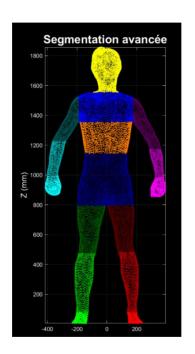
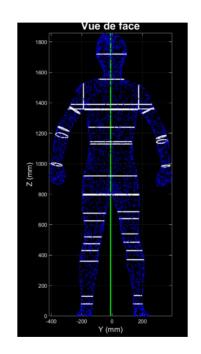
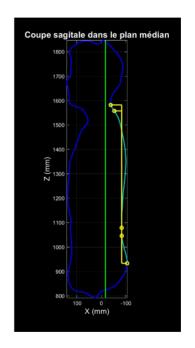
# Youdome 3D avatar reconstruction and measurement software For pro sport and health care diagnosis

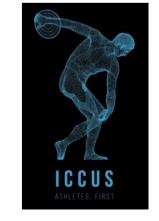








Nicolas Douillet, R&D engineer in body scanning 2018 - 2019



#### **Outline**

Overall goal: automate, improve and accelerate tape measure

body limb girths. Compute athlete's biometric profile



- (1): Point set processing
- (2): Mesh processing
- (3): Body measurements on mesh and results
- (4): Video demos
- (5): Data management and computation optimization
- (6): Customers, collaborations and partnerships

#### The dome



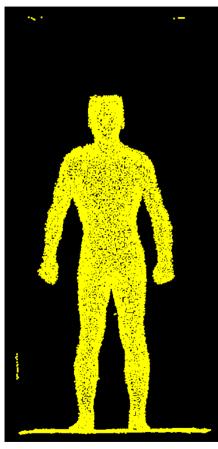
- Geodesic dome (truncated v-2-0 geoid)
- Acquisition system and computer inside.
- 20 IR sensors.

#### Point set processing steps

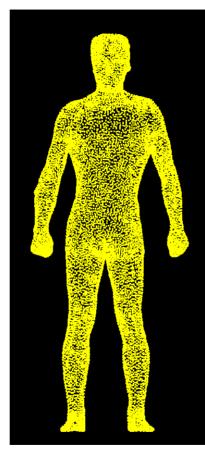
- (1): Realignement + bounding box thresholding
- (2): Outlier removal
- (3): Smoothing
- (4): Grid simplification / random decimation
- (5): Vertex normals computation

-

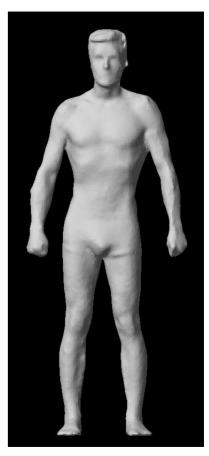
#### Point set processing



Raw noisy point set With artefacts



Processed point set



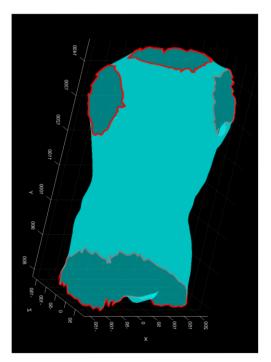
Reconstructed surface (triangular mesh)

#### Mesh processing steps

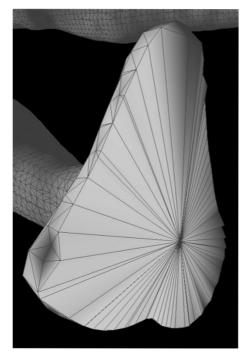
- (1): Holes and boundary detection, simplification, smoothing, hole filling
- (2): Mesh subselection and substripe selection
- (3): Isotropic **mesh slicing** algorithm
- (4) : Avatar slicing video
- (5): Avatar stick skeleton
- (6): Avatar advanced segmentation and labelling
- (7): Vectorized / oriented slicing

#### Hole and boundary detection, hole filling

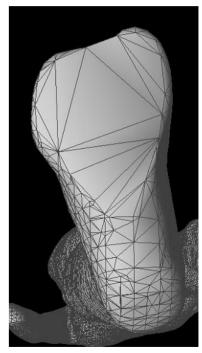
→ Need to cut the mesh above the ground (~zero level altitude thresholding) to correct Poisson mesh bulky reconstructed feet.



Boundary detection



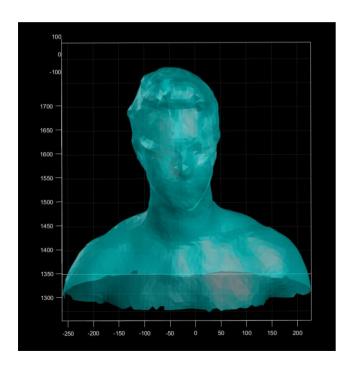
Feet cut hole filling I Contour isobarycentre

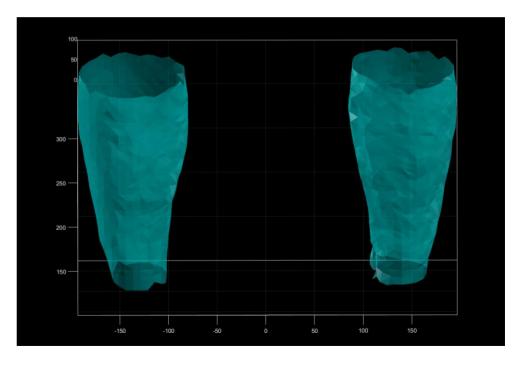


Feet cut hole filling II
Ensure curvature continuity

#### Mesh subselections

- Vectorized bounding boxes basic principle (point set then mesh)
- Usefull for segmentation and for CPU performances improvement
- → Avoid to process all the mesh and allows instead to select only the area of interest.



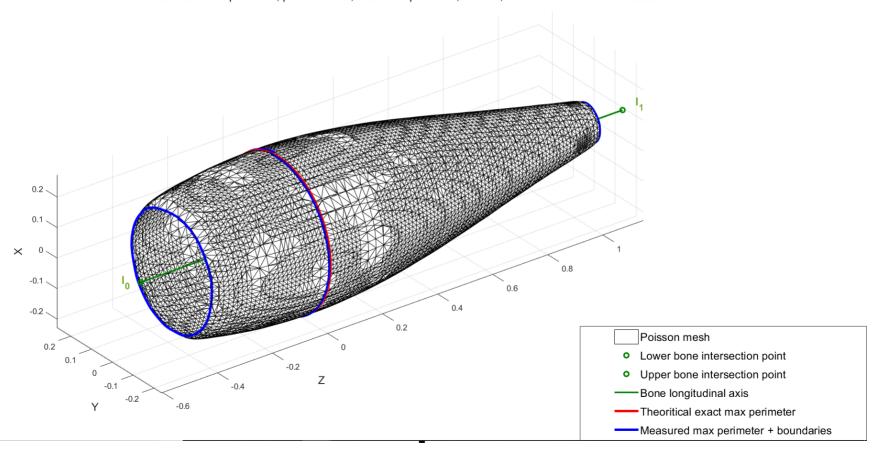


Bust

#### Mesh slicing beginings 1: simulation data

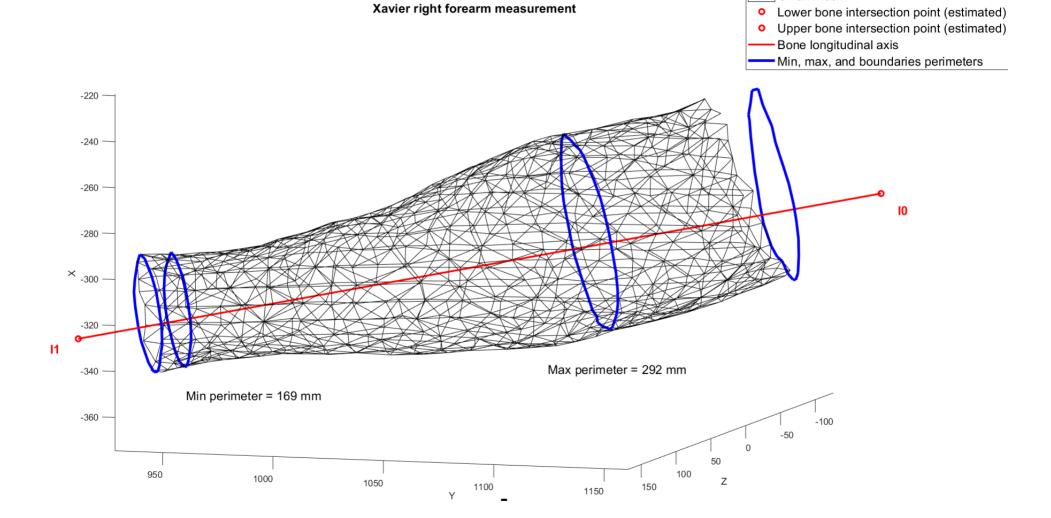
Muscle modelization (point set + mesh) and measure its transversal slice perimeter

Theoritical exact perimeter, pi/2 = 1.5708; measured perimeter, 1.5948; Relative error  $\Delta$   $\epsilon$  /  $\epsilon$  = 1.53%



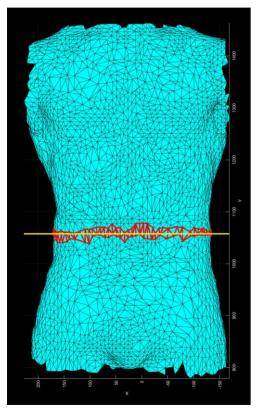
#### Mesh slicing beginings 2: real data

Given mesh

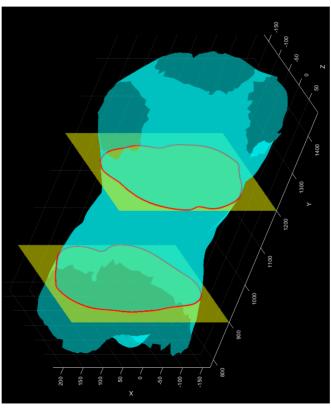


#### Mesh slicing

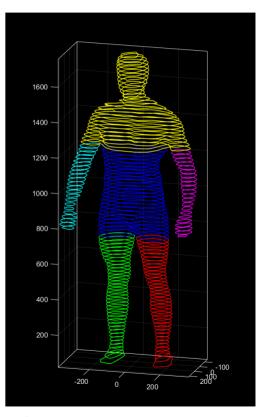
- Exact and robust slices
- Compute new points (intersections)



Triangles belt selection

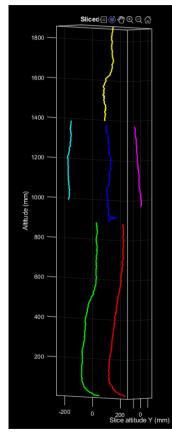


Avatar slices

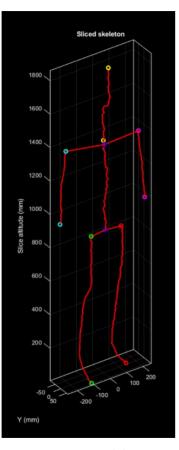


Sliced rebuilt avatar

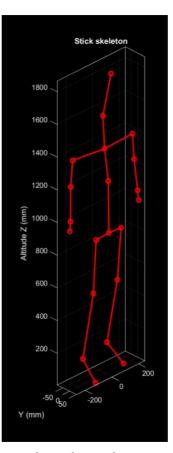
#### Stick skeleton computational steps



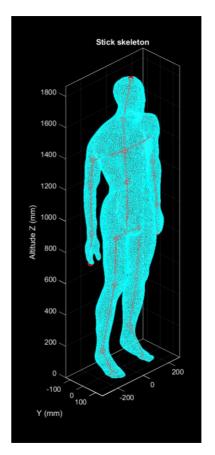
Sliced skeleton

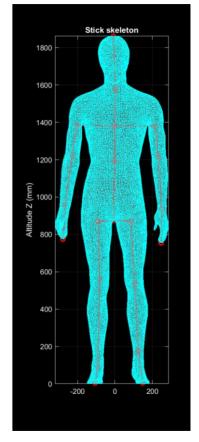


+ extremities & junctions



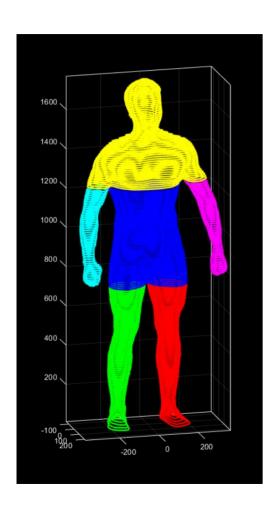
+ landmarks





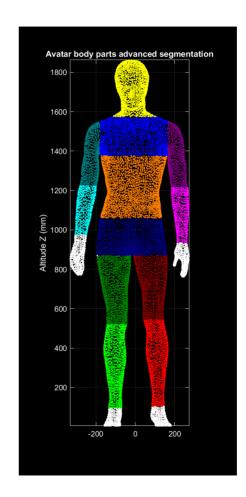
→ Avatar advanced segmentation

#### Segmentations steps



## Avatar 1st rough segmentation

- 4 limbs + trunk + bust
- based on evolution of contours number
- Robust, but lacks of accuracy for further measurements



## Avatar 2nd full segmentation

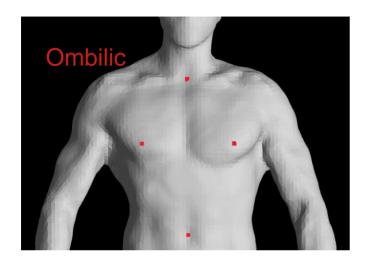
- 8 half limbs
  - + 4 extremities
  - + head
  - + 3 parts trunk
- Uses landmarks Information in addition and relative position location a priori.
- Best accuracy

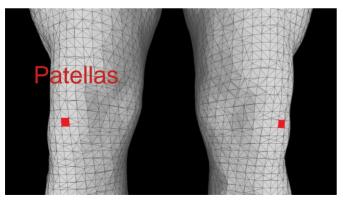
#### Body measurements on mesh and results

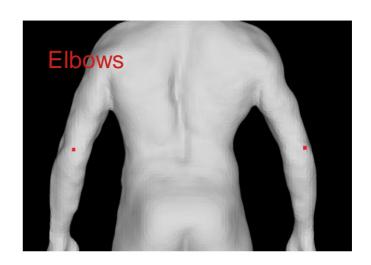
- (1): Landmarks level / altitude detection
- (2): Limb girths and body perimeter curves
- (3): Lumbar profile extraction and bending values estimation
- (4): 2D Convex hull in 3D option for slices girth

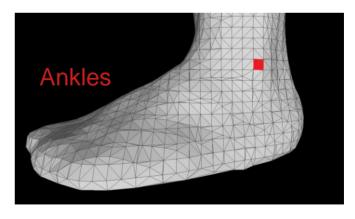
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#### Landmarks detection: examples



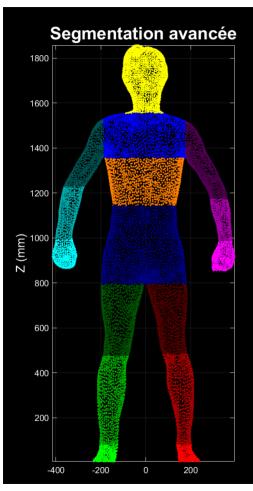




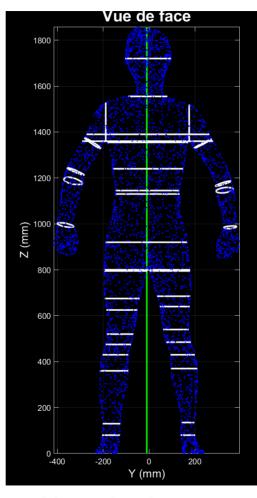


Required precision on landmarks location: ~5 cents coin diameter

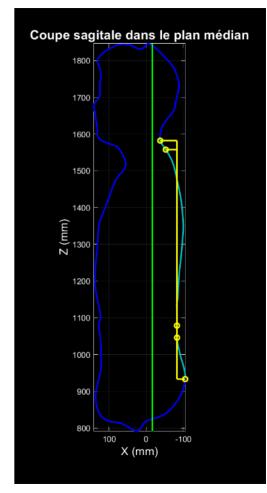
### Results: limb girths



Advanced segmentation

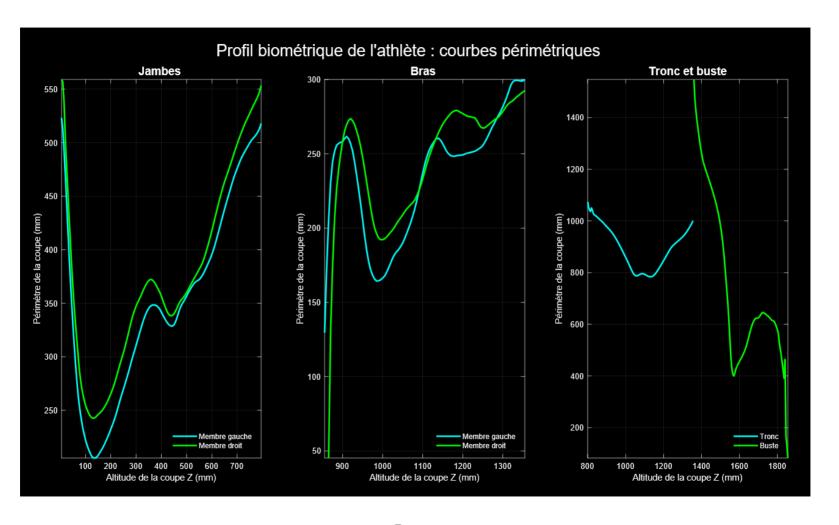


Vectorized slicing

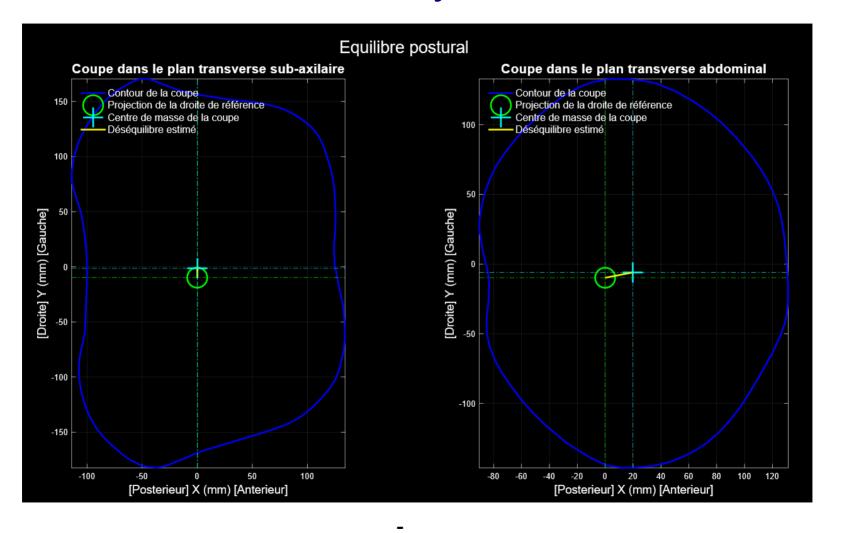


Lumbar profile

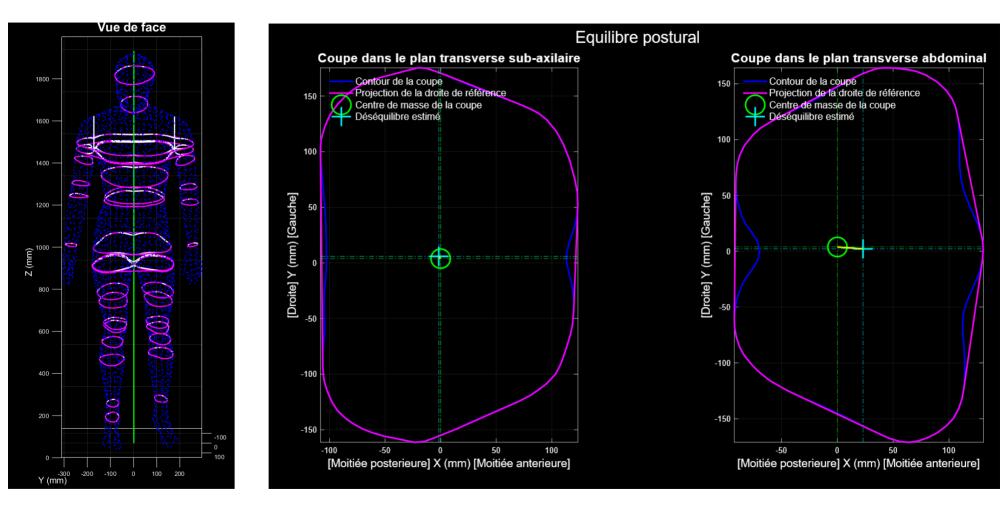
#### Results: athlete's body shape profile



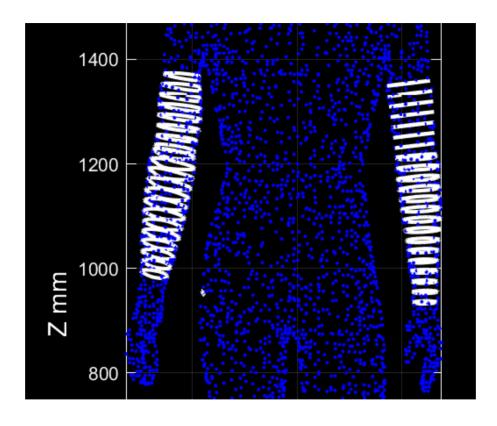
#### Results: athlete's body balance estimation



#### Convex hull of the slice



#### Vectorized / oriented slicing



Advanced segmentation allows to perform a second slicing, which axis is oriented following the limb longitudinal direction, and provides the best measurement accuracy for avatar upper limb girths especially.

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#### Video demo I : slicing + athlete's biometric profile

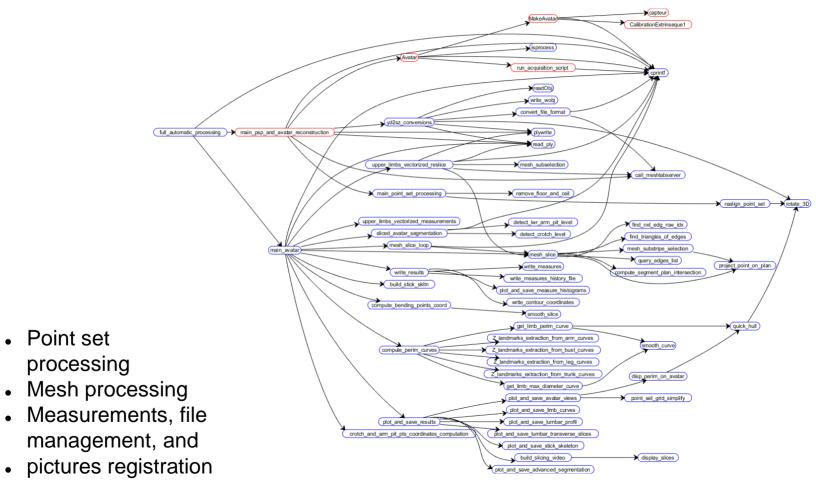


## Data management and computation optimization

- Body scan (x3) + avatar point set generation : < 5s (Christian Barat)
- Point set processing + mesh generation + mesh processing + measurements : ~45s highly depending on avatar resolution (number of triangles).
- Code vectorization
- Parallel processing : for and while loops for the slicing algorithm
- Anonymous (RGPD) athlete scan automatic folder and files creation and biometric data analysis update.

-

#### Functions graph



Platform interface

Point set

#### Main challenges to rise and solutions found

| Challenges  | Solutions   |
|---|---|
| Wide range of body shapes and morphologies (men / women, body mass index, young, old, body shape adaptation / specialization to sport). | → Integration of lots of test avatars with various morphologies<br>(boxers, dancers, tennismen, climbers, swimmers, football<br>players, bodybuilders, etc.). |
| Body imperfections and asymetries.  | → Global approach but no projection on an average morphology avatar.  |
| Human morphological positioning and ratio a priori.   | → Local and relative landmarks positioning, human ratio tables.   |
| Body positioning, hands, long « wild » hairs.   | → Body positioning protocole + beany.   |
| Landmarks location algorithm and location precision.  | → Advanced segmentation and relative landmarks positioning  |
| Computational ressources minimization (time, memory).   | → Vectorization, // processing, submesh selection, code<br>optimization, point set and mesh simplifications.  |

-

#### Main partnerships and customers

Monaco football club



Les ballets de Monte Carlo (Monaco princess Grace dance academy)

 Reknown sportsmen in tennis, boxing, bodybuilding swimming, etc... (confidential)

#### Main collaborations

- Christian Barat, I3S / INRIA
   Acquisition, point set generation,
   3D reconstruction
- Maks Ovsjanikov, LIX Polytechnique Landmarks detection

- Clément Lavallard, Iccus / Diocles CEO

## Thank you!