

# Application of the Level Method for Computing Locational Convex Hull Prices

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# Pricing under non-convexities

$$\min_{c,p,u,f} \sum_{g \in \mathcal{G}} c_g \quad (1a)$$

$$(\pi_t^i) \quad \sum_{g \in \mathcal{G}_i} p_{g,t} - D_t^i = \sum_{\substack{l \in \\ from(i)}} f_{l,t} - \sum_{\substack{l \in \\ to(i)}} f_{l,t} \quad \forall i, t \quad (1b)$$

$$(c_g, p_{g,t}, u_{g,t}) \in \mathcal{X}_g \quad \forall g \in \mathcal{G} \quad (1c)$$

$$f \in \mathcal{F} \quad (1d)$$

## Typical market clearing problem

Minimize costs

Market clearing constraint (supply = demand)

Supply (generator / orders) technical constraints

Network constraints

- In a competitive market, a **market operator** computes:
  - Market **matches** (commitment & dispatch)
  - Market **prices**
- Good price signals are essential in a competitive market
- In **convex cases**, the dual variable associated to (1b) is an **equilibrium price**

$$\max_{c,p,u} \sum_t p_{g,t} \pi_t^{i(g)} - c_g \quad (2a)$$

$$(c_g, p_{g,t}, u_{g,t}) \in \mathcal{X}_g \quad (2b)$$

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Non-convexities are at the heart of power system operations:

- the **Network model** (the AC power flow equations)
- **Market orders** (the MIP constraints that describe the market offers)

$$c_g \quad (2a)$$

$$(c_g, p_{g,t}, u_{g,t}) \in \mathcal{X}_g \quad (2b)$$

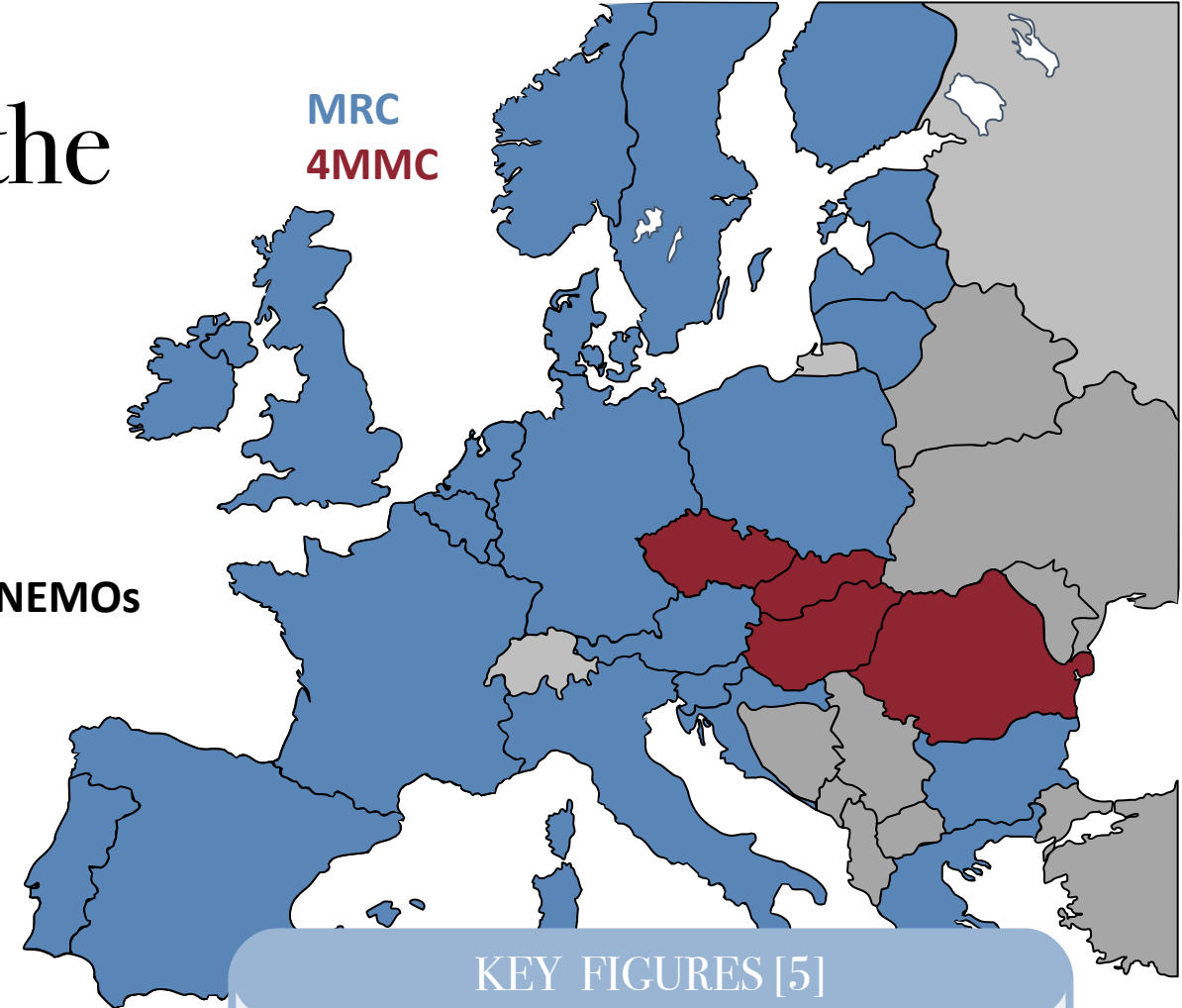
- In **convex cases**, the dual variable associated to (1b) is an **equilibrium price**

# Convex hull pricing (CHP) minimizes uplifts

- Under non-convexity: impossible to find a set of equilibrium uniform prices
  - Combine the **uniform price** with **discriminatory payments (uplifts)** to restore the proper incentives
  - Popular non-uniform pricing schemes include:
    - **IP pricing** proposed by O'Neill [1]
    - **Convex hull pricing** proposed by Gribik and Hogan [2-3]
    - **Extended LMP pricing**, applied in the PJM market [4]
- **Convex Hull Pricing minimize uplifts**
  - Uplifts are undesirable
    - Distort the incentives of bidders
    - Create revenue adequacy problems for the market operator
  - But CHP is computationally challenging!  
→ **Our research aims at addressing these computational challenges**

# CHP is also considered in the EU day-ahead market

- CHP has been so far mainly debated in the US (e.g. PJM)
- But it has recently received consideration by the European NEMOs as a possible option for the European DA energy auction [5]
- **The European DA market** is a huge market
  - Runs once per day
  - Couples EU countries
  - Set the **dispatch** and the **electricity prices**
  - Complex institutional structure:
    - **TSO** (regulated monopoly): Elia, RTE, Statnett, etc.
    - **NEMO**: EPEX SPOT, Nord Pool, etc.
  - Market clearing **algorithm**: **EUPHEMIA**



## KEY FIGURES [5]

- Geographical ext.: **27** countries
- TSOs: **35**
- NEMOs: **16**
- Traded vol.: **4.08** TWh/session
- Welfare: **8.8** B€/session
- Convex bids: **>200,000** /session
- Non-convex bids: **>5,000** /session

## Introduction

- Pricing under non-convexity
- Main concepts related to Convex Hull Pricing (CHP)
- EU day-ahead market context

## CHP formulation

- Mathematical formulation of CHP
- Algorithmic schemes to compute CHP

## The Level Method

- Kelley's algorithm
- Level stabilization
- Adaptation of the basic algorithm to CHP specificities

## Numerical Results

- Size of the EU day-ahead market problem
- Comparison of the Level Method and the Dantzig Wolfe algorithm on EU instances

## Conclusion

- Perspective for future research

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# Minimizing the uplifts amounts to solving a Lagrangian relaxation

$$\pi^{CHP} = \arg \max_{\pi} L(\pi) \quad (3)$$

$$L(\pi) = \sum_{i,t} \pi_t^i D_t^i \quad (4a)$$

$$- \sum_{g \in \mathcal{G}} \max_{(c,p,u)_{g \in \mathcal{X}_g}} \left\{ \sum_t p_{g,t} \pi_t^{i(g)} - c_g \right\} \quad (4b)$$

$$+ \min_{f \in \mathcal{F}} \left\{ \sum_{i,t} \pi_t^i \left( \sum_{\substack{l \in \\ from(i)}} f_{l,t} - \sum_{l \in to(i)} f_{l,t} \right) \right\} \quad (4c)$$

## Property 1 (Concave).

Function  $L(\pi)$  is concave in  $\pi$ .

## Property 2 (Non-smooth).

Function  $L(\pi)$  is a *non-smooth (piecewise linear)* function, i.e. each facet can be seen as corresponding to a set of binary (commitment) decisions  $u_g$ .

## Property 3 (First-order oracle).

A first-order oracle is available, i.e. given a price  $\pi$ , both the function value  $L(\pi)$  as well as its supergradient  $g \in \partial L(\pi)$  can be evaluated.

## Property 4 (Supergradient).

Let  $(c^*, p^*, u^*, f^*)$  be the optimal reactions to  $\pi$  (solving respectively (4b) and (4c)). Then

$g = D_t^i - \sum_{g \in \mathcal{G}} p_{g,t}^* + \sum_{l \in from(i)} f_{l,t}^* - \sum_{l \in to(i)} f_{l,t}^*$  is a supergradient of  $L$  in  $\pi$ ; i.e.  $g \in \partial L(\pi)$



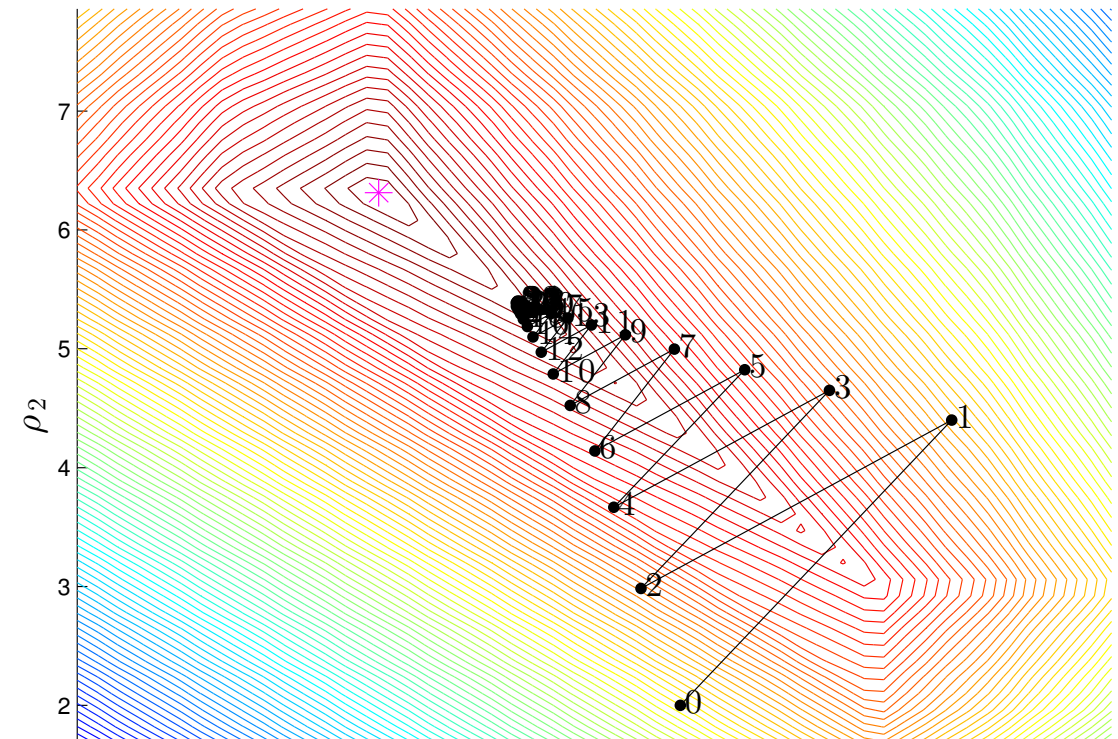
# An example: the subgradient algorithm

Toy example [6]				
Demand: [30, 40] MW		Two-periods, single node		
$G$	$C_g^P$	$C_g^{SU}$	$P_g^{\min}$	$P_g^{\max}$
SMOKESTACK01	3	53	0	16
SMOKESTACK02	3	53	0	16
SMOKESTACK03	3	53	0	16
HIGH_TECH01	2	30	0	7
HIGH_TECH02	2	30	0	7
MED_TECH01	7	0	2	6

## GENERIC ALGORITHMIC SCHEME

1. Given a price  $\pi_k$ ,  $L(\pi_k)$  and  $\partial L(\pi_k)$  are evaluated
2. Given this information, a new price  $\pi_{k+1}$  is generated
3. If stopping criterion, stop. Otherwise, go to 1

Lagrangian value function and Subgradient path



- **Supgradient** algorithm is **memoryless**
  - Typical oscillation behavior
- In moderate dimension, such as for our CHP problem, there are more optimistic algorithmic schemes

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# The Kelley's algorithm [7]

- Basis for the Level Method
- Based on the idea of iteratively constructing a **model**: the piecewise linear function  $L(\pi)$  is **upper-approximated** at each iterate by a model function  $\hat{L}(\pi, k)$  consisting of **supporting hyperplanes**

**Model  
function**

$$\hat{L}(\pi, k) = \min_{j=0..k} [\langle g_j, \pi - \pi_j \rangle + L(\pi_j)] \quad (5)$$

**Master  
program**

$$\begin{aligned} \max_{\pi \in Q, \theta} \quad & \theta \\ \text{s.t.} \quad & \theta \leq \langle g_j, \pi \rangle + b_j \quad \forall j = 0..k \end{aligned} \quad (6)$$

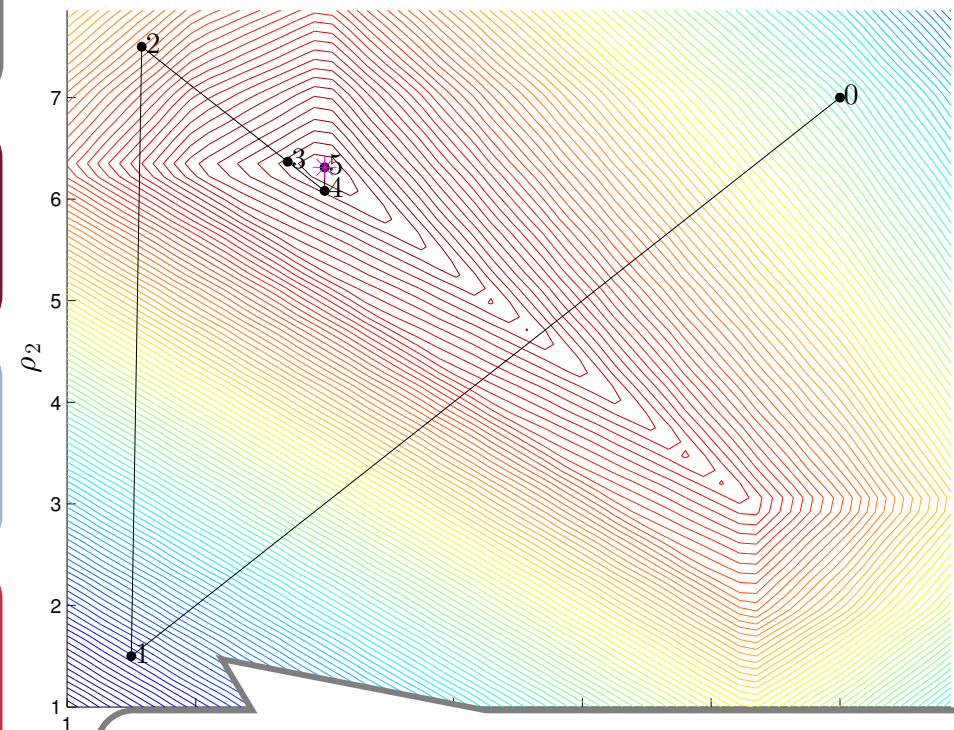
**Update rule**

$$\pi_{k+1} = \arg \max_{\pi} \hat{L}(\pi, k). \quad (7)$$

**Stopping  
criterion**

$$\frac{UB_k - LB_k}{|UB_k|} \leq \epsilon \quad (8)$$

Lagrangian value function and Kelley path



- Oscillations already appear in low dimension
- **Unstable** in high dimension: adding a new supporting hyperplane can move the optimum far from the previous point

# The Level stabilization [7]

- The underlying idea of the Level Method is to **update prices more smoothly**
- Select the next iterate  $\pi_{k+1}$  so that it is better than  $\pi_k$  (as evaluated by  $\hat{L}(\pi, k)$ ), without being optimal at all costs

Same **Model**  
function as Kelley

Same **Master**  
program as Kelley

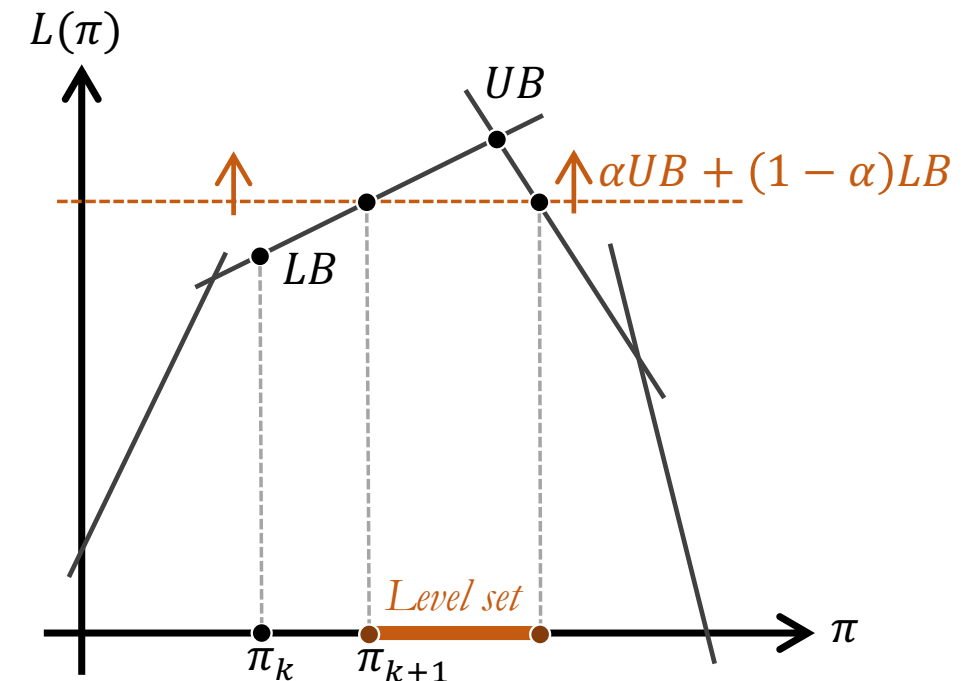
**NEW Update rule**  
Projection prog.

Same **Stopping**  
criterion as Kelley

$$\begin{aligned} \min_{\pi \in Q} \quad & \|\pi - \pi_k\|_2^2 \\ \text{s.t.} \quad & \langle g_j, \pi \rangle + b_j \geq \alpha UB_k + (1 - \alpha) LB_k \quad \forall j = 0..k \end{aligned} \quad (9)$$

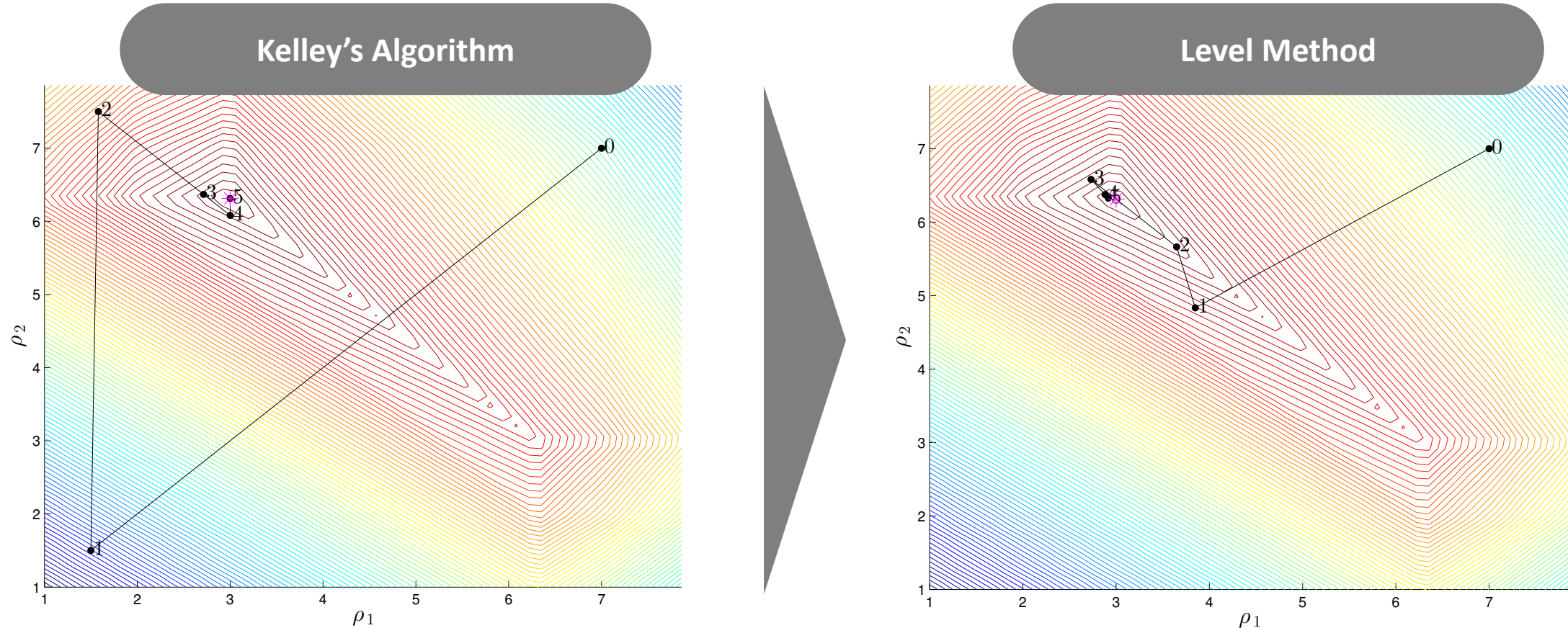
$\alpha$  is the **projection parameter**

- $\alpha = 1$  : Kelley's algorithm
- $\alpha = 0$  : the iterate does not move





# The Level Method stabilizes Kelley's path – illustration on 2D example



# Two adaptation of the Level Method to the CHP specificities

**Two tricks** can improve the classical Level formulation to the specificities of the CHP problem

$$L(\pi) = \sum_{i,t} \pi_t^i D_t^i \quad (4a)$$

$$- \sum_{g \in \mathcal{G}} \max_{(c,p,u)_g \in \mathcal{X}_g} \left\{ \sum_t p_{g,t} \pi_t^{i(g)} - c_g \right\} \quad (4b)$$

$$+ \min_{f \in \mathcal{F}} \left\{ \sum_{i,t} \pi_t^i \left( \sum_{l \in \text{from}(i)} f_{l,t} - \sum_{l \in \text{to}(i)} f_{l,t} \right) \right\} \quad (4c)$$

All generators are separable  $\rightarrow$  write one upper approximation  $\theta_g$  per generator (one cut per generator) **1**

- Dualize the convex network equations
- Insert it back into the Lagrangian function (i.e. it becomes explicit variable of the master & projection) **2**

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# Computing CHP in the European day-ahead auction

## Requirements [5]



- Euphemia is afforded **12 minutes** of run time



- The market model includes a network of ~ **40 bidding zones**, and its geographic footprint is expected to be further enlarged



- The market model is expected to move towards **15-minute granularity** by 2022 (a horizon of **96 periods**)

## Test cases



- We focus on the sensitivity of the algorithms towards the **dimension of the price space** (the ultimate goal is to compute **prices** optimizing  $L(\pi)$ )



- Tested on 2 sets of cases
  - FERC data** (11 instances, no network, >900 generators) [8]
  - Central Europe data** (6 times series, 2 different networks) [9]



- The Level Method is benchmarked against a **Dantzig-Wolfe algorithm** [10]

TABLE II  
DESCRIPTION OF THE SIZE OF THE EU INSTANCES.

Test case	Bidding Zones	Lines	Generators
<b>BE</b>	30	30	74
<b>BE-NL</b>	59	63	145



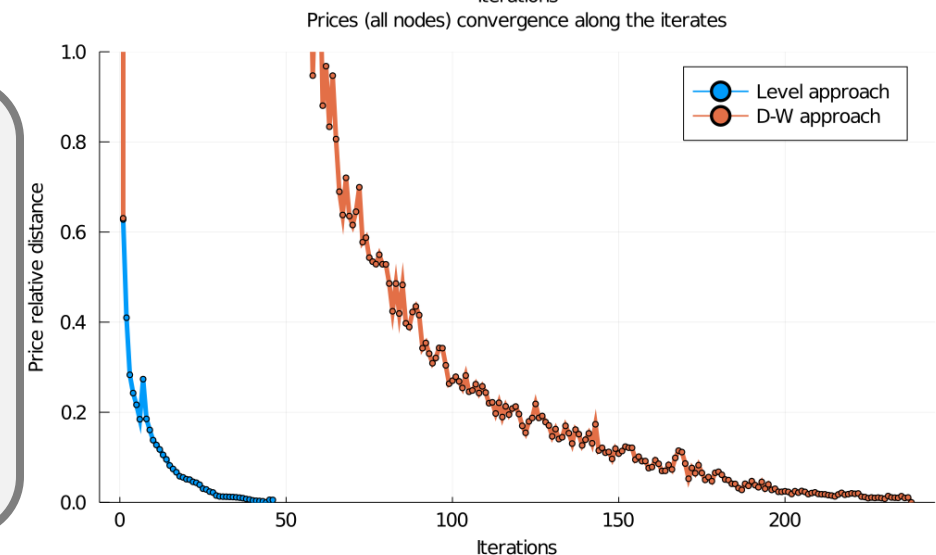
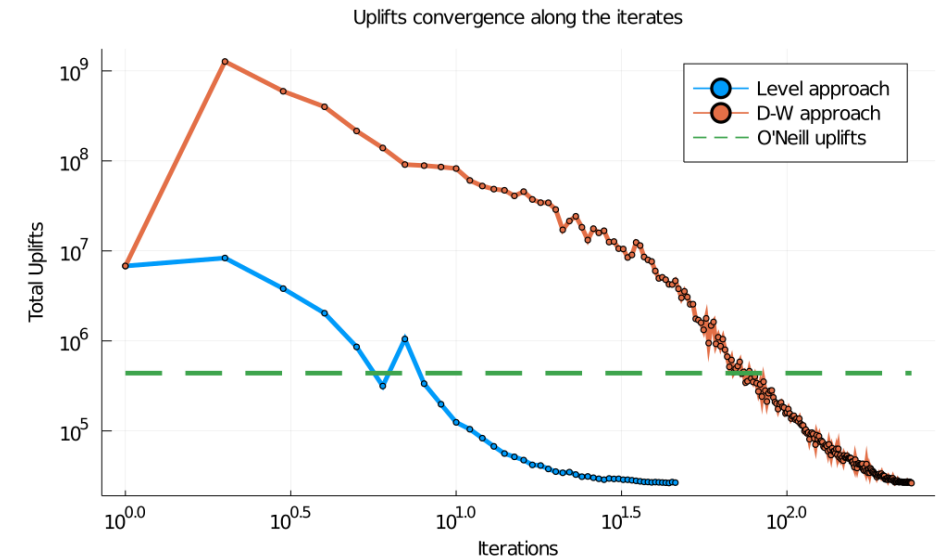
# Comparison of the Level Method and Dantzig-Wolfe algorithm

TABLE III  
RESULTS OF THE LEVEL METHOD AND THE DANTZIG-WOLFE  
ALGORITHM ON THE BE TEST CASE FOR DIFFERENT TIME HORIZONS  
(AVERAGE OVER 6 INSTANCES).

horizon	Dispatch Cost [€]	IP Uplifts [€]	CHP Uplifts [€]	Level iter	Level av. time per iter <sup>a</sup> [s]	D-W iter	D-W av. time per iter <sup>a</sup> [s]
12	2,767,841	398,003	6,621	22	0.5 (0.05)	18	0.3 (0.02)
24	4,963,246	144,125	10,149	28	0.8 (0.1)	39	0.6 (0.1)
48	11,335,441	288,741	20,746	32	1.9 (0.4)	78	1.9 (0.3)
96	24,104,303	2,587,632	28,987	46	6.4 (1.8)	241	6.5 (2.1)

<sup>a</sup> (·) denotes the average time per iterate for solving the “master programs”  
(i.e. master plus projection in the case of the Level Method).

- Implementation
  - Julia (JuMP)
  - Run on a personal computer (Intel Core i5, 2.6 GHz, 8 GB of RAM)
  - Gurobi 9.1.1
  - Stopping criterion: 0.01%
- **Iteration count:** < 50 iterates
- **Robustness:** the Level Method reaches quickly good price candidates (valuable since clearing time limited to 12 min)



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# Conclusion

- The Level Method exhibits **favorable empirical performance** to solve Convex Hull Pricing problem
- It is capable to **compute Convex Hull Prices on large instances** including network and a horizon of 96 periods (which anticipates future EU DA market evolution)
- Further promising paths of research:
  1. **Expanding tests** on realistic instances of Euphemia
  2. Examining the **effects of non-uniform pricing on enhancing welfare** in the EU day-ahead market
  3. Understanding **distributional effects** of non-uniform pricing as well as **gaming effects**

# Thank you!

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