## OPTI 570 LECTURE Th Sep 4) Representations CT TO C ex: 20 space To = ax + by => (a, b) represents To in the >x, y | basis To = c û + d v = (c, d) represents To in the >u, v > bosis $(a,b) \neq (c,d) \neq \vec{r}$ Notation: To, sx, igs = (b) To -0 (b) in the 5x, yg basis (c) = (coxo sin o) (c) transformation representation matrix Representations in Quantum Mechanics Let } 14,>, [4,>, 142) & a basis Por & 1,2,2 14>= a | u,> + b | u 2> + c | u3> 14> - (b) = 14>(u) u mailie presents 14> in the contraction u bosis representation

$$| \frac{1}{1} \frac{$$

Trans or ming between representations example: .30 state space & ·14> & E how to represent in two di) lerent bases \u\, \V\ Î = É | ujx uj | and Î = É | vjx vj | Q: < Um/Um> = 2 m, m a: < vm/vm> = 2mm Q: < um | Vm> = Scaler & C LOCMORM < 1 1. Express 142 in the lul basis representation: (4> = 1 |4> = = \$ |u;xu;| 4> =  $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} > | u_{3} >$   $= \frac{3}{2} < u_{3} | \Psi > | u_{3} >$  Corresponding < 4 | 1 mg = (< 4 | u, > < 4 | u2> < 4 | u3>) = (< 4,14) Same .. same in {v} basis  $|\Psi\rangle_{\zeta_{\psi\zeta}} = |\langle v_1 | \Psi \rangle \rangle \\ |\langle v_2 | \Psi \rangle \rangle$ 

If we know 
$$|\Psi\rangle$$
 in the  $\langle u|$  repres  $\langle \underline{\alpha}: \omega \rangle$  in the  $\langle u|$  repres  $\langle \underline{\alpha}: \omega \rangle$  in the  $\langle u|$  repres  $\langle \underline{\alpha}: \omega \rangle$  in the  $\langle u|$  repres  $\langle \underline{\alpha}: \omega \rangle$  in the  $\langle u|$  repres  $\langle \underline{\alpha}: \omega \rangle$  in the  $\langle u|$  repres  $\langle \underline{\alpha}: \omega \rangle$  in the  $\langle u|$  representation:

$$|V_1\rangle = \frac{1}{\langle z|} |u_1\rangle + o|u_2\rangle + \frac{1}{\langle z|} |u_3\rangle$$

$$|V_2\rangle = \frac{1}{\langle z|} |u_1\rangle + o|u_2\rangle - \frac{1}{\langle z|} |u_3\rangle$$

$$|V_2\rangle \langle u| = \langle u| |u_1\rangle = \langle u| |u_2\rangle = \langle u| |u_2\rangle$$

$$|V_2\rangle \langle u| = \langle u| |u_1\rangle = \langle u| |u_2\rangle = \langle u| |u_2\rangle$$

$$|V_2\rangle \langle u| = \langle u| |u_1\rangle = \langle u| |u_2\rangle = \langle u| |u_2\rangle$$

$$|V_2\rangle \langle u| = \langle u| |u_1\rangle = \langle u| |u_2\rangle = \langle u| |u_2\rangle$$

$$|V_2\rangle \langle u| = \langle u| |u_1\rangle = \langle u| |u_2\rangle =$$

$$|\Psi\rangle_{\{0\}} = \left( \langle v_1 | \psi_2 \rangle \right) = \left( \langle v_1 | u_1 \times u_1 | \psi_2 \rangle + \langle v_1 | u_2 \times u_1 | \psi_2 \rangle + \langle v_1 | u_3 \times u_4 | \psi_2 \rangle \right) = \left( \langle v_1 | u_1 \rangle + \langle v_1 | u_2 \rangle + \langle v_1 | u_2 \rangle + \langle v_1 | u_3 \rangle + \langle v_1 | u_2 \rangle + \langle v_1 | u_2 \rangle + \langle v_1 | v_2 \rangle + \langle v_1 | v_2 \rangle + \langle v_1 | v_2 \rangle + \langle v_2 | v_2 \rangle + \langle v_2 | v_3 \rangle + \langle v_1 | v_2 \rangle + \langle v_1 | v_2 | v_3 \rangle + \langle v_1 | v_3 | v_3 \rangle$$

Operator representation

$$\hat{A} = \hat{1} \hat{A} \hat{1} = \sum_{i=1}^{2} |u_{i} \times u_{i}| \hat{A} \times \sum_{i=1}^{2} |u_{m} \times u_{m}| = \sum_{i=1}^{2} |u_{i} \times u_{i}| \hat{A} \times \sum_{i=1}^{2} |u_{m} \times u_{m}| = \sum_{i=1}^{2} \sum_{i=1}^{2} |u_{i} \times u_{i}| \hat{A} \times \sum_{i=1}^{2} |u_{i} \times u_{m}| = \sum_{i=1}^{2} \sum_{i=1}^{2} |u_{i} \times u_{m}| \hat{A} \times \sum_{i=1}^{2} |u_{i} \times u_{m}$$