

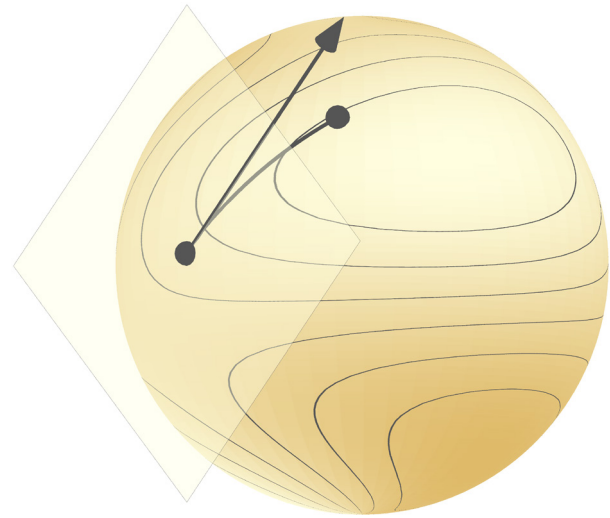
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Distance, geodesics and complete manifolds

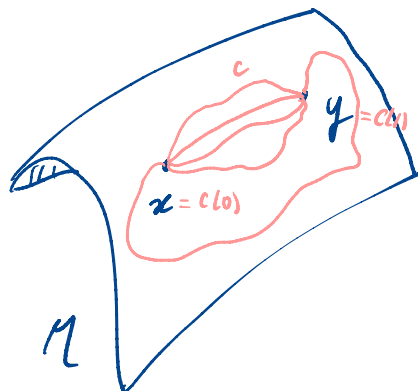
Spring 2023

Optimization on manifolds, MATH 512 @ EPFL

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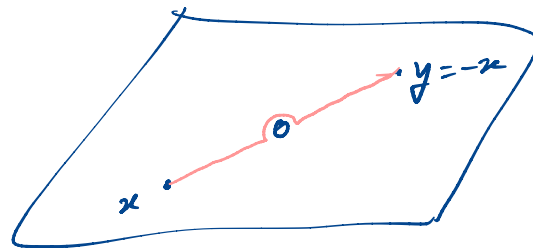
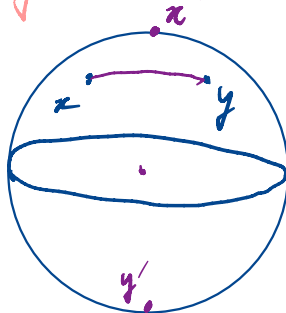
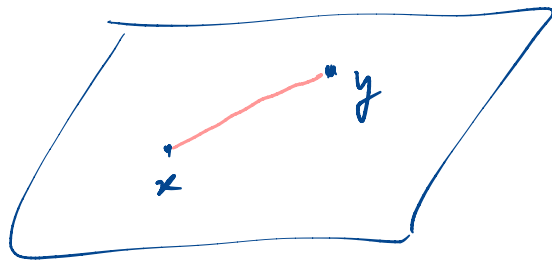
The Riemannian metric induces a distance



$$\text{Length}(c) = \int_0^1 \|c'(t)\|_{c(t)} dt$$

$$\text{dist}(x, y) = \inf_{\substack{c: [0,1] \rightarrow M \\ c(0)=x, c(1)=y}} \text{Length}(c)$$

this defines a distance if M is connected.



Def: The **length** of a smooth curve segment $c: [0, 1] \rightarrow \mathcal{M}$ is

$$\text{Length}(c) = \int_0^1 \|c'(t)\|_{c(t)} dt$$

Fact: If \mathcal{M} is **connected**, the function $\text{dist}: \mathcal{M} \times \mathcal{M} \rightarrow \mathbf{R}$,

$$\text{dist}(x, y) = \inf_{\substack{c: [0, 1] \rightarrow \mathcal{M} \\ c(0)=x, c(1)=y}} \text{Length}(c),$$

defines a distance on \mathcal{M} . We call it the **Riemannian distance**.

With that distance, \mathcal{M} is a metric space.

The **metric topology** and the **manifold topology** are the **same**.

continuous: $x \mapsto \text{dist}(x, y)$ | $\{x \in \mathcal{M} : \text{dist}(x, y) < r\}$ open

Fact: If there exists a curve segment $c: [0,1] \rightarrow \mathcal{M}$ from x to y such that $\text{Length}(c) = \text{dist}(x, y)$, then c is a geodesic.

We call such c a **minimizing geodesic**.

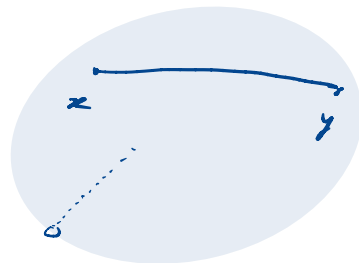
with time parametrization s.t.
 $\|c'(t)\|_{c(t)}$
is constant.

Def.: x_0, x_1, x_2, \dots is a **Cauchy sequence** if its points eventually get arbitrarily close: $\forall \varepsilon > 0, \exists K$ s.t. $\text{dist}(x_k, x_\ell) < \varepsilon$ for all $k, \ell \geq K$.

Def.: \mathcal{M} is **metrically complete** if all Cauchy sequences converge.

Fact: On a complete and connected manifold,
each pair x, y is connected by a minimizing geodesic.

Completeness is sufficient but not necessary.



Metric completeness captures more than existence of minimizing geodesics: it captures the fact that geodesics “keep going forever”.

Recall: a curve c is a **geodesic** if $\frac{D}{dt} c'(t) = 0$ for all t .

This is a smooth **differential equation**:

The solution c is uniquely determined by **initial conditions** $c(0) = x$ and $c'(0) = v$.

But $c(t)$ is not necessarily defined for all t : what can stop it?

Def.: \mathcal{M} is **geodesically complete** if all geodesics exist for all $t \in \mathbf{R}$.

Theorem (Hopf–Rinow). For \mathcal{M} connected, these are **equivalent**:

- \mathcal{M} is geodesically complete;
- \mathcal{M} is metrically complete;
- A subset of \mathcal{M} is compact iff it is closed and bounded.

Example: If \mathcal{M} is embedded in \mathcal{E} and closed in \mathcal{E} , it is complete.