0686K--	68	R68 (2 terminals)	9	1.4	22.8	40
FFB54E0686KJC	68	R68 (4 terminals)	9	1.4	22.8	40
V_{ndc} 300V Vrms max.: 90 volts Voltage Code: H						
FFB14H0755K--	7.5	PO	2.4	16	40.7	15
FFB24H0116K--	11	18	3.6	11	33.5	20
FFB34H0166K--	16	19	5.2	8	29.9	25
FFB44H0186K--	18	26	6	7	27.1	32
FFB54H0276K--	27	R68 (2 terminals)	9	5	22.9	40
FFB54H0276KJC	27	R68 (4 terminals)	9	5	22.9	40

LIFETIME EXPECTANCY vs VOLTAGE AND HOT SPOT TEMPERATURE – POLYESTER DIELECTRIC

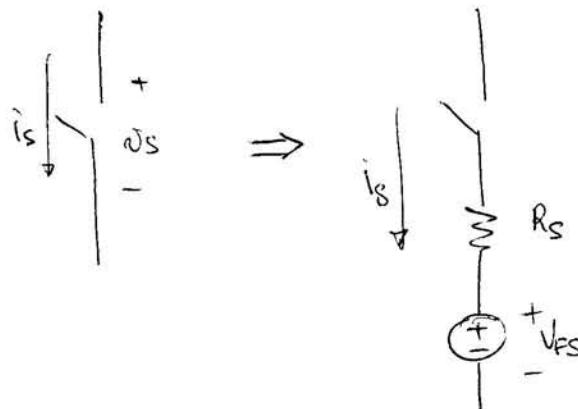


V_w = Permanent working or operating DC voltage.

LECTURE 5

Conduction losses

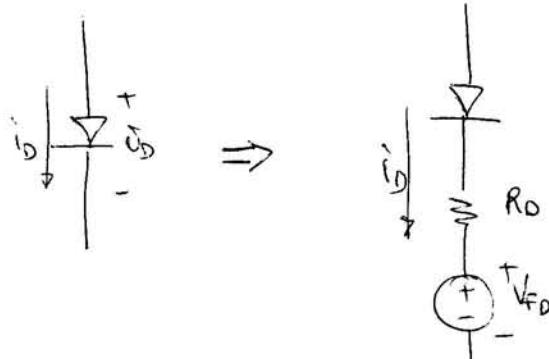
Switch



$$P_S = R_S I_{S, RMS}^2 + V_{FS} \langle i_s \rangle$$

[for a mosfet: $V_{FS} = 0$
 $R_S = R_{DS, ON}$]

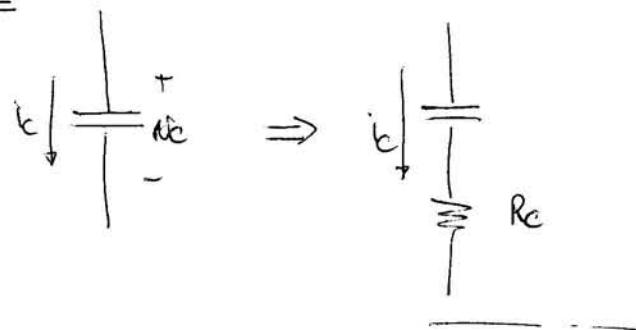
Diode



$$P_D = R_D I_{D, RMS}^2 + V_{FD} \langle i_D \rangle$$

[generally $R_D \approx 0$]

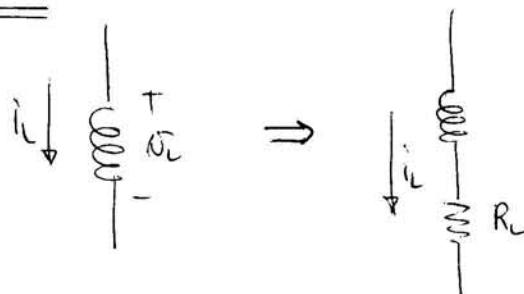
Capacitor



$$P_C = R_C \cdot I_{C, RMS}^2$$

[R_C is generally called ESR]

Inductor

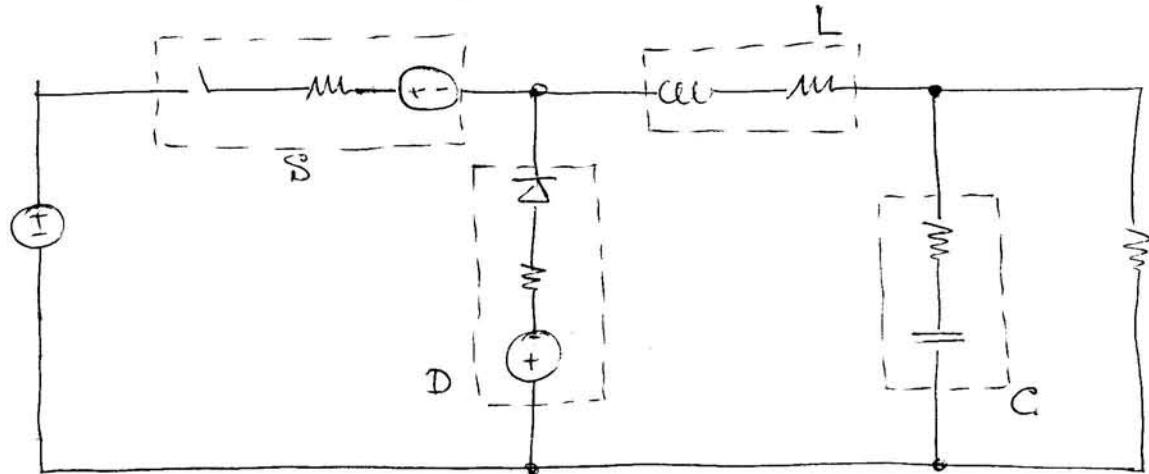


$$P_L = R_L \cdot I_{L, RMS}^2$$

$$P_T = P_S + P_D + P_C + P_L$$

Modified circuits

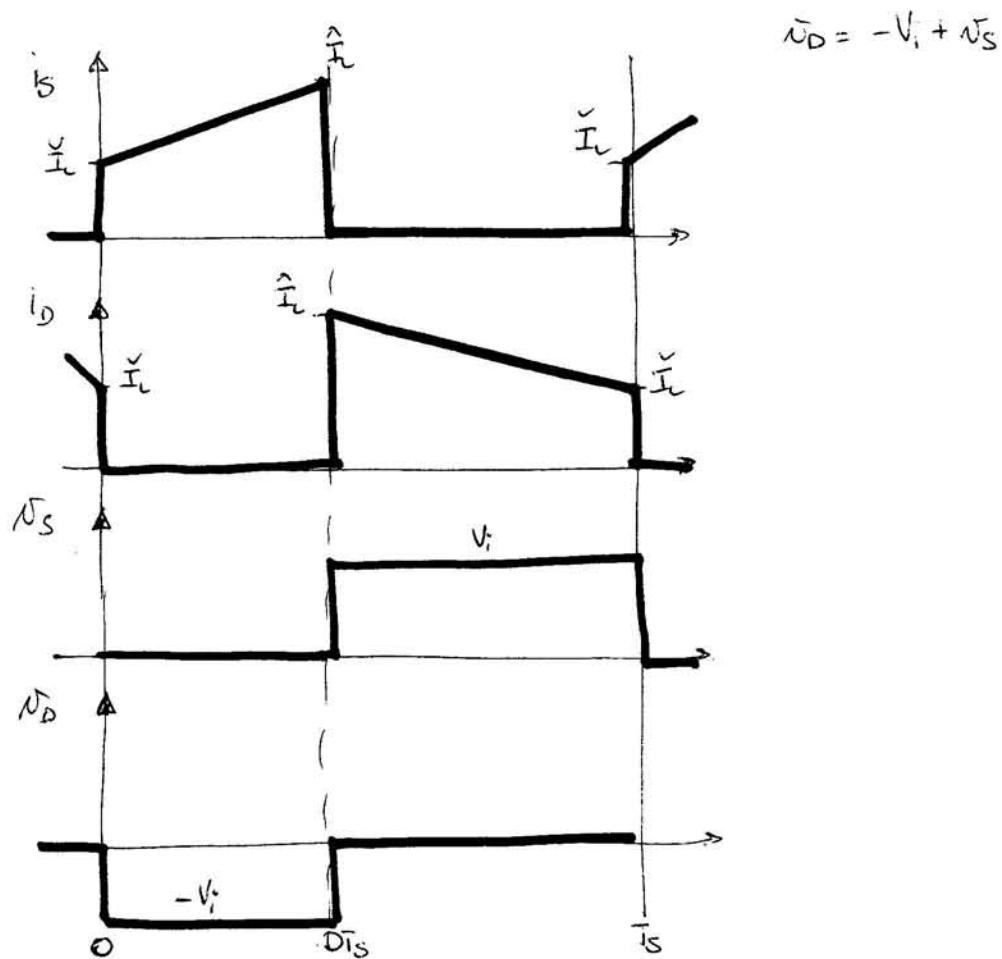
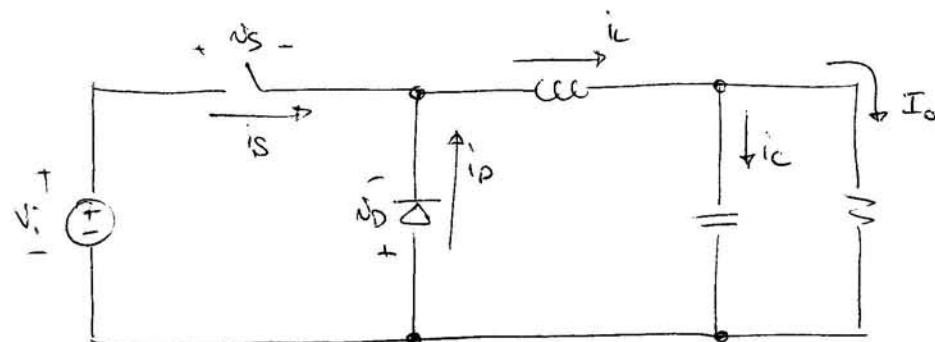
Buck



Hyp: V_{FS} , V_{FD} , R_S , R_D , R_L , R_C don't significantly influence the behavior of the circuit.

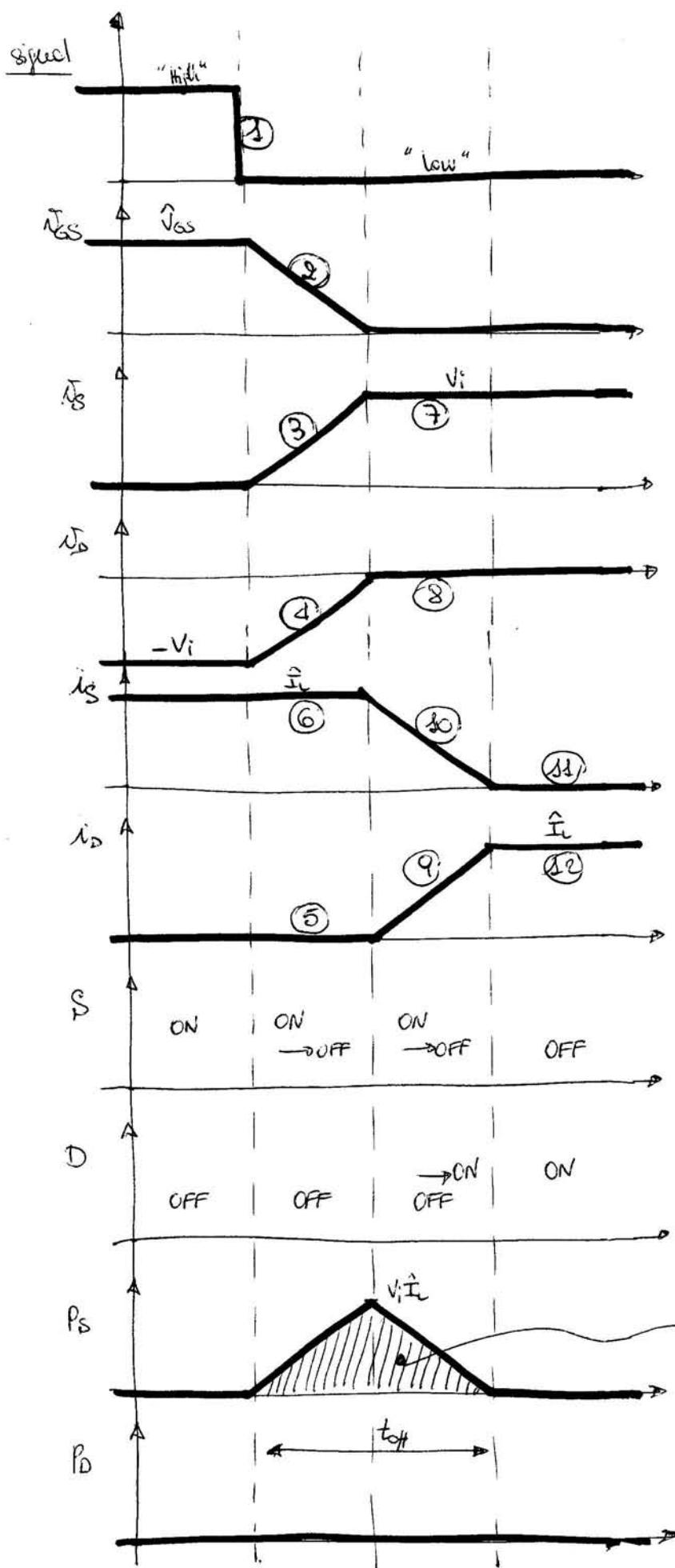
Switching losses

- Origins:
 - it takes time to turn off and on switches and diodes
 - power diodes need an extra negative current to be turned off
- Simplified analysis
- Switching losses depend on the circuit: ex w/ buck.



S TURN-OFF } transient
 D TURN-ON } transient

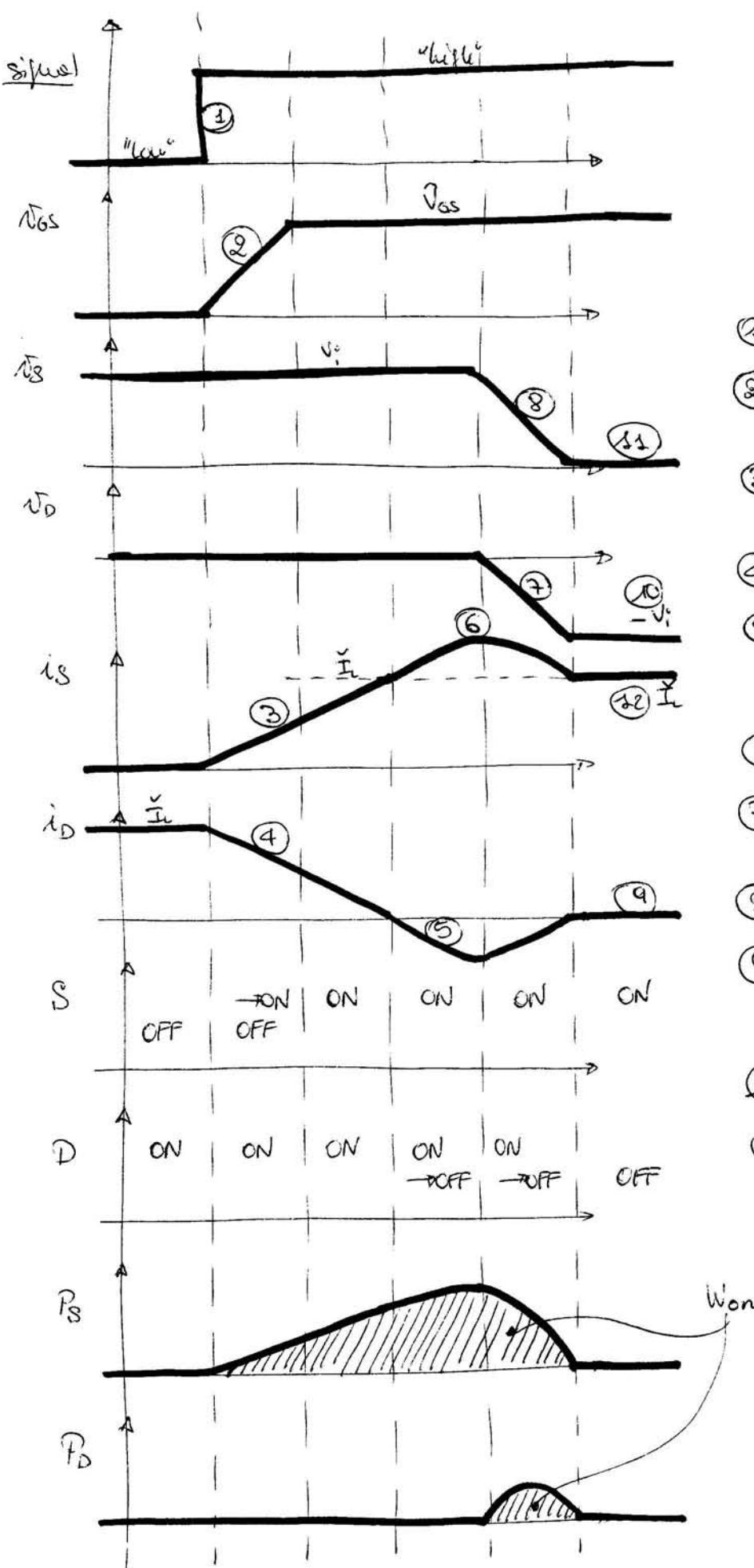
S TURN-ON } transient
 D TURN-OFF } transient

Switch turn-off/Diode turn-on transient


- ① signal "High" \rightarrow "Low"
- ② Driver extracts charges
 $\hookrightarrow V_{DS}$ decreases linearly
- ③ R_{ds} increases, $V_S = R_{ds} \cdot \hat{I}_L$ increases
- ④ $\bar{V}_D = -(V_i - V_S) = -V_i + V_S$
- ⑤ if $\bar{V}_D < 0 \Rightarrow D_{off} \Rightarrow i_D = 0$
- ⑥ $i_S + i_D = i_L \Rightarrow i_S = i_L - \hat{I}_L$
- ⑦ $\bar{V}_S = V_i$
- ⑧ $\bar{V}_D = 0$: diode can turn-on
- ⑨ diode turns on
- ⑩ $i_S = i_L - i_D$
- ⑪ $i_S = 0 \rightarrow S_{off}$
- ⑫ $i_D = \hat{I}_L \rightarrow D$ fully on

$$W_{off} = \frac{1}{2} V_i \cdot \hat{I}_L \cdot t_{off}$$

Switch turn-on/Diode turn-off transient



- ① Signal "low" \rightarrow "high"
- ② Driver injects charges \rightarrow V_{GS} increases linearly
- ③ Switch starts conducting $\rightarrow i_S$ increases
- ④ $i_D = I_L - i_S$
- ⑤ i_D becomes negative to release all the charges $\rightarrow i_S > I_L$
- ⑥ the diode starts opening $\rightarrow |V_D|$ increases
- ⑦ $V_S = V_D + V_i \rightarrow V_S$ increases
- ⑧ $i_D = 0$ recovery finished $\rightarrow D$ is fully off
- ⑨ $V_D = -V_i$
- ⑩ $i_S = I_L \rightarrow S$ is fully on

$$W_T = W_{on} + W_{off} + W_{anc}$$

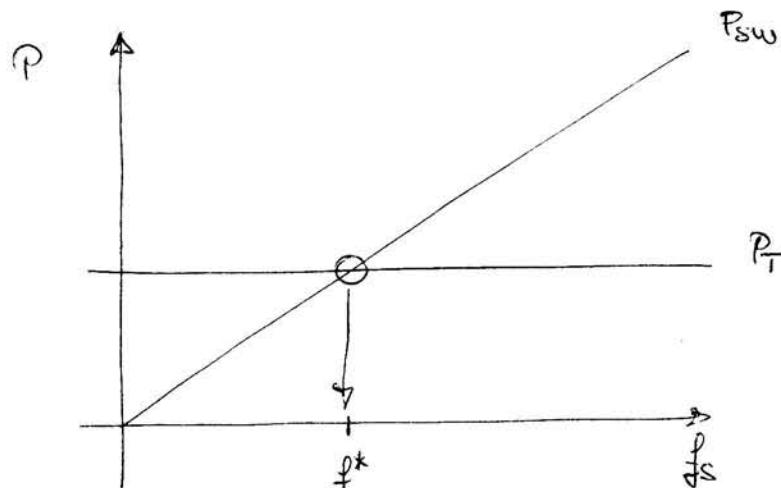
W_{anc} : ancillary losses
(mosfet drivers)

$$P_{sw} = \frac{W_t}{T_S} = W_t \cdot f_s$$

Total losses

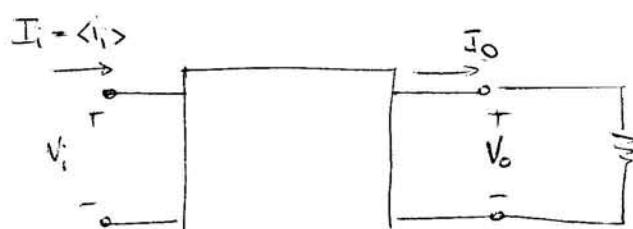
$$P_L = P_T + P_{sw}$$

Critical frequency



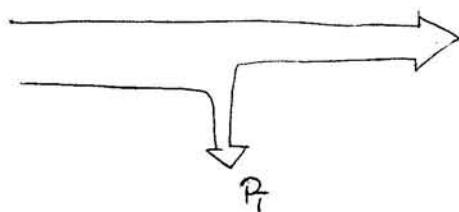
"Critical frequency"

Efficiency



$$P_o = V_o I_o$$

$$P_i = V_i I_i$$

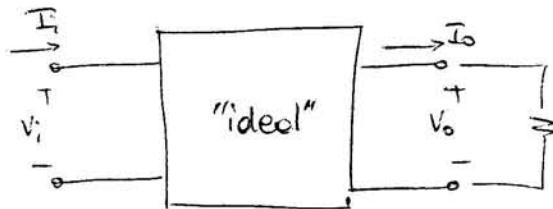


$$P_i = P_o + P_{TL}$$

$$\eta = \frac{P_o}{P_i} = \frac{P_o}{P_o + P_{TL}}$$

Average input voltage

Theoretically : $I_i = \langle i_i \rangle = D I_o$



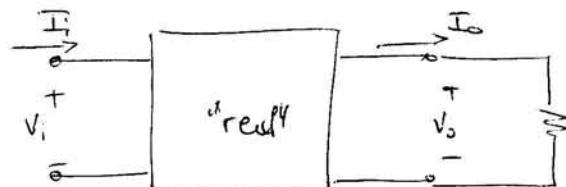
$$V_o = D V_i$$

$$P_i = P_o + P_{TL} = P_o$$

$$V_i I_i = V_o I_o = D V_i I_o$$

$$I_i = D I_o$$

Actually
(trick)



$$V_o = D V_i$$

$$P_i = P_o + P_{TL}$$

$$V_i I_i = V_o I_o + P_{TL}$$

$$I_i = \frac{V_o}{V_i} I_o + \frac{P_{TL}}{V_i} = D I_o + \boxed{\frac{P_{TL}}{V_i}}$$

Magnetism

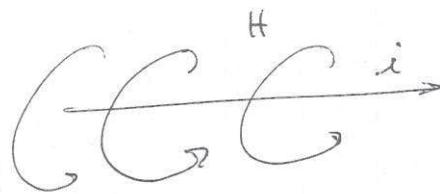
H

A current "i" generates a magnetic field " \vec{H} "

$$H \propto i$$

$$i [A] \quad H \left[\frac{A}{m} \right]$$

Magnetic field of a conductor with current



Right hand rule

B

Magnetic field in different materials ~~because~~ has different effects: → "Flux density" or "B-field"

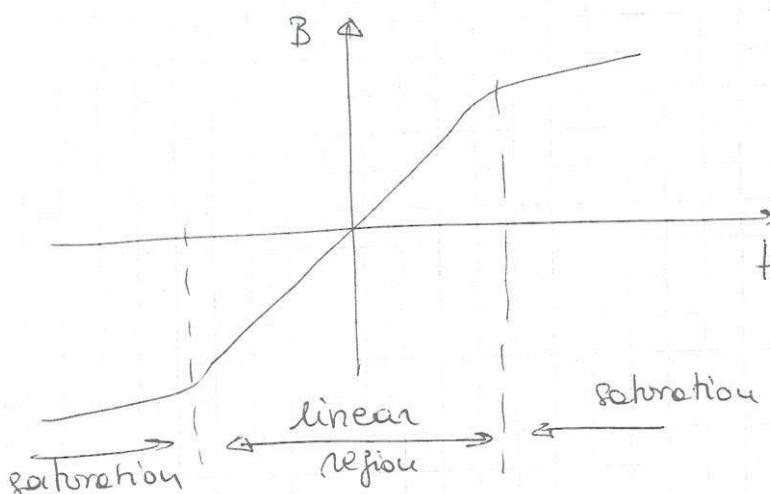
$$B = \mu H = \mu_0 \mu_r H$$

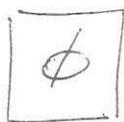
μ_0 : permeability of vacuum $4\pi \cdot 10^{-7} \frac{H}{A}$

μ_r : absolute permeability

μ_r : relative permeability

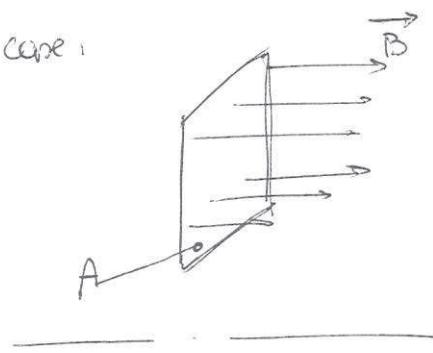
} property of the medium





Flux : always referred to a surface

perpendicular case:

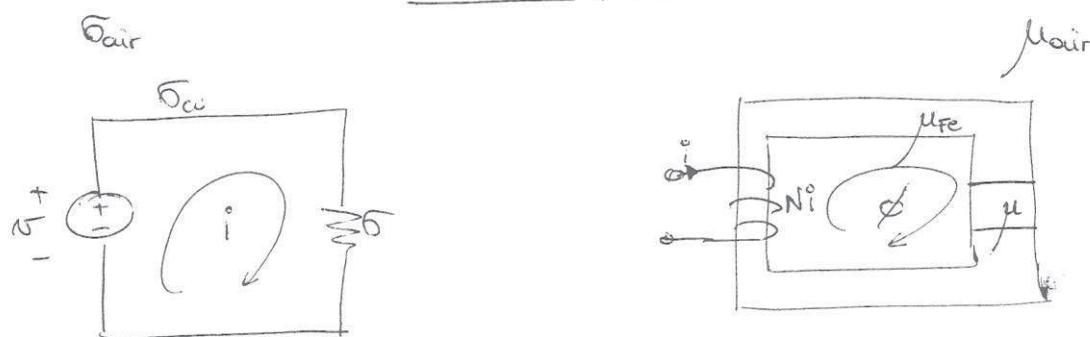


$$\phi = A \cdot B$$

$$= A \cdot \mu H$$

$$= A \cdot \mu_0 \mu_r H \propto i$$

Similarities between electric
and magnetic circuits



$$\sigma_{co} \gg \sigma_{air}$$

$$\sigma \ll \sigma_{co}$$

} Conductivity

i

Current

V

Voltage

$$R = \frac{V}{i}$$

Resistance

$$G = \frac{1}{R}$$

Conductance

$$\mu_{fe} \gg \mu_{air}$$

$$\mu < \mu_{fe}$$

} Permeability

φ

Flux

Ni

Muf

$$R = \frac{Ni}{\phi}$$

Reluctance

$$P = \frac{1}{R}$$

Permeance

$$\sum i = 0 \text{ @ nodes}$$

KVL

$$\sum \phi = 0$$

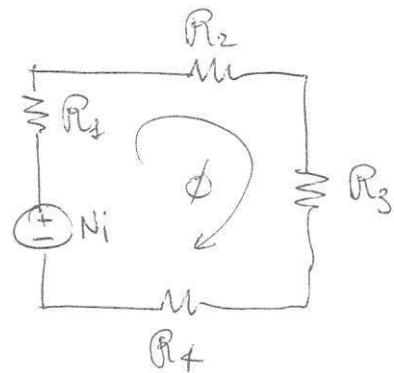
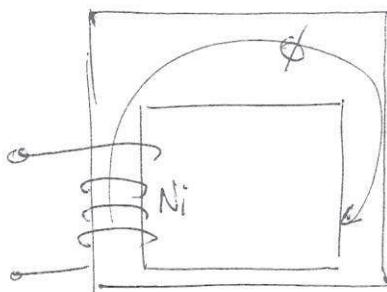
$$\sum V = 0 \text{ on loops}$$

KCL

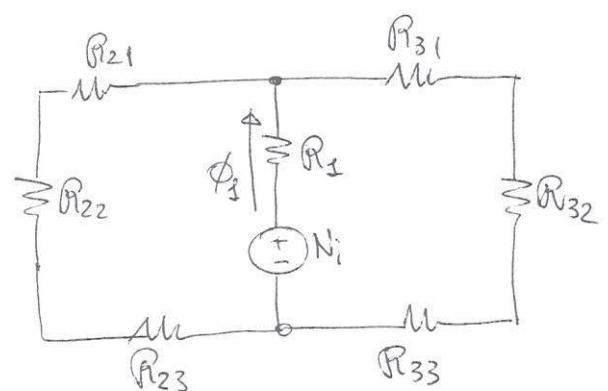
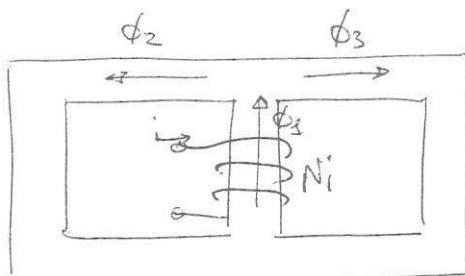
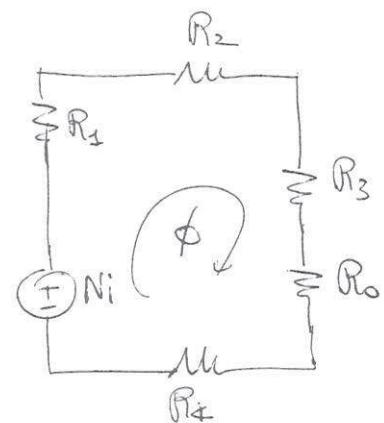
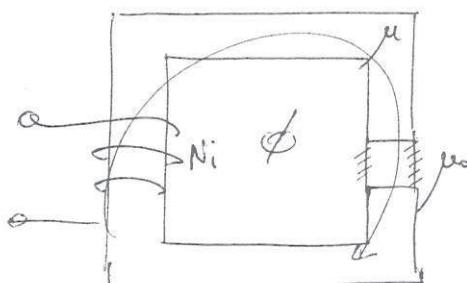
$$\sum N_i = 0$$

$$R = \rho \frac{l}{S} = \frac{\rho}{\sigma} \frac{l}{S}$$

$$R = \frac{1}{\mu} \frac{l}{S}$$

Ex

$$\phi = \frac{Ni}{R_1 + R_2 + R_3 + R_4}$$

ExEx (important)

$$R = \frac{l}{\mu} \frac{l}{S}$$

$$R_o = \frac{1}{\mu_0} \frac{l}{S}$$

$$\mu \gg \mu_0$$

$$R \ll R_o$$

$$\phi = \frac{Ni}{R_o + R_1 + R_2 + R_3 + R_4} \approx \frac{Ni}{R_o}$$

Inductance

$$\text{Def: } L = \frac{N\phi}{i}$$

$$R = \frac{Ni}{\phi} \rightarrow \phi = \frac{Ni}{R}$$

$$\hookrightarrow L = \frac{N}{\gamma} \left[\frac{Ni}{R} \right] = \frac{N^2}{R} \quad \boxed{L = \frac{N^2}{R}}$$

Inductance is a property of:

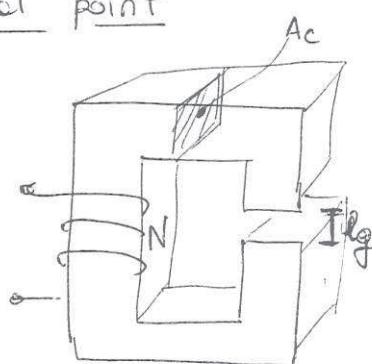
- the magnetic circuit (R)
- the number of turns

INDUCTOR DESIGN

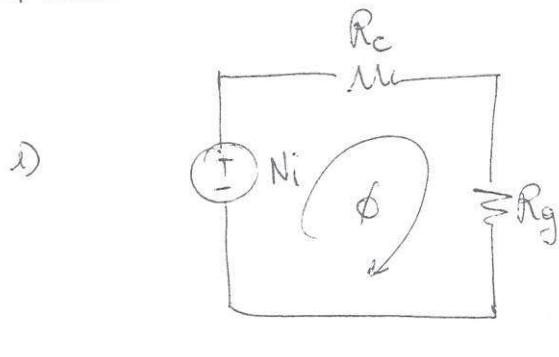
Starting point

- Desired inductance . L
- Maximum current: \hat{I}_L
- RMS current: $I_{L,RMS}$
- Maximum copper losses: $P_{L,W}$
- Winding resistivity ρ
- Maximum B-field \hat{B}
- Fill factor (winding technique) k_w [< 1]

Arrival point



- Core geometry
- Number of turns N
- Air gap length lg
- Conductor section A_w

Equation reminder

$$\phi = \frac{N_i}{R_c + R_g} \approx \frac{N_i}{R_g}$$

$$R_g = \frac{1}{\mu_0} \frac{l_g}{A_c}$$

2) $\phi = B \cdot A_c$

The four Conditions① Maximum flux density

$$N_i = \phi R_g = B A_c R_g$$

$$\hookrightarrow N_i^{\hat{}} = \hat{B} A_c R_g = \hat{B} \frac{1}{\mu_0} \frac{l_g}{A_c} = \frac{\hat{B} R_g}{\mu_0}$$

$(N_i)^{\hat{}} = \hat{B} \frac{R_g}{\mu_0}$

② Inductance

$$L = \frac{N^2}{R_g} = \frac{\mu_0 A_c}{l_g} N^2$$

$L = \frac{\mu_0 (A_c N)^2}{l_g}$

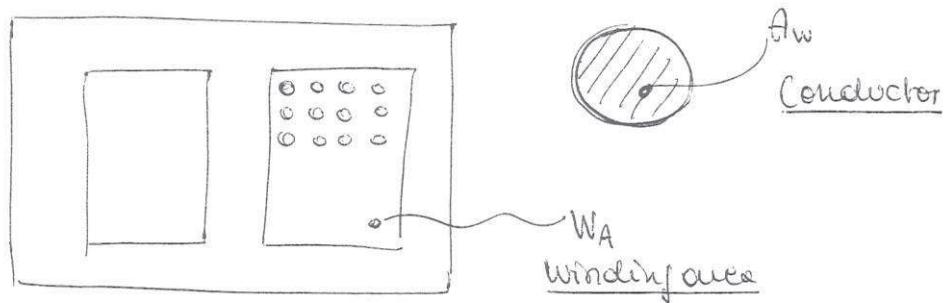
③ Winding resistance

$$R = p \frac{l_w}{A_w} = p \frac{N l_T}{A_w}$$

l_T : mean length per turn
(function of core geometry)

$R = p \frac{(N l_T)}{A_w}$

④ Winding area



$$K_U W_A \geq N A_w$$

$K_U \cdot \text{fill factor}$

[$K_U \approx 0.5$ for low-voltage inductors]

Derivation of the expressions

$$\left\{ \begin{array}{l} \hat{N} I = \frac{\hat{B}}{\mu_0} \lg \\ L = \frac{\mu_0 A_c (\hat{N}^2)}{\lg} \end{array} \right. \rightarrow \begin{array}{l} N = \frac{\hat{B}}{\hat{I}} \frac{\lg}{\mu_0} \\ L = \cancel{\mu_0} A_c \frac{\hat{B}^2}{\hat{I}^2} \frac{\lg}{\mu_0} \end{array}$$

$$\Rightarrow \boxed{\lg = \frac{L \hat{I}^2 \mu_0}{A_c \hat{B}^2}}$$

$$N = \frac{\hat{B}}{\hat{I}} \frac{\lg}{\mu_0} = \frac{\hat{B}}{\hat{I}} \cancel{\frac{1}{\mu_0}} \frac{L \hat{I}^2 \mu_0}{A_c \hat{B}^2} = \frac{L \hat{I}}{A_c \hat{B}}$$

$$\boxed{N = \frac{L \hat{I}}{A_c \hat{B}}}$$

$$R = \frac{\rho N l_r}{A_w} \rightarrow \boxed{A_w = \frac{\rho N l_r}{R}}$$

$$K_U W_A \geq N A_w$$

$$\geq N \frac{\rho N l_r}{R} = \frac{\rho N^2 l_r}{R} = \frac{\rho l_r}{R} \left[\frac{L \hat{I}}{A_c \hat{B}} \right]^2 = \frac{\rho l_r}{R} \frac{L^2 \hat{I}^2}{A_c^2 \hat{B}^2}$$

$$K_U W_A \geq \frac{\rho l_r}{R} \frac{L^2 \hat{I}^2}{A_c^2 \hat{B}^2}$$

$$\frac{W_A A_c^2}{R_T} \geq \frac{L^2 I^2 p}{B^2 R K_u}$$

Depends on the geometry Depends on the problem.

$$K_g = \frac{W_A A_c^2}{R_T}$$

$$K_g' = \frac{L^2 I^2 p}{B^2 R K_u}$$

- Finding a geometry whose $K_g \geq \frac{L^2 I^2 p}{B^2 R K_u}$.

Then we can find the rest.

Precision: ~~for~~ Magnetic core with distributed gap.

The manufacturer gives the permeance of the core, often indicated with A_L .

$$A_L = P = \frac{1}{R} = \frac{\mu_0 A_c}{l_g} \quad \cancel{1/l_g} / \cancel{\mu_0 A_c}$$

$$A_L = \mu_0 A_c \left[\frac{A_c B^2}{L I^2 \mu_0} \right] = \frac{A_c^2 B^2}{L I^2}$$

$$A_L = \frac{A_c^2 B^2}{L I^2}$$

(instead of using l_g)

SIZING PROCEDURE

(with example)

$$\hat{I}_L = 76 \text{ A}$$

$$I_{LANS} = 43 \text{ A}$$

$$L = 2,4 \mu\text{H}$$

$$T = 100^\circ\text{C} \rightarrow \rho_{\text{core}} = 23 \cdot 10^{-9} \Omega \cdot \text{m} \quad \text{①}$$

$$f_s = 60 \text{ kHz}$$

$$R = 0,14 \text{ m}\Omega$$

$$k_J = 0,5$$

DCR operation

① Switching frequency → material [site: Ferroxcube]

$$\text{Ex: } 300\varphi \rightarrow B_{\text{sat}} = 38 \text{ mT} \rightarrow \hat{B} = 250 \text{ mT}$$

~~1472186800000~~

② Finding k_g minimum

$$k_g^* = \frac{\rho L^2 \hat{I}^2}{\hat{B}^2 R k_u} = \frac{23 \cdot 10^{-9} (2,4 \cdot 10^{-6})^2 \cdot 76^2}{(250 \cdot 10^{-3})^2 \cdot 0,14 \cdot 10^{-3} \cdot 0,5}$$

$$= 8,75 \cdot 10^{-10}$$

③ Finding the core whose $k_g \geq k_g^*$

$$k_g = \frac{A_c^2 W_A}{l_T}$$

A_c : cross-sectional area

W_A : core window area

l_T : mean length per turn

From Femoxcube site, we try with

E47/20/16

$$W_A = 130 \cdot 10^{-6} \text{ m}^2$$

$$l_T = 93,3 \cdot 10^{-3} \text{ m}$$

$$A_C = 234 \cdot 10^{-6} \text{ m}^2$$

$$kg = \frac{A_C^2 W_A}{l_T} = 7,63 \cdot 10^{-11} \rightarrow \text{too small (but close)}$$

→ we try with the next

E55/28/21

$$W_A = 250 \cdot 10^{-6} \text{ m}^2$$

$$l_T = 116 \cdot 10^{-3} \text{ m}$$

$$A_C = 353 \cdot 10^{-6} \text{ m}^2$$

$$kg = \frac{A_C^2 W_A}{l_T} = 2,69 \cdot 10^{-10} \rightarrow \underline{\text{OK}}$$

E55/28/21

(the core has been chosen)

④ Finding A_L (or lg)

$$lg = \frac{L \hat{I}^2 \mu_0}{A_C \hat{B}^2}$$

$$lg = \frac{2,4 \cdot 10^{-6} \cdot 76^2 \cdot 4\pi \cdot 10^{-7}}{353 \cdot 10^{-6} \cdot 250^2 \cdot 10^{-6}} = 0,79 \mu\text{H}$$

$$lg_1 = 0,7 \mu\text{H}$$

$$lg_2 = 0,8 \mu\text{H}$$

$$l_1 = \frac{lg_1 \cdot A_C \cdot \hat{B}^2}{\hat{I}^2 \cdot \mu_0} = \frac{0,7 \cdot 10^{-3} \cdot 353 \cdot 10^{-6} \cdot 250^2 \cdot 10^{-6}}{76^2 \cdot 4\pi \cdot 10^{-7}} = 2,13 \mu\text{H}$$

$$l_2 = \frac{lg_2 \cdot A_C \cdot \hat{B}^2}{\hat{I}^2 \cdot \mu_0} = \frac{0,8 \cdot 10^{-3} \cdot 353 \cdot 10^{-6} \cdot 250^2 \cdot 10^{-6}}{76^2 \cdot 4\pi \cdot 10^{-7}} = 2,43 \mu\text{H}$$

if CCR \rightarrow $l_{g2} \& L_2 = 2,4 \mu\text{H}$

if DCR \rightarrow $l_{g2} \& L_2 = 2,1 \mu\text{H}$

$$L_1 = 2,1 \mu\text{H} \& l_{g1} = 0,7 \text{ mm}$$

⑤ Number of turns

$$N = \frac{L \hat{I}}{A_C \hat{B}} = \frac{2,1 \cdot 10^{-6} \cdot 76}{353 \cdot 10^{-6} \cdot 250 \cdot 10^{-3}} = 1,81$$

$$N_1 = 1$$

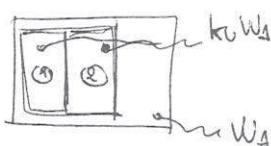
$$N_2 = 2$$

$$\rightarrow \hat{B}_{1s} = \frac{L \hat{I}}{N_1 A_C} = 452 \text{ mT} \quad \text{NO: SATURATION}$$

$$\hat{B}_{2s} = \frac{L \hat{I}}{N_2 A_C} = 226 \text{ mT} \quad \text{OK}$$

$$N = 2$$

⑥ Copper cross-sectional area



$$A_W = \frac{k_0 W_A}{N} = \frac{0,5 \cdot 250 \cdot 10^{-6}}{2} = 62,5 \cdot 10^{-6} \text{ m}^2$$

$$A_W = 62,5 \text{ mm}^2$$

⑦ Current density

$$J_{L,RMS} = \frac{I_{L,RMS}}{A_W} = \frac{43 \text{ A}}{62,5 \text{ mm}^2} = 0,688 \text{ A/mm}^2$$

$$J_{L,RMS} = 0,688 \text{ A/mm}^2$$

(quite low)

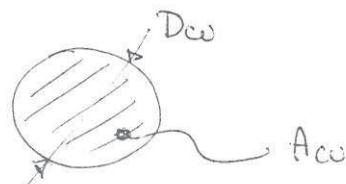
⑧ Number of parallel wires N_w

Eddy currents in conductor $\Rightarrow D_{cu} \leq 2 \cdot D_{skin}$

$$D_{skin} = \sqrt{\frac{\rho}{\pi \cdot f_s \cdot \mu_0}} = \sqrt{\frac{23 \cdot 10^{-9}}{\pi \cdot 60 \cdot 10^3 \cdot 4\pi \cdot 10^{-7}}} = \begin{matrix} 0,3 \cdot 10^{-3} \\ \text{m} \\ \underline{= 0,3 \text{ mm}} \end{matrix}$$

$$D_w = 2 \cdot D_{skin}$$

$$D_w = 0,6 \text{ mm}$$



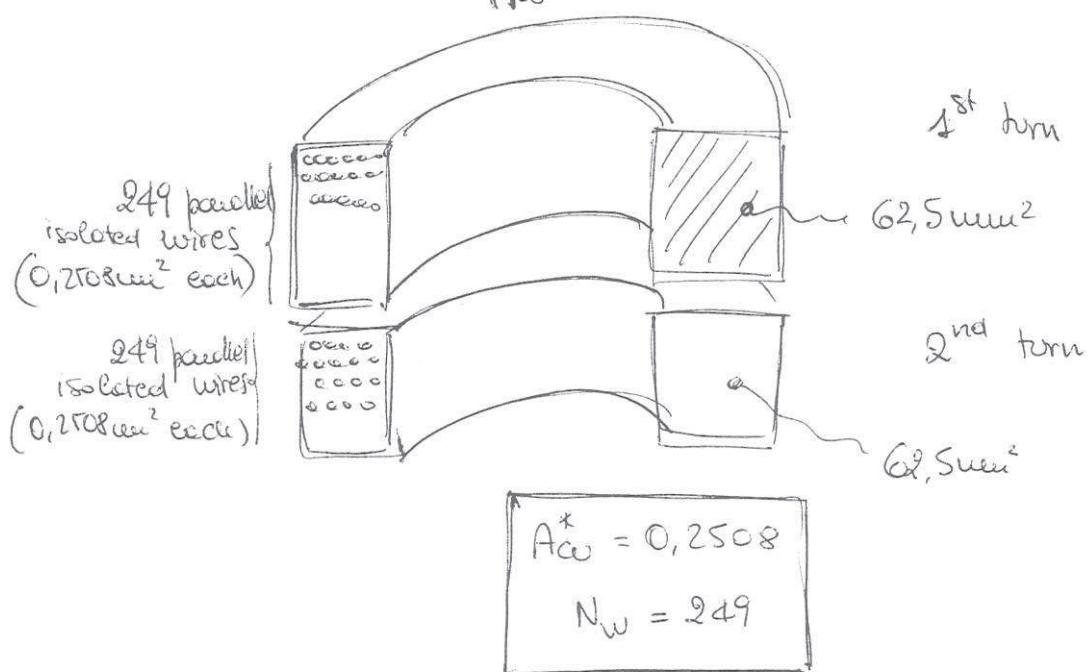
$$A_{cu} = \pi \frac{D_{cu}^2}{4} = \pi \cdot \frac{0,6^2 \cdot 10^{-6}}{4} = 0,2826 \cdot 10^{-6} \text{ m}^2$$

\downarrow
 $= 0,2826 \text{ mm}^2$

→ Closer commercial (available) conductor

$$A_{cu}^* = 0,2508 \text{ mm}^2 \quad (\text{AWG 23})$$

$$N_w = \frac{A_w}{A_{cu}^*} = \frac{62,5 \text{ mm}^2}{0,2508 \text{ mm}^2} = 249$$



⑨ DC Resistance

$$R_i = \frac{\rho N e_T}{A_w} = \frac{\rho N e_T}{N_w \cdot \text{f}_{\text{ew}}^*} = \frac{23 \cdot 10^{-9} \cdot 2 \cdot 116 \cdot 10^{-3}}{249 \cdot 0,2508 \cdot 10^{-6}} = 88 \cdot 10^{-6} = 0,088 \mu\Omega$$

(quite small!)

⑩ Copper losses

$$P_{\text{Cu}} = R_i \cdot I_{\text{L RMS}}^2 = 88 \cdot 10^{-6} \cdot 43^2 = 0,157 \mu\text{W}$$

⑪ Core losses

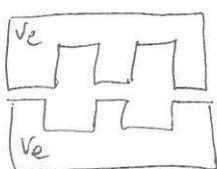
From datasheet core : $2 \cdot V_e = 88 \cdot 10^{-6} \text{ m}^3$

From datasheet material : $P_V \approx 350 \text{ kW/m}^3$

@ $\hat{B} = 250 \text{ mT}$ $f_s = 60 \text{ kHz}$

$$P_{\text{Co}} = \underline{2 \cdot V_e} \cdot P_V = 2 \cdot 44 \cdot 10^{-6} \cdot 350 \cdot 10^3 = 30,8 \text{ W}$$

The core is made of two "E", and V_e is the volume of only one "E"



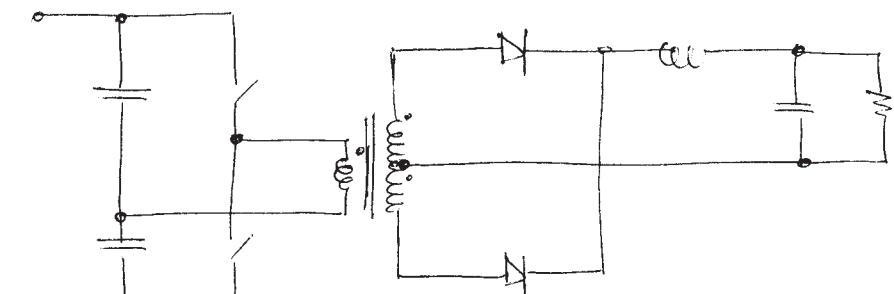
$$\boxed{P_{\text{Cu}} + P_{\text{Co}} = 31 \text{ W}}$$

(Mostly in the core!)

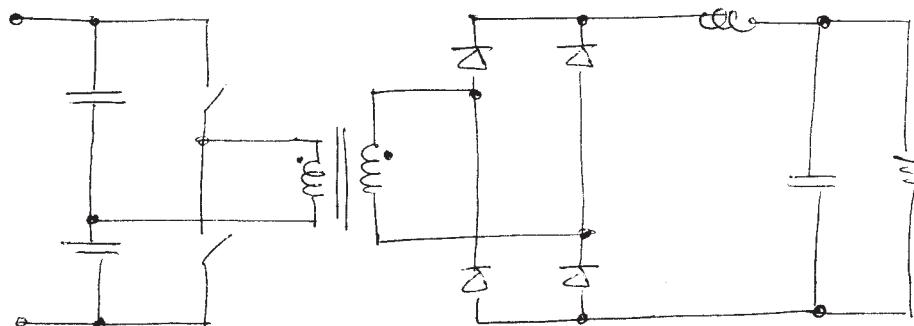
HALF BRIDGE

- Topology derived from the buck
- Transformer
- Different variations on the secondary side:

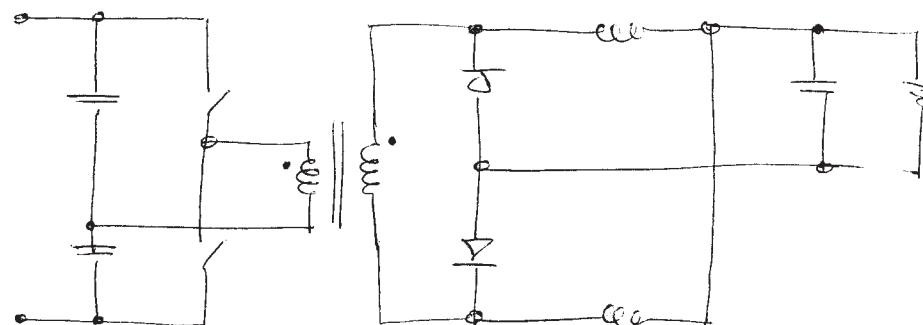
(1)

"FULL WAVE RECTIFIER"

(2)

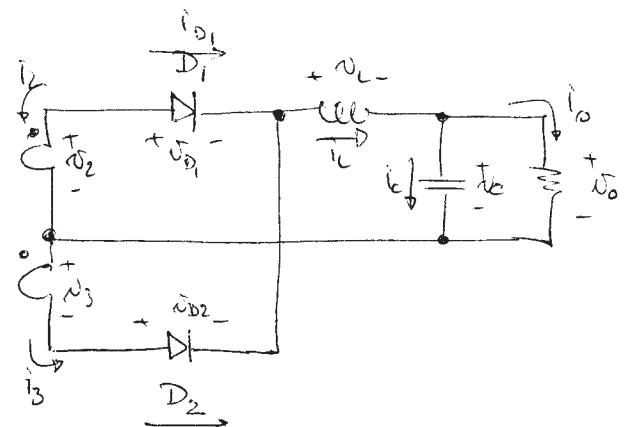
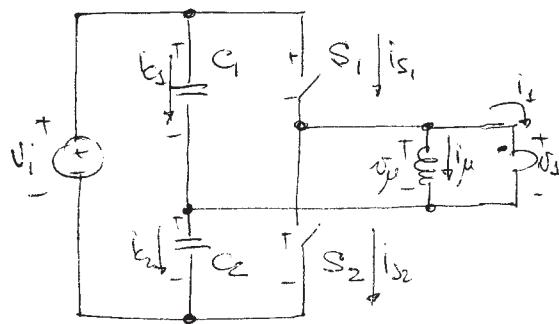
"BRIDGE RECTIFIER"

(3)

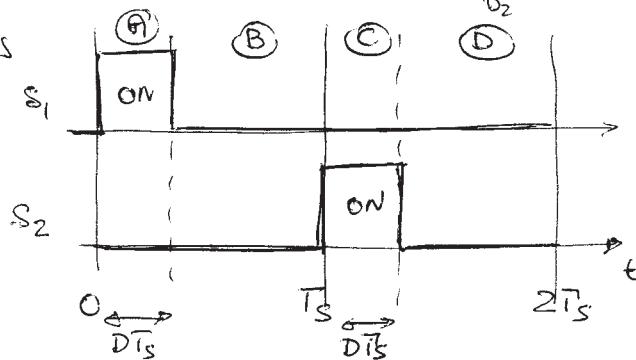
"CURRENT DUBLER"

Half bridge with full-wave rectifier
CCM

① General circuit



Switches



$$N_2 = N_3$$

② Studying the possible circuits

(A) S_1 on, S_2 off, D_1 ? D_2 ?

$$v_{c_1} = v_{c_2} = \frac{V_i}{2} \quad v_3 = \frac{V_i}{2} \quad v_{D_1} = \frac{V_i}{2} \quad N_{S_1} = 0 \quad N_{S_2} = V_i$$

$$\frac{N_1}{N_2} = \frac{N_2}{N_3} = \frac{N_3}{N_2} \quad N_2 = \frac{N_2}{N_1} \frac{V_i}{2} \quad v_3 = \frac{N_2}{N_1} \frac{V_i}{2}$$

$$i_L > 0 \Rightarrow \begin{cases} D_1 \text{ on } \wedge D_2 \text{ on} \\ D_3 \text{ on} \\ D_2 \text{ on} \end{cases}$$

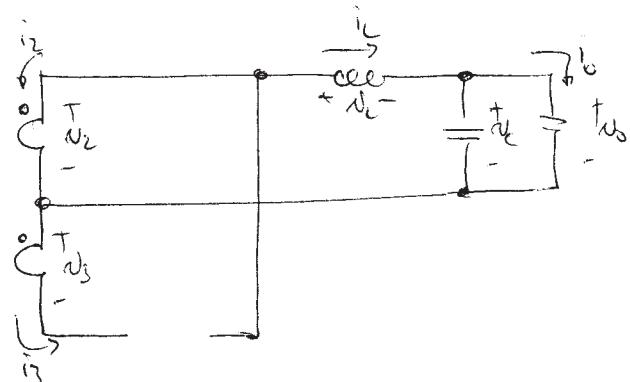
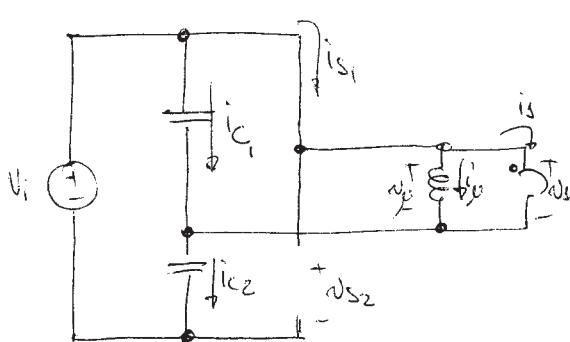
$$\boxed{D_1 \text{ on} \wedge D_2 \text{ on?}} \Rightarrow v_3 + v_2 = 0 \quad v_2 = -v_3 \quad \frac{N_2}{N_1} \frac{V_i}{2} = -\frac{N_2}{N_1} \frac{V_i}{2} \\ \Rightarrow V_i = -V_i \Rightarrow V_i = 0 \quad \underline{N_0}$$

$$\boxed{D_2 \text{ on} \wedge D_1 \text{ off?}} \Rightarrow v_3 + v_2 - v_{D_1} = 0$$

$$v_{D_1} = v_2 + v_3 = \frac{N_2}{N_1} \left(\frac{V_i}{2} + \frac{V_i}{2} \right) = \frac{N_2}{N_1} V_i > 0 \quad \underline{N_0}$$

$$\boxed{D_2 \text{ off} \wedge D_1 \text{ on} \Rightarrow \tilde{v}_3 + \tilde{v}_2 + \tilde{v}_{D2} = 0}$$

$$\tilde{v}_{D2} = -\tilde{v}_3 - \tilde{v}_2 = -\frac{N_2}{N_1} V_i < 0 \rightarrow \underline{\text{OK}}$$



$$\tilde{v}_L = \tilde{v}_2 - V_o = \frac{N_2}{N_1} \frac{V_i}{2} - V_o = V'_i - V_o$$

$$i_L = \frac{V'_i - V_o}{L} t + \tilde{I}_L$$

$$i_o = \tilde{I}_o = \frac{V_o}{R} \quad i_C = i_L - \tilde{I}_o \quad i_{D2} = 0 \quad i_{D1} = i_L \quad i_2 = -i_L$$

$$i_3 = 0$$

$$N_2 i_2 + N_1 i_1 = 0 \quad i_2 = -\frac{N_2}{N_1} i_1 = -\frac{N_2}{N_1} (-i) = \frac{N_2}{N_1} i_1$$

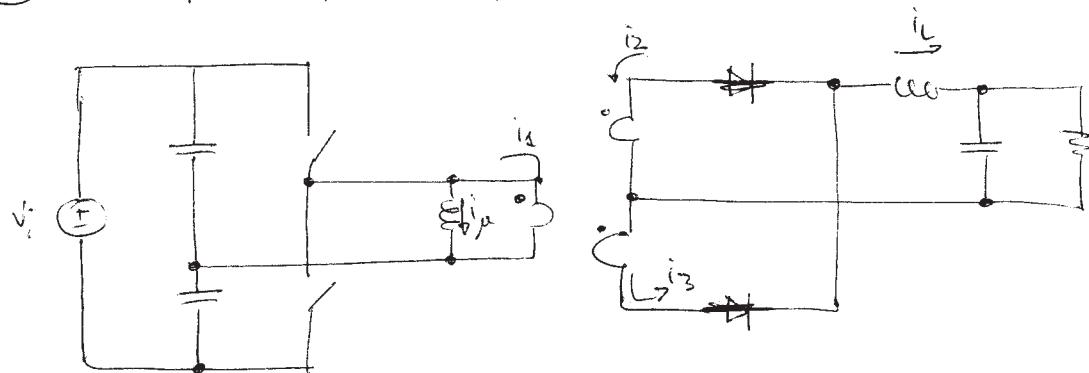
$$i_{\mu} = \frac{V_i}{L_\mu} t + \tilde{I}_\mu \quad i_{ss} = i_2 + i_\mu$$

$$i_{C2} = i_{C1} + i_{ss} \quad |i_{C1}| = |i_{C2}| \quad \left| \begin{array}{l} i_{C1} = i_{C2} \Rightarrow i_{ss} = 0 \quad \underline{\text{NO}} \\ i_{C3} = -i_{C2} \Rightarrow i_{C2} = \frac{i_{ss}}{2} \quad \underline{\text{OK}} \end{array} \right.$$

$$i_{C4} = -\frac{i_{ss}}{2}$$

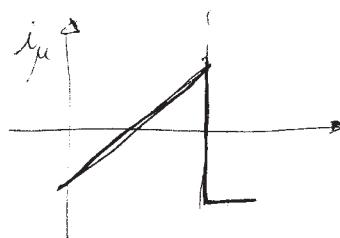
$$i_1 = i_{C4} + i_{ss} = \frac{i_{ss}}{2}$$

(B) S_1 off, S_2 off, D_1 ? , D_2 ?



$$i_u > 0 \Rightarrow \begin{cases} D_1 \text{ on} \wedge D_2 \text{ on} \\ D_1 \text{ on} \\ D_2 \text{ on} \end{cases}$$

D_1 on? $i_{\mu} = -i_1 \quad i_3 = -\frac{N_2}{N_1} i_2 = \frac{N_2}{N_1} i_u \quad i_{\mu} = -\frac{N_2}{N_1} i_u$



$$\bar{i}_{\mu} = L \frac{di_{\mu}}{dt} \quad \frac{di_{\mu}}{dt} = \pm \infty \Rightarrow \bar{i}_{\mu} = \pm \infty$$

No

(" i_{μ} " shouldn't have jumps")

D_2 on? $i_{\mu} = \frac{N_2}{N_1} i_u \quad$ similar \Rightarrow No

D_1 on \wedge D_2 on

$$i_4 = -i_{\mu}$$

$$i_3 = i_2 + i_1$$

$$N_3 i_3 + N_2 i_2 + N_2 i_1 = 0$$

$$N_3 (-i_{\mu}) + N_2 i_2 + N_2 (i_2 + i_1) = 0$$

$$-N_3 i_{\mu} + 2N_2 i_2 + N_2 i_1 = 0$$

$$i_2 = \frac{-N_2 i_1 + N_3 i_{\mu}}{2N_2} = -\frac{i_1}{2} + \frac{N_1}{N_2} \frac{i_{\mu}}{2}$$

$$i_{D2} = -i_2 = \frac{i_L}{2} - \frac{N_1}{N_2} \frac{i_M}{2}$$

$$i_{D2} > 0 \Leftrightarrow \frac{i_L}{2} - \frac{N_1}{N_2} \frac{i_M}{2} > 0 \Leftrightarrow i_L > \frac{N_1}{N_2} i_M$$

(Heavy load)

$$i_3 = i_2 + i_L = -\frac{i_L}{2} + \frac{N_1}{N_2} \frac{i_M}{2} + i_L = \frac{i_L}{2} + \frac{N_1}{N_2} \frac{i_M}{2}$$

$$i_{D3} = i_3 > 0 \quad \underline{\text{always}}$$

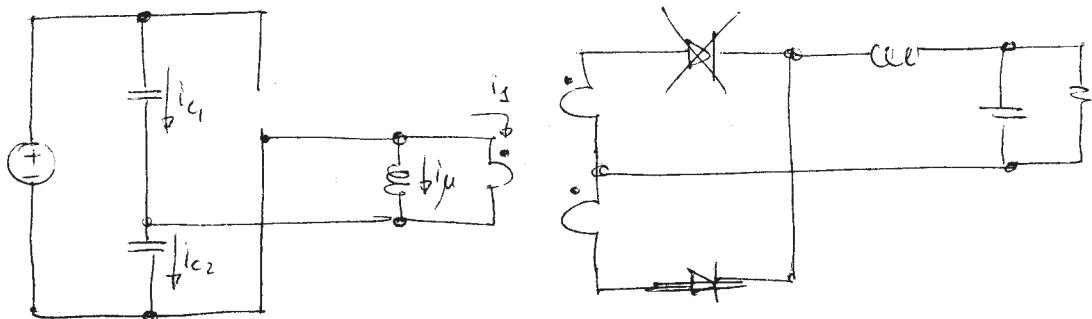
$$\bar{v}_3 = -\bar{v}_2 \Rightarrow \frac{N_2}{N_3} \bar{v}_1 = -\frac{N_2}{N_3} \bar{v}_4 \Rightarrow \bar{v}_4 = -\bar{v}_1 \Rightarrow \bar{v}_4 = 0$$

$$\Rightarrow \bar{v}_2 = 0 \quad \bar{v}_3 = 0 \quad \bar{v}_M = 0$$

$$i_M \equiv \text{const} \equiv \hat{i}_M \quad v_L = -V_0 \quad i_L = -\frac{V_0}{L} t + \hat{i}_L$$

$$v_{S1} = v_{S2} = \frac{V_1}{2}$$

(C) S_1 off, S_2 on, $D_1?$, $D_2?$



$$\bar{v}_M = -\frac{V_1}{2} \quad \bar{v}_1 = -\frac{V_1}{2} \quad \bar{v}_2 = \frac{N_2}{N_1} \bar{v}_4 = -\frac{N_2}{N_1} \frac{V_1}{2} \quad \bar{v}_3 = \bar{v}_2$$

D_1 off, D_2 on?

$$\bar{v}_{D1} = \bar{v}_2 = -\frac{N_2}{N_1} \frac{V_1}{2} \ll 0 \rightarrow \underline{\text{OK}}$$

$$\tilde{N_L} = -\tilde{i}_3 - V_0 = \frac{N_2}{N_1} \frac{V_i}{2} - V_0 = V_i - V_0 \quad i_L = \frac{V_i - V_0}{L} t + \tilde{I}_L$$

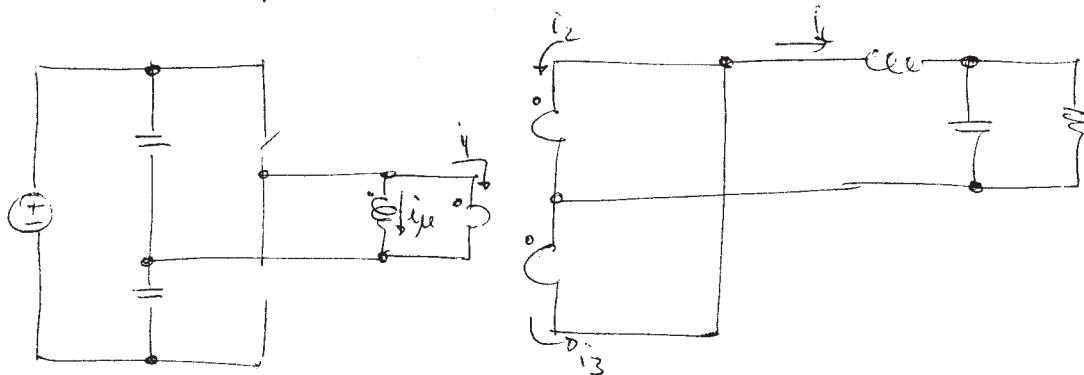
$$i_2 = 0 \quad i_3 = i_L \quad i_f = -\frac{N_2}{N_1} i_L$$

$$i_{ju} = \hat{I}_{ju} - \frac{V_i}{2L} t$$

$$i_{S2} = -i_{ju} - i_f = -i_{ju} + \frac{N_2}{N_1} i_L$$

$$i_{C1} = i_{S2}/2 \quad i_{C2} = -i_{S2}/2 \quad i_f = i_{ef} = i_{S2}/2$$

D) S_1 off S_2 off D_1 ? D_2 ?



$$i_f = -i_{ju}$$

$$N_1 i_f + N_2 i_2 + N_3 i_3 = 0$$

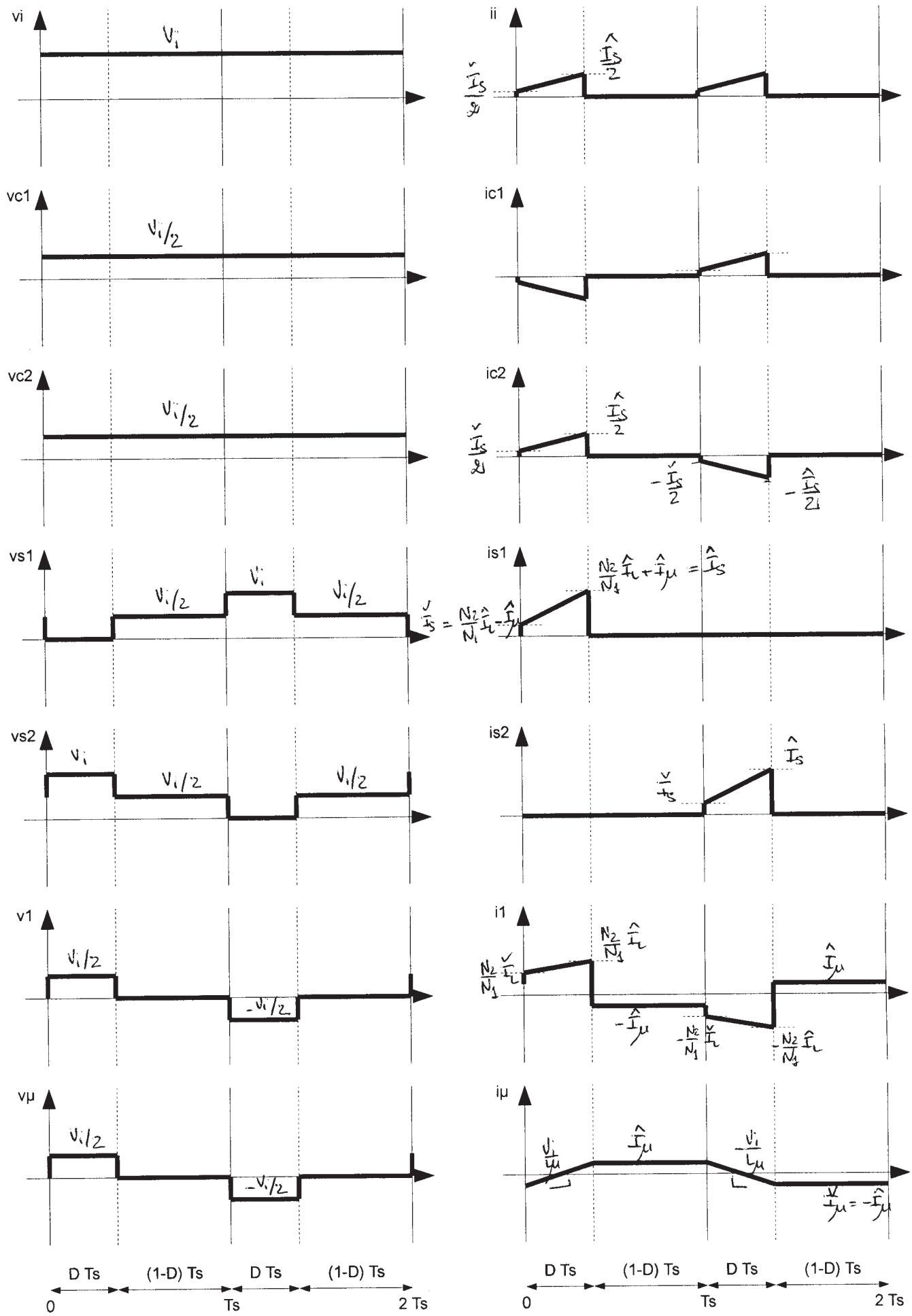
$$N_3 (-i_{ju}) + N_2 i_2 + N_2 (i_2 + i_L) = 0$$

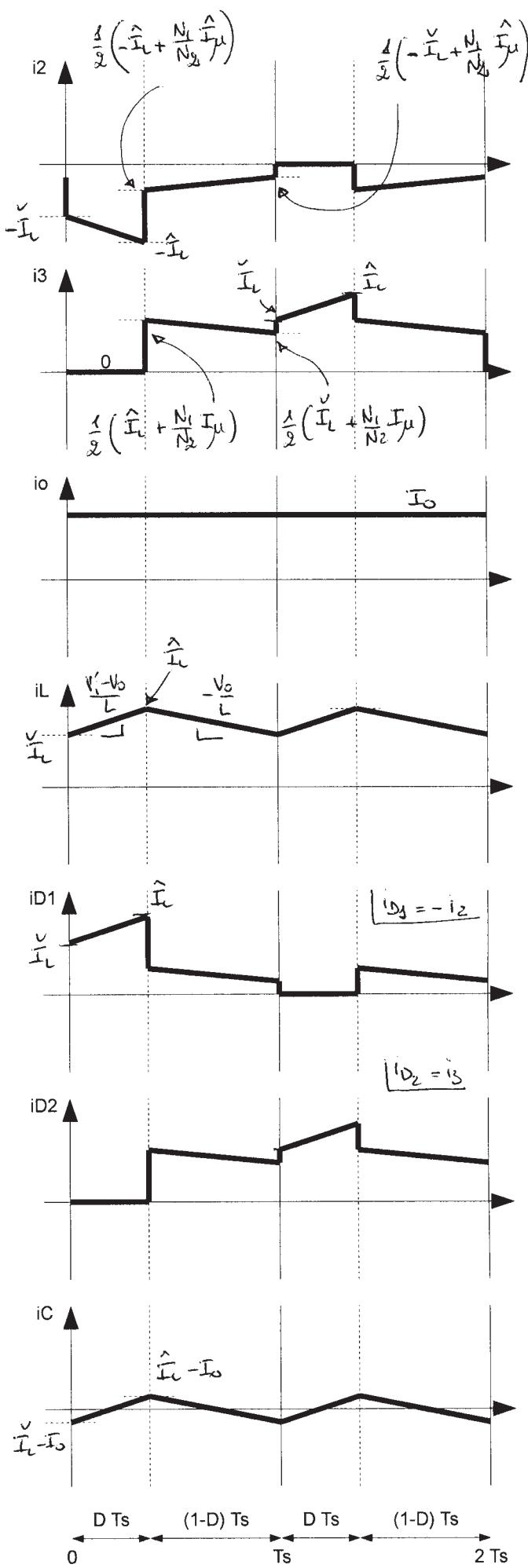
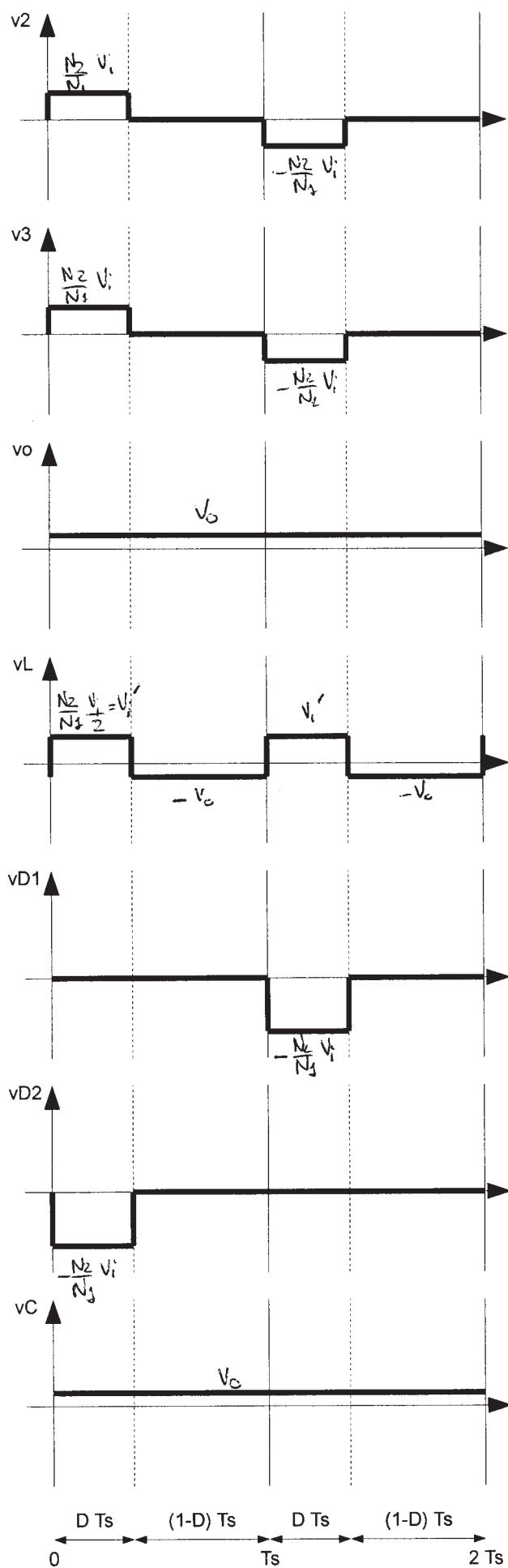
$$-N_1 i_{ju} + 2N_2 i_2 + N_2 i_L = 0$$

$$i_2 = -\frac{i_L}{2} + \frac{N_1}{N_2} \frac{i_{ju}}{2}$$

$$i_3 = i_2 + i_L = \frac{i_L}{2} + \frac{N_1}{N_2} \frac{i_{ju}}{2}$$

$$\tilde{N_1} = \tilde{N_2} = \tilde{N_3} = 0 \quad \rightarrow \tilde{i_{ju}} = 0 \quad \rightarrow i_{ju} = \text{const} = \frac{V}{L} = -\hat{I}_{ju}$$





4) Steady-state conditions

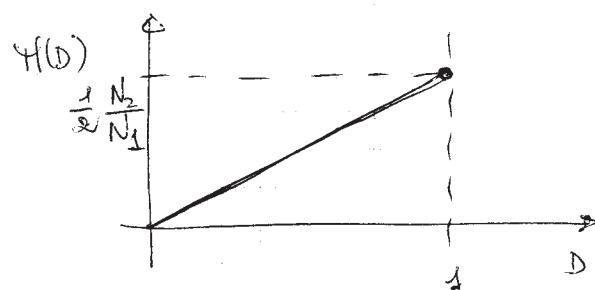
Defined $V_i' = \frac{N_2}{N_1} \frac{V_i}{2}$, the second part of the

converter behaves like a buck with an input voltage V_i' . All the equations are then similar.

$$V_o = D V_i' = D \frac{N_2}{N_1} \frac{V_i}{2}$$

5) Conversion ratio

$$H(D) = \frac{V_o}{V_i} = D \frac{N_2}{N_1} \cdot \frac{1}{2}$$



6) Current ripple (inductor)

$$\Delta i_L = \frac{V_i' T_s}{L} (1-D)D = \frac{N_2}{N_1} \frac{V_i T_s}{2L} (1-D)D$$

7) Average and maximum current

$$\langle i_L \rangle = I_0 = \frac{V_o}{R}$$

$$\hat{i}_L = I_0 + \frac{\Delta i_L}{2}$$

$$\hat{i}_{D_1} = \hat{i}_{D_2} = \hat{i}_L$$

$$|\hat{i}_2| = \hat{i}_L \quad |\hat{i}_1| = \frac{N_2}{N_1} \hat{i}_L \quad |\hat{i}_3| = \hat{i}_L$$

$$\hat{I}_{S_1} = \hat{I}_{S_2} = \frac{N_2}{N_1} \hat{I}_L + \hat{I}_\mu$$

$$\langle i_{D_1} \rangle = - \langle i_2 \rangle =$$

$$\langle i_{D_2} \rangle = \langle i_3 \rangle =$$

$$\langle i_4 \rangle = 0$$

$$\langle i_{S_1} \rangle =$$

$$\langle i_{S_2} \rangle =$$

$$\langle i_i \rangle =$$

8) Maximum Voltage

$$|\hat{N}_{S_1}| = |\hat{N}_{S_2}| = V_i$$

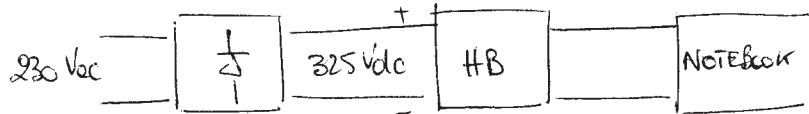
$$|\hat{N}_{D_1}| = |\hat{N}_{D_2}| = \frac{N_2}{N_1} V_i$$

9) Output voltage ripple

$$\Delta V_C = \frac{V_i T_s^2}{8LC} (1-D)D = \frac{N_2}{N_1} \frac{V_i T_s^2}{16LC} (1-D)D$$

Exercise

1) Design the following converter using a HB



$$N_1 = 325$$

$$V_b = 90 \text{ V}$$

$$L_M = 60 \mu\text{H}$$

$$P_o = (40 + 90) \text{ W}$$

$$f_s = 40 \text{ kHz}$$

$$\Delta V_C = 0,2 \text{ V}$$

Heavy load operation

$$N_2 = ? \quad I_o = ? \quad D = ? \quad L = ? \quad C = ?$$

$$\Delta i_L = ? \quad \langle i_L \rangle = ? \quad \langle i_{S_1} \rangle = ? \quad \langle i_{S_2} \rangle = ? \quad \langle i_{D_1} \rangle = ?$$

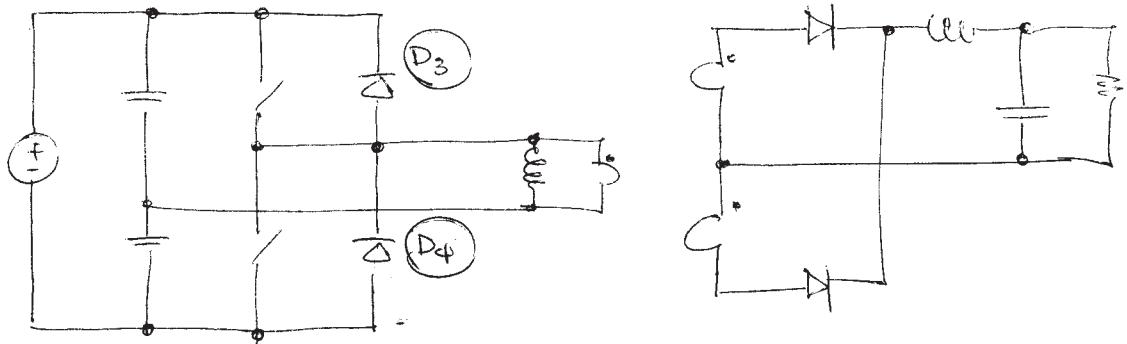
$$\langle i_{D_2} \rangle = ? \quad \hat{I}_L = ? \quad \hat{I}_{S_1} = ? \quad \hat{I}_{S_2} = ? \quad \hat{I}_{D_1} = ?$$

$$\hat{I}_{D_2} = ? \quad |\hat{v}_{S_1}| = ? \quad |\hat{v}_{S_2}| = ? \quad |\hat{v}_o| = ? \quad |\hat{v}_{D_2}| = ?$$

Light load

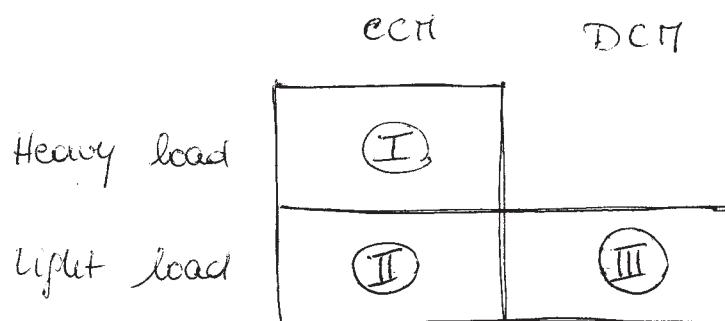
$$i_L \leq \frac{N_1}{N_2} i_{L0}$$

- Need of more diodes (to let i_L circulate)



↳ the behavior of the circuits changes

- There is also a discontinuous conduction mode, like for the buck.



The case (I) has been presented.

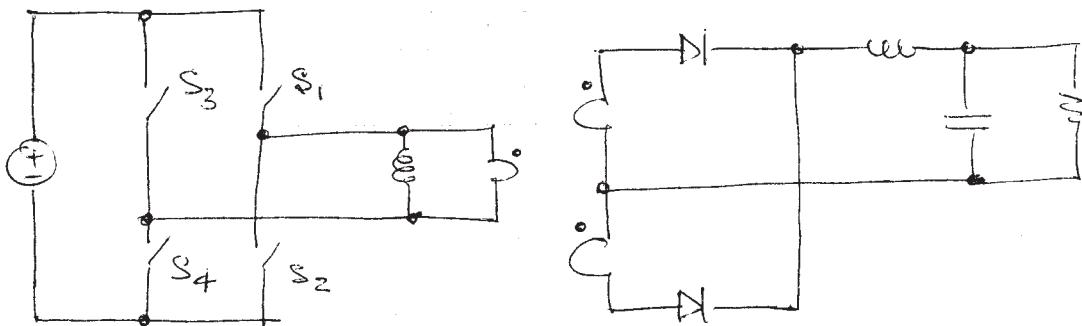
Exercises: - study the other cases.

FULL BRIDGE

- Topology derived from the buck
- Transformer
- Similar variations on the secondary side as for the HB

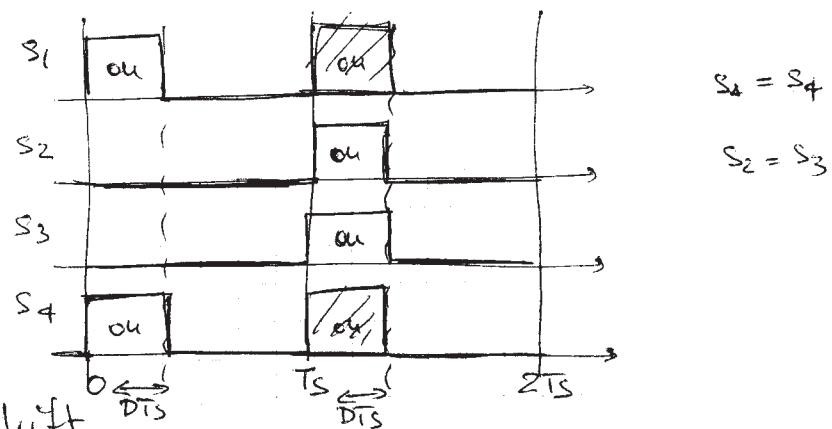
Full bridge with full-wave rectifier

① General circuit



Two control strategies

A) Diagonal switches



B) Please shift

