

# **Notes of Quantum Mechanics**

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# Preface

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## Chapter 1

# Mathematical Formalism

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## 1.1 Introduction

The formalism of quantum mechanics (QM) involves symbols and methods for denoting and determining the time dependent state of a physical system along with a mathematical structure for evaluating the possible outcomes and associated probabilities of measurements.

### State

A **state** is everything knowable about the dynamical aspects of a system at a certain time.

A particle has associated a **wavefunction**  $\psi(\mathbf{r}, t)$  whose probability interpretation resides on  $|\psi(\mathbf{r}, t)|^2$ : it represents the probability density function which serves as a probability finder in space and time. The probability of finding the particle somewhere in space is thus equal to 1:

$$\int_{\text{all space}} d^3r |\psi(\mathbf{r}, t)|^2 = 1. \quad (1.1)$$

Thus, in order that this integral converges, we must deal with a set of square-integrable functions, called  $L^2$ . We can only retain the functions  $\psi(\mathbf{r}, t)$  which are everywhere defined, continuous, and infinitely differentiable  $C^\infty$ . Also, we confine to wavefunctions that have a bounded domain (we can find the particle in a finite region of space).

We list the formal definition of a vector space which is used to define particular vector spaces.

### Vector space

A **vector space** over a field  $F$  (set defined with addition and multiplication) is a non-empty set  $V$  together with a *vector addition* and a *scalar multiplication* that satisfies eight axioms. The elements of  $V$  are called vectors and the elements of  $F$  are called scalars.

Commutativity of vector addition	$\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$	
Associativity of vector addition	$(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$	
Identity element of vector addition	$\exists \mathbf{0}, \mathbf{v} \in V : \mathbf{v} + \mathbf{0} = \mathbf{v}$	
Inverse element of vector addition	$\forall \mathbf{v} \in V, \exists -\mathbf{v} \in V : \mathbf{v} + (-\mathbf{v}) = \mathbf{0}$	(1.2)
Associativity of scalar multiplication	$\alpha(\beta\mathbf{v}) = (\alpha\beta)\mathbf{v}$	
Distributivity over vector addition	$\alpha(\mathbf{u} + \mathbf{v}) = \alpha\mathbf{u} + \alpha\mathbf{v}$	
Distributivity over scalar addition	$(\alpha + \beta)\mathbf{v} = \alpha\mathbf{v} + \beta\mathbf{v}$	
Identity element of scalar multiplication	$1\mathbf{v} = \mathbf{v}$	

When the scalar field is the real numbers, the vector space is called a real vector space, when the scalar field is the complex numbers, then is called a complex vector space.

### Vector space $\mathcal{F}$

The set of wavefunctions  $\mathcal{F} \in L^2$  is composed of sufficiently regular functions of  $L^2$ .

#### 1.1.1 Scalar product

With each pair of ordered elements of  $\mathcal{F}$ ,  $(\varphi(\mathbf{r}), \psi(\mathbf{r}))$ , we associate a *complex number*:

$$(\varphi, \psi) = \int d^3r \varphi^*(\mathbf{r})\psi(\mathbf{r}) \in \mathbb{C}. \quad (1.3)$$

Its properties are listed below:

Adjoint	Linear in the second term	Antilinear in the first term
$(\varphi, \psi) = (\psi, \varphi)^*$	$(\varphi, \lambda_1 \psi_1 + \lambda_2 \psi_2) = \lambda_1 (\varphi, \psi_1) + \lambda_2 (\varphi, \psi_2)$	$(\lambda_1 \varphi_1 + \lambda_2 \varphi_2, \psi) = \lambda_1^* (\varphi_2, \psi) + \lambda_2^* (\varphi_2, \psi)$

If  $(\varphi, \psi) = 0$ , then  $\varphi(\mathbf{r})$  and  $\psi(\mathbf{r})$  are said to be **orthogonal**. In addition, the scalar product of a vector with itself return its *norm squared*:

$$\text{Parseval's theorem} \quad (\varphi, \varphi) = \int d^3r |\psi(\mathbf{r})|^2 \geq 0 \in \mathbb{R}. \quad (1.4)$$

We also have the Schwarz inequality defined with the norms:

$$|(\psi_1, \psi_2)| \leq \sqrt{(\psi_1, \psi_1)} \sqrt{(\psi_2, \psi_2)}. \quad (1.5)$$

### 1.1.2 Linear operators

A linear operator  $A$  is a mathematical entity which associates with every function  $\phi(\mathbf{r}) \in \mathcal{F}$  another function  $\phi'(\mathbf{r})$  linearly:

$$\begin{aligned} \phi'(\mathbf{r}) &= A\phi(\mathbf{r}) \\ A[\lambda_1 \phi_1(\mathbf{r}) + \lambda_2 \phi_2(\mathbf{r})] &= \lambda_1 A\phi_1(\mathbf{r}) + \lambda_2 A\phi_2(\mathbf{r}) \end{aligned} \quad (1.6)$$

Let  $A, B$  be two linear operators, their product  $AB$  on a vector corresponds to the application of  $B$  first, and then  $A$  acts on the new vector  $\varphi(\mathbf{r}) = B\psi(\mathbf{r})$ :

$$(AB)\psi(\mathbf{r}) = A[B\psi(\mathbf{r})]. \quad (1.7)$$

In general, the order of application matter and a way to quantify it is through the **commutator**:

$$[A, B] = AB - BA. \quad (1.8)$$

### 1.1.3 Discrete orthonormal bases in $\mathcal{F} : \{u_i(\mathbf{r})\}$

Definition of discrete orthonormal bases

Let be a countable set of function  $\{u_1(\mathbf{r})\} \in \mathcal{F}$ .

- This set is orthonormal if only the inner product of the same function returns a non-zero value:

$$\text{Orthonormalization relation} \quad (u_i, u_j) = \int d^3r u_i^*(\mathbf{r}) u_j(\mathbf{r}) = \delta_{ij}, \quad (1.9)$$

where  $\delta_{ij}$  is the kronecker function:

$$\delta_{ij} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}. \quad (1.10)$$

- It constitutes a **basis** if every function  $\psi(\mathbf{r}) \in \mathcal{F}$  can be expanded in only **one way** in  $\{u_i(\mathbf{r})\}$  as a linear combination:

$$\text{Expansion} \quad \psi(\mathbf{r}) = \sum_i c_i u_i(\mathbf{r}), \quad (1.11)$$

whose elements of projection  $c_i$  are obtained computing the scalar product  $(u_j, \psi(x))$ :

$$(u_j, \psi) = \left( u_j, \sum_i c_i u_i(\mathbf{r}) \right) = \sum_i c_i (u_j, u_i) = \sum_i c_i \delta_{ij} = c_j.$$

Thus,

$$\text{Coefficient expansion} \quad c_i = (u_i, \psi) = \int d^3r \, u_i^*(\mathbf{r}) \psi(\mathbf{r}). \quad (1.12)$$

Once projected in  $\{u_i(\mathbf{r})\}$  it is equivalent to specify  $\psi(\mathbf{r})$  or the set of  $c_i$ , which represent  $\psi(\mathbf{r})$  in the  $\{u_i(\mathbf{r})\}$  basis. The 3D generalization is given in A-22-A-24.

The scalar product of two wavefunctions can also be expressed in terms of the coefficients of projection. Let be  $\varphi(\mathbf{r}), \psi(\mathbf{r})$ ,

$$(\varphi, \psi) = \left[ \sum_i b_i u_i, \sum_j c_j u_j \right] = \sum_{i,j} b_i^* c_j (u_i, u_j) = \sum_{i,j} b_i^* c_j \delta_{ij}. \quad (1.13)$$

Therefore, the scalar product is:

$$\text{Scalar product} \quad (\varphi, \psi) = \sum_i b_i^* c_i \quad (1.14)$$

Its generalization for 3D is given in A-28.

### Closure relation

Equation (1.9) is called *orthonormalization relation* over the set  $\{u_i(\mathbf{r})\}$ . There is another condition called *Closure relation*, which express the fact that this set constitutes a basis.

If  $\{u_i(\mathbf{r})\} \in \mathcal{F}$ , the any function  $\psi(\mathbf{r}) \in \mathcal{F}$  is decomposed using equation (1.11):

$$\psi(\mathbf{r}) = \sum_i c_i u_i(\mathbf{r}) = \sum_i (u_i, \psi) u_i(\mathbf{r}) = \sum_i \left[ \int d^3r' \, u_i^*(\mathbf{r}') \psi(\mathbf{r}') \right] u_i(\mathbf{r}) = \int d^3r' \, \psi(\mathbf{r}') \left[ \sum_i u_i(\mathbf{r}) u_i^*(\mathbf{r}') \right]$$

This integration with sum will be  $\psi(\mathbf{r})$  only when  $\mathbf{r} = \mathbf{r}'$ , which is characteristic of a delta function centered at  $\mathbf{r} = \mathbf{r}'$ . Thus, the only way to achieve that is that the sum must be a delta function  $\delta(\mathbf{r} - \mathbf{r}')$  and we have

$$\text{Closure relation} \quad \sum_i u_i(\mathbf{r}) u_i^*(\mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}'). \quad (1.15)$$

If an orthonormal set  $\{u_i(\mathbf{r})\}$  satisfies the closure relation then it constitutes a basis.

#### 1.1.4 Bases not belonging to $\mathcal{F}$

The  $\{u_i(\mathbf{r})\}$  bases are composed of square-integrable functions. It can also be convenient to introduce bases of functions **not belonging** to  $\mathcal{F}$  or  $L_2$ , but in terms of which any wavefunction  $\psi(\mathbf{r})$  can nevertheless be expanded. We will discuss two examples: 1D plane wave, and delta functions, after which we will study continuous bases.

## Plane waves

Consider a plane wave  $v_p(x)$  with wave vector  $p/\hbar$

$$v_p(x) = \frac{1}{\sqrt{2\pi\hbar}} e^{ipx/\hbar}. \quad (1.16)$$

The integral of  $|v_p(x)|^2 = \frac{1}{2\pi\hbar}$  over  $x \in \mathbb{R}$  diverges, therefore  $v_p(x) \notin \mathcal{F}_x$ . We shall designate  $\{v_o(x)\}$  the set of all plane waves, with the continuous index  $p \in (-\infty, \infty)$ . The Fourier-pair equations

$$\psi(x) = \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{\infty} dp \bar{\psi}(p) e^{ipx/\hbar}, \quad \text{and} \quad \bar{\psi}(p) = \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{\infty} dx \psi(x) e^{-ipx/\hbar},$$

can be rewritten with the definition of the plane wave:

$$\psi(x) = \int_{-\infty}^{\infty} dp \bar{\psi}(p) v_p(x), \quad (1.17)$$

$$\bar{\psi}(p) = (v_p, \psi) = \int_{-\infty}^{\infty} dx v_p^*(x) \psi(x). \quad (1.18)$$

The two formulas can be compared to equations (1.11) and (1.12). In this case, every function  $\psi(x) \in \mathcal{F}_x$  can be expanded in only one way as a continuous linear combination of planes waves, whose components are given by (1.18). The set of these components constitutes a function of  $p$ ,  $\bar{\psi}(p)$ , the Fourier transform of  $\psi(x)$ .

$\bar{\psi}(p)$  is analogous to  $c_i$ , both represent the components of the same function  $\psi(x)$  in two different bases:  $\{v_p(x)\}$  and  $\{u_i(x)\}$ .

If we calculate the square of the norm of  $\psi(x)$  we will get:

$$\text{Parseval's theorem} \quad (\psi, \psi) = \int_{-\infty}^{\infty} dp |\bar{\psi}(p)|^2. \quad (1.19)$$

We can also show that  $v_p(x)$  satisfy the closure relation:

$$\begin{aligned} \psi(x) &= \int_{-\infty}^{\infty} dp \bar{\psi}(p) v_p(x) = \int_{-\infty}^{\infty} dp (v_p, \psi) v_p(x) = \int_{-\infty}^{\infty} dp \left[ \int_{-\infty}^{\infty} dx' v_p^*(x') \psi(x') \right] v_p(x) \\ &= \int_{-\infty}^{\infty} dx' \psi(x') \left[ \int_{-\infty}^{\infty} dp v_p(x) v_p^*(x') \right]. \end{aligned}$$

The term inside the brackets corresponds to

$$\text{Closure relation} \quad \int_{-\infty}^{\infty} dp v_p(x) v_p^*(x') = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{dp}{\hbar} e^{i\frac{p}{\hbar}(x-x')} \stackrel{(a)}{=} \delta(x - x'). \quad (1.20)$$

In (a) the following relation was used:

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{iku} = \delta(u).$$

Equation (1.20) is analogous to (1.15). In the same way, we can derive the orthonormalization relation using (a):

$$(v_p, v_{p'}) = \int_{-\infty}^{\infty} dx v_p^*(x) v_{p'}(x) = \frac{1}{2\pi} \int \frac{dx}{\hbar} e^{i\frac{x}{\hbar}(p'-p)} = \delta(p - p').$$

Therefore,

$$\text{Orthonormalization relation} \quad (v_p, v_{p'}) = \delta(p - p'). \quad (1.21)$$

Now instead of a kronecker delta, we have a delta function. If  $p = p'$ , the scalar product **diverges**: we see again that  $v_p(x) \notin \mathcal{F}_x$ . It is also said that  $v_p(x)$  is "orthonormalized in the Dirac sense". The generalization to three dimension is given by

$$v_{\mathbf{p}}(\mathbf{r}) = \left( \frac{1}{2\pi\hbar} \right)^{3/2} e^{i\mathbf{p}\cdot\mathbf{r}/\hbar}. \quad (1.22)$$

The functions of  $\{v_{\mathbf{p}}(\mathbf{r})\}$  basis now depend on the three continuous indices  $p_x, p_y, p_z$  condensed in  $\mathbf{p}$ . In addition,

$$\text{Expansion} \quad \psi(\mathbf{r}) = \int d^3p \bar{\psi}(\mathbf{p}) v_{\mathbf{p}}(\mathbf{r}) \quad (1.23)$$

$$\text{Coefficient expansion} \quad \bar{\psi}(\mathbf{p}) = (v_{\mathbf{p}}, \psi) = \int d^3r v_{\mathbf{p}}^*(\mathbf{r}) \psi(\mathbf{r}) \quad (1.24)$$

$$\text{Scalar product} \quad (\varphi, \psi) = \int d^3p \bar{\varphi}^*(\mathbf{p}) \bar{\psi}(\mathbf{p}) \quad (1.25)$$

$$\text{Closure relation} \quad \int d^3p v_{\mathbf{p}}(\mathbf{r}) v_{\mathbf{p}}^*(\mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}') \quad (1.26)$$

$$\text{Orthonormalization relation} \quad (v_{\mathbf{p}}, v_{\mathbf{p'}}) = \delta(\mathbf{p} - \mathbf{p'}) \quad (1.27)$$

The  $v_{\mathbf{p}}(\mathbf{r})$  can be considered to constitute a **continuous** basis.

### Delta function

We can also consider a set of functions of  $\mathbf{r}$ ,  $\{\xi_{\mathbf{r}_0}(\mathbf{r})\}$ , labeled by the continuous index  $\mathbf{r}_0 = (x_0, y_0, z_0)$  and defined by

$$\xi_{\mathbf{r}_0}(\mathbf{r}) = \delta(\mathbf{r} - \mathbf{r}_0). \quad (1.28)$$

Obviously,  $\xi_{\mathbf{r}_0}(\mathbf{r})$  is not square-integrable:  $\xi_{\mathbf{r}_0}(\mathbf{r}) \notin \mathcal{F}$ .

Then, we can have the following

$$\text{Expansion} \quad \psi(\mathbf{r}) = \int d^3r_0 \psi(\mathbf{r}_0) \xi_{\mathbf{r}_0}(\mathbf{r}), \quad \text{and} \quad (1.29)$$

$$\text{Coefficient expansion} \quad \psi(\mathbf{r}_0) = (\xi_{\mathbf{r}_0}, \psi) = \int d^3r \xi_{\mathbf{r}_0}^*(\mathbf{r}) \psi(\mathbf{r}). \quad (1.30)$$

The equations are analogous to equations (1.11) and (1.12).

$\psi(\mathbf{r}_0)$  is the equivalent of  $c_i$ , which represent the components of the same function  $\psi(\mathbf{r})$  in two different bases:  $\{\xi_{\mathbf{r}_0}(\mathbf{r})\}$  and  $\{u_i(\mathbf{r})\}$ .

We also list, the other formulas:

$$\text{Scalar product} \quad (\varphi, \psi) = \int d^3 r_0 \varphi^*(\mathbf{r}_0) \psi(\mathbf{r}_0) \quad (1.31)$$

$$\text{Closure relation} \quad \int d^3 r_0 \xi_{\mathbf{r}_0}(\mathbf{r}) \xi_{\mathbf{r}_0}^*(\mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}') \quad (1.32)$$

$$\text{Orthonormalization relation} \quad (\xi_{\mathbf{r}_0}, \xi_{\mathbf{r}_0'}) = \delta(\mathbf{r}_0 - \mathbf{r}_0') \quad (1.33)$$

The  $\xi_{\mathbf{r}_0}(\mathbf{r})$  can be considered to constitute a **continuous** basis.

A physical state must **always** correspond to a square-integrable wavefunction. In no case  $v_p(\mathbf{r})$  and  $\xi_{\mathbf{r}_0}(\mathbf{r})$  can represent the state of a particle. They are nothing more than intermediaries, useful for calculations.

### Continuous orthonormal bases

We will denote a continuous orthonormal basis to a set of function of  $\mathbf{r}$ ,  $\{w_\alpha(\mathbf{r})\}$ , labeled by a continuous index  $\alpha$ , which satisfy the closure and orthonormalization relations:

$$\text{Orthonormalization relation} \quad (w_\alpha, w_{\alpha'}) = \int d^3 r w_\alpha^*(\mathbf{r}) w_{\alpha'}(\mathbf{r}) = \delta(\alpha - \alpha') \quad (1.34)$$

$$\text{Closure relation} \quad \int d\alpha w_\alpha(\mathbf{r}) w_\alpha^*(\mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}'). \quad (1.35)$$

When  $\alpha = \alpha'$ ,  $(w_\alpha, w_{\alpha'})$  **diverges**. Therefore,  $w_\alpha(\mathbf{r}) \notin \mathcal{F}$ . Recall that this is a generalized continuous basis, so it can represent the plane waves and delta functions by setting  $\alpha = \mathbf{p}$  and  $\alpha = \mathbf{r}_0$ , respectively.

In the case of mixed (discrete and continuous) basis  $\{u_i(\mathbf{r}), w_\alpha(\mathbf{r})\}$ , the orthonormalization relations are

$$\begin{aligned} \text{Orthonormalization relation for mixed basis} \quad & (u_i, u_j) = \delta_{ij} \\ & (w_\alpha, w_{\alpha'}) = \delta(\alpha - \alpha') \quad . \\ & (u_i, w_\alpha) = 0 \end{aligned} \quad (1.36)$$

And the closure relation becomes:

$$\text{Closure relation for mixed basis} \quad \sum_i u_i(\mathbf{r}) u_i^*(\mathbf{r}') + \int d\alpha w_\alpha(\mathbf{r}) w_\alpha^*(\mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}'). \quad (1.37)$$

We also list the expansion, coefficient of expansion and the scalar product for the continuous basis:

$$\text{Expansion} \quad \psi(\mathbf{r}) = \int d\alpha c(\alpha) w_\alpha(\mathbf{r}) \quad (1.38)$$

$$\text{Coefficient expansion} \quad c(\alpha) = (w_\alpha, \psi) = \int d^3 r' w_\alpha^*(\mathbf{r}') \psi(\mathbf{r}') \quad (1.39)$$

$$\text{Scalar product} \quad (\varphi, \psi) = \int d\alpha b^*(\alpha) c(\alpha) \quad (1.40)$$

The squared norm of the wavefunction with itself is then

$$\text{Parseval's theorem} \quad (\psi, \psi) = \int d\alpha |c(\alpha)|^2. \quad (1.41)$$

Finally, all the formulas can thus be generalized from discrete basis of index  $i$  and continuous basis with index  $\alpha$  (which can consider the plane wave and delta functions) through the following change of variables:

$$\text{Transformation } \{u_i(\mathbf{r})\} \longleftrightarrow \{w_\alpha(\mathbf{r})\} \quad \begin{array}{l} i \longleftrightarrow \alpha \\ \sum_i \longleftrightarrow \int d\alpha \\ \delta_{ij} \longleftrightarrow \delta(\alpha - \alpha') \end{array} \quad (1.42)$$

**Table 1.1** Fundamental formulas for discrete and continuous basis.

Property	Discrete basis $\{u_i(\mathbf{r})\}$	Continuous basis $\{w_\alpha(\mathbf{r})\}$
Scalar product	$(\varphi, \psi) = \sum_i b_i^* c_i$	$(\varphi, \psi) = \int d\alpha b^*(\alpha) c(\alpha)$
Parseval	$(\psi, \psi) = \sum_i  c_i ^2$	$(\psi, \psi) = \int d\alpha  c(\alpha) ^2$
Orthonormalization relation	$(u_i, u_j) = \delta_{ij}$	$(w_\alpha, w_{\alpha'}) = \delta(\alpha - \alpha')$
Closure relation	$\sum_i u_i(\mathbf{r}) u_i^*(\mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}')$	$\int d\alpha w_\alpha(\mathbf{r}) w_\alpha^*(\mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}')$
Expansion	$\psi(\mathbf{r}) = \sum_i c_i u_i(\mathbf{r})$	$\psi(\mathbf{r}) = \int d\alpha c(\alpha) w_\alpha(\mathbf{r})$
Components	$c_i = (u_i, \psi)$	$c(\alpha) = (w_\alpha, \psi)$

## 1.2 Dirac notation

Each quantum state of a particle will be characterized by a **state vector**, belonging to an abstract space  $\mathcal{E}_r$ , called the **state space** of the particle. The fact that the space  $\mathcal{F}$  is a subspace of  $L^2$  means that  $\mathcal{E}_r$  is a subspace of a Hilbert space.

The introduction of these quantities permits a generalization of the formalism. In fact, there exist physical systems whose quantum description cannot be given by a wavefunction.

### State vector

The quantum state of any physical system is characterized by a state vector, belonging to a space  $\mathcal{E}$  which is the state space of the system. The state space is the set of all of the possible states in which the system can exist.

### 1.2.1 Ket and Bra vectors

#### Ket vectors

Any element or vector of space  $\mathcal{E}$  is called a **key vector** or ket, and is represented by the symbol  $|\cdot\rangle$ . We shall define the space  $\mathcal{E}_r$  of the states of a particle by associating with every square-integrable function  $\psi(r)$  a ket vector  $|\psi\rangle$  of  $\mathcal{E}_r$ :

$$\psi(r) \in \mathcal{F} \implies |\psi\rangle \in \mathcal{E}_r. \quad (1.43)$$

Although  $\mathcal{F}$  and  $\mathcal{E}_r$  are **isomorphic**, we shall carefully distinguish between them. We see that the  $r$ -dependence no longer appears in  $|\psi\rangle$ : only appears  $\psi$  as an object that is used to extract information.

#### Dual space and bra vectors

A **linear function**  $\chi$  is a linear operation which associates a complex number with every ket  $|\psi\rangle$ :

$$\begin{aligned} |\psi\rangle \in \mathcal{E} &\xrightarrow{\chi} \chi(|\psi\rangle) \in \mathbb{C} \\ \chi(\lambda_1|\psi_1\rangle + \lambda_2|\psi_2\rangle) &= \lambda_1\chi(|\psi_1\rangle) + \lambda_2\chi(|\psi_2\rangle). \end{aligned} \quad (1.44)$$

A linear functional is an operator that returns a complex number, while a linear operator returns another ket (vector).

The set of linear functionals defined on  $|\psi\rangle \in \mathcal{E}$  constitutes a vector space, which is called **dual space** of  $\mathcal{E}$  and which will be symbolized by  $\mathcal{E}^*$ .

Any element, or vector of the space  $\mathcal{E}^*$  is called a **bra vector**, or bra and is denoted by  $\langle\cdot|$ .

The bra acts as a linear operator over the ket, which can be used to define the scalar product to return a complex number:

$$\text{Scalar product} \quad \langle\varphi|\psi\rangle = (|\varphi\rangle, |\psi\rangle). \quad (1.45)$$

We then have similar properties for the scalar product:

Adjoint	Linear to the second vector	Antilinear to the first vector
$\langle\varphi \psi\rangle = \langle\psi \varphi\rangle^*$	$\langle\varphi \lambda_1\psi_1 + \lambda_2\psi_2\rangle = \lambda_1\langle\varphi \psi_1\rangle + \lambda_2\langle\varphi \psi_2\rangle$	$\langle\lambda_1\varphi_1 + \lambda_2\varphi_2 \psi\rangle = \lambda_1^*\langle\varphi_1 \psi\rangle + \lambda_2^*\langle\varphi_2 \psi\rangle$

(1.46)

#### Relation bra-ket

There is an antilinear relation between a ket and its bra, so that we have the following multiplications by a scalar for the vectors

$$|\lambda\psi\rangle = \lambda|\psi\rangle \in \mathcal{E} \implies \langle\lambda\psi| = \lambda^*\langle\psi| \in \mathcal{E}^*, \quad \lambda \in \mathbb{C}. \quad (1.47)$$

Although to every ket there corresponds a bra, it is possible to find bras that have no corresponding kets such as delta functions and plane waves spaces. This dissymetry of the correspondence bra-ket is related to the existence of continuous basis for  $\mathcal{F}_x$ . This happens when the norm of the functions blow up making them not belong to  $\mathcal{F}_x$ , so we cannot associate a ket of  $\mathcal{E}_x$  with them. Nevertheless, their scalar product with a function of  $\mathcal{F}_x$  is defined, and this permits us to associate with them a linear function of  $\mathcal{E}_x$ : the bra



belonging to  $\mathcal{E}_x^*$ . However, we can define **generalized kets**, defined using functions that are not  $L^2$ , but whose scalar product with every function of  $\mathcal{F}_x$  exists.

When working with plane waves and delta functions, we assume the following approximation:

$$|\xi_{x_0}\rangle \xrightarrow{\text{Refers to}} |\xi_{x_0}^{(\epsilon)}\rangle, \quad \text{and} \quad |v_{p_0}\rangle \xrightarrow{\text{Refers to}} |v_{p_0}^{(L)}\rangle, \quad (1.48)$$

where  $\epsilon$  is very small and  $L$  very large compared to all other lengths of the problem, so we are always working in  $\mathcal{E}_x$ .

Note that

$$\begin{aligned} \xi_{x_0}^{(\epsilon)}(x) \in \mathcal{F}_x &\iff |\xi_{x_0}^{(\epsilon)}\rangle \in \mathcal{E}_x & v_{p_0}^{(L)}(x) \in \mathcal{F}_x &\iff |v_{p_0}^{(L)}\rangle \in \mathcal{E}_x \\ \lim_{\epsilon \rightarrow 0} |\xi_{x_0}^{(\epsilon)}\rangle &\notin \mathcal{E}_x & \lim_{L \rightarrow \infty} |v_{p_0}^{(L)}\rangle &\notin \mathcal{E}_x \\ \lim_{\epsilon \rightarrow 0} \langle \xi_{x_0}^{(\epsilon)} | &= \langle \xi_{x_0} | \in \mathcal{E}_x^* & \lim_{L \rightarrow \infty} \langle v_{p_0}^{(L)} | &= \langle v_{p_0} | \in \mathcal{E}_x^* \\ |\psi\rangle \in \mathcal{E}_x &\implies \langle \xi_{x_0} | \psi \rangle = \psi(x_0) & |\psi\rangle \in \mathcal{E}_x &\implies \langle v_{p_0} | \psi \rangle = \bar{\psi}(p_0) \end{aligned} \quad , \quad \text{and} \quad (1.49)$$

In general, the dual space  $\mathcal{E}^*$  and the state space  $\mathcal{E}$  are not isomorphic, except that  $\mathcal{E}$  is finite-dimensional. Although to each ket there corresponds a bra, the converse is not true. In addition to use vector of  $\mathcal{E}$  (whose norm is finite), **generalized kets** with infinite norms but whose scalar product with every ket of  $\mathcal{E}$  is finite. Thus, to each bra of  $\mathcal{E}^*$  there will correspond a ket. But generalized kets do not represent physical states of the system.

### 1.2.2 Linear operators

A linear operator  $A$  associates with every ket  $|\psi\rangle \in \mathcal{E}$  another ket  $|\psi'\rangle \in \mathcal{E}$  linearly:

$$|\psi'\rangle = A|\psi\rangle \quad (1.50)$$

$$A(\lambda_1|\psi_1\rangle + \lambda_2|\psi_2\rangle) = \lambda_1 A|\psi_1\rangle + \lambda_2 A|\psi_2\rangle. \quad (1.51)$$

The product of two linear operators  $AB$  is defined by first acting  $B$  in the ket  $|\psi\rangle$ , and then  $A$ :

$$(AB)|\psi\rangle = A(B|\psi\rangle). \quad (1.52)$$

The commutator express the degree of difference between the change of order of operation:

$$[A, B] = AB - BA. \quad (1.53)$$

We call the **matrix element** of  $A$  between  $|\varphi\rangle$  and  $|\psi\rangle$ , the scalar product that measure the collinearity between the action of the operator onto  $|\varphi\rangle$ :

$$\langle \varphi | A | \psi \rangle \in \mathbb{C}. \quad (1.54)$$

### Projector

Lets assume that  $\langle \psi | \psi \rangle = 1$  (normalized), we define the **projector** as an operator that projects a ket into another ket:

$$P_\psi = |\psi\rangle\langle\psi| \quad (1.55)$$

When it acts into a vector, it first compute the scalar product and then assign the value to the vector from which the product was computed:

$$P_\psi|\varphi\rangle = |\psi\rangle \underbrace{\langle\psi|\varphi\rangle}_{\text{number}}.$$

It is also *idempotent*, which means that

$$P_\psi^2 = P_\psi P_\psi = |\psi\rangle\langle\psi|\psi\rangle\langle\psi| = |\psi\rangle\langle\psi| = P_\psi. \quad (1.56)$$

The most generalized form is project a ket into a orthonormalized ( $\langle\varphi_i|\varphi_j\rangle = \delta_{ij}$ ) subspace  $\{\varphi_q\} \in \mathcal{E}_q \subseteq \mathcal{E}$ . Let  $P_q$  be then the linear operator

$$P_q = \sum_{i=1}^q |\varphi_i\rangle\langle\varphi_i|. \quad (1.57)$$

It then takes the ket, and compute the projection to every vector  $|\varphi_i\rangle$  and then form a linear combination.

### 1.2.3 Hermitian conjugation (adjoint)

There is also possible to define actions of  $A$  on bras as  $\langle\chi|A$ , whose order is important.

We can also link with every linear operator  $A$  another linear operator  $A^\dagger$ , called the adjoint operator (or Hermitian conjugate) of  $A$ . The operator  $A$  associates with it another ket  $|\psi'\rangle = A|\psi\rangle \in \mathcal{E}$ . The correspondence between kets and bras permits us to define the action of operator  $A^\dagger$  on the bras:

$$|\psi\rangle \text{ corresponds to } \langle\psi| \implies |\psi'\rangle = A|\psi\rangle \text{ corresponds to } \langle\psi'| = \langle\psi|A^\dagger. \quad (1.58)$$

The relation  $\langle\psi'| = \langle\psi|A^\dagger$  is **linear**, as

$$A(\lambda_1^*|\psi_1\rangle + \lambda_2^*|\psi_2\rangle) = \lambda_1^*A|\psi_1\rangle + \lambda_2^*A|\psi_2\rangle \text{ corresponds to } (\lambda_1\langle\psi_1| + \lambda_2\langle\psi_2|)A^\dagger = \lambda_1\langle\psi_1|A^\dagger + \lambda_2\langle\psi_2|A^\dagger.$$

Therefore,  $A^\dagger$  is a linear operator defined by

$$|\psi'\rangle = A|\psi\rangle \iff \langle\psi'| = \langle\psi|A^\dagger, \quad (1.59)$$

which also implies that

$$\langle\psi|A^\dagger|\varphi\rangle = \langle\varphi|A|\psi\rangle^*. \quad (1.60)$$

### Properties

$$\begin{aligned} (A^\dagger)^\dagger &= A \\ (\lambda A)^\dagger &= \lambda^* A^\dagger \\ (A + B)^\dagger &= A^\dagger + B^\dagger \\ (AB)^\dagger &= B^\dagger A^\dagger \end{aligned}$$

### Hermitian conjugation in Dirac notation

A ket  $|\psi\rangle$  and its corresponding bra  $\langle\psi|$  are said to be Hermitian conjugates of each other. In the same manner,  $A^\dagger$  is also called Hermitian conjugate operator of  $A$ .

The operation of Hermitian conjugate is followed by a very simple rule:

**Rule of Hermitian conjugate**

To obtain the adjoint of any expression composed of constants, kets, bras, and operators, one must:

Replace	$\left\{ \begin{array}{l} \text{the constants by their complex conjugates} \\ \text{the kets by the bras associated} \\ \text{the bras by the kets associated} \\ \text{the operators by their adjoints} \end{array} \right.$
Reverse the order of the factors	Only constants can move around (commute)

As an example,

$$(\lambda \langle u|A|v\rangle |w\rangle \langle \psi|)^{\dagger} = |\psi\rangle \langle w| \langle v|A^{\dagger}|u\rangle \underbrace{\lambda^*}_{\text{can move around}}$$

**Hermitian operators**

An operator  $A$  is said to be Hermitian if  $A = A^{\dagger}$ , which satisfy the following relations:

$$\langle \psi|A|\varphi\rangle = \langle \varphi|A|\psi\rangle^* \quad \text{and} \quad \langle A\varphi|\psi\rangle = \langle \varphi|A\psi\rangle.$$

In addition, the projector  $P_{\psi}$  is an Hermitian operator:

$$P_{\psi}^* = |\psi\rangle \langle \psi| = P_{\psi}. \quad (1.61)$$

The product of two Hermitian operators  $A, B$  is Hermitian only if  $[A, B] = 0$ .

## 1.3 Representations in state space

Choosing a representation means choosing an orthonormal (discrete or continuous) basis in the state space  $\mathcal{E}$ . Vectors and operators are then represented in this basis by *numbers*: components for the vectors, matrix elements for the operators.

We now translate all properties such as orthonormalization relation and closure relation to the Dirac notation.

### 1.3.1 Relations characteristic of an orthonormal basis

#### Orthonormalization relation

A set of kets, discrete  $\{|u_i\rangle\}$  or continuous  $\{|w_{\alpha}\rangle\}$  is said to be orthonormal if they satisfy the following equation:

$$\text{Orthonormalization relation} \quad \begin{array}{l} \langle u_i|u_j\rangle = \delta_{ij} \\ \langle w_{\alpha}|w_{\alpha'}\rangle = \delta(\alpha - \alpha') \end{array}. \quad (1.62)$$

As can be seen, for a continuous set  $\langle w_{\alpha}|w_{\alpha}\rangle$  **does not exist**: the  $|w_{\alpha}\rangle$  have an infinite norm and therefore do not belong to  $\mathcal{E}$ . Nevertheless, the vectors of  $\mathcal{E}$  can be expanded on the  $|w_{\alpha}\rangle$ . It is useful then to accept  $|w_{\alpha}\rangle$  as *generalized kets*.

### Closure relation

A discrete or continuous set constitutes a basis if every ket  $|\psi\rangle \in \mathcal{E}$  has a **unique** expansion on  $|u_i\rangle$  or  $|w_\alpha\rangle$ :

$$\begin{aligned} \text{Closure relation} \quad & \begin{aligned} |\psi\rangle &= \sum_i c_i |u_i\rangle \\ |\psi\rangle &= \int d\alpha c(\alpha) |w_\alpha\rangle \end{aligned}, \end{aligned} \quad (1.63)$$

whose components are obtained multiplying  $\langle u_j|$  ( $\langle w_{\alpha'}|$ ) in the closure relation and using equation (1.62):

$$\begin{aligned} \text{Coefficient expansion} \quad & \begin{aligned} \langle u_j|\psi\rangle &= c_j \\ \langle w_{\alpha'}|\psi\rangle &= c(\alpha') \end{aligned}. \end{aligned} \quad (1.64)$$

We can reexpress the expansion employing the coefficient expansion equations:

$$\begin{aligned} |\psi\rangle &= \sum_i c_i |u_i\rangle = \sum_i \langle u_i|\psi\rangle |u_i\rangle = \sum_i |u_i\rangle \langle u_i|\psi\rangle = \left[ \sum_i |u_i\rangle \langle u_i| \right] |\psi\rangle = P_{\{u_i\}} |\psi\rangle, \\ |\psi\rangle &= \int d\alpha c(\alpha) |w_\alpha\rangle = \int d\alpha \langle w_\alpha|\psi\rangle |w_\alpha\rangle = \int d\alpha |w_\alpha\rangle \langle w_\alpha|\psi\rangle = \left[ \int d\alpha |w_\alpha\rangle \langle w_\alpha| \right] |\psi\rangle = P_{\{w_\alpha\}} |\psi\rangle. \end{aligned}$$

We then have the projector onto a discrete and continuous basis:

$$\begin{aligned} \text{Projectors} \quad & \begin{aligned} P_{\{u_i\}} &= \sum_i |u_i\rangle \langle u_i| = \mathbb{1} \\ P_{\{w_\alpha\}} &= \int d\alpha |w_\alpha\rangle \langle w_\alpha| = \mathbb{1} \end{aligned} \end{aligned} \quad \begin{aligned} & \text{Closure relation,} \\ & (1.65) \end{aligned}$$

where  $\mathbb{1}$  denotes the identity operator in  $\mathcal{E}$ . These relations express the fact that  $\{|u_i\rangle\}$  and  $\{|w_\alpha\rangle\}$  constitute bases.

**Table 1.2** Fundamental formulas for calculation in the  $\{|u_i\rangle\}$  and  $\{|w_\alpha\rangle\}$  representations.

$\{ u_i\rangle\}$ representation	$\{ w_\alpha\rangle\}$ representation
$\langle u_i u_j\rangle = \delta_{ij}$	$\langle w_\alpha w_{\alpha'}\rangle = \delta(\alpha - \alpha')$
$P_{\{u_i\}} = \sum_i  u_i\rangle \langle u_i  = \mathbb{1}$	$P_{\{w_\alpha\}} = \int d\alpha  w_\alpha\rangle \langle w_\alpha  = \mathbb{1}$

### 1.3.2 Representation of kets and bras

In the  $\{|u_i\rangle\}$  basis, the ket  $|\psi\rangle$  is represented by a set of its components  $x_i \langle u_i|\psi\rangle$ . These numbers are arranged vertically to form a column matrix. On the other hand, for continuous basis  $\{|w_\alpha\rangle\}$ , the ket  $|\psi\rangle$  is represented by a continuous **infinity** of numbers  $c(\alpha) = \langle w_\alpha|\psi\rangle$ : a function of  $\alpha$ . We then draw a vertical axis with the values of  $c(\alpha)$ :

$$\begin{aligned} |\psi\rangle_{\{|u_i\rangle\}} &= \mathbb{1}|\psi\rangle = P_{\{u_i\}}|\psi\rangle = \sum_i |u_i\rangle \langle u_i|\psi\rangle = \sum_i c_i |u_i\rangle, \\ |\psi\rangle_{\{|w_\alpha\rangle\}} &= \mathbb{1}|\psi\rangle = P_{\{w_\alpha\}}|\psi\rangle = \int d\alpha |w_\alpha\rangle \langle w_\alpha|\psi\rangle = \int d\alpha c(\alpha) |w_\alpha\rangle. \end{aligned}$$

Then,

$$|\psi\rangle_{\{|u_i\rangle\}} = \begin{bmatrix} \langle u_1|\psi\rangle \\ \langle u_2|\psi\rangle \\ \vdots \\ \langle u_i|\psi\rangle \\ \vdots \end{bmatrix}, \quad \text{and} \quad |\psi\rangle_{\{|w_\alpha\rangle\}} = \alpha \downarrow \begin{bmatrix} \vdots \\ \vdots \\ \langle w_\alpha|\psi\rangle \\ \vdots \\ \vdots \end{bmatrix}. \quad (1.66)$$

Something similar happens to the respective bras:

$$\begin{aligned} \langle\varphi|_{\{|u_i\rangle\}} &= \langle\varphi|\mathbb{1} = \langle\varphi|P_{\{|u_i\rangle\}} = \sum_i \langle\varphi|u_i\rangle \langle u_i| = \sum_i b_i^* \langle u_i|, \\ \langle\varphi|_{\{|w_\alpha\rangle\}} &= \langle\varphi|\mathbb{1} = \langle\varphi|P_{\{|w_\alpha\rangle\}} = \int d\alpha \langle\varphi|w_\alpha\rangle \langle w_\alpha| = \int d\alpha b^*(\alpha) \langle\varphi|. \end{aligned}$$

We can see that the components of the bra are the complex conjugates of the components  $b_i = \langle u_i|\varphi\rangle$  and  $b(\alpha) = \langle w_\alpha|\varphi\rangle$  of the ket  $|\varphi\rangle$  associated with  $\langle\varphi|$ .

Let us then arrange them horizontally, to form a row matrix:

$$\langle\varphi|_{\{|u_i\rangle\}} = [\langle\varphi|u_1\rangle \quad \langle\varphi|u_2\rangle \quad \cdots \quad \langle\varphi|u_i\rangle \quad \cdots], \quad \text{and} \quad (1.67)$$

$$\langle\varphi|_{\{|w_\alpha\rangle\}} = \begin{matrix} \alpha \\ \rightarrow \\ [\cdots \quad \cdots \quad \langle\varphi|w_\alpha\rangle \quad \cdots \quad \cdots] \end{matrix}. \quad (1.68)$$

The scalar product is then given by a **matrix multiplication**:

$$\langle\varphi|\psi\rangle = \langle\varphi|\mathbb{1}|\psi\rangle = \langle\varphi|P_{\{|u_i\rangle\}}|\psi\rangle = \sum_i \langle\varphi|u_i\rangle \langle u_i|\psi\rangle = \sum_i b_i^* c_i \quad (1.69)$$

$$\langle\varphi|\psi\rangle = \langle\varphi|\mathbb{1}|\psi\rangle = \langle\varphi|P_{\{|w_\alpha\rangle\}}|\psi\rangle = \int d\alpha \langle\varphi|w_\alpha\rangle \langle w_\alpha|\psi\rangle = \int d\alpha b^*(\alpha) c(\alpha). \quad (1.70)$$

### 1.3.3 Representation of operators

Representation of  $A$  by a square matrix

Given a linear operator  $A$ , we can in  $\{|u_i\rangle\}$  or  $\{|w_\alpha\rangle\}$  basis, associate with it a series of numbers defined by

$$A_{ij} = \langle u_i|A|u_j\rangle, \quad \text{or} \quad A(\alpha, \alpha') = \langle w_\alpha|A|w_{\alpha'}\rangle. \quad (1.71)$$

They are arranged into a square matrix, as

$$\begin{bmatrix} A_{11} & A_{12} & \cdots & A_{1j} & \cdots \\ A_{21} & A_{22} & \cdots & A_{2j} & \cdots \\ \vdots & \vdots & & \vdots & \\ A_{i1} & A_{i2} & \cdots & A_{ij} & \cdots \\ \vdots & \vdots & & \vdots & \end{bmatrix}, \quad \text{or} \quad \alpha \downarrow \begin{matrix} \alpha' \\ \rightarrow \\ \begin{bmatrix} \vdots \\ \vdots \\ A(\alpha, \alpha') & \cdots \\ \vdots \end{bmatrix} \end{matrix}. \quad (1.72)$$

For the case of the matrix representing the operator  $AB$  in the  $\{|u_i\rangle\}$  basis, we have:

$$\langle u_i|AB|u_j\rangle = \langle u_i|A\mathbb{1}|u_j\rangle = \langle u_i|AP_{\{u_k\}}B|u_j\rangle = \sum_k \langle u_i|A|u_k\rangle \langle u_k|B|u_j\rangle = \sum_k A_{ik}B_{kj}.$$

**Representation of the ket  $|\psi'\rangle = A|\psi\rangle$**

Knowing the components of  $|\psi\rangle$  and the matrix elements of  $A$  in a given representation, how can we calculate the components of  $|\psi'\rangle = S|\psi\rangle$  in the same representation?

We know that in the  $\{|u_i\rangle\}$  and  $\{|w_\alpha\rangle\}$  basis, we have

$$c'_i = \langle u_i|\psi'\rangle = \langle u_i|A|\psi\rangle, \quad \text{and} \quad c'(\alpha) = \langle w_\alpha|\psi'\rangle.$$

Inserting the closure relation between  $A$  and  $|\psi\rangle$ :

$$\begin{aligned} c'_i &= \langle u_i|A\mathbb{1}|\psi\rangle = \langle u_i|AP_{\{u_j\}}|\psi\rangle = \sum_j \langle u_i|A|u_j\rangle \langle u_j|\psi\rangle = \sum_j A_{ij}c_j \\ c'(\alpha) &= \langle w_\alpha|A\mathbb{1}|\psi\rangle = \int d\alpha' \langle w_\alpha|A|w_{\alpha'}\rangle \langle w_{\alpha'}|\psi\rangle = \int d\alpha' A(\alpha, \alpha')c(\alpha'). \end{aligned}$$

We see that the column matrix representing  $|\psi'\rangle$  is equal to the matrix multiplication of the column matrix  $|\psi\rangle$  and the square matrix  $A$ .

**Expression for the number  $\langle\varphi|A|\psi\rangle$**

On the other hand, we can derive an expression for  $\langle\varphi|A|\psi\rangle$  for both basis:

$$\begin{aligned} \langle\varphi|A|\psi\rangle &= \langle\varphi|P_{\{u_i\}}AP_{\{u_j\}}|\psi\rangle = \sum_{i,j} \langle\varphi|u_i\rangle \langle u_i|A|u_j\rangle \langle u_j|\psi\rangle = \sum_{i,j} b_i^* A_{ij}c_j, \\ \langle\varphi|P_{\{w_\alpha\}}AP_{\{w_{\alpha'}\}}|\psi\rangle &= \iint d\alpha d\alpha' \langle\varphi|w_\alpha\rangle \langle w_\alpha|A|w_{\alpha'}\rangle \langle w_{\alpha'}|\psi\rangle = \iint d\alpha d\alpha' b^*(\alpha) A(\alpha, \alpha')c(\alpha'). \end{aligned}$$

Thus, the term  $\langle\varphi|A|\psi\rangle$  which is a number, can be computed as a matrix multiplication of the column vector  $|\psi\rangle$  by the matrix  $A$ , and then by the row vector  $\langle\varphi|$ .

**Matrix representation of  $A^\dagger$**

The adjoint of  $A$  can also be written as:

$$\begin{aligned} (A^\dagger)_{ij} &= \langle u_i|A^\dagger|u_j\rangle = \langle u_j|A|u_i\rangle^* = A_{ji}^* \\ A^\dagger(\alpha, \alpha') &= \langle w_\alpha|A^\dagger|w_{\alpha'}\rangle = \langle w_{\alpha'}|A|w_\alpha\rangle^* = A^*(\alpha', \alpha). \end{aligned} \tag{1.73}$$

The matrices representing  $A$  and  $A^\dagger$  are then Hermitian conjugates of each other.

If  $A$  is Hermitian, then  $A_{ij} = A_{ji}^*$  and  $A(\alpha, \alpha') = A^*(\alpha', \alpha)$ . A hermitian operator is therefore represented by a Hermitian matrix. For  $i = j$ ,  $\alpha = \alpha'$  we see that  $A_{ii} = A_{ii}^*$ ,  $A(\alpha, \alpha) = A^*(\alpha, \alpha)$ . Thus,

The diagonal elements of a Hermitian matrix are therefore always real numbers.

### 1.3.4 Change of representation

We can representate a ket  $|\psi\rangle$  in different bases, similar to representing a point in space by cartesian and spherical coordinates. The relation of these two representation allow us to turn from one to the other easily.

If we assume an old discrete basis  $\{|u_i\rangle\}$  to a new one  $\{|t_k\rangle\}$ , the change of basis is defined by specifying the components  $S_{ik} = \langle u_i | t_k \rangle$  of each kets of the new basis in terms of the kets of the old one. The adjoint is:  $(S^\dagger)_{ki} = (S_{ik})^* = \langle t_k | u_i \rangle$ . This transformation matrix is **unitary**:  $S^\dagger S = S S^\dagger = I$ .

We will derive the transformation for a ket, a bra, and the matrix elements of an operator using the closure relation of each basis as explained in the derivation.

$$\begin{aligned}
\langle t_k | \psi \rangle &= \langle t_k | \mathbb{1} | \psi \rangle = \langle t_k | P_{\{u_i\}} | \psi \rangle = \sum_i \langle t_k | u_i \rangle \langle u_i | \psi \rangle = \sum_i S_{ki}^\dagger \langle u_i | \psi \rangle \\
\langle u_i | \psi \rangle &= \langle u_i | \mathbb{1} | \psi \rangle = \langle u_i | P_{\{t_k\}} | \psi \rangle = \sum_k \langle u_i | t_k \rangle \langle t_k | \psi \rangle = \sum_k S_{ik} \langle t_k | \psi \rangle \\
\langle \psi | t_k \rangle &= \langle \psi | \mathbb{1} | t_k \rangle = \langle \psi | P_{\{u_i\}} | t_k \rangle = \sum_i \langle \psi | u_i \rangle \langle u_i | t_k \rangle = \sum_i \langle \psi | u_i \rangle S_{ik} \\
\langle \psi | u_i \rangle &= \langle \psi | \mathbb{1} | u_i \rangle = \langle \psi | P_{\{t_k\}} | u_i \rangle = \sum_k \langle \psi | t_k \rangle \langle t_k | u_i \rangle = \sum_k \langle \psi | t_k \rangle S_{ki}^\dagger \\
A_{kl} &= \langle t_k | A | t_l \rangle = \langle t_k | \mathbb{1} A \mathbb{1} | t_l \rangle = \langle t_k | P_{\{u_i\}} A P_{\{u_j\}} | t_l \rangle = \sum_{i,j} \langle t_k | u_i \rangle \langle u_i | A | u_j \rangle \langle u_j | t_l \rangle = \sum_{i,j} S_{ki}^\dagger A_{ij} S_{jl} \\
A_{ij} &= \langle u_i | A | u_j \rangle = \langle u_i | \mathbb{1} A \mathbb{1} | u_j \rangle = \langle u_i | P_{\{t_k\}} A P_{\{t_l\}} | u_j \rangle = \sum_{k,l} \langle u_i | t_k \rangle \langle t_k | A | t_l \rangle \langle t_l | u_j \rangle = \sum_{k,l} S_{ik} A_{kl} S_{lj}^\dagger.
\end{aligned}$$

The final results are shown in table

**Table 1.3** Transformation of a ket, bra, and matrix elements from one basis to another.

Transformation	Expression
Ket components $\{u_i\} \longrightarrow \{t_k\}$ representation	$\langle t_k   \psi \rangle = \sum_i S_{ki}^\dagger \langle u_i   \psi \rangle$
Ket components $\{t_k\} \longrightarrow \{u_i\}$ representation	$\langle u_i   \psi \rangle = \sum_k S_{ik} \langle t_k   \psi \rangle$
Bra components $\{u_i\} \longrightarrow \{t_k\}$ representation	$\langle \psi   t_k \rangle = \sum_i \langle \psi   u_i \rangle S_{ik}$
Bra components $\{t_k\} \longrightarrow \{u_i\}$ representation	$\langle \psi   u_i \rangle = \sum_k \langle \psi   t_k \rangle S_{ki}^\dagger$
Matrix elements $\{u_{i,j}\} \longrightarrow \{t_{k,l}\}$ representation	$A_{kl} = \sum_{i,j} S_{ki}^\dagger A_{ij} S_{jl}$
Matrix elements $\{t_{k,l}\} \longrightarrow \{u_{i,j}\}$ representation	$A_{ij} = \sum_{k,l} S_{ik} A_{kl} S_{lj}^\dagger$

## 1.4 Eigenvalue equations. Observables

### 1.4.1 Eigenket and eigenbra equations

$|\psi\rangle$  is said to be an **eigenvector** (or eigenket) of the linear operator  $A$  if

$$\text{Eigenket equation of } A \quad A|\psi\rangle = \lambda|\psi\rangle, \quad \lambda \in \mathbb{C}. \quad (1.74)$$

This eigenket equation possesses solutions only when  $\lambda$  takes on certain values, called **eigenvalues** of  $A$ . The set of the eigenvalues is called **spectrum** of  $A$ .

#### Collinear of an eigenvector is also an eigenvector

If  $|\psi\rangle$  is an eigenvector of  $A$  with eigenvalue  $\lambda$ , then  $\alpha|\psi\rangle$ ,  $\alpha \in \mathbb{C}$  is also an eigenvector of  $A$ .

The eigenvalue  $\lambda$  is called *non-degenerate* (or simple) when its corresponding eigenvector is **unique** to within a constant factor (collinear). On the other hand, if there exists at least two linearly independent eigenkets with the **same** eigenvalue, the eigenvalue is said to be *degenerate*. Its *degree of degeneracy*  $g$  is then the number of linearly independent eigenvectors  $|\psi^i\rangle$ ,  $i = \{1, 2, \dots, g\}$  associated with it.

The set of eigenkets associated with a degenerate eigenvalue constitutes a  $g$ -dimensional vector space called **eigensubspace** of  $\lambda$ .

Taking the adjoint of the eigenket equation yields its corresponding form to eigenbra equation

$$\text{Eigenbra equation of } A^\dagger \quad \langle\psi|A^\dagger = \lambda^*\langle\psi|. \quad (1.75)$$

If  $|\psi\rangle$  is an eigenket of  $A$  with  $\lambda$ , it can also be said that  $\langle\psi|$  is an eigenbra of  $A^\dagger$  with  $\lambda^*$ .

#### Finding the eigenvalues and eigenvector in an operator

Assuming the state space is of finite dimension  $N$ , granting the generalization to an infinite-dimensional state space.

Choosing  $\{|u_i\rangle\}$ , lets us project the vector (1.74) onto the various orthonormal basis vectors  $|u_i\rangle$ :

$$\langle u_i|A|\psi\rangle = \lambda\langle u_i|\psi\rangle. \quad (1.76)$$

Inserting the closure relation between  $A$  and  $|\psi\rangle$ :

$$\langle u_i|A\mathbb{1}|\psi\rangle = \sum_j \underbrace{\langle u_i|A|u_j\rangle}_{A_{ij}} \underbrace{\langle u_j|\psi\rangle}_{c_j} = \lambda \underbrace{\langle u_i|\psi\rangle}_{c_i} \longrightarrow \sum_j [A_{ij} - \lambda\delta_{ij}]c_j = 0. \quad (1.77)$$

Equation (1.77) is a system of equations with  $N$  equations and  $N$  unknowns  $c_j$ . It has non-trivial solution iff its characteristic equation is zero:

$$\text{Characteristic equation of the eigenket equation} \quad P(\lambda) = \det[A - \lambda I] = 0. \quad (1.78)$$

This expression enable us to determine the spectrum of  $A$ . The characteristic equation is **independent** of the representation chosen. Then,



The eigenvalues of an operator are the roots  $\lambda$  of its  $N$ th order characteristic equation  $P(\lambda)$ .

### Determination of eigenvectors

Given a transformation  $T(v) = Mv : V \in \mathbb{C}^N \longrightarrow W \in \mathbb{C}^N$ , the theorem says:

$$\dim(V) = \text{rank}(T) + \text{null}(T), \quad (1.79)$$

where

$\dim(V)$  = Number of columns of  $V$

$\text{rank}(T)$  = Number of independent equations (non zero rows)

$\text{null}(T) = \dim[\ker(T)]$  = Number of free variables, degree of freedom (dof).

In our case,  $T(v) = Mv = (A - \lambda I)v$  and  $\dim(V) = N$ .

Based on the nature of the eigenvalue, we can have different eigenvalues but also repeated. Therefore, we define the following useful quantities:

- **Algebraic multiplicity (AM)** Number of repetition of the eigenvalue (degree of degeneracy  $g$ ).
- **Geometric multiplicity (GM)** Dimension of the subspace that the eigenvalues generate (how many linearly independent eigenvectors exist for that eigenvalue).

We then can have the following three cases:

- $AM = GM = 1$  Only one eigenvector corresponds to the eigenvalue (within a constant factor). At the moment of substituting an eigenvalue  $\lambda_0$  into equation (1.77) there will be  $\text{rank}(M) = N - 1$  independent equations so one equation is redundant. When this happens,  $\text{null}(M) = 1$  free variable (or degree of freedom, dof)  $c_1$  is available which can be defined arbitrarily and from which all other variables can be expressed.

If we fix  $c_1$ , then all  $c_j$  are proportional to it:

$$c_j = \alpha_j^0 c_1 \quad (\alpha_1^0 = 1). \quad (1.80)$$

the  $N - 1$  coefficients  $\alpha_j^0$ ,  $j \neq 1$  are determined from the matrix elements  $A_{ij}$  and  $\lambda_0$ . The eigenvectors associated with  $\lambda_0$  differ only by the value chosen for  $c_1$ . They are therefore all given by

$$|\psi_0(c_1)\rangle = \sum_j \alpha_j^0 c_1 |u_j\rangle = c_1 |\psi_0\rangle, \quad \text{with} \quad |\psi_0\rangle = \sum_j \alpha_j^0 |u_j\rangle. \quad (1.81)$$

When  $\lambda_0$  is simple, only one eigenvector corresponds to it.

### Ejemplo 1.1

In the matrix

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 3 \end{bmatrix}$$

### Simple eigenvalues

the eigenvalues are  $\lambda \in \{1, 2, 3\}$ . Lets make  $\lambda_0 = 1$  and replace it into the eigenvalue problem:

$$(A - \lambda I)v = (A - I)v = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{bmatrix} v = 0$$

We see that there is no value in the first column, meaning that  $x_1$  is free whereas  $x_2 = x_3 = 0$ . Therefore, the eigenvector is  $v_1 = (1 \ 0 \ 0)$ .

- $AM = GM > 1$  When evaluating  $\lambda_0$ , the system will have  $\text{rank}(M) = N - p$  independent equations ( $1 < p < q$ ). To the eigenvalue  $\lambda_0$  there corresponds an eigensubspace of dimension  $\text{null}(M) = p$ , and  $\lambda_0$  is a  $p$ -fold degenerate eigenvalue.

Assuming that for  $\lambda = \lambda_0$  is composed of  $N - 2$  linearly independent equations. These equations enable us to calculate the coefficients  $c_j$  in terms of any of them, for example  $c_1$  and  $c_2$ :

$$c_j = \beta_j^0 c_1 + \gamma_j^0 c_2.$$

All the eigenvectors associated with  $\lambda_0$  are then of the form

$$|\psi_0(c_1, c_2)\rangle = c_1|\psi_0^1\rangle + c_2|\psi_0^2\rangle, \quad \text{with} \quad |\psi_0^1\rangle = \sum_j \beta_j^0 |u_j\rangle, \quad |\psi_0^2\rangle = \sum_j \gamma_j^0 |u_j\rangle. \quad (1.82)$$

The vectors  $|\psi_0(c_1, c_2)\rangle$  do indeed constitute a two-dimensional vector space, this being characteristic of a two-fold degenerate eigenvalue.

- $AM > GM > 1$  In this case, the subspace is less than the degree of degeneracy and therefore not all degenerate eigenvectors are linearly independent. This means that there is not enough information to create a basis. However, techniques such as Jordan canonical form helps to create generalized eigenvector and to span the whole space.

When an operator is Hermitian, it can be shown that the degree of degeneracy  $p$  of an eigenvalue  $\lambda$  is always equal to the multiplicity of the corresponding root in the characteristic equations. In a space of finite dimension  $N$ , a Hermitian operator always has  $N$  linearly independent eigenvectors: this operator can therefore be diagonalized.

### 1.4.2 Observables

Properties of the eigenvalues and eigenvectors of a Hermitian operator

- The eigenvalues of a Hermitian operator are real.
- Two eigenvectors of a Hermitian operator corresponding to two different eigenvalues are orthogonal.

#### Definition of a observable

Consider a Hermitian operator  $A$  with discrete spectrum. The degree of degeneracy of the eigenvalue  $a_n$  is denoted by  $g_n$ . We shall denote by  $|\psi_n^i\rangle$   $g_n$  linearly independent vectors chosen in the eigensubspace  $\mathcal{E}_n$  of  $a_n$ :

$$A|\psi_n^i\rangle = a_n|\psi_n^i\rangle, \quad i = 1, 2, \dots, g_n. \quad (1.83)$$

Every vector of  $\mathcal{E}_n$  is orthogonal to every vector of another subspace  $\mathcal{E}_{n'}$ :  $\langle \psi_n^i | \psi_{n'}^j \rangle = 0$ ,  $n \neq n'$ . Inside the subspace  $\mathcal{E}_n$ , the  $|\psi_n^i\rangle$  can always be chosen orthonormal, such that

$$\langle \psi_n^i | \psi_n^j \rangle = \delta_{ij}. \quad (1.84)$$

If such a choice is made, the result is an orthonormal system of eigenvectors of  $A$ : the  $|\psi_n^i\rangle$  satisfying the relations:

$$\langle \psi_n^i | \psi_{n'}^{i'} \rangle = \delta_{nn'} \delta_{ii'}. \quad (1.85)$$

### Observable

The Hermitian operator  $A$  is an **observable** if this orthonormal system of vectors form a basis in the state space:

$$\text{Closure relation of an observable} \quad \sum_{n=1}^{\infty} \sum_{i=1}^{g_n} |\psi_n^i\rangle \langle \psi_n^i| = \mathbb{1}. \quad (1.86)$$

The projector onto the subspace  $\mathcal{E}_n$  is written as:

$$P_n = \sum_{i=1}^{g_n} |\psi_n^i\rangle \langle \psi_n^i|. \quad (1.87)$$

The observable  $A$  is then given by:

$$A = \sum_n a_n P_n. \quad (1.88)$$

Equation (1.86) can be generalized to include cases of continuous spectrum using the previous table of the first section.

If  $A$  has a mixed spectrum, then it is an observable if this system form a basis, that is, if

$$\sum_n \sum_{i=1}^{g_n} |\psi_n^i\rangle \langle \psi_n^i| + \int_{\nu_1}^{\nu_2} d\nu |\psi_\nu\rangle \langle \psi_\nu| = \mathbb{1}. \quad (1.89)$$

### The projector $P_\psi$ is an observable

The projector  $P_\psi = |\psi\rangle \langle \psi|$  is an observable. We know that it is Hermitian, and that its eigenvalues are 1 and 0, the first one is simple and the other infinitely degenerate. It can be shown that any ket  $|\psi\rangle$  can be expanded on these eigenkets, therefore  $P_\psi$  is an observable.

## 1.4.3 Sets of commuting observables

Important theorems

**Theorem I**

If two operators  $A$  and  $B$  commute, and if  $|\psi\rangle$  is an eigenvector of  $A$ ,  $B|\psi\rangle$  is also an eigenvector of  $A$ , with the same eigenvalue.

Another form:

If two operators  $A$  and  $B$  commute, every eigensubspace of  $A$  is globally invariant under the action of  $B$  ( $B|\psi\rangle$  belongs to the eigensubspace  $\mathcal{E}_a$  of  $A$ , corresponding to the eigenvalue  $a$ ).

**Theorem II (consequence of theorem I)**

If two observables  $A$  and  $B$  commute, and if  $|\psi_1\rangle$  and  $|\psi_2\rangle$  are two eigenvectors of  $A$  with different eigenvalues, the matrix element  $\langle\psi_1|B|\psi_2\rangle$  is zero.

**Theorem III**

If two observables  $A$  and  $B$  commute, one can construct an orthonormal basis of the state space with eigenvectors common to  $A$  and  $B$ .

Let's prove the theorem III. Consider two commuting observables  $A$  and  $B$ , with discrete spectrum. Since  $A$  is observable, there exists at least one orthonormal system of eigenvectors  $|u_n^i\rangle$  which forms a basis in the state space:

$$A|u_n^i\rangle = a_n|u_n^i\rangle, \quad \begin{matrix} n = 1, 2, \dots \\ i = 1, 2, \dots, g_n \end{matrix} \quad (1.90)$$

We also have  $\langle u_n^i | u_{n'}^{i'} \rangle = \delta_{nn'} \delta_{ii'}$ . What does the matrix look like which represents  $B$  in the  $\{|u_n^i\rangle\}$  basis? We know that the matrix elements  $\langle u_n^i | B | u_{n'}^{i'} \rangle$  are zero when  $n \neq n'$  (theorem II). Let us arrange the basis vectors  $|u_n^i\rangle$  in the order:

$$|u_1^1\rangle, |u_1^2\rangle, \dots, |u_1^{g_1}\rangle; |u_2^1\rangle, \dots, |u_2^{g_2}\rangle; |u_3^1\rangle, \dots$$

We then obtain for  $B$  a block-diagonal matrix of the form:

$$\begin{bmatrix} & \mathcal{E}_1 & & \mathcal{E}_2 & & \mathcal{E}_3 & \dots \\ \mathcal{E}_1 & \ddots & \ddots & 0 & & 0 & 0 \\ & \ddots & \ddots & & & & \\ \mathcal{E}_2 & & & \ddots & \ddots & \ddots & \\ & 0 & & \ddots & \ddots & \ddots & 0 & 0 \\ & & & \ddots & \ddots & \ddots & & \\ \mathcal{E}_3 & 0 & & 0 & & \ddots & 0 \\ \vdots & 0 & & 0 & & 0 & \ddots & \ddots & \ddots \end{bmatrix} \quad (1.91)$$

Then the degeneracy of the eigenvalue is 1, then the block reduces to a  $1 \times 1$  matrix. In the column associated with  $|u_n\rangle$  all the other matrix elements are zero, this expresses the fact that  $|u_n\rangle$  is an eigenvector common to  $A$  and  $B$ . When  $a_n$  is a  $g_n$ -degenerate eigenvalue of  $A$ , the block which represents  $B$  in  $\mathcal{E}_n$  is not, in general, diagonal: the  $|u_n^i\rangle$  are not, in general, eigenvectors of  $B$ . The action of  $A$  in the  $g_n$  eigenvectors  $|u_n^i\rangle$  reduces to  $a_n|u_n^i\rangle$ , the matrix representing the restriction of  $A$  within  $\mathcal{E}_n$  is equal to  $a_n I_{g_n \times g_n}$ . The matrix representing the operator  $A$  in  $\mathcal{E}_n$  is always diagonal and equal to  $a_n I_{g_n \times g_n}$ .

We use this property to obtain a basis of  $\mathcal{E}_n$  composed of vectors that are also eigenvectors of  $B$ . The matrix representing  $B$  in  $\mathcal{E}_n$  when the basis is chosen is

$$\{|u_n^i\rangle, \quad i = 1, 2, \dots, g_n\}, \quad (1.92)$$

has for its elements:

$$\beta_{ij}^{(n)} = \langle u_n^i | B | u_n^j \rangle. \quad (1.93)$$

This matrix is Hermitian, since  $B$  is a Hermitian operator. It is therefore diagonalizable: one can find a new basis  $\{|v_n^i\rangle; i = 1, 2, \dots, g_n\}$  in which  $B$  is represented by a diagonal matrix:

$$\langle v_n^i | B | v_n^j \rangle = \beta_i^n \delta_{ij}. \quad (1.94)$$

This means that the new basis vectors in  $\mathcal{E}_n$  are eigenvectors of  $B$ :

$$B|v_n^i\rangle = \beta_i^{(n)}|v_n^i\rangle. \quad (1.95)$$

These vectors are automatically eigenvectors of  $A$  with an eigenvalue  $a_n$  since they belong to  $\mathcal{E}_n$ .

Eigenvectors of  $A$  associated with degenerate eigenvalues are not necessarily eigenvectors of  $B$ . It is always possible to choose, in every eigensubspace of  $A$ , a basis of eigenvectors common to  $A$  and  $B$ .

If we perform this operation in all the subspaces  $\mathcal{E}_n$ , we obtain a basis of  $\mathcal{E}$ , formed by eigenvectors common to  $A$  and  $B$ .

We shall denote by  $|u_{n,p}^i\rangle$  the eigenvectors common to  $A$  and  $B$ :

$$A|u_{n,p}^i\rangle = a_n|u_{n,p}^i\rangle, \quad \text{and} \quad B|u_{n,p}^i\rangle = b_p|u_{n,p}^i\rangle. \quad (1.96)$$

The index  $i$  will be used to distinguish between different basis vectors which correspond to the same eigenvalues  $a_n$  and  $b_p$ .

### Complete sets of commuting observables (C.S.C.O.)

Consider an observable  $A$  and a basis  $\mathcal{E}$  composed of eigenvectors  $|u_n^i\rangle$  of  $A$ .

If none of the eigenvalues of  $A$  is degenerate, the various basis vectors of  $\mathcal{E}$  can be labelled by the eigenvalue  $a_n$  (index  $i$  is not necessary). Therefore, specifying the eigenvalue determines in a unique way the corresponding eigenvector. In other words, there exists only one basis of  $\mathcal{E}$  formed by the eigenvectors of  $A$ . It is said that the observable  $A$  constitutes, by itself, a C.S.C.O.

On the other hand, if at least one eigenvalue of  $A$  is degenerate, specifying  $a_n$  is no longer always sufficient to characterize a basis vector: the basis of eigenvectors of  $A$  is not unique. One can choose any basis inside each of the degenerate eigensubspaces  $\mathcal{E}_n$ . We can choose another observable  $B$  which commutes with  $A$  to construct an orthonormal basis of eigenvectors common to  $A$  and  $B$ .  $A$  and  $B$  form a C.S.C.O. if this basis is unique, that is, if to each of the possible pairs of eigenvalues  $\{a_n, b_p\}$  there corresponds only one basis vector. For  $A$  and  $B$  to constitute a C.S.C.O., it is necessary and sufficient that, inside each of these subspaces, all the  $g_n$  eigenvalues of  $B$  be distinct. We can add indefinitely observables until we reach the C.S.C.O.

A set of observables  $A, B, C, \dots$  is called a complete set of commuting observables if:

- (i) all the observables commute by pairs.
- (ii) specifying the eigenvalue of all the operators determines a unique common eigenvector. The ket then is denoted as  $|a_n, b_p, c_r, \dots\rangle$ .

This means that they are C.S.C.O. if there exists a unique orthonormal basis of common eigenvectors.

Identification of CSCOs is necessary in order to construct physically meaningful bases for  $\mathcal{E}$ . Knowing the CSCOs that are available tells the experimenter the possible sets of measurements that can be made to achieve this goal.

We list some CSCOs for specific problems. (table 31 anerson)

## 1.5 Representation $\{r\}$ and $\{p\}$

## Formula sheet

### Constants and Conversions

Unit	Name	Equivalent SI value
$eV$	electron-volt	$\approx 1.602 \cdot 10^{-19} \text{ J}$
$G$	Gauss	$10^{-4} \text{ T}$

Speed of light in vacuum  $c = 2.998 \cdot 10^8 \text{ m/s}$  | Reduced Planck's constant  $\hbar = 1.055 \cdot 10^{-34} \text{ J} \cdot \text{s}$

#### 1.5.1 Useful formulas

Closure relation (discrete)	$\sum_k \sum_{i=1}^{g_k}  v_k^i\rangle \langle v_k^i  = \mathbb{1}$	Closure relation (continuous)	$\int_{\beta} d\beta  \omega_{\beta}\rangle \langle \omega_{\beta}  = \mathbb{1}$
Glauber Formula	$e^{A+B} = e^A e^B e^{-\frac{1}{2}[A,B]}$	Generalized uncertainty relation	$\Delta A \Delta B \geq \frac{1}{2}  \langle [A, B] \rangle $
Function of an operator	$F(A) = \sum_{n=0}^{\infty} \frac{(A-a)^n}{n!} F^{(n)}(a)$		$\Delta Q = \sqrt{\langle Q^2 \rangle - \langle Q \rangle^2}$
Transformation $\{u\} \rightarrow \{v\}$	$\mathbb{M}_{jk} = \langle u_j   v_k \rangle$	$ \psi\rangle_{\{u\}} = \mathbb{M}  \psi\rangle_{\{v\}}$ $A_{\{u\}} = \mathbb{M} A_{\{v\}} \mathbb{M}^{\dagger}$	$ \psi\rangle_{\{v\}} = \mathbb{M}^{\dagger}  \psi\rangle_{\{u\}}$ $A_{\{v\}} = \mathbb{M}^{\dagger} A_{\{u\}} \mathbb{M}$

Quantity	Discrete basis (sum over $j, k$ )	Continuous basis (integrate over $\beta, \beta'$ )
$\mathbb{1}$	$= \sum  v_k\rangle \langle v_k $	$= \int d\beta  \omega_{\beta}\rangle \langle \omega_{\beta} $
$ \psi\rangle = \mathbb{1}  \psi\rangle$	$= \sum  v_k\rangle \langle v_k   \psi \rangle$	$= \int d\beta  \omega_{\beta}\rangle \langle \omega_{\beta}   \psi \rangle$
$\langle \varphi   = \langle \varphi   \mathbb{1}$	$= \sum \langle \varphi   v_k \rangle \langle v_k  $	$= \int d\beta \langle \varphi   \omega_{\beta} \rangle \langle \omega_{\beta}  $
$A = \mathbb{1} A \mathbb{1}$	$= \sum \sum  v_j\rangle \langle v_j   A   v_k \rangle \langle v_k  $	$= \iint d\beta d\beta'  \omega_{\beta}\rangle \langle \omega_{\beta}   A   \omega_{\beta'} \rangle \langle \omega_{\beta'}  $

Quantity	$X$ representation	$P_x$ representation
$X$	$x$	$i\hbar \partial / \partial p$
$P_x$	$-i\hbar \partial / \partial x$	$p$
$ x'\rangle$	$\langle x   x' \rangle = \delta(x - x')$	$\langle p   x' \rangle = \frac{1}{\sqrt{2\pi\hbar}} \exp(-ix'p/\hbar)$
$ p'\rangle$	$\langle x   p' \rangle = \frac{1}{\sqrt{2\pi\hbar}} \exp(ixp'/\hbar)$	$\langle p   p' \rangle = \delta(p - p')$

#### Fourier transforms for 3D wavefunctions

$$\tilde{\psi}(\mathbf{p}) = \mathcal{F}[\psi(\mathbf{r})] = \left(\frac{1}{2\pi\hbar}\right)^{3/2} \int_{-\infty}^{\infty} d^3\mathbf{r} e^{-i\mathbf{r}\cdot\mathbf{p}/\hbar} \psi(\mathbf{r}) \quad \left| \quad \psi(\mathbf{r}) = \mathcal{F}^{-1}[\tilde{\psi}(\mathbf{p})] = \left(\frac{1}{2\pi\hbar}\right)^{3/2} \int_{-\infty}^{\infty} d^3\mathbf{p} e^{i\mathbf{r}\cdot\mathbf{p}/\hbar} \tilde{\psi}(\mathbf{p}) \right.$$

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