XML GUIDE FOR DUALSPHYSICS

COUPLING WITH MOORDYN+ SPECIAL: MOORDYN



July 2020

DualSPHysics team

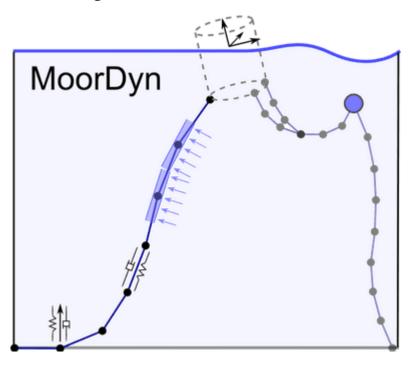
http://dual.sphysics.org

DualSPHysics has been coupled with MoorDyn+ https://github.com/imestevez/MoorDynPlus

MoorDyn+ is a new implementation of MoorDyn http://www.matt-hall.ca/moordyn.html

MoorDyn is an open-source dynamic mooring line model developed by **Matt Hall** MoorDyn discretizes mooring lines as point masses (nodes) connected by linear spring-damper segments to provide elasticity in the axial direction. MoorDyn uses a lumped-mass formulation for modelling:

- axial elasticity
- hydrodynamics
- bottom contact.



```
<special>
    <moorings>
                                               Saves VTK with moorings
        <savevtk moorings value="true" />
        <savecsv points value="true" />
                                               Saves CSV with link points
        <savevtk points value="false" />
                                               Saves VTK with link points
        <mooredfloatings>
            <floating mkbound="45"
                                            mkbound of those moored objects
            <floating mkbound="50" />
        </mooredfloatings>
        <moordyn file="moordyn.xml"</pre>
    </moorings>
</special>
```

Configuration for the MoorDyn+ library can be defined in:

A) a new separated XML file <moordyn file="moordyn.xml" comment="MoorDyn configuration"/>

B) in the same XML including this sections:

```
<moordyn comment="MoorDyn configuration">
    <solverOptions>
        <waterDepth value="0.45" />
        <freesurface value="0" />
        <kBot value="3.0e6" />
        <cBot value="3.0e5" />
        <dtM value="0.001" />
        <frictionCoefficient value="0" />
        <fricDamp value="200" />
        <statDynFricScale value="1.0" />
        <dtIC value="1.0" />
        <cdScaleIC value="2" />
        <threshIC value="0.001" />
        <tmaxIC value="1" />
    </solverOptions>
    <bodies>
    lines>
    <output>
</moordyn>
```

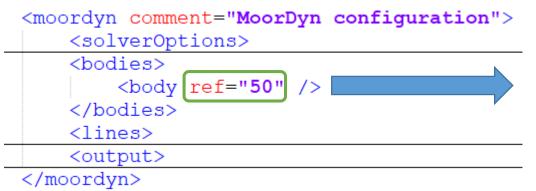
MORE INFORMATION:

http://www.matt-hall.ca/moordyn.html

- -Water depth (m)
- -Z position of free surface (m)
- -Bottom stiffness constant (Pa/m)
- -Bottom damping constant (Pa·s/m)
- -Mooring model time step (s)
- -Bottom friction coefficient
- -Damping coefficient used to model friction at speeds near zero
- -Ratio of static to dynamic friction

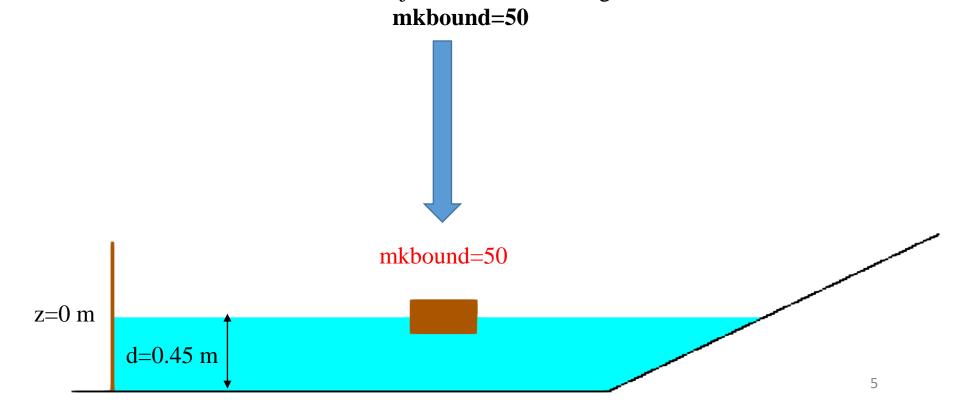
IC: initial conditions

- -Period to analyse convergence of dynamic relaxation
- -Factor to scale drag coefficients
- -Convergence threshold
- -Maximum time without convergence



ref indicates which fluid-driven
 object will be moored
 ref==mkbound

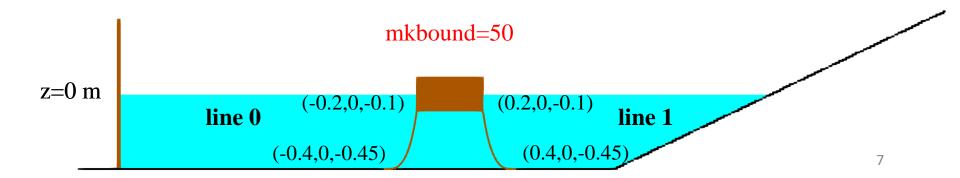
Fluid-driven object to attach mooring lines:



```
ea: line stiffness (N)
<moordyn comment="MoorDyn configuration">
                                                    elasticity modulus * cross-sectional area
    <solverOptions>
    <bodies>
                                                    diameter: volume-equivalent diameter (m)
    lines>
                                                    massDenInAir: mass per unit length (kg/m)
         <linedefault >
              <ea value="2.9e3" />
                                                    ba: internal damping (Ns)
              <diameter value="3.656e-3" />
              <massDenInAir value="0.0607" />
                                                    can: transverse added mass coefficient
              <ba value="-0.8" />
                                                    cat: tangential added mass coefficient
              <can value="1.0" />
              <cat value="0.0" />
                                                    cdn: transverse drag coefficient
              <cdn value="1.6" />
                                                    cdt: tangential drag coefficient
              <cdt value="0.05" />
              <breaktension value="500" />
                                                    breaktension: Maximum value of tension (N)
              <outputFlags value="pv" />
                                                    outputFlags:
         -: None, p:Positions, v:velocities
         <line> %line 0
                  %line 1
                                                         U:Wave Velocities, t:Tension
         line>
    </lines>
                                                         D:Hydrodynamic Drag Force
    <output>
                                                         d: rate of strain of each segment
</moordyn>
                                                         s:Strain of each segment
                                   mkbound=50
                                                         C:Internal Damping
 z=0 m
          d=0.45 \text{ m}
                                                                                    6
```

Shared properties for each line

```
Connects the line to a fluid-driven object
<line> %line 0
    <vesselconnection bodyref="50" x="-0.2" y="0.0" z="-0.1" />
    < fixconnection x="-0.4" y="0.0" z="-0.45" />
    <length value="0.45" />
    <segments value="40" />
                                         vesselconnection is attached to
    <breaktension value="300" />
                                              the body with ref=50
</line>
<line> %line 1
    <vesselconnection|bodyref="50"|</pre>
                                     x="0.2" v="0.0" z="-0.1" />
    < fixconnection x="0.4" y="0.0" z="-0.45" />
    <length value="0.45" />
    <seqments value="40" />
    <breaktension value="350" />
</line>
```



Output data is saved since **startTime** till **endTime** every **dtOut** seconds

tension: stores tensions of connections types selected for each line **force**: stores forces of connections types selected for each line **velocity**: stores velocities of connections types selected for each line **position**: stores positions of connections types selected for each line type = fixed, vessel, all