Submission Date	2019-09-D=12					
Project Name	Smart Tennis Ball Machine					
Student Names	Gurwarris Sohi, Sahil Sahil, and Nicolas Cristiano					
Project repository	https://github.com/Warris-Sohi/SmartTennisBallMachine					
SensorsEffectors						
choices	Infrared Sensors, Motion Sensors, Servomotors, Stepper motors					
The database will store	Our databases will keep the parameters for each play-type or practice session.					
The mobile device						
functionality will	The app is gonna be able to set individual parameters, you can save your level of play					
include	(level of difficulty). Our just choose one of our presets for difficulty of play.					
I will be collaborating						
with the following						
company/department	Startup Life					
My group in the winter						
semester will include	Gurwarris Sohi, Sahil Sahil, and Nicolas Cristiano					
	Tennis ball machines today are costly and in the age where every aspect of our life can					
	be remotely controlled from a mobile device, tennis ball machines are still stuck with					
50 word problem	buttons and 8 bit displays. Present machines are more hardcoded and way less					
statement	autonomous than today's standards.					
	Tennis ball machines us a container filled with a number of balls (100 balls by present					
	standards), and then some machine use pressure to launch the ball and at the end a					
	pair of tires placed on either side of the ejection tube either horizontally or vertically					
	to finally launch the ball give the needed spin for each serve type. The whole					
	contraption at the end is moved and horizontally and vertically to aim the ball					
	trajectory. This part only affects the elevation and direction of the ball. But a ball can					
100 words of	have same max height and distance with different elevations, with different launch					
background	speeds.					
Current product APA						
citation	Baldwin, D. M. (1977). Using the tennis ball serving machine. The Physics Teacher, 15(7), 432–4					
Existing research IEEE						
paper APA citation	N/A					
	We are planning our machine on a Raspberry Pi 3, which will controll the servo motors					
Brief description of	that laungh the ball, and also the stepper motors that will aim the ball accordingly and					
planned purchases	motion sensors to modulate ball speed.					
	Our machine is based on a simpler design than the present machine, which will make					
	the machine cost effective and when the machine is connected to the app, most of the					
	processing is done on the mobile side. So we can have smaller processing size on the					
Solution description	machine.					

34. doi: 10.1119/1.2339719,5. Understanding the Motion of the Ball (Ball Trajectories). (n.d.). <i>Tennis Science for Tennis</i>									

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<i>Players</i> . doi	: 10.9783/97	7808122014	58.72,