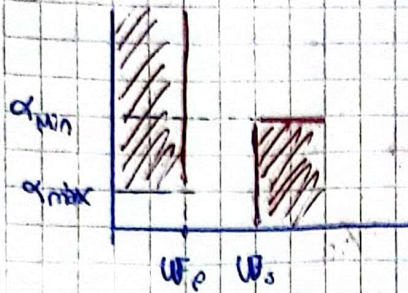


TP Semanal 3



$$\alpha_{min} = 12 \text{ dB}$$

$$\omega_s = 2\pi \cdot 3000 \text{ Hz}$$

$$\alpha_{max} = 1 \text{ dB}$$

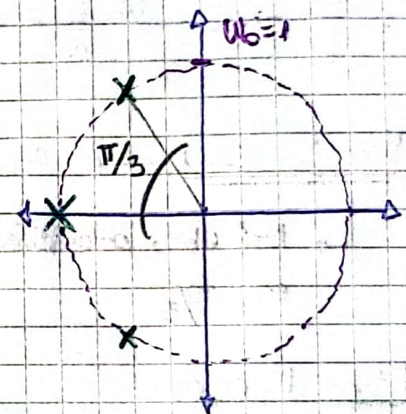
$$\omega_p = 2\pi \cdot 1500 \text{ Hz}$$

* Normalizado $\omega_p = 1$ $\omega_s = 2$ $\omega_c = 2\pi \cdot 1500 \text{ Hz}$

* Armo Pz map

↳ n: impar \rightarrow polo sobre el eje real

↳ polos separados π/n



$$\frac{1}{2 \cos(\pi/3)} = Q = 1$$

* Cálculo n

$$\alpha_{min} < 10 \log(1 + \epsilon^2 \omega_s^{2n})$$

Iteración:

n	α_{min}
1	3,087 < 10
2	7,11 < 10
3	12,45 > 10 $\checkmark \rightarrow n=3$

* Armo Transferencia

$$|T(\omega)|^2 = \frac{1}{1 + \epsilon^2 \omega^{2n}}$$

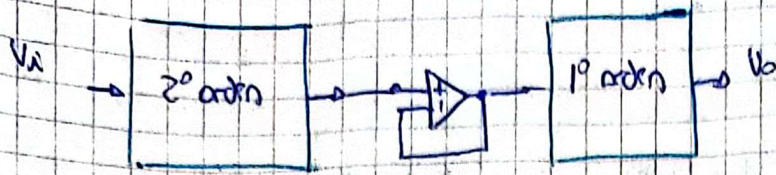
* Renormalizo

$$\omega_c = \frac{2\pi \cdot 1500 \text{ Hz}}{\sqrt{\epsilon}} = 11805 \frac{\text{rad}}{\text{s}}$$

$$|T(\omega)|^2 = \frac{1}{1 + \omega^{2n}}$$

NOTA

* Diseño Crawlto



* Etapa 2º orden

$$\frac{V_o}{V_i} = \frac{\frac{1}{j\omega C}}{\frac{1}{j\omega C} + j\omega L + R} = \frac{\frac{1}{j\omega C}}{\frac{1}{j\omega C} + j\omega \frac{L}{C} + \frac{R}{C}} = \frac{\frac{1}{j\omega C}}{j^2 \omega^2 \frac{L}{C} + j\omega \frac{R}{C} + \frac{1}{C}}$$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

$$\frac{\omega_0}{Q} = \frac{R}{L} \Rightarrow Q = \omega_0 \frac{L}{R} = \frac{1}{R} \sqrt{\frac{L}{C}}$$

Normalizado

$$\omega_0 = 1 \rightarrow L = 1/C$$

$$Q = 1 \rightarrow R = L$$

Necesito $Q=1 \rightarrow R=1 ; C=1 ; L=1$

Así ubicar polos en $\pi/3$

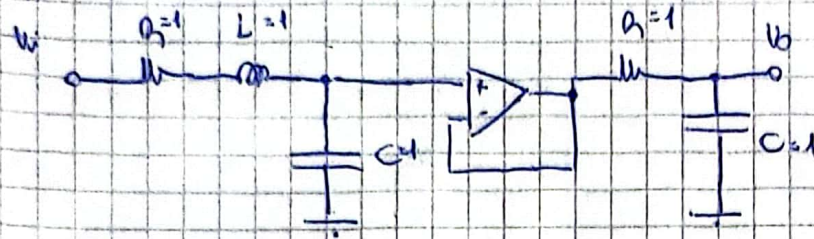
* Etapa 1º orden

$$\frac{V_o}{V_i} = \frac{\frac{1}{j\omega C}}{\frac{1}{j\omega C} + R} = \frac{1}{j\omega CR + 1} = \frac{1/CR}{j\omega + 1/CR}$$

Necesito polo en $-1 \rightarrow \frac{1}{j\omega + 1} \rightarrow \frac{1}{CR} = 1$

Normalizado $R = \frac{1}{C} \rightarrow R=1$
 $C=1$

* Respeto Circuito



* Respeto Valores Realiz

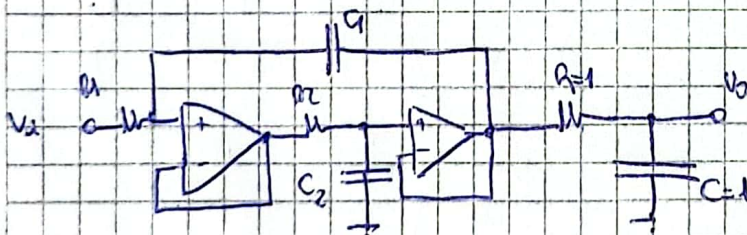
$$R_1 = 1 \cdot \Omega \rightarrow R_1 = 847 \Omega \leftarrow$$

$$L = 1 \cdot \frac{\Omega}{s} \rightarrow L = \frac{847 \Omega}{11805 \frac{\text{rad}}{\text{seg}}} = 71,75 \text{ mH} \leftarrow$$

$$C = 100 \text{ nF} = \frac{1 \cdot \frac{1}{s}}{\Omega \cdot \frac{1}{s}} \Rightarrow \Omega \cdot \frac{1}{100 \text{ nF} \cdot \frac{1}{s}} = \frac{1}{100 \text{ nF} \cdot 11805 \frac{\text{rad}}{\text{seg}}} = 847 \Omega$$

* Modifico Circuito para no usar inductores

↳ Implemento pasabajas bicuadrado



$$\omega_0 = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}} \rightarrow R_1 R_2 C_1 C_2 = 1$$

$$\left. \begin{array}{l} R_1 = 1 \quad R_2 = 1 \\ C_1 = 1 \quad C_2 = 1 \end{array} \right\}$$

→ Mismos valores que antes

$$Q = \sqrt{\frac{R_1 C_1}{R_2 C_2}} = 1 \rightarrow R_1 C_1 = R_2 C_2$$

Cálculo del sistema con método por transformación:

$$|H(j\omega)|^2 = \frac{1}{1 + \epsilon^2 \cdot \omega^{2n}} \quad n=3$$

$$\epsilon = 0,5088$$

Cambio de Dominio

$$|H(j\omega)|^2 = \frac{1}{1 + \epsilon^2 \cdot \left(\frac{\phi}{j}\right)^{2n}} = \frac{1}{1 - \epsilon^2 \cdot \phi^{2n}} = H(\phi) \cdot H(-\phi) =$$

ejemplo n=3

Por igualación de términos

$$\begin{aligned} 1 &= d & -a^2 &= -\epsilon^2 \rightarrow a = \epsilon \\ 0 &= b^2 - 2ac \rightarrow b^2 = 2ac \\ 0 &= c^2 - 2bd \rightarrow c^2 = 2bd \end{aligned}$$

Resolución sistema ecuaciones

$$b = \sqrt{2ac} \rightarrow c^2 = 2\sqrt{2ac} \cdot \phi \rightarrow c^4 = 8ac \rightarrow c = \sqrt[3]{8a} \rightarrow c = 2\epsilon^{1/3}$$

$$\rightarrow b = \sqrt{2\epsilon \cdot 2\epsilon^{1/3}} = 2\sqrt{\epsilon^{4/3}} = 2\epsilon^{2/3}$$

$$H(\phi) = \frac{1/\epsilon}{\phi^3 \cdot \frac{\epsilon}{\epsilon} + \phi^2 \cdot \frac{2\epsilon^{2/3}}{\epsilon} + \phi \cdot \frac{2\epsilon^{1/3}}{\epsilon} + \frac{1}{\epsilon}} = \frac{1/\epsilon}{\phi^3 + \phi^2 \cdot 2 \cdot \epsilon^{-1/3} + \phi \cdot 2 \cdot \epsilon^{-2/3} + 1/\epsilon}$$

$$H(\phi) = \frac{1}{\phi + 1,25} \cdot \frac{1,9654}{(\phi + 0,96203 + 1,0848j) \cdot (\phi + 0,96203 - 1,0848j)}$$

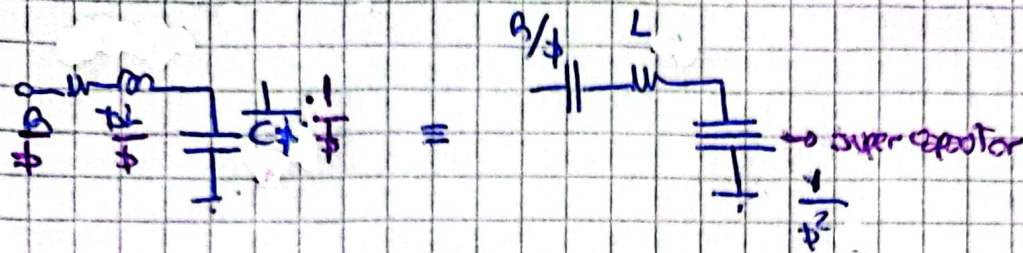
$$= 1,2520 \cdot 1,569$$

$$= \frac{1}{\phi + 1,2520} \cdot \frac{1,9654}{\phi^2 + \phi \cdot 1,2520 + 1,569} = \frac{1,2520}{\phi + 1,2520} \cdot \frac{1,569}{\phi^2 + \phi \cdot 1,2520 + 1,569}$$

Aproximación

$$H(\phi) = \frac{1}{\phi + 1} \cdot \frac{1}{\phi^2 + \phi \cdot 1 + 1} \rightarrow \text{Mismo Transferencia que 2to}$$

Decoupling ALC por girador para co-ovar bobinas



$$H(s) = \frac{\frac{1}{sC} \cdot \frac{1}{s}}{\frac{R}{s} + \frac{sL}{s} + \frac{1}{sC} \cdot \frac{1}{s}} = \frac{\frac{1}{s^2 C}}{\frac{R}{s} + L + \frac{1}{s^2 C}}$$

