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Linear convergence with Polyak–Łojasiewicz

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A comfortable assumption to make

Let $f: \mathcal{M} \rightarrow \mathbf{R}$ be differentiable on a Riemannian manifold \mathcal{M} .

Def.: We say f satisfies the **Polyak–Łojasiewicz condition** with constant $\mu > 0$ on a set $S \subseteq \mathcal{M}$ if

$$f(x) - f^* \leq \frac{1}{2\mu} \|\text{grad} f(x)\|_x^2 \quad \text{for all } x \in S,$$

where $f^* = \inf_{x \in S} f(x)$.

In words: within S , **the gradient norm² bounds the optimality gap.**

PŁ + sufficient decrease \Rightarrow linear cvgce

Let $f: \mathcal{M} \rightarrow \mathbf{R}$ be differentiable on a Riemannian manifold \mathcal{M} .

Consider a **sequence** of points x_0, x_1, x_2, \dots on \mathcal{M} .

Theorem. Assume the following hold for all k :

1. Decrease: $f(x_k) - f(x_{k+1}) \geq \frac{1}{2L} \|\text{grad} f(x_k)\|_{x_k}^2$
2. PŁ: $f(x_k) - f^* \leq \frac{1}{2\mu} \|\text{grad} f(x_k)\|_{x_k}^2$

$$\text{Then, } f(x_k) - f^* \leq \left(1 - \frac{1}{L/\mu}\right)^k (f(x_0) - f^*) \quad \forall k$$

$$\begin{aligned}
 \underline{\text{Pf:}} \quad f(x_{k+1}) - f^* &= f(x_{k+1}) - f(x_k) + f(x_k) - f^* \\
 &\leq -\frac{1}{2L} \|\text{grad} f(x_k)\|_{x_k}^2 + f(x_k) - f^* \\
 &\leq -\frac{\mu}{2L} (f(x_k) - f^*) + f(x_k) - f^* \\
 &= \left(1 - \frac{\mu}{L}\right) (f(x_k) - f^*).
 \end{aligned}$$

PL holds for geodesically strongly convex f

Fact/Def.: A function $f: \mathcal{M} \rightarrow \mathbf{R}$ is **geodesically μ -strongly convex** on a geodesically convex set S if

$$\text{Hess}f(x) \succcurlyeq \mu \text{Id} \quad \sim \quad \langle v, \text{Hess}f(x)[v] \rangle_x \geq \mu \|v\|_x^2$$

for all $x \in S$.

Fact: Under that definition, for all $x, x^* \in S$, we have:

$$f(x) - \underbrace{f(x^*)}_{\substack{\text{can be replaced with} \\ \inf_{x^* \in S} f(x^*) \doteq f^*}} \leq \frac{1}{2\mu} \|\text{grad}f(x)\|_x^2$$

Since $x, x^* \in S$ which is g -convex, there exists a geodesic segment $c: [0, 1] \rightarrow M$ s.t. $c(0) = x$, $c(1) = x^*$, $c(t) \in S$ $\forall t \in [0, 1]$
 let $g = f \circ c$;

$$f(x^*) = g(1) = g(0) + \int_0^1 g'(t) dt = g(0) + \int_0^1 g'(0) + \int_0^t g''(\tau) d\tau dt$$

$$g'(t) = Df(c(t)) [c'(t)] = \langle \text{grad} f(c(t)), c'(t) \rangle_{c(t)}$$

$$g''(t) = \left\langle \frac{D}{dt} \text{grad} f(c(t)), c'(t) \right\rangle_{c(t)} + \left\langle \text{grad} f(c(t)), \frac{D}{dt} c'(t) \right\rangle_{c(t)}$$

$$= \langle \text{Hess} f(c(t)) [c'(t)], c'(t) \rangle_{c(t)}$$


$$\geq \mu \|c'(t)\|_{c(t)}^2 \quad \forall t \in [0, 1] \quad \text{since } f \text{ is } \mu\text{-strongly } g\text{-convex in } S.$$

$$\begin{aligned} & \frac{d}{dt} \|c'(t)\|_{c(t)}^2 = \frac{d}{dt} \langle c'(t), c'(t) \rangle_{c(t)} = 0 \\ & = \mu \|c'(0)\|_x^2 \doteq \mu \|v\|_x^2 \quad \text{w/ } v = c'(0). \end{aligned}$$

$$\Rightarrow f(x^*) \geq f(x) + \langle \text{grad} f(x), v \rangle_x + \int_0^1 \int_0^t \mu \|v\|_x^2 d\tau dt$$

$$= f(x) + \langle \text{grad} f(x), v \rangle_x + \frac{\mu}{2} \|v\|_x^2$$

$$\geq \inf_{u \in T_x M} \left[f(x) + \langle \text{grad} f(x), u \rangle_x + \frac{\mu}{2} \|u\|_x^2 \right]$$

$u = -\frac{1}{\mu} \text{grad} f(x)$ 

$$= f(x) - \frac{1}{2\mu} \|\text{grad} f(x)\|_x^2$$

To learn more about the PL condition, see for example arxiv.org/abs/2303.00096.

Application: intrinsic means

Given m points x_1, \dots, x_m on a Riemannian manifold (say, a sphere), what is a good notion of **mean** or **average** of those points?

The **Fréchet mean** is any minimizer of:

$$f(x) = \frac{1}{2m} \sum_{i=1}^m \text{dist}(x, x_i)^2$$

It's fun to explore how the above applies to this f .

