

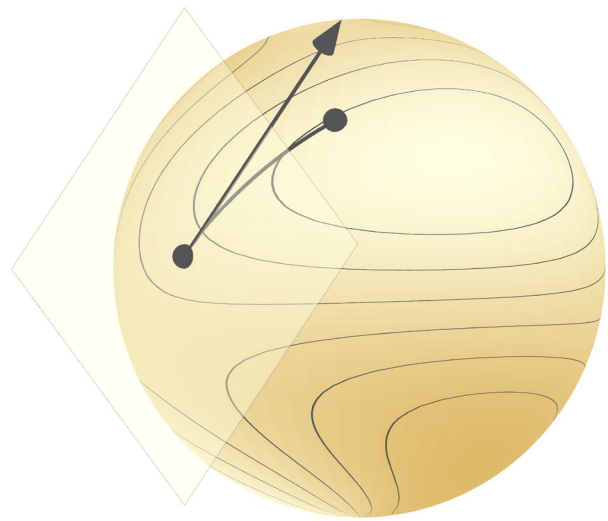
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More about conjugate gradients

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Optimization on manifolds, MATH 512 @ EPFL

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Why do people really care about CG?

It is not because of finite termination:
that fails numerically, and it is irrelevant in high dimension.

It is because, in practice, it converges much faster than GD,
for essentially the same cost per iteration.

We understand very well *why*, and the proof is beautiful.

Conjugate gradients to minimize $g(\mathbf{v}) = \frac{1}{2} \langle \mathbf{v}, H\mathbf{v} \rangle_x - \langle \mathbf{b}, \mathbf{v} \rangle_x$ on $T_x\mathcal{M}$:

Initialize $\mathbf{v}_0 = 0$, $\mathbf{r}_0 = \mathbf{b}$, $\mathbf{p}_0 = \mathbf{r}_0$

For n in 1, 2, 3, ...

- Compute $H\mathbf{p}_{n-1}$
- $\alpha_n = \frac{\|\mathbf{r}_{n-1}\|_x^2}{\langle \mathbf{p}_{n-1}, H\mathbf{p}_{n-1} \rangle_x}$
- $\mathbf{v}_n = \mathbf{v}_{n-1} + \alpha_n \mathbf{p}_{n-1}$
- $\mathbf{r}_n = \mathbf{r}_{n-1} - \alpha_n H\mathbf{p}_{n-1}$
- **If** $\|\mathbf{r}_n\|_x \leq \text{tol} \cdot \|\mathbf{b}\|_x$, **output** \mathbf{v}_n
- $\beta_n = \frac{\|\mathbf{r}_n\|_x^2}{\|\mathbf{r}_{n-1}\|_x^2}$
- $\mathbf{p}_n = \mathbf{r}_n + \beta_n \mathbf{p}_{n-1}$

$$\begin{aligned}v_n &= v_{n-1} + \alpha_n p_{n-1} \\r_n &= r_{n-1} - \alpha_n H p_{n-1} \\p_n &= r_n + \beta_n p_{n-1}\end{aligned}$$

The three sequences of CG

The **iterates** v_0, v_1, v_2, \dots converge to the minimizer of g .

The **residues** r_0, r_1, r_2, \dots converge to zero.

The **basis vectors** p_0, p_1, p_2, \dots are H -conjugate directions.

$$\begin{aligned} v_n &= v_{n-1} + \alpha_n p_{n-1} \\ r_n &= r_{n-1} - \alpha_n H p_{n-1} \\ p_n &= r_n + \beta_n p_{n-1} \end{aligned}$$

The Krylov space \mathcal{K}_n

Fact: $\mathcal{K}_n = \text{span}(p_0, \dots, p_{n-1}) = \text{span}(b, Hb, H^2b, \dots, H^{n-1}b)$

Proof. It's clear for $n = 1$. Now proceed by induction.

Note: $\dim \text{span}(b, \dots, H^n b) \leq n + 1 = \dim \text{span}(p_0, \dots, p_n)$.

By induction, we know $\text{span}(p_0, \dots, p_{n-1}) \subseteq \text{span}(b, \dots, H^n b)$.

Exercise: show p_n is in $\text{span}(b, \dots, H^n b)$ and conclude.

Detour: the H -norm property of v_n

We already know v_n minimizes $g(\boldsymbol{v}) = \frac{1}{2}\langle \boldsymbol{v}, H\boldsymbol{v} \rangle_x - \langle \boldsymbol{b}, \boldsymbol{v} \rangle_x$ over \mathcal{K}_n .

Fact: v_n also minimizes the H -norm distance to the global min.

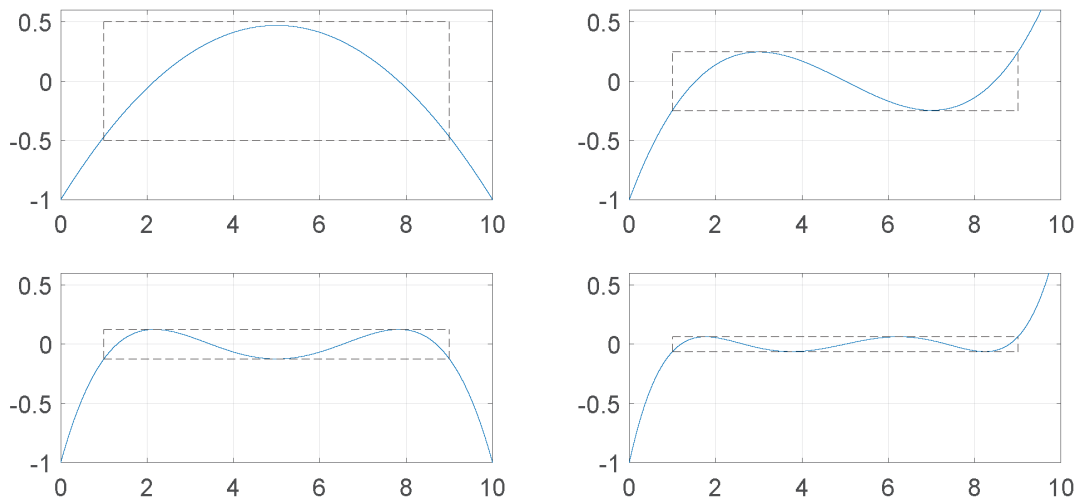
The polynomial perspective

$$\begin{aligned}v_n &= v_{n-1} + \alpha_n p_{n-1} \\r_n &= r_{n-1} - \alpha_n H p_{n-1} \\p_n &= r_n + \beta_n p_{n-1}\end{aligned}$$

$$v_n = \operatorname{argmin}_{v \in \mathcal{K}_n} g(v) \quad \text{with} \quad \mathcal{K}_n = \operatorname{span}(b, Hb, H^2b, \dots, H^{n-1}b)$$

Theorem. If the eigenvalues of H are in $[\lambda_{\min}, \lambda_{\max}]$ with $\kappa = \frac{\lambda_{\max}}{\lambda_{\min}}$, then:

$$\|v_n - s\|_H \leq \|s\|_H \cdot 2 \left(\frac{\sqrt{\kappa}-1}{\sqrt{\kappa}+1} \right)^n \leq \|s\|_H \cdot 2e^{-n/\sqrt{\kappa}}.$$



For each degree n , one can find a polynomial in \mathcal{Q}_n with maximal absolute value less than $2 \left(\frac{\sqrt{9}-1}{\sqrt{9}+1} \right)^n$ over the interval $[1, 9]$: see Fig. 6.1 in book for details.