

Data preprocessing, model complexity.

Victor Kitov

v.v.kitov@yandex.ru

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Hyperparameters selection

- Using CV we can select hyperparameters of the model¹
- Each model has hyperparameter, corresponding to model complexity.
- Model complexity - ability to reproduce training set.
- Examples:
 - regression: # of features d , e.g. $x, x^2, \dots x^d$
 - K-NN: number of neighbors K

¹can we use CV loss in this case as estimation for future losses?

Underfitted and overfitted models²

Too simple (underfitted) model

Model that oversimplifies true relationship $\mathcal{X} \rightarrow \mathcal{Y}$.

Too complex (overfitted) model

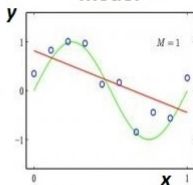
Model that is too tuned on particular peculiarities (noise) of the training set instead of the true relationship $\mathcal{X} \rightarrow \mathcal{Y}$.

²In fact most models overfit, meaning that empirical risk < expected risk. Underfitted models just have lower difference than overfitted ones.

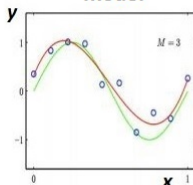
Examples of overfitted / underfitted models

- true relationship
- estimated relationship with polynimes of order M
- objects of the training sample

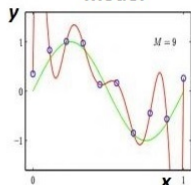
regression:
too simple model



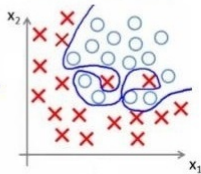
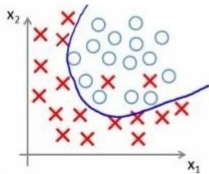
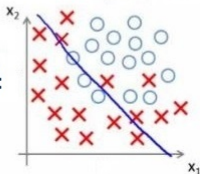
relevant model



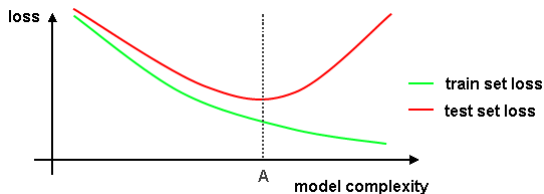
too complex model



classification:



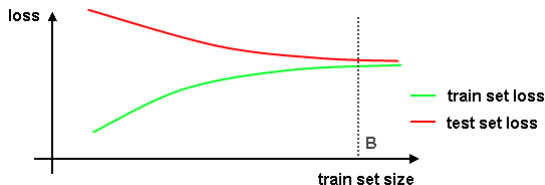
Loss vs. model complexity



Comments:

- expected loss on test set is always higher than on train set.
- left to A: model too simple, underfitting, high bias
- right to A: model too complex, overfitting, high variance

Loss vs. train set size



Comments:

- expected loss on test set is always higher than on train set.
- right to B there is no need to further increase training set size
 - useful to limit training set size when model fitting is time consuming

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1 Model complexity

2 Data preprocessing

- Missing data
- Data reduction
- Data transformation
- Feature type transformations

What we need to do

- Data preprocessing:
 - deal with missing data
 - clean incorrect data
 - data subsampling
 - data scaling
 - data type transformation

2 Data preprocessing

- Missing data
- Data reduction
- Data transformation
- Feature type transformations

Missing data

What we can do with missing features:

- **remove all objects, having at least one missing feature**
 - easiest way, but lose information
- **fill missing features using most likely value**
 - mean, median for numeric features
 - averaged neighbours for continuous time-series
 - mode for categorical feature
- **predict missing features using known features**
 - regression task for numeric features
 - classification task for categorical feature
- **use models, which ignore missing features**
 - such as decision trees

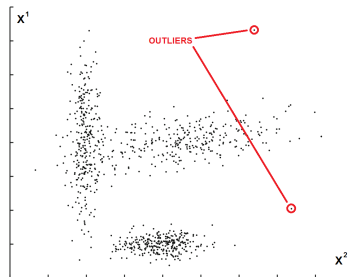
Comments on imputation

- imputing missing features with estimates induces imputation bias
 - to get rid of this bias: for feature d add binary feature, indicating whether this feature was known or was imputed.
- imputation implies that feature absence and feature value are independent
 - may not be the case
 - in surveys people prefer not to tell their salary when it is big.
 - if they are dependent additional expert info should be used for feature reconstruction

Incorrect data

We can detect incorrect data using:

- consistency check across different databases
 - e.g. surname of the same person is spelled differently in different records
- domain knowledge
 - e.g. human height cannot be 4 meters
- statistical methods: remove outliers



Outlier removal, having extreme values

- 1D outlier removal:

³which of these measures are robust to outliers and why?

⁴which of these measures are robust to outliers and why?

Outlier removal, having extreme values

- 1D outlier removal:
 - outliers are outside $[center - \alpha scatter, center + \alpha scatter]$, $\alpha > 0$
 - center³: mean, median
 - scatter⁴: standard deviation, 95% quantile - 5% quantile, median $\{|x - \text{median}\{x\}|\}$
- Outliers can be not errors, but interesting regimes:
 - manual inspection of outliers needed
 - examples:
 - medical data: rare disease
 - network data: hacker attack
 - card transaction data: fraud

³which of these measures are robust to outliers and why?

⁴which of these measures are robust to outliers and why?

2 Data preprocessing

- Missing data
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Objects reduction

If N is too large, then

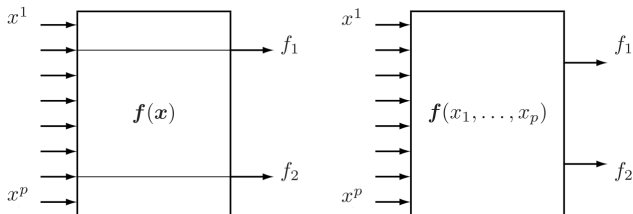
- additional disk/memory/CPU data transfer requirements
- slow-down of optimization in ML methods

Objects reduction:

- random uniform
 - purely random subsampling
 - random with stratification
 - stratification by output (or feature) value to preserve output (or object types) distribution
- random non-uniform
 - sample new objects more (in dynamic context)
 - sample rare classes/objects more (underrepresented data)
 - sample harder objects more (mistakes)

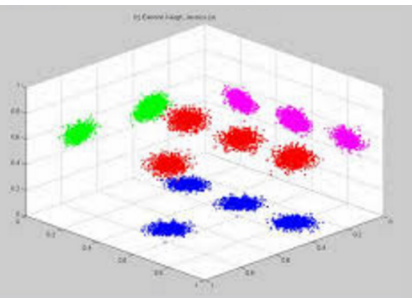
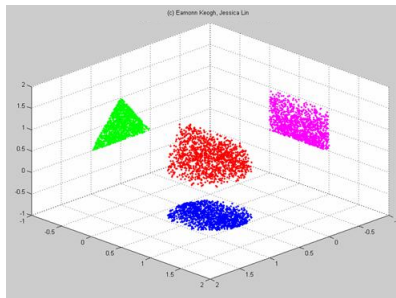
Feature reduction

- Feature selection vs. feature extraction:



- Feature selection:
 - unsupervised (e.g. variance<threshold)
 - filter (e.g. by correlation with output)
 - wrapper (e.g. compare performance with/without feature)
 - embedded inside ML model

Brute-force feature selection may lead to information loss



2 Data preprocessing

- Missing data
- Data reduction
- **Data transformation**
- Feature type transformations

Normalization of features

- Feature scaling may affect ML model, e.g. K-NN.
- Need equal features impact - make their scatter common.
- Make some features more important - increase their scatter.
- Typical scaling operators:

Name	Transformation	Properties of result
Standardization	$u' = \frac{x_j - \text{mean}(u)}{\text{std}(u)}$	mean=0, std=1
Min-max normalization	$u' = \frac{u - \min(u)}{\max(u) - \min(u)}$	$\in [0, 1]$, 0->0 for sparse data
Average normalization	$u' = \frac{u - \text{mean}(u)}{\max(u) - \min(u)}$	zero mean, range=1

- All operators aren't robust to outliers. Propose robust variants.

Non-linear feature transformations

- Feature with skewed distribution with large rare values:

$$u' = \log(1 + u), \quad u' = u^p, \quad 0 \leq p < 1$$

- For uniformly distributed output ($F(\cdot)$ -c.d.f. of u)

$$u' = F(u)$$

- For normally distributed output ($\Phi^{-1}(\cdot)$ -inverse function to c.d.f. of $\mathcal{N}(0, 1)$)⁵.

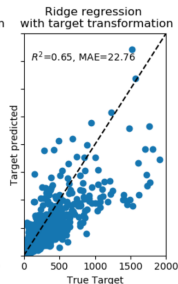
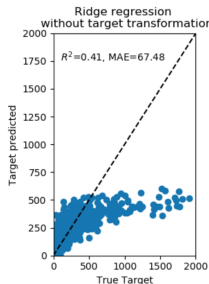
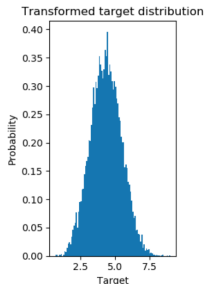
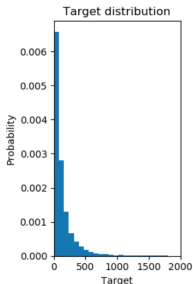
$$u' = \Phi^{-1}(F(u))$$

- Object normalization $x' \rightarrow x / \|x\|$, $x \in \mathbb{R}^D$.
 - when feature ratios are more important than absolute values.
 - example:
 - x - counts of words within document
 - x' - frequencies of words within document
 - documents of different length become comparable!

⁵Prove that. See `sklearn.preprocessing.QuantileTransformer`.

Transformation of output⁶

$$y' = \ln(1 + y)$$



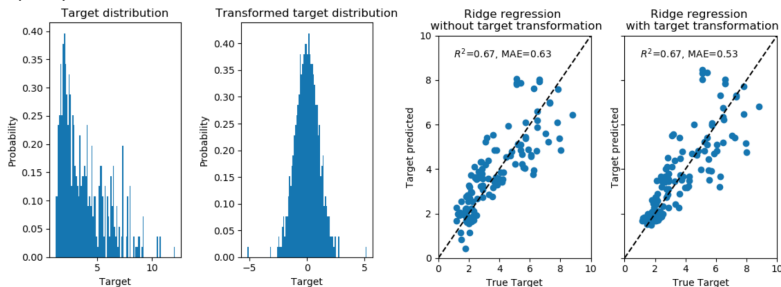
$$MAE = \frac{1}{N} \sum_{n=1}^N |\hat{y}_n - y_n|,$$

$$R^2 = 1 - \frac{(1/N) \sum_{n=1}^N |\hat{y}_n - y_n|}{(1/N) \sum_{n=1}^N |\text{mean}(y_n) - y_n|}$$

⁶See [scikit-learn demo](#).

Transformation of output⁷

$y' = \Phi^{-1}(F(y))$, $F(\cdot)$ - c.d.f. of y , $\Phi^{-1}(\cdot)$ -inverse function to c.d.f. of $\mathcal{N}(0, 1)$.



$$MAE = \frac{1}{N} \sum_{n=1}^N |\hat{y}_n - y_n|, \quad R^2 = 1 - \frac{(1/N) \sum_{n=1}^N |\hat{y}_n - y_n|}{(1/N) \sum_{n=1}^N |\text{mean}(y_n) - y_n|}$$

⁷See [scikit-learn demo](#).

- 2 Data preprocessing
 - Missing data
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 - Feature type transformations

Possible features types

- **Numeric**
 - salary
 - flat size
- **Categorical**
 - occupation (programmer, manager, engineer, etc.)
 - city (Moscow, Kaluga, etc.)
- **Binary** (may be considered both numeric and categorical)
 - sex
 - employment indicator
 - marital status

Numeric \rightarrow categorical (discretization)

- 1 Split feature domain into intervals

$$[b_1, b_2], [b_2, b_3], \dots [b_K, b_{K+1}]$$

- 2 $u \rightarrow u' \in \mathbb{R}^K$

$$u' = (\mathbb{I}[u \in [b_1, b_2]], \mathbb{I}[u \in [b_2, b_3]], \dots \mathbb{I}[u \in [b_K, b_{K+1}]])$$

- Loose some information.
- Makes model pay attention to special groups (e.g. by age - students, working, pensioners).
- Intervals selection:
 - equal length of each interval
 - equal density of points in each interval

Categorical->numeric

- **One hot encoding** - encode categorical feature

$$u \in \{c_1, c_2, \dots, c_K\} \text{ with } u' \in \mathbb{R}^K$$

$$u' = (\mathbb{I}[u = c_1], \mathbb{I}[u = c_2], \dots, \mathbb{I}[u = c_K])$$

Original data:		One-hot encoding format:					
id	Color	id	White	Red	Black	Purple	Gold
1	White	1	1	0	0	0	0
2	Red	2	0	1	0	0	0
3	Black	3	0	0	1	0	0
4	Purple	4	0	0	0	1	0
5	Gold	5	0	0	0	0	1

- Original u is then replaced by u' , total number of features increases by $K - 1$.

Categorical->numeric

Mean value encoding - replace discrete feature f with aggregated another feature g .

- Continuous g :
 - replace f with $\text{average}(g|f)$
- Discrete $g \in \{1, 2, \dots, C\}$:
 - replace f with C binary features
 $p(g = 1|f), p(g = 2|f), \dots, p(g = C|f)$

g may be taken as output y .

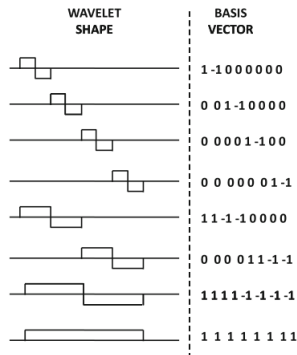
- intuitive method but overfits
 - e.g. consider f =client id, unique for each object.
- to prevent overfitting calculate aggregation statistics on **separate training set.**

Time series / spatial \rightarrow numeric

- **Time series \rightarrow numeric:**
 - use discrete wavelet transform (DWT).
- **Spatial data \rightarrow numeric:**
 - use discrete wavelet transform (DWT).

Haar wavelet transform

- Suppose we have time series $f(t)$, $t = 1, 2, \dots, T$.
 - e.g. temperature measurements from sensor every second
- How can we get compact description of $f(t)$?
- Consider the following set of basis functions $\phi_k(t)$ (Haar wavelets):
- They are orthogonal $\langle \phi_i, \phi_j \rangle = \sum_t \phi_i(t) \phi_j(t) = 0 \quad \forall i \neq j$.
- Represent $f_t = \sum_{k=1}^K a_k \phi_k(t)$, so $f_t \rightarrow (a_1, a_2, \dots, a_K)$.



Finding wavelet coefficients

Finding wavelet coefficients:

- ① Set first coefficient to $\frac{1}{T} \sum_t f(t)$
- ② repeat until given resolution achieved:
 - ① next wavelet coefficient = $0.5 * (\text{difference between average value of time series value on 1st halve and 2nd halves})$
 - ② recursively apply this approach to 1st and second half of time series

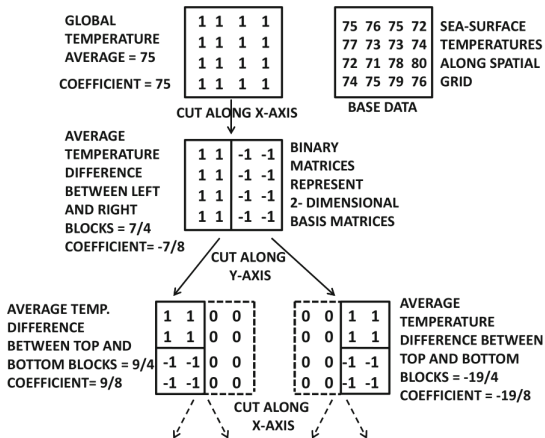
Dimensionality reduction with wavelets

$$f_t = \sum_{k=1}^K a_k \phi(t) = \sum_{k=1}^K a_k \|\phi_k(t)\| \frac{\phi_k(t)}{\|\phi_k(t)\|}$$

- $\frac{\phi_k(t)}{\|\phi_k(t)\|}$ are orthonormal, so comparable.
- Leave only coefficients, having $a_k \|\phi_k(t)\| > threshold$.
- When have P time series simultaneously, we can
 - leave coefficients for $\phi_k(t)$ that are on average important for all time series
 - or leave coefficients for each time series independently, set other to 0, get sparse matrix.
 - then we can get economical representation of this matrix with SVD decomposition.

Wavelets for spatial data

Top levels of the wavelet decomposition for spatial data



Other transformations

- **Discrete sequence->numeric:**

- 1 for each t replace f_t with one-hot encoded $\tilde{f}_t \in \mathbb{R}^K$
- 2 for each $k = 1, 2, \dots, K$: apply wavelet transform to each binary time series \tilde{f}_t^k
- 3 append wavelet coefficients into single vector representation.

- **Any type->set of numeric points** y_1, \dots, y_N , $y_i \in \mathbb{R}^K$:

- solve *multidimensional scaling* problem:

$$\sum_{i,j: i > j} (\rho(x_i, x_j) - \|y_i - y_j\|)^2 \rightarrow \min_{y_1, \dots, y_N}$$

Other transformations

- **Time series \rightarrow discrete sequence:**

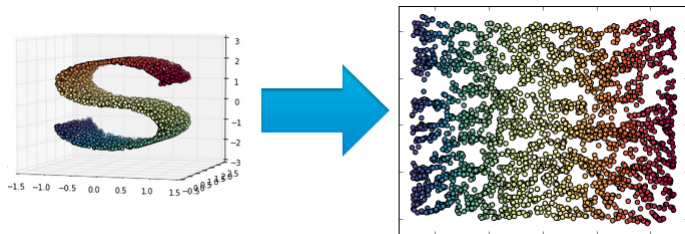
- 1 Consider time series f_t , t -time.
- 2 Divide time into windows of equal size, $f_t \rightarrow$ averaged value on each window
- 3 Discretize averaged values using equiwidth or equiwidth discretization.

- **Any type \rightarrow graph:**

- each object is represented by a node
- connection between x_i, x_j exists $\Leftrightarrow x_i, x_j$ are sufficiently close:
 $\rho(x_i, x_j) < threshold$
 x_i, x_j are belong to K nearest neighbours of each other.
- weight of connection:

$$w_{ij} = e^{-\gamma \rho(x_i, x_j)^2}$$

Why we may need graphs



Distance along the graph may be useful.

Summary

- Each model has complexity parameter - tune it!
- Data preprocessing is important and includes the following steps:
 - deal with missing data
 - clean incorrect data
 - data subsampling
 - data scaling
 - data type transformation
 - one-hot and aggregation encodings are most important.