# Assignment 4

# OPTI 570 Quantum Mechanics

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## Problem I

a) The sixth postulates of Quantum mechanics states the time evolution of the state  $|\psi\rangle$ :

$$i\hbar \frac{d}{dt}|\psi(t)\rangle = H(t)|\psi(t)\rangle.$$
 (1)

If we multiplty equation (1) by  $\langle \phi(t) |$  and use the product rule of differentiation we get

$$\frac{d}{dt}\langle\psi(t)|\phi(t)\rangle = \left[\frac{d}{dt}\langle\psi(t)|\right]|\phi(t)\rangle + \langle\psi(t)|\left[\frac{d}{dt}|\phi(t)\rangle\right].$$

On the one hand, from Schrodinger equation we have

$$\frac{d}{dt}|\phi(t)\rangle = \frac{1}{i\hbar}H(t)|\phi(t)\rangle.$$

On the other hand, if we compute the adjoint of the Schrodinger equation for  $|\psi(t)\rangle$ :

$$\frac{d}{dt}\langle\psi(t)| = -\frac{1}{i\hbar}\langle\psi(t)|H(t). \qquad (H^{\dagger}(t) = H(t))$$

Replacing both results into the product rule yields:

$$\begin{split} \frac{d}{dt} \langle \psi(t) | \phi(t) \rangle &= \left[ -\frac{1}{i\hbar} \langle \psi(t) | H(t) \right] | \phi(t) \rangle + \langle \psi(t) | \left[ \frac{1}{i\hbar} H(t) | \phi(t) \rangle \right] \\ &= -\frac{1}{i\hbar} \langle \psi(t) | H(t) | \phi(t) \rangle + \frac{1}{i\hbar} \langle \psi(t) | H(t) | \phi(t) \rangle \\ \frac{d}{dt} \langle \psi(t) | \phi(t) \rangle &= 0. \end{split} \tag{2}$$

The evolution of a state  $|\psi(t_0)\rangle$  to  $|\psi(t)\rangle$  follows a linear fashion. Therefore, the transformation can be represented by a linear evolution operator  $U(t,t_0)$  so that

$$|\psi(t)\rangle = U(t, t_0)|\psi(t_0)\rangle. \tag{3}$$

The time derivative is zero means that the argument must be a constant:

$$\frac{d}{dt}\langle \varphi(t)|\phi(t)\rangle = 0 \Longrightarrow \langle \varphi(t)|\phi(t)\rangle = \text{cte} = \langle \varphi(t_0)|\phi(t_0)\rangle.$$

We put the definition of the evolution operator

$$\langle \varphi(t_0)U^{\dagger}(t,t_0)U(t,t_0)|\phi(t_0)\rangle = \langle \varphi(t_0)|\phi(t_0)\rangle$$

By comparison, we have that

$$U^{\dagger}(t, t_0)U(t, t_0) = 1$$
,

which is the definition of an unitary operator.

b) If  $|\psi(t_0)\rangle = |\phi_n^i\rangle$ , then the state is fully characterized by a single eigenvector of the Hamiltonian. This corresponds to its expansion

$$|\psi(t)\rangle = c_n(t)|\phi_n^i\rangle$$
, with  $c_n(t) = \langle \phi_n^i|\psi(t)\rangle = 1$ .

We use the coefficient in the Schrodinger equation:

$$i\hbar \frac{d}{dt} \langle \phi_n^i | \psi(t) \rangle = \langle \phi_n^i | H | \psi(t) \rangle = E_n \langle \phi_n^i | \psi(t) \rangle.$$

The first and last equation, construct a first-order differential equation in the coefficient  $c_n(t)$ :

$$i\hbar \frac{d}{dt}c_n(t) = E_n c_n(t) \longrightarrow c_n(t) = c_n(t_0)e^{-E_n(t-t_0)/\hbar},$$

where  $c_n(t_0)$  is the value for  $\psi(t_0)$ , in this case,  $\psi(t_0) = |\psi_n^i\rangle$  and  $c_n(t_0) = 1$ . Therefore,

$$|\psi(t)\rangle = 1e^{-iE_n(t-t_0)/\hbar}|\psi(t_0)\rangle.$$

c) In the general case, where the state vector has more than one coefficient of projection, we can do the same with the inclusion of the summation for each coefficient, including also the degree of degeneracy. We can think of the previous result as just one of the several terms, but all share the same structure. We give a small derivation,

$$\sum_{n,i} i\hbar \frac{d}{dt} c_n^i(t) = \sum_{n,i} E_n c_n^i(t) \longrightarrow \sum_{n,i} c_{n,i}(t) = \sum_{n,i} c_{n,i}(t_0) e^{-E_n(t-t_0)/\hbar},$$

The equations above are for each eigenvector, which then construct the state vector:

$$|\psi(t)\rangle = \sum_{n,i} c_n^i(t_0) e^{-iE_n(t-t_0)/\hbar} |\phi_n^i\rangle.$$

To be a stationary state, there only have to be a global phase common to all the eigenvectors. However, if the state vector is represented by several eigenvectors, each one will have its own phase, that represent the relative phase factor. How behaves this phase factor depends on the argument of the esponential term:  $-iE_n(t-t_0)/\hbar$ . The only variable we can study is  $E_n$  that corresponds to the eigenvalue. In order to remain the phase equal for all the eigenvectors, we need that  $E_n = E_{n+1} = \cdots = E$ , that is, we should live in a single eigensubspace of the Hamiltonian, which may have several eigenvectors but all share the same eigenvalue and therefore the same phase factor.

### Problem II

a. We need to normalized the wavefunction in the range  $x \in (-\infty, \infty)$  so that its norm is unitary.

$$\int_{-\infty}^{\infty} dx \ |\psi(x)|^2 = \int_{-\infty}^{\infty} dx \ \left| N \frac{e^{ip_0 x/\hbar}}{\sqrt{x^2 + a^2}} \right|^2 = N^2 \int_{-\infty}^{\infty} dx \ \frac{1}{x^2 + a^2} = N^2 \frac{\pi}{a} = 1 \longrightarrow N = \sqrt{\frac{a}{\pi}}.$$

The integral was computed with the change of variable  $x = a \tan \theta$ . The wave function is then

$$\psi(x) = \sqrt{\frac{a}{\pi}} \frac{e^{ip_0 x/\hbar}}{\sqrt{x^2 + a^2}}.$$

b. To find the probability in the range given, we integrate  $|\psi(x)|^2$  in the interval. We also notice that the integrand will be even, so we only integrate one part and multiply it by two:

$$\sqrt{\frac{a}{\pi}} \int_{-a/\sqrt{3}}^{a/\sqrt{3}} \frac{1}{x^2 + a^2} = 2\sqrt{\frac{a}{\pi}} \int_0^{a/\sqrt{3}} \frac{1}{x^2 + a^2} = \frac{\sqrt{\pi}}{3\sqrt{a}}.$$

c. To get the mean value of the momentum, we will compute the following:

$$\langle P \rangle_{\psi} = \langle \psi | P | \psi \rangle = \langle \psi | \mathbb{1}P | \psi \rangle = \int dx \, \langle \psi | x \rangle \langle x | P | \psi \rangle = \int dx \, \psi^*(x) [-i\hbar \partial_x \psi(x)].$$

The time derivative is:

$$\partial_x \psi(x) = \sqrt{\frac{a}{\pi}} \left[ \frac{ip_o}{\hbar} (x^2 + a^2)^{-1/2} - x(x^2 + a^2)^{-3/2} \right] e^{ip_0 x/\hbar}.$$

The multiplication  $\psi^*(x) \cdot \partial_x \psi(x)$  is:

$$\psi^*(x) \cdot \partial_x \psi(x) = \sqrt{\frac{a}{\pi}} (x^2 + a^2)^{-1/2} e^{-ip_0 x/\hbar} \cdot \sqrt{\frac{a}{\pi}} \left[ \frac{ip_0}{\hbar} (x^2 + a^2)^{-1/2} - x(x^2 + a^2)^{-3/2} \right] e^{ip_0 x/\hbar}$$

$$= \frac{a}{\pi} (x^2 + a^2)^{-1/2} \left[ \frac{ip_0}{\hbar} (x^2 + a^2)^{-1/2} - x(x^2 + a^2)^{-3/2} \right]$$

$$\psi^*(x) \cdot \partial_x \psi(x) = \frac{a}{\pi} \left[ \frac{ip_0}{\hbar} (x^2 + a^2)^{-1/2} - x(x^2 + a^2)^{-2} \right].$$

We proceed to integrate it:

$$\begin{split} \langle P \rangle_{\psi} &= \frac{-i\hbar a}{\pi} \left[ \frac{ip_o}{\hbar} \int_{-\infty}^{\infty} dx \; (x^2 + a^2)^{-1/2} - \int_{-\infty}^{\infty} dx \; x (x^2 + a^2)^{-2} \right] \\ &= \frac{-i\hbar a}{\pi} \left[ \frac{ip_o}{\hbar} \frac{\pi}{|a|} - 0 \right] \\ &= \frac{-i\hbar a}{\pi} \frac{ip_o}{\hbar} \frac{\pi}{|a|} \\ \langle P \rangle_{\psi} &= p_o. \end{split}$$

## Problem III

a. In this case, the wave function is expanded in a discrete set  $\{\psi_n\}$  of length four. Each of these eigenvectors has a  $E_n$  associated. We are asked of the probability of getting an energy less than  $E_{\approx 2.4}$ , which is the same than asking for a probability less or equal than  $E_2$ .

$$P(H \le E_2) = \frac{1}{\langle \psi | \psi \rangle} \sum_{n=1}^{2} \langle \psi | P_n | \psi \rangle = \frac{1}{\langle \psi | \psi \rangle} \left[ \langle \psi | P_1 | \psi \rangle + \langle \psi | P_2 | \psi \rangle \right] = \frac{|a_1|^2 + |a_2|^2}{|a_1|^2 + |a_2|^2 + |a_3|^2 + |a_4|^2}.$$

b. On the one hand, the mean value of the enegy is:

$$\langle H \rangle_{\psi} = \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{\sum_{n} \langle \psi | \varphi_{n} \rangle \langle \varphi_{n} | H | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{\sum_{n} |a_{n}|^{2} E_{n}}{\langle \psi | \psi \rangle} = \frac{|a_{1}|^{2} E_{1} + |a_{2}|^{2} E_{2} + |a_{3}|^{2} E_{3} + |a_{4}|^{4} E_{4}}{|a_{1}|^{2} + |a_{2}|^{2} + |a_{3}|^{2} + |a_{4}|^{2}}.$$

On the other hand, the RMS deviation of the energy is:

$$\Delta H = \sqrt{\langle H^2 \rangle - \langle H \rangle^2}.$$

The term  $\langle E^2 \rangle_{\psi}$  must be recalculated following the previous procedure:

$$\langle H^2 \rangle_{\psi} = \frac{\langle \psi | H^2 | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{\sum_n |a_n|^2 E_n^2}{\langle \psi | \psi \rangle} = \frac{|a_1|^2 E_1^2 + |a_2|^2 E_2^2 + |a_3|^2 E_3^2 + |a_4|^4 E_4^2}{|a_1|^2 + |a_2|^2 + |a_3|^2 + |a_4|^2}.$$

Finally, the RMS deviation is:

$$\Delta H = \sqrt{\frac{\sum_n |a_n|^2 E_n^2}{\langle \psi | \psi \rangle} - \left(\frac{\sum_n |a_n|^2 E_n}{\langle \psi | \psi \rangle}\right)^2}.$$

c. The Hamiltonian of this system does not depend on time so that the system in conservative. We already know the expansion of the state vector at t = 0. Therefore, we only need to add the temporal phase factor to each of them to construct the state vector at time t:

$$|\psi(t)\rangle = \sum_{n=1}^{4} a_n e^{-iE_n(t-t_0)/\hbar} |\varphi_n\rangle.$$

Because the system is projected in more than one eigenvector of the Hamiltonian, it is not a stationary state. This implies that the the state vector will be different over time due to the relative phase factors, and therefore we expect  $\langle E \rangle$  and  $\Delta E$  to change.

d. When the measurement is performed, the result corresponds to the eigenvalue  $E_4$  (n=4). This means that the eigenvector obtained in the state of the system is  $|\varphi_4\rangle$ , with the corresponding normalization factor:

$$|\psi(t)\rangle \stackrel{(E_4)}{\Longrightarrow} \frac{P_4|\varphi\rangle}{\sqrt{\langle\psi|P_4|\psi\rangle}} = \frac{a_4}{|a_4|} e^{-iE_4(t-t_0)/\hbar} |\varphi_4\rangle.$$

Now, we have the state  $|\varphi_4\rangle$  just after the measurement. However, because the Hamiltonian is time-independent, it will only evolve a global phase factor that will not affect the physical meaning of the state. In consequence, after the measurement we will always get  $|\varphi_4\rangle$ .

### Problem IV

We have the followings eigenpairs for each observator:

$$H: \{(\hbar\omega_0, |u_1\rangle), (2\hbar\omega_0, |u_2\rangle), (2\hbar\omega_0, |u_3\rangle)\}.$$

A: 
$$\{(a, |u_1\rangle), (a, |+\rangle = \frac{|u_2\rangle + |u_3\rangle}{\sqrt{2}}, (-a, |-\rangle = \frac{|u_2\rangle - |u_3\rangle}{\sqrt{2}}\}$$

B: 
$$\{(b, |+\rangle = \frac{|u_1\rangle + |u_2\rangle}{\sqrt{2}}\}, (-b, |-\rangle = \frac{|u_1\rangle - |u_2\rangle}{\sqrt{2}}\}, (b, |u_3\rangle)\}.$$

We give a small derivation of how the eigenvector of A were obtained. The first case is trivial, but for the second row we have:

$$A|u_2\rangle = a|u_3\rangle.$$

We can see that it doesn't map onto  $|u_2\rangle$ , but on other vector. We then think of the eigenvector as a combination of them:

$$|v\rangle = \alpha |u_2\rangle + \beta |u_3\rangle.$$

Then,

$$A|v\rangle = \lambda|v\rangle \longrightarrow a(\beta|u_2\rangle + \alpha|u_3\rangle) = \lambda(\alpha|u_2\rangle + \beta|u_3\rangle).$$

Equating the vectors results in the following relations:

$$a\beta = \lambda\alpha \wedge a\alpha = \lambda\beta \Longrightarrow \lambda^2 = \alpha^2.$$

For  $\lambda = +a$ ,  $\beta = \alpha$  and  $|v_{+}\rangle \propto |u_{2}\rangle + |u_{3}\rangle$ . For  $\lambda = -a$ ,  $\beta = -\alpha$  and  $|v_{-}\rangle \propto |u_{2}\rangle - |u_{3}\rangle$ . After normalize each results we have the eigenket we have listed.

a. The results can only be eigenvalues of the Hamiltonian by the third postulate. Each one has a given probability, therefore:

$$\hbar\omega_0, \text{ with } P(\hbar\omega_0) = \langle \psi | P_{\hbar\omega_0} | \psi \rangle = |\langle u_1 | \psi \rangle|^2 = \frac{1}{2}$$

$$2\hbar\omega_0, \text{ with } P(2\hbar\omega_0) = \langle \psi | P_{2\hbar\omega_0} | \psi \rangle = |\langle u_2 | \psi \rangle|^2 + |\langle u_3 | \psi \rangle|^2 = \frac{1}{4} + \frac{1}{4} = \frac{1}{2}.$$

In each case the projector was:

$$P_{\hbar\omega_0} = |u_1\rangle\langle u_1| = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad \text{and} \quad P_{2\hbar\omega_0} = |u_2\rangle\langle u_2| + |u_3\rangle\langle u_3| = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

The mean value is:

$$\langle H \rangle_{\psi} = \langle \psi | H | \psi \rangle = \sum_{n=1}^{2} \sum_{i=1}^{g_n} \langle \psi | H | u_n^i \rangle \langle u_n^i | \psi \rangle = \sum_{n=1}^{2} E_n P(E_n) = (\hbar \omega_0) \frac{1}{2} + (2\hbar \omega_0) \frac{1}{2} = \frac{3\hbar \omega_0}{2}.$$

On the other hand, the term  $\langle H^2 \rangle_{\psi}$  is:

$$\langle H^2 \rangle_{\psi} = \sum_{n=1}^{2} E_n^2 P(E_n) = (\hbar \omega_0)^2 \frac{1}{2} + (2\hbar \omega_0)^2 \frac{1}{2} = \frac{5\hbar^2 \omega_0^2}{2}.$$

Then,

$$\Delta H = \sqrt{\langle H^2 \rangle - \langle H \rangle^2} = \sqrt{\frac{5\hbar^2 \omega_0^2}{2} - \left(\frac{3\hbar\omega_0}{2}\right)^2} = \frac{\hbar\omega_0}{2}.$$

b. In order to define the probability of every outcome, we will define first the projector for every result:

$$P_{a} = |u_{1}\rangle\langle u_{1}| + |+\rangle\langle +| = |u_{1}\rangle\langle u_{1}| + \frac{1}{2}[|u_{2}\rangle\langle u_{2}| + |u_{2}\rangle\langle u_{3}| + |u_{3}\rangle\langle u_{2}| + |u_{3}\rangle\langle u_{3}|] = \frac{1}{2}\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix},$$

$$P_{-a} = |-\rangle\langle -| = \frac{1}{2}[|u_{2}\rangle\langle u_{2}| - |u_{2}\rangle\langle u_{3}| - |u_{3}\rangle\langle u_{2}| + |u_{3}\rangle\langle u_{3}|] = \frac{1}{2}\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 1 \end{bmatrix}.$$

Now, the outcomes along with their probabilities are:

a, with 
$$P(a) = \langle \psi | P_a | \psi \rangle = |\langle u_1 | \psi \rangle|^2 + \frac{1}{2} \left[ |\langle u_2 | \psi \rangle|^2 + |\langle \psi | u_2 \rangle \langle u_3 | \psi \rangle|^2 + |\langle \psi | u_3 \rangle \langle u_2 | \psi \rangle|^2 + |\langle u_3 | \psi \rangle|^2 \right] = 1$$

$$-a, \quad \text{with} \quad P(-a) = \langle \psi | P_{-a} | \psi \rangle = \frac{1}{2} \left[ |\langle u_2 | \psi \rangle|^2 - |\langle \psi | u_2 \rangle \langle u_3 | \psi \rangle|^2 - |\langle \psi | u_3 \rangle \langle u_2 | \psi \rangle|^2 + |\langle u_3 | \psi \rangle|^2 \right] = 0.$$

Given the above, The state vector immmediately after a measurement will be:

$$|\psi\rangle \stackrel{(a)}{\Longrightarrow} \frac{P_a|\psi\rangle}{\sqrt{\langle\psi|P_a|\psi\rangle}} = \frac{1}{\sqrt{2}}|u_1\rangle + \frac{1}{2}|u_2\rangle + \frac{1}{2}|u_3\rangle.$$

Recall that each eigenvalue has its own projector. It is used to compute probabilities and states after measurements.

c. The system is conservative as the Hamiltonian is time-independent. Therefore, the evolution of the state to an arbitrary time t is:

$$|\psi(t)\rangle = \sum_{n=1}^{2} \sum_{i=1}^{g_n} c_n^i e^{-iE_n t/\hbar} |u_n^i\rangle = \frac{1}{\sqrt{2}} e^{-i\omega_0 t} |u_1\rangle + \frac{1}{2} e^{-i2\omega_0 t} |u_2\rangle + \frac{1}{2} e^{-i2\omega_0 t} |u_3\rangle.$$

d. First, the mean value of A over time needs to explicitly state the eigenequation for A:

$$A|u_1\rangle = a|u_1\rangle, \quad A|u_2\rangle = a|u_3\rangle, \quad A|u_3\rangle = 2|u_2\rangle.$$

$$\begin{split} \langle A \rangle(t) &= \langle \psi | A | \psi \rangle = \sum_{n=1}^2 \sum_{i=1}^{g_n} = \sum_{n=1}^2 \sum_{i=1}^{g_n} \langle \psi | A | u_n^i \rangle \langle u_n^i | \psi \rangle \\ &= \langle \psi | A | u_1 \rangle \langle u_1 | \psi \rangle + \langle \psi | A | u_2 \rangle \langle u_2 | \psi \rangle + \langle \psi | A | u_3 \rangle \langle u_3 | \psi \rangle \\ &= \langle \psi | A | u_1 \rangle \frac{1}{\sqrt{2}} e^{-i\omega_0 t} + \langle \psi | A | u_2 \rangle \frac{1}{2} e^{-i2\omega_0 t} + \langle \psi | A | u_3 \rangle \frac{1}{2} e^{-i2\omega_0 t} \\ &= a \langle \psi | u_1 \rangle \frac{1}{\sqrt{2}} e^{-i\omega_0 t} + a \langle \psi | u_3 \rangle \frac{1}{2} e^{-i2\omega_0 t} + a \langle \psi | u_2 \rangle \frac{1}{2} e^{-i2\omega_0 t} \\ &= a \left[ \frac{1}{\sqrt{2}} e^{i\omega_0 t} \right] \frac{1}{\sqrt{2}} e^{-i\omega_0 t} + a \left[ \frac{1}{2} e^{i2\omega_0 t} \right] \frac{1}{2} e^{-i2\omega_0 t} + a \left[ \frac{1}{2} e^{-i2\omega_0 t} \right] \frac{1}{2} e^{-i2\omega_0 t} \\ &= \frac{a}{2} + \frac{a}{4} + \frac{a}{4} \\ \langle A \rangle(t) &= a. \end{split}$$

The matrix formalism can also be used:

$$\langle B \rangle(t) = \langle \psi | B | \psi \rangle$$

$$= \begin{bmatrix} \frac{1}{\sqrt{2}} e^{i\omega_0 t} & \frac{1}{2} e^{i2\omega_0 t} & \frac{1}{2} e^{i2\omega_0 t} \end{bmatrix} \cdot \begin{bmatrix} 0 & b & 0 \\ b & 0 & 0 \\ 0 & 0 & b \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} e^{-i\omega_0 t} \\ \frac{1}{2} e^{-i2\omega_0 t} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{\sqrt{2}} e^{i\omega_0 t} & \frac{1}{2} e^{i2\omega_0 t} & \frac{1}{2} e^{i2\omega_0 t} \end{bmatrix} \cdot \frac{b}{2} \begin{bmatrix} e^{-i2\omega_0 t} \\ \sqrt{2} e^{-i\omega_0 t} \\ e^{-i2\omega_0 t} \end{bmatrix}$$

$$= \frac{b}{2} \begin{bmatrix} \frac{\sqrt{2}}{2} e^{-i\omega_0 t} + \frac{\sqrt{2}}{2} e^{i\omega_0 t} + \frac{1}{2} \end{bmatrix}$$

$$\langle B \rangle(t) = \frac{b}{2} \begin{bmatrix} \sqrt{2} \cos \omega_0 t + \frac{1}{2} \end{bmatrix}.$$

The mean value of A is time-independent, while for B is not.

e. The probability for A are:

$$a: \qquad P(a) = \langle \psi | P_b | \psi \rangle = \begin{bmatrix} \frac{1}{\sqrt{2}} e^{i\omega_0 t} & \frac{1}{2} e^{i2\omega_0 t} & \frac{1}{2} e^{i2\omega_0 t} \end{bmatrix} \frac{1}{2} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} e^{-i\omega_0 t} \\ \frac{1}{2} e^{-i2\omega_0 t} \end{bmatrix} = 1.$$

$$-a: \qquad P(-a) = \langle \psi | P_{-a} | \psi \rangle = \begin{bmatrix} \frac{1}{\sqrt{2}} e^{i\omega_0 t} & \frac{1}{2} e^{i2\omega_0 t} & \frac{1}{2} e^{i2\omega_0 t} \end{bmatrix} \frac{1}{2} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} e^{i\omega_0 t} \\ \frac{1}{2} e^{i2\omega_0 t} \\ \frac{1}{2} e^{i2\omega_0 t} \end{bmatrix} = 0.$$

For B, we have the following eigensubspace projectors:

$$P_{b} = |+\rangle\langle +|+|u_{3}\rangle\langle u_{3}| = \frac{1}{2}[|u_{1}\rangle\langle u_{1}|+|u_{1}\rangle\langle u_{2}|+|u_{2}\rangle\langle u_{1}|+|u_{2}\rangle\langle u_{2}|] + |u_{3}\rangle\langle u_{3}| = \frac{1}{2}\begin{bmatrix} 1 & 1 & 0\\ 1 & 1 & 0\\ 0 & 0 & 2 \end{bmatrix}$$

$$P_{-b} = |-\rangle\langle -| = \frac{1}{2}[|u_{1}\rangle\langle u_{1}|-|u_{1}\rangle\langle u_{2}|-|u_{2}\rangle\langle u_{1}|+|u_{2}\rangle\langle u_{2}|] = \frac{1}{2}\begin{bmatrix} 1 & -1 & 0\\ -1 & 1 & 0\\ 0 & 0 & 0 \end{bmatrix}.$$

The possibilities are:

$$b: P(b) = \langle \psi | P_b | \psi \rangle$$

$$= \left[ \frac{1}{\sqrt{2}} e^{i\omega_0 t} \quad \frac{1}{2} e^{i2\omega_0 t} \quad \frac{1}{2} e^{i2\omega_0 t} \right] \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} e^{-i\omega_0 t} \\ \frac{1}{2} e^{-i2\omega_0 t} \end{bmatrix}$$

$$= \frac{1}{2} \left[ \frac{1}{\sqrt{2}} \cos \omega_0 t + \frac{5}{4} \right],$$

$$-b: P(-b) = \langle \psi | P_{-b} | \psi \rangle$$

$$= \left[ \frac{1}{\sqrt{2}} e^{i\omega_0 t} \quad \frac{1}{2} e^{i2\omega_0 t} \quad \frac{1}{2} e^{i2\omega_0 t} \right] \frac{1}{2} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} e^{-i\omega_0 t} \\ \frac{1}{2} e^{-i2\omega_0 t} \\ \frac{1}{2} e^{-i2\omega_0 t} \end{bmatrix}$$

$$= \frac{1}{2} \left[ \frac{3}{4} - \frac{1}{\sqrt{2}} \cos \omega_0 t \right].$$

### Problem V

a. A free particle has the following Hamiltonian

$$H = \frac{P^2}{2m} + 0.$$

We use Ehrnfest's theorem to establish that  $\langle X \rangle$  is linear of time:

$$\begin{split} \frac{d}{dt}\langle X\rangle &= \frac{1}{i\hbar}\langle [X,H]\rangle + \langle \frac{\partial X}{\partial t}\rangle \\ &= \frac{1}{i\hbar}\langle \frac{i\hbar P}{m}\rangle + 0 \\ &= \frac{1}{m}\langle P\rangle. \end{split}$$

If we differentiate the term  $\langle P \rangle$  and assuming the initial time as t=0:

$$\frac{d}{dt}\langle P \rangle = -\langle \partial_x V(X) \rangle = 0 \longrightarrow \langle P \rangle(t) = \text{cte} = \langle P(0) \rangle.$$

Then,

$$\frac{d}{dt}\langle X\rangle = \frac{\langle P(0)\rangle}{m} \longrightarrow \langle X\rangle(t) = \frac{\langle P(0)\rangle}{m}t + \langle X(0)\rangle.$$

b. Doing the same for  $X^2$  we have:

$$\frac{d}{dt}\langle X^2\rangle = \frac{1}{i\hbar}\langle [X^2,H]\rangle + \langle \frac{\partial X^2}{\partial t}\rangle = \frac{1}{i\hbar}\frac{i\hbar}{m}\langle \{X,P\}\rangle + 0 = \frac{1}{m}\langle XP + PX\rangle.$$

In addition, the mean value of the anticommutator of X and P:

$$\begin{split} \frac{d}{dt}\langle XP+PX\rangle &= \frac{1}{i\hbar}\langle [XP+PX,H]\rangle + \langle \frac{\partial (XP+PX)}{\partial t}\rangle \\ &= \frac{1}{i\hbar}\langle [XP+PX,\frac{P^2}{2m}]\rangle + 0 \\ &= \frac{1}{i\hbar}\langle [XP,\frac{P^2}{2m}] + [PX,\frac{P^2}{2m}]\rangle \\ &= \frac{1}{i\hbar}\langle X[P,\frac{P^2}{2m}] + [X,\frac{P^2}{2m}]P + P[X,\frac{P^2}{2m}] + [P,\frac{P^2}{2m}]X\rangle \\ &= \frac{1}{i\hbar}\langle \left( [X,\frac{P}{2m}]P + P[X,\frac{P}{2m}] \right)P + P\left( [X,\frac{P}{2m}]P + P[X,\frac{P}{2m}] \right)\rangle \\ &= \frac{1}{i\hbar}\langle \left( \frac{i\hbar P}{m} \right)P + P\left( \frac{i\hbar P}{m} \right)\rangle \\ &= \frac{1}{i\hbar}\frac{i2\hbar}{m}\langle P^2\rangle \\ \frac{d}{dt}\langle XP+PX\rangle &= \frac{2}{m}\langle P^2\rangle. \end{split}$$

The integral of d(XP + PX)/dt is

$$\int \frac{d}{dt} \langle XP + PX \rangle \ dt = \langle XP + PX \rangle_0 + \frac{2}{m} \int \langle P^2 \rangle \ dt = \langle XP + PX \rangle_0 + \frac{2}{m} \langle P^2 \rangle_0 t.$$

We can replace this in the  $\langle X^2 \rangle$  equation:

$$\frac{d}{dt}\langle X^2\rangle = \frac{1}{m}\langle XP + PX\rangle = \frac{1}{m}\left[\langle XP + PX\rangle_0 + \frac{2}{m}\langle P^2\rangle_0 t\right]$$

Now, we integrate one last time

$$\langle X^2 \rangle(t) = \langle X^2 \rangle_0 + \frac{1}{m} \langle XP + PX \rangle_0 t + \frac{1}{m^2} \langle P^2 \rangle_0 t^2.$$

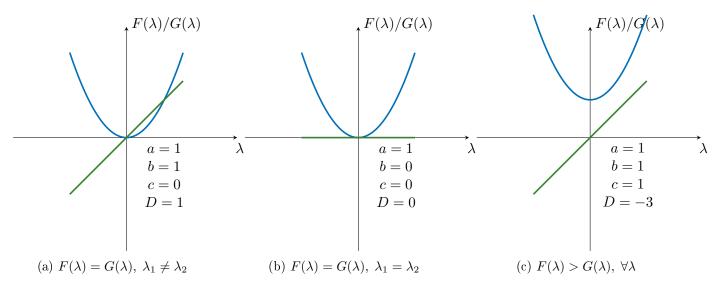
Which is similar to the cinematic function in classical mechanics, but this corresponds to the dimension of  $[L^2]$ . In the derivation we have assumed that  $\langle P^2 \rangle = \langle P^2 \rangle_0 = \text{cte}$  as we have proven that  $\langle P \rangle = \langle P(0) \rangle$ . Also, recall X and P are not time-dependent.

## **Optional**

## Problem VI

### Part 1.

(a) Given that  $F(\lambda) = a\lambda^2 + c$  and  $G(\lambda) = b\lambda$ , with  $a, c \in \mathbb{R}^+$  and  $b \in \mathbb{R}$ , we plot the three scenarios required with specific values for (a, b, c).



(b) We equation both expression and solver using the quadratic formula:

$$a\lambda^2 + c = b\lambda$$
$$a\lambda^2 - b\lambda + c = 0$$

The roots are:

$$\lambda_{1,2} = \frac{b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{b \pm \sqrt{D}}{2a}.$$

In order to have two real and distinct roots, we must have  $D = b^2 - 4ac > 0$ .

(c) In this case, we have that

$$a\lambda^2 - b\lambda + c \ge 0.$$

The roots are same same that the previous cases:

$$\lambda_{1,2} = \frac{b \pm \sqrt{D}}{2a} \in \{\frac{b - \sqrt{D}}{2a}, \frac{b + \sqrt{D}}{2a}\}.$$

In this case, in order to satisfy that  $F(\lambda) \geq G(\lambda)$ ,  $\forall \lambda$ , we would have complex roots which can only happen for  $D = b^2 - 4ac \leq 0$ .

### Part 2.

a) We can show it by using properties of Hermitian operation:

$$G^{\dagger} = (iF)^{\dagger} = -iF^{\dagger} = -iF = -G \Longrightarrow G^{\dagger} = -G.$$

b) It can be prooved by looking the eigenvalues of the operator:

$$G|\psi\rangle = g|\psi\rangle$$
 and  $(G|\psi\rangle)^{\dagger} = (g|\psi\rangle)^{\dagger}$  
$$\langle \psi|G^{\dagger} = g^*\langle \psi|$$
 
$$-\langle \psi|G = g^*\langle \psi|$$
 
$$\langle \psi|G = -g^*\langle \psi|.$$

Therefore, if under an adjoint operator the eigenvalue changes from g to  $-g^*$ , it means that it is a pure imaginary term. If it would have consisted of also a real part, it will not be possible to extract the minus sign from g. The same can be done for the expectation value:

$$\langle \psi | G | \psi \rangle^{\dagger} = \langle \psi | G^{\dagger} | \psi \rangle = -\langle \psi | G | \psi \rangle.$$

The minus sign reveals the same nature on this number.

c) The commutator already has a property for the adjoint, we will use it and also the inversion of the arguments with the minus sign included:

$$([A, B])^{\dagger} = [B^{\dagger}, A^{\dagger}] = -[A^{\dagger}, B^{\dagger}] = -([A, B])^{\dagger}.$$

The other follows the same idea:

$$\langle \psi | [A,B] | \psi \rangle^\dagger = \langle \psi | [A,B]^\dagger | \psi \rangle = - \langle \psi | [A,B] | \psi \rangle.$$

We have used the previous results of the commutator directly.

#### Part 3

(a) The scalar product is:

$$\begin{split} \langle \phi | \phi \rangle &= \langle \psi | (A - i\lambda B)(A + i\lambda B) | \psi \rangle \\ &= \langle \psi | A^2 | \psi \rangle + \langle \psi | i\lambda AB - i\lambda BA | \psi \rangle + \langle \psi | \lambda^2 B | \psi \rangle \\ &= \langle \psi | A^2 | \psi \rangle + i\lambda \langle \psi | [A, B] | \psi \rangle + \langle \psi | \lambda^2 B^2 | \psi \rangle \\ \langle \phi | \phi \rangle &= \langle A^2 \rangle + i\langle [A, B] \rangle \lambda + \langle B^2 \rangle \lambda^2 \geq 0. \end{split}$$

This consists of a second-order polynomial of  $\lambda$ . The roots must be complex, which implies that the determinant must be  $D \leq 0$ :

$$D = \langle [A, B] \rangle^2 - 4\langle B^2 \rangle \langle A^2 \rangle \le 0 \longrightarrow \langle A^2 \rangle \langle B^2 \rangle \ge \frac{1}{4} |\langle [A, B] \rangle|^2.$$

(b) To verify that [A', B'] = [A, B] we substitute  $A' = A - \langle A \rangle$  and  $B' = B - \langle B \rangle$ :

$$[A', B'] = A'B' - B'A'$$

$$= (A - \langle A \rangle)(B - \langle B \rangle)(B - \langle B \rangle)(A - \langle A \rangle)$$

$$= AB - A\langle B \rangle - \langle A \rangle B + \langle A \rangle \langle B \rangle - BA + B\langle A \rangle + \langle B \rangle A - \langle B \rangle \langle A \rangle$$

$$= AB - BA$$

$$[A', B'] = [A, B].$$

This implies that we could began with A' and B' in the second-order equation. Therefore, it is a matter or substitue A by A' and B by B':

$$\langle (A')^2 \rangle \langle (B')^2 \rangle \ge \frac{1}{2} |\langle [A, B] \rangle|^2.$$

(c) This derivation is strongly linked with the above one.

$$\langle (A')^2 \rangle \langle (B')^2 \rangle \ge \frac{1}{4} |\langle [A, B] \rangle|^2$$

$$\langle (A - \langle A \rangle)^2 \rangle \langle (B - \langle B \rangle)^2 \rangle \ge$$

$$\langle (A^2 - 2A\langle A \rangle + \langle A \rangle^2) \rangle \langle (B^2 - 2B\langle B \rangle + \langle B \rangle^2) \rangle \ge$$

$$(\langle A^2 \rangle - 2\langle A \rangle^2 + \langle A \rangle^2) (\langle B^2 \rangle - 2\langle B \rangle^2 + \langle B \rangle^2) \ge$$

$$(\langle A^2 \rangle - \langle A \rangle^2) (\langle B^2 \rangle - \langle B \rangle^2) \ge$$

$$(\Delta A)^2 (\Delta B)^2 \ge \frac{1}{4} |\langle [A, B] \rangle|^2.$$

(d) If two observables Q and P have the commutation  $[Q,P]=i\hbar$ , we can compare them with the initial statement that

$$|\phi\rangle = (A + i\lambda B)|\psi\rangle$$
 with  $[A, B] = iC$ .

Then,  $C = \hbar$  for this case. Also, by doing the derivation we could also get the relation in terms of Q and P. Is now just a matter of replace them: uncertainty:

$$|(\Delta Q)^2 (\Delta P)^2 \ge \frac{1}{4} |\langle [Q, P] \rangle|^2 = \frac{1}{4} |\langle i\hbar \rangle|^2 = \frac{1}{4} |i\hbar|^2 = \frac{\hbar^2}{4}.$$

### Problem VII

(a) Im sure this is not the best way, but basically I took out the integration operator and the integrand is left is [H(t), H(t')] which is non-zero by assumption. Therefore, if we assume the integrand to be monotonically positive, there is no form to get zero:

$$[H(t), H(t')] \neq 0 \Longrightarrow \int_{t_0}^t [H(t), H(t')] dt' \neq 0.$$

The only way it can be zero if the commutator is negative and also positive so that may exist a completely cancellation.

(b) We will assume that  $H(t_0)$  is a constant and therefore can commute:

$$\begin{split} \left[ F(t), \frac{d}{dt} F(t) \right] &= -\frac{1}{\hbar^2} \left[ \int_{t_0}^t H(t') \ dt', \int_{t_0}^t \frac{d}{dt} H(t'') \ dt'' \right] \\ &= -\frac{1}{\hbar^2} \left[ \int_{t_0}^t H(t') \ dt', H(t) - H(t_0) \right] \\ &= -\frac{1}{\hbar^2} \left[ \int_{t_0}^t H(t') \ dt', H(t) \right] - \frac{1}{\hbar^2} \left[ \int_{t_0}^t H(t') \ dt', H(t_0) \right] \\ \left[ F(t), \frac{d}{dt} F(t) \right] &= -\frac{1}{\hbar^2} \left[ \int_{t_0}^t H(t') \ dt', H(t) \right]. \end{split}$$

The other equation can be easily verified by using the [A, B] = -[B, A] identity.

- (c) I couldnt:(
- (d) We use separation of variable by thinking of  $y = U(t, t_0)$ :

$$\frac{dU(t,t_0)}{dt} \frac{1}{U(t,t_0)} = -\frac{i}{\hbar} H(t) / \int_{t_0}^t dt$$

$$\ln U(t,t_0) = -\frac{i}{\hbar} \int_{t_0}^t H(t') dt' / e^t$$

$$U(t,t_0) = e^{-\frac{i}{\hbar} \int_{t_0}^t H(t') dt'}.$$

I dont know how [H(t), H(t')] = 0 restricts the above.