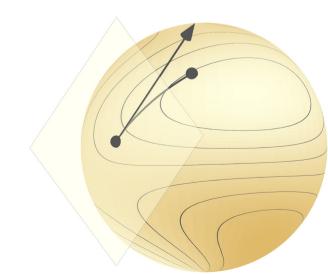
213

Linear convergence with Polyak–Łojasiewicz

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Optimization on manifolds, MATH 512 @ EPFL

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A comfortable assumption to make

Let $f: \mathcal{M} \to \mathbf{R}$ be differentiable on a Riemannian manifold \mathcal{M} .

Def.: We say f satisfies the Polyak–Łojasiewicz condition with constant $\mu > 0$ on a set $S \subseteq \mathcal{M}$ if

$$f(x) - f^* \le \frac{1}{2\mu} \|\operatorname{grad} f(x)\|_{x}^{2} \quad \text{for all } x \in S,$$

where $f^* = \inf_{x \in S} f(x)$.

In words: within *S*, the gradient norm² bounds the optimality gap.

PŁ + sufficient decrease ⇒ linear cvgce

Let $f: \mathcal{M} \to \mathbf{R}$ be differentiable on a Riemannian manifold \mathcal{M} . Consider a sequence of points $x_0, x_1, x_2, ...$ on \mathcal{M} .

Theorem. Assume the following hold for all *k*:

1. Decrease:
$$f(x_k) - f(x_{k+1}) \ge \frac{1}{2L} \| \operatorname{grad} f(x_k) \|_{x_k}^2$$

2. PŁ:
$$f(x_k) - f^* \le \frac{1}{2\mu} \| \operatorname{grad} f(x_k) \|_{x_k}^2$$

Then,
$$f(x_k) - f^* \le \left(1 - \frac{1}{L/\mu}\right)^k (f(x_0) - f^*)$$

$$\begin{aligned}
f(x_{k+1}) - f^* &= f(x_{k+1}) - f(x_k) + f(x_k) - f^* \\
&\leq -\frac{1}{2L} \|g(x_k) f(x_k)\|_{X_k}^2 + f(x_k) - f^* \\
&\leq -\frac{2m}{2L} (f(x_k) - f^*) + f(x_k) - f^* \\
&= (1 - f^*) (f(x_k) - f^*).
\end{aligned}$$

PŁ holds for geodesically strongly convex f

Fact/Def.: A function $f: \mathcal{M} \to \mathbf{R}$ is geodesically μ -strongly convex on a geodesically convex set S if

$$\operatorname{Hess} f(x) \geqslant \mu \operatorname{Id} - \left\langle V, \operatorname{Hunf} (\mu) [V] \right\rangle_{\mathcal{H}} \geqslant \mu \operatorname{Id} V_{\mathcal{H}}^{2}$$
 for all $x \in S$.

Fact: Under that definition, for all $x, x^* \in S$, we have:

$$f(x) - f(x^*) \le \frac{1}{2\mu} \|\operatorname{grad} f(x)\|_{x}^{2}$$

$$\text{Can be replaced with } \inf_{x^* \in S} f(x^*) \stackrel{?}{=} f^*.$$

graderic Argment
$$C: [0,i] \rightarrow M$$
 A.t. $C(0) = x$, $C(i) = x^2$, $C(0) \in S$

If $g = f \circ C$;

$$f(x^0) = g(1) = g(0) + \int_0^1 g'(t) dt = g(0) + \int_0^1 g'(0) + \int_0^1 g''(t) dt dt$$

$$g''(t) = Df(C(t))[c'(t)] = \angle gradf(c(t)), c'(t) \rangle_{C(t)}$$

$$g'''(t) = \angle \frac{D}{dt} gradf(c(t)), c'(t) \rangle_{C(t)} + \angle gradf(c(t)), Dc'(t) \rangle_{C(t)}$$

$$= \angle \text{Hen } f(c(t))[c'(t)], c'(t) \rangle_{C(t)}$$

$$= A \text{Hen } f(c(t))[c'(t)], c'(t) \rangle_{C(t)}$$

Since x, x + e S which is g-convex, there exists a

$$\frac{d}{dt} \| c'(t) \|_{c(t)}^{2} = \frac{d}{dt} \langle c'(t), c'(t) \rangle_{dt} = 0$$

$$= \mu \| c'(t) \|_{x}^{2} = \mu \| v \|_{x}^{2} \quad \text{wi} \quad v = c'(t).$$

$$= \int (x^{\mu}) + \langle g(a) f(a), v \rangle_{x} + \int_{0}^{t} \int_{0}^{t} \mu \| v \|_{x}^{2} d\tau d\tau$$

$$= \int (x) + \langle g(a) f(a), v \rangle_{x} + \int_{2}^{t} \| v \|_{x}^{2}$$

$$= \int (x) + \langle g(a) f(a), v \rangle_{x} + \int_{2}^{t} \| v \|_{x}^{2}$$

$$= \int (x) + \langle g(a) f(a), v \rangle_{x} + \int_{2}^{t} \| u \|_{x}^{2}$$

$$= \int (x) - \frac{1}{2\mu} \| g(a) f(a) \|_{x}^{2}$$

To learn more about the PŁ condition, see for example arxiv.org/abs/2303.00096.

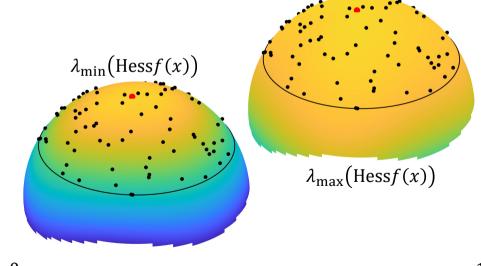
Application: intrinsic means

Given m points $x_1, ..., x_m$ on a Riemannian manifold (say, a sphere), what is a good notion of mean or average of those points?

The Fréchet mean is any minimizer of:

$$f(x) = \frac{1}{2m} \sum_{i=1}^{m} \operatorname{dist}(x, x_i)^2$$

It's fun to explore how the above applies to this f.



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